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4) No - Rock, paper - Scissors has no PNE to converge

EXERCISE 3

1) NEP returned by numpy are

$$\begin{bmatrix} (1), (1) \\ (0), (0) \end{bmatrix}, \begin{bmatrix} (0), (0) \\ (1), (1) \end{bmatrix}, \begin{bmatrix} (0,5), (0,75) \\ (0,5), (0,25) \end{bmatrix}. \quad \checkmark$$

2) Payoff vectors

$$v_1 = \frac{4u_{2C} + 2u_{2D}}{2u_{2C} + 6u_{2D}} \begin{pmatrix} 4u_{2C} \\ 2u_{2C} + 6u_{2D} \end{pmatrix} = \begin{pmatrix} 4u_{2C} \\ 6 - 4u_{2C} \end{pmatrix}$$

$$v_2 = \begin{pmatrix} 6u_{1A} \\ 2u_{1A} + 4u_{1B} \end{pmatrix} = \begin{pmatrix} 6 - 6u_{1B} \\ 2 + 2u_{1B} \end{pmatrix}$$

$$u_{1B} = u_{1B} [v_1(B) - v_1(R, \frac{u_{2C}}{u_{2D}})]$$

$$= u_{1B} [6 - 4u_{2C} - 4u_{1A}u_{2C} - u_{1B}(6 - 4u_{2C})]$$

$$= u_{1B} [6 - 4u_{2C} - 4(1-u_{1B})u_{2C} - u_{1B}(6 - 4u_{2C})]$$

$$= u_{1B} [6 - 4u_{2C} - 4u_{2C} + 4u_{1B}u_{2C} - 6u_{1B}u_{2C}]$$

$$= u_{1B} [6 - 6u_{1B} - 8u_{2C} + 8u_{1B}u_{2C}]$$

$$= u_{1B} (1 - u_{1B}) (6 - 8u_{2C}). \quad \checkmark$$

$$x_{2C} = u_{2C} [v_2(C) - v_2(x)]$$

$$= u_{2C} [6 - 6u_{1B} - u_{2C}(6 - 6u_{1B}) - u_{2D}(2 + 2u_{1B})]$$

$$= u_{2C} [6 - 6u_{1B} - u_{2C}(6 - 6u_{1B}) - (1-u_{2C})(2 + 2u_{1B})]$$

$$= u_{2C} [6 - 6u_{1B} - 6u_{2C} + 6u_{1B}u_{2C} - 2 - 2u_{1B} + 2u_{2C} + 2u_{1B}u_{2C}]$$

$$= u_{2C} [4 - 8u_{1B} - 4u_{2C} + 8u_{1B}u_{2C}]$$

$$= 4u_{2C} (1 - 2u_{1B}) (1 - 4u_{2C}) \quad \checkmark$$

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NOTE :

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Université de Limoges

Faculté des Sciences et Techniques

FACULTÉ
DES SCIENCES
ET TECHNIQUES

Date : 24/10/2024 Session :

Diplôme :

UE :

Nombre de feuilles intercalaires :

Nom (en majuscules): CHAU

Prénoms : Dang Minh

Date de naissance : 21/08/2002

Lieu de naissance : Viet Nam

Exercice 1

$$1) \text{ Denote } u_1 = (u_{1A}, u_{1B}, u_{1C})^T \quad u_2 = (u_1)$$

$$u_2 = (u_{2A}, u_{2B}, u_{2C})^T$$

$$\text{we have } v_i(x) = \begin{pmatrix} 6u_{2C} + 6u_{2D} + 4u_{2D} \\ 7u_{2C} + 4u_{2D} \\ 5u_{2D} \end{pmatrix} \quad \checkmark$$

$$v_2(u_1) = \begin{pmatrix} 5u_{1A} + 10u_{1B} + u_{1C} \\ 4u_{1A} + 6u_{1B} \\ 3u_{1C} \end{pmatrix} \quad \checkmark$$

not satisfying

2) Suppose that there is a function $\phi: A_1 \times A_2 \rightarrow \mathbb{R}$ such that $\phi(A, x) - \phi(B, x) = u_1(A, x) - u_1(B, x) = 6 - 7 = -1$ condition of

$$\phi(B, x) - \phi(C, x) = 7$$

$$\phi(A, Y) - \phi(B, Y) = 2$$

$$\phi(B, Y) - \phi(C, Y) = 4$$

$$\phi(A, Z) - \phi(B, Z) = 4$$

$$\phi(B, Z) - \phi(C, Z) = -5$$

Let $\phi(A, x) = c \Rightarrow \phi(B, x) = c+1$

$$\text{Hence } \phi(C, x) = c-6$$

$$\text{From } \phi(A, x) - \phi(A, Y) = u_2(A, x) - u_2(A, Y) = 1$$

$$\text{We have } \phi(A, Y) = c-1$$

$$\text{Hence } \phi(B, Y) = c-3 \text{ and } \phi(C, Y) = c-7$$

$$\text{From } \phi(A, x) - \phi(A, Z) = u_2(A, x) - u_2(A, Z) = 5$$

$$\text{We have } \phi(A, Z) = c-5 \text{ and } \phi(B, Z) = c-9$$

$$\phi(C, Z) = c-4$$

In summary, ϕ is represented in a table as

	X	Y	Z
A	c	c-1	c-5
B	c+1	c-3	c-9
C	c-6	c-7	c-4

We can check that ϕ satisfies other differences of payoffs.

Thus, the game is potential, a valid potential function is given already

i) the maximizer of ϕ is a Nash equilibrium of Γ (NE)
hence (B, x) is an NE.

EXERCISE 2 -

1) Denote $X > Y$ if Y is dominated by X .

Step 1: $D > E$, $B \rightarrow A$. $A > B$

Remaining	A	C	D
X	(50, -2)	(50, -2)	(-4, 40)
Y	(0, 0)	(-2, -2)	(-4, -10)
Z	(30, 2)	(4, 4)	(24, 0)
V	(40, 2)	(30, -2)	(8, -2)
W	(1, -6)	(-6, 8)	(5, -12)

Step 2: $X > Y$, $Z > W$

A C D

Remaining

Step 1: $B > A$

Remaining	B	C	D	E
X	(-4, 0)	(50, -2)	(-4, 40)	(-6, 39)
Y	(-2, 30)	(-2, -2)	(-4, -10)	(-6, -40)
Z	(4, 10)	(4, 4)	(24, 0)	(4, 6)
V	(0, 4)	(30, -2)	(8, -2)	(0, 8)
W	(-1, 10)	(-6, 8)	(5, -12)	(-2, -24)

Step 2: $Z > Y$, $Z > W$

Remaining	B	C	D	E
X	(-4, 0)	(50, -2)	(-4, 40)	(-6, 39)
Z	(4, 10)	(4, 4)	(24, 0)	(4, 6)
V	(0, 4)	(30, -2)	(8, -2)	(0, 8)

Step 3: $B > C$

Remaining	B	D	E
X	(-4, 0)	(-4, 40)	(-6, 39)
Z	(4, 10)	(24, 0)	(4, 6)
V	(0, 4)	(8, -2)	(0, 8)

Step 4: $Z > X$

Remaining	B	D	E
Z	(4, 10)	(8, -2)	(0, 8)
V	(0, 4)	(8, -2)	(0, 8)

Step 5: $B > D$

Remaining	B	E
Z	(24, 0)	(4, 6)
V	(8, -2)	(0, 8)

Step 6: $Z > V$

Remaining	B	E
Z	(24, 0)	(4, 6)

Step 7: $B > E$

Remaining (Z, B)

2). The game is dominance solvable, since the remaining after elimination is a singleton $\{Z, B\}$

$$Z = \arg \max_a u_1(a, E)$$

$$(W, E) \xrightarrow[C = \arg \max_b u_2(W, b)]{} (Z, C)$$

at each step, pick "one" player to choose his best action while fixing the action of the other player.

$$X = \arg \max_a u_1(a, C)$$

$$\xrightarrow[B = \arg \max_b u_2(Z, b)]{} (X, B)$$

$$B = \arg \max_b u_2(Z, C)$$

$$(S \text{imilarly}) \rightarrow (Z, D) \rightarrow (V, B) \rightarrow (Z, B) \rightarrow (Z, B)$$

converges.

The convergent point is (Z, B)

NOTE :

Nom (en majuscules): CHAU

Prénoms : Dang Minh

Date de naissance :

Lieu de naissance :

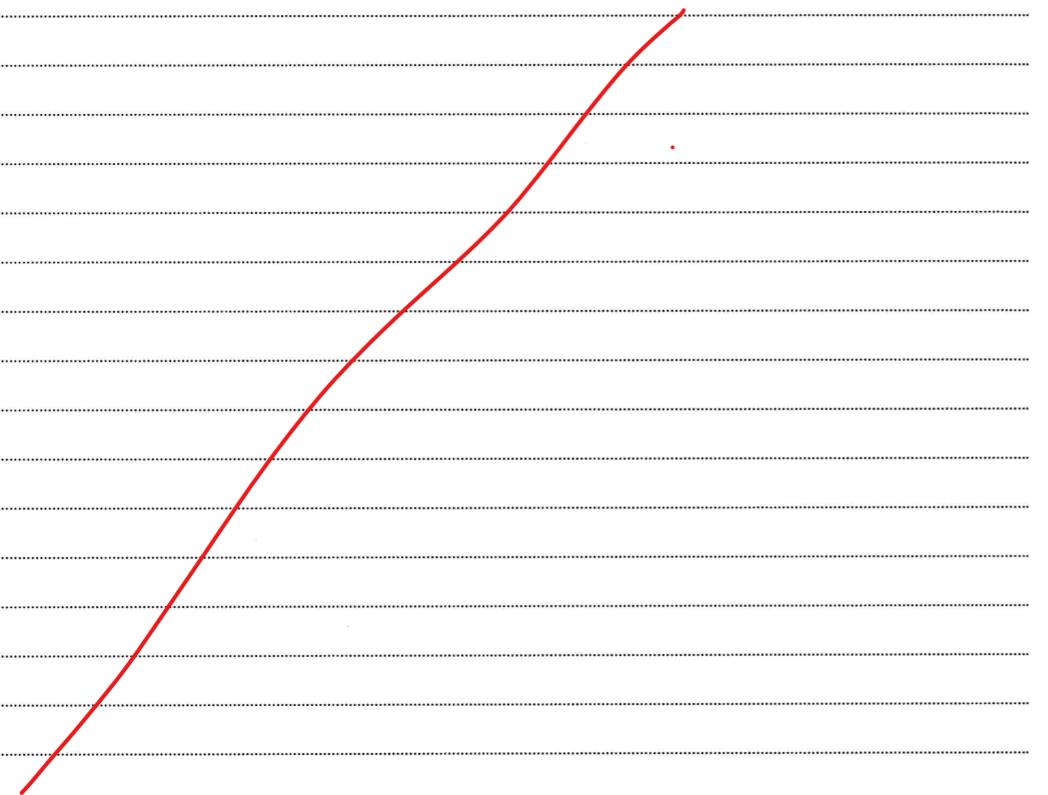
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3) RD approaches $\left[\begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right]$ ✓

4) $u_1 \left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right) = \text{some} \geq u_1 \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right]$.

$\Rightarrow x_1$ is not a NE, hence not stable.

Similarly for x_4 . ✓

From Nashpy, x_2, x_3, x_5 are NEs. ✓

$$v_1 \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} \right) = 4u_{1A} + 2u_{1B} =$$

$$u_1 \left(\begin{pmatrix} u_{1A} \\ u_{2B} \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right) = 4u_{1A} + 2u_{2B}$$

$$= 4 - 2u_{2B} \leq 4$$

Equality holds iff $u_{2B} = 0$

Similarly for u_2 .

Hence x_2 is a strict NE, hence asymptotically stable.

Similarly for x_3 . ✓

From ODES, all points are stationary.

$$u_1 \left(\begin{pmatrix} u_{1A} \\ u_{2B} \end{pmatrix}, \begin{pmatrix} 0,75 \\ 0,25 \end{pmatrix} \right) = 3(u_{1A} + u_{2B}) = 3, \forall u_{1A} \in [0,1]$$

Hence x_5 is not strict NE

Run RD for starting point
Since RD for $u(0) = \begin{pmatrix} 0,6 \\ 0,15 \end{pmatrix}$ converges to $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$

There exists a neighborhood $\epsilon > 0$

such that $\| x(t) - \begin{pmatrix} 0,5 \\ 0,75 \end{pmatrix} \| > \epsilon$

Hence x_5 is not Lyapunov stable. ✓

Summary	Stationary :	x_1	x_2	x_3	x_4	x_5
	NE		x_2	x_3		x_5
	Strict NE		x_2	x_3		
	Lyapunov stable		x_2	x_3		
	Asymptotically stable		x_2	x_3		

