

1 Different Behaviors for the Holes

We build an OA serving as a prototype for connection-oriented communication protocols. Let N be the number of data units to be sent, whose index ranges from 0 to $N - 1$. There are two holes, namely Sender and Receiver. The Sender invokes actions **send**, **receive** and **process**, corresponding to sending a data unit, receiving an acknowledgement and doing an internal work, such as waiting until timeout. The Receiver also invokes actions **send**, **receive** and **process**, but here it sends an acknowledgement and receives a data unit. A data unit or an acknowledgement may also be lost during transmission. From the environment's perspective, a data unit can be in one of the following situation

- it needs to be sent,
- it is on fly i.e. it was sent by the Sender but not arrives at the Receiver yet,
- it has been received by the Receiver, or
- it has been sent and acknowledged successfully.

Hence we use four variables of type lists D_{tosend} , D_{onfly} , D_{received} and D_{done} to store the indices of the data units in these situations. For an acknowledgement, it can also be on fly, which is store in A_{onfly} . We do not need to store received acknowledgements because the Sender processes an acknowledgement immediately when receiving it. The initial values are $D_{\text{tosend}} = [0, \dots, N - 1]$ and $D_{\text{onfly}} = D_{\text{received}} = D_{\text{done}} = A_{\text{onfly}} = []$. We use two operation on a list L

- $L.\text{push}(i)$: appending i to the list, and
- $L.\text{pop}(i)$: removing i in its first appearance from the list or return the old list if there is no i

and a function $\min(L)$ to find the minimal element in the list. The transitions are given in the following table.

N.O.	Source	Target	Action	Hole actions	Guard	Reassignment
1	q_0	q_0	$\text{sendData}(i)$	Sender \mapsto send (i)	$i = \min(D_{\text{tosend}})$	$D_{\text{onfly}}.\text{push}(i)$
2	q_0	q_0	$\text{receiveAck}(i)$	Sender \mapsto receive (i)	$i \in A_{\text{onfly}}$	$A_{\text{onfly}}.\text{pop}(i)$ $D_{\text{tosend}}.\text{pop}(i)$
3	q_0	q_0	τ	Sender \mapsto process ($opts$)	True	
4	q_0	q_0	$\text{receiveData}(i)$	Receiver \mapsto receive (i)	$i \in D_{\text{onfly}}$	$D_{\text{onfly}}.\text{pop}(i)$ $D_{\text{received}}.\text{push}(i)$
5	q_0	q_0	$\text{sendAck}(i)$	Receiver \mapsto send (i)	$i \in D_{\text{received}}$	$D_{\text{received}}.\text{pop}(i)$
6	q_0	q_0	τ	Sender \mapsto process ($opts$)	True	
7	q_0	q_0	$\text{loseData}(i)$		$i \in D_{\text{onfly}}$	$D_{\text{onfly}}.\text{pop}(i)$
8	q_0	q_0	$\text{loseAck}(i)$		$i \in A_{\text{onfly}}$	$A_{\text{onfly}}.\text{pop}(i)$

Table 1: Transition Table for Protocol OA

An protocol implementing the Sender and Receiver is correct if given the initial assignments of the lists, the composed OA always arrives at a terminal state with $D_{\text{done}} = [1, \dots, N]$.

Consider and example. Let $D_{\text{tosend}} = [0, 1, 2]$ and $D_{\text{onfly}} = D_{\text{received}} = D_{\text{done}} = A_{\text{onfly}} = []$. Denote by $(D_{\text{tosend}}, D_{\text{onfly}}, D_{\text{received}}, A_{\text{onfly}})$ each configuration of the OA. One possible run is

$$([0, 1, 2], [], [], []) \xrightarrow{\text{sendData}(0)} ([1, 2], [0], [], [])$$