

## AGENDA

- 1-> strategy Design Pattern
- 2-> Observer design pattern

[ Behavioural Design Patterns ]

start by 9:07 PM IST

## \*] BEHAVIOURAL DP:

These are mostly concerned with assignment of responsibility b/w objects.

i.e. How to handle special / edge cases for behaviour.

## 1> STRATEGY DESIGN PATTERN:

Eg: Google Maps

search for A → B

different routes / mode of transport shown:

train → route (1) -

bus → route (2) -

Sometimes - for a road : cars are not allowed.

Bus not allowed / one way etc...

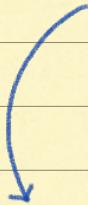
searching for routes:



we get multiple ways to travel

Each way has:

- ① different route / ETA



# if we write code-

```
class GoogleMaps {
```

```
    = findPath (source, destination, mode) {
```

```
        if (mode == car)
```

```
            getPathForCar()           // shortest
```

```
        else if (mode == bus)
```

```
            getPathForBus()          // Bus
```

```
        ...
```

```
        else if (mode == metro)
```

```
    }
```

PROBLEM .... ?

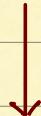
- ① violates SRP / OCP
- ② supporting new mode is difficult
- ③ making change requires full PA

Problem statement:

When multiple ways to do something. we often observe violation of SRP/OCP.



end up using if/else...



= solution: use STRATEGY D.P.

### \*] OBSERVATION:

```
findPath (source, destination, mode) {
```

```
    if (mode == car)
```

getpathforcar()

```
    else if (mode == bus)
```

getPathforbus

⋮

Y

→ code for specific use cases → completely different / Independent

Hence; Instead of having all behaviours in same method

Implement them in separate class.

### \*] STEPS:

1.) for every way to do particular thing → create class

- a.) carPathcalculator ✓
- b.) BikePathcalculator ✓
- c.) walkPathcalculator ✓

x



USAGE:

```
class Googlemaps {  
    carPathcalculator c;  
    BikePathcalculator b;  
    walkPathcalculator w;
```

X

}

.....



Y

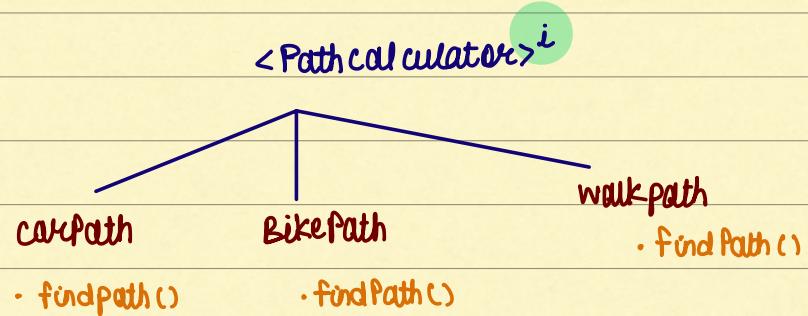
violates → .... D·I ....

# create Interface:



Always code to Interface; rather than  
Implementation

## 2. Create Interface



## 3. Use the Interface in Maps class

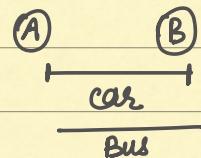
```
class GoogleMaps {
    findPath(origin, dest, mode);
    getInstances(mode);
}
```

By *factory* gets

The code block shows a class named 'GoogleMaps' with two methods: 'findPath(origin, dest, mode)' and 'getInstances(mode)'. An annotation 'By' is placed above the second method, with an arrow pointing to the word 'factory' and another arrow pointing to the word 'gets'.

//ON basis of mode → I want object

design pattern :



Now, In GoogleMaps class :

class GoogleMaps {

< Modes >

findPath (origin, dest, mode);

get Path calc(mode) · findPath()

y  
y

class Pathcalculatorfactory {

get Pathcalculator (mode);

if mode == car

return Carpathcalculator();

:

y

SUMMARIZE: Multiple ways to do something  
↳ use structural D.P.

strategy of

(2) / (3)

# ASSIGNMENT/HW:

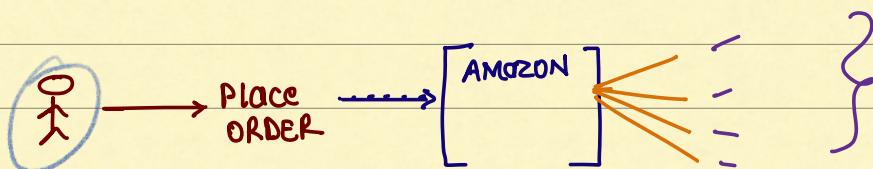
Rain Water Trapp. Problem

→ write code in All ways.

## \*] OBSERVER DESIGN PATTERN:

definition - useful when we are interested in state of object  $\neq$  want to get notified whenever there's any change.

e.g:



e.g: Amazon

Whenever order is placed  $\rightarrow$  what happens:

Inventory check

User: Notification / Invoice



orderPlaced() {

    updateInventory()

    NotifyWarehouse()

    updateDelivery()

    triggerNotifications()

    ::

}

=  
facade

so helper  
classes

PROBLEM

=  
observer dp

violates OCP / SRP



# New Requirement: update details in Analytics system



would Need changes

- ① In your existing code
- ② In Runtime, we validate Many things-

eg: for Prime music/video

→ No warehouse update is Needed.

Using Above solution → becomes tricky.

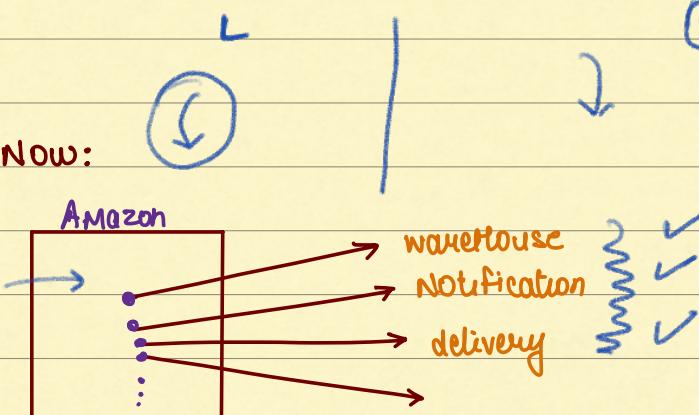
### Problem statement

① When some Event happens → we Need to do lot of things everytime. [This becomes less scalable]

② We cannot modify things at Runtime during Any event

## SOLUTION: OBSERVER DP

As of Now:



(1) class is responsible to trigger many flows

\*] STEPS:

1.] In such cases, think in opposite way

Multiple classes want to process something when  
Any Event happens.

basically: Many classes wait ON me.

Amazon

⋮  
⋮

HOW CLASSES ARE NOTIFIED ABOUT EVENT:

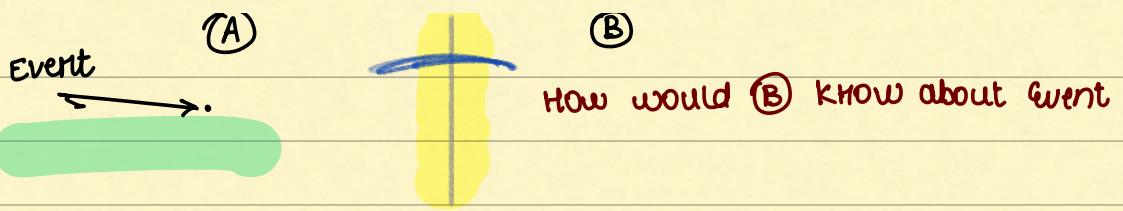
As of Now: No link / communication b/w ② independent classes



Amazon

O

different



(P)      (S)

### \*] TERMINOLOGIES:

- ① Publisher: classes that generate the event (A)
- ② Subscriber: classes who would want to know if an event has happened (consume) (B/C/D...)

1 publisher for 1 event; but many subscribers

### 2-> create Method in Publisher

This Method allows subscribers to register themselves

class Amazon {

List<Ops> ops;

registerOrderPlaceSubscribers(i)

orderplaced();

for(...);

ops.add(=?);

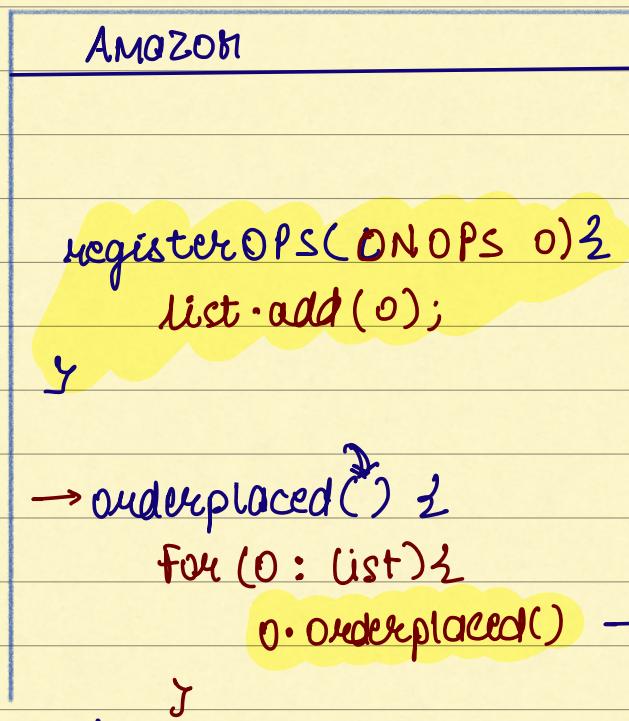
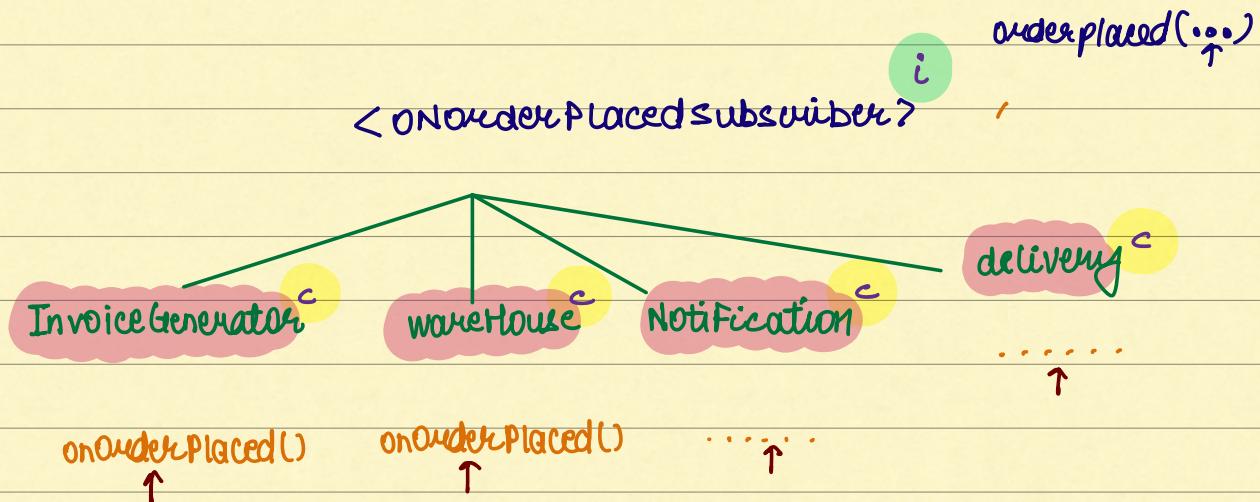
y

? ↗

What should be passed ??

Y

→ Create Interface & Implement in All subscribers.



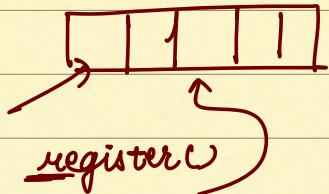
registerPlaceUnderSubscriber ( underplaced subscriber )

\* Advantages :

1. > Adding New subscriber is easy

Similarly; → Method should be added for  
⇒ unRegisterUnderplacedSubs()

3. > Registering subscriber

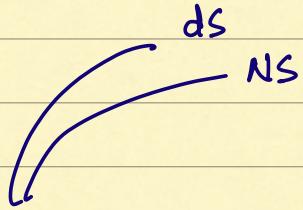


Q.) When subscriber should register themselves ?



Mostly, when object is created.

eg:



InvoiceGenerator Implements OPS 2

IG() 2

amazon.registerOPS(this);

IG(... ) 2

amazon.register(this);

}

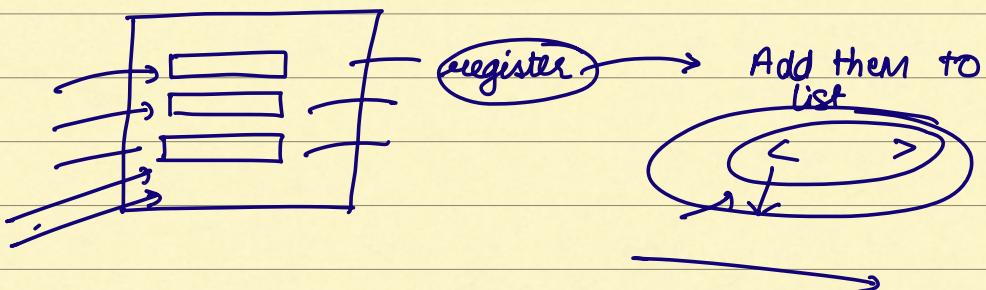
orderplaced(...) 2

y



EXTRA:

Can we Add / Remove subscriber on  
Runtime ?



(P)

(P) (S)

## Amazon ↴

- //  ① access all subscribers -  
② Publish

`list<Orderplacedsubscriber> list;`

`registerOrderPS ( ON orderp subs. s ) {`

`list.add (ops);`

↳



`orderplaced () {`

↳

`InvoiceGen .. Impl OPS`

`client xx`

→ `IG ig = new IGC(); // xx`



v



custom cons



⇒ register yourself

CINUX



SubscriberManager class 3

JOB/

CRON JOB

g

< >

CRON JOB →

