

Embedded Software

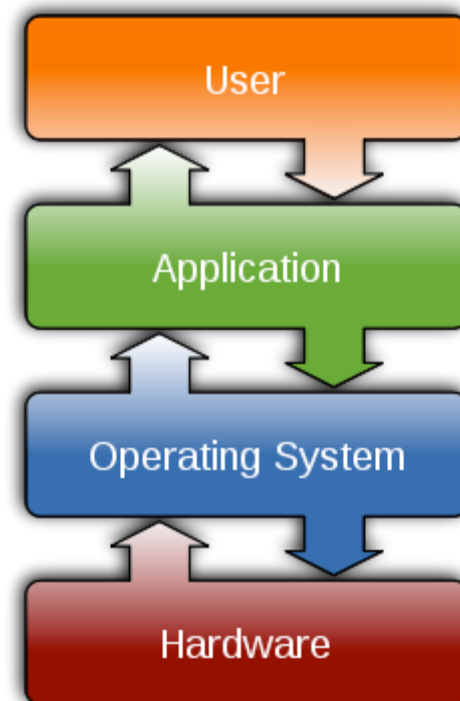
Introduction to operating systems

Agenda

- What is an operating system?
- OS structure
 - ▶ Process management
 - ▶ Memory and storage mgmt.
 - ▶ I/O subsystem
- Operating systems - Real-Time OS's

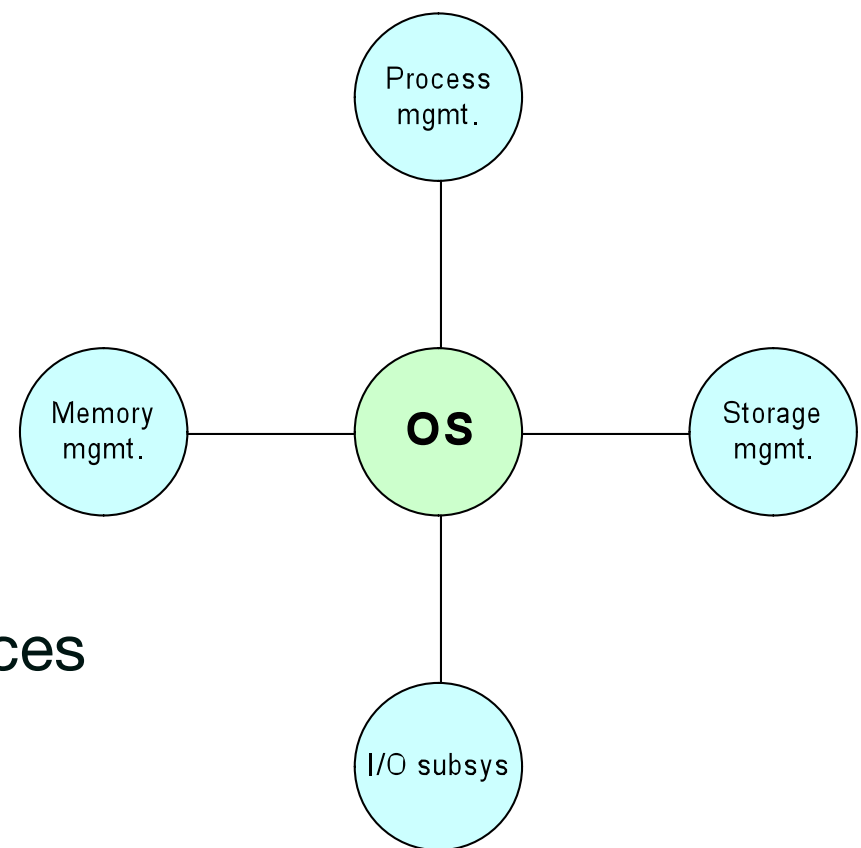
What is an operating system?

- What is an operating system?
 - ▶ Wikipedia: *“An operating system (OS) is software (...) that manages computer hardware resources and provides common services for efficient execution of various application software.”*



OS structure

- Many computer types – many OS designs
 - ▶ Mainframe OSs are optimized for HW utilization
 - ▶ Desktop OSs are optimized for generality
 - ▶ Embedded OSs are optimized for efficiency, size, safety, speed, low power
 - ▶ ...
- Some commonalities, though:
 - ▶ Process management – handles multiprogramming and keep the CPU busy
 - ▶ Memory management – (de)allocation and process swapping
 - ▶ Storage management – persistent storage and cache
 - ▶ I/O subsystem management – manage I/O devices
- Let's take a look at process management



OS structure - Process management

- ***What is a process? Is it a program?***

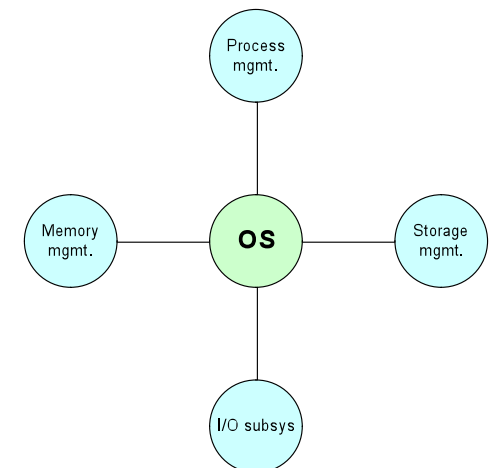
- ▶ No - a process is a program in execution

- ***How many processes can run at a time?***

- ▶ There can be many processes that want to run, but only one per CPU that actually runs

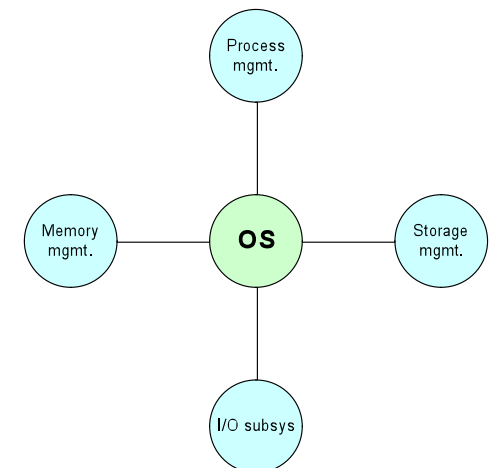
- The OS manages processes

- ▶ Creates, deletes, and allocates resources for them
- ▶ Swaps them in and out of memory
- ▶ Suspends and resumes them
- ▶ Provides mechanisms for synchronization and communication between processes



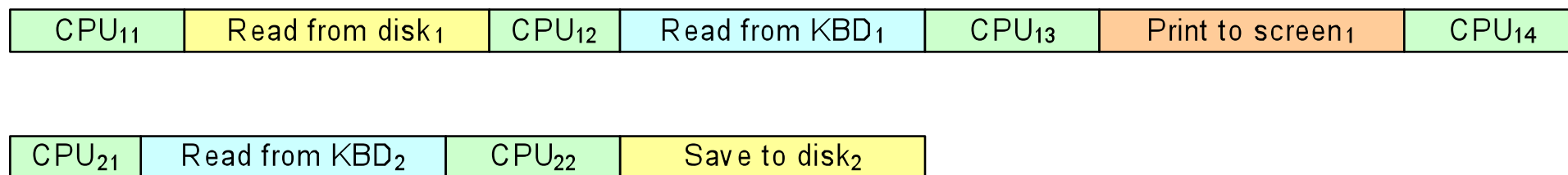
Process management – why?

- Processes either compute or perform device I/O
- ***What does a process do while it performs I/O?***
 - ▶ It must wait for I/O to complete before it can resume
- ***What should the system do meanwhile?***
 - ▶ Without process management: CPU idles
 - ▶ With process management: Switch to another ready process

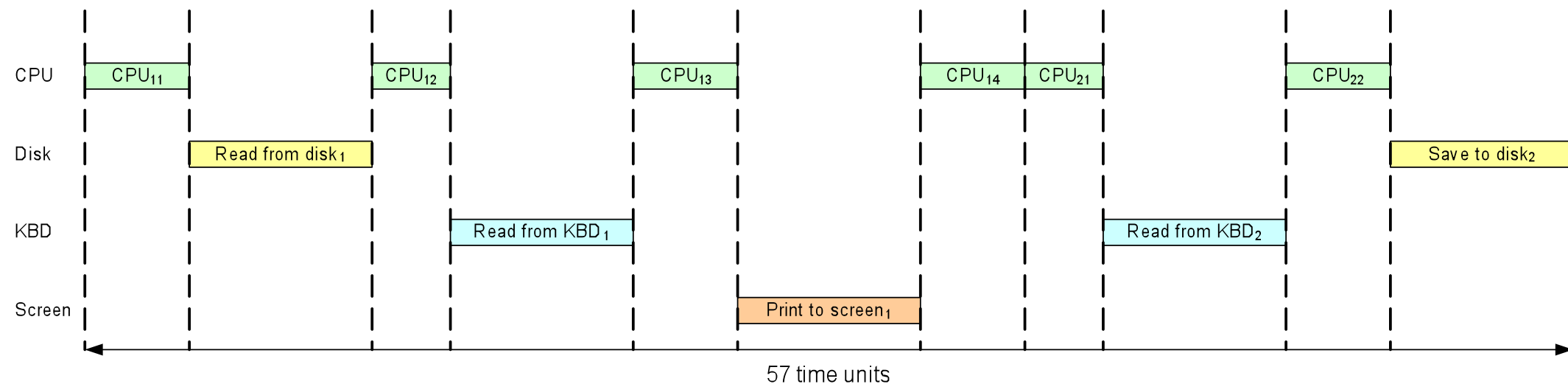


Process management - example

- Consider two tasks:

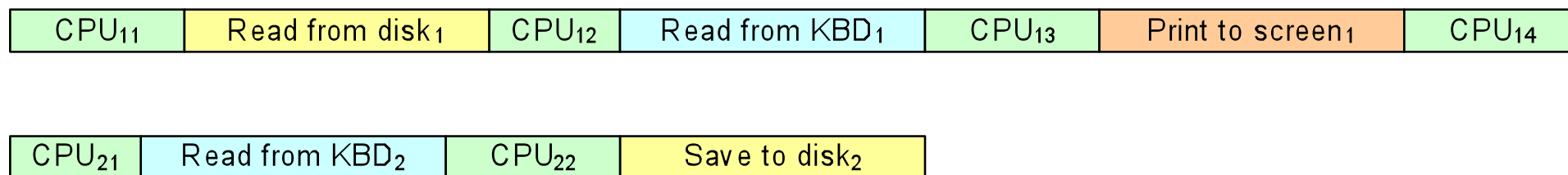


- Scheduling without resource management (batch processing)?***

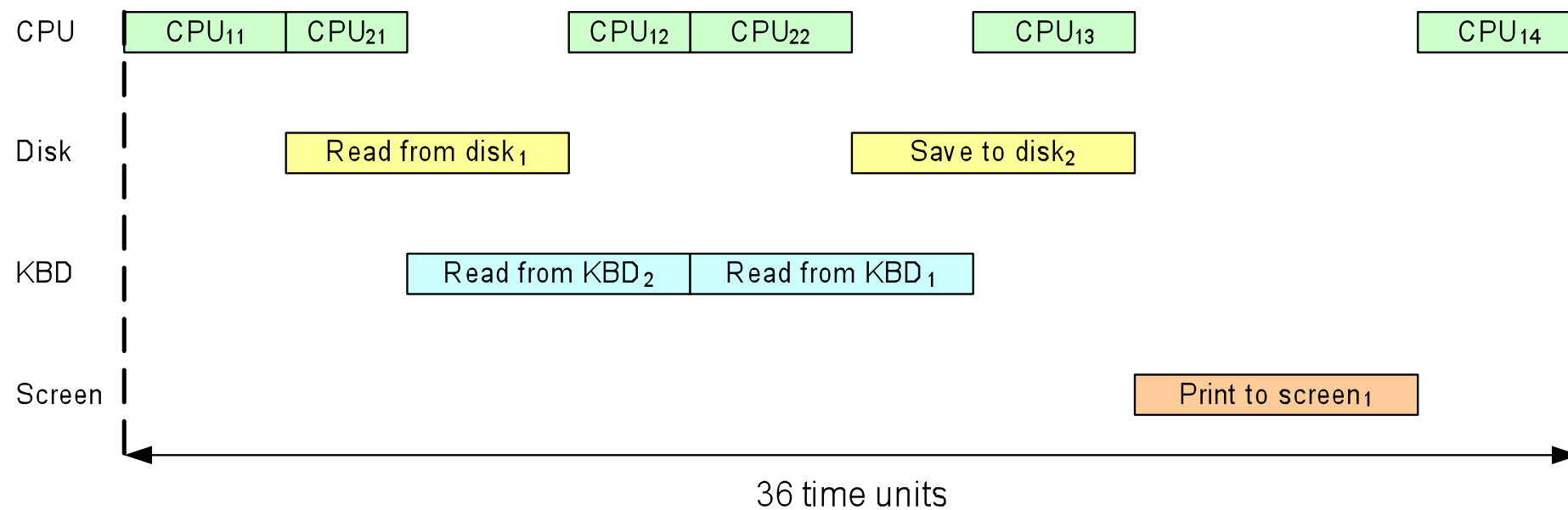


Process management - example

- Consider two tasks:



- Scheduling with resource management?***

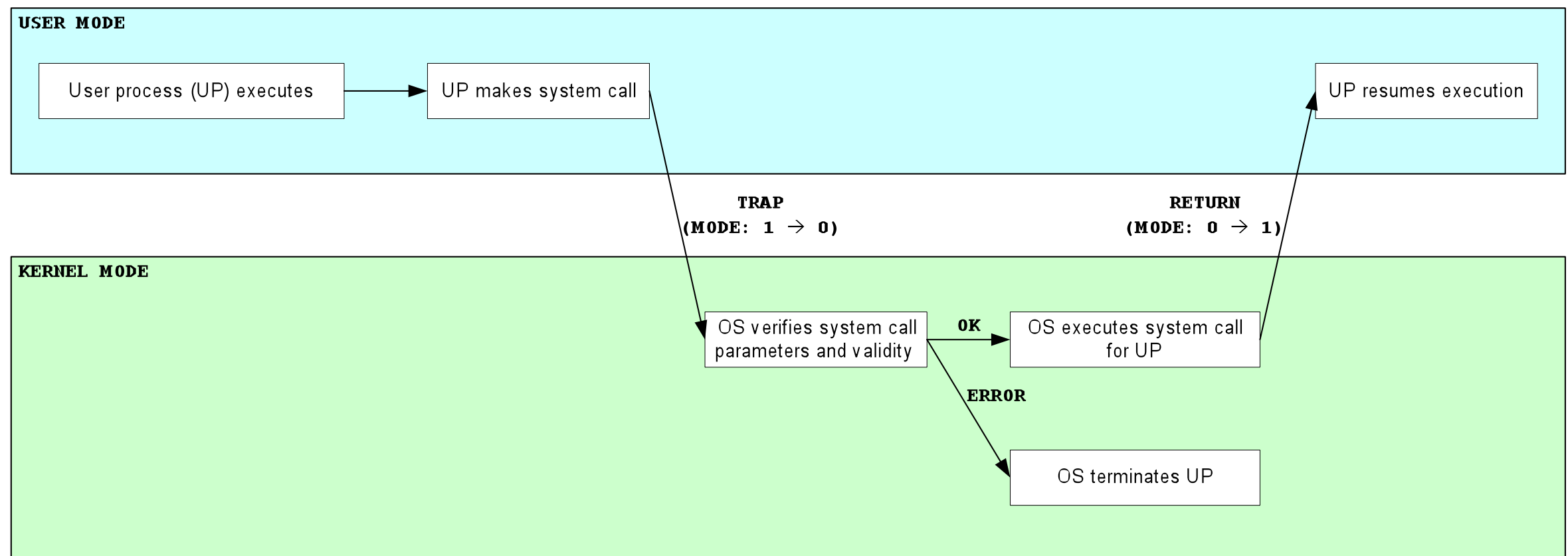


Process management - protection

- Consider an “evil” process – what damage could it do?
 - ▶ Destroy, eavesdrop on, change other processes
 - ▶ Destroy OS
 - ▶ Destroy files and HW
- The OS guards against this using dual-mode operation (MODE bit in CPU)
 - ▶ Applications run in user mode (AKA restricted mode)
 - ▶ The OS kernel runs in kernel mode (AKA protected, privileged, supervisor mode)
- Potentially dangerous operations (I/O, IPC, ...) can only be done via privileged instructions
 - ▶ Restricted instructions – user and kernel mode
 - ▶ Privileged instructions – kernel mode only

Dual-mode operation – system calls

- When processes need to perform I/O, it does so via the OS via well-defined **system calls** (version 2.6.35: 337 different syscalls)
- The OS (which is in kernel mode) verifies the system call and its parameters



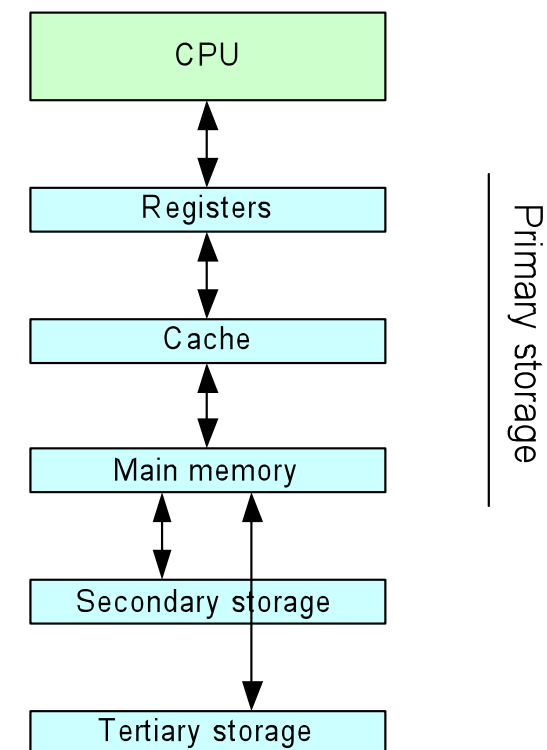
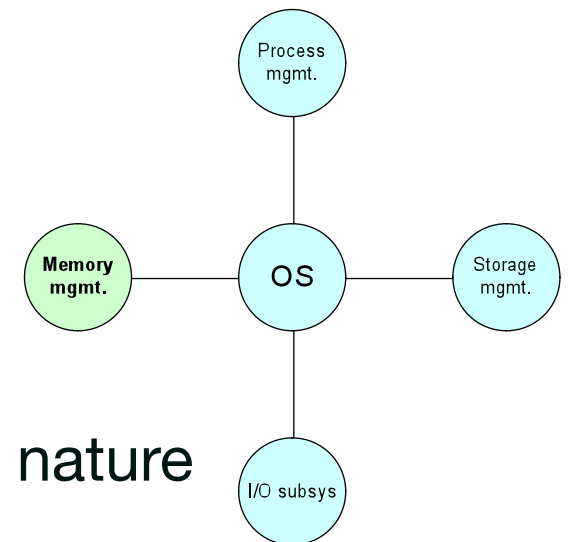
Dual-mode operation – system calls

- How often are system calls made?

```
$ ./hello  
Hello World!
```

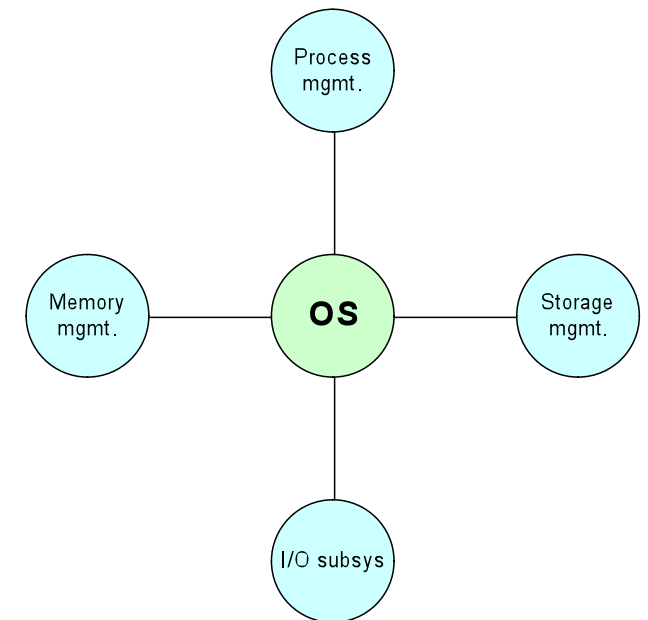
OS Structure - Memory and storage mgmt.

- Memory management
 - ▶ Keep track of several processes in memory at a time
 - ▶ Decide which (parts of) processes to move in and out of memory
 - ▶ Many different algorithms depending on hardware and the OS' nature
 - ▶ Allocate and deallocate memory as necessary
- Storage management
 - ▶ The primary storage is never big enough to accommodate all needs
 - ▶ A hierarchy of memory:
 - ▶ Size? Price (per MB)? Capacity? Bandwidth?
 - ▶ Move data in/out of hierarchy



OS Structure - I/O subsystem

- The I/O subsystem hides the oddities of individual I/O devices
- Instead, it provides a uniform interface (in Linux: a file)
 - ▶ The file is I/F to a device driver
 - ▶ The device driver knows how to operate the device



Operating systems - Real-Time OS's

- Real-Time Operating Systems (RTOSs) are OSs intended for RT systems (!)
- ***Some key properties?***
 - ▶ Minimum interrupt latency
 - ▶ Minimum task switching latency
 - ▶ Includes known worst case latency (must be small)
 - ▶ Static task priorities
- The programmer (you!) is responsible for correct priority assignment