# **Machine Language**

Make everything as simple as possible, but not simpler.

—Albert Einstein (1879-1955)

A computer can be described constructively, by laying out its hardware platform and explaining how it is built from low-level chips. A computer can also be described abstractly, by specifying and demonstrating its machine language capabilities. And indeed, it is convenient to get acquainted with a new computer system by first seeing some low-level programs written in its machine language. This helps us understand not only how to program the computer to do useful things, but also why its hardware was designed in a certain way. With that in mind, this chapter focuses on low-level programming in machine language. This sets the stage for chapter 5, where we complete the construction of a general-purpose computer designed to run machine language programs. This computer will be constructed from the chip set built in chapters 1-3.

A machine language is an agreed-upon formalism, designed to code low-level programs as series of machine instructions. Using these instructions, the programmer can command the processor to perform arithmetic and logic operations, fetch and store values from and to the memory, move values from one register to another, test Boolean conditions, and so on. As opposed to high-level languages, whose basic design goals are generality and power of expression, the goal of machine language's design is direct execution in, and total control of, a given hardware platform. Of course, generality, power, and elegance are still desired, but only to the extent that they support the basic requirement of direct execution in hardware.

Machine language is the most profound interface in the overall computer enterprise—the fine line where hardware and software meet. This is the point where the abstract thoughts of the programmer, as manifested in symbolic instructions, are turned into physical operations performed in silicon. Thus, machine language can be construed as both a programming tool and an integral part of the hardware platform. In fact, just as we say that the machine language is designed to exploit a given hardware platform, we can say that the hardware platform is designed to fetch, interpret, and execute instructions written in the given machine language.

The chapter begins with a general introduction to machine language programming. Next, we give a detailed specification of the Hack machine language, covering both its binary and its symbolic assembly versions. The project that ends the chapter engages you in writing a couple of machine language programs. This project offers a hands-on appreciation of low-level programming and prepares you for building the computer itself in the next chapter.

Although most people will never write programs directly in machine language, the study of low-level programming is a prerequisite to a complete understanding of computer architectures. Also, it is rather fascinating to realize how the most sophisticated software systems are, at bottom, long series of



# 4.1 Background

This chapter is language-oriented. Therefore, we can abstract away most of the details of the underlying hardware platform, deferring its description to the next chapter. Indeed, to give a general description of machine languages, it is sufficient to focus on three main abstractions only: a processor, a memory, and a set of registers.

#### 4.1.1 Machines

A *machine language* can be viewed as an agreed-upon formalism, designed to manipulate a memory using a processor and a set of registers.

**Memory** The term *memory* refers loosely to the collection of hardware devices that store data and instructions in a computer. From the programmer's standpoint, all memories have the same structure: A continuous array of cells of some fixed width, also called words or locations, each having a unique address. Hence, an individual word (representing either a data item or an instruction) is specified by supplying its address. In what follows we will refer to such individual words using the equivalent notation Memory[address], RAM[address], or M[address] for brevity.

**Processor** The processor, normally called Central Processing Unit or CPU, is a device capable of performing a fixed set of elementary operations. These typically include arithmetic and logic operations, memory access operations, and control (also called branching) operations. The operands of these operations are binary values that come from registers and selected memory locations. Likewise, the results of the operations (the processor's output) can be stored either in registers or in selected memory locations.

**Registers** Memory access is a relatively slow operation, requiring long instruction formats (an address may require 32 bits). For this reason, most processors are equipped with several registers, each capable of holding a single value. Located in the processor's immediate proximity, the registers serve as a high-speed local memory, allowing the processor to manipulate data and instructions quickly. This setting enables the programmer to minimize the use of memory access commands, thus speeding up the program's execution.

## 4.1.2 Languages

A machine language program is a series of coded instructions. For example, a typical instruction in a 16-bit computer may be 1010001100011001. In order to figure out what this instruction means, we have to know the rules of the game, namely, the instruction set of the underlying hardware platform. For example, the language may be such that each instruction consists of four 4-bit fields: The left-most field codes a CPU operation, and the remaining three fields represent the operation's operands. Thus the previous command may code the operation set R3 to R1 + R9, depending of course on the hardware specification and the machine language syntax.

Since binary codes are rather cryptic, machine languages are normally specified using both binary codes and symbolic mnemonics (a mnemonic is a symbolic label whose name hints at what it stands for—in our case hardware elements and binary operations). For example, the language designer can decide that the operation code 1010 will be represented by the mnemonic add and that the registers of the machine will be symbolically referred to using the symbols R0, R1, R2, and so forth. Using these conventions, one can specify machine language instructions either directly, as 1010001100011001, or symbolically, as, say, ADD R3,R1,R9.

Taking this symbolic abstraction one step further, we can allow ourselves not only to read symbolic notation, but to actually write programs using symbolic commands rather than binary instructions. Next, we can use a text processing program to parse the symbolic commands into their underlying fields (mnemonics and operands), translate each field into its equivalent binary representation, and assemble the resulting codes into binary machine instructions. The symbolic notation is called assembly language, or simply assembly, and the program that translates from assembly to binary is called assembler.

Since different computers vary in terms of CPU operations, number and type of registers, and assembly syntax rules, there is a Tower of Babel of machine languages, each with its own obscure syntax. Yet irrespective of this variety, all machine languages support similar sets of generic commands, which we now describe.

#### 4.1.3 Commands

**Arithmetic and Logic Operations** Every computer is required to perform basic arithmetic operations like addition and subtraction as well as basic Boolean operations like bit-wise negation, bit shifting, and so forth. Here are some examples, written in typical machine language syntax:

```
ADD R2,R1,R3 // R2←R1+R3 where R1,R2,R3 are registers

ADD R2,R1,foo // R2←R1+foo where foo stands for the

// value of the memory location pointed

// at by the user-defined label foo.

AND R1,R1,R2 // R1←bit wise And of R1 and R2
```

**Memory Access** Memory access commands fall into two categories. First, as we have just seen, arithmetic and logical commands are allowed to operate not only on registers, but also on selected memory locations. Second, all computers feature explicit load and store commands, designed to move data between registers and memory. These memory access commands may use several types of addressing *modes*—ways of specifying the address of the required memory word. As usual, different computers offer different possibilities and different notations, but the following three memory access modes are almost always supported:

■ *Direct addressing* The most common way to address the memory is to express a specific address or use a symbol that refers to a specific address, as follows:

```
LOAD R1,67 // R1←Memory[67]

// Or, assuming that bar refers to memory address 67:

LOAD R1,bar // R1←Memory[67]
```

■ *Immediate addressing* This form of addressing is used to load constants—namely, load values that appear in the instruction code: Instead of treating the numeric field that appears in the instruction as an address, we simply load the value of the field itself into the register, as follows:

```
LOADI R1,67 // R1←67
```

■ *Indirect addressing* In this addressing mode the address of the required memory location is not hard-coded into the instruction; instead, the instruction specifies a memory location that holds the required address. This addressing mode is used to handle pointers. For example, consider the high-level command x=foo[j], where foo is an array variable and x and j are integer variables. What is the machine language equivalent of this command? Well, when the array foo is declared and initialized in the high-level

program, the compiler allocates a memory segment to hold the array data and makes the symbol foo refer to the base address of that segment.

Now, when the compiler later encounters references to array cells like foo[j], it translates them as follows. First, note that the jth array entry should be physically located in a memory location that is at a displacement j from the array's base address (assuming, for simplicity, that each array element uses a single word). Hence the address corresponding to the expression foo[j] can be easily calculated by adding the value of j to the value of foo. Thus in the C programming language, for example, a command like x=foo[j] can be also expressed as x=\*(foo+j), where the notation "\*n" stands for "the value of Memory[n]". When translated into machine language, such commands typically generate the following code (depending on the assembly language syntax):

```
// Translation of x=foo[j] or x=*(foo+j):
ADD R1,foo,j // R1←foo+j
LOAD* R2,R1 // R2←Memory[R1]
STR R2,x // x←R2
```

Flow of Control While programs normally execute in a linear fashion, one command after the other, they also include occasional branches to locations other than the next command. Branching serves several purposes including repetition (jump backward to the beginning of a loop), conditional execution (if a Boolean condition is false, jump forward to the location after the "if-then" clause), and subroutine calling (jump to the first command of some other code segment). In order to support these programming constructs, every machine language features the means to jump to selected locations in the program, both conditionally and unconditionally. In assembly languages, locations in the program can also be given symbolic names, using some syntax for specifying labels. Figure 4.1 illustrates a typical example.

```
High-level

// A while loop:
while (R1>=0) {
    code segment 1
}

code segment 2

// Typical translation:
beginWhile:

JNG R1,endWhile // If R1<0 goto endWhile

// Translation of code segment 1 comes here

JMP beginWhile // Goto beginWhile
endWhile:

// Translation of code segment 2 comes here
```

**Figure 4.1** High- and low-level branching logic. The syntax of goto commands varies from one language to another, but the basic idea is the same.

Unconditional jump commands like JMP beginWhile specify only the address of the target location. Conditional jump commands like JNG R1, endWhile must also specify a Boolean condition, expressed in some way. In some languages the condition is an explicit part of the command, while in others it is a byproduct of executing a previous command.

This ends our informal introduction to machine languages and the generic operations that they normally support. The next section gives a formal description of one specific machine language—the native code of the computer that we will build in chapter 5.

**4.2 Hack Machine Language Specification** 

#### 4.2.1 Overview

The Hack computer is a von Neumann platform. It is a 16-bit machine, consisting of a CPU, two separate memory modules serving as instruction memory and data memory, and two memory-mapped I/O devices: a screen and a keyboard.

**Memory Address Spaces** The Hack programmer is aware of two distinct address spaces: an instruction memory and a data memory. Both memories are 16-bit wide and have a 15-bit address space, meaning that the maximum addressable size of each memory is 32K 16-bit words.

The CPU can only execute programs that reside in the instruction memory. The instruction memory is a read-only device, and programs are loaded into it using some exogenous means. For example, the instruction memory can be implemented in a ROM chip that is pre-burned with the required program. Loading a new program is done by replacing the entire ROM chip, similar to replacing a cartridge in a game console. In order to simulate this operation, hardware simulators of the Hack platform must provide a means to load the instruction memory from a text file containing a machine language program.

**Registers** The Hack programmer is aware of two 16-bit registers called D and A. These registers can be manipulated explicitly by arithmetic and logical instructions like A=D-1 or D=!A (where "!" means a 16-bit Not operation). While D is used solely to store data values, A doubles as both a data register and an address register. That is to say, depending on the instruction context, the contents of A can be interpreted either as a data value, or as an address in the data memory, or as an address in the instruction memory, as we now explain.

First, the A register can be used to facilitate direct access to the data memory (which, from now on, will be often referred to as "memory"). Since Hack instructions are 16-bit wide, and since addresses are specified using 15 bits, it is impossible to pack both an operation code and an address in one instruction. Thus, the syntax of the Hack language mandates that memory access instructions operate on an implicit memory location labeled "M", for example, D=M+1. In order to resolve this address, the convention is that M always refers to the memory word whose address is the current value of the A register. For example, if we want to effect the operation D = Memory[516] - 1, we have to use one instruction to set the A register to 516, and a subsequent instruction to specify D=M-1.

In addition, the hardworking A register is also used to facilitate direct access to the instruction memory. Similar to the memory access convention, Hack jump instructions do not specify a particular address. Instead, the convention is that any jump operation always effects a jump to the instruction located in the memory word addressed by A. Thus, if we want to effect the operation goto 35, we use one instruction to set A to 35, and a second instruction to code a goto command, without specifying an address. This sequence causes the computer to fetch the instruction located in InstructionMemory[35] in the next clock cycle.

**Example** Since the Hack language is self-explanatory, we start with an example. The only non-obvious command in the language is @value, where value is either a number or a symbol representing a number. This command simply stores the specified value in the A register. For example, if sum refers to memory

location 17, then both @17 and @sum will have the same effect:  $A \leftarrow 17$ .

And now to the example: Suppose we want to add the integers 1 to 100, using repetitive addition. Figure 4.2 gives a C language solution and a possible compilation into the Hack language.

Although the Hack syntax is more accessible than that of most machine languages, it may still look obscure to readers who are not familiar with low-level programming. In particular, note that every operation involving a memory location requires two Hack commands: One for selecting the address on which we want to operate, and one for specifying the desired operation. Indeed, the Hack language consists of two generic instructions: an address instruction, also called A-instruction, and a compute instruction, also called C -instruction. Each instruction has a binary representation, a symbolic representation, and an effect on the computer, as we now specify.

#### 4.2.2 The A-Instruction

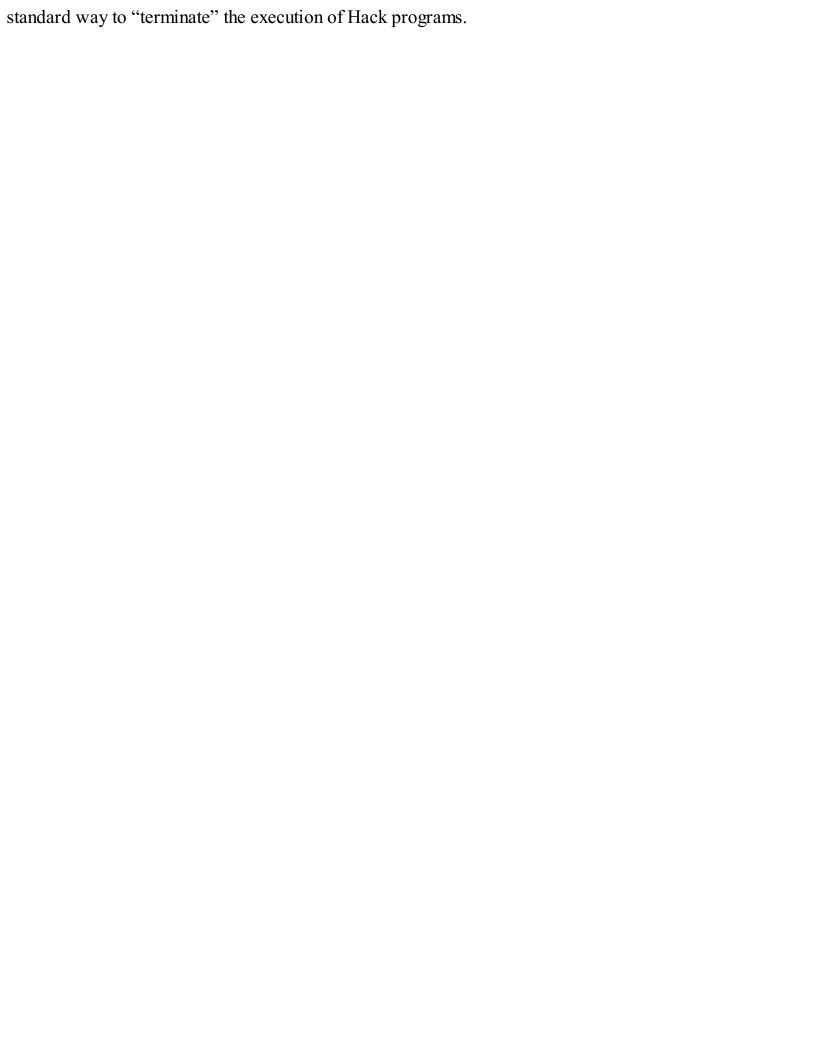
The A-instruction is used to set the A register to a 15-bit value:

This instruction causes the computer to store the specified value in the A register. For example, the instruction @ 5, which is equivalent to 00000000000101, causes the computer to store the binary representation of 5 in the A register.

The *A*-instruction is used for three different purposes. First, it provides the only way to enter a constant into the computer under program control. Second, it sets the stage for a subsequent *C*-instruction designed to manipulate a certain data memory location, by first setting A to the address of that location. Third, it sets the stage for a subsequent *C*-instruction that specifies a jump, by first loading the address of the jump destination to the A register. These uses are demonstrated in figure 4.2.

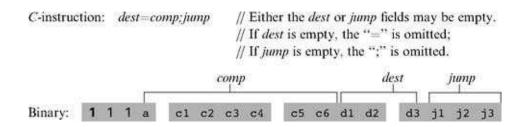
```
C language
                       Hack machine language
 // Adds 1+...+100.
                        // Adds 1+...+100.
  int i = 1;
                               #i // i refers to some mem. location.
  int sum = 0;
   While (i <= 100) (
                                      // sum refers to some mem. location.
     sum += i;
                                      // sum=0
     i++;
                         (LOOP)
                                      // D=i
                               D=M
                               £100
                               D=D-A // D=i-100
                               D:JGT // If (i-100)>0 goto END
                               ei
                               D=M
                                      // D=i
                               Ssum
                               M=D+M // sum=sum+i
                               êi
                               M=M+1 // i=i+1
                                @LOOP
                               0;JMP // Goto LOOP
                          (END)
                               @END
                               0;JMP // Infinite loop
```

Figure 4.2 C and assembly versions of the same program. The infinite loop at the program's end is our



#### 4.2.3 The *C*-Instruction

The *C*-instruction is the programming workhorse of the Hack platform—the instruction that gets almost everything done. The instruction code is a specification that answers three questions: (a) what to compute, (b) where to store the computed value, and (c) what to do next? Along with the *A*-instruction, these specifications determine all the possible operations of the computer.



The leftmost bit is the *C*-instruction code, which is 1. The next two bits are not used. The remaining bits form three fields that correspond to the three parts of the instruction's symbolic representation. The overall semantics of the symbolic instruction *dest* = comp; jump is as follows. The comp field instructs the ALU what to compute. The dest field instructs where to store the computed value (ALU output). The jump field specifies a jump condition, namely, which command to fetch and execute next. We now describe the format and semantics of each of the three fields.

**The Computation Specification** The Hack ALU is designed to compute a fixed set of functions on the D, A, and M registers (where M stands for Memory[A]). The computed function is specified by the a-bit and the six c-bits comprising the instruction's comp field. This 7-bit pattern can potentially code 128 different functions, of which only the 28 listed in figure 4.3 are documented in the language specification.

Recall that the format of the *C*-instruction is 111a cccc ccdd djjj. Suppose we want to have the ALU compute D-1, the current value of the D register minus 1. According to figure 4.3, this can be done by issuing the instruction 111**0 0011 10**00 0000 (the 7-bit operation code is in bold). To compute the value of D|M, we issue the instruction 111**1 0101 01**00 0000. To compute the constant-1, we issue the instruction 111**0 1110 10**00 0000, and so on.

**The Destination Specification** The value computed by the comp part of the *C*-instruction can be stored in several destinations, as specified by the instruction's 3-bit dest part (see figure 4.4). The first and second d-bits code whether to store the computed value in the A register and in the D register, respectively. The third d-bit codes whether to store the computed value in M (i.e., in Memory[A]). One, more than one, or none of these bits may be asserted.

(when a=0) comp mnemonic	cl	c2	<b>c</b> 3	c4	c5	c6	(when a=1) comp mnemonic
0	1	0	1.	0	1	0	
1	1	1	1	1	1	1	
-1	1	1	1	0	1	0	
D	0	0	1	1	0	0	
A	1	1	0	0	0	0 0 1	M
I D	0	0	1	1	0	1	
1A	1	1	0	0	0	1	1 M
-D	0	0	1	1	1	1	
-A	1	1	0	0	1	1 1 1	-M
D+1	0	1	0	0 1 1	1 1	1	
A+1	1	1	0	1	1	1	M+1
D-1	0	0	1	1	1	0	
A-1	1	1	0	0	1	0	M-1
D+A	0	0	0	0	1	0 0 1	D+M
D-A	0	1	0	0	1 1 1	1	D-M
A-D	0	0	0	1	1	1	M-D
D&A	0	0	0	0	0	0	D&M
DIA	0	1	0	1	0	1	DIM

**Figure 4.3** The compute field of the *C*-instruction. D and A are names of registers. M refers to the memory location addressed by A, namely, to Memory[A]. The symbols + and - denote 16-bit 2's complement addition and subtraction, while !, |, and & denote the 16-bit bit-wise Boolean operators Not, Or, and And, respectively. Note the similarity between this instruction set and the ALU specification given in figure 2.6.

Recall that the format of the *C*-instruction is 111a cccc ccdd djjj. Suppose we want the computer to increment the value of Memory[7] by 1 and to also store the result in the D register. According to figures 4.3 and 4.4, this can be accomplished by the following instructions:

```
0000 0000 0000 0111 // @7
1111 1101 1101 1000 // MD=M+1
```

d1	d2	d3	Mnemonic	Destination (where to store the computed value)
0	0	0	null	The value is not stored anywhere
0	0	1	M	Memory[A] (memory register addressed by A)
0	1	0	D	D register
0	1	1	MD	Memory[A] and D register
1	0	0	A	A register
1	0	1	AM	A register and Memory[A]
1	1	0	AD	A register and D register
1	1	1	AMD	A register, Memory[A], and D register

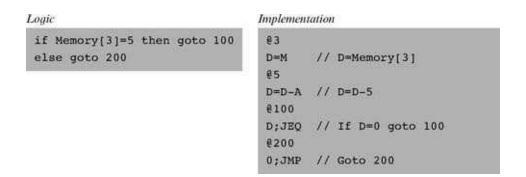
**Figure 4.4** The dest field of the *C*-instruction.

The first instruction causes the computer to select the memory register whose address is 7 (the so-called M register). The second instruction computes the value of M + 1 and stores the result in both M and D.

**The Jump Specification** The *jump* field of the *C*-instruction tells the computer what to do next. There are two possibilities: The computer should either fetch and execute the next instruction in the program, which is the default, or it should fetch and execute an instruction located elsewhere in the program. In the latter case, we assume that the A register has been previously set to the address to which we have to jump.

Whether or not a jump should actually materialize depends on the three j-bits of the jump field and on the ALU output value (computed according to the comp field). The first j-bit specifies whether to jump in case this value is negative, the second j-bit in case the value is zero, and the third j-bit in case it is positive. This gives eight possible jump conditions, shown in figure 4.5.

The following example illustrates the jump commands in action:



<b>j1</b> (out < 0)	$\mathbf{j2}$ $(out=0)$	j3 $(out > 0)$	Mnemonic	Effect
0	0	0	nul1	No jump
0	0	1	JGT	If $out > 0$ jump
0	1	0	JEQ	If $out = 0$ jump
0	1	1	JGE	If $out \ge 0$ jump
1	0	0	JLT	If $out < 0$ jump
1	0	1	JNE	If $out \neq 0$ jump
1	1	0	JLE	If $out \leq 0$ jump
1	1	1	JMP	Jump

**Figure 4.5** The *jump* field of the *C*-instruction. *Out* refers to the ALU output (resulting from the instruction's comp part), and jump implies "continue execution with the instruction addressed by the A register."

The last instruction (0; JMP) effects an unconditional jump. Since the *C*-instruction syntax requires that we always effect some computation, we instruct the ALU to compute 0 (an arbitrary choice), which is ignored.

**Conflicting Uses of the A Register** As was just illustrated, the programmer can use the A register to select either a data memory location for a subsequent *C*-instruction involving M, or an instruction memory location for a subsequent *C*-instruction involving a jump. Thus, to prevent conflicting use of the A register, in well-written programs a *C*-instruction that may cause a jump (i.e., with some non-zero j bits) should not contain a reference to M, and vice versa.

## **4.2.4 Symbols**

Assembly commands can refer to memory locations (addresses) using either constants or symbols. Symbols are introduced into assembly programs in the following three ways:

- *Predefined symbols:* A special subset of RAM addresses can be referred to by any assembly program using the following predefined symbols:
- *Virtual registers:* To simplify assembly programming, the symbols R0 to R15 are predefined to refer to RAM addresses 0 to 15, respectively.
- *Predefined pointers:* The symbols SP, LCL, ARG, THIS, and THAT are predefined to refer to RAM addresses 0 to 4, respectively. Note that each of these memory locations has two labels. For example, address 2 can be referred to using either R2 or ARG. This syntactic convention will come to play in the implementation of the virtual machine, discussed in chapters 7 and 8.
- *I/O pointers:* The symbols SCREEN and KBD are predefined to refer to RAM addresses 16384 (0x4000) and 24576 (0x6000), respectively, which are the base addresses of the screen and keyboard memory maps. The use of these I/O devices is explained later.
- Label symbols: These user-defined symbols, which serve to label destinations of goto commands, are declared by the pseudo-command "(Xxx)". This directive defines the symbol Xxx to refer to the instruction memory location holding the next command in the program. A label can be defined only once and can be used anywhere in the assembly program, even before the line in which it is defined.
- *Variable symbols*: Any user-defined symbol Xxx appearing in an assembly program that is not predefined and is not defined elsewhere using the "(Xxx)" command is treated as a variable, and is assigned a unique memory address by the assembler, starting at RAM address 16 (0x0010).

## 4.2.5 Input/Output Handling

The Hack platform can be connected to two peripheral devices: a screen and a keyboard. Both devices interact with the computer platform through memory maps. This means that drawing pixels on the screen is achieved by writing binary values into a memory segment associated with the screen. Likewise, listening to the keyboard is done by reading a memory location associated with the keyboard. The physical I/O devices and their memory maps are synchronized via continuous refresh loops.

**Screen** The Hack computer includes a black-and-white screen organized as 256 rows of 512 pixels per row. The screen's contents are represented by an 8K memory map that starts at RAM address 16384 (0x4000). Each row in the physical screen, starting at the screen's top left corner, is represented in the RAM by 32 consecutive 16-bit words. Thus the pixel at row r from the top and column c from the left is mapped on the c%16 bit (counting from LSB to MSB) of the word located at RAM[16384 + r · 32 + c/16]. To write or read a pixel of the physical screen, one reads or writes the corresponding bit in the RAM-resident memory map (1 = black, 0 = white). Example:

**Keyboard** The Hack computer interfaces with the physical keyboard via a single-word memory map located in RAM address 24576 (0x6000). Whenever a key is pressed on the physical keyboard, its 16-bit ASCII code appears in RAM[24576]. When no key is pressed, the code 0 appears in this location. In addition to the usual ASCII codes, the Hack keyboard recognizes the keys shown in figure 4.6.

#### 4.2.6 Syntax Conventions and File Format

**Binary Code Files** A binary code file is composed of text lines. Each line is a sequence of sixteen "0" and "1" ASCII characters, coding a single machine language instruction. Taken together, all the lines in the file represent a machine language program. The contract is such that when a machine language program is loaded into the computer's instruction memory, the binary code represented by the file's *n*th line is stored in address n of the instruction memory (the count of both program lines and memory addresses starts at 0). By convention, machine language programs are stored in text files with a "hack" extension, for example, Prog. hack.

**Assembly Language Files** By convention, assembly language programs are stored in text files with an "asm" extension, for example, Prog.asm. An assembly language file is composed of text lines, each representing either an instruction or a symbol *declaration:* 

Key pressed	Code	Key pressed	Code
newline	128	end	135
backspace	129	page up	136
left arrow	130	page down	137
up arrow	131	insert	138
right arrow	132	delete	139
down arrow	133	esc	140
home	134	f1-f12	141-15

Figure 4.6 Special keyboard codes in the Hack platform.

- *Instruction*: an *A*-instruction or a *C*-instruction.
- (Symbol): This pseudo-command causes the assembler to assign the label Symbol to the memory location in which the next command of the program will be stored. It is called "pseudo-command" since it generates no machine code.

(The remaining conventions in this section pertain to assembly programs only.)

**Constants and Symbols** *Constants* must be non-negative and are always written in decimal notation. A user-defined symbol can be any sequence of letters, digits, underscore (\_), dot (.), dollar sign (\$), and colon (:) that does not begin with a digit.

Comments Text beginning with two slashes (//) and ending at the end of the line is considered a comment

and is ignored.

White Space Space characters are ignored. Empty lines are ignored.

**Case Conventions** All the assembly mnemonics must be written in uppercase. The rest (user-defined labels and variable names) is case sensitive. The convention is to use uppercase for labels and lowercase for variable names.

# 4.3 Perspective

The Hack machine language is almost as simple as machine languages get. Most computers have more instructions, more data types, more registers, more instruction formats, and more addressing modes. However, any feature not supported by the Hack machine language may still be implemented in software, at a performance cost. For example, the Hack platform does not supply multiplication and division as primitive machine language operations. Since these operations are obviously required by any high-level language, we will later implement them at the operating system level (chapter 12).

In terms of syntax, we have chosen to give Hack a somewhat different look-and-feel than the mechanical nature of most assembly languages. In particular, we have chosen a high-level language-like syntax for the *C*-command, for example, D=M and D=D+M instead of the more traditional LOAD and ADD directives. The reader should note, however, that these are just syntactic details. For example, the + character plays no algebraic role whatsoever in the command D=D+M. Rather, the three-character string D+M, taken as a whole, is treated as a single assembly mnemonic, designed to code a single ALU operation.

One of the main characteristics that gives machine languages their particular flavor is the number of memory addresses that can appear in a single command. In this respect, Hack may be described as a "saddress machine": Since there is no room to pack both an instruction code and a 15-bit address in the 16-bit instruction format, operations involving memory access will normally be specified in Hack using two instructions: an A-instruction to specify the address and a C-instruction to specify the operation. In comparison, most machine languages can directly specify at least one address in every machine instruction.

Indeed, Hack assembly code typically ends up being (mostly) an alternating sequence of A- and C-instructions, for example, @xxx followed by D=D+M, @YYY followed by 0; JMP, and so on. If you find this coding style tedious or even peculiar, you should note that friendlier macro commands like D=D+M[xxx] and GOTO YYY can easily be introduced into the language, causing Hack assembly code to be more readable as well as about 50 percent shorter. The trick is to have the assembler translate these macro commands into binary code effecting @xxx followed by D=D+M,@YYY followed by 0; JMP, and so on.

The assembler, mentioned several times in this chapter, is the program responsible for translating symbolic assembly programs into executable programs written in binary code. In addition, the assembler is responsible for managing all the system- and user-defined symbols found in the assembly program, and for replacing them with physical memory addresses, as needed. We return to this translation task in chapter 6, in which we build an assembler for the Hack language.

# 4.4 Project

**Objective** Get a taste of low-level programming in machine language, and get acquainted with the Hack computer platform. In the process of working on this project, you will also become familiar with the assembly process, and you will appreciate visually how the translated binary code executes on the target hardware.

**Resources** In this project you will use two tools supplied with the book: An assembler, designed to translate Hack assembly programs into binary code, and a CPU emulator, designed to run binary programs on a simulated Hack platform.

**Contract** Write and test the two programs described in what follows. When executed on the CPU emulator, your programs should generate the results mandated by the test scripts supplied in the project directory.

- Multiplication Program (Mult.asm): The inputs of this program are the current values stored in R0 and R1 (i.e., the two top RAM locations). The program computes the product R0\*R1 and stores the result in R2. We assume (in this program) that R0>=0, R1>=0, and R0\*R1<32768. Your program need not test these conditions, but rather assume that they hold. The supplied Mult.tst and Mult.cmp scripts will test your program on several representative data values.
- *I/O-Handling Program* (Fill.asm): This program runs an infinite loop that listens to the keyboard input. When a key is pressed (any key), the program blackens the screen, namely, writes "black" in every pixel. When no key is pressed, the screen should be cleared. You may choose to blacken and clear the screen in any spatial order, as long as pressing a key continuously for long enough will result in a fully blackened screen and not pressing any key for long enough will result in a cleared screen. This program has a test script (Fill.tst) but no compare file—it should be checked by visibly inspecting the simulated screen.

## **Steps** We recommend proceeding as follows:

- 0. The assembler and CPU emulator programs needed for this project are available in the tools directory of the book's software suite. Before using them, go through the assembler tutorial and the CPU emulator tutorial.
- 1. Use a plain text editor to write the first program in assembly, and save it as projects/04/mult/Mult.asm.
- 2. Use the supplied assembler (in either batch or interactive mode) to translate your program. If you get syntax errors, go to step 1. If there are no syntax errors, the assembler will produce a file called projects/04/mult/Mult.hack, containing binary machine instructions.
- 3. Use the supplied CPU emulator to test the resulting Mult.hack code. This can be done either

interactively, or batch-style using the supplied Mult.tst script. If you get run-time errors, go to step 1.

4. Repeat stages 1-3 for the second program (Fill.asm), using the projects/04/ fill directory.

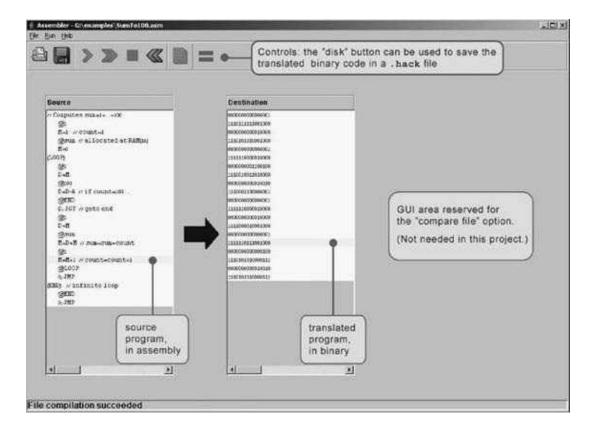
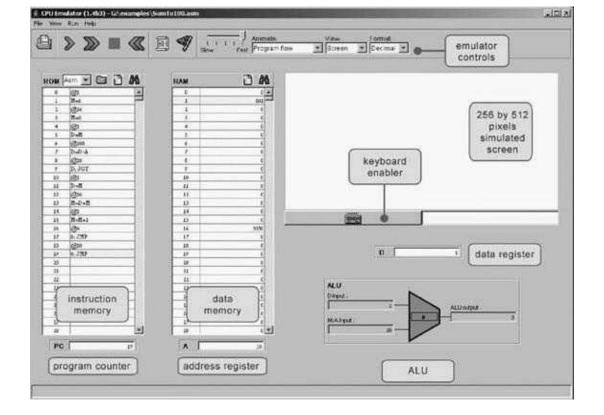


Figure 4.7 The visual assembler supplied with the book.

**Debugging Tip** The Hack language is case sensitive. A common error occurs when one writes, say, @foo and @Foo in different parts of the program, thinking that both commands refer to the same variable. In fact, the assembler treats these symbols as two completely different identifiers.

**The Supplied Assembler** The book's software suite includes a Hack assembler that can be used in either command mode or GUI mode. The latter mode of operation allows observing the translation process in a visual and step-wise fashion, as shown in figure 4.7.

The machine language programs produced by the assembler can be tested in two different ways. First, one can run the .hack program in the CPU emulator. Alternatively, one can run the same program directly on the hardware, by loading it into the computer's instruction memory using the hardware simulator. Since we will finish building the hardware platform only in the next chapter, the former option makes more sense at this stage.



**Figure 4.8** The CPU emulator supplied with the book. The loaded program can be displayed either in symbolic notation (as shown in this screen shot) or in binary code. The screen and the keyboard are not used by this particular program.

**The Supplied CPU Emulator** This program simulates the Hack computer platform. It allows loading a Hack program into the simulated ROM and visually observing its execution on the simulated hardware, as shown in figure 4.8.

For ease of use, the CPU emulator enables loading binary .hack files as well as symbolic .asm files. In the latter case, the emulator translates the assembly program into binary code on the fly. This utility seems to render the supplied assembler unnecessary, but this is not the case. First, the supplied assembler shows the translation process visually, for instructive purposes. Second, the binary files generated by the assembler can be executed directly on the hardware platform. To do so, load the Computer chip (built in chapter 5's project) into the hardware simulator, then load the .hack file generated by the assembler into the computer's ROM chip.

# **Computer Architecture**

Form ever follows function.	—Louis Sullivan (1856—1924), architect
Form IS function.	—Ludwig Mies van der Rohe (1886—1969), architect

This chapter is the pinnacle of the "hardware" part of our journey. We are now ready to take all the chips that we built in chapters 1-3 and integrate them into a general-purpose computer capable of running stored programs written in the machine language presented in chapter 4. The specific computer we will build, called Hack, has two important virtues. On the one hand, Hack is a simple machine that can be constructed in just a few hours, using previously built chips and the hardware simulator supplied with the book. On the other hand, Hack is sufficiently powerful to illustrate the key operating principles and hardware elements of any digital computer. Therefore, building it will give you an excellent understanding of how modern computers work at the low hardware and software levels.

Following an introduction of the stored program concept, section 5.1 gives a detailed description of the von Neumann *architecture*—a central dogma in computer science underlying the design of almost all modern computers. The Hack platform is one example of a von Neumann machine, and section 5.2 gives its exact hardware specification. Section 5.3 describes how the Hack platform can be implemented from available chips, in particular the ALU built in chapter 2 and the registers and memory systems built in chapter 3.

The computer that will emerge from this construction will be as simple as possible, but not simpler. This means that it will have the minimal configuration necessary to run interesting programs and deliver a reasonable performance. The comparison of this machine to typical computers is taken up in section 5.4, which emphasizes the critical role that optimization plays in the design of industrial-strength computers, but not in this chapter. As usual, the simplicity of our approach has a purpose: All the chips mentioned in the chapter, culminating in the Hack computer itself, can be built and tested on a personal computer running our hardware simulator, following the technical instructions given in section 5.5. The result will be a minimal yet surprisingly powerful computer.

# 5.1 Background

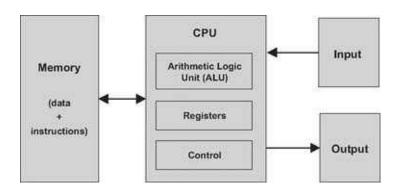
### **5.1.1 The Stored Program Concept**

Compared to all the other machines around us, the most unique feature of the digital computer is its amazing versatility. Here is a machine with finite hardware that can perform a practically infinite array of tasks, from interactive games to word processing to scientific calculations. This remarkable flexibility—a boon that we have come to take for granted—is the fruit of a brilliant idea called the *stored program* concept. Formulated independently by several mathematicians in the 1930s, the stored program concept is still considered the most profound invention in, if not the very foundation of, modern computer science.

Like many scientific breakthroughs, the basic idea is rather simple. The computer is based on a fixed hardware platform, capable of executing a fixed repertoire of instructions. At the same time, these instructions can be used and combined like building blocks, yielding arbitrarily sophisticated programs. Moreover, the logic of these programs is not embedded in the hardware, as it was in mechanical computers predating 1930. Instead, the program's code is stored and manipulated in the computer memory, just like data, becoming what is known as "software." Since the computer's operation manifests itself to the user through the currently executing software, the same hardware platform can be made to behave completely differently each time it is loaded with a different program.

#### **5.1.2** The von Neumann Architecture

The stored program concept is a key element of many abstract and practical computer models, most notably the universal Turing machine (1936) and the von Neumann machine (1945). The Turing machine —an abstract artifact describing a deceptively simple computer—is used mainly to analyze the logical foundations of computer systems. In contrast, the von Neumann machine is a practical architecture and the conceptual blueprint of almost all computer platforms today.



**Figure 5.1** The von Neumann architecture (conceptual). At this level of detail, this model describes the architecture of almost all digital computers. The program that operates the computer resides in its memory, in accordance with the "stored program" concept.

The von Neumann architecture is based on a central processing unit (CPU), interacting with a memory device, receiving data from some input device, and sending data to some output device (figure 5.1). At the heart of this architecture lies the stored program concept: The computer's memory stores not only the data that the computer manipulates, but also the very instructions that tell the computer what to do. Let us explore this architecture in some detail.

#### **5.1.3 Memory**

The memory of a von Neumann machine holds two types of information: data items and programming instructions. The two types of information are usually treated differently, and in some computers they are stored in separate memory units. In spite of their different functions though, both types of information are represented as binary numbers that are stored in the same generic random-access structure: a continuous array of cells of some fixed width, also called words or locations, each having a unique address. Hence, an individual word (representing either a data item or an instruction) is specified by supplying its address.

**Data Memory** High-level programs manipulate abstract artifacts like variables, arrays, and objects. When translated into machine language, these data abstractions become series of binary numbers, stored in the computer's data memory. Once an individual word has been selected from the data memory by specifying its address, it can be either read or written to. In the former case, we retrieve the word's value. In the latter case, we store a new value into the selected location, erasing the old value.

**Instruction Memory** When translated into machine language, each high-level command becomes a series of binary words, representing machine language instructions. These instructions are stored in the computer's instruction memory. In each step of the computer's operation, the CPU fetches (i.e., reads) a word from the instruction memory, decodes it, executes the specified instruction, and figures out which instruction to execute next. Thus, changing the contents of the instruction memory has the effect of completely changing the computer's operation.

The instructions that reside in the instruction memory are written in an agreed-upon formalism called machine language. In some computers, the specification of each operation and the codes representing its operands are represented in a single-word instruction. Other computers split this specification over several words.

## **5.1.4 Central Processing Unit**

The CPU—the centerpiece of the computer's architecture—is in charge of executing the instructions of the currently loaded program. These instructions tell the CPU to carry out various calculations, to read and write values from and into the memory, and to conditionally jump to execute other instructions in the program. The CPU executes these tasks using three main hardware elements: an Arithmetic-Logic Unit (ALU), a set of registers, and a control unit.

**Arithmetic Logic Unit** The ALU is built to perform all the low-level arithmetic and logical operations featured by the computer. For instance, a typical ALU can add two numbers, test whether a number is positive, manipulate the bits in a word of data, and so on.

**Registers** The CPU is designed to carry out simple calculations quickly. In order to boost performance, it is desirable to store the results of these calculations locally, rather than ship them in and out of memory. Thus, every CPU is equipped with a small set of high-speed registers, each capable of holding a single word.

**Control Unit** A computer instruction is represented as a binary code, typically 16, 32, or 64 bits wide. Before such an instruction can be executed, it must be decoded, and the information embedded in it must be used to signal various hardware devices (ALU, registers, memory) how to execute the instruction. The instruction decoding is done by some control unit, which is also responsible for figuring out which instruction to fetch and execute next.

The CPU operation can now be described as a repeated loop: fetch an instruction (word) from memory; decode it; execute it, fetch the next instruction, and so on. The instruction execution may involve one or more of the following micro tasks: have the ALU compute some value, manipulate internal registers, read a word from the memory, and write a word to the memory. In the process of executing these tasks, the CPU also figures out which instruction to fetch and execute next.

## 5.1.5 Registers

Memory access is a slow affair. When the CPU is instructed to retrieve the contents of address j of the memory, the following process ensues: (a) j travels from the CPU to the RAM; (b) the RAM's direct-access logic selects the memory register whose address is j; (c) the contents of RAM[j] travel back to the CPU. Registers provide the same service—data retrieval and storage—without the round-trip travel and search expenses. First, the registers reside physically inside the CPU chip, so accessing them is almost instantaneous. Second, there are typically only a handful of registers, compared to millions of memory cells. Therefore, machine language instructions can specify which registers they want to manipulate using just a few bits, resulting in thinner instruction formats.

Different CPUs employ different numbers of registers, of different types, for different purposes. In some computer architectures each register can serve more than one purpose:

Data registers: These registers give the CPU short-term memory services. For example, when calculating the value of  $(a - b) \cdot c$ , we must first compute and remember the value of (a - b). Although this result can be temporarily stored in some memory location, a better solution is to store it locally inside the CPU—in a data register.

Addressing registers: The CPU has to continuously access the memory in order to read data and write data. In every one of these operations, we must specify which individual memory word has to be accessed, namely, supply an address. In some cases this address appears as part of the current instruction, while in others it depends on the execution of a previous instruction. In the latter case, the address should be stored in a register whose contents can be later treated as a memory address—an addressing register.

Program counter register: When executing a program, the CPU must always keep track of the address of the next instruction that must be fetched from the instruction memory. This address is kept in a special register called program counter, or PC. The contents of the PC are then used as the address for fetching instructions from the instruction memory. Thus, in the process of executing the current instruction, the CPU updates the PC in one of two ways. If the current instruction contains no goto directive, the PC is incremented to point to the next instruction in the program. If the current instruction includes a goto n directive that should be executed, the CPU loads n into the PC.

# 5.1.6 Input and Output

Computers interact with their external environments using a diverse array of input and output (I/O) devices. These include screens, keyboards, printers, scanners, network interface cards, CD-ROMs, and so forth, not to mention the bewildering array of proprietary components that embedded computers are called to control in automobiles, weapon systems, medical equipment, and so on. There are two reasons why we do not concern ourselves here with the anatomy of these various devices. First, every one of them represents a unique piece of machinery requiring a unique knowledge of engineering. Second, and for this very same reason, computer scientists have devised various schemes to make all these devices look exactly the same to the computer. The simplest trick in this art is called memory-mapped *I/O*.

The basic idea is to create a binary emulation of the I/O device, making it "look" to the CPU like a normal memory segment. In particular, each I/O device is allocated an exclusive area in memory, becoming its "memory map." In the case of an input device (keyboard, mouse, etc.), the memory map is made to continuously reflect the physical state of the device; in the case of an output device (screen, speakers, etc.), the memory map is made to continuously drive the physical state of the device. When external events affect some input devices (e.g., pressing a key on the keyboard or moving the mouse), certain values are written in their respective memory maps. Likewise, if we want to manipulate some output devices (e.g., draw something on the screen or play a tune), we write some values in their respective memory maps. From the hardware point of view, this scheme requires each I/O device to provide an interface similar to that of a memory unit. From a software point of view, each I/O device is required to define an interaction contract, so that programs can access it correctly. As a side comment, given the multitude of available computer platforms and I/O devices, one can appreciate the crucial role that standards play in designing computer architectures.

The practical implications of a memory-mapped I/O architecture are significant: The design of the CPU and the overall platform can be totally independent of the number, nature, or make of the I/O devices that interact, or will interact, with the computer. Whenever we want to connect a new I/O device to the computer, all we have to do is allocate to it a new memory map and "take note" of its base address (these one-time configurations are typically done by the operating system). From this point onward, any program that wants to manipulate this I/O device can do so—all it needs to do is manipulate bits in memory.



#### 5.2.1 Overview

The Hack platform is a 16-bit von Neumann machine, consisting of a CPU, two separate memory modules serving as instruction memory and data memory, and two memory-mapped I/O devices: a screen and a keyboard. Certain parts of this architecture—especially its machine language—were presented in chapter 4. A summary of this discussion is given here, for ease of reference.

The Hack computer executes programs that reside in its instruction memory. The instruction memory is a read-only device, and thus programs are loaded into it using some exogenous means. For example, the instruction memory can be implemented in a ROM chip that is preburned with the required program. Loading a new program can be done by replacing the entire ROM chip. In order to simulate this operation, hardware simulators of the Hack platform must provide a means for loading the instruction memory from a text file containing a program written in the Hack machine language. (From now on, we will refer to Hack's data memory and instruction memory as RAM and ROM, respectively.)

The Hack CPU consists of the ALU specified in chapter 2 and three registers called data register (D), address register (A), and program counter (PC). D and A are general-purpose 16-bit registers that can be manipulated by arithmetic and logical instructions like A=D-1, D=D|A, and so on, following the Hack machine language specified in chapter 4. While the D-register is used solely to store data values, the contents of the A-register can be interpreted in three different ways, depending on the instruction's context: as a data value, as a RAM address, or as a ROM address.

The computer architecture is wired in such a way that the output of the program counter (PC) chip is connected to the address input of the ROM chip. This way, the ROM chip always emits the word ROM[PC], namely, the contents of the instruction memory location whose address is "pointed at" by the PC. This value is called the current instruction. With that in mind, the overall computer operation during each clock cycle is as follows:

*Execute:* Various bit parts of the current instruction are simultaneously fed to various chips in the computer. If it's an address instruction (most significant bit = 0), the A-register is set to the 15-bit constant embedded in the instruction. If it's a *compute instruction* (MSB = 1), its underlying a-, c-, d- and j-bits are treated as control bits that cause the ALU and the registers to execute the instruction.

Fetch: Which instruction to fetch next is determined by the jump bits of the current instruction and by the ALU output. Taken together, these values determine whether a jump should materialize. If so, the PC is set to the value of the A-register; otherwise, the PC is incremented by 1. In the next clock cycle, the instruction that the program counter points at emerges from the ROM's output, and the cycle continues.

This particular fetch-execute cycle implies that in the Hack platform, elementary operations involving memory access usually require two instructions: an address instruction to set the A register to a particular address, and a subsequent compute instruction that operates on this address (a read/write operation on the

RAM or a jump operation into the ROM).

We now turn to formally specify the Hack hardware platform. Before starting, we wish to point out that this platform can be assembled from previously built components. The CPU is based on the ALU built in chapter 2. The registers and the program counter are identical copies of the 16-bit register and 16-bit counter, respectively, built in chapter 3. Likewise, the ROM and the RAM chips are versions of the memory units built in chapter 3. Finally, the screen and the keyboard devices will interface with the hardware platform through memory maps, implemented as built-in chips that have the same interface as RAM chips.

# **5.2.2** Central Processing Unit (CPU)

The CPU of the Hack platform is designed to execute 16-bit instructions according to the Hack machine language specified in chapter 4. It expects to be connected to two separate memory modules: an instruction memory, from which it fetches instructions for execution, and a data memory, from which it can read, and into which it can write, data values. Figure 5.2 gives the specification details.

### **5.2.3 Instruction Memory**

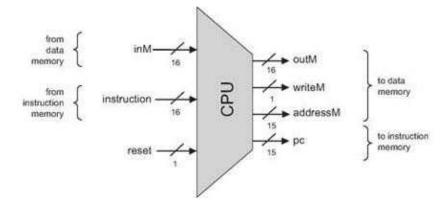


#### 5.2.4 Data Memory

Hack's *data memory* chip has the interface of a typical RAM device, like that built in chapter 3 (see, e.g., figure 3.3). To read the contents of register n, we put n in the memory's address input and probe the memory's out output. This is a combinational operation, independent of the clock. To write a value v into register n, we put v in the in input, n in the address input, and assert the memory's load bit. This is a sequential operation, and so register n will commit to the new value v in the next clock cycle.

In addition to serving as the computer's general-purpose data store, the data memory also interfaces between the CPU and the computer's input/output devices, using *memory maps*.

Memory Maps In order to facilitate interaction with a user, the Hack platform can be connected to two peripheral devices: screen and keyboard. Both devices interact with the computer platform through memory-mapped buffers. Specifically, screen images can be drawn and probed by writing and reading, respectively, words in a designated memory segment called screen memory map. Similarly, one can check which key is presently pressed on the keyboard by probing a designated memory word called keyboard memory map. The memory maps interact with their respective I/O devices via peripheral logic that resides outside the computer. The contract is as follows: Whenever a bit is changed in the screen's memory map, a respective pixel is drawn on the physical screen. Whenever a key is pressed on the physical keyboard, the respective code of this key appears in the keyboard's memory map.



```
// Central Processing Unit
Chip Name: CPU
Inputs:
           inM[16],
                             // M value input (M = contents of RAM[A])
           instruction[16],
                            // Instruction for execution
           reset
                             // Signals whether to restart the current
                             // program (reset=1) or continue executing
                             // the current program (reset=0)
Outputs:
          outM[16],
                             // M value output
          writeM,
                             // Write to M?
                             // Address of M in data memory
           addressM[15],
                             // Address of next instruction
          pc[15]
Function:
          Executes the instruction according to the Hack machine language
           specification. The D and A in the language specification refer to
          CPU-resident registers, while M refers to the memory location
           addressed by A (inM holds the value of this location).
           If the instruction needs to write a value to M, the value is
          placed in outM, the address is placed in addressM, and the writeM
          bit is asserted. (When writeM=0, any value may appear in outM.)
           If reset=1, then the CPU jumps to address 0 (i.e., sets pc=0 in
           the next time unit) rather than to the address resulting from
           executing the current instruction.
```

**Figure 5.2** The Central Processing Unit. Assembled from the ALU and the registers built in chapters 2 and 3, respectively.

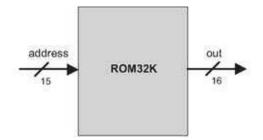


Figure 5.3 Instruction memory.

We specify first the built-in chips that interface between the hardware interface and the I/O devices, then the complete memory module that embeds these chips.

**Screen** The Hack computer can interact with a black-and-white screen organized as 256 rows of 512 pixels per row. The computer interfaces with the physical screen via a memory map, implemented by a chip called Screen. This chip behaves like regular memory, meaning that it can be read and written to. In addition, it features the side effect that any bit written to it is reflected as a pixel on the physical screen (1 = black, 0 = white). The exact mapping between the memory map and the physical screen coordinates is given in figure 5.4.

**Keyboard** The Hack computer can interact with a standard keyboard, like that of a personal computer. The computer interfaces with the physical keyboard via a chip called Keyboard (figure 5.5). Whenever a key is pressed on the physical keyboard, its 16-bit ASCII code appears as the output of the Keyboard chip. When no key is pressed, the chip outputs 0. In addition to the usual ASCII codes, the Keyboard chip recognizes, and responds to, the keys listed in figure 5.6.

```
Chip Name: Screen
                        // Memory map of the physical screen
Inputs:
          in[16],
                        // What to write
                       // Write-enable bit
           load,
           address[13] // Where to write
                        // Screen value at the given address
Output:
           out[16]
Function: Functions exactly like a 16-bit 8K RAM:

    out(t)=Screen[address(t)](t)

    If load(t-1) then Screen[address(t-1)](t)=in(t-1)

           (t is the current time unit, or cycle)
           Has the side effect of continuously refreshing a 256
Comment:
           by 512 black-and-white screen (simulators must
           simulate this device). Each row in the physical
           screen is represented by 32 consecutive 16-bit words,
           starting at the top left corner of the screen. Thus
           the pixel at row r from the top and column c from the
           left (0<=r<=255, 0<=c<=511) reflects the c%16 bit
           (counting from LSB to MSB) of the word found at
           Screen[r*32+c/16].
```

Figure 5.4 Screen interface.

Figure 5.5 Keyboard interface.

Key pressed	Keyboard output	Key pressed	Keyboard output
newline	128	end	135
backspace	129	page up	136
left arrow	130	page down	137
up arrow	131	insert	138
right arrow	132	delete	139
down arrow	133	esc	140
home	134	f1-f12	141-152

Figure 5.6 Special keyboard keys in the Hack platform.

Now that we've described the internal parts of the data memory, we are ready to specify the entire data memory address space.

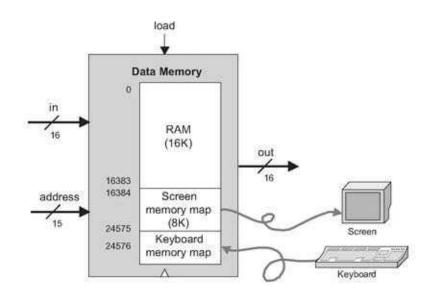
**Overall Memory** The overall address space of the Hack platform (i.e., its entire data memory) is provided by a chip called Memory. The memory chip includes the RAM (for regular data storage) and the screen and keyboard memory maps. These modules reside in a single address space that is partitioned into four sections, as shown in figure 5.7.

#### 5.2.5 Computer

The topmost chip in the Hack hardware hierarchy is a complete computer system designed to execute programs written in the Hack machine language. This abstraction is described in figure 5.8. The Computer chip contains all the hardware devices necessary to operate the computer including a CPU, a data memory, an instruction memory (ROM), a screen, and a keyboard, all implemented as internal parts. In order to execute a program, the program's code must be preloaded into the ROM. Control of the screen and the keyboard is achieved via their memory maps, as described in the Screen and Keyboard chip specifications.

# 5.3 Implementation

This section gives general guidelines on how the Hack computer platform can be built to deliver the various services described in its specification (section 5.2). As usual, we don't give exact building instructions, expecting readers to come up with their own designs. All the chips can be built in HDL and simulated on a personal computer using the hardware simulator that comes with the book. As usual, technical details are given in the final Project section of this chapter.



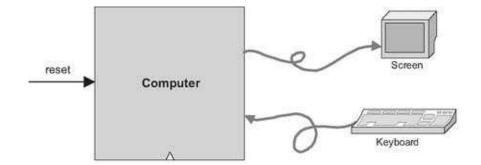
```
Chip Name: Memory
                        // Complete memory address space
Inputs:
                        // What to write
           in[16],
           load,
                        // Write-enable bit
           address[15]
                        // Where to write
Output:
                        // Memory value at the given address
Function:

    out(t)=Memory[address(t)](t)

    If load(t-1) then Memory(address(t-1))(t)=in(t-1)

           (t is the current time unit, or cycle)
           Access to any address>24576 (0x6000) is invalid.
Comment:
           Access to any address in the range 16384-24575
           (0x4000-0x5FFF) results in accessing the screen
           memory map. Access to address 24576 (0x6000) results
           in accessing the keyboard memory map. The behavior
           in these addresses is described in the Screen and
           Keyboard chip specifications.
```

**Figure 5.7** Data memory.



Chip Name: Computer // Topmost chip in the Hack platform
Input: reset
Function: When reset is 0, the program stored in the computer's
ROM executes. When reset is 1, the execution of the
program restarts. Thus, to start a program's
execution, reset must be pushed "up" (1) and then
"down" (0).

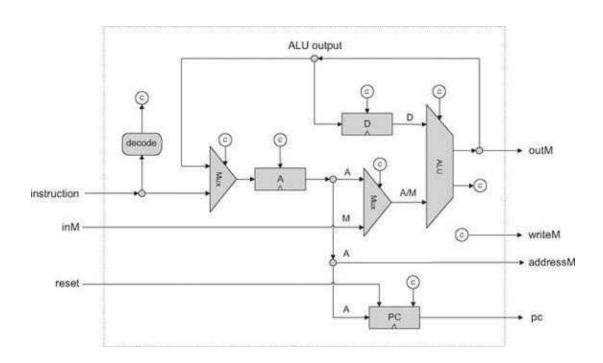
From this point onward the user is at the mercy of
the software. In particular, depending on the
program's code, the screen may show some output and
the user may be able to interact with the computer
via the keyboard.

Figure 5.8 Computer. Topmost chip of the Hack hardware platform.

Since most of the action in the Hack platform occurs in its Central Processing Unit, the main implementation challenge is building the CPU. The construction of the rest of the computer platform is straightforward.

#### **5.3.1** The Central Processing Unit

The CPU implementation objective is to create a logic gate architecture capable of executing a given Hack instruction and fetching the next instruction to be executed. Naturally, the CPU will include an ALU capable of executing Hack instructions, a set of registers, and some control logic designed to fetch and decode instructions. Since almost all these hardware elements were already built in previous chapters, the key question here is how to connect them in order to effect the desired CPU operation. One possible solution is illustrated in figure 5.9.



**Figure 5.9** Proposed CPU implementation. The diagram shows only *data* and *address paths*, namely, wires that carry data and addresses from one place to another. The diagram does not show the CPU's *control logic*, except for inputs and outputs of control bits, labeled with a circled "c". Thus it should be viewed as an incomplete chip diagram.

The key element missing in figure 5.9 is the CPU's *control logic*, designed to perform the following tasks:

- *Instruction decoding:* Figure out what the instruction means (a function of the instruction).
- *Instruction execution:* Signal the various parts of the computer what they should do in order to execute the instruction (a function of the instruction).
- *Next instruction fetching:* Figure out which instruction to execute next (a function of the instruction and the ALU output).

(In what follows, the term proposed CPU implementation refers to figure 5.9.)

**Instruction Decoding** The 16-bit word located in the CPU's instruction input can represent either an *A*-instruction or a *C*-instruction. In order to figure out what this 16-bit word means, it can be broken into the fields "i xx a ccccc ddd jjj". The i-bit codes the instruction type, which is 0 for an *A*-instruction and 1 for a *C*-instruction. In case of a *C*-instruction, the a-bit and the c-bits code the comp part, the d-bits code the dest part, and the j-bits code the jump part of the instruction. In case of an *A*-instruction, the 15 bits other than the i-bit should be interpreted as a 15-bit constant.

**Instruction Execution** The various fields of the instruction (i-, a-, c-, d-, and j-bits) are routed simultaneously to various parts of the architecture, where they cause different chips to do what they are supposed to do in order to execute either the *A*-instruction or the *C*-instruction, as mandated by the machine language specification. In particular, the a-bit determines whether the ALU will operate on the A register input or on the Memory input, the c-bits determine which function the ALU will compute, and the d-bits enable various locations to accept the ALU result.

**Next Instruction Fetching** As a side effect of executing the current instruction, the CPU also determines the address of the next instruction and emits it via its pc output. The "driver" of this task is the *program counter*—an internal part of the CPU whose output is fed directly to the CPU's pc output. This is precisely the PC chip built in chapter 3 (see figure 3.5).

Most of the time, the programmer wants the computer to fetch and execute the next instruction in the program. Thus if t is the current time-unit, the default program counter operation should be PC(t) = PC(t - 1) + 1. When we want to effect a *goto* n operation, the machine language specification requires to first set the A register to n (via an A-instruction) and then issue a jump directive (coded by the j-bits of a subsequent C-instruction). Hence, our challenge is to come up with a hardware implementation of the following logic:

If jump(t) then 
$$PC(t) = A(t-1)$$
  
else  $PC(t) = PC(t-1) + 1$ 

Conveniently, and actually by careful design, this jump control logic can be easily effected by the proposed CPU implementation. Recall that the PC chip interface (figure 3.5) has a load control bit that enables it to accept a new input value. Thus, to effect the desired jump control logic, we start by connecting the output of the A register to the input of the PC. The only remaining question is when to enable the PC to accept this value (rather than continuing its steadfast counting), namely, when does a jump need to occur. This is a function of two signals: (a) the j-bits of the current instruction, specifying on which condition we are supposed to jump, and (b) the ALU output status bits, indicating whether the condition is satisfied. If we have a jump, the PC should be loaded with A's output. Otherwise, the PC should increment by 1.

Additionally, if we want the computer to restart the program's execution, all we have to do is reset the program counter to 0. That's why the proposed CPU implementation feeds the CPU's reset input directly into the reset pin of the PC chip.

#### **5.3.2 Memory**

According to its specification, the Memory chip of the Hack platform is essentially a package of three lower-level chips: RAM16K, Screen, and Keyboard. At the same-time, users of the Memory chip must see a single logical address space, spanning from location 0 to 24576 (0x0000 to 0x6000—see figure 5.7). The implementation of the Memory chip should create this continuum effect. This can be done by the same technique used to combine small RAM units into larger ones, as we have done in chapter 3 (see figure 3.6 and the discussion of n-register memory that accompanies it).

### **5.3.3 Computer**



## **5.4 Perspective**

Following the general spirit of the book, the architecture of the Hack computer is rather minimal. Typical computer platforms have more registers, more data types, more powerful ALUs, and richer instruction sets. However, these differences are mainly quantitative. From a qualitative standpoint, Hack is quite similar to most digital computers, as they all follow the same conceptual paradigm: the von Neumann architecture.

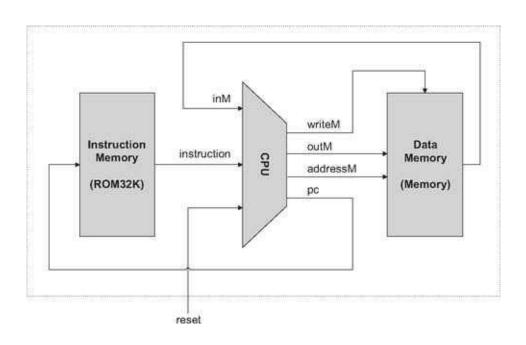


Figure 5.10 Proposed implementation of the topmost Computer chip.

In terms of function, computer systems can be classified into two categories: *general-purpose computers*, designed to easily switch from executing one program to another, and dedicated computers, usually embedded in other systems like cell phones, game consoles, digital cameras, weapon systems, factory equipment, and so on. For any particular application, a single program is burned into the dedicated computer's ROM, and is the only one that can be executed (in game consoles, for example, the game software resides in an external cartridge that is simply a replaceable ROM module encased in some fancy package). Aside from this difference, general-purpose and dedicated computers share the same architectural ideas: stored programs, fetch-decode-execute logic, CPU, registers, program counter, and so on.

Unlike Hack, most general-purpose computers use a single address space for storing both data and instructions. In such architectures, the instruction address as well as the optional data address specified by the instruction must be fed into the same destination: the single address input of the shared address space. Clearly, this cannot be done at the same time. The standard solution is to base the computer implementation on a two-cycle logic. During the fetch cycle, the instruction address is fed to the address input of the memory, causing it to immediately emit the current instruction, which is then stored in an instruction register. In the subsequent execute cycle, the instruction is decoded, and the optional data

address inferred from it is fed to the memory's address input, allowing the instruction to manipulate the selected memory location. In contrast, the Hack architecture is unique in that it partitions the address space into two separate parts, allowing a single-cycle fetch-execute logic. The price of this simpler hardware design is that programs cannot be changed dynamically.

In terms of I/O, the Hack keyboard and screen are rather spartan. General-purpose computers are typically connected to multiple I/O devices like printers, disks, network connections, and so on. Also, typical screens are obviously much more powerful than the Hack screen, featuring more pixels, many brightness levels in each pixel, and colors. Still, the basic principle that each pixel is controlled by a memory-resident binary value is maintained: instead of a single bit controlling the pixel's black or white color, several bits are devoted to control the level of brightness of each of the three primary colors that, together, produce the pixel's ultimate color. Likewise, the memory mapping of the Hack screen is simplistic. Instead of mapping pixels directly into bits of memory, most modern computers allow the CPU to send high-level graphic instructions to a graphics card that controls the screen. This way, the CPU is relieved from the tedium of drawing figures like circles and polygons directly—the graphics card takes care of this task using its own embedded chip-set.

Finally, it should be stressed that most of the effort and creativity in designing computer hardware is invested in achieving better performance. Thus, hardware architecture courses and textbooks typically evolve around such issues as implementing memory hierarchies (cache), better access to I/O devices, pipelining, parallelism, instruction prefetching, and other optimization techniques that were sidestepped in this chapter.

Historically, attempts to enhance the processor's performance have led to two main schools of hardware design. Advocates of the Complex Instruction Set Computing (CISC) approach argue for achieving better performance by providing rich and elaborate instruction sets. Conversely, the Reduced Instruction Set Computing (RISC) camp uses simpler instruction sets in order to promote as fast a hardware implementation as possible. The Hack computer does not enter this debate, featuring neither a strong instruction set nor special hardware acceleration techniques.

# 5.5 Project

Objective Build the Hack computer platform, culminating in the topmost Computer chip.

**Resources** The only tools that you need for completing this project are the hardware simulator supplied with the book and the test scripts described here. The computer platform should be implemented in the HDL language specified in appendix A.

**Contract** The computer platform built in this project should be capable of executing programs written in the Hack machine language, specified in chapter 4. Demonstrate this capability by having your Computer chip run the three programs given here.

**Component Testing** We supply test scripts and compare files for unit-testing the Memory and CPU chips in isolation. It's important to complete the testing of these chips before building and testing the overall Computer chip.

**Test Programs** A natural way to test the overall Computer chip implementation is to have it execute some sample programs written in the Hack machine language. In order to run such a test, one can write a test script that loads the Computer chip into the hardware simulator, loads a program from an external text file into its ROM chip, and then runs the clock enough cycles to execute the program. We supply all the files necessary to run three such tests, as follows:

- 1. Add.hack: Adds the two constants 2 and 3 and writes the result in RAM[0].
- 2. Max.hack: Computes the maximum of RAM[0] and RAM[1] and writes the result in RAM[2].
- 3. Rect.hack: Draws a rectangle of width 16 pixels and length RAM[0] at the top left of the screen.

Before testing your Computer chip on any one of the above programs, read the test script associated with the program and be sure to understand the instructions given to the simulator. Appendix B may be a useful reference here.

Steps Build the computer in the following order:

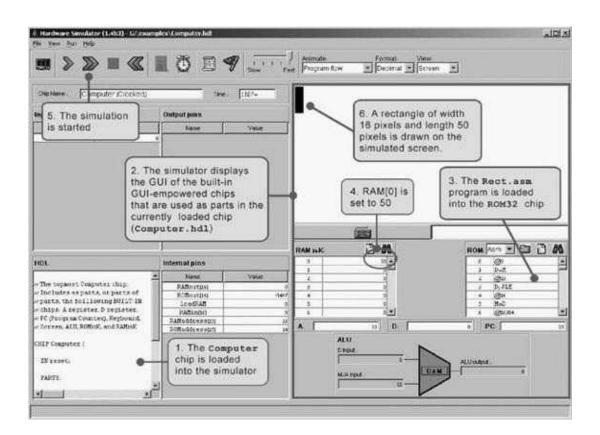
- *Memory:* Composed from three chips: RAM16K, Screen, and Keyboard. The Screen and the Keyboard are available as built-in chips and there is no need to build them. Although the RAM16K chip was built in the project in chapter 3, we recommend using its built-in version, as it provides a debugging-friendly GUI.
- CPU: Can be composed according to the proposed implementation given in figure 5.9, using the ALU

and register chips built in chapters 2 and 3, respectively. We recommend using the built-in versions of these chips, in particular ARegister and DRegister. These chips have exactly the same functionality of the Register chip specified in chapter 3, plus GUI side effects.

In the course of implementing the CPU, it is allowed (but not necessarily recommended) to specify and build some internal chips of your own. This is up to you. If you choose to create new chips not mentioned in the book, be sure to document and test them carefully before you plug them into the architecture.

- *Instruction Memory:* Use the built-in ROM32K chip.
- *Computer*: The topmost Computer chip can be composed from the chips mentioned earlier, using figure 5.10 as a blueprint.

**The Hardware Simulator** As in the projects in chapters 1-3, all the chips in this project (including the topmost Computer chip) can be implemented and tested using the hardware simulator supplied with the book. Figure 5.11 is a screen shot of testing the Rect.hack program on a Computer chip implementation.



**Figure 5.11** Testing the Computer chip on the hardware simulator. The Rect program draws a rectangle of width 16 pixels and length RAM[0] at the top left of the screen. Note that the program is correct. Thus, if it does not work properly, it means that the computer platform on which it runs (Computer.hdl and/or some of its lower-level parts) is buggy.