


# Nonparametric Inference

Nonparametric estimation is also referred as curve estimation or smoothing. We do not make any functional assumptions.

## The Bias-Variance Tradeoff

Let  $g$  denote an unknown function such as a density function or a regression function. Let  $\hat{g}_n$  denote an estimator of  $g$ . Bear in mind that  $\hat{g}_n$  is a random function evaluated at a point  $x$ . The estimator is random because it depends on the data.

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A loss function, we will use integrated squared error (ISE):

$$L(g, \hat{g}_n) = \int (g(u) - \hat{g}_n(u))^2$$

The **risk** or mean integrated squared error (MISE) with respect to squared error loss is

$$R(f, \hat{f}) = E(L(g, \hat{g}))$$

Then, the risk can be written as

$$R(f, \hat{f}) = \int b^2(x)dx + \int v(x)dx$$

where

$$b(x) = E(\hat{g}_n) - g(x)$$

is the bias of  $\hat{g}_n(x)$  at a fixed  $x$  and

$$v(x) = \text{Var}(\hat{g}_n(x)) = E([\hat{g}_n - E(\hat{g}_n)]^2)$$

is the variance of  $\hat{g}_n(x)$  at a fixed  $x$ .

In summary,

$$\text{RISK} = \text{BIAS}^2 + \text{VARIANCE}$$

When the data are oversmoothed, the bias term is large and the variance is small. When the data are undersmoothed the opposite is true.

This is called the bias-variance tradeoff.

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# Kernel Regression Estimators

## Nadaraya-Watson Kernel Regression

Kernel regression estimation is an example of fully nonparametric estimation (others are splines, nearest neighbors, etc.). We'll consider the Nadaraya-Watson kernel regression estimator in a simple case.

Suppose we have an iid sample from the joint density  $f(x, y)$ , where  $x$  is  $k$ -dimensional. The model is

$$y_t = g(x_t) + \varepsilon_t,$$

where

$$E(\varepsilon_t | x_t) = 0.$$

The conditional expectation of  $y$  given  $x$  is  $g(x)$ . By definition of the conditional expectation, we have

$$\begin{aligned} g(x) &= \int y \frac{f(x, y)}{h(x)} dy \\ &= \frac{1}{h(x)} \int y f(x, y) dy, \end{aligned}$$

where  $h(x)$  is the marginal density of  $x$  :

$$h(x) = \int f(x, y) dy.$$

This suggests that we could estimate  $g(x)$  by estimating  $h(x)$  and  $\int y f(x, y) dy$ .

### Estimation of the denominator

A kernel estimator for  $h(x)$  has the form

$$\hat{h}(x) = \frac{1}{n} \sum_{t=1}^n \frac{K[(x - x_t) / \gamma_n]}{\gamma_n^k},$$

where  $n$  is the sample size and  $k$  is the dimension of  $x$ .

The function  $K(\cdot)$  (the kernel) is absolutely integrable:

$$\int |K(x)| dx < \infty,$$

and  $K(\cdot)$  integrates to 1 :

$$\int K(x) dx = 1.$$

In this respect,  $K(\cdot)$  is like a density function, but we do not necessarily restrict  $K(\cdot)$  to be nonnegative.

The window width parameter,  $\gamma_n$  is a sequence of positive numbers that satisfies

$$\begin{aligned}\lim_{n \rightarrow \infty} \gamma_n &= 0 \\ \lim_{n \rightarrow \infty} n\gamma_n^k &= \infty\end{aligned}$$

So, the window width must tend to zero, but not too quickly.

To show **pointwise consistency** of  $\hat{h}(x)$  for  $h(x)$ , first consider the expectation of the estimator (because the estimator is an average of iid terms, we only need to consider the expectation of a representative term):

$$E[\hat{h}(x)] = \int \gamma_n^{-k} K[(x - z)/\gamma_n] h(z) dz.$$

Change variables as  $z^* = (x - z)/\gamma_n$ , so  $z = x - \gamma_n z^*$  and  $|\frac{dz}{dz^*}| = \gamma_n^k$ , we obtain

$$\begin{aligned}E[\hat{h}(x)] &= \int \gamma_n^{-k} K(z^*) h(x - \gamma_n z^*) \gamma_n^k dz^* \\ &= \int K(z^*) h(x - \gamma_n z^*) dz^*.\end{aligned}$$

Now, asymptotically,

$$\begin{aligned}\lim_{n \rightarrow \infty} E[\hat{h}(x)] &= \lim_{n \rightarrow \infty} \int K(z^*) h(x - \gamma_n z^*) dz^* \\ &= \int \lim_{n \rightarrow \infty} K(z^*) h(x - \gamma_n z^*) dz^* \\ &= \int K(z^*) h(x) dz^* \\ &= h(x) \int K(z^*) dz^* \\ &= h(x),\end{aligned}$$

since  $\gamma_n \rightarrow 0$  and  $\int K(z^*) dz^* = 1$  by assumption. (Note: that we can pass the limit through the integral is a result of the dominated convergence theorem. For this to hold we need that  $h(\cdot)$  be dominated by an absolutely integrable function.)

Next, considering the **variance** of  $\hat{h}(x)$ , we have, due to the iid assumption

$$\begin{aligned}n\gamma_n^k V[\hat{h}(x)] &= n\gamma_n^k \frac{1}{n^2} \sum_{t=1}^n V\left\{\frac{K[(x - x_t)/\gamma_n]}{\gamma_n^k}\right\} \\ &= \gamma_n^{-k} \frac{1}{n} \sum_{t=1}^n V\{K[(x - x_t)/\gamma_n]\}\end{aligned}$$

By the representative term argument, this is

$$n\gamma_n^k V [\hat{h}(x)] = \gamma_n^{-k} V \{K[(x-z)/\gamma_n]\}$$

Also, since  $V(x) = E(x^2) - E(x)^2$  we have

$$\begin{aligned} n\gamma_n^k V [\hat{h}(x)] &= \gamma_n^{-k} E \left\{ (K[(x-z)/\gamma_n])^2 \right\} - \gamma_n^{-k} \{E(K[(x-z)/\gamma_n])\}^2 \\ &= \int \gamma_n^{-k} K[(x-z)/\gamma_n]^2 h(z) dz - \gamma_n^{-k} \left\{ \int \gamma_n^{-k} K[(x-z)/\gamma_n] h(z) dz \right\}^2 \\ &= \int \gamma_n^{-k} K[(x-z)/\gamma_n]^2 h(z) dz - \gamma_n^k E [\hat{h}(x)]^2 \end{aligned}$$

The second term converges to zero:

$$\gamma_n^k E [\hat{h}(x)]^2 \rightarrow 0,$$

by the previous result regarding the expectation and the fact that  $\gamma_n \rightarrow 0$ . Therefore,

$$\lim_{n \rightarrow \infty} n\gamma_n^k V [\hat{h}(x)] = \lim_{n \rightarrow \infty} \int \gamma_n^{-k} K[(x-z)/\gamma_n]^2 h(z) dz.$$

Using exactly the same change of variables as before, this can be shown to be

$$\lim_{n \rightarrow \infty} n\gamma_n^k V [\hat{h}(x)] = h(x) \int [K(z^*)]^2 dz^*.$$

Since both  $\int [K(z^*)]^2 dz^*$  and  $h(x)$  are bounded, the RHS is bounded, and since  $n\gamma_n^k \rightarrow \infty$  by assumption, we have that

$$V [\hat{h}(x)] \rightarrow 0.$$

Since the bias and the variance both go to zero, we have **pointwise consistency** (convergence in quadratic mean implies convergence in probability).

## Estimation of the numerator

To estimate  $\int y f(x, y) dy$ , we need an estimator of  $f(x, y)$ . The estimator has the same form as the estimator for  $h(x)$ , only with one dimension more:

$$\hat{f}(x, y) = \frac{1}{n} \sum_{t=1}^n \frac{K_*[(y - y_t)/\gamma_n, (x - x_t)/\gamma_n]}{\gamma_n^{k+1}}$$

The kernel  $K_*(\cdot)$  is required to have mean zero:

$$\int y K_*(y, x) dy = 0$$

and to marginalize to the previous kernel for  $h(x)$  :

$$\int K_*(y, x) dy = K(x).$$

With this kernel, we have (not obviously, see Li and Racine, Ch. 2, section 2.1)

$$\int y \hat{f}(y, x) dy = \frac{1}{n} \sum_{t=1}^n y_t \frac{K[(x - x_t) / \gamma_n]}{\gamma_n^k}$$

by marginalization of the kernel, so we obtain

$$\begin{aligned} \hat{g}(x) &:= \frac{1}{\hat{h}(x)} \int y \hat{f}(y, x) dy \\ &= \frac{\frac{1}{n} \sum_{t=1}^n y_t \frac{K[(x - x_t) / \gamma_n]}{\gamma_n^k}}{\frac{1}{n} \sum_{t=1}^n \frac{K[(x - x_t) / \gamma_n]}{\gamma_n^k}} \\ &= \frac{\sum_{t=1}^n y_t K[(x - x_t) / \gamma_n]}{\sum_{t=1}^n K[(x - x_t) / \gamma_n]} \end{aligned}$$

This is the Nadaraya-Watson kernel regression estimator.

## Kernel Regression

Defining:

$$w_t = \frac{K[(x - x_t) / \gamma_n]}{\sum_{t=1}^n K[(x - x_t) / \gamma_n]},$$

the kernel regression estimator for  $g(x_t)$  can be written as

$$\hat{g}(x) = \sum_{t=1}^n y_t w_t,$$

a weighted average of the  $y_j$ ,  $j = 1, 2, \dots, n$ , where higher weights are associated with points that are closer to  $x_t$ .

- The window width parameter  $\gamma_n$  imposes smoothness. The estimator is increasingly flat as  $\gamma_n \rightarrow \infty$ , since in this case each weight tends to  $1/n$ .
- A large window width reduces the variance (strong imposition of flatness), but increases the bias.
- A small window width reduces the bias, but makes very little use of information except points that are in a small neighborhood of  $x_t$ . Since relatively little information is used, the variance is large when the window width is small.
- The standard normal density is a popular choice for  $K(\cdot)$  and  $K_*(y, x)$ , though there are possibly better alternatives.

One can choose the window width using Cross-validation.

## Example: Nadaraya-Watson Estimator with Guassian Kernel and Silverman's Rule of Thumb Window

In [65]: `n=1000`  
`k=2`

```
ydata = rand(Bernoulli(0.5),n)
xdata = randn(n,k);
```

```
In [77]: function nw_ap(xeval,xdata,ydata)
        h = 1.06.*std(xdata,dims=1).*(size(xdata,1)^-0.2) #Silverman's rule of thumb
        input = (repeat(randn(2)',size(xdata,1)) .- xdata) ./ repeat(h,size(xdata,1))
        phi = exp.(-0.5.*(input).^2)./sqrt(2*pi)
        phiprod = prod(phi,dims=2).*(1/(prod(h)*size(xdata,1)))

        return sum(phiprod.*ydata) / sum(phiprod)

end
```

```
Out[77]: nw_ap (generic function with 1 method)
```

```
In [86]: nw_ap(randn(2),xdata,ydata)
```

```
Out[86]: 0.47560938381448953
```