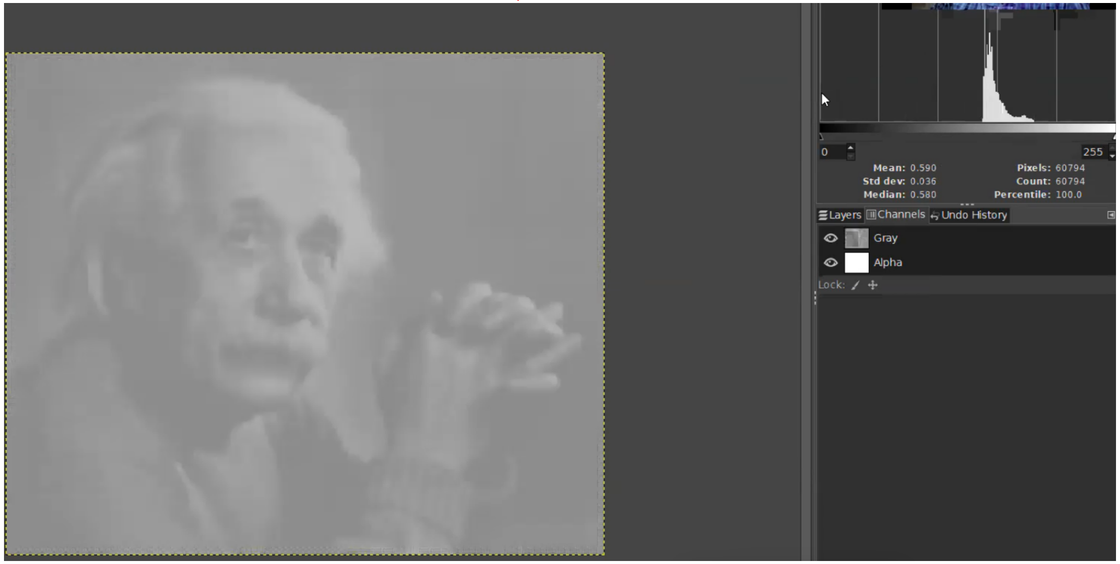
# Histogram Processing

- Histogram of a digital image with gray levels in the range [0,L-1] is a **discrete function**

$$h(r_k) = n_k$$

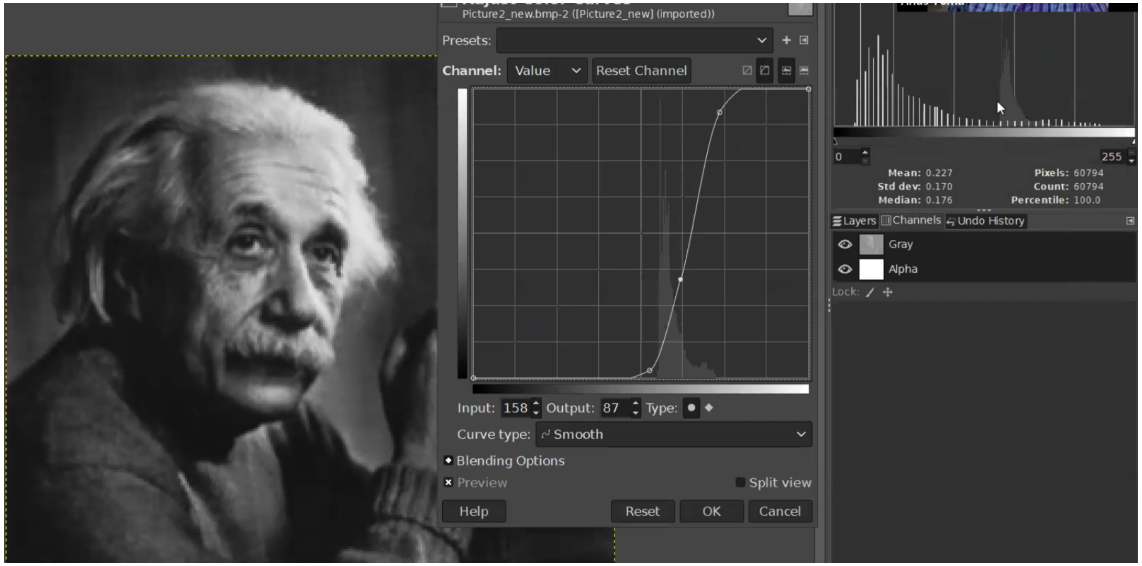

  - Where
    - $r_k$ : the $k^{th}$ gray level
    - $n_k$ : the number of pixels in the image having gray level $r_k$
    - $h(r_k)$ : histogram of a digital image with gray levels $r_k$

(1)



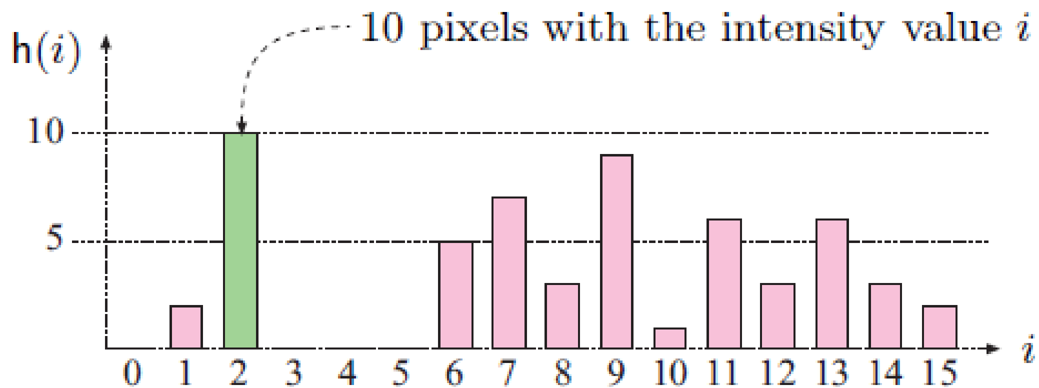
0
255
Mean: 0.590
Std dev: 0.036
Median: 0.580
Pixels: 60794
Count: 60794
Percentile: 100.0
Layers
Channels
Undo History
Gray
Alpha
Lock:


(2)



Picture2_new.bmp-2 ([Picture2_new] (imported))
Presets:
Channel:
Value
Reset Channel
Input: 158
Output: 87
Type:
Curve type:
Smooth
Blending Options
Preview
Split view
Help
Reset
OK
Cancel
0
255
Mean: 0.227
Std dev: 0.170
Median: 0.176
Pixels: 60794
Count: 60794
Percentile: 100.0
Layers
Channels
Undo History
Gray
Alpha
Lock:

# Example




| | | | | | | | | | | | | | | | | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| h($i$) | 0 | 2 | 10 | 0 | 0 | 0 | 5 | 7 | 3 | 9 | 1 | 6 | 3 | 6 | 3 | 2 |
| $i$ | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |

- Histogram vector for an image with ***L* = 16** possible intensity values
- The **indices** of the vector element *i* = 0. . . 15 represent **intensity values**
- The value of 10 at index 2 means that the image contains 10 pixels of intensity value 2.

# Normalized Histogram

- Dividing each of histogram value at gray level $\boldsymbol{r_k}$ by the total number of pixels in the image, ***MN***

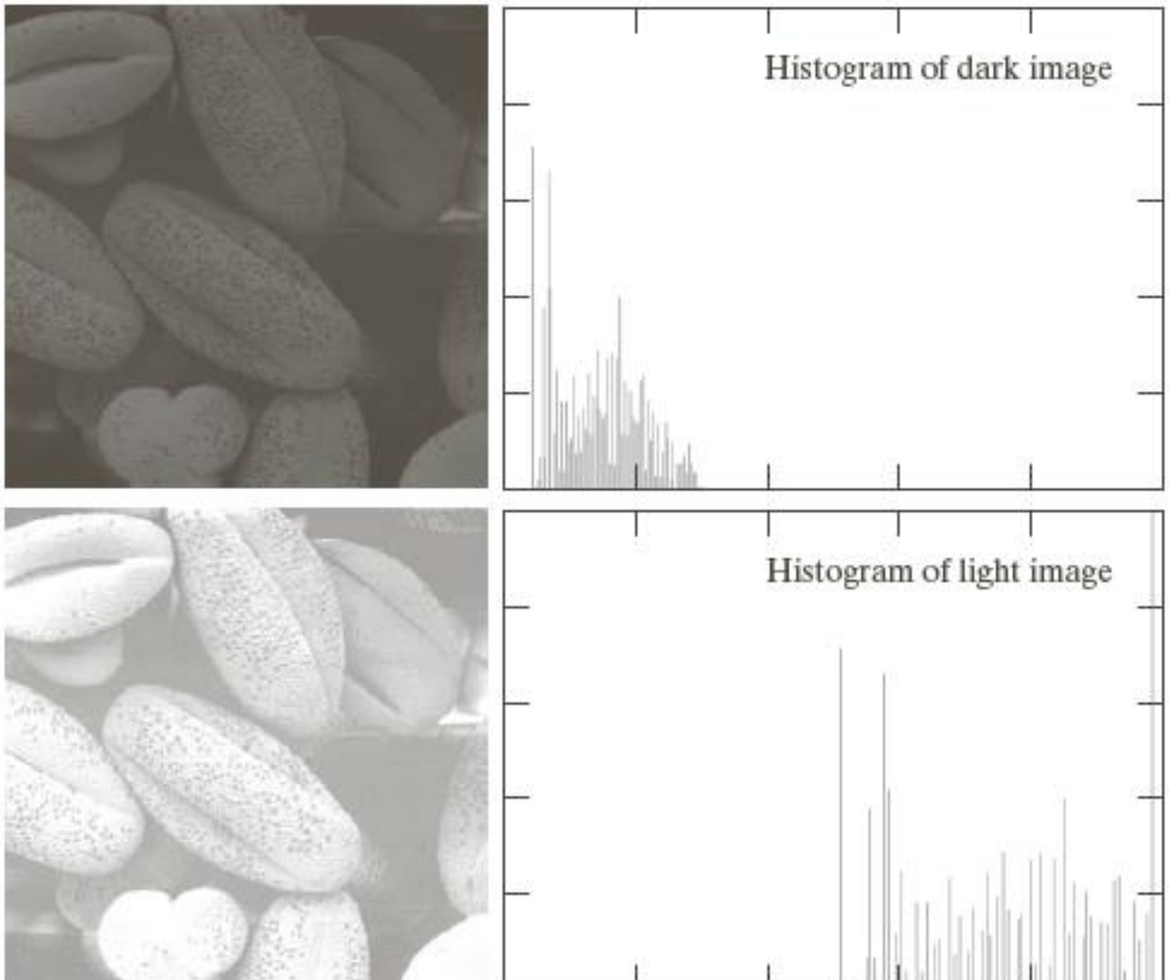
$$\boldsymbol{p(r_k) = n_k / MN}$$

  - For k = 0,1,…,L-1
  - $\boldsymbol{p(r_k)}$ gives an estimate of the probability of occurrence of gray level $\boldsymbol{r_k}$
  - The sum of all components of a normalized histogram is equal to 1
  - **M** and **N** are the row and column dimensions of the image.

# Histogram Processing

- Basic for numerous **spatial domain** processing techniques
- Used effectively for image enhancement
- **Information** inherent in histograms also is useful in **image compression** and **segmentation**
- Data-dependent pixel-based image enhancement method.

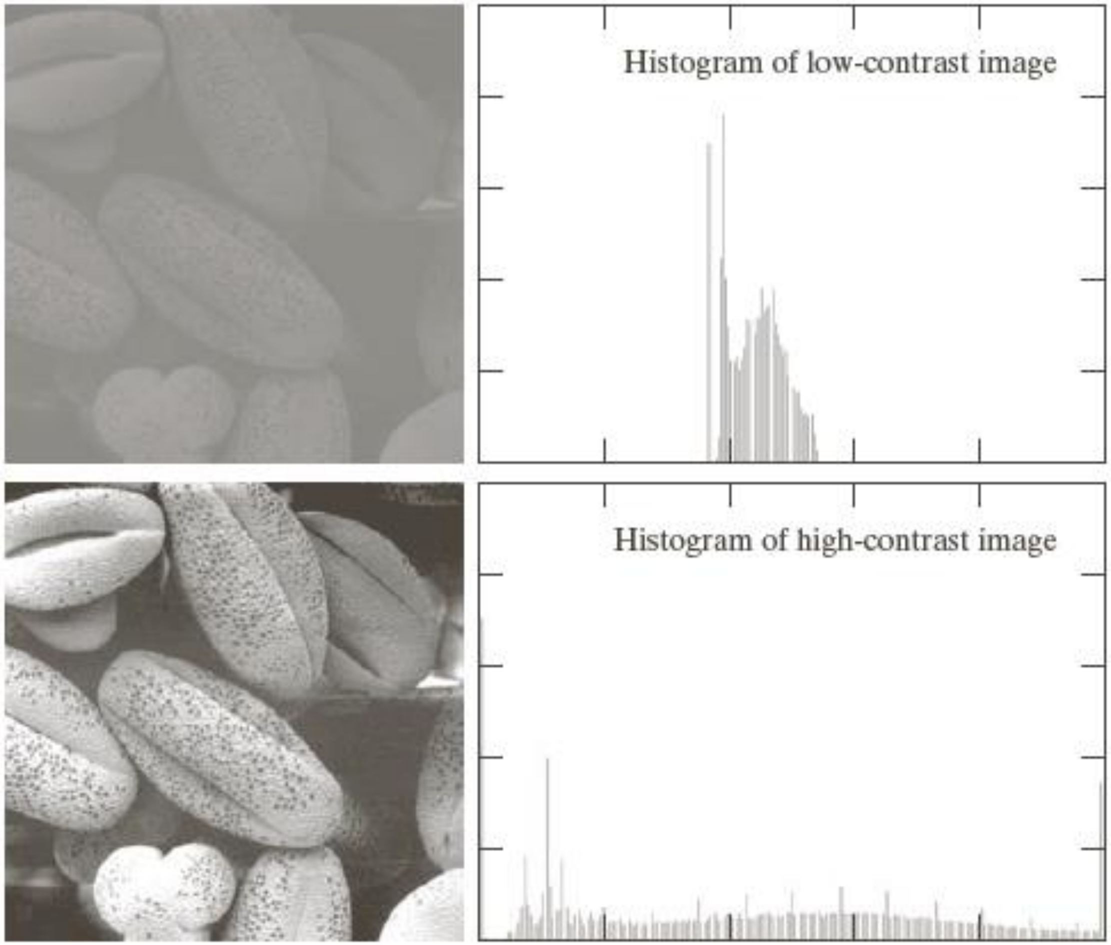
# Example




- **Dark image**
  - Components of histogram are concentrated on the low side of the gray scale.
- **Bright image**
  - Components of histogram are concentrated on the high side of the gray scale.

Images are from the Digital Image Processing textbook, see slide 7

# Example




- **Low-contrast image**
  - Histogram is narrow and centered toward the middle of the gray scale
- **High-contrast image**
  - Histogram covers broad range of the gray scale and the distribution of pixels is not too far from uniform, with very few vertical lines being much higher than the others

# Histogram Equalization

- As the low-contrast image's histogram is narrow and centered toward the middle of the gray scale, if we **distribute the histogram to a wider range** the quality of the image will be improved.

- We can do it by adjusting the **probability density function (PDF)** of the original histogram of the image so that the **probability spreads equally**

# Discrete intensities and histogram equalization

- For discrete values, we deal with probabilities (histogram values) instead of PDF. So $p_r(r_k)=n_k/MN$, $k=0,1,2,\ldots,L-1$
- Summations instead of integrals
- So $s_k=T(r_k)=(L\text{-}1)\sum_{j=0}^{k} p_r(rj) = \frac{(L-1)}{MN}\sum_{j=0}^{k} n_j$
- Thus, a processed (output) image is obtained by mapping each pixel in the **input image with intensity $r_k$ into a corresponding pixel with level $s_k$ in the output image**, using the above equation.

# Implementation

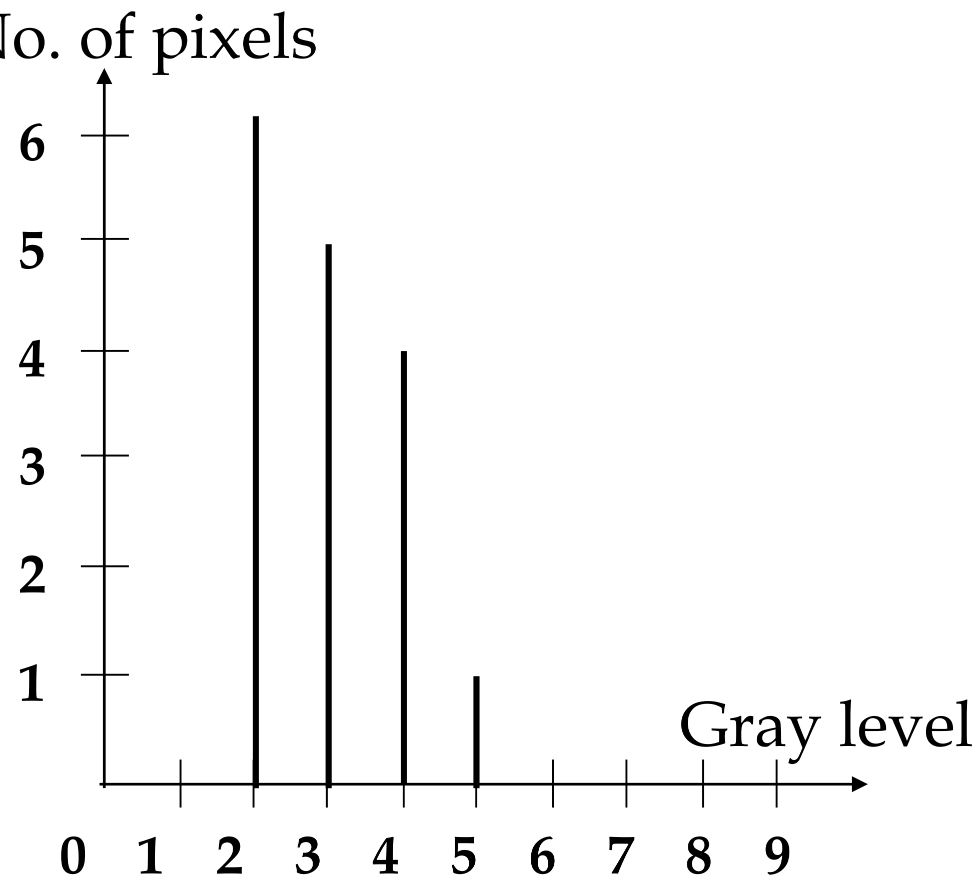
1. Obtain the histogram of the input image.
2. For each input gray level k, compute the cumulative sum.
3. For each gray level k, scale the sum by (max gray level)/(number of pixels).
4. Discretize the result obtained in 3.
5. Replace each gray level k in the input image by the corresponding level obtained in 4.

# Example

| | | | |
|---|---|---|---|
| 2 | 3 | 3 | 2 |
| 4 | 2 | 4 | 3 |
| 3 | 2 | 3 | 5 |
| 2 | 4 | 2 | 4 |

4x4 image

Gray scale = [0,9]




histogram

# Example

| Gray Level($k$) | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|---|---|---|---|---|---|---|---|---|---|
| No. of pixels ($n_k$) | | | | | | | | | | |
| $\sum_{j=0}^{k} n_j$ | | | | | | | | | | |
| $s = \sum_{j=0}^{k} \frac{n_j}{n}$ | | | | | | | | | | |
| **s x 9** | | | | | | | | | | |

# Example

| Gray Level($k$) | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|---|---|---|---|---|---|---|---|---|---|
| No. of pixels ($n_k$) | 0 | 0 | 6 | 5 | 4 | 1 | 0 | 0 | 0 | 0 |
| $\sum_{j=0}^{k} n_j$ | | | | | | | | | | |
| $s = \sum_{j=0}^{k} \frac{n_j}{n}$ | | | | | | | | | | |
| $s \times 9$ | | | | | | | | | | |

# Example

| Gray Level($k$) | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|---|---|---|---|---|---|---|---|---|---|
| No. of pixels ($n_k$) | 0 | 0 | 6 | 5 | 4 | 1 | 0 | 0 | 0 | 0 |
| $\sum_{j=0}^{k} n_j$ | 0 | 0 | 6 | 11 | 15 | 16 | 16 | 16 | 16 | 16 |
| $s = \sum_{j=0}^{k} \frac{n_j}{n}$ | | | | | | | | | | |
| **s x 9** | | | | | | | | | | |

# Example

| Gray Level($k$) | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|---|---|---|---|---|---|---|---|---|---|
| No. of pixels ($n_k$) | 0 | 0 | 6 | 5 | 4 | 1 | 0 | 0 | 0 | 0 |
| $\sum_{j=0}^{k} n_j$ | 0 | 0 | 6 | 11 | 15 | 16 | 16 | 16 | 16 | 16 |
| $s = \sum_{j=0}^{k} \frac{n_j}{n}$ | 0 | 0 | 6 / 16 | 11 / 16 | 15 / 16 | 16 / 16 | 16 / 16 | 16 / 16 | 16 / 16 | 16 / 16 |
| **s x 9** | | | | | | | | | | |

maximum

# Example

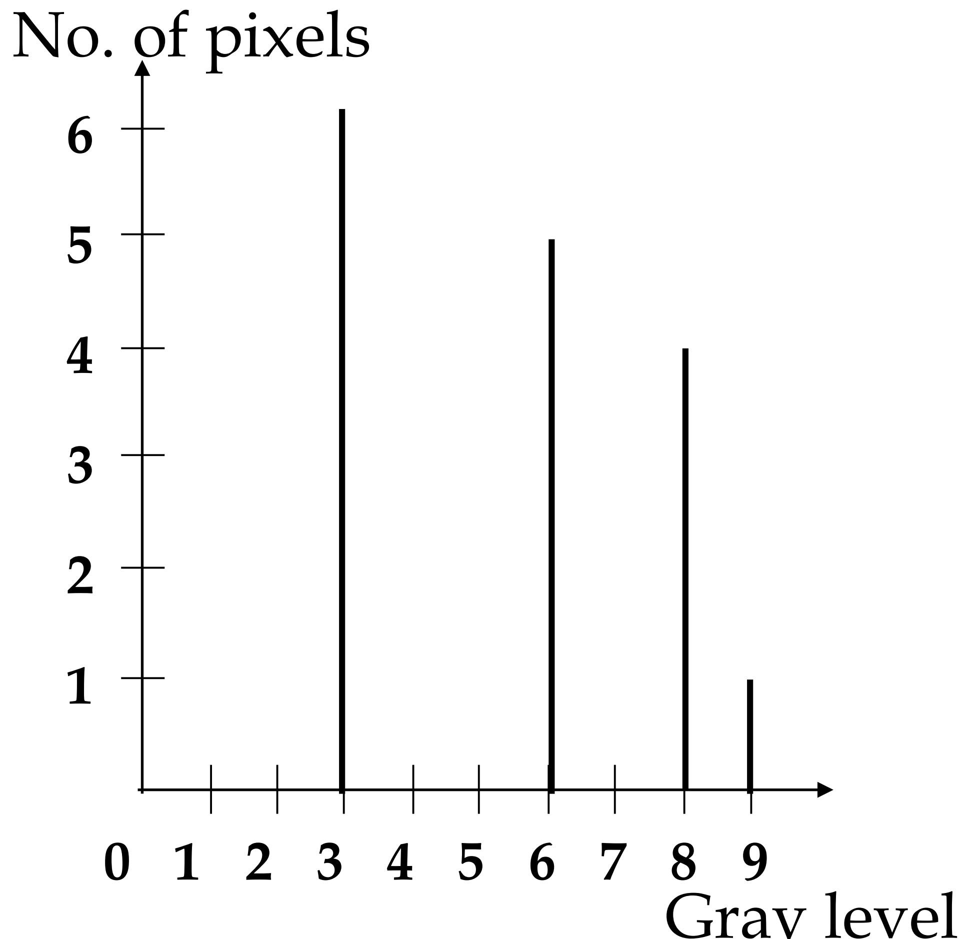
| Gray Level($k$) | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|---|---|---|---|---|---|---|---|---|---|
| No. of pixels ($n_k$) | 0 | 0 | 6 | 5 | 4 | 1 | 0 | 0 | 0 | 0 |
| $\sum_{j=0}^{k} n_j$ | 0 | 0 | 6 | 11 | 15 | 16 | 16 | 16 | 16 | 16 |
| $s = \sum_{j=0}^{k} \frac{n_j}{n}$ | 0 | 0 | 6 / 16 | 11 / 16 | 15 / 16 | 16 / 16 | 16 / 16 | 16 / 16 | 16 / 16 | 16 / 16 |
| **s x 9** | 0 | 0 | 3.3 ≈3 | 6.1 ≈6 | 8.4 ≈8 | 9 | 9 | 9 | 9 | 9 |

# Example

| | | | |
|---|---|---|---|
| 3 | 6 | 6 | 3 |
| 8 | 3 | 8 | 6 |
| 6 | 3 | 6 | 9 |
| 3 | 8 | 3 | 8 |

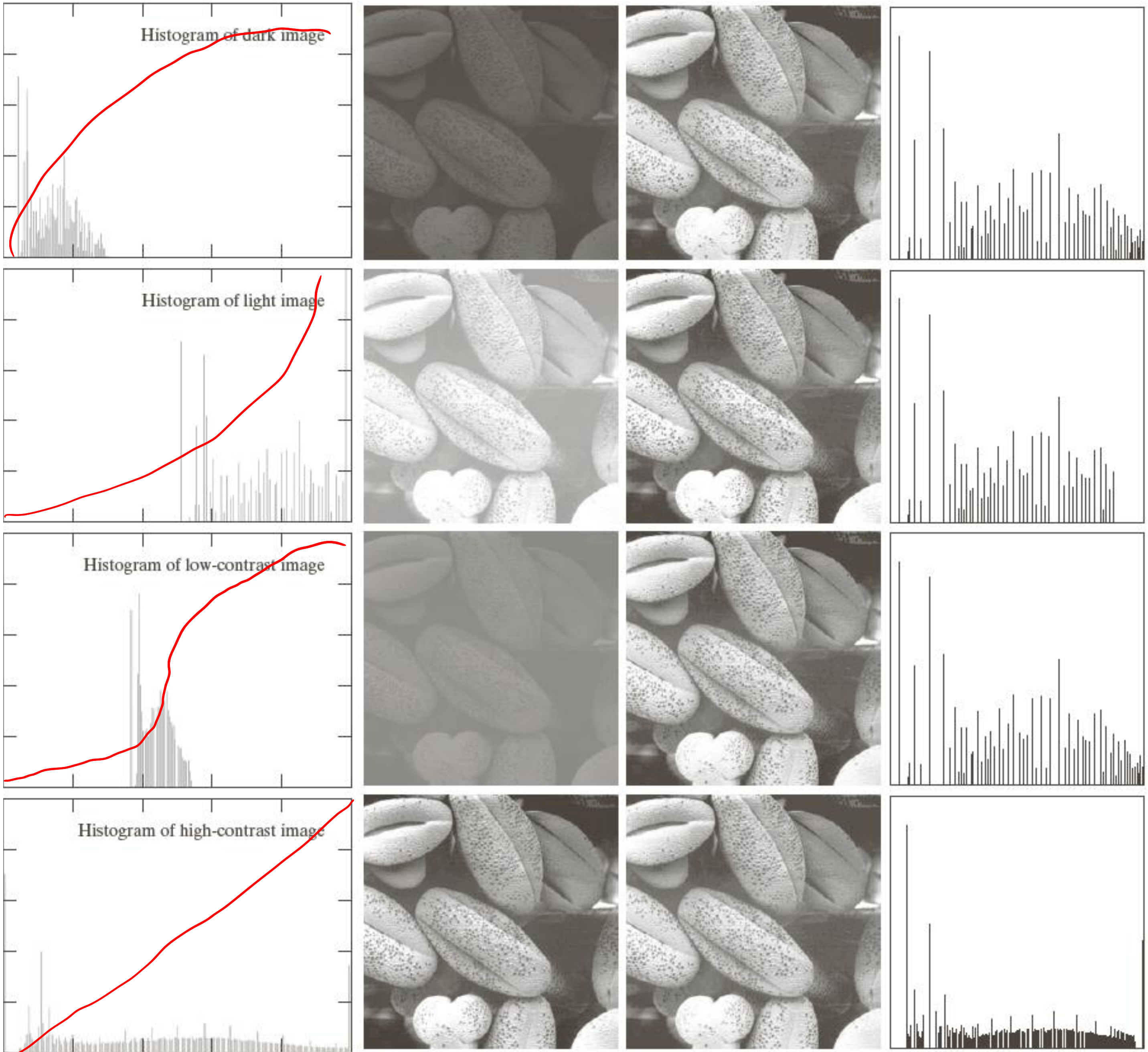
Output image

Gray scale = [0,9]




Histogram equalization

# Histogram equalization Example




- First column from left is histogram for each picture in the secod column.
- Third column for left is the images after applying histogram equalization to each correspondent image in the second column
- Fourth column is shows histogram of each image in the third column

# Properties of Histogram Equalization

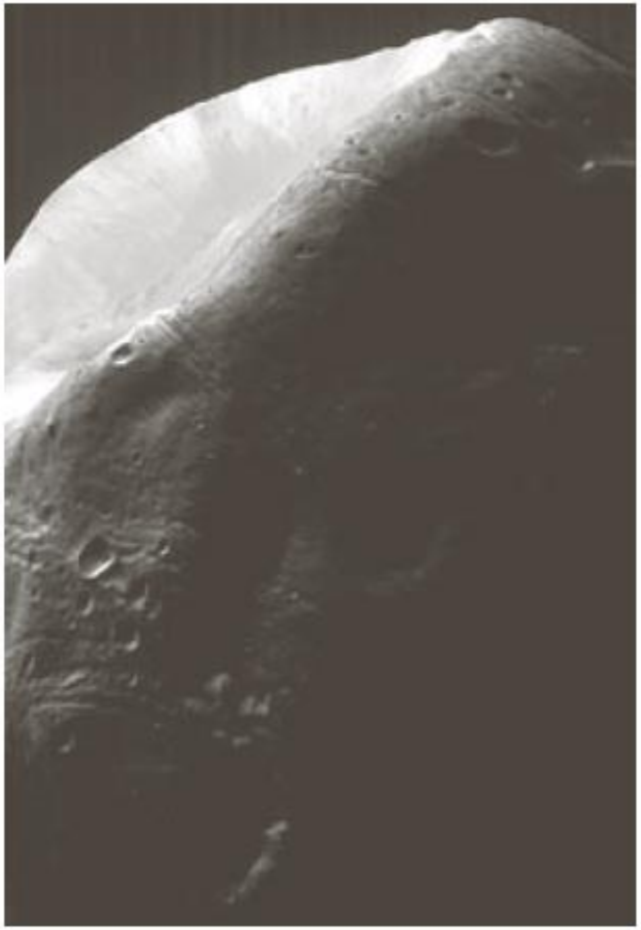
- The gray levels are spread over the entire intensity reange
  - Fully automatic
  - Data dependent
  - contrast enhancement

- Perfectly flat histograms are rare in practical applications of histogram equalization.

# Histogram Matching (Specification)

- Histogram equalization has a disadvantage which is, it can generate only **one type of output image**.
- This is **not always disired**, and **may not work** for some applications
- It doesn't have to be a uniform histogram
- It is useful sometimes to be able to specify the **shape of the histogram that we wish the processed image to have**.
- To generate a processed image that has a specified histogram is called *histogram matching* or *histogram specification.*

# Example



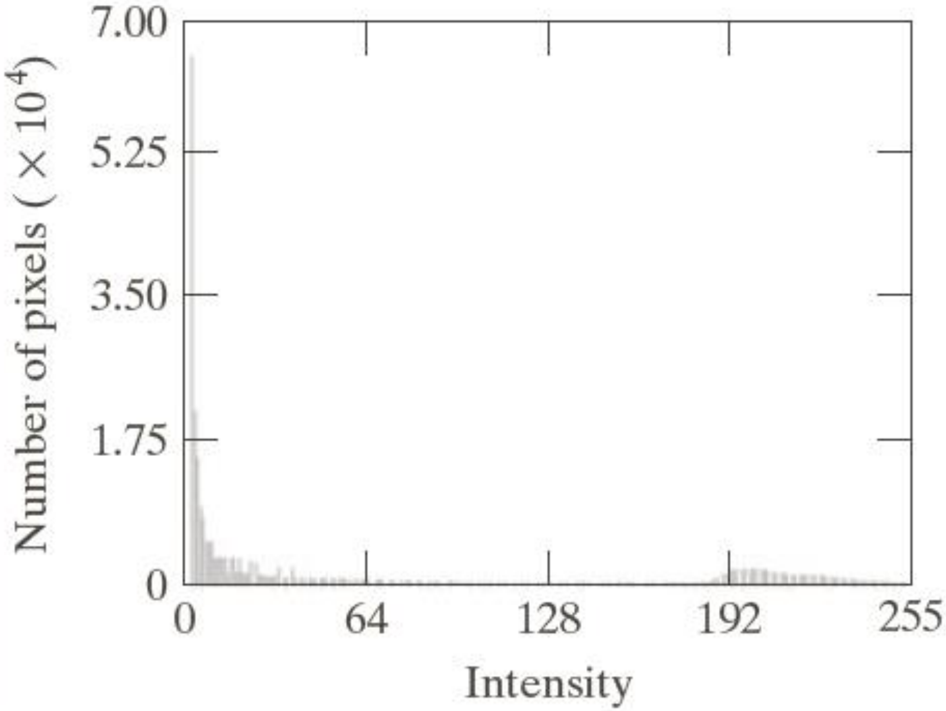
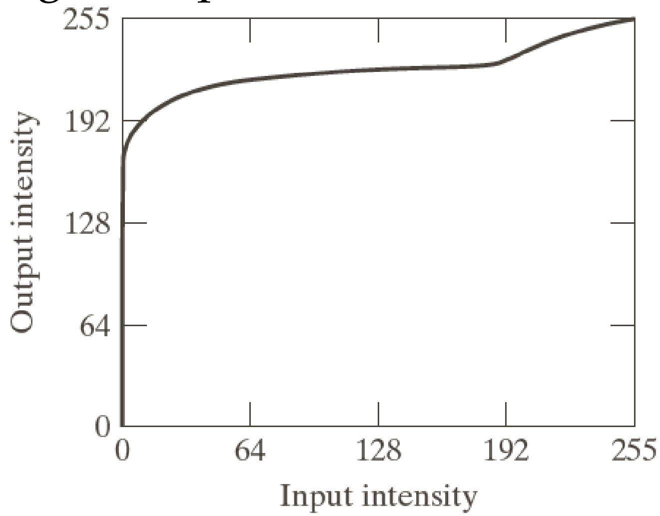
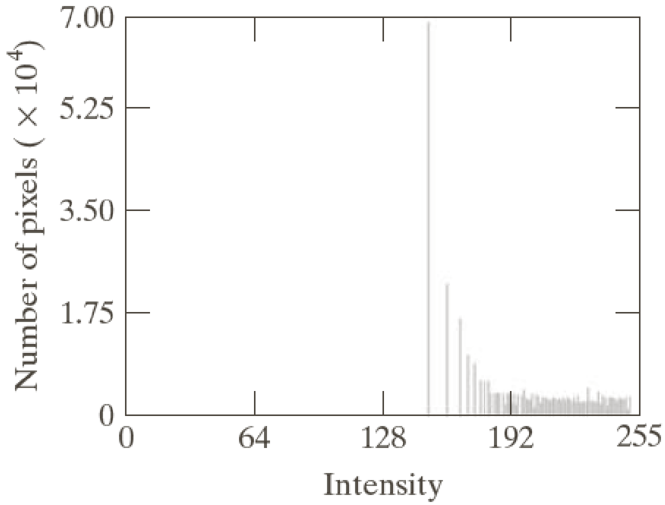



Image is dominated by large, dark areas, resulting in a histogram characterized by a large concentration of pixels in pixels in the dark end of the gray scale

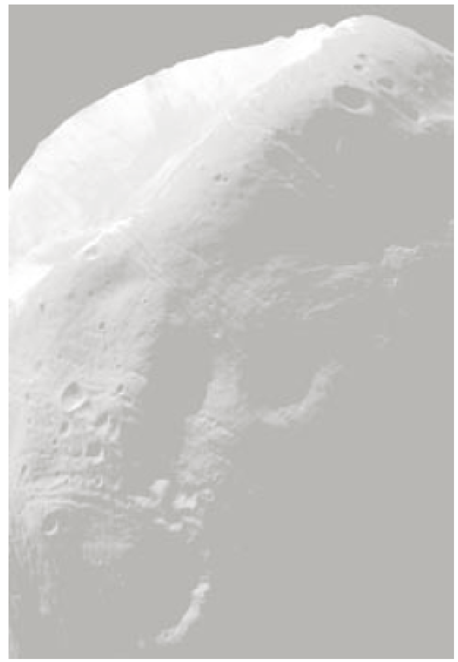
# Histogram Equalization

Transformation function for histogram equalization




Transformation function for histogram equalization



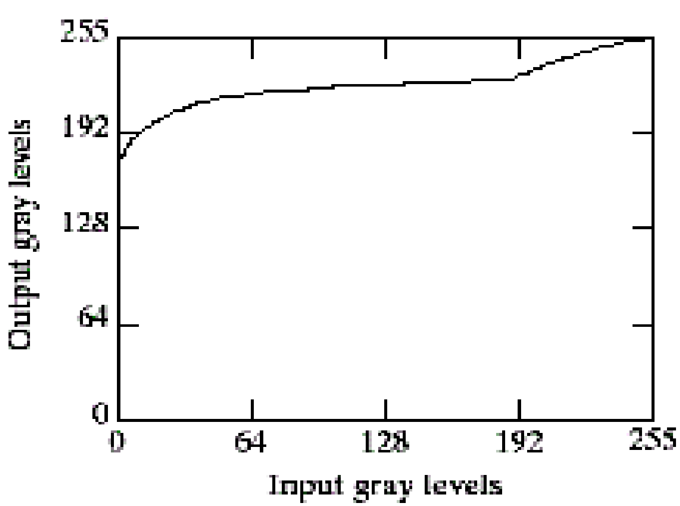
Result image after histogram equalization

- The histogram equalization doesn't make the result image look better than the original image.
- Consider the histogram of the result image, the net effect of this method is to map a very narrow interval of dark pixels into the upper end of the gray scale of the output image.
- As a consequence, the output image is light and has a washed-out appearance.

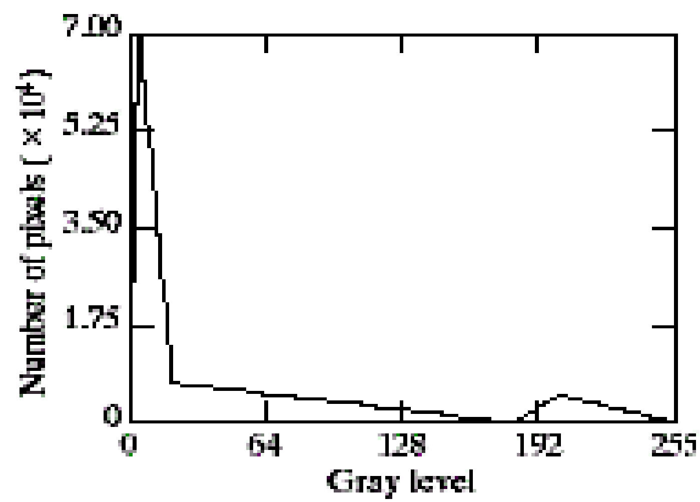
# Solve the Problem

- Since the problem with the transformation function of the histogram equalization was caused by a **large concentration of pixels in the original image with levels near 0**
- A reasonable approach is to modify the histogram of that image so that it does not have this property

Histogram Equalization




Histogram Specification

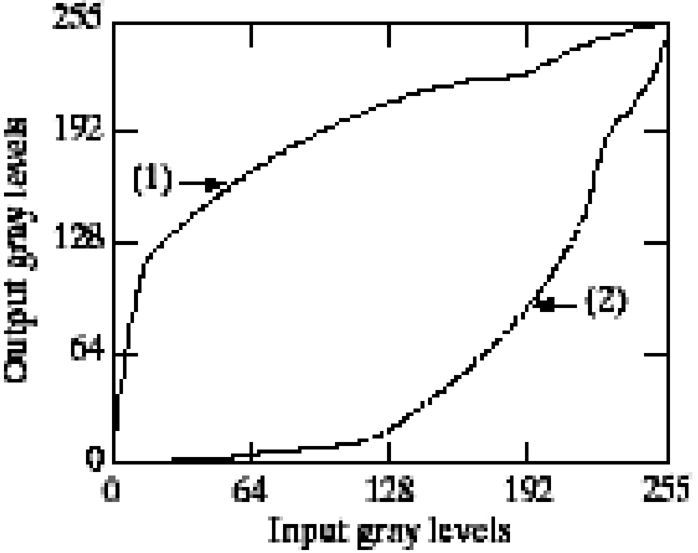


# Histogram Specification

- (1) The transformation function G(z) obtained from

$$G(z_k) = \sum_{i=0}^{k} p_z(z_i) = s_k$$

$$k = 0,1,2,\ldots, L-1$$




- (2) The inverse transformation $G^{-1}(s)$

# Histogram Specification

(1) Obtain the transformation function $T(r)$ by calculating the histogram equalization of the input image

$$S = T(r)$$

(2) Obtain the transformation function $G(z)$ by calculating histogram equalization of the desired density function

$$v = G(z)$$

# Histogram Specification

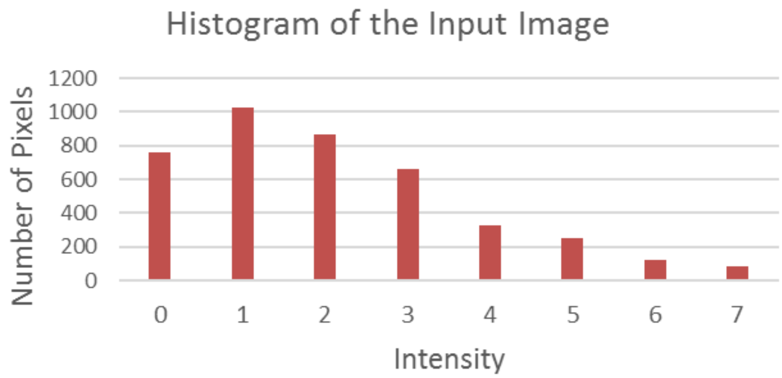
(3) Set v = s to obtain the inversed transformation function $G^{-1}$

$$z = G^{-1}(s) = G^{-1}[T(r)]$$

(4) Obtain the output image by applying the processed gray-level from the inversed transformation function to all the pixels in the input image

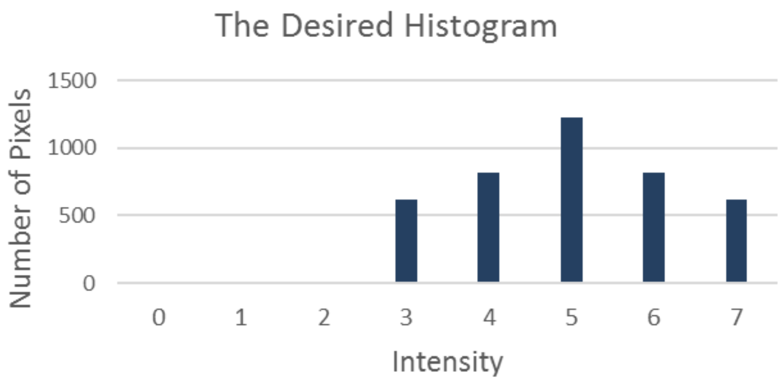
# Histogram Specification - Example

- Given a histogram for 8-level image




| | |
|---|---|
| 0 | 760 |
| 1 | 1023 |
| 2 | 870 |
| 3 | 660 |
| 4 | 331 |
| 5 | 249 |
| 6 | 122 |
| 7 | 81 |

- Match it to this histogram




| | |
|---|---|
| 0 | 0 |
| 1 | 0 |
| 2 | 0 |
| 3 | 615 |
| 4 | 819 |
| 5 | 1229 |
| 6 | 819 |
| 7 | 614 |

# Histogram Specification - Example

(1) Equalize the histogram of the input image using transform $s = T(r)$

| $r$ | $n_r$ | $\sum$ | $s$ | $s*7$ | $s=T(r)$ |
|---|---|---|---|---|---|
| 0 | 760 | 760 | 0.185547 | 1.298828 | 1 |
| 1 | 1023 | 1783 | 0.435303 | 3.047119 | 3 |
| 2 | 870 | 2653 | 0.647705 | 4.533936 | 5 |
| 3 | 660 | 3313 | 0.808838 | 5.661865 | 6 |
| 4 | 331 | 3644 | 0.889648 | 6.227539 | 6 |
| 5 | 249 | 3893 | 0.950439 | 6.653076 | 7 |
| 6 | 122 | 4015 | 0.980225 | 6.861572 | 7 |
| 7 | 81 | 4096 | 1 | 7 | 7 |

# Histogram Specification - Example

(2) Equalize the desired histogram $v = G(z)$

| $z$ | $n_z$ | $\sum$ | $v$ | $v*7$ | $v=T(z)$ |
|---|---|---|---|---|---|
| 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | 0 | 0 | 0 |
| 2 | 0 | 0 | 0 | 0 | 0 |
| 3 | 615 | 615 | 0.150146 | 1.051025 | 1 |
| 4 | 819 | 1434 | 0.350098 | 2.450684 | 2 |
| 5 | 1229 | 2663 | 0.650146 | 4.551025 | 5 |
| 6 | 819 | 3482 | 0.850098 | 5.950684 | 6 |
| 7 | 614 | 4096 | 1 | 7 | 7 |

# Histogram Specification - Example

- (3) Set $v = s$ to obtain the composite transform $z = G^{-1}(s) = G^{-1}[T(r)]$

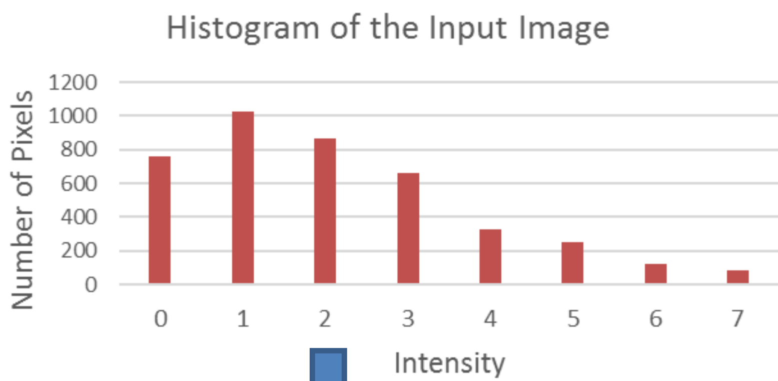
| $r$ | $s=T(r)$ | $z = G^{-1}[T(r)]$ |
|---|---|---|
| 0 | 1 | 3 |
| 1 | 3 | 4 |
| 2 | 5 | 5 |
| 3 | 6 | 6 |
| 4 | 6 | 6 |
| 5 | 7 | 7 |
| 6 | 7 | 7 |
| 7 | 7 | 7 |

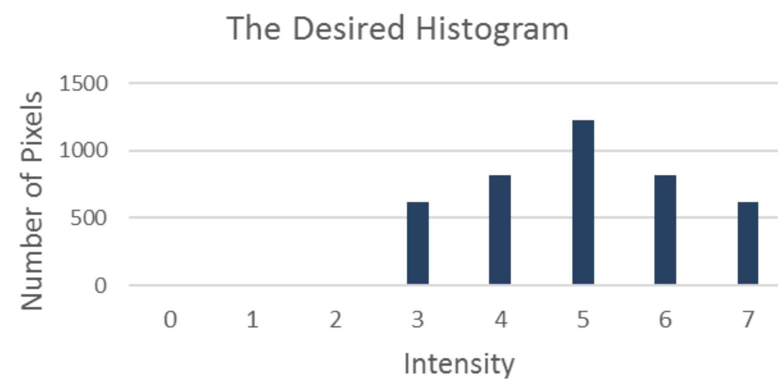
# Histogram Specification - Example

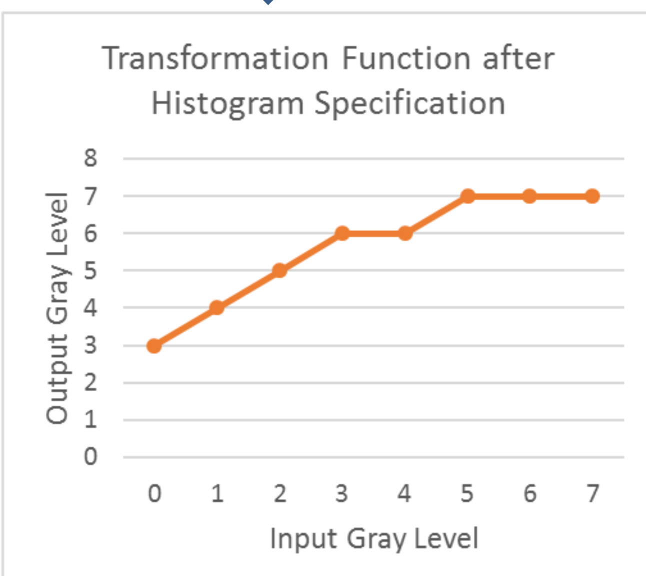
- (4) Obtain the output image (after histogram specification) according to the following table:

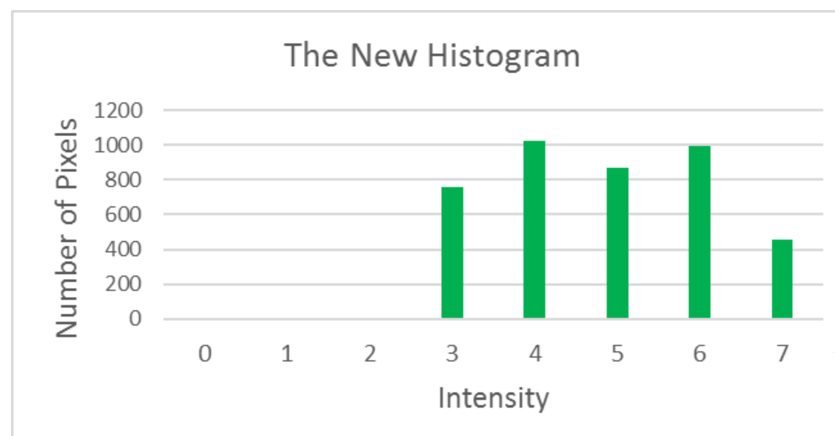
| Input gray level | Output gray level |
|---|---|
| 0 | 3 |
| 1 | 4 |
| 2 | 5 |
| 3 | 6 |
| 4 | 6 |
| 5 | 7 |
| 6 | 7 |
| 7 | 7 |

# Histogram Specification - Summary



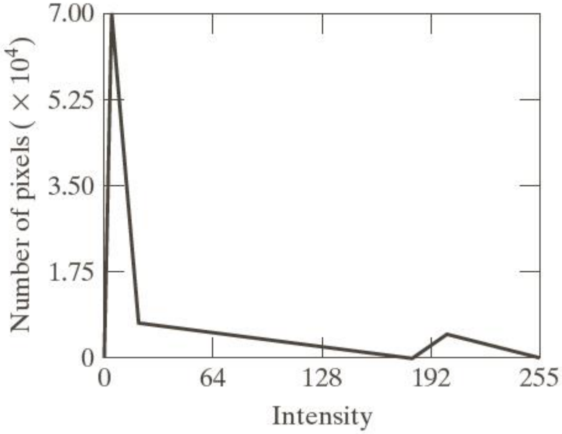



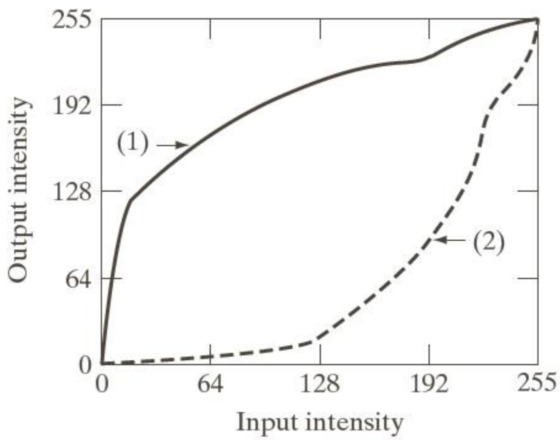



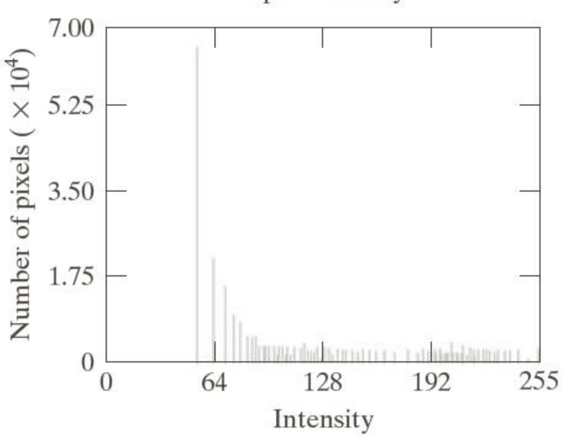




| | |
|---|---|
| 0 | 3 |
| 1 | 4 |
| 2 | 5 |
| 3 | 6 |
| 4 | 6 |
| 5 | 7 |
| 6 | 7 |
| 7 | 7 |

# Result Image and its Histogram




After histogram Specification

Result image after histogram equalization

Original image

Notice that the output histogram's low end has shifted right toward the lighter region of the gray scale as desired.

# Note

- Histogram specification is a **trial-and-error process**

- There are **no rules** for specifying histograms, and one must resort to analysis on a **case-by-case** basis for any given enhancement task.

# Note

- The previously Histogram processing methods are **global processing**, in the sense that pixels are modified by a transformation function based on the gray-level content of an entire image.

- Sometimes, we may need to enhance details **over small areas in an image**, which is called a **local enhancement**.

# Local histogram

- The procedure is to define a neighborhood and move its center from pixel to pixel.
- At each location, the histogram of the points in the neighborhood is computed and either a histogram equalization or histogram specification transformation function is obtained.
- The movement overlapping produce no problem. The nonoverlapping movement, however, produces an undesirable „blocky” effect

# Local Enhancement

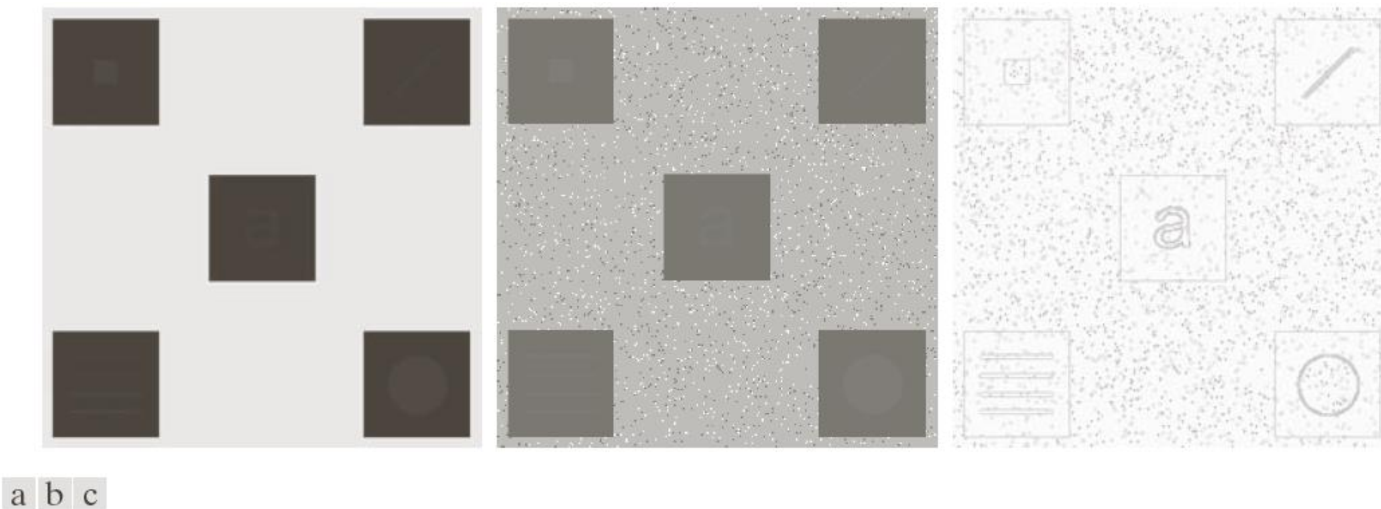


FIGURE 3.26 (a) Original image. (b) Result of global histogram equalization. (c) Result of local histogram equalization applied to (a), using a neighborhood of size 3 × 3.

a) Original image (slightly blurred to reduce noise)
b) global histogram equalization (enhance noise & slightly increase contrast but the construction is not changed)
c) local histogram equalization using 3x3 neighborhood (reveals the small squares inside larger ones of the original image.

# Explanation of the result in c)

- Basically, the original image consists of many small objects inside the larger dark squares.
- However, the small objects were too close in gray level to the larger squares, and their sizes were too small to influence global histogram equalization significantly.
- So, when we use the local enhancement technique, it reveals the small areas.
- Note also the finer noise texture is resulted by the local processing using relatively small neighborhoods.

# Using Histogram Statistics for Image Enhancement

- Mean and variance can be calculated using the n<sup>th</sup>-momentum equation using histogram, but it also can be caluculated using the following equations:

mean

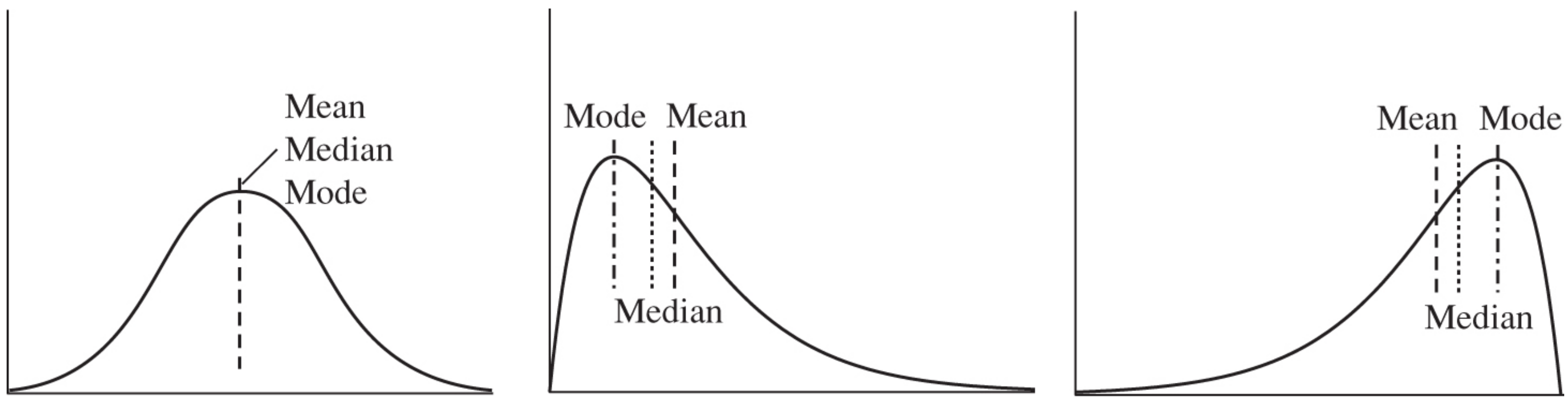
- $m = \frac{1}{MN}\sum_{x=0}^{M-1}\sum_{y=0}^{N-1} f(x,y)$
- $\sigma^2 = \frac{1}{MN}\sum_{x=0}^{M-1}\sum_{y=0}^{N-1}[f(x,y) - m]^2$

standard deviation

Images are from the Digital Image Processing textbook, see slide 7

# Symmetric vs. Skewed Data

- Median, mean and mode of symmetric, positively and negatively skewed data




**(a)** Symmetric data **(b)** Positively skewed data **(c)** Negatively skewed data

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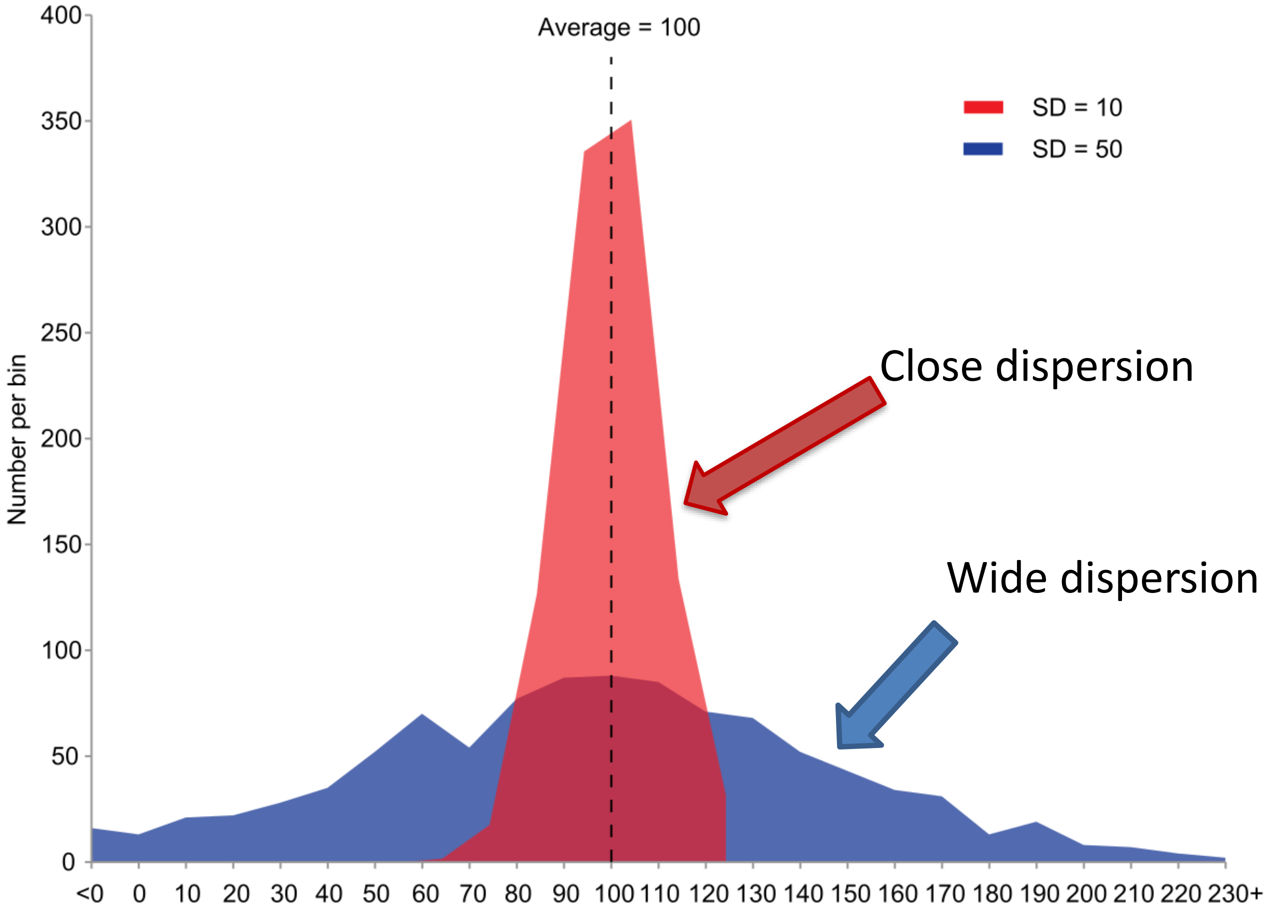
# Measuring the Dispersion of Data




Images are from the Digital Image Processing textbook, see slide 7