

Department of Computing and Mathematics

M.Sc. in Artificial Intelligence

Assessment:

AUTOTRADER CARPRICE PREDICTION

Module: ADVANCED MACHINE LEARNING

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Chapter 1: Data Processing for Machine Learning

1.0. I used this to generates a dataset summary to make sense of my data e.g correlations

```
[1] !pip install ydata-profiling
```

1.1. I mount directly from my Google Drive so I don't have to upload every time.

```
from google.colab import drive
drive.mount("/content/drive/", force_remount=True)

Mounted at /content/drive/
```

1.2 Here I imported my libraries for visualization, my analysis, sets plotting format, random seed (for reproducing my result), and imports 'ProfileReport' and 'StandardScaler'.

```
import random
import matplotlib.pyplot as plt
import pandas as pd
import numpy as np
import seaborn as sns
from ydata_profiling import ProfileReport
from sklearn.preprocessing import StandardScaler

*config InlineBackend.figure_format = 'retina'
sns.set(
    style='ticks',
    context='talk',
    font_scale=0.8,
    rc=('figure.figsize': (8,6))
)

seed = 60
random.seed(seed)
np.random.seed(seed)
np.random.seed(seed)
```

1.3. Here, I read my file from the Google Drive and displays the first few rows of the DataFrame.



1.4. I checked the price of over 2 million to really know if they were real great cars or mere mistakes.

<pre>over_2m = df.query('price > 2e6') print(over_2m.shape) over_2m.head()</pre>											
(16, 12	,	mileage	reg_code	standard_colour	standard_make	standard_model	vehicle_condition	year_of_registration	price	body_type	crossov
51741	202002257718775	4400.0	14	Black	Bugatti	Veyron	USED	2014.0	2850000	Coupe	
64910	202006039766650	189.0	NaN	Black	McLaren	P1	USED	NaN	2695000	Coupe	
72681	202007010711087	475.0	15	Yellow	Ferrari	LaFerrari	USED	2015.0	2299950	Coupe	
94033	202007020778467	1900.0	18	White	Pagani	Huayra	USED	NaN	2400000	Convertible	
141833	202007050883898	87450.0	NaN	Red	Ferrari	250	USED	NaN	9999999	Coupe	

Chapter 2. Feature Engineering

- 2.0.I dropped public_reference, standard_model, and reg_code columns because they were too distinct, meaning unique/uncorrelated and represented already
- 2.1. I also dropped rows with a price and mileage of 9,999,999 because they were clearly placeholders/errors.
- 2.2.Moving further, I converted the mileage & crossover_car_and_van columns to float and string respectively. The reason I did this is to enable me work with the mileage more precisely and since 'crossover' is categorical, it makes more sense as string.



2.3.For standard_colour, instead of dropping missing rows ridiculously, I gathered all the colours and generated random colours from my list for the missing columns.

did a tricky thing next, for all the new

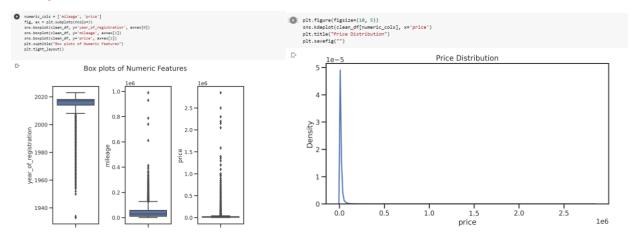
cars I changed it to 2023 for year registered (This doesn't matter, I just thought they can be bought this year)

- 2.5. For invalid year of registration, I went further with my inquisitive nature, I saw some real cars registered between 1921 & 'new'. I literarily googled the old car and saw them. So, instead of dropping unintelligently, I simply dropped values below 1921. Moreso, cars were invented in 1886 and they were weird cars at that, more like carriages. Doesn't make sense to have cars registered earlier. Then, I converted to integers.
- 2.6.Body type & fuel type missing values are removed. No point keeping them, no impact

	marcago	Demmara_corour	Deamanka_mane	venicie_condicion	Jear_or_regreeren	price	poul_clbc	erossorer_ear_ana_van	rucz_c/pc
0	0.0	Grey	Volvo	NEW	2023	73970	suv	False	Petrol Plug-in Hybrid
1	108230.0	Blue	Jaguar	USED	2011	7000	Saloon	False	Diesel
2	7800.0	Grey	SKODA	USED	2017	14000	suv	False	Petrol
3	45000.0	Brown	Vauxhall	USED	2016	7995	Hatchback	False	Diesel
4	64000.0	Grey	Land Rover	USED	2015	26995	SUV	False	Diesel

2.7.My cleaned dataset

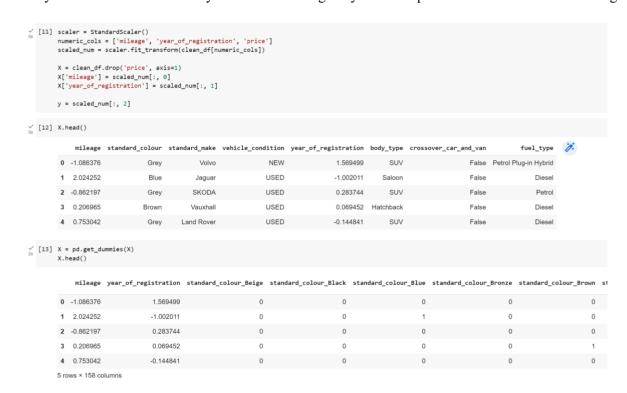
2.4.I



2.8.Here, I visualized my year of registration, mileage, price and the distribution. To see the outliers. I know there are but I want to make it robust.

Chapter 3. Feature Selection and Dimensionality Reduction

- 3.0. I did numerical scaling to my price, mileage, year of registration here.
- 3.1. To prepare the new dataset for training, I dropped price and parsed the rest into X
- 3.2. I assigned the price, my target to Y
- 3.3. When I use the get_dummies(), it auto creates a new column for each unique value in the variable. For each row, the corresponding column is set to 1, while all other columns are set to 0. The reason why I did this is to make my Machine learning easy. This step is known as one-hot encoding.



Chapter 4. Model Building

4.1 **A Linear Model**: After importing my necessary libraries, I used the X_train and y_train data to train the linear regression model, the target variable values are then predicted using the X test data. The values in the array are my y pred.

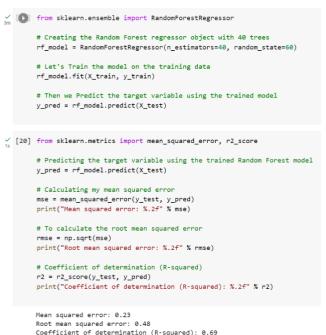
```
v [15] from sklearn.linear_model import LinearRegression
         from sklearn.metrics import precision_recall_fscore_support
         # We will create a Linear Regression model object
         lr_model = LinearRegression()
         # Then here we train the model
        lr_model.fit(X_train, y_train)
         # Then, we predict the target variable model we trained above
        y_pred = lr_model.predict(X_test)
/ [16] y_pred
        array([-0.14553737, -0.56337729, 0.11060696, ..., 0.14093772, -0.1159312 , -0.17476165])
/ [17] y_test
         array([-0.24141814, -0.46871322, 0.06301404, ..., -0.16886895,
                 -0.21590587, -0.13207982])
✓ [18] from sklearn.metrics import mean squared error, r2 score
         # To get my mean squared error
        mse = mean_squared_error(y_test, y_pred)
print("Mean squared error: %.2f" % mse)
        # For the root mean squared error
         rmse = np.sqrt(mse)
        print("Root mean squared error: %.2f" % rmse)
         # coefficient of determination (R-squared)
        r2 = r2_score(y_test, y_pred)
print("Coefficient of determination (R-squared): %.2f" % r2)
        Mean squared error: 0.30
Root mean squared error: 0.55
        Coefficient of determination (R-squared): 0.59
```

To know how well my the test fits the data, I checked for; Mean squared error (MSE) measuring the average squared difference of the predicted values and the actual values. Root mean squared error (RMSE) is the square root of the MSE above. Coefficient of determination explains the proportion of the variance in the target variable that is explained by the linear regression model.

Result

With a mean squared error of 0.3 and a root mean squared error of 0.55, my linear regression model's overall accuracy was 59%.

4.2 A Random Forest Model: Using the training set of data, I built my Random Forest



regressor object with 40 trees. Finally, fit & predicted the target variable for the test using the trained model.

Result

The Random Forest model is better than Linear regression above because it reduced the mean squared error to 0.23, RSME to 0.48 and improved the R-squared value to 69%.

4.3 A Boosted Tree: I used a learning rate of 0.1 and a random state of 60, this trains the

```
from sklearn.ensemble import GradientBoostingRegressor
     from sklearn.metrics import mean_squared_error, r2_score
     # To create the Gradient Boosting regressor object
     gb_model = GradientBoostingRegressor(n_estimators=40, learning_rate=0.1, random_state=60)
     # Training the model with the training data
     gb_model.fit(X_train, y_train)
     # Here we predict the target variable using the trained model
     y_pred = gb_model.predict(X_test)
     # We evaluate the performance
     mse = mean_squared_error(y_test, y_pred)
     rmse = np.sqrt(mse)
     r2 = r2_score(y_test, y_pred)
     print("Mean squared error: %.2f" % mse)
     print("Root mean squared error: %.2f" % rmse)
     print("Coefficient of determination (R-squared): %.2f" % r2)
    Mean squared error: 0.30
     Root mean squared error: 0.54
     Coefficient of determination (R-squared): 0.60
```

Gradient Boosting Regression model with 40 estimators. The target variable is then predicted by the model like the models above where accuracy of the prediction is assessed using R-squared, MSE, and RSME.

Result

The MSE being the average

squared difference between pred and actual values is 0.30, RMSE i.e square root as said earlier is 0.54. The coefficient of determination (R-squared), which is 60% in this case. So, Random Forest is better in explaining my data.

4.4. **LightGBM**: I found this model type while doing my assessment and tried it. I installed

```
| Looking in Indexes: https://pub.ore/simple, https://us-nython.des.dev/colab-mheels/qublic/simple
| Requirement already satisfied: lightgom in /usr/local/lib/python3.18/dist-packages (33.3.5)
| Requirement already satisfied: wheel in /usr/local/lib/python3.18/dist-packages (from lightgom) (1.22.4)
| Requirement already satisfied: wheel in /usr/local/lib/python3.18/dist-packages (from lightgom) (1.22.4)
| Requirement already satisfied: scikit-learniep.22.0 in /usr/local/lib/python3.18/dist-packages (from sightgom) (1.2.2)
| Requirement already satisfied: scikit-learniep.22.0 in /usr/local/lib/python3.18/dist-packages (from sightgom) (1.2.0)
| Requirement already satisfied: threadpoolctl>w2.0.0 in /usr/local/lib/python3.18/dist-packages (from scikit-learniep.22.0-)lightgom) (1.2.0)
| Requirement already satisfied: threadpoolctl>w2.0.0 in /usr/local/lib/python3.18/dist-packages (from scikit-learniep.22.0-)lightgom) (1.2.0)
| Requirement already satisfied: threadpoolctl>w2.0.0 in /usr/local/lib/python3.18/dist-packages (from scikit-learniep.22.0-)lightgom) (1.2.0)
| Requirement already satisfied: threadpoolctl>w2.0.0 in /usr/local/lib/python3.18/dist-packages (from scikit-learniep.0.22.0-)lightgom) (1.2.0)
| Requirement already satisfied: threadpoolctl>w2.0.0 in /usr/local/lib/python3.18/dist-packages (from scikit-learniep.0.22.0-)lightgom) (1.2.0)
| Requirement already satisfied: maintendent already in /usr/local/lib/python3.18/dist-packages (from scikit-learniep.0.22.0-)lightgom) (1.2.0)
| Remaintendent already satisfied: maintendent already in /usr/local/lib/python3.18/dist-packages (from scikit-learniep.0.22.0-)lightgom) (1.2.0)
| Remaintendent already satisfied: maintendent already in /usr/local/lib/python3.18/dist-packages (from scikit-learniep.0.22.0-)lightgom) (1.2.0)
| Remaintendent already satisfied: maintendent already s
```

the LightGBM library, created a LightGBM dataset, then went on to set my model's hyperparameters. Lastly, trained the model using the training data, and the target variable is predicted as the initial model I did above.

Result

The trained LightGBM model is used to predict the target variable, and the

performance of the model is assessed using the mean squared error, root mean squared error, and coefficient of determination (R-squared). When completed, coefficient of determination (R-squared), target variable's variance is explained to a degree of 68%, the MSE is 0.24 shows low level error and my RMSE of 0.49 meaning predictions are close to true values but not totally at all.

4.5. An Averager/Voter/Stacker Ensemble

- I created list of all models used above except LightGBM to use in the ensemble
- Then, I trained each model on the training data and tried the predictions on the test data
- Next, I computed the aevrage of the predictions above and the root mean squared error (RMSE) from the same average predictions
- Went on to computes the majority vote of the predictions and the RMSE of the majority vote's predictions
- I did a new dataset from the predictions and used it to train a meta-model (optional)
- Let's see the stacked model's predictions and the RMSE.

Result

• The Ensemble RMSE is 0.46: root mean squared error of the predictions made by average

```
\mbox{\tt\#} Creating a list of models to use in the ensemble models = [rf_model,
                    gb_model,
lr_model]
         # Train each model on the training data and make predictions on the test data
          predictions = []
         for model in models:
    y_pred = model.predict(X_test)
    predictions.append(y_pred)
         average predictions = np.mean(predictions, axis=0)
             We compute the root mean squared error based on the averager predictions
         rmse = np.sqrt(mean_squared_error(y_test, average_predictions))
         print("Ensemble RMSE: {:.2f}".format(rmse))
         # We compute the majority vote of the predictions
vote_predictions = np.round(np.mean(predictions, axis=0))
         # We Compute the root mean squared error of the majority vote's predictions
          rmse = np.sqrt(mean_squared_error(y_test, vote_predictions))
         print("Majority Vote RMSE: {:.2f}".format(rmse))
         # Here we will create a new dataset from the predictions and use it to train a meta-model (advanced)
         # I really don't need this step, But let's see
stacked_dataset = np.column_stack(predictions)
         meta model = LinearRegression()
          meta_model.fit(stacked_dataset, y_test)
         # We make predictions with the stacked model
         stacked_predictions = meta_model.predict(stacked_dataset)
         # Finally. Computing the root mean squared error of the stacked model's predictions
rmse = np.sqrt(mean_squared_error(y_test, stacked_predictions))
         print("Stacked Model RMSE: {:.2f}".format(rmse))
         Ensemble RMSE: 0.46
Majority Vote RMSE: 0.55
Stacked Model RMSE: 0.44
[26] from sklearn.ensemble import VotingRegressor
          from sklearn import metrics
         enble_model = VotingRegressor([gb_model,lr_model])
```

the predictions of the three models

- Majority Vote RMSE: 0.55: root mean squared error of the predictions made by taking the majority vote of the three models.
- Stacked Model RMSE: 0.44: root mean squared error of the predictions made by training a meta-model on the predictions of the three models. I used linear regression for my meta-model.

Observation

I noticed the scores are somewhat on par with my other models which is bizarre. I expected a better result since it averages all the model. Apparently, the linear regression just takes in the new dataset as just figures.

5.0 Model Evaluation and Analysis

5.1 Overall Performance with Cross-Validation

a. I went on to Perform the Cross-Validation utilizing the training data (X_train and Y_train) and a linear regression model (lr_model), the code runs 5-fold cross-validation with 'r2' as my score metric. The observed result of the five scores array, with the negative scores denoting a bad match and positive values denoting a better fit, shows the goodness of fit of the model for each fold. My first score's is severe negativity (-3.07834745e+15) and the other scores' proximity to zero, the first score stands out as an anomaly.

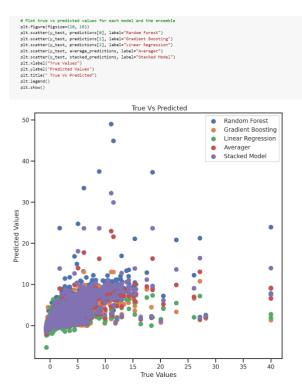
```
[ ] #LInear model
     from sklearn.model_selection import cross_val_score
     from sklearn import metrics
     result = cross_val_score( lr_model, X_train, y_train, cv=5, scoring='r2')
     array([-3.07834745e+15, 5.69733780e-01, -5.47851404e+14, 4.89956444e-01,
             5.55501405e-01])
[ ] #The Boosted Tree model
     from sklearn import metrics
     result = cross_val_score( gb_model, X_train, y_train, cv=5, scoring='r2')
     result
     array([0.47280835, 0.58396908, 0.58407736, 0.63075761, 0.62191164])
[ ] #my Random Forest model
     from sklearn import metrics
     from sklearn.model_selection import cross_val_score
     result = cross_val_score(rf_model, X_train, y_train, cv=5, scoring='r2')
     result
    array([0.64259594, 0.713573 , 0.75093412, 0.77949902, 0.74459367])
```

b. For Boosted Trees, the scores range from 0.47 to 0.63, the array of 5 scores shows that the model has a moderate to good fit for all folds. Overall, the findings of the cross-validation indicate that the Boosted Tree model would be a superior option over the linear regression model.

c. For Random Forest, the scores range from 0.64 to 0.78. Now, the cross-validation results

shows that the Random Forest model could be a strong candidate for further analysis.

5.2 True vs Predicted Analysis



a particular model, as shown by the legend.

The scatter plot here shows my 5 models (Random Forest, Gradient Boosting, Linear Regression, an Averager model, and a Stacked model). This contrasts the true values of the target variable (y_test) with their anticipated values. The true values are on the x-axis and predicted on y_axis. The predicted values are plotted as a scatter of points on the graph for each model.

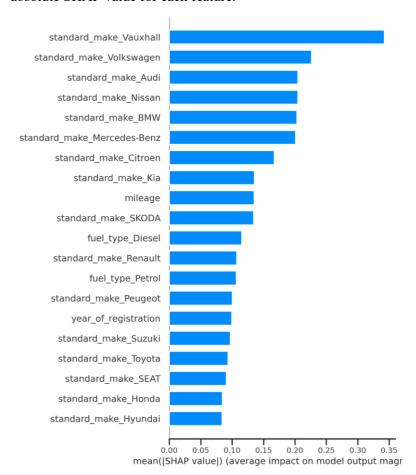
Result and Observation:

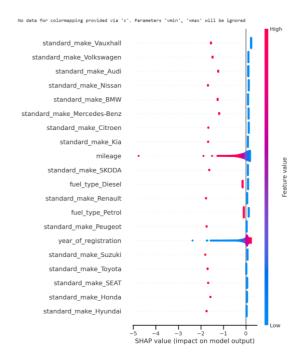
From what we can see comparing the performance of the models visually, we have almost all the models towards 0 and at one side. This means that the models are not making too much large errors in their prediction. They are similar, my actual and predicted. Each colour on the graph corresponds to

5.3 Global and Local Explanations with SHAP



object and uses two plots namely; a summary bar plot and a scatter plot to show the feature importance of each variable in the model's predictions. The scatter plot shows a more in-depth look at the link between the feature values and the model's predictions, while the summary bar plot displays the average absolute SHAP value for each feature.

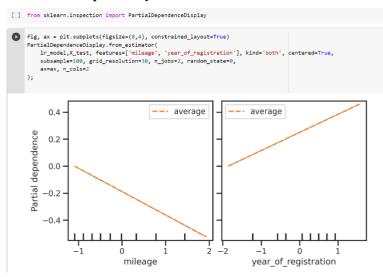




Result and Observation

The plots above shows the features that are perfect. Meaning they are the best for my model. You will notice that some of them are not originally column features from the adverts dataset e.g Standard_make_vauxhall and Volkswagen's. They were created from when I did the one hot encoding. My future work will be to test this features in building another model to see if they perform better.

5.4 Partial Dependency Plots



After importing my libraries, I generated my partial dependence plot for the mileage and year of registration features. The plot shows the anticipated target variable shifts as each feature is altered while maintaining those of the features. Another thing is, so as to individual and two-way display interaction graphs, the 'kind' option is set to 'both'. Just as I did with the

other above, the computation and presentation of the plot are done by the 'subsample', 'grid_resolution', and 'n_jobs' parameters. The 'axe' parameter defines the plot's axes, while the 'n_cols' option establishes the plot's number of columns.

Result & Observation: The main reason why all my result and also PDP is showing -1 to 2, -2 to 1, -0.4 to 0.4 is because of my scaler. I had scaled it earlier. The plot as mentioned above shows my spread and average of the feature I selected to understand it more.