zkMatrix: Batched Short Proof for Committed Matrix Multiplication

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AsiaCCS Presentation 2024.7



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Problem Definition: zkSNARK for Matrix Multiplication

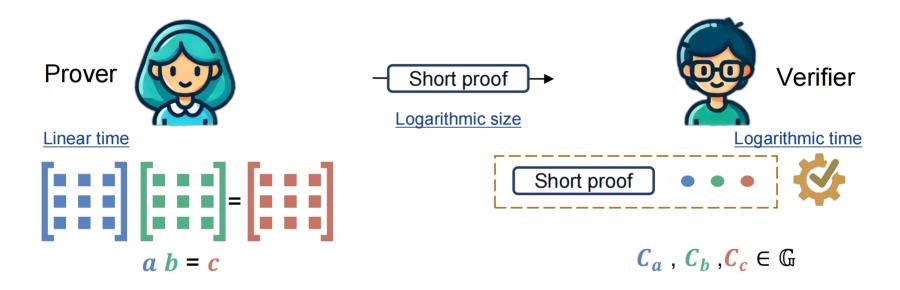


Figure: The prover holds three $n \times n$ secret matrices $a, b, c \in \mathbb{Z}_p^{n \times n}$. The verifier knows their commitments $C_a, C_b, C_c \in \mathbb{G}$. The prover provides a short proof to let the verifier verify that ab = c.

Matrix Commitment

- Commit a matrix $a \in \mathbb{Z}_p^{m \times n}$ to a group element $C_a \in \mathbb{G}$.
- ullet Pedersen vector commitment to $m{a}\in\mathbb{Z}_p^{m imes n}$ using bases $m{G}\in\mathbb{G}^{m imes n}$:

The committed matrix multiplication relation:

$$\mathcal{R}_{\mathsf{comMatMul}} = \left\{ \begin{pmatrix} C_c, C_a, C_b \in \mathbb{G}; \\ \boldsymbol{U} \in \mathbb{G}^{m \times n}, \\ \boldsymbol{G} \in \mathbb{G}^{m \times l}, \\ \boldsymbol{H} \in \mathbb{G}^{l \times n} \end{pmatrix} : \begin{pmatrix} \boldsymbol{c} \in \mathbb{Z}_p^{m \times n}, \\ \boldsymbol{a} \in \mathbb{Z}_p^{m \times l}, \\ \boldsymbol{b} \in \mathbb{Z}_p^{l \times n} \end{pmatrix} \middle| \begin{pmatrix} \boldsymbol{c} = \boldsymbol{a}\boldsymbol{b}, \\ \wedge C_c = \langle \boldsymbol{c}, \boldsymbol{U} \rangle \\ \wedge C_a = \langle \boldsymbol{a}, \boldsymbol{G} \rangle \\ \wedge C_b = \langle \boldsymbol{b}, \boldsymbol{H} \rangle \end{pmatrix} \right\}.$$

Application: zkSNARK for Neural Networks

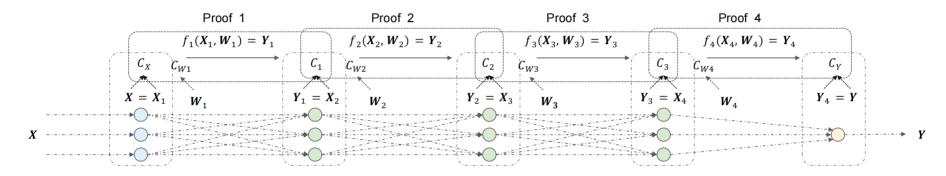


Figure: Neural networks with zero-knowledge proofs. X_i and Y_i represent the input and output of the neural network's layer i, with a weight W_i such that $f_i(X_i, W_i) = Y_i$ for some matrix function f_i . C_A stands for the commitment to the secret vector/matrix A, bridging sub-protocols throughout the CNN computation.

Application: Verifiable Statistics on Private Dataset

- Example: A health institute may publish reliable statistical analysis on the efficacy of a medical treatment without leaking sensitive patient data.
- Estimation of coefficients for the linear regression (LR) model: $y = \beta x + \epsilon$:

$$\hat{\boldsymbol{\beta}} = (\boldsymbol{X}^{\top} \boldsymbol{X})^{-1} (\boldsymbol{X}^{\top} \boldsymbol{Y}).$$

Difficulty for Matrix Multiplication

Inherent superlinearity of matrix multiplication:

Schoolbook algorithm requires n^3 multiplication gates for $n \times n$ matrix multiplication. The best algorithm in the literature needs $> n^{2.37}$ multiplications.

- General-purpose zkSNARKs (e.g. Groth16 [2]) requires RAM usage and prover time proportional to the number of multiplication gates.
- Interactive protocols (e.g. Quicksilver [6] , Thaler's protocol [4]) enable $O(n^2)$ prover time but lack succinct proof size or logarithmic verifier time.

How We Solve This Problem

Freivalds' Algorithm

Freivalds' Algorithm

Freivalds' Algorithm verifies matrix multiplication probabilistically via:

$$m{ab} = m{c} \iff m{ab}\vec{r} = m{c}\vec{r}, \; ext{where } \vec{r} \in \mathbb{Z}_p^{*n} \; ext{is a random vector.}$$

• We apply Freivalds' Algorithm twice and verify:

$$\vec{l}^{\top}ab\vec{r} = \vec{l}^{\top}c\vec{r}$$
, where $\vec{l} \in \mathbb{Z}_p^{*m}, \vec{r} \in \mathbb{Z}_p^{*n}$ are random vectors.

• We use powers of a random challenge $y \overset{\$}{\leftarrow} \mathbb{Z}_p^*$ to generate $\vec{m{l}}, \vec{m{r}}$:

$$\vec{l} \leftarrow \vec{y}_L = (1, y^n, \dots, y^{(m-1)n}), \vec{r} \leftarrow \vec{y}_R = (1, y, \dots, y^{n-1}).$$

• We verify:

$$ec{oldsymbol{y}}_L^ op(oldsymbol{a}oldsymbol{b})ec{oldsymbol{y}}_R = ec{oldsymbol{y}}_L^ op oldsymbol{c}ec{oldsymbol{y}}_R.$$

Matrix Multiplication Through Four Inner Products

Matrix Multiplication to Four Inner Product Relations

$$\{ \boldsymbol{c} = \boldsymbol{a} \boldsymbol{b} \} \Leftrightarrow \{ \forall y \in \mathbb{Z}_p, (\vec{\boldsymbol{y}}_L^{\top} \boldsymbol{c} \vec{\boldsymbol{y}}_R)^{\textcircled{1}} = ((\vec{\boldsymbol{y}}_L^{\top} \boldsymbol{a})^{\textcircled{2}} (\boldsymbol{b} \vec{\boldsymbol{y}}_R)^{\textcircled{3}})^{\textcircled{4}} \}.$$

- Inner product ①: $d := \vec{y}_L^{\top} c \vec{y}_R = \sum_{i=1}^m \sum_{j=1}^n c_{ij} y^{(i-1)n + (j-1)}$.
- (High-dimensional) inner product:

$$\textcircled{2} \vec{a}_y := \sum_{i=1}^m \vec{a}_{i*} y^{(i-1)n}, \quad \textcircled{3} \vec{b}_y := \sum_{j=1}^n \vec{b}_{*j} y^{j-1}.$$

• Inner product ④: $d = \vec{a}_y \bullet \vec{b}_y$.

Verify Four Inner Products Using Bulletproofs.

- Committed Inner-Product Argument for 4.
- Committed Semi-Inner-Product Argument for the inner-product between a committed vector and a public vector in ①.
- Committed High-Dimensional Semi-Inner-Product Argument for high-dimensional inner products ② and ③.

Improvement on Bulletproofs

Faster Verifier Time Via Trusted Setup

Shift the verifier's multi-exponentiation computation load to the prover.

ullet Verification of classical Bulletproofs involves computing a group element V such that:

$$V = \zeta_1 G_1 \oplus \zeta_2 G_2 \oplus \cdots \oplus \zeta_q G_q,$$

where q is the size of the prover's secret vectors, G_1, \ldots, G_q are public group elements and $\zeta_1, \ldots, \zeta_q \in \mathbb{Z}_p$ can be computed by the verifier.

- We propose the use of structured bases $\hat{s}\hat{G}, \hat{s}^2\hat{G}, \dots, \hat{s}^q\hat{G}$ for some $\hat{s} \in \mathbb{Z}_p$ and $\hat{G} \in \mathbb{G}_1$ in a pairing group.
- Define $\phi(x) = \zeta_1 x + \dots + \zeta_q x^q \in \mathbb{Z}_p[X]$. By using a random challenge $s \in \mathbb{Z}_p^*$, the prover computes $W \leftarrow (\frac{\phi(s) \phi(\hat{s})}{s \hat{s}})\hat{G}$, and the verifier verifies:

$$e(W, s(\hat{G} \ominus \hat{s}\hat{G})) = e(\phi(s)(\hat{G} \ominus V), \hat{G}).$$



Verification of High-Dimensional Inner Product

High-Dimensional Inner Product to Normal Inner Product

$$\vec{c} = a\vec{b} \wedge C_a = \langle a, G \rangle \wedge C_c = \langle \vec{c}, \vec{U} \rangle \iff \forall x \in \mathbb{Z}_p^*, C_a \oplus x C_c = \langle a, \{G_{ij} \oplus x U_i b_j\} \rangle.$$

- By using a random challenge $x \in \mathbb{Z}_p^*$, verification of the high-dimensional inner product is transformed into verifying inner product between $a \in \mathbb{Z}_p^{m \times n}$ and the base matrix $\{G_i \oplus xb_jU_i\} \in \mathbb{G}^{m \times n}$.
- This transformed inner product is verified by Bulletproof.

Batch Proving for Multiple Matrix Multiplications

Batched zkMatrix for t Matrix Multiplications

• For a common b, batched zkMatrix is achieved using a challenge $\rho \stackrel{\$}{\leftarrow} \mathbb{Z}_p^*$:

$$a_{(i)}b = c_{(i)}, \forall i \in (1, t) \iff \forall \rho \in \mathbb{Z}_p^*, \quad (\sum_{i=1}^t \rho^{i-1}a_{(i)})b = \sum_{i=1}^t \rho^{i-1}c_{(i)}.$$

• For distinct matrices $a_{(i)}, b_{(i)}, c_{(i)}$ such that $a_{(i)}b_{(i)} = c_{(i)}$, batched zkMatrix is achieved by batch processing inner products (1), (2), and (3).

Batch Proving for Multiple Matrix Multiplications (Continued)

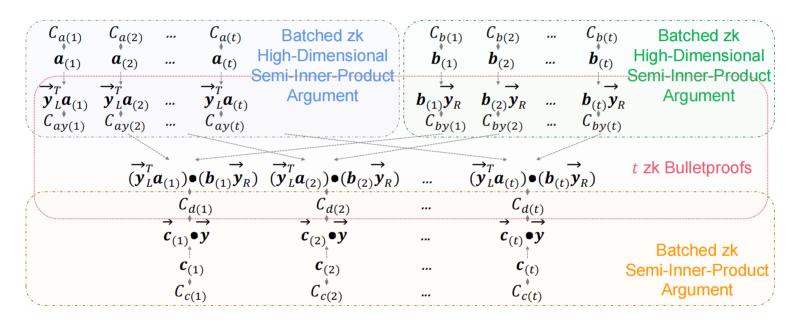


Figure: Batched zkMatrix for t matrix multiplications $a_{(i)}b_{(i)}=c_{(i)}, i=1,\cdots,t$. Inner products arguments for ①, ②, and ③ are batch processed, while those for ④ are processed individually for t matrix multiplications. The prover time is $O(n^2+tn)$ group operations.

Adding Zero Knowledge

Zero-knowledge proof via random masking matrices.

We use two random masking matrices $\alpha \in \mathbb{Z}_p^{m \times l}$ and $\boldsymbol{\beta} \in \mathbb{Z}_p^{l \times n}$:

$$\{\boldsymbol{c} = \boldsymbol{a}\boldsymbol{b}\} \Leftrightarrow \begin{cases} \forall x \in \mathbb{Z}_p^*, \ x^2(\boldsymbol{\alpha}\boldsymbol{\beta} + x(\boldsymbol{a}\boldsymbol{\beta} + \boldsymbol{\alpha}\boldsymbol{b}) + x^2\boldsymbol{c}) \\ = (x(\boldsymbol{\alpha} + x\boldsymbol{a}))(x(\boldsymbol{\beta} + x\boldsymbol{b})) \end{cases}.$$

Why zkMatrix is Better

Comparison With Existing Methods

First zkSNARK With Linear Prover Time for Matrix Multiplication

For $n \times n$ matrix multiplication, we achieve $O(n^2)$ prover time, $O(\log n)$ proof size, and $O(\log n)$ verifier time.

Protocol	Communi-	RAM Usage		Timing		
	cation	Prover	Verifier	Prover	Verifier	Consistency
Pinocchio [3]	O(1)	$O(n^3)$	O(1)	$O(n^3)$	O(1)	No
Thaler [4]	$O(\log n)$	$O(n^2)$	$O(n^2)$	$O(n^2)$	$O(n^2)$	No
LegoSNARK [1]	$O(\log n)$	$O(n^2)$	$O(n^2)$	$O(n^2)$	$O(n^2)$	Yes
Libra [5]	$O(\log^2 n)$	$O(n^3)$	$O(\log n)$	$O(n^3)$	$O(\log^2 n)$	No
QuickSilver [6]	$O(n^2)$	$O(n^2)$	$O(n^2)$	$O(n^2)$	$O(n^2)$	Yes
Single zkMatrix	$O(\log n)$	$O(n^2)$	$O(\log n)$	$O(n^2)$	$O(\log n)$	Yes
Batched zkMatrix	$O(t \log n)$	$O(n^2 + tn)$	$O(t \log n)$	$O(n^2 + tn)\mathbb{E} + O(tn^2)\mathbb{M}$	$O(t \log n)$	Yes

Table: Comparison of the Zero-Knowledge Proofs for Matrix Multiplication of $n \times n$ Matrices. The timing columns only show the dominating factor(s). For most schemes, it is the number of exponentiations $\mathbb E$ in ECC or pairing groups. $\mathbb M$ represents the number of multiplications in $\mathbb Z_p$, and one exponentiation roughly takes $\log_2 p$ multiplications. All group and modular additions, hashing operations, and non-dominating pairing operations are omitted in the table for simplicity.

Evaluations

Our Codes is Available

We have implemented DualMatrix, an improvement over zkMatrix. You can access the code at: https://github.com/mirandaprivate/dualmatrix.

	DualMatrix	Thaler's ^a	zkMatrix ^b	Libra ^c	Spartand	HyperPlonk ^d
Setup time	1.94s	NA	419.54s	26.93s	$427.23 \mathrm{ms}$	48.22s
SRS size	361.61KB	NA	801.11MB	2.06GB	1.44MB	3.22 G B
Preprocessing	23.38s	NA	17.45s	6.76s	23.47s	87.46s
Prover time	5.63s	$77.54 \mathrm{ms}$	33.42s	258.63s	357.49s	149.91s
Verifier time	469.50ms	942.78ms	78.87ms	150.38ms	$682.00 \mathrm{ms}$	$25.32\mathrm{ms}$
Transcript size	131.13KB	168B	7.85KB	48.00KB	501.35KB	17.96KB

Table: Benchmarking Performance on Dense Matrices of Size $1,024 \times 1,024$. All experiments were conducted on the same machine, utilizing 64 threads for parallelization. DualMatrix, Spartan, and HyperPlonk are implemented in Rust, whereas Thaler's protocol and Libra are implemented in C++. We exclude the time for computing the underlying matrix multiplication from the prover times.

- ^a In Thaler's protocol, the matrices a, b, and c are public. Its performance is not fairly comparable with those of other protocols.
- ^b The performance metrics of zkMatrix are estimated from the theoretical performance and execution times of single group and field operations on the same machine.
- ^c Libra encountered a memory overflow on our machine when processing $1,024 \times 1,024$ matrices. Consequently, we report its performance on smaller 512×512 matrices.
- $^{
 m d}$ The performance metrics for Spartan and Hyperplonk are measured for a mock circuit with 2^{24} constraints, under the assumption of the ideal matrix-multiplication-to-circuit conversion. These are lower bounds for real implementations of the matrix multiplication circuit.

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Thank you! Q & A