# yacoub: a Python package for Simulating Generalized Fading Channels

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Abstract—We present a well tested Python-based library for simulating and computing generalized fading channels, named yacoub. We describe the applicability of yacoub using examples in scenarios of communications channels impaired by generalized fading, namely: spectrum sensing, bit error rate computation, and fading estimation. For the latter, we develop an iterative algorithm using the Majorization-Minimization framework, which allows reliable estimation of the fading parameter. The development of yacoub is open source and its code along with examples are avaliable at http://github.com/mirca/yacoub.

### I. INTRODUCTION

Notation

Scalars and random variables are denoted as italic, smallcase letters e.g. x; sets and events are denoted as italic, capital letters e.g., A; vectors and random vectors are denoted as *italic*, boldface, small-case letters e.g. x. The n-th component of a vector x is denoted as  $x_n$ . A complex vector of length n is defined as  $x \in \mathbb{C}^{n \times 1}$ . All vectors are column vectors. Matrices are denoted as italic, boldface, capital letters as in X; the identity matrix of order n is denoted as  $I_n$ . We define a discrete-time circularly symmetric Gaussian process z as any collection of random variables z = x + iy,  $i \triangleq \sqrt{-1}$ , such that x and y are i.i.d. jointly Gaussian, with zero mean vector and covariance matrix given by  $\mathbb{E} |zz^{\dagger}|$ , in which  $z^{\dagger}$  means the conjugate transpose of z. The expectation value w.r.t. to the probability distribution of a random variable x is denoted as  $\mathbb{E}_x$ . The probability of an event A is denoted as  $\mathbb{P}(A)$ . The indicator function is denoted as  $\mathbb{I}(\cdot)$ , it evaluates to one if its argument is true and zero otherwise. For any given two real functions f and g defined on the same domain D,  $f \cong g$ means that there exist a constant c such that f(x) = g(x) + c,

## II. THE ACCEPTANCE-REJECTION SAMPLER IN LOG-SPACE

# III. MAJORIZATION-MINIMIZATION ALGORITHMS

# IV. EXAMPLES

A. Spectrum Sensing in Complex Generalized Fading Channels

The spectrum sensing problem consists in deciding whether or not a given channel frequency band is being occupied by a licensed (primary) user and, in case that such frequency band is available, how to opportuniscally allocate secondary users such that the interference on the primary user is negligible.

From a probabilistic point of view, the spectrum sensing problem may be framed as a decision theory problem, as follows

$$H_0: \ \boldsymbol{y} = \boldsymbol{w},\tag{1}$$

$$H_1: \ \boldsymbol{y} = h\boldsymbol{s} + \boldsymbol{w},\tag{2}$$

in which  $\boldsymbol{y} \in \mathbb{C}^{n \times 1}$  is the decoded received vector signal,  $\boldsymbol{w} \in \mathbb{C}^{n \times 1}$  is complex Gaussian noise process with zero mean vector and covariance matrix given as  $\sigma^2 \boldsymbol{I}_n$ , and h is the channel gain.

In [?], the authors have shown that the probability distribution of the energy statistic  $\tilde{y} \triangleq y^{\dagger}y$  conditioned on the knowledge of h, in case that s is an M-PSK signal such that every symbol has the same probability of occurrence,  $\mathbb{P}(s_n=s)=\frac{1}{M}$ , is given as

$$p(\tilde{y}|h, H_1) = 1 - Q_n \left( \sqrt{\frac{2n|h|^2 E_s}{\sigma^2}}, \sqrt{\frac{2\tilde{y}}{\sigma^2}} \right), \quad (3)$$

in which  $Q_n$  is the Marcum-Q function and  $E_s$  is the energy per symbol.

The pdf of  $\tilde{y}$  can be written using the Law of Total Expectation

$$p(\tilde{y}|H_1) = \mathbb{E}_h \left[ p(\tilde{y}|h, H_1) \right] = \int_{-\infty}^{+\infty} p(\tilde{y}|h, H_1) p(h) \, dh.$$
 (4)

Recall that the energy detection rule can be expressed as

$$d_{\delta}(\tilde{y}) = \mathbb{I}(\tilde{y} > \delta) \tag{5}$$

in which  $\delta$  is a strictly positive real number known as energy threshold, and  $d_{\delta}(\tilde{y}) = j, \ j \in \{0,1\}$ , means that the detector has decided in favor of the hypothesis  $H_{j}$ .

As a result, the probabilities of false alarm and miss detection can be written as

$$p_f \triangleq \mathbb{P}\left(d_\delta(\tilde{y}) = 1|H_0\right) = 1 - p(\delta|H_0),\tag{6}$$

$$p_d \triangleq \mathbb{P}\left(d_{\delta}(\tilde{y}) = 0 | H_1\right) = \mathbb{E}_h\left[p(\delta, h | H_1)\right],\tag{7}$$

## B. Parameter Estimation in Nakagami-m fading

The Nakagami-m density is given as

$$p(\mathbf{h}) = \prod_{i=1}^{n} \frac{2m^m}{\Gamma(m)\Omega^m} h_i^{2m-1} \exp\left(-\frac{mh_i^2}{\Omega}\right)$$
$$= \left(\frac{2m^m}{\Gamma(m)\Omega^m}\right)^n \exp\left(-\frac{m\sum_{i=1}^{n} h_i^2}{\Omega}\right) \prod_{i=1}^{n} h_i^{2m-1} \tag{8}$$

And the log likelihood function (up to an additive constant) is given as

$$\log p(\boldsymbol{h}) \cong n \left( m \left( \log m - \log \Omega \right) - \log \Gamma(m) \right)$$
$$- m \left( \frac{\sum_{i=1}^{n} h_i^2}{\Omega} - 2 \sum_{i=1}^{n} \log h_i \right)$$
(9)

A direct maximum likelihood estimator (MLE) for (9) has been investigated to be infeasible [?].

Therefore, we use a Majorization-Minimization algorithm to find smooth and easy to optimize lower bounds for  $\log p(h)$ . More precisely, we need to find lower bounds for  $m \log m$  and  $-\log \Gamma(m)$  for  $m \geq \frac{1}{2}$ . The former function is convex for  $m \geq 0$ , hence it can be lower bounded by its first order Taylor series as

$$m\log m \ge m(1+\log m_t) - m_t,\tag{10}$$

The function  $-\log \Gamma(m)$  is concave, therefore, it can be lower bounded by its second order Taylor series expansion as

$$-\log \Gamma(m) \ge -\log \Gamma(m_t) - \psi(m_t)(m - m_t) - \frac{\psi'(\frac{1}{2})}{2}(m - m_t)^2, \ m \ge \frac{1}{2}, \ m_t \ge \frac{1}{2},$$
(11)

in which  $\psi(x)=\frac{\Gamma'(x)}{\Gamma(x)}$  is known as the digamma function. For both inequalities presented above, equality is achieved at  $m=m_t$ .

Substituting (10) and (11) into (9), a lower bound for  $\log p(h)$  is obtained in (14). Due to the simple form of  $g(m|m_t)$ , its maximizer can be found in closed form, and an updating rule for the MLE can be written as

$$m_{t+1} = 1 + \frac{1}{\psi'(\frac{1}{2})} \left( 1 + \log \frac{m_t}{\Omega} - \psi(m_t) + \frac{1}{n} \left( 2 \sum_{i=1}^n \log h_i - \frac{\sum_{i=1}^n h_i^2}{\Omega} \right) \right)$$
(12)

Additionally, note that  $m_{t+1}$  is an estimator of the true parameter value m. Its expected value, conditioned on the knowledge of  $m_t$ , is given as

$$\mathbb{E}(m_{t+1}|m_t) = 1 + \frac{1}{\psi'(\frac{1}{2})} \left( 1 + \log \frac{m_t}{\Omega} - \psi(m_t) + \frac{1}{n} \left( 2 \sum_{i=1}^n \mathbb{E}(\log h_i) - \frac{\sum_{i=1}^n \mathbb{E}(h_i^2)}{\Omega} \right) \right)$$
(13)

C. BER in Complex  $\alpha - \mu$  Fading

Consider the system

$$y = hs + w \tag{15}$$

in which  $s \in \mathbb{C}^{n \times 1}$  is a complex On-Off Keying (OOK) signal, h is a complex  $\alpha - \mu$  random variable and w is a complex Gaussian process with zero mean vector and covariance matrix equals  $\sigma^2 \mathbf{I}_n$ , and y is the received complex vector signal.

Assume that the OOK symbols are equiprobable and that there exist no interference between the in-phase and quadrature components, then the probability of one bit error is given as

$$p_e = \frac{1}{2} \left( \mathbb{P} \left( \hat{y}_i = 0 | s_i = 1 \right) + \mathbb{P} \left( \hat{y}_i = 1 | s_i = 0 \right) \right).$$
 (16)

Assume that the decoded vector  $\hat{y}$  is estimated using the minimum distance decoding rule, i.e.,

### V. Conclusions

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$$g(m|m_t) = n \left( -m \log \Omega + m(1 + \log m_t) - m_t - \log \Gamma(m_t) - \psi(m_t)(m - m_t) - \frac{\psi'\left(\frac{1}{2}\right)}{2}(m - m_t)^2 \right) - m \left( \frac{\sum_{i=1}^n h_i^2}{\Omega} - 2\sum_{i=1}^n \log h_i \right)$$
(14)