Sequential P Systems with Active Membranes without counting*

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Abstract. We study variants of P systems that are working in the sequential mode. Basically, they are not computationally universal, but there are possible extensions that can increase the computation power. Extensions that implement a notion of zero-checking, are often computationally universal. P systems with an ability to create new membranes are a rare exception as they are known to be computationally universal even in the sequential mode without using a dedicated zero-check operation. Using sets instead of multiset was inspired by Reaction systems.

1 Introduction

Membrane systems (P systems) [1] were introduced by Păun (see [2]) as distributed parallel computing devices inspired by the structure and functionality of cells. Starting from the observation that there is an obvious parallelism in the cell biochemistry and relying on the assumption that "if we wait enough, then all reactions which may take place will take place", a feature of the P systems is given by the maximal parallel way of using the rules. For various reasons ranging from looking for more realistic models to just more mathematical challenge, the maximal parallelism was questioned, either simply criticized, or replaced with presumably less restrictive assumptions. In some cases, a sequential model may be a more reasonable assumption. In sequential P systems, only one rewriting rule is used in each step of computation. Without priorities, they are equivalent to Petri nets [3], hence not computationally universal. However priorities, inhibitors and other modifications can increase the computation power. It seems that there is a link between universality and ability to zero-check [4].

2 Preliminaries

Here we recall several notions from the classical theory of formal languages.

An **alphabet** is a finite nonempty set of symbols. Usually it is denoted by Σ. A **string** over an alphabet is a finite sequence of symbols from the alphabet. We denote by Σ^* the set of all strings over an alphabet Σ. By $\Sigma^+ = \Sigma^* - \{\varepsilon\}$ we denote the set of all nonempty strings over Σ. A **language** over the alphabet Σ is any subset of Σ^*.

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The number of occurrences of a given symbol $a \in \Sigma$ in the string $w \in \Sigma^*$ is denoted by $|w|_a$. $\Psi_\Sigma(w) = (|w|_{a_1}, |w|_{a_2}, \ldots, |w|_{a_n})$ is called a Parikh vector associated with the string $w \in \Sigma^*$, where $\Sigma = \{a_1, a_2, \ldots, a_n\}$. For a language $L \subseteq \Sigma^*$, $\Psi_\Sigma(L) = \{\Psi_\Sigma(w) | w \in L\}$ is the Parikh image of L. If FL is a family of languages, PsFL denotes the family of Parikh images of languages in FL.

Next, we recall notions from graph theory.

A **rooted tree** is a tree, in which a particular node is distinguished from the others and called the root node. Let T be a rooted tree. We will denote its root node by r_T. Let d be a node of $T \setminus \{r_T\}$. As T is a tree, there is a unique path from d to r_T. The node adjacent to d on that path is also unique and is called a **parent node** of d and is denoted by $parent_T(d)$. We will denote the set of nodes of T by $V(T)$ and set of its edges by $E(T)$. Let T_1, T_2 be rooted trees. A bijection $f : V(T_1) \to V(T_2)$ is an **isomorphism** iff $\{(f(u), f(v)) | (u, v) \in E(T_1)\} = E(T_2)$ and $f(r_{T_1}) = r_{T_2}$.

3 Active P systems

The fundamental ingredient of a P system is the **membrane structure** (see [5]). It is a hierarchically arranged set of membranes, all contained in the **skin membrane**. Each membrane determines a compartment, also called region, which is the space delimited from above by it and from below by the membranes placed directly inside, if any exists. Clearly, the correspondence membrane – region is one-to-one, that is why we sometimes use interchangeably these terms. The membrane structure can be also viewed as a rooted tree with the skin membrane as the root node.

A P system consists of a membrane structure, where each membrane is labeled with a number from 1 to m. Each membrane contains a set of objects. Objects can be transformed into other objects and sent through a membrane according to given rules defined for membrane labels. The rules are known from the beginning for each possible membrane, even for the ones that do not exist yet, or the ones that will never exist.

In this paper we work with P systems with active membranes (Active P systems). The rules can modify the membrane structure by dissolving and creating new membranes. That is why we will define the configuration to include the membrane structure as well.

Let Σ be a set of objects. A **membrane configuration** is a tuple (T, l, c), where:

- T is a rooted tree,
- $l \in \mathbb{N}^{V(T)}$ is a mapping that assigns for each node of T a number (label), where $l(r_T) = 1$, so the skin membrane is always labeled with 1,
- $c \in (2^\Sigma)^{V(T)}$ is a mapping that assigns for each node of T a set of objects from Σ, so it represents the contents of the membrane.

An **active P system** is a tuple $(\Sigma, C_0, R_1, R_2, \ldots, R_m)$, where:

- Σ is a set of objects,

- C_0 is initial membrane configuration,
- $R_1, R_2, \ldots, R_m$ are finite sets of rewriting rules associated with the labels $1, 2, \ldots, m$ and can be of forms:
  - $u \to w$, where $u \subseteq \Sigma$, $|u| \geq 1$, $w \subseteq (\Sigma \times \{\cdot, \uparrow, \downarrow_j\})$ and $1 \leq j \leq m$,
  - a dissolving rule $u \to w\delta$, where $u \subseteq \Sigma$, $|u| \geq 1$, $w \subseteq (\Sigma \times \{\cdot, \uparrow, \downarrow_j\})$ and $1 \leq j \leq m$,
  - a membrane creation $u \to [_j v]_j$, where $u \subseteq \Sigma$, $|u| \geq 1$, $v \subseteq \Sigma$ and $1 \leq j \leq m$.

For the first two forms, each rewriting rule may specify for each object on the right side, whether it stays in the current region (we will omit the symbol $\cdot$), moves through the membrane to the parent region ($\uparrow$) or to a specific child region ($\downarrow_j$, where j is a label of a membrane). We denote these transfers with an arrow immediately after the symbol. An example of such rule is the following: $ab \to ab \downarrow_2 c \uparrow c\delta$.

By applying the rule we mean the removal of objects specified on the left side and the addition of the objects on the right side with respect to set union semantics. Symbol $\delta \notin \Sigma$ does not represent an object. It may be present only at the end of the rule, which means that after the application of the rule, the membrane is dissolved and its contents (objects, child membranes) are propagated to the parent membrane.

Active P systems differ from classic (passive) P systems in ability to create new membranes by rules of the third form. Such rule will create new child membrane with a given label j and a given set of objects v as its contents. If there already is such a membrane, nothing happens. TODO: Do we really need this sort of rule? I think the sending down in sufficient (i.e. if the target membrane we want to send objects to does not exists, one such is automatically created). When allowing multiple children with same label, this sort of rule was essential, but now it is useless. EDIT: yeah, but our simulation would be overcomplicated then, having hard time detecting the innermost membrane

TODO: refactor using the creation-by-sending-to-nonexistent

For an active P system $(\Sigma, C_0, R_1, R_2, \ldots, R_m)$, configuration $C = (T, l, c)$, membrane $d \in V(T)$ the rule $r \in R_{l(d)}$ is **applicable** iff:

- $r = u \to w$ and $u \subseteq c(d)$ and for all $(a, \downarrow_k) \in w$ there exists $d_2 \in V(T)$ such that $l(d_2) = k \wedge parent(d_2) = d$,
- $r = u \to w\delta$ and $u \subseteq c(d)$ and for all $(a, \downarrow_k) \in w$ there exists $d_2 \in V(T)$ such that $l(d_2) = k \wedge parent(d_2) = d$ and $d \neq r_T$,
- $r = u \to [_j v]_j$ and $u \subseteq c(d)$.

In this paper we assume only sequential systems, so in each step of the computation, there is one rule nondeterministically chosen among all applicable rules in all membranes to be applied.

A **computation step** of P system is a relation $\Rightarrow$ on the set of configurations such that $C_1 \Rightarrow C_2$ holds iff there is an applicable rule in a membrane in C_1 such that applying that rule can result in C_2.

The P system can work in generating or in accepting mode. For the generating mode we consider the concatenation of the objects which leave the system, in the order they are sent out of the skin membrane (if several symbols are expelled at the same time, then any ordering of them is considered). In this case we generate a language. The result of a single computation is clearly only one multiset or a string, but for one initial configuration there can be multiple possible computations. It follows from the fact that there can be more than one applicable rule in each configuration and they are chosen nondeterministically.

For the accepting mode the input word in encoded into a membrane structure by a given encoding and it is accepted if and only if a given accepting configuration can be reached[3].

4 Simulation of register machine

4.1 Register machine

Definition 1. *A* n**-register machine** *is a tuple* $M = (n, P, i, h)$*, where:*

- n *is the number of registers,*
- P *is a set of labeled instructions of the form* $j : (op(r), k, l)$*, where* $op(r)$ *is an operation on register* $r \leq n$*, and* j*,* k*,* l *are labels from the set* $Lab(M)$ *such that there are no two instructions with the same label* j*,*
- i *is the initial label, and*
- h *is the final label.*

The machine is capable of the following instructions:

- $(add(r), k, l)$: Add one to the contents of register r and proceed to instruction k or to instruction l; in the deterministic variants usually considered in the literature we demand $k = l$.
- $(sub(r), k, l)$: If register r is not empty, then subtract one from its contents and go to instruction k, otherwise proceed to instruction l.
- *halt* : This instruction stops the machine. This additional instruction can only be assigned to the final label h.

A deterministic m-register machine can analyze an input $(n_1, \ldots, n_m) \in N_0^m$ in registers 1 to m, which is recognized if the register machine finally stops by the halt instruction with all its registers being empty (this last requirement is not necessary). If the machine does not halt, the analysis was not successful.

A configuration of a register machine is a tuple $(r_1, \ldots, r_m, ip)$, where r_i is value of the register i and ip (instruction pointer) is the label of current instruction to be executed.

We define a bisimulation relation as follows:

For a configuration of register machine (r_1, r_2, ip) the membrane structure will consist of a skin membrane, a chain consisting of r_1 membranes embedded one into another like in a Matryoshka doll with label 1, a similar chain of r_2 membranes labeled 2. The two innermost membranes contain a single object t_1

or t_2. If $r_i = 0$ then t_i is in the skin membrane. Label of the current instruction (ip) is in the skin membrane.

We will have following rules in the skin membrane:

- $u_j \to j$,
- $j \to j\downarrow_i$ for instruction $j : op(i)$,
- $j, t_i \to [_1 u_k, t_i]_1$ for instruction $j : (add(i), k, \_)$,
- $j, t_i \to l$ for instruction $j : (sub(i), \_, l)$

For the membrane i:

- $j \to j\downarrow_i$ for instruction $j : op(i)$,
- $j, t_i \to [_1 u_k, t_i]_1$ for instruction $j : (add(i), k, \_)$,
- $u_j \to u_j\uparrow$ for instruction $j : (op(i), \_, \_)$,
- $j, t_i \to u_k, t_i, \delta$ for instruction $j : (sub(i), k, l)$

If empty register halting is needed, we will consume t_1 and t_2 symbols with the label of a halting instruction in the skin membrane.

The simulation was quite straightforward. We proved that the model is computational complete. It could be improved in several ways:

- The number of membranes we use depends on the sum of values of registers. Could this be optimized? Similarly, the number of computational steps needed to simulate one instruction is huge. If the optimization is succesful, the next steps could be considering solving SAT in polynomial time (or perhaps in linear time when using membrane division instead of simple creation)
- Could the simulation be done in a simple way if there is no rule for membrane creation? The only possible way to create membrane would be through sending objects into membrane which does not exist (as we mentioned in previous section).
  - We could introduce an object *haschild* instead of t object which would mean the exact opposite. Then, the sending the instruction downwards would be performed using an object *haschild* as a catalyst[1]. In the innermost membrane no such catalyst is present, so we can execute the corresponding membrane structure modification (create a new membrane of dissolve a membrane).

References

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[1] I think I can prove that without this catalyst (relying only on the rules defined for membranes) the sending of instruction downward would always lead to an infinite membrane creation

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