

2023/09/06

Exercise 3

Consider a sigmoid neuron with 1D input x , weight w , bias b and output $y = \sigma(wx + b)$. The target is the variable z . Consider the cost function $J(w, b) = \frac{1}{2}(y - z)^2$.

- Find $\nabla J(w, b)$ and show that $\|\nabla J\| < \frac{1}{4}\sqrt{1+x^2}(1+|z|)$.
- Write the gradient descent iteration for the sequence (w_n, b_n) .

• Gradient $\nabla J(w, b)$

$$\text{define } v = wx + b \quad y = \sigma(v) \quad J = \frac{1}{2}(y - z)^2$$

$$\text{using chain rule: } \begin{cases} \frac{\partial J}{\partial w} = \frac{\partial J}{\partial y} \cdot \frac{\partial y}{\partial v} \cdot \frac{\partial v}{\partial w} \\ \frac{\partial J}{\partial b} = \frac{\partial J}{\partial y} \cdot \frac{\partial y}{\partial v} \cdot \frac{\partial v}{\partial b} \end{cases}$$

→ compute each derivative

$$\begin{cases} \frac{\partial J}{\partial y} = y - z \\ \frac{\partial y}{\partial v} = \sigma(v)(1 - \sigma(v)) = y(1 - y) \\ \frac{\partial v}{\partial w} = x, \quad \frac{\partial v}{\partial b} = 1 \end{cases} \quad (\text{derivative of sigmoid})$$

→ chain rule

$$\begin{cases} \frac{\partial J}{\partial w} = (y - z) \cdot y(1 - y)x \\ \frac{\partial J}{\partial b} = (y - z) \cdot y(1 - y) \end{cases}$$

• Bound on $\|J\| = \sqrt{\left(\frac{\partial J}{\partial w}\right)^2 + \left(\frac{\partial J}{\partial b}\right)^2}$

with $0 < y < 1 \rightarrow 0 < y(1-y) \leq \frac{1}{4}$

(maximum when $y = 0.5 \rightarrow y(1-y) = 0.25$)

denote $A = (y - z) y(1 - y)$

$$\rightarrow \left(\frac{\partial J}{\partial w}\right)^2 + \left(\frac{\partial J}{\partial b}\right)^2 = A^2(x^2 + 1)$$

using the bound $|A| = |y - z| \cdot y(1 - y) \leq (|y| + |z|) \cdot \frac{1}{4} \leq \frac{1 + |z|}{4}$

hence $\|\nabla J\| \leq \sqrt{(x^2 + 1)} \cdot \left(\frac{1 + |z|}{4}\right) = \frac{1}{4} \sqrt{1 + x^2} (1 + |z|)$

• Gradient descent iteration

Take $\eta > 0$

$$w^{i+1} = w^i - \eta \frac{\partial J}{\partial w} = w^i - \eta (y - z) y (1 - y) x$$

$$b^{i+1} = b^i - \eta \frac{\partial J}{\partial b} = b^i - \eta (y - z) y (1 - y)$$

(with $q = \sigma(w^i x + b^i)$)

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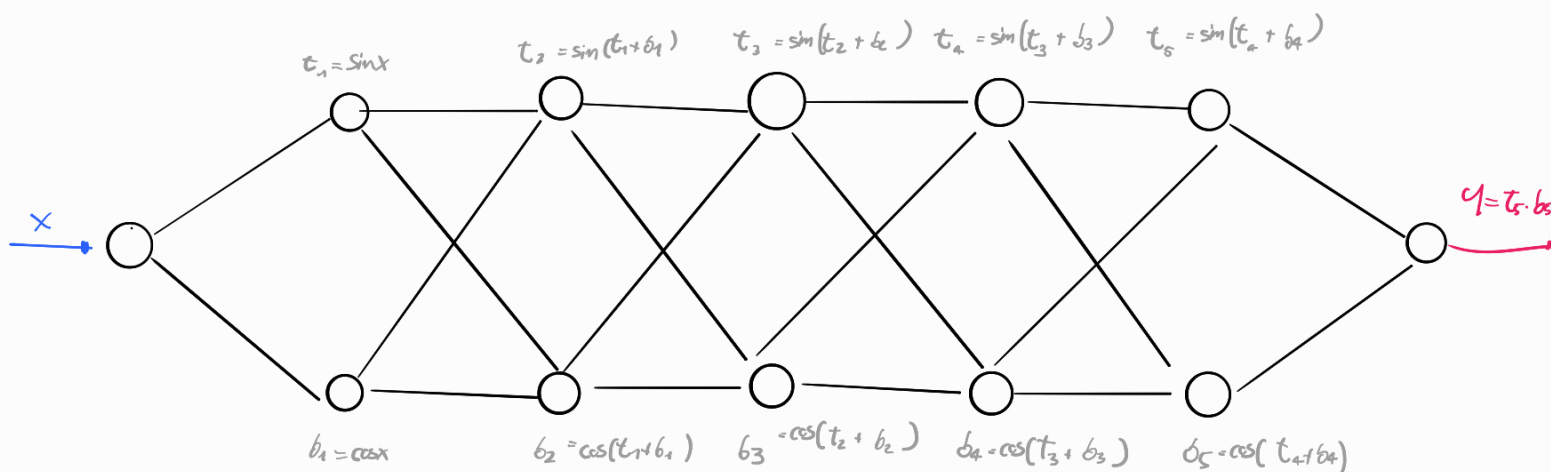
Exercise 3

Consider the following computational graph:



Figure 1: Computational Graph

The upper node in each layer computes $\sin(x + y)$ and the lower computes $\cos(x + y)$ with respect to its 2 inputs. For the first hidden layer, there is only a single input x , and therefore the values $\sin(x)$ and $\cos(x)$ are computed. The final node computes the product of the two inputs. The single input is denoted by x (value in radians). Compute the numerical value of the partial derivative of the output with respect to x for $x = 1$ using the backpropagation algorithm. Explain clearly each step you have performed.



$x=1$

Forward Pass

$$h_1 \begin{cases} t_1 = \sin(1) = 0.84 \\ b_1 = \cos(1) = 0.54 \end{cases}$$

$$h_2 \begin{cases} t_2 + b_1 = 1.38 \\ t_2 = \sin(1.38) = 0.98 \\ b_2 = \cos(1.38) = 0.18 \end{cases}$$

$$h_3 \begin{cases} t_2 + b_2 = 1.16 \\ t_3 = \sin(1.16) = 0.91 \\ b_3 = \cos(1.16) = 0.40 \end{cases}$$

$$h_4 \begin{cases} t_3 + b_3 = 1.31 \\ t_4 = \sin(1.31) = 0.92 \\ b_4 = \cos(1.31) = 0.25 \end{cases}$$

$$h_5 \begin{cases} t_4 + b_4 = 1.22 \\ t_5 = \sin(1.22) = 0.92 \\ b_5 = \cos(1.22) = 0.34 \end{cases}$$

$$\text{output } y = t_5 \cdot b_5 = 0.32$$

Backward Pass $\left(\frac{d \sin x}{dx} = \cos x, \frac{d \cos x}{dx} = -\sin x \right)$

$$\dot{t} = \frac{\partial y}{\partial t}$$

obs: t and b have same contribute on derivative (symmetry!)

$$h_5 \begin{cases} \dot{t}_5 = \dot{b}_5 = 0.34 \\ \dot{b}_5 = t_5 = 0.92 \end{cases}$$

$$h_4 \begin{cases} \dot{t}_4 = \dot{t}_5 \cdot \cos(t_4 + b_4) + \dot{b}_5 \cdot (-\sin(t_4 + b_4)) = \dots = -0.72 \\ \dot{b}_4 = -0.72 \end{cases}$$

$$h_3 \begin{cases} \dot{t}_3 = \dot{t}_1 \cos(t_3 + b_3) + \dot{b}_1 (-\sin(t_3 + b_3)) = \dots 0,54 \\ \dot{b}_3 = 0,54 \end{cases}$$

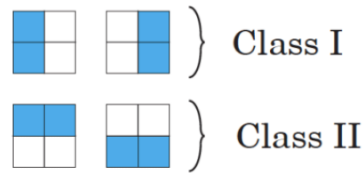
$$h_2 \begin{cases} \dot{t}_2 = \dot{t}_3 \cos(t_2 + b_2) + \dot{b}_3 (-\sin(t_2 + b_2)) = \dots -0,28 \\ \dot{b}_2 = -0,28 \end{cases}$$

$$h_1 \begin{cases} \dot{t}_1 = \dot{t}_2 \cos(t_1 + b_1) + \dot{b}_2 (-\sin(t_1 + b_1)) = 0,22 \\ \dot{b}_1 = 0,22 \end{cases}$$

$$input \quad \dot{x} = \dot{t}_1 \cos(\gamma) + \dot{b}_1 (-\sin(\gamma)) = -0,02$$

Exercise 3

Consider the two classes of patterns that are shown in the following figure where Class I represents vertical lines and Class II represents horizontal lines.



1. Are these categories linearly separable?
2. Design a multilayer network to distinguish these categories.

• Encode input as $[x_1, x_2, x_3, x_4]$

$[1 \ 0 \ 1 \ 0] \rightarrow \text{class 1}$
 $[0 \ 1 \ 0 \ 1] \rightarrow \text{class 1}$
 $[1 \ 1 \ 0 \ 0] \rightarrow \text{class 2}$
 $[0 \ 0 \ 1 \ 1] \rightarrow \text{class 2}$

→ Linear decision boundary in the form $Wx + b > 0$ (e.g. $10 \rightarrow \text{class 1}$)

$$[1 \ 0 \ 1 \ 0] \rightarrow W_1 + W_3 > 0 \quad (1)$$

$$[0 \ 1 \ 0 \ 1] \rightarrow W_2 + W_4 > 0 \quad (2)$$

$$[1 \ 1 \ 0 \ 0] \rightarrow W_1 + W_2 < 0 \quad (3)$$

$$[0 \ 0 \ 1 \ 1] \rightarrow W_3 + W_4 < 0 \quad (4)$$

→ It raises inconsistencies:

$$\text{From (1) and (3)} \rightarrow \begin{cases} W_1 + W_3 > 0 \\ -W_1 > W_2 \end{cases} \xrightarrow{\text{sum}} W_3 > W_2 \quad \nabla$$

$$\text{From (2) and (4)} \rightarrow \begin{cases} W_2 + W_4 > 0 \\ -W_4 > W_3 \end{cases} \xrightarrow{\text{sum}} W_2 > W_3$$

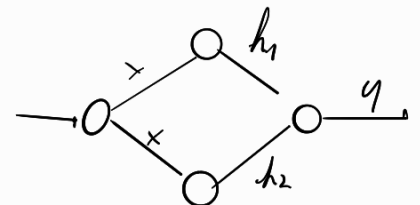
• Multi-layer perceptron

$$\text{vertical detector: } h_1 = \sigma(x_1 + x_3 - x_2 - x_4)$$

$$\text{horizontal detector: } h_2 = \sigma(x_1 + x_2 - x_3 - x_4)$$

$$\text{output: } y = \sigma(W_1 h_1 + W_2 h_2 + b)$$

loss: cross-entropy



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Exercise 3

Suppose that the output \hat{y}_k of a given unit in a neural network is given by the softmax function i.e.:

$$\hat{y}_k = \frac{\exp(a_k)}{\sum_j \exp(a_j)}. \quad (2)$$

- Show that the output of the softmax function does not change if you shift, in all components, the activations a_j by some constant c .
- Explain why the shift $c = -\max_j(a_j)$ can be useful.

• Invariance to shift

suppose shift all activation a_j by constant c : $a'_j = a_j + c$

$$\hat{y}'_k = \frac{e^{a_k + c}}{\sum_j e^{a_j + c}} = \frac{e^{a_k} e^c}{\sum_j e^{a_j} e^c} = \frac{\cancel{e^c} e^{a_k}}{\cancel{e^c} \sum_j e^{a_j}} = \frac{e^{a_k}}{\sum_j e^{a_j}} = \hat{y}_k$$

• Choosing $a'_j = a_j - \max_j(a_j)$

obs: $a'_j \leq 0$ it helps numerical stability!

• when sum a_j are large e^{a_j} can overflow

• if maximum is 0 we ensure all components to be ≤ 1 and avoid overflow!

2023/01/20

Exercise 3

Show that a multi-layer neural network with linear activation function $s(x) = x$ is equivalent to a single layer linear network. Assume that in each layer the inputs follow a Normal distribution with mean zero and small variance, i.e. $\sigma \ll 1$. For which of the activation functions $s(x) = 1/(1 + \exp(-x))$, $s(x) = \tanh(x)$, $s(x) = \text{relu}(x)$ and $s(x) = \text{selu}(x)$ is a deep network equivalent to a linear network for the given distribution? The selu function is given by:

$$\text{selu}(x) = \begin{cases} \lambda x & \text{if } x > 0 \\ \alpha(\exp(x) - 1) & \text{otherwise} \end{cases} \quad (4)$$

where $\lambda \approx 1.0507$ and $\alpha \approx 1.75814$. (Hint: consider the case $\sigma \rightarrow 0$ using a Taylor expansion around 0.)

• Deep Linear = single linear

M2P (with L layers) has about: $y = W^L \cdot W^{L-1} \cdot \dots \cdot W^2 \cdot W^1 \cdot x$

We can just bundle $W^L \cdot W^{L-1} \cdot \dots \cdot W^2 \cdot W^1 = W_{\text{eff}} \rightarrow y = W_{\text{eff}} x$
(single neuron!)

• for which activation functions is a deep network approximately linear when $x \sim N(0, \sigma^2)$ with $\sigma^2 \ll 1$?

1) Sigmoid $s(x) = \frac{1}{1+e^{-x}}$

Taylor expansion in x : $s(x) \approx \frac{1}{2} + \frac{x}{4} - \frac{x^3}{48} + \dots$

for small σ $s(x) \approx \frac{1}{2} + \frac{x}{4}$

Not linear: constant bias
breaks linearity over multiple layers x

2) $\tanh(x)$

Taylor expansion $s(x) = x - \frac{x^3}{3} + \frac{2x^5}{15} - \dots$

for small σ $s(x) = x$

Linear ✓

3) $\text{ReLU}(x) = \max(0, x)$

$x > 0 \rightarrow \text{output } x$

$x \leq 0 \rightarrow \text{output } 0$

↳ normal distribution around 0 means that whole input is mapped into 0
Non linearity!

$$a) \text{ Solu}(x) = \begin{cases} \lambda x & x \geq 0 \\ \lambda \alpha (e^x - 1) & x < 0 \end{cases}$$

Taylor expansion

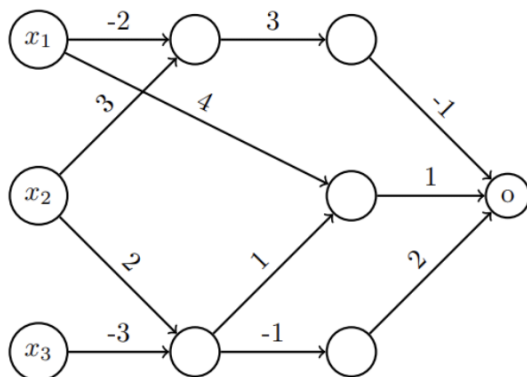
$$\begin{cases} \lambda x & x \geq 0 \\ \lambda \alpha (x + \frac{x^2}{2} + \dots) \approx \lambda \alpha x & x < 0 \end{cases}$$

↳ this is piecewise linear (but not globally) slope differs between $x \geq 0$ and $x < 0$

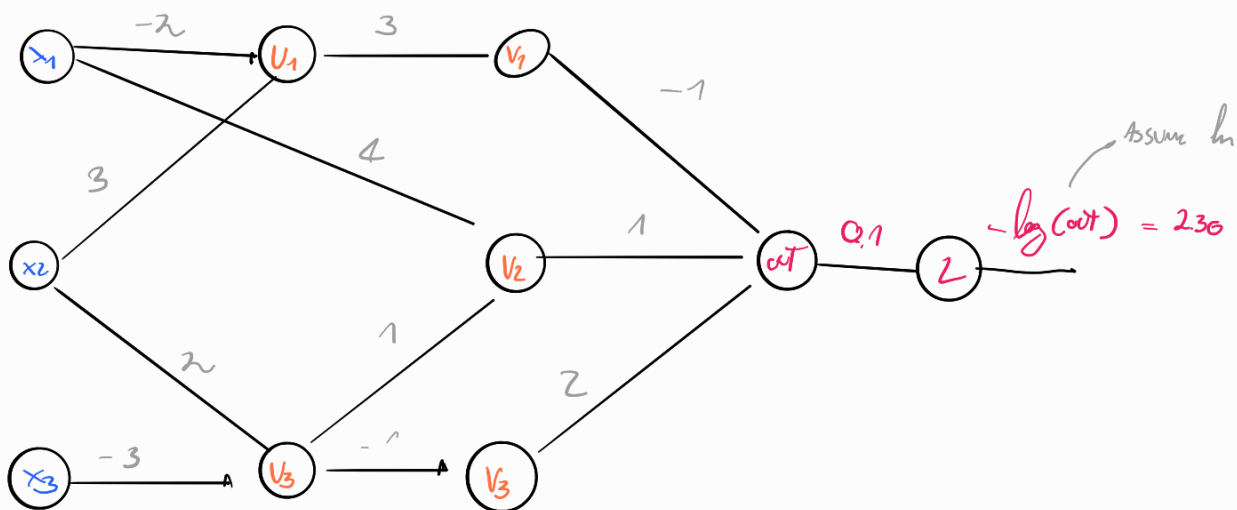
2022/09/01

Exercise 3

Consider the following network where on each edge (i, j) the value of $\frac{\partial y(j)}{\partial y(i)}$ is given; $y(k)$ denotes the activation of node k .



The output o is equal to 0.1 and the loss function is $L = -\log(o)$. Compute the value of $\frac{\partial L}{\partial x_i}$ for each input x_i using the backpropagation method.



$$\frac{\partial L}{\partial o} = -\frac{1}{o} = -10$$

$$\frac{\partial L}{\partial u_1} = \frac{\partial L}{\partial o} \cdot \frac{\partial o}{\partial u_1} = -10 \cdot -1 = 10$$

$$\frac{\partial L}{\partial u_2} = \frac{\partial L}{\partial o} \cdot \frac{\partial o}{\partial u_2} = -10 \cdot 1 = -10$$

$$\frac{\partial L}{\partial u_3} = \frac{\partial L}{\partial o} \cdot \frac{\partial o}{\partial u_3} = -10 \cdot 2 = -20$$

$$\frac{\partial L}{\partial x_1} = \frac{\partial L}{\partial u_1} \cdot \frac{\partial u_1}{\partial x_1} = 10 \cdot 3 = 30$$

$$\frac{\partial L}{\partial x_3} = \frac{\partial L}{\partial u_2} \cdot \frac{\partial u_2}{\partial x_3} + \frac{\partial L}{\partial u_3} \cdot \frac{\partial u_3}{\partial x_3} = (-10 \cdot 1) + (-20 \cdot -1) = 10$$

$$\frac{\partial L}{\partial x_1} = \frac{\partial L}{\partial v_1} \cdot \frac{\partial v_1}{\partial x_1} + \frac{\partial L}{\partial v_2} \cdot \frac{\partial v_2}{\partial x_1} = (30 \cdot -2) + (-10 \cdot 4) = -60 - 40 = -100$$

$$\frac{\partial L}{\partial x_2} = \frac{\partial L}{\partial v_1} \cdot \frac{\partial v_1}{\partial x_2} + \frac{\partial L}{\partial v_3} \cdot \frac{\partial v_3}{\partial x_2} = (30 \cdot 3) + (10 \cdot 2) = 90 + 20 = 110$$

$$\frac{\partial L}{\partial x_3} = \frac{\partial L}{\partial v_3} \cdot \frac{\partial v_3}{\partial x_3} = 10 \cdot -3 = -30$$

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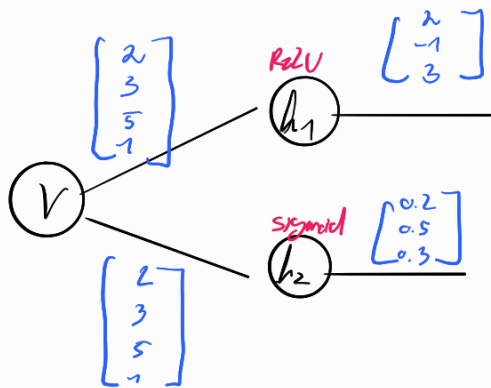
Exercise 3

Consider a neural network in which a vectored node v feeds into two distinct vectored nodes h_1 and h_2 computing different functions. The functions computed at the nodes are $h_1 = \text{ReLU}(W_1 v)$ and $h_2 = \text{sigmoid}(W_2 v)$. We do not know anything about the values of the variables in other parts of the network, but we know that $h_1 = [2, -1, 3]^T$ and $h_2 = [0.2, 0.5, 0.3]^T$, that are connected to the node $v = [2, 3, 5, 1]^T$. Furthermore the loss gradients are $\frac{\partial L}{\partial h_1} = [-2, 1, 4]^T$ and $\frac{\partial L}{\partial h_2} = [1, 3, 2]^T$, respectively. Show that the backpropagated loss gradient $\frac{\partial L}{\partial v}$ can be computed in terms of W_1 and W_2 as follows:

$$\frac{\partial L}{\partial v} = W_1^T \begin{bmatrix} -2 \\ 0 \\ 4 \end{bmatrix} + W_2^T \begin{bmatrix} 0.16 \\ 0.75 \\ -0.42 \end{bmatrix} \quad (5)$$

What are the sizes of W_1, W_2 and $\frac{\partial L}{\partial v}$?

Remember that $\text{ReLU}(x) = \max(0, x)$ and $\text{sigmoid}(x) = \frac{\exp(x)}{\exp(x) + 1}$.



$$\frac{\partial L}{\partial h_1} = \begin{bmatrix} -2 \\ 1 \\ 4 \end{bmatrix}$$

$$\frac{\partial L}{\partial h_2} = \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix}$$

• With backpropagation rule

$$\frac{\partial L}{\partial v} = \frac{\partial L}{\partial h_1} \cdot \frac{\partial h_1}{\partial v} + \frac{\partial L}{\partial h_2} \cdot \frac{\partial h_2}{\partial v}$$

$$= W_1^T \left(\frac{\partial L}{\partial h_1} \odot \frac{\partial h_1}{\partial z_1} \right) + W_2^T \left(\frac{\partial L}{\partial h_2} \odot \frac{\partial h_2}{\partial z_2} \right)$$

$$\text{with } z_1 = W_1 v, \quad h_1 = \text{ReLU}(z_1) \implies \frac{\partial h_1}{\partial z_1} = \text{ReLU}'(z_1)$$

$$z_2 = W_2 v, \quad h_2 = \text{sigmoid}(z_2) \implies \frac{\partial h_2}{\partial z_2} = \sigma(z_2) (1 - \sigma(z_2))$$

$$\implies \frac{\partial h_1}{\partial z_1} \quad \text{ReLU}' = \begin{cases} 1 & z_i > 0 \\ 0 & z_i \leq 0 \end{cases}$$

$$\text{from } h_1 = \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix} \implies z_1 = W_1 v = \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix} \implies \text{ReLU}'(z_1) = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\implies \frac{\partial L}{\partial h_1} \odot \text{ReLU}'(z_1) = \begin{bmatrix} -2 \\ 1 \\ 4 \end{bmatrix} \odot \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -2 \\ 0 \\ 4 \end{bmatrix}$$

$$\Rightarrow \frac{\partial h_2}{\partial z_2} \quad \sigma'(z) = \sigma(z)(1 - \sigma(z))$$

$$\text{From } h_2 = \begin{bmatrix} 0.2 \\ 0.5 \\ 0.3 \end{bmatrix} \rightarrow z_2 = W_2 V \begin{bmatrix} 0.2 \\ 0.5 \\ 0.3 \end{bmatrix} \rightarrow \sigma'(z_2) = \begin{bmatrix} 0.2 \cdot 0.8 \\ 0.5 \cdot 0.5 \\ 0.3 \cdot 0.7 \end{bmatrix} = \begin{bmatrix} 0.16 \\ 0.25 \\ 0.21 \end{bmatrix}$$

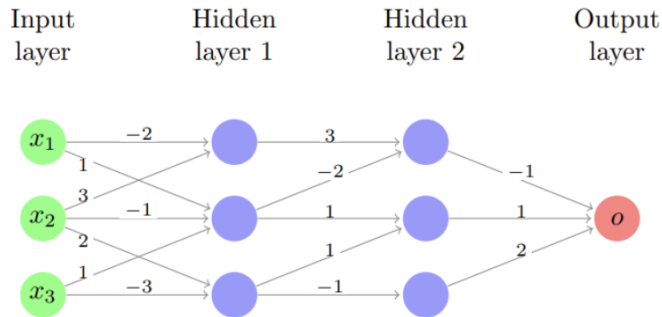
$$\Rightarrow \frac{\partial \mathcal{L}}{\partial h_2} \odot \sigma'(z_2) = \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} \odot \begin{bmatrix} 0.16 \\ 0.25 \\ 0.21 \end{bmatrix} = \begin{bmatrix} 0.16 \\ 0.75 \\ 0.42 \end{bmatrix}$$

$$\text{Sizes: } V \in \mathbb{R}^a \quad h_1, h_2 \in \mathbb{R}^b \quad W_1, W_2 \in \mathbb{R}^{3 \times a} \quad \frac{\partial \mathcal{L}}{\partial V} \in \mathbb{R}^a$$

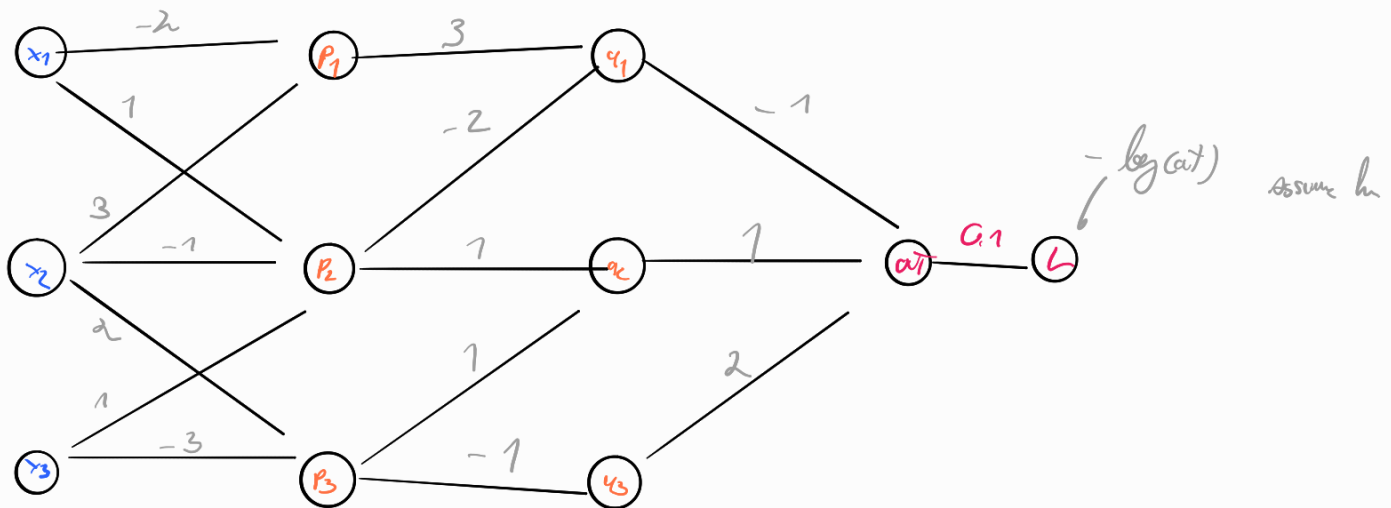
2022/06/16

Exercise 3

Consider the following network where on each edge (i, j) the value of $\frac{\partial y(j)}{\partial y(i)}$ is given; $y(k)$ denotes the activation of node k .



The output o is equal to 0.1 and the loss function is $L = -\log(o)$. Compute the value of $\frac{\partial L}{\partial x_i}$ for each input x_i using the backpropagation method.



Backpropagation

$$\frac{\partial L}{\partial act} = -\frac{1}{act} = -\frac{1}{0.1} = -10$$

$$\frac{\partial L}{\partial q_1} = \frac{\partial L}{\partial act} \cdot \frac{\partial act}{\partial q_1} = -10 \cdot 1 = -10$$

$$\frac{\partial L}{\partial q_2} = \frac{\partial L}{\partial act} \cdot \frac{\partial act}{\partial q_2} = -10 \cdot 1 = -10$$

$$\frac{\partial L}{\partial q_3} = \frac{\partial L}{\partial act} \cdot \frac{\partial act}{\partial q_3} = -10 \cdot 2 = -20$$

$$\frac{\partial L}{\partial p_1} = \frac{\partial L}{\partial q_1} \cdot \frac{\partial q_1}{\partial p_1} = 10 \cdot 3 = 30$$

$$\frac{\partial L}{\partial p_2} = \frac{\partial L}{\partial q_1} \cdot \frac{\partial q_1}{\partial p_2} + \frac{\partial L}{\partial q_2} \cdot \frac{\partial q_2}{\partial p_2} = (10 \cdot -2) + (-10 \cdot 1) = -30$$