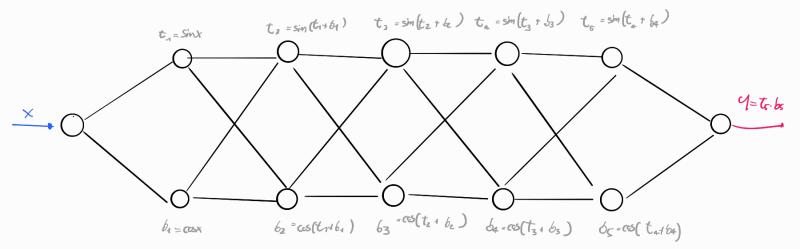


Figure 1: Computational Graph

The upper node in each layer computes $\sin(x+y)$ and the lower computes $\cos(x+y)$ with respect to its 2 inputs. For the first hidden layer, there is only a single input x, and therefore the values $\sin(x)$ and $\cos(x)$ are computed. The final node computes the product of the two inputs. The single input is denoted by x (value in radiants). Compute the numerical value of the partial derivative of the output with respect to x for x=1 using the backpropagation algorithm. Explain clearly each step you have performed.



forward pass

$$\begin{cases}
E_1 = \sin(4) = 0.84 \\
b_1 = \cos(1) = 0.84
\end{cases}$$

$$\begin{cases}
(1+b_1 = 1.38) = 0.98 \\
b_2 = \cos(1.38) = 0.98
\end{cases}$$

$$\begin{cases}
b_2 = \cos(1.38) = 0.98 \\
b_3 = \cos(1.38) = 0.98
\end{cases}$$

$$\begin{cases}
(1+b_2 = 1.16) \\
(1+b_3 = 1.16) = 0.99 \\
b_3 = \cos(1.16) = 0.40
\end{cases}$$

$$\int_{C} \left\{ \frac{c_{3}+b_{3}=1.31}{6x=Slm(131)} = c_{19} \right\}$$

$$\int_{C} \left\{ \frac{c_{4}+b_{4}=c_{5}(1.31)}{6x=c_{5}(1.31)} = c_{19} \right\}$$

$$\int_{C} \left\{ \frac{c_{4}+b_{4}=1.2z}{6x=Slm(1.2z)} = c_{19} \right\}$$

$$\int_{C} \left\{ \frac{c_{5}+b_{3}=0.3z}{6x=C_{5}(1.2z)} - c_{13} \right\}$$

$$\int_{C} \left\{ \frac{c_{5}+b_{5}=0.3z}{6x=C_{5}(1.2z)} - c_{13} \right\}$$

$$\int_{C} \left\{ \frac{c_{5}+b_{5}=0.3z}{6x=C_{5}(1.2z)} - c_{13} \right\}$$

$$\int_{C} \left\{ \frac{c_{5}+b_{5}=0.3z}{6x=C_{5}(1.2z)} - c_{13} \right\}$$

obs: T and 6 have

(symmty!)

sur cartible on develue

Backward Pass
$$\left(\frac{d \sin x}{dx} = \cos x\right)$$
, $\frac{d \cos x}{dx} = -\sin x$ $t = \frac{34}{3t}$

$$\begin{cases} \dot{t}_5 = b_5 = c_{,34} \\ \dot{b}_5 = \dot{t}_5 = c_{,994} \end{cases}$$

$$\begin{cases} \dot{t}_6 = \dot{t}_5 \cdot \cos(\dot{t}_{04} + b_4) + \dot{b}_5 \left(-\sin(\dot{t}_{04} b_4)\right) = -c_{,772} \\ \dot{b}_4 = -c_{,772} \end{cases}$$

$$\begin{cases}
\dot{t}_{3} = \dot{t}_{1} \cos (\dot{t}_{3} + b_{3}) + \dot{b}_{4} \left(-\sin (\dot{t}_{3} + b_{3})\right) = ... \cos (\dot{t}_{5} + b_{5}) + \dot{b}_{4} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + b_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + b_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + b_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + b_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + b_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + b_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + \dot{b}_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + \dot{b}_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + \dot{b}_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + \dot{b}_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + \dot{b}_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + \dot{b}_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + \dot{b}_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5}) + \dot{b}_{5} \left(-\sin (\dot{t}_{5} + \dot{b}_{5})\right) = ... \cos (\dot{t}_{5} + \dot{b}_{5} + \dot$$