

Rysowanie w aplikacji, śledząc ruch markera przy pomocy systemu wizyjnego

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Część V

Gesty

```
gocv.CvtColor(img, &imgGrey, gocv.ColorBGRTToGray)
gocv.GaussianBlur(imgGrey, &imgBlur, image.Pt(35, 35), 0, 0, gocv.BorderDefault)
gocv.Threshold(imgBlur, &imgThresh, 0, 255, gocv.ThresholdBinaryInv+gocv.ThresholdOtsu)

contours := gocv.FindContours(imgThresh, gocv.RetrievalExternal, gocv.ChainApproxSimple)
c := getBiggestContour(contours)

gocv.ConvexHull(c, &hull, true, false)
gocv.ConvexityDefects(c, hull, &defects)

var angle float64
defectCount := 0
for i := 0; i < defects.Rows(); i++ {
    start := c[defects.GetIntAt(i, 0)]
    end := c[defects.GetIntAt(i, 1)]
    far := c[defects.GetIntAt(i, 2)]

    a := math.Sqrt(math.Pow(float64(end.X-start.X), 2) + math.Pow(float64(end.Y-start.Y), 2))
    b := math.Sqrt(math.Pow(float64(far.X-start.X), 2) + math.Pow(float64(far.Y-start.Y), 2))
    c := math.Sqrt(math.Pow(float64(end.X-far.X), 2) + math.Pow(float64(end.Y-far.Y), 2))

    // apply cosine rule here
    angle = math.Acos((math.Pow(b, 2)+math.Pow(c, 2)-math.Pow(a, 2))/(2*b*c)) * 57

    // ignore angles > 90 and highlight rest with dots
    if angle <= 90 {
        defectCount++
        gocv.Circle(&img, far, 10, green, 2)
    }
}

return defectCount
```

Gesty

```
socket.onmessage = msg => {  
  let count = JSON.parse(msg.data).count;  
  if (count === 0 || count === 1) {  
    this.setPen();  
  } else if (count === 2 || count === 3) {  
    this.setBrush();  
  } else {  
    this.setEraser();  
  }  
};  
}
```

Pauszowanie i czyszczenie

