Total Type Error Localization and Recovery with Holes

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Reality check

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Most of the code we write is **ill-typed**

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- **localize type errors**: describe *what* and *where* they are
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i.e., code completion, type hints, and other downstream services shouldn't suddenly all fail because of one error!

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OCaml: the first branch is right

```
let f=\lambda b : bool. \cdots in let x= if true then 5 else false in f x 1 | let x= if true then 5 else false in f x
```

Error: This expression has type bool but an expression
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Error: This expression has type int but an expression
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Haskell: 5 is the problem

```
let f=\lambda b : bool. \cdots in let x= if true then \bf 5 else false in f x Main.hs:4:26: error: [GHC-39999]

• No instance for 'Num Bool' arising from the literal '5'

4 | _ = let x = if True then \bf 5 else False in f x
```

Rust: maybe 5 is also the problem?

```
let f=\lambda b : bool. \cdots in let x= if true then 5 else false in f x error[E0308]: 'if' and 'else' have incompatible types -> src/main.rs:2:30 | 6 | let x= if true 5 else false ; f(x); | - ^^^^ expected integer, found 'bool' | | expected because of this
```

Hazel: the whole thing's all messed up!

let $f = \lambda b$: bool. \cdots in let x =if true then 5 else false in f(x)

```
let f = fun b : Bool -> in
let x = if true then 5 else false in f(x)
EXP ? If expression Branches have inconsistent types: Int , Bool
```

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- localization can be varied, often guessing about *user intent*
- recovery necessitates reasoning without complete knowledge about types
- decisions can influence other downstream decisions

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If a type error appears **anywhere**, the program is meaningless **everywhere**.

The goal

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Totality

These semantics should give meaning to *all well-typed and ill-typed programs*.

Uniting *local* and *global* type inference for principled total type error localization and recovery:

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- the **marked lambda calculus**: a judgmental framework for bidirectional type error localization and recovery
- **type hole inference**: a global, constraint-based system that is neutral in error localization and recovery

Marked lambda calculus: a tutorial

Start: a small gradually typed lambda calculus*

```
	au ::= ? \mid \text{num} \mid \text{bool} \mid 	au 	o 	au
e ::= x \mid \lambda x : 	au . e \mid e e \mid n \mid \text{true} \mid \text{false} \mid \text{if } e \text{ then } e \text{ else } e
```

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Start: a small gradually typed lambda calculus*

```
	au ::= ? \mid \text{num} \mid \text{bool} \mid \tau \to \tau
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```

with a standard bidirectional type system

$$\Gamma \vdash e \Rightarrow \tau \quad (e \text{ synthesizes type } \tau)$$

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*We need only the *static semantics* for ill-typed programs!

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Synthesizing the type of a variable is standard:

SVAR

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But what if $x \notin \text{dom}(\Gamma)$?

How do we handle this failure case?

```
let rec syn ctx e =
  match e with
  Var x ->
    match Ctx.lookup ctx x with
       Some ty -> ty
       None -> ???
...
```

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```
let rec syn ctx e =
  match e with
  Var x ->
    match Ctx.lookup ctx x with
       Some ty -> ty
       None    -> failwith (x ++ " is unbound")
...
```

How do we handle this failure case?

```
let rec syn ctx e =
  match e with
  Var x ->
    match Ctx.lookup ctx x with
       Some ty -> Ok(ty)
       None -> Error(UnboundError(...))
...
```

We've *localized* the error: "this occurrence of x is unbound!"

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Solution. ?

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Solution. ? \leftarrow unknown type

Idea. Augment the type checking process with *marking*!

• localize and report the error as a *mark*

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 - compiler messages

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 - editor decorations
- use the unknown type to encapsulate missing type information

$$rac{ au_1 \sim au_1}{ au_2 \sim au_2} \qquad rac{ au_1 \sim au_1' \qquad au_2 \sim au_2'}{ au_1
ightarrow au_2 \sim au_1'
ightarrow au_2'}$$

Supplement the *unmarked* syntax

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	au ::= ? \mid \text{num} \mid \text{bool} \mid \tau \to \tau
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into a *marked* one that contains *error marks*:

$$\check{e} ::= x \mid \lambda x : \tau. \check{e} \mid \check{e} \check{e} \mid n \mid \text{true} \mid \text{false} \mid \text{if } \check{e} \text{ then } \check{e} \text{ else } \check{e} \mid (x)_{\square}$$

 $(x)_{\square}$ is a marked term denoting a free occurrence of x

Extend the original typing judgments

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into the bidirectional **marking judgments**:

```
\Gamma \vdash e \hookrightarrow \check{e} \Rightarrow \tau (e is marked into \check{e} and synthesizes type \tau)
\Gamma \vdash e \hookrightarrow \check{e} \Leftarrow \tau (e is marked into \check{e} and analyzes against type \tau)
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Type-based semantic services use marked terms!

$$\Gamma \vdash_{\!\!\scriptscriptstyle{M}} \check{e} \Rightarrow \tau \quad (\check{e} \text{ synthesizes type } \tau)$$
 $\Gamma \vdash_{\!\!\scriptscriptstyle{M}} \check{e} \Leftarrow \tau \quad (\check{e} \text{ analyzes against type } \tau)$

One typing rule for variables

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$$\frac{x:\tau\in\Gamma}{\Gamma\vdash x\looparrowright x\Rightarrow\tau}$$

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$$\begin{array}{ccc} \mathsf{MKSVar} & \mathsf{MKSFree} \\ x: \tau \in \Gamma & & x \not\in \mathsf{dom}(\Gamma) \\ \hline \Gamma \vdash x \looparrowright x \Rightarrow \tau & & \Gamma \vdash x \looparrowright & \Rightarrow \end{array}$$

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One typing rule for variables

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$$\frac{x : \tau \in \Gamma}{\Gamma \vdash x \hookrightarrow x \Rightarrow \tau} \qquad \frac{\text{MKSFree}}{\Gamma \vdash x \hookrightarrow (x)_{\square} \Rightarrow ?}$$

The standard subsumption principle:

$$rac{\Gamma dash e \Rightarrow au' \qquad au \sim au'}{\Gamma dash e \Leftarrow au}$$

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becomes the analytic marking rule:

$$\frac{\Gamma \vdash e \looparrowright \check{e} \Rightarrow \tau' \qquad \tau \sim \tau'}{\Gamma \vdash e \looparrowright \check{e} \Leftarrow \tau}$$

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$$\frac{\Gamma \vdash e \hookrightarrow \check{e} \Rightarrow \tau' \qquad \tau \sim \tau'}{\Gamma \vdash e \hookrightarrow \check{e} \Leftarrow \tau} \qquad \frac{\text{MKAInconsistentTypes}}{\Gamma \vdash e \hookrightarrow \check{e} \Leftarrow \tau} \qquad \frac{\Gamma \vdash e \hookrightarrow \check{e} \Rightarrow \tau' \qquad \tau \nsim \tau'}{\Gamma \vdash e \hookrightarrow (|\check{e}|) \iff \tau}$$

MKAInconsistentTypes
$$\frac{\Gamma \vdash e \looparrowright \check{e} \Rightarrow \tau' \qquad \tau \nsim \tau'}{\Gamma \vdash e \looparrowright (\![\check{e}]\!]_{\tau} \Leftarrow \tau}$$

What if
$$\tau \nsim \tau'$$
, e.g., in $5 + \frac{\text{(true)}_{\sim}}{\text{?}}$?

$$\check{e} ::= \cdots \mid (x)_{\square} \mid (\check{e})_{\nsim}$$

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... and the rest

```
e ::= \cdots
| (|\check{e}_1|)^{\Rightarrow}_{\blacktriangleright, \neq} \check{e}_2
| (|\mathsf{if} \; \check{e}_1 \; \mathsf{then} \; \check{e}_2 \; \mathsf{else} \; \check{e}_3|)_{\nabla}
| (|\lambda x : \tau . \; \check{e}|)^{\Leftarrow}_{\blacktriangleright, \neq}
| (|\lambda x : \tau . \; \check{e}|)_{:}
```

 \check{e}_1 synthesizes non-matched arrow type branches synthesize inconsistent types analysis against non-matched arrow type ascription inconsistent with domain

A total marking

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Theorem 2.1. Totality

For all Γ and e, $\exists \check{e}, \tau$ s.t. $\Gamma \vdash e \hookrightarrow \check{e} \Rightarrow \tau$.

For all Γ , e, and τ , $\exists \check{e}$ s.t. $\Gamma \vdash e \hookrightarrow \check{e} \Leftarrow \tau$.

(Every unmarked term can be marked under any context!)

A sensible marking

Theorem 2.2. Well-Formedness

If $\Gamma \vdash e \hookrightarrow \check{e} \Rightarrow \tau$, then $\Gamma \vdash_{\!\scriptscriptstyle{M}} \check{e} \Rightarrow \tau$ and $\check{e}^{\square} = e$. If $\Gamma \vdash e \hookrightarrow \check{e} \Leftarrow \tau$, then $\Gamma \vdash_{\!\scriptscriptstyle{M}} \check{e} \Leftarrow \tau$ and $\check{e}^{\square} = e$. (Marking only adds marks, *i.e.*, marking then erasing is identity!)

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```

Theorem 2.3(1). Well-Typed Terms

```
If \Gamma \vdash_{v} e \Rightarrow \tau, then \exists \check{e} s.t. \Gamma \vdash e \looparrowright \check{e} \Rightarrow \tau and \check{e} markless. If \Gamma \vdash_{v} e \Leftarrow \tau, then \exists \check{e} s.t. \Gamma \vdash e \looparrowright \check{e} \Leftarrow \tau and \check{e} markless. (Marking well-typed terms introduces no marks!)
```

Theorem 2.2. Well-Formedness

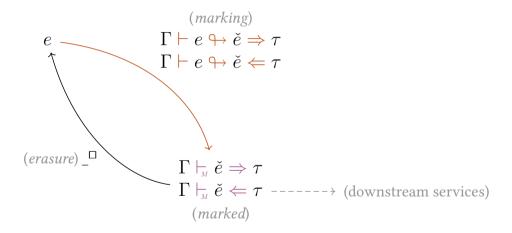
```
If \Gamma \vdash e \hookrightarrow \check{e} \Rightarrow \tau, then \Gamma \vdash_{\!\scriptscriptstyle{M}} \check{e} \Rightarrow \tau and \check{e}^{\square} = e.

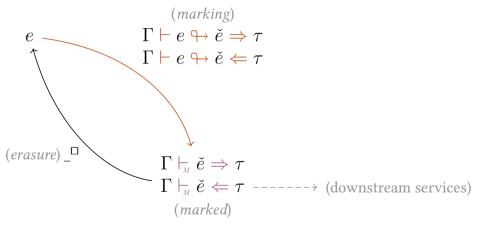
If \Gamma \vdash e \hookrightarrow \check{e} \Leftarrow \tau, then \Gamma \vdash_{\!\scriptscriptstyle{M}} \check{e} \Leftarrow \tau and \check{e}^{\square} = e.

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Theorem 2.3(1). Well-Typed Terms

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Metatheory completely mechanized in Agda [hazelgrove/error-localization-agda]

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- Derive marking rules from each typing rule
 - Consider the "success" case
 - Consider the "failure" cases, introducing error marks
- *Not* prescriptive *w.r.t.* localization strategy
 - We formalize three possible localization strategies for if-then-else with inconsistent branches

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 : ? . $f(f+1)$

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Global, constraint-based type checking would have caught this!

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Get the best of both worlds by layering **constraint-based inference** atop the marked lambda calculus

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- Type hole inference solves and marks *global inconsistencies*
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fun f: Int
$$\rightarrow$$
 \leftarrow \rightarrow f (f + 1)

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Control returned to bidirectional system after user selects

• A full description of the marked lambda calculus





- A full description of the marked lambda calculus, and
 - mechanization in Agda [hazelgrove/error-localization-agda]





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 - connections to structured editing
- A more thorough discussion of type hole inference, and
 - filling expression holes





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- VI.1
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Reusable VI

- connections to structured editing
- A more thorough discussion of type hole inference, and
 - filling expression holes
 - polymorphic generalization
- Implementations of both in Hazel [hazel.org] [hazelgrove/hazel]

More in the paper and artifact

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 - connections to structured editing
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 - filling expression holes
 - polymorphic generalization
- Implementations of both in Hazel [hazel.org] [hazelgrove/hazel]





Consider using these techniques for your next language!

MKSIF

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow$$

.....

MKSIF

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool}$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow$$

 \Rightarrow

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1$$

$$\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow$$

MKSIF

 $\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \text{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2$

 $\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow$

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathrm{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2$$

$$\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1$$

$$\Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2$$

$$\tau_3 = \tau_1 \sqcap \tau_2$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow$$

$$\Rightarrow$$

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2$$

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$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3 \Rightarrow$$

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool}$$

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$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2$$

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MKSIF

$$\frac{\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \text{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2}{\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3 \Rightarrow \tau_3}$$

MKSINCONSISTENTBRANCHES

$$\frac{\Gamma \vdash e_1 \looparrowright \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \looparrowright \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \looparrowright \check{e}_3 \Rightarrow \tau_2 \qquad \tau_1 \nsim \tau_2}{\Gamma \vdash \mathsf{if} \ e_1 \ \mathsf{then} \ e_2 \ \mathsf{else} \ e_3 \looparrowright} \Rightarrow$$

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MKSIF

$$\frac{\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2}{\Gamma \vdash \mathsf{if} \ e_1 \ \mathsf{then} \ e_2 \ \mathsf{else} \ e_3 \hookrightarrow \mathsf{if} \ \check{e}_1 \ \mathsf{then} \ \check{e}_2 \ \mathsf{else} \ \check{e}_3 \Rightarrow \tau_3}$$

MKSInconsistentBranches

$$\frac{\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_1 \nsim \tau_2}{\Gamma \vdash \mathsf{if} \qquad \mathsf{if$$

 $\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow (\text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3)_{\not \sqcap} \Rightarrow$

29

MKSIF

$$\frac{\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \text{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2}{\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3 \Rightarrow \tau_3}$$

MKSInconsistentBranches

$$\frac{\Gamma \vdash e_1 \looparrowright \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \looparrowright \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \looparrowright \check{e}_3 \Rightarrow \tau_2 \qquad \tau_1 \nsim \tau_2}{\Gamma \vdash \mathsf{if} \ e_1 \ \mathsf{then} \ e_2 \ \mathsf{else} \ e_3 \looparrowright \ (\mathsf{if} \ \check{e}_1 \ \mathsf{then} \ \check{e}_2 \ \mathsf{else} \ \check{e}_3)_{\bowtie} \Rightarrow ?}$$

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MKSIF
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$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathrm{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2$$

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MKSInconsistentBranches

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \overline{\tau_1} \nsim \overline{\tau_2}$$

$$\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1$$

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$$\tau_1 \nsim \tau_2$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow (\text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3)_{|\gamma|} \Rightarrow ?$$

MKSIE'

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow$$

MKSIF

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2$$

$$\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1$$

$$\Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2$$

$$\tau_3 = \tau_1 \sqcap \tau_2$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3 \Rightarrow \tau_3$$

MKSInconsistentBranches

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \overline{\tau_1} \nsim \overline{\tau_2}$$

$$\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1$$

$$\Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2$$

$$au_1 \nsim au_2$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \{\text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3\}_{|\gamma|} \Rightarrow ?$$

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool}$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow$$



MKSIF

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2$$

$$\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1$$

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$$\tau_3 = \tau_1 \sqcap \tau_2$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3 \Rightarrow \tau_3$$

MKSInconsistentBranches

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \overline{\tau_1} \nsim \overline{\tau_2}$$

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$$au_1 \nsim au_2$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \{\text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3\}_{\bowtie} \Rightarrow ?$$

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \text{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau$$

$$\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow$$

MKSIF

$$\frac{\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \text{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2}{\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3 \Rightarrow \tau_3}$$

MKSINCONSISTENTBRANCHES

$$\frac{\Gamma \vdash e_1 \looparrowright \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \looparrowright \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \looparrowright \check{e}_3 \Rightarrow \tau_2 \qquad \tau_1 \nsim \tau_2}{\Gamma \vdash \mathsf{if} \ e_1 \ \mathsf{then} \ e_2 \ \mathsf{else} \ e_3 \looparrowright \ (\mathsf{if} \ \check{e}_1 \ \mathsf{then} \ \check{e}_2 \ \mathsf{else} \ \check{e}_3)_{\bowtie} \Rightarrow ?}$$

.....

$$\frac{\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \begin{array}{c} (\mathsf{prioritize\;first\;branch}) \\ \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau \end{array} \qquad \begin{array}{c} (\mathsf{blame\;second\;branch}) \\ \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Leftarrow \tau \\ \hline \Gamma \vdash \mathsf{if}\; e_1 \; \mathsf{then}\; e_2 \; \mathsf{else}\; e_3 \hookrightarrow \\ \end{array} \Rightarrow$$

MKSIF

$$\frac{\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2}{\Gamma \vdash \mathsf{if} \ e_1 \ \mathsf{then} \ e_2 \ \mathsf{else} \ e_3 \hookrightarrow \mathsf{if} \ \check{e}_1 \ \mathsf{then} \ \check{e}_2 \ \mathsf{else} \ \check{e}_3 \Rightarrow \tau_3}$$

MKSInconsistentBranches

$$\frac{\Gamma \vdash e_1 \looparrowright \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \looparrowright \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \looparrowright \check{e}_3 \Rightarrow \tau_2 \qquad \tau_1 \nsim \tau_2}{\Gamma \vdash \mathsf{if} \ e_1 \ \mathsf{then} \ e_2 \ \mathsf{else} \ e_3 \looparrowright \ (\mathsf{jif} \ \check{e}_1 \ \mathsf{then} \ \check{e}_2 \ \mathsf{else} \ \check{e}_3)_{\bowtie} \Rightarrow ?}$$

.....

MKSIF'

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \text{bool} \qquad \begin{array}{c} \text{(prioritize first branch)} \\ \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau \end{array} \qquad \begin{array}{c} \text{(blame second branch)} \\ \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Leftarrow \tau \end{array}$$

 $\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3 \Rightarrow$

MKSIF

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \tau_3 = \tau_1 \sqcap \tau_2$$

$$\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1$$

$$\Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2$$

$$\tau_3 = \tau_1 \sqcap \tau_2$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3 \Rightarrow \tau_3$$

MKSInconsistentBranches

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool} \qquad \Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1 \qquad \Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2 \qquad \overline{\tau_1} \nsim \overline{\tau_2}$$

$$\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau_1$$

$$\Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Rightarrow \tau_2$$

$$au_1 \nsim au_2$$

$$\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow (\text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3)_{\bowtie} \Rightarrow ?$$

MKSIF'

$$\Gamma \vdash e_1 \hookrightarrow \check{e}_1 \Leftarrow \mathsf{bool}$$
 $\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau$ $\Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Leftarrow \tau$

$$\Gamma \vdash e_2 \hookrightarrow \check{e}_2 \Rightarrow \tau$$

$$\Gamma \vdash e_3 \hookrightarrow \check{e}_3 \Leftarrow \tau$$

 $\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \hookrightarrow \text{if } \check{e}_1 \text{ then } \check{e}_2 \text{ else } \check{e}_3 \Rightarrow \tau$

- Link occurrences of ? to the originating type hole or error mark (denoted by unique id *u*)
- Distinguish between different ? based on locus

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$$p ::= u \mid exp(u) \mid \rightarrow_L (p) \mid \rightarrow_R (p)$$

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$$p ::= u \mid exp(u) \mid \to_L (p) \mid \to_R (p)$$

$$\tau ::= \cdots \mid ?^p$$

- Link occurrences of ? to the originating type hole or error mark (denoted by unique id u)
- Distinguish between different ? based on locus

$$p ::= u \mid exp(u) \mid \to_L (p) \mid \to_R (p)$$

$$\tau ::= \cdots \mid ?^p$$

$$\check{e} ::= \cdots \mid (x)_{\square}^u \mid (\check{e})_{\blacktriangleright}^{\to, u} \mid (\check{e})_{\sim}^u$$

Augment the type system (of the marked language) to generate sets C of constraints $\tau_1 \approx \tau_2$

$$\Gamma \vdash \check{e} \Rightarrow \tau \mid C$$
 $\Gamma \vdash \check{e} \Leftarrow \tau \mid C$

$$\Gamma \vdash \check{e} \Rightarrow \tau \mid C$$
 $\Gamma \vdash \check{e} \Leftarrow \tau \mid C$

$$\frac{\Gamma \vdash \check{e} \Rightarrow \tau' \mid C \qquad \tau \sim \tau'}{\Gamma \vdash \check{e} \Leftarrow \tau \mid C \cup \{\tau \approx \tau'\}}$$

$$\Gamma \vdash \check{e} \Rightarrow \tau \mid C$$
 $\Gamma \vdash \check{e} \Leftarrow \tau \mid C$

MASubsume-C
$$\frac{\Gamma \vdash \check{e} \Rightarrow \tau' \mid C \qquad \tau \sim \tau'}{\Gamma \vdash \check{e} \Leftarrow \tau \mid C \cup \{\tau \approx \tau'\}}$$

MAInconsistentTypes-C
$$\frac{\Gamma \vdash \check{e} \Rightarrow \tau' \mid C \qquad \tau \nsim \tau'}{\Gamma \vdash (\![\check{e}]\!]^u \Leftarrow \tau \mid C \cup \{\tau \approx ?^{exp(u)}\}}$$

For each occurrence of ?, accumulate the PotentialTypeSet

For each occurrence of ?, accumulate the PotentialTypeSet: *all* potential type fillings as inferred from the constraints

```
Potential
TypeSet s ::= \{t^*\} Potential
Type t ::= ?^p \mid \text{num} \mid \text{bool} \mid s \rightarrow s
```

For each occurrence of ?, accumulate the PotentialTypeSet: *all* potential type fillings as inferred from the constraints

```
PotentialTypeSet s := \{t^*\}
PotentialType t := ?^p \mid \text{num} \mid \text{bool} \mid s \rightarrow s
```

To unify $\tau_1 \approx \tau_2$, recursively merge PotentialTypeSet(τ_1) and PotentialTypeSet(τ_2) without substituting

$$\lambda f: ?^1$$
 . $f\left(f+1
ight)$

$$\lambda f: ?^1$$
 . $f(f+1)$

yields the (inconsistent) constraints

$$\{?^1 \approx ?^{\rightarrow_L(1)} \rightarrow ?^{\rightarrow_R(1)}\}$$

$$\lambda f: ?^1$$
 . $f(f+1)$

yields the (inconsistent) constraints

$$\{?^1pprox ?^{ o_{L}(1)} o ?^{ o_{R}(1)}, \mathsf{num}pprox ?^1\}$$

$$\lambda f: ?^1$$
 . $f(f+1)$

yields the (inconsistent) constraints

$$\{?^1pprox?^{oldsymbol{ o}_{oldsymbol{L}}(1)}
ightarrow?^{oldsymbol{ o}_{oldsymbol{R}}(1)}, \mathsf{num}pprox?^1, \mathsf{num}pprox?^{oldsymbol{ o}_{oldsymbol{L}}(1)}\}$$

$$\lambda f: ?^1$$
 . $f(f+1)$

yields the (inconsistent) constraints

$$\{?^1pprox?^{ o_L(1)} o?^{ o_R(1)}, \mathsf{num}pprox?^1, \mathsf{num}pprox?^{ o_L(1)}\}$$

$$PotentialTypeSet(?^1) = \{\}$$

$$\lambda f: ?^1$$
 . $f(f+1)$

yields the (inconsistent) constraints

$$\{?^1\approx?^{\boldsymbol{\rightarrow_L(1)}}_{\quad \ \, \wedge}\rightarrow?^{\boldsymbol{\rightarrow_R(1)}}, \mathbf{num}\approx?^1, \mathbf{num}\approx?^{\boldsymbol{\rightarrow_L(1)}}\}$$

PotentialTypeSet(?¹) =
$$\{\{?^{\rightarrow_L(1)}\} \rightarrow \{?^{\rightarrow_R(1)}\}\}$$

$$\lambda f: ?^1$$
 . $f(f+1)$

yields the (inconsistent) constraints

$$\{?^1 \approx ?^{\rightarrow_L(1)} \rightarrow ?^{\rightarrow_R(1)}, \mathsf{num} \underset{\wedge}{\approx} ?^1, \mathsf{num} \approx ?^{\rightarrow_L(1)}\}$$

PotentialTypeSet
$$(?^1) = \{\{?^{\rightarrow_L(1)}\} \rightarrow \{?^{\rightarrow_R(1)}\}, \underline{\text{num}}\}$$

$$\lambda f: ?^1$$
 . $f(f+1)$

yields the (inconsistent) constraints

$$\{?^1\approx?^{\boldsymbol{\rightarrow_L}(1)}\rightarrow?^{\boldsymbol{\rightarrow_R}(1)},\mathbf{num}\approx?^1,\mathbf{num}\underset{\wedge}{\approx}?^{\boldsymbol{\rightarrow_L}(1)}\}$$

$$PotentialTypeSet(?^1) = \{\{\underline{num}\} \rightarrow \{?^{\rightarrow_R(1)}\}, num\}$$