

Binary SearchTrees

Outline

1. Review on Fundamental Data Structures
2. Binary Search Trees

Dynamic Sets

- A dynamic set is a *collection* of data that can *change* over time both in size and contents
- Basic operations on dynamic sets:
 - Insert (S, x), Delete (S, x), Search (S, x)
- There are *various types of Dynamic Sets*
 - These are referred to as *Fundamental Data Structures*
 - A type of a Dynamic Set (a Fundamental Data Structure) **serves a specific purpose** and is designed to **address a particular usage context** determined by:
 - the **subsets of operations** they frequently use:
 - List, Array
 - the **special semantics** of the basic operations:
 - Stack, Queue

Fundamental Data Structures

Review

- **Stacks:**
 - *Insert (Push), Delete (Pop)*
 - Implemented by **Lists**; $O(1)$, $O(1)$
- **Queues:**
 - *Insert (Enqueue), Delete (Dequeue)*
 - Implemented by **Lists**; $O(1)$, $O(1)$
- **Priority Queues:** see [Sedgewick 2.4] [CLRS chap 6.5]
 - *Insert, Maximum, ExtractMax, IncreaseKey*
 - Implemented by **Heaps**; $O(\log n)$, $O(1)$, $O(\log n)$, $O(\log n)$
- **Dictionaries:** data structure for key-value pairs
 - *Insert, Search, Delete*
 - Implemented by **Hashtables**: see [Sedgewick chap 3.4][CLRS chap 11]
 - Generalizes the simple arrays, allows direct addressing of arbitrary positions in $O(1)$
 - *Hashing with chaining; Hashing with open addressing*

Libraries Implementing Fundamental Data Structures

- There are standard libraries implementing the fundamental data structures for most languages
- In industrial practice is recommended to use library implementations instead of redoing your own
- *Sometimes* you may need a very *customized* implementation
- *BUT: in order to **understand** them and to use them correct and appropriate, don't forget anything that you learned about fundamental data structures !*
- Example: Java: Collections
 - <https://docs.oracle.com/javase/tutorial/collections/TOC.html>

Fundamental Data Structures - Java

- Class `java.util.Stack<E>`
- Interface `java.util.Queue<E>`
 - General purpose queue implementation:
`class java.util.LinkedList<E>`
- Class `java.util.PriorityQueue<E>`
 - Implements an unbounded priority queue based on a *Heap*.
- Dictionaries: Interface `java.util.Map<K,V>`
 - General purpose implementation with Hashing:
`Class java.util.HashMap<K,V>`

Binary SearchTrees

[Sedgewick] – Chap 3.2

[CLRS] – Chap 12

Context and Problem

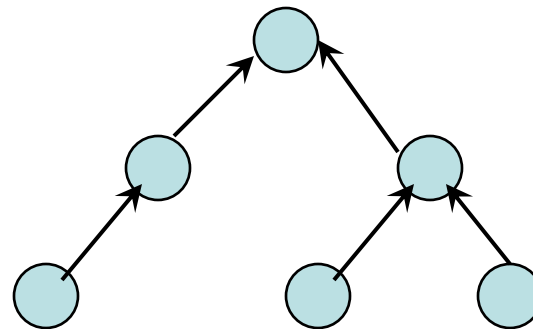
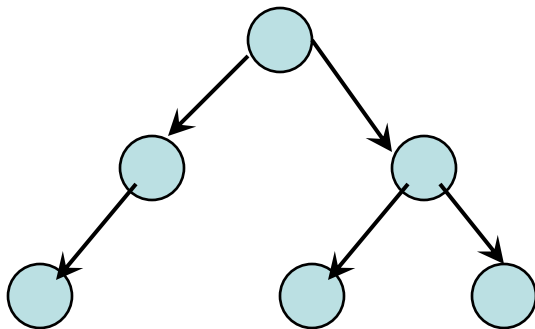
- We need a dynamic set that generalizes both the *Dictionary* structure as well as the *Priority Queue* structure
 - A **Sorted Dictionary**: a Dictionary that provides a *total ordering of the keys* (keys can be sorted, have min, max values, etc)
 - *all operations are equally important*: insert, delete, search, maximum, minimum, ordered list
- Such an abstract data type exists in Java collections:
- Interface `java.util.SortedMap<K,V>`
 - Extends interface `Map<K,V>`
- General purpose implementation: Class `java.util.TreeMap<K,V>`
 - `TreeMap` is implemented by *Balanced Binary Search Trees*

Kinds of Trees

- Binary Trees
 - Min-heaps and Max-heaps
 - Trees for arithmetic expressions
- Binary **Search** Trees
- **Balanced** Binary Search Trees

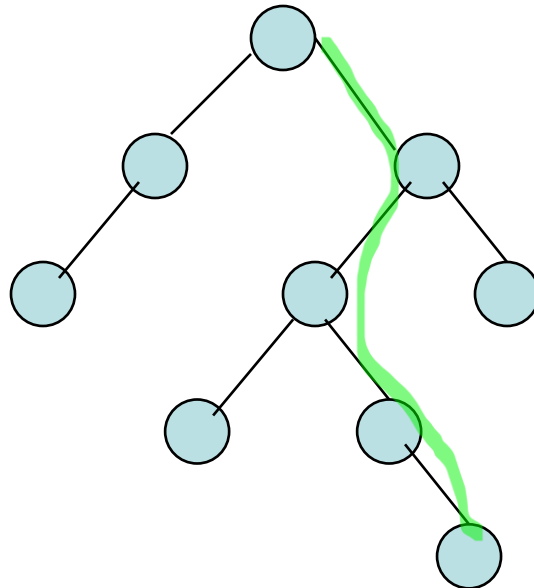
What is a **binary tree** ?

- A binary tree is a *linked data structure* in which *each node* is an object that contains following *attributes*:
 - a *key* and satellite data
 - *left*, pointing to its left *child*
 - *right*, pointing to its right *child*
 - *p*, pointing to its parent
- An implementation of a binary tree as a linked data structure may chose to represent it with help of links to children only or links to parent only.



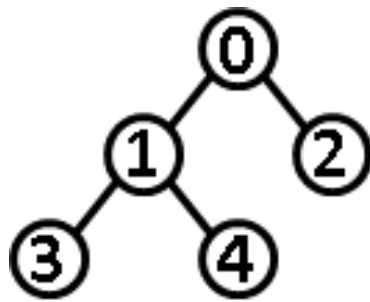
Concepts of a binary tree

- Particular kinds of nodes:
 - **Root:** node that has no parent
 - **Leaves:** nodes that have no children
- **Height** of a tree: longest path from the root to one of the leaves;
 $\max(\text{heights of subtrees}) + 1$

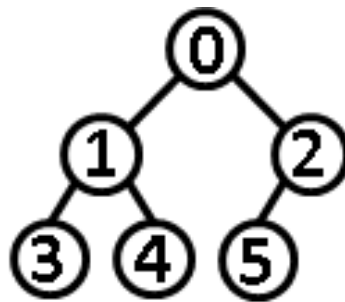


Shapes of binary trees

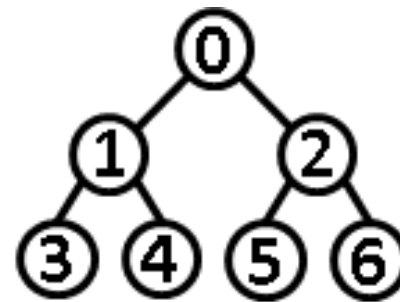
- A **full binary tree** is a binary tree in which every node other than the leaves has two children.
- A **complete binary tree** is a binary tree in which every level, except possibly the last, is completely filled, and all nodes are as far left as possible.
- A **perfect binary tree** is a binary tree in which all interior nodes have two children *and* all leaves have the same *level*.
- Degenerated tree – if every node has only 1 child, the tree is like a list



full
binary tree



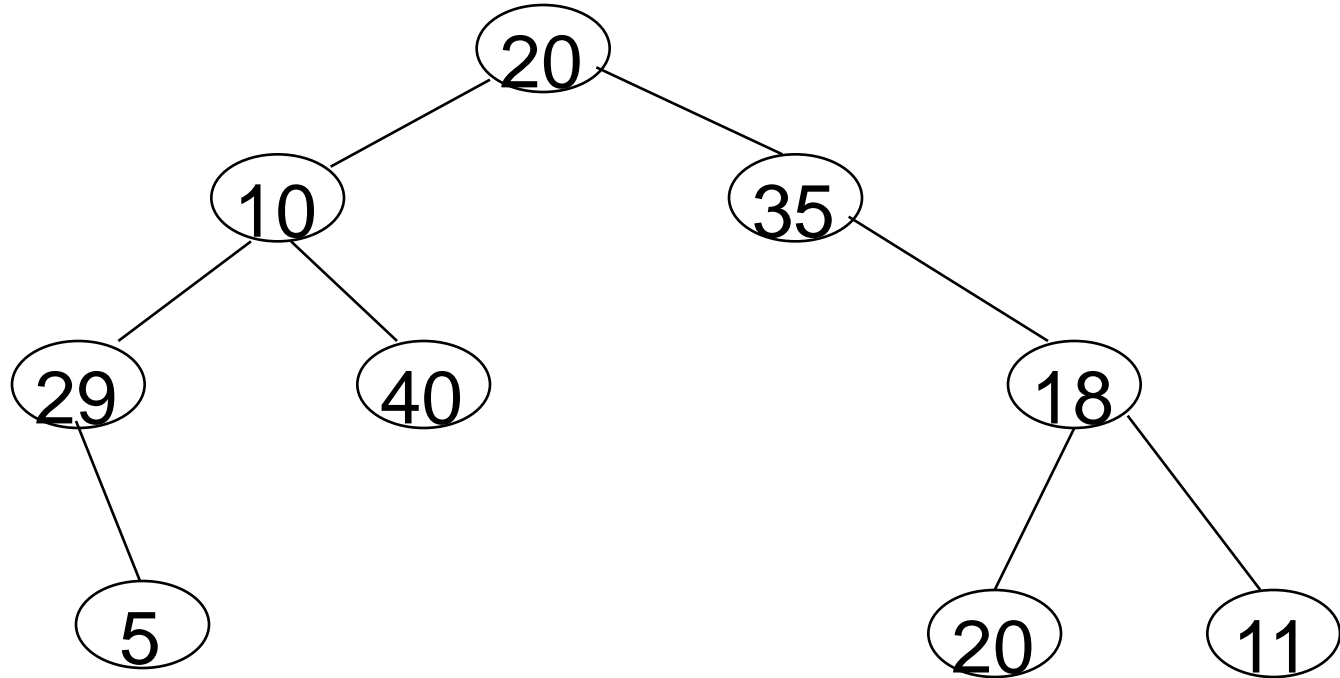
complete
binary tree



perfect
binary tree

Kinds of binary trees

- **General binary tree: no conditions regarding key values and tree shape.** Example:

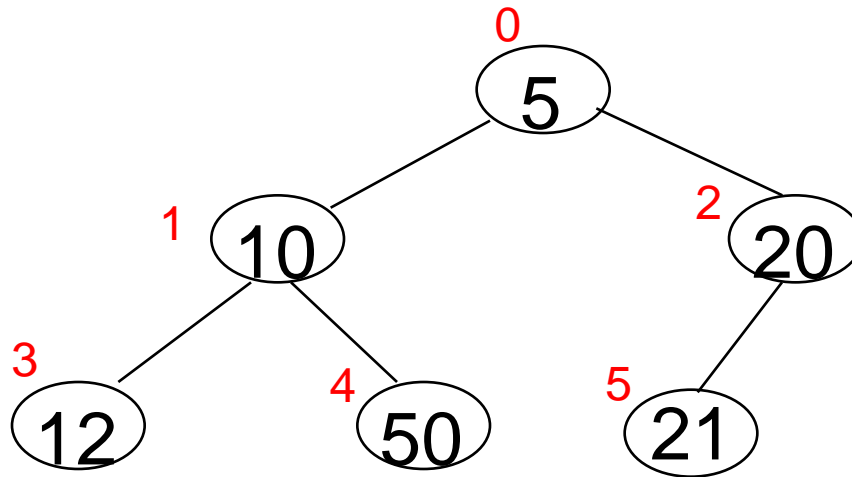


Kinds of binary trees

- **Min-heap tree:** is a binary tree such that:
 - the key contained in each node is *less* than (or equal to) the key in that node's children.
 - the binary tree is *complete*
- **Max-heap tree:** is a binary tree such that:
 - the key contained in each node is bigger than (or equal to) the key in that node's children.
 - the binary tree is *complete*
- Because Max-heap and Min-heap are *complete* trees they can be *represented as arrays* (position in array corresponds to position in complete binary tree) not as linked structures
- Review: Min-heap and Max-heap were used for Priority Queues and Sorting

Min-heap kind of Binary Tree

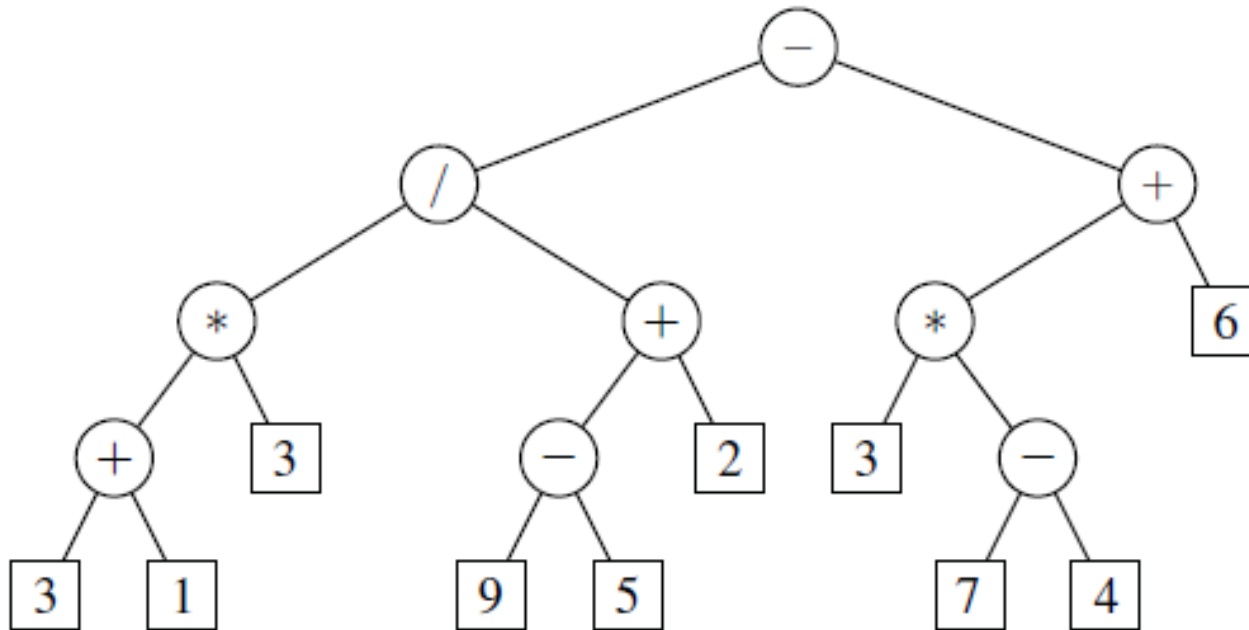
Example



0	1	2	3	4	5	
5	10	20	12	50	21	

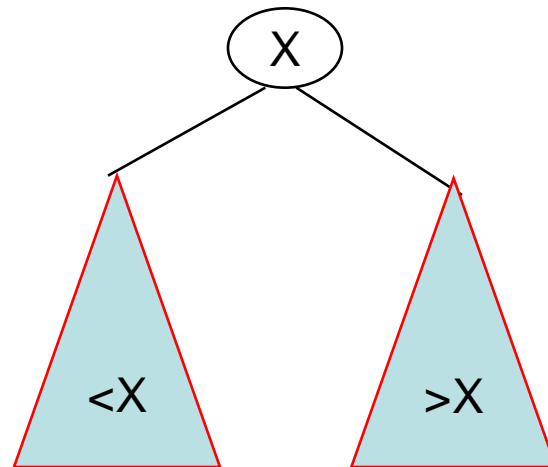
Binary Tree Representing Arithmetic Expression

- Leaves contain numbers, and internal nodes contain binary operators
- Each node has a value associated with it:
 - For non-leaves the value is defined by applying its operation to the values of its children
- Example: $((3+1)*3)/((9-5)+2)-((3*(7-4))+6)$

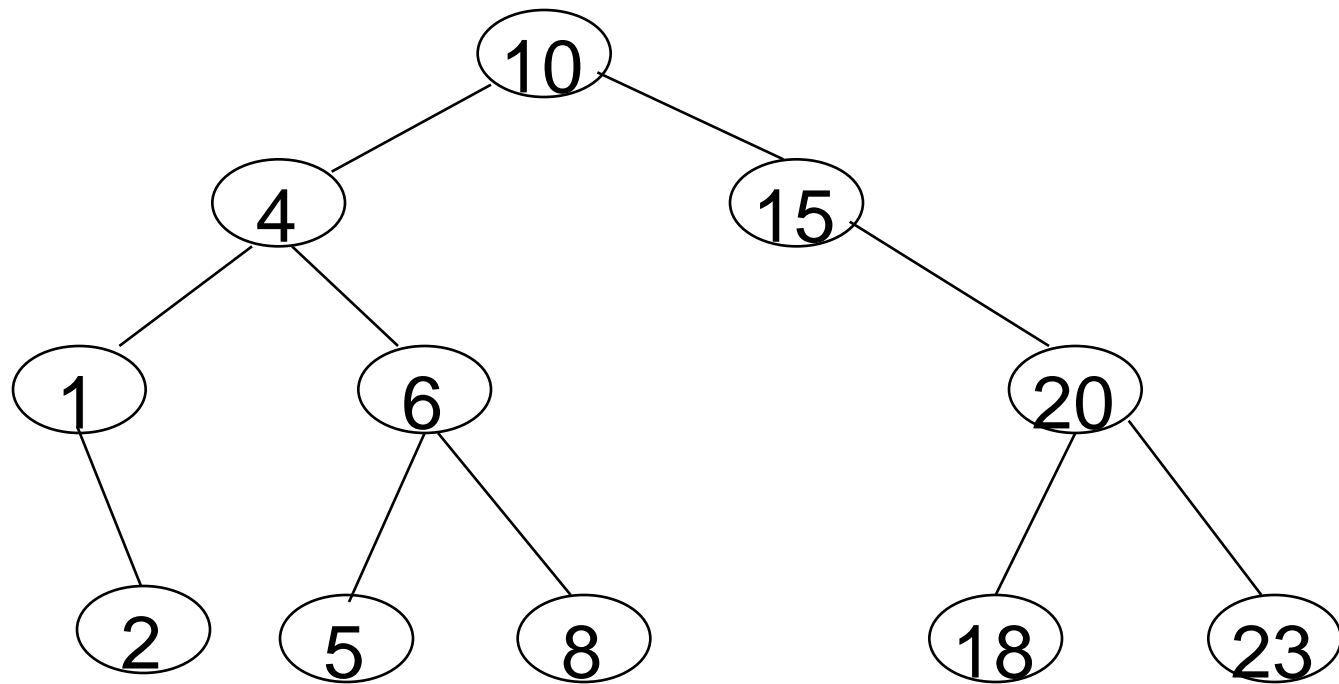


What is a Binary **Search** Tree (**BST**)

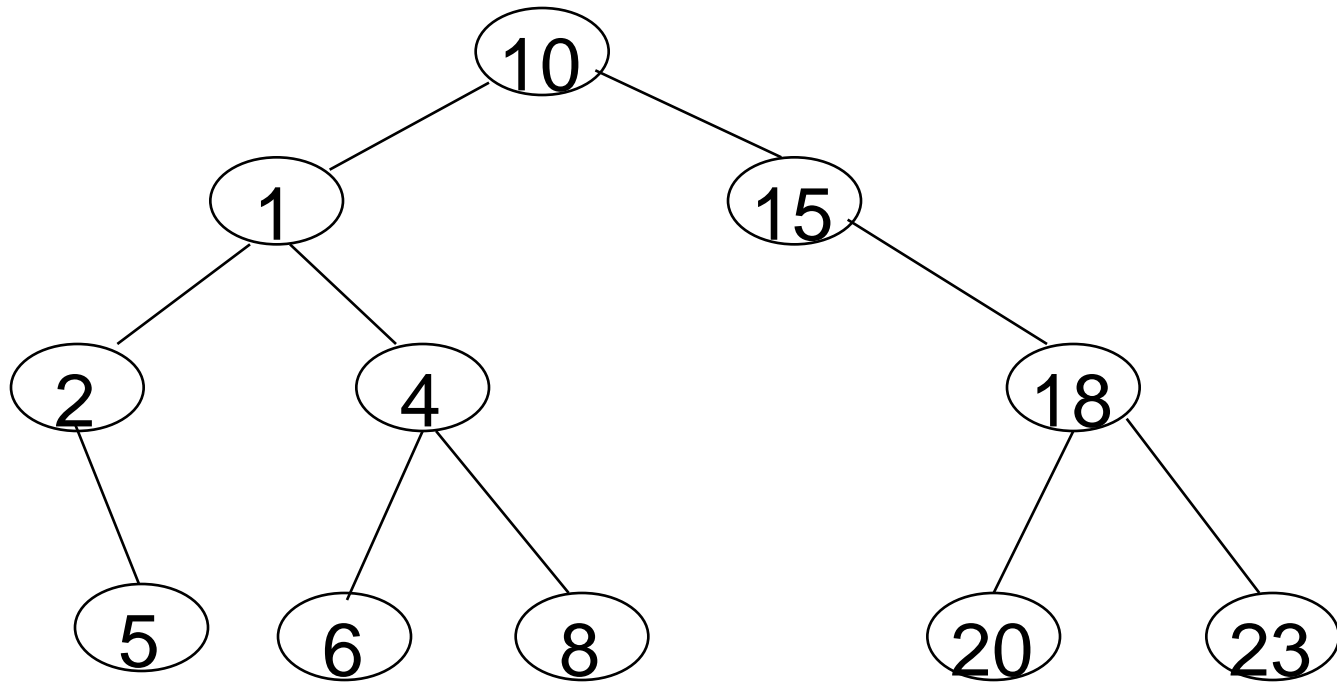
- The ***binary-search-tree property***:
- A *binary search tree* (BST) is a binary tree where each node has a Comparable key and satisfies the restriction that the key in ***any node*** is larger than the keys in all nodes in that node's left subtree and smaller than the keys in all nodes in that node's right subtree.



Example – BST



Counterexample – NOT a BST !



Simple BST in Java

```
public class IntBST {  
  
    private class Node { // BST Node = nested inner class  
        int key;           // sorted by Key  
        int val;          // associated data  
        Node left, right; // left and right subtrees  
  
        Node(int key, int val) {  
            this.key = key;  
            this.val = val;  
        }  
    }  
  
    private Node root; // root of BST  
  
    public IntBST() {  
        root = null; // initializes empty BST  
    }  
    // ...  
}
```

As a first example, we consider a **simple BST**, having `int` keys and values

If Node is an inner class, then only class IntBST can see it!
Public methods of IntBST cannot have Node in their signature !

What can be done on a BST ?

- Queries

- Search: search if there is a node with the given key
 - `boolean contains(int key);`
- Minimum: returns smallest key
 - `int min();`
- Maximum: returns biggest key
 - `int max();`

- Tree walks

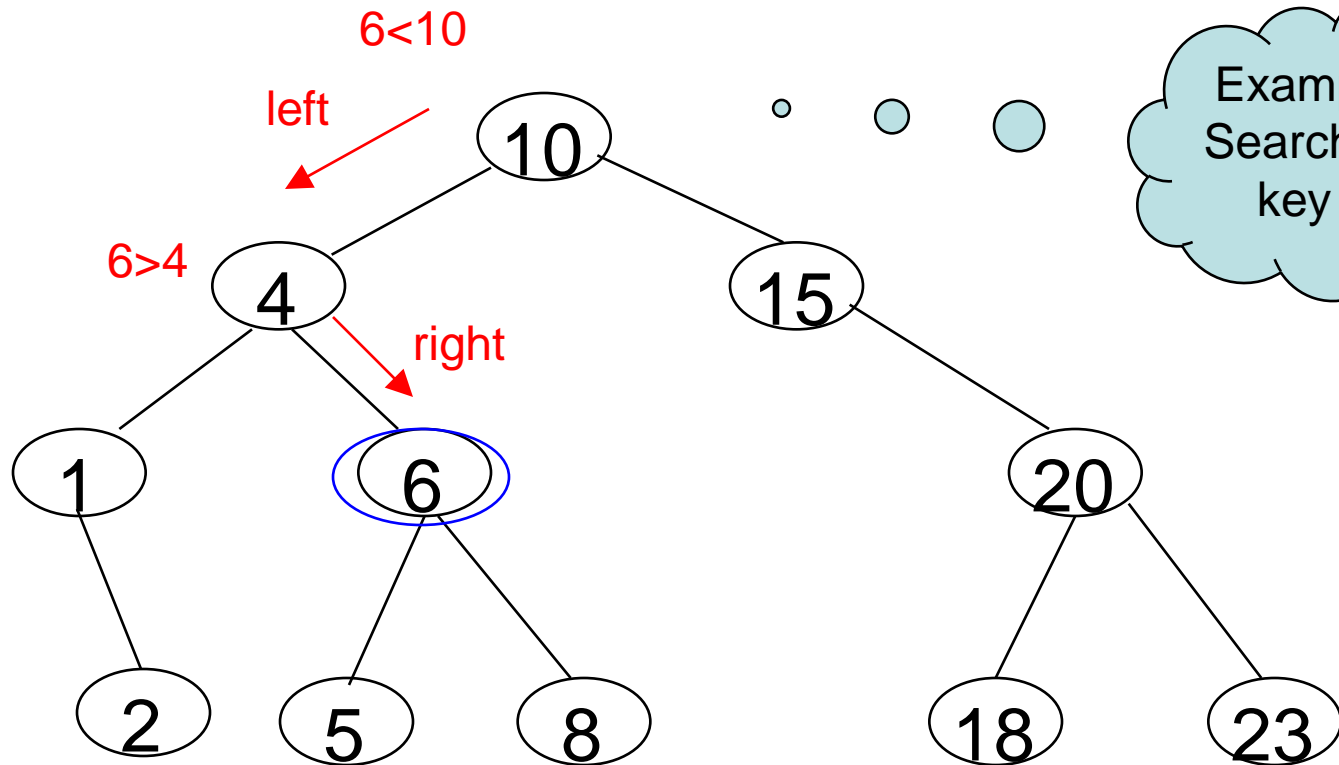
- List in order: prints all keys in increasing order
 - `void inorder();`

- Modifying

- Insert: if key is not in tree, add node, else update the value
 - `void put(int key, int value);`
- Delete: delete the node containing key
 - `void delete(int key);`

```
public class IntBST {  
  
    private class Node {  
        ...  
    }  
  
    private Node root;  
  
    public IntBST() { root = null; }  
  
    public boolean contains(int key) { ... }  
  
    public int min() { ... }  
  
    public int max() { ... }  
  
    public void inorder() { ... }  
  
    public void put(int key, int val) { ... }  
  
    public void delete(int key) { ... }  
  
}
```

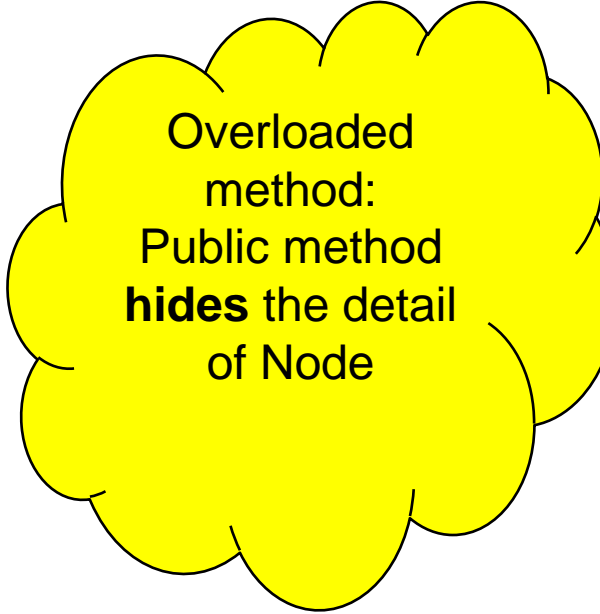
Search - Example



Search – recursive implementation

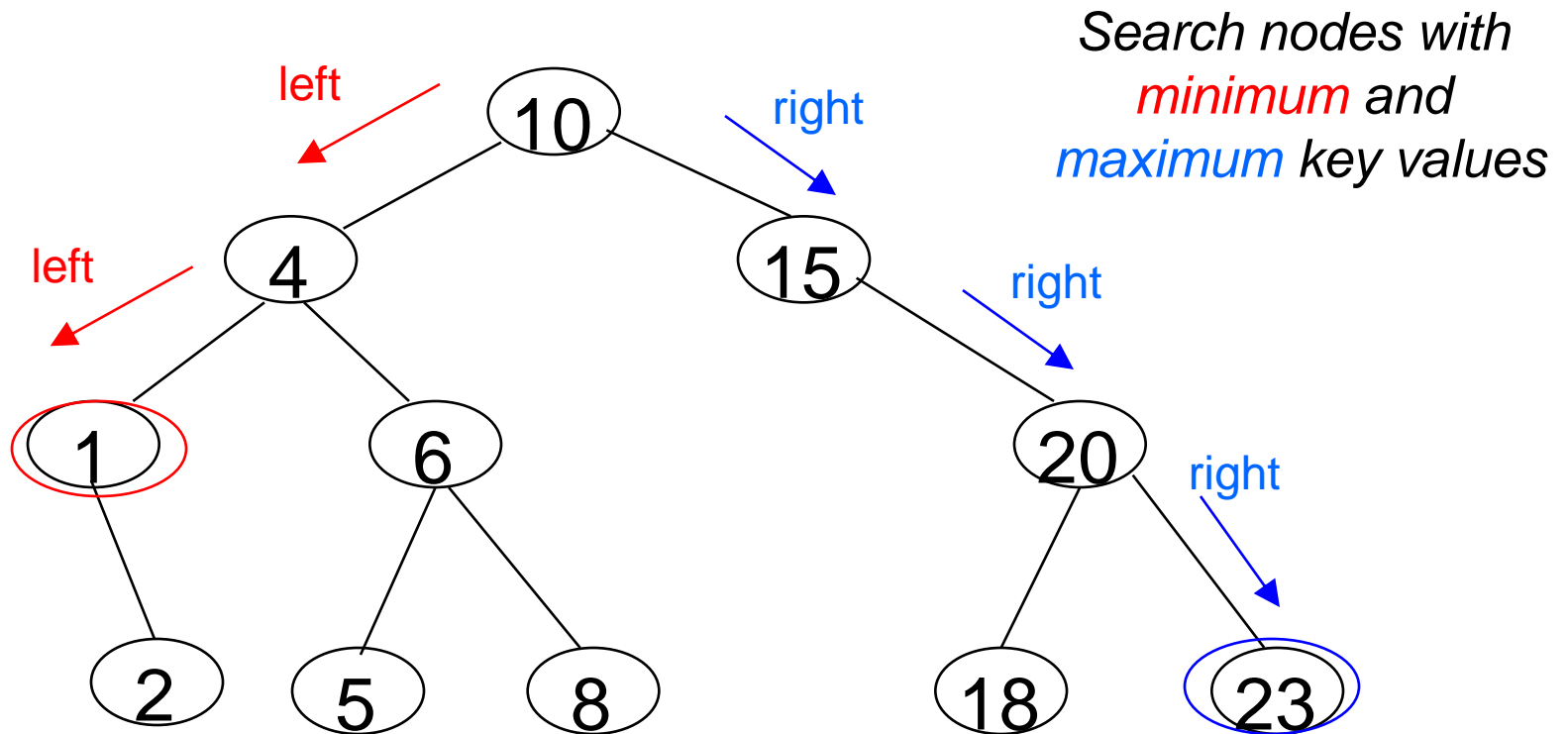
```
public boolean contains(int key) {  
    return contains(root, key);  
}
```

```
private boolean contains(Node x, int key) {  
    if (x == null) return false;  
    if (key < x.key) return contains(x.left, key);  
    else if (key > x.key) return contains(x.right, key);  
    else return true;  
}
```



Overloaded
method:
Public method
hides the detail
of Node

Minimum and Maximum - Example



Minimum - Implementation

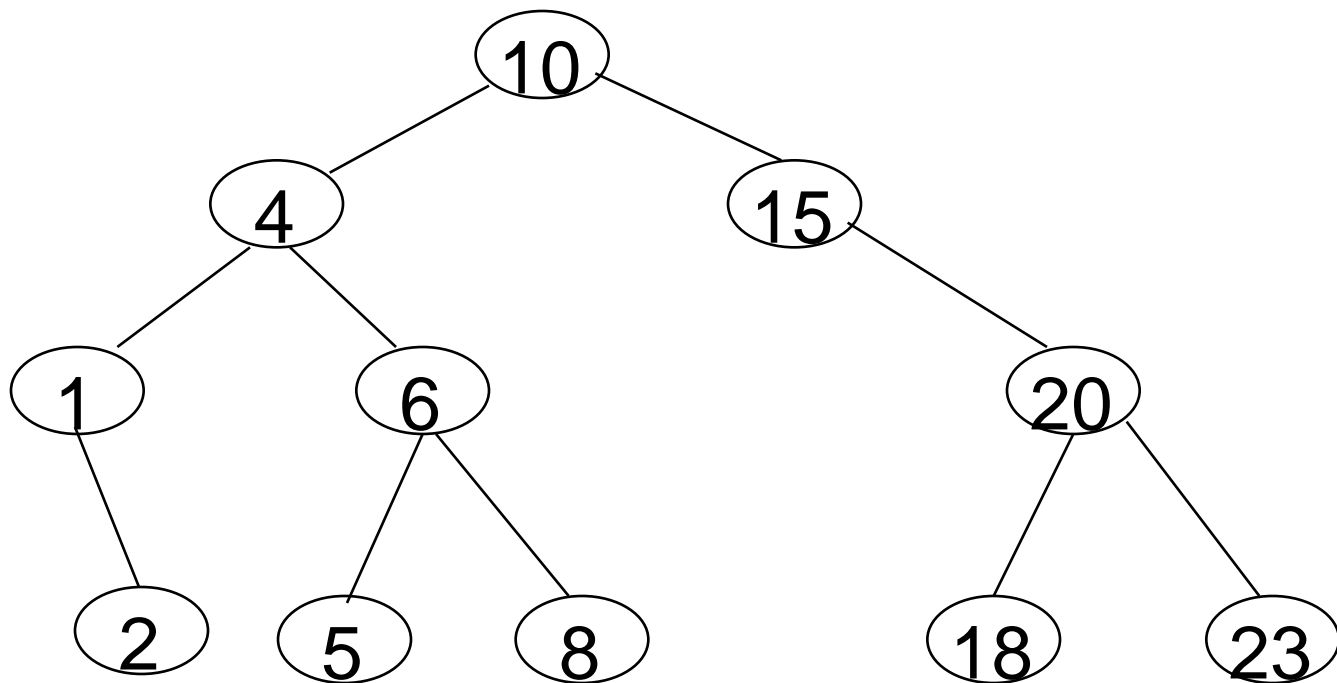
```
public int min() {  
    if (root == null) throw  
        new NoSuchElementException("calls min() with empty BST");  
    return min(root).key;  
}
```

```
private Node min(Node x) {  
    if (x.left == null) return x;  
    else return min(x.left);  
}
```

Complexity of queries

- Search: we count the number of nodes inspected during the search
- The maximum number of nodes that are inspected is equal with the height of the tree (the longest path from root to a leaf)
 - This is the worst case for search
 - $O(h)$, h =the height of the BST

Tree walks- List in order - Example

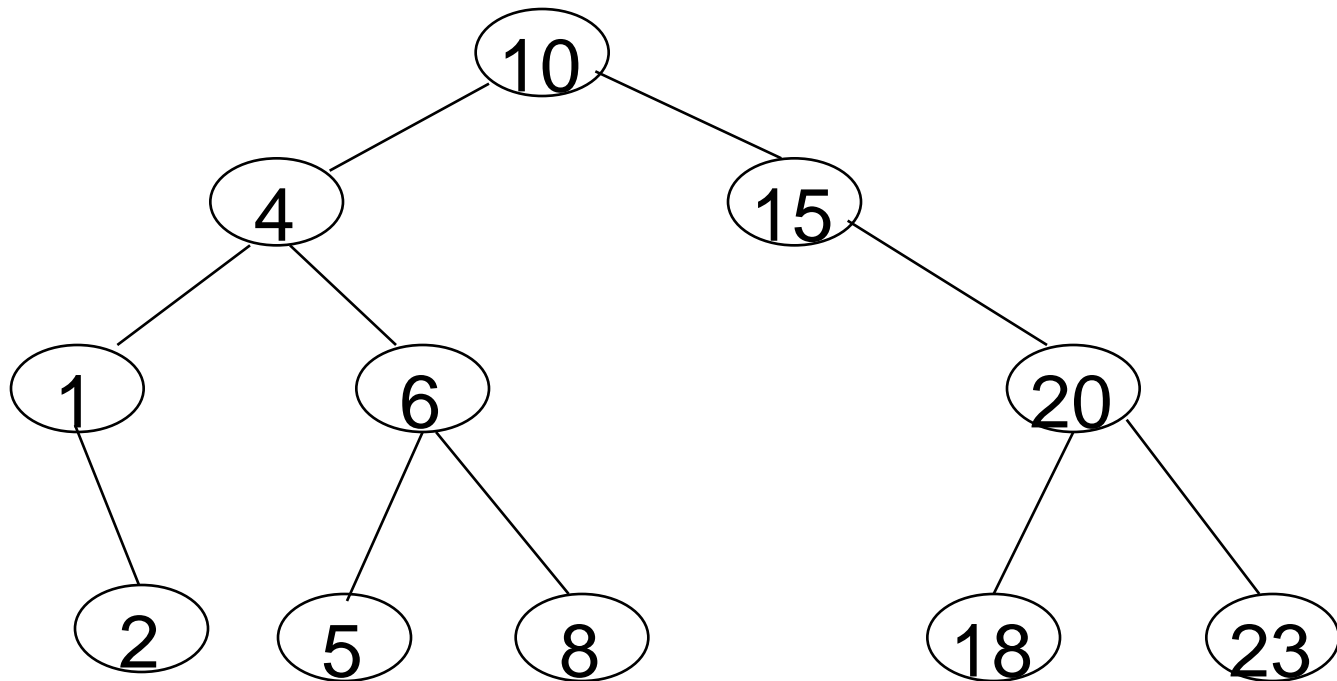


List in order: 1 2 4 5 6 8 10 15 18 20 23

Tree walks

- The binary-search-tree property allows us to print out all the keys in a binary search tree in sorted order by a simple recursive algorithm, called an ***inorder tree walk***.
- This algorithm is so named because it prints the key of the *root in between* printing the values in its left subtree and printing those in its right subtree.
- ***Postorder***: print subtrees, *after* this print root
- ***Preorder***: print *root first* and then print subtrees

Tree walks - Example



Inorder: 1 2 4 5 6 8 10 15 18 20 23

Postorder: 2 1 5 8 6 4 18 23 20 15 10

Preorder: 10 4 1 2 6 5 8 15 20 18 23

Inorder - Implementation

```
public void inorder() {  
    inorder(root);  
}
```

```
private void inorder(Node x) {  
    if (x == null) return;  
    inorder(x.left);  
    System.out.print(" "+x.key);  
    inorder(x.right);  
}
```

Complexity of tree walks

- We have a BST with n nodes
- Intuitively: count how many nodes are visited: every node is visited exactly once and a constant time operation (print) is done on it $\Rightarrow \Theta(n)$
- Formal:
- Suppose that the BST with n nodes has k nodes in the left subtree and $n-k-1$ in the right subtree
- $T(n)=c$, if $n=0$
- $T(n)=T(k)+T(n-k-1)+d$, if $n>0$
- We assume that $T(n)=(c+d)*n+c \Rightarrow$ easy proof by *induction* (verify basecase for $n=0$, assume true for all smaller than n , replace in $T(n)$ and prove that it is according to the assumed formula)

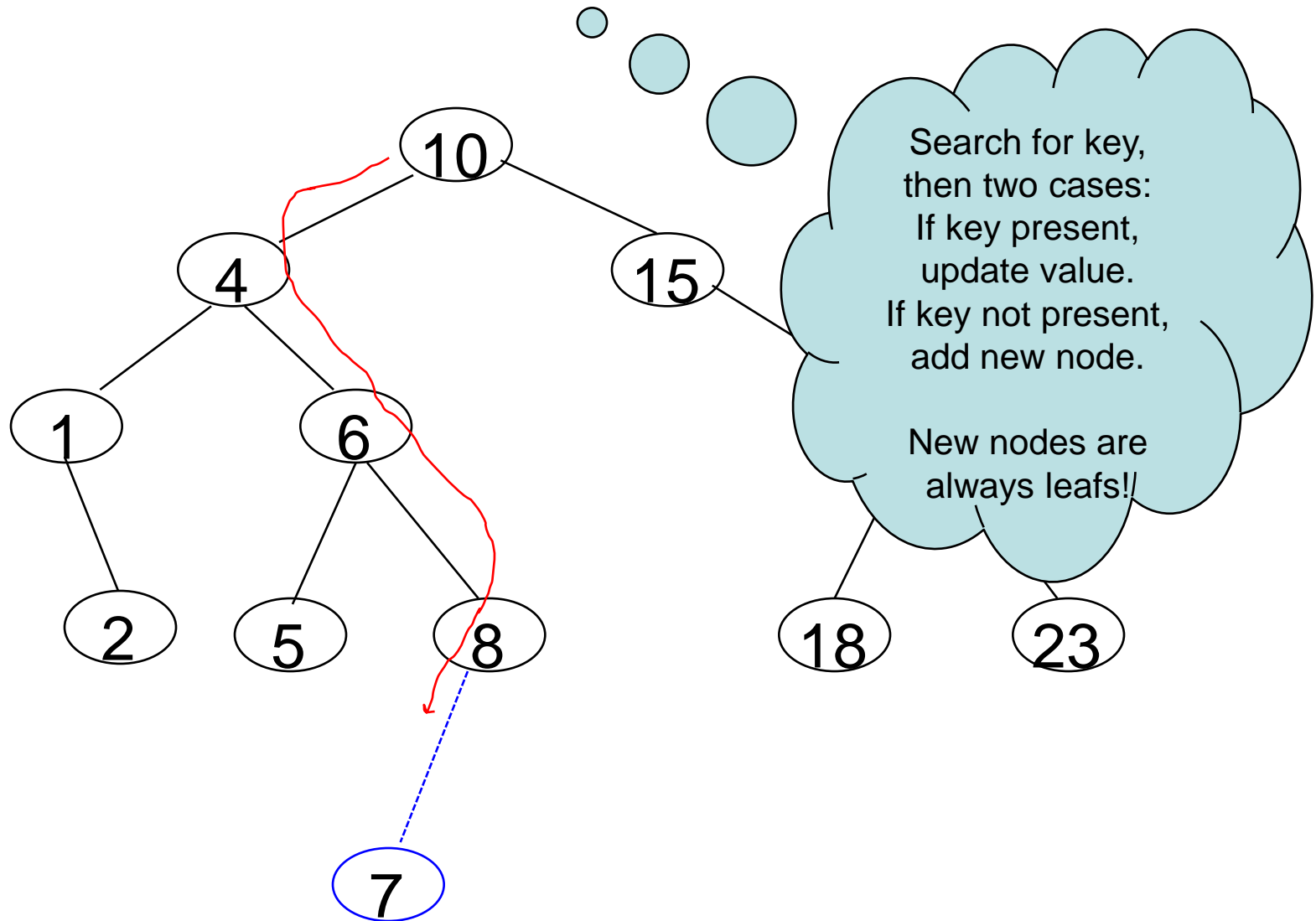
Modifying a binary search tree

- The operations of insertion and deletion cause the dynamic set represented by a binary search tree to change.
- The data structure must be modified to reflect this change, but in such a way that the binary-search-tree property continues to hold !

Operation: Insert

- `put(key, value)` creates and inserts a new node in BST, if the BST does not already contain the key
- If BST already contains the key, no new node is created but the value is updated
- Key must be non null
- After insertion, the tree must remain a binary search tree

Example – Insert key 7



Insert – recursive implementation

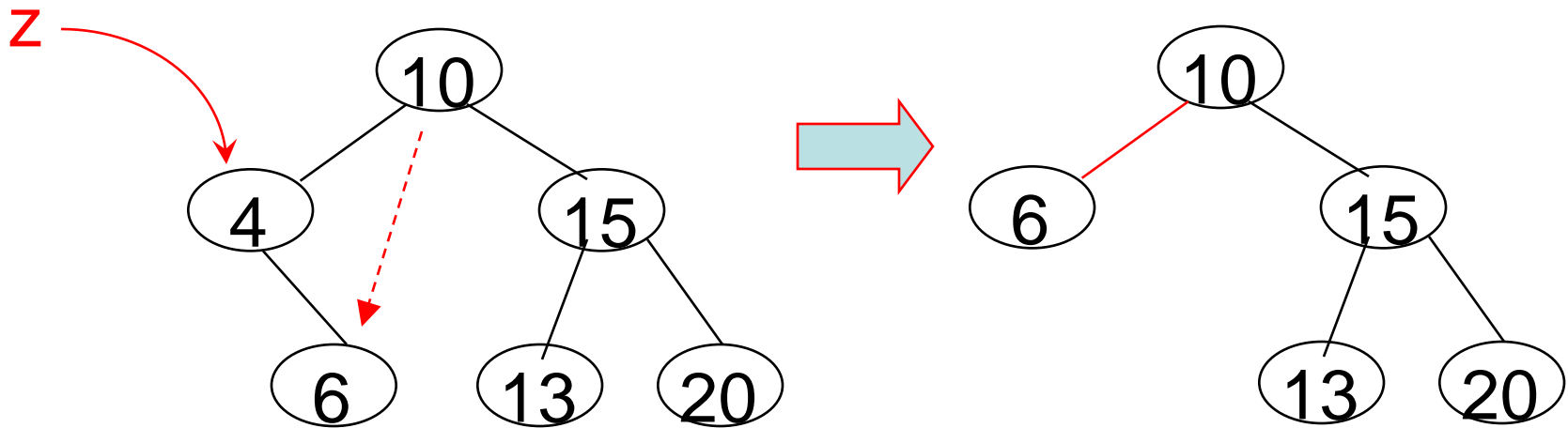
```
public void put(int key, int val) {  
    root=put(root, key, val);  
}
```

```
private Node put(Node x, int key, int val) {  
    if (x == null) return new Node(key, val);  
    if (key < x.key) x.left = put(x.left, key, val);  
    else if (key > x.key) x.right = put(x.right, key, val);  
    else x.val = val;  
    return x;  
}
```

Operation: Delete

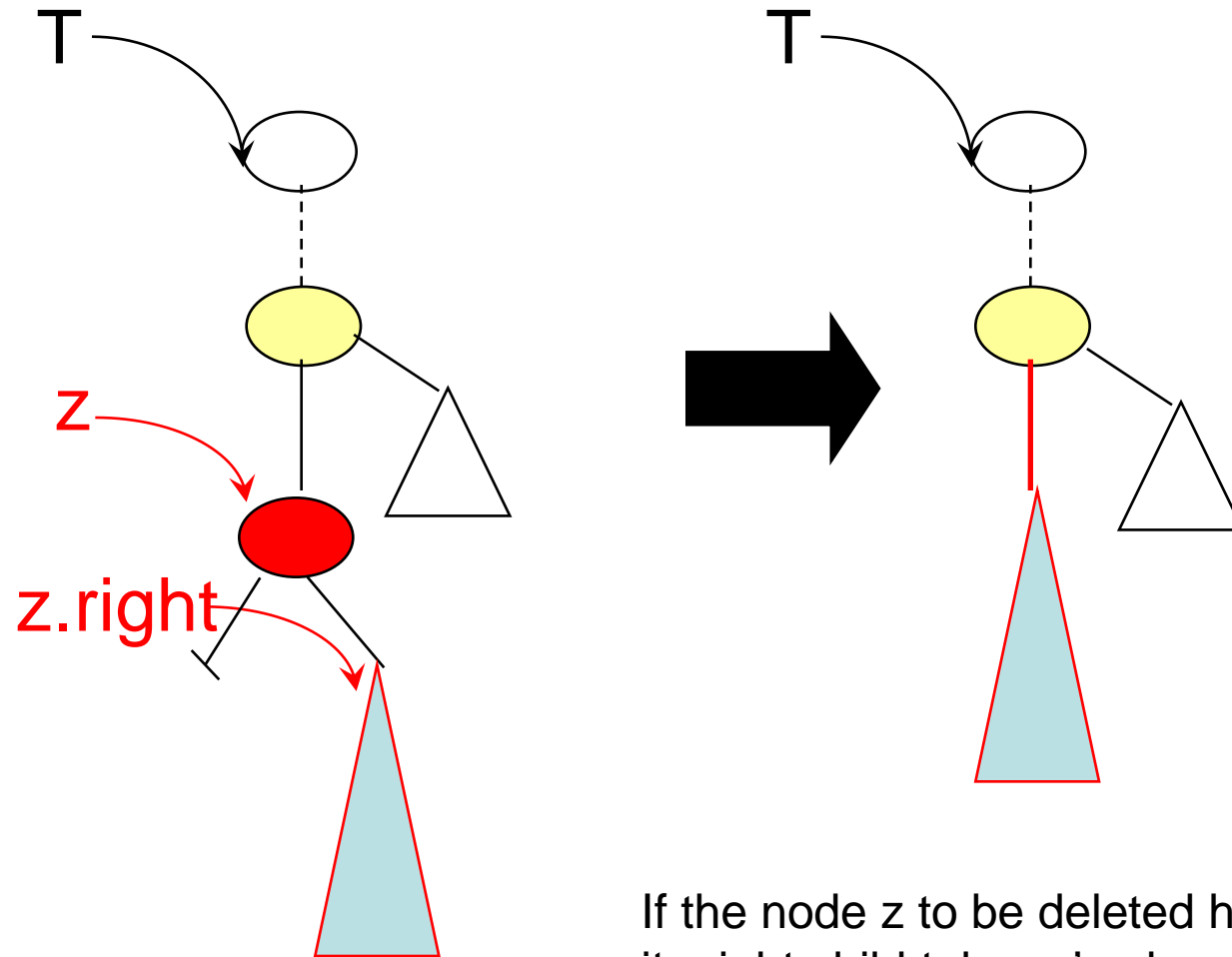
- Delete a node z from a binary search tree T
- After delete, T must remain a binary search tree
 - Important requirement for a good delete algorithm: do a minimum number of tree link reassignments!
- Cases:
 - Cases 1A+1B: node z has only 1 child \rightarrow the only child takes the place of its deleted parent z
 - Case 2A+2B: node z has 2 children. The *successor* of z will take its place.
 - In this case (node z has two children), the successor of z is the minimum value in the right subtree of z
 - In a general case, the successor of a node with no right child is among its ancestors!

Example - delete



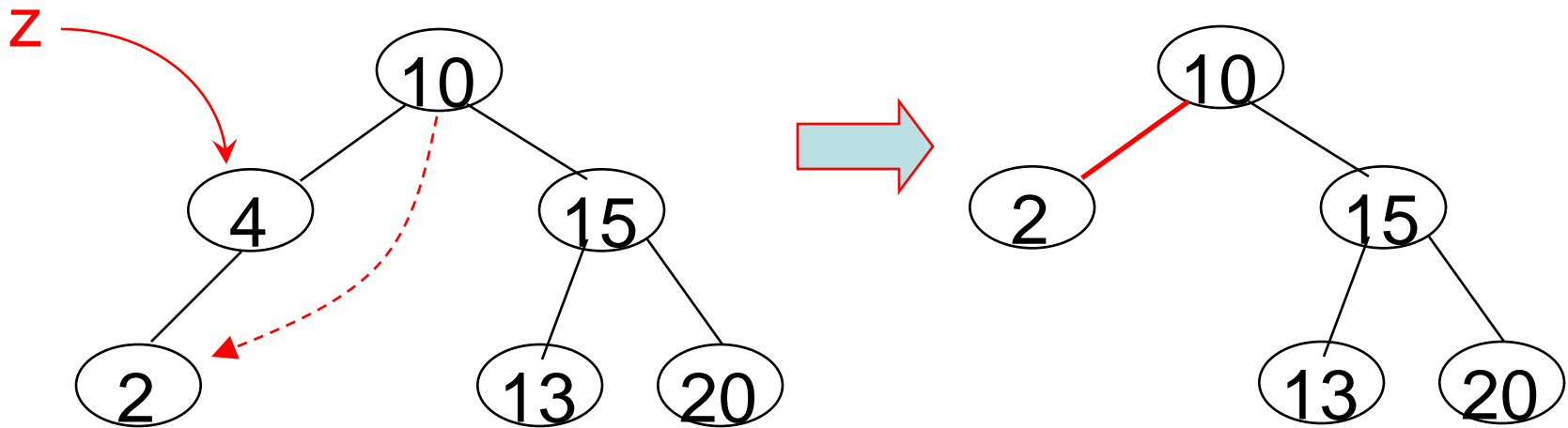
Delete z . Case 1A: z has no left child

Tree delete – case 1A



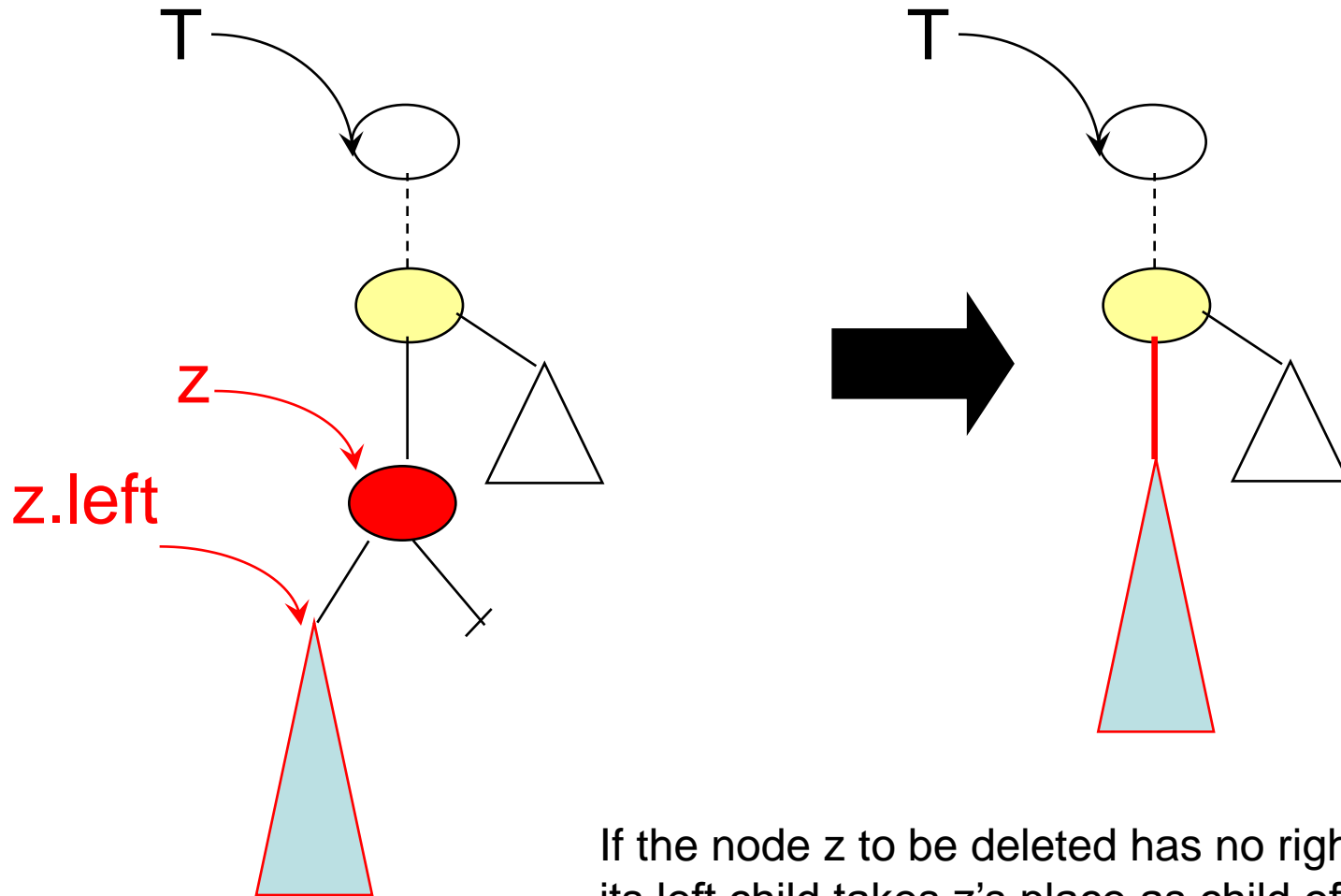
If the node z to be deleted has no left child, its right child takes z 's place as child of z 's parent

Example - delete



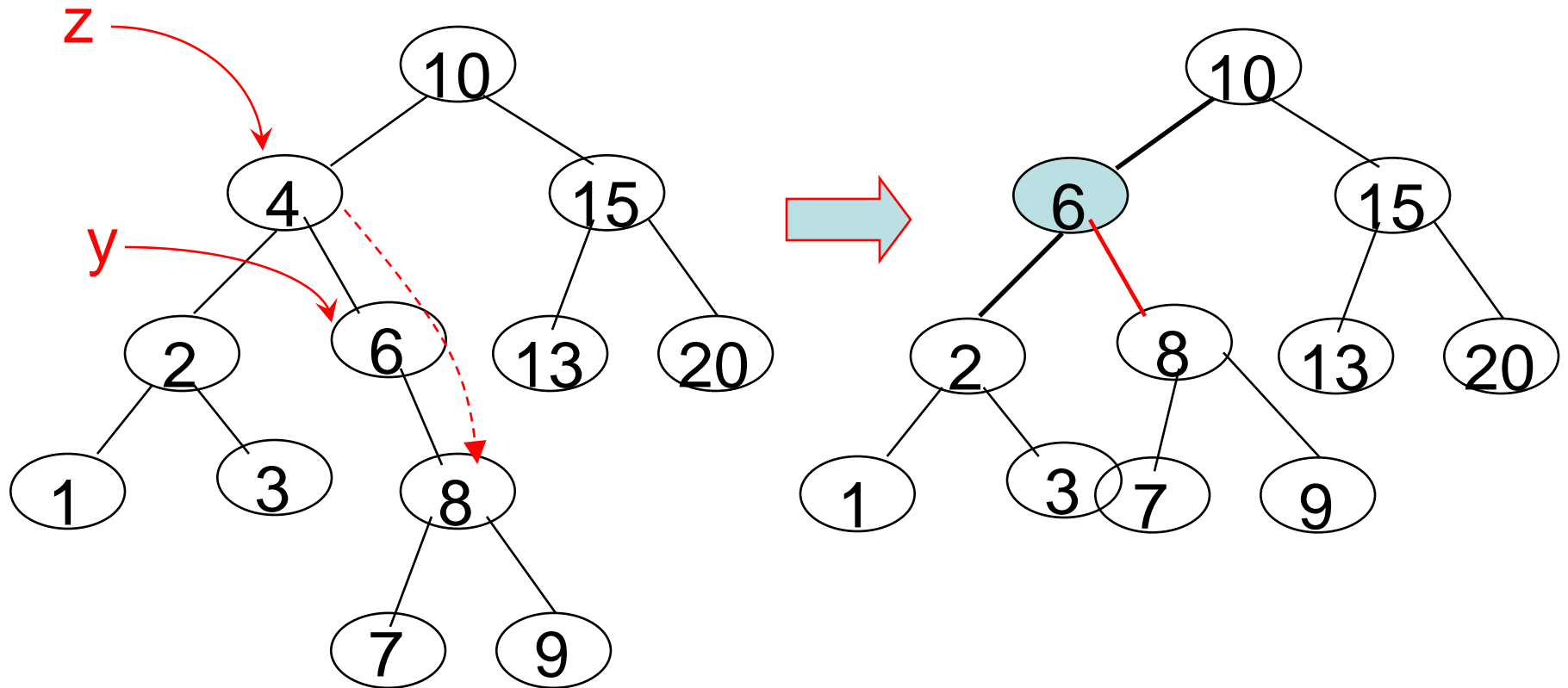
Delete z . Case 1B: z has no right child

Tree delete – case 1B



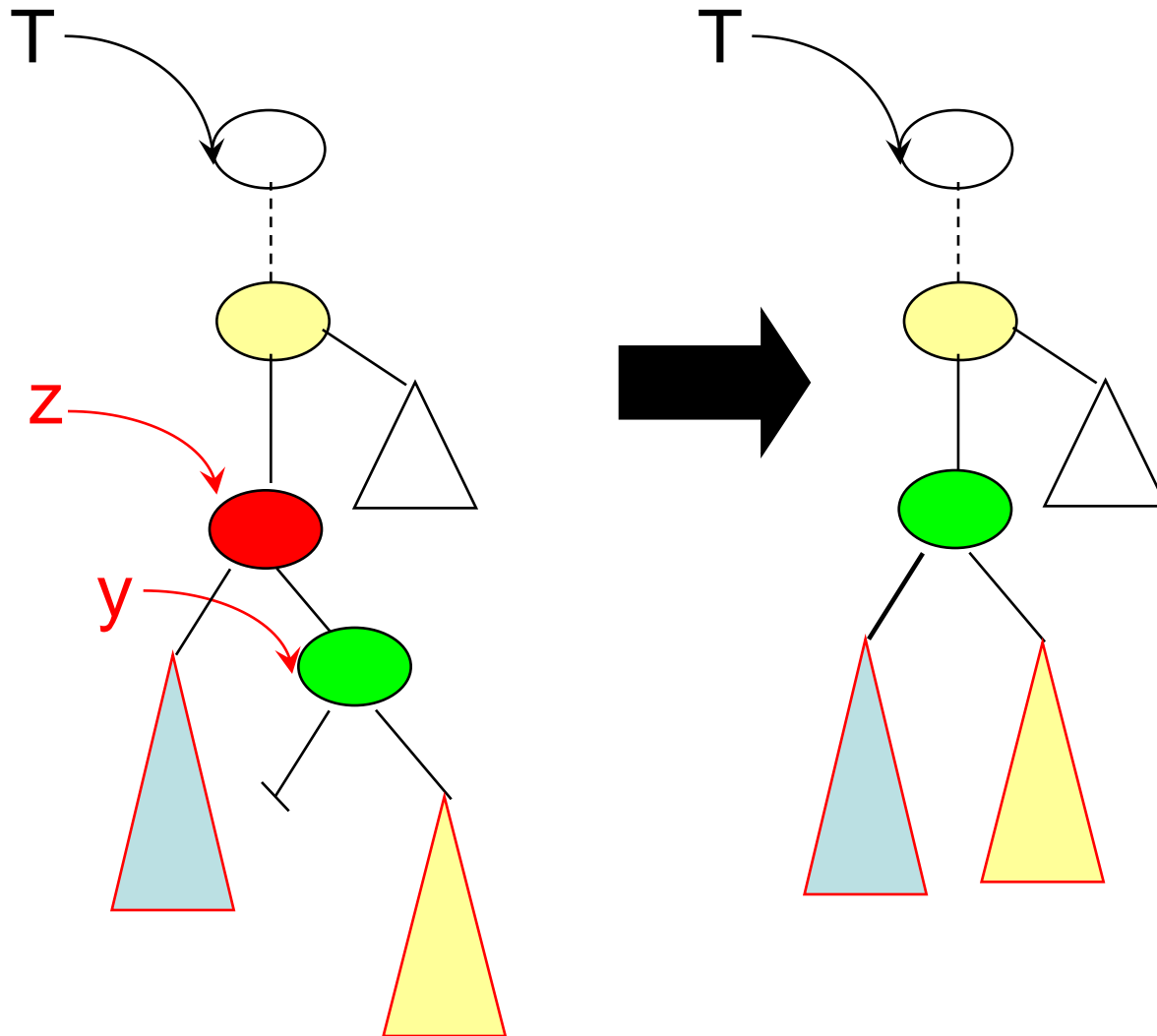
If the node z to be deleted has no right child, its left child takes z 's place as child of z 's parent

Example - delete



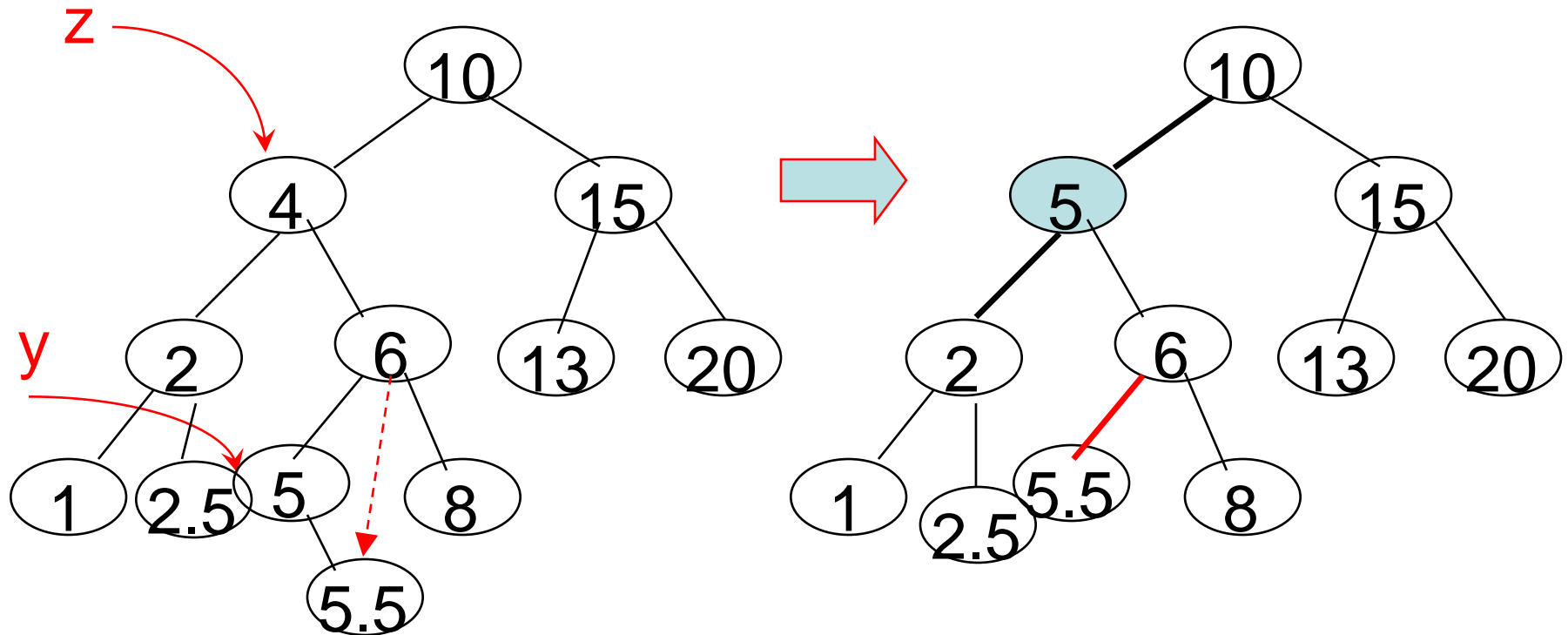
Delete z . Case 2A: z has 2 children and z 's successor, y , is the right child of z

Tree delete – case 2A



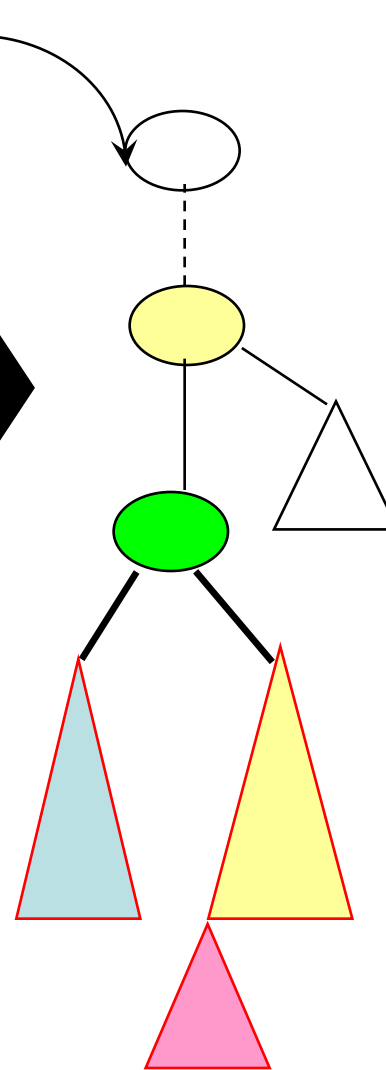
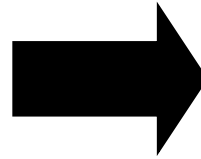
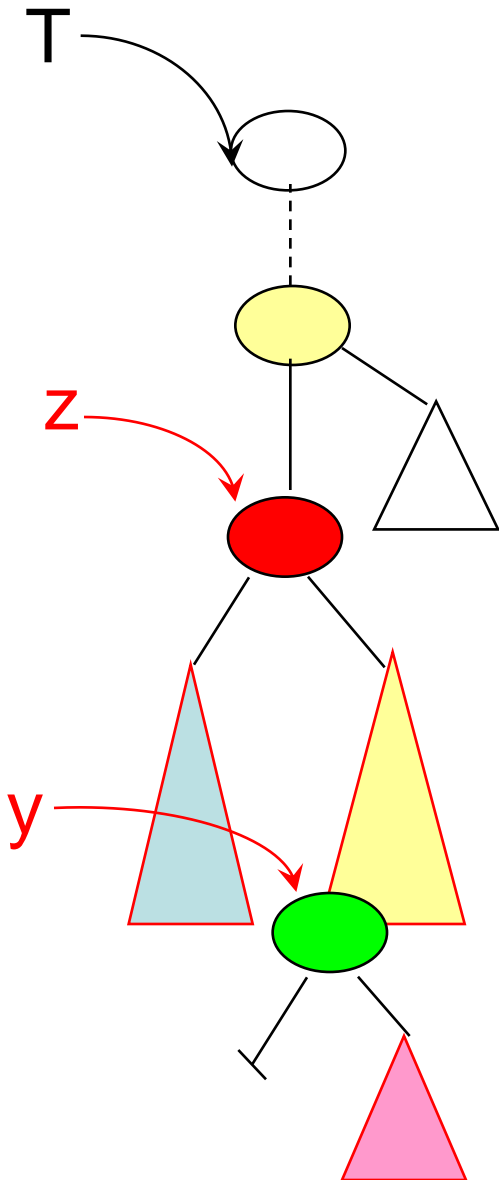
If the node z to be deleted has two children, find minimum y in right subtree of z , delete y from tree, and replace value of z by value of y

Example - delete



Delete z . Case 2B: z has 2 children and z 's successor, y , is not the right child of z

Tree delete – case 2B



If the node z to be deleted has two children, find minimum y in right subtree of z , delete y from tree, and replace value of z by value of y

Delete – recursive implementation

```
public void delete(int key) {  
    root = deleteRecursive(root, key);  
}
```

```
private Node deleteRecursive(Node z, int key) {  
    if (z == null) return null;  
    if (key < z.key) z.left = deleteRecursive(z.left, key);  
    else if (key > z.key) z.right = deleteRecursive(z.right, key);  
    else {  
        // node z contains the key to be deleted  
        if (z.right == null) return z.left; // case 1: only 1 child left  
        if (z.left == null) return z.right; // case 1: only 1 child right  
        //case 2: node z to be deleted has 2 children  
        Node y = min(z.right); // find minimum in its right subtree (successor of z)  
        z.right = deleteRecursive(z.right, y.key); //delete minimum node - we KNOW it  
        has max 1 child  
        z.key = y.key; //replace current key with minimum key  
    }  
    return z;  
}
```

BST Delete

- The previous implementation of BST Delete considered replacing the deleted node z with its successor
- Another similar solution is to replace the deleted node z with its predecessor

Exercise

- Draw the Binary Search Tree that results from following sequence of operations:
- Insert 29, 37, 1, 3, 7, 20, 89, 75, 4, 2, 6, 30, 35
- Delete 30, 3

Analysis

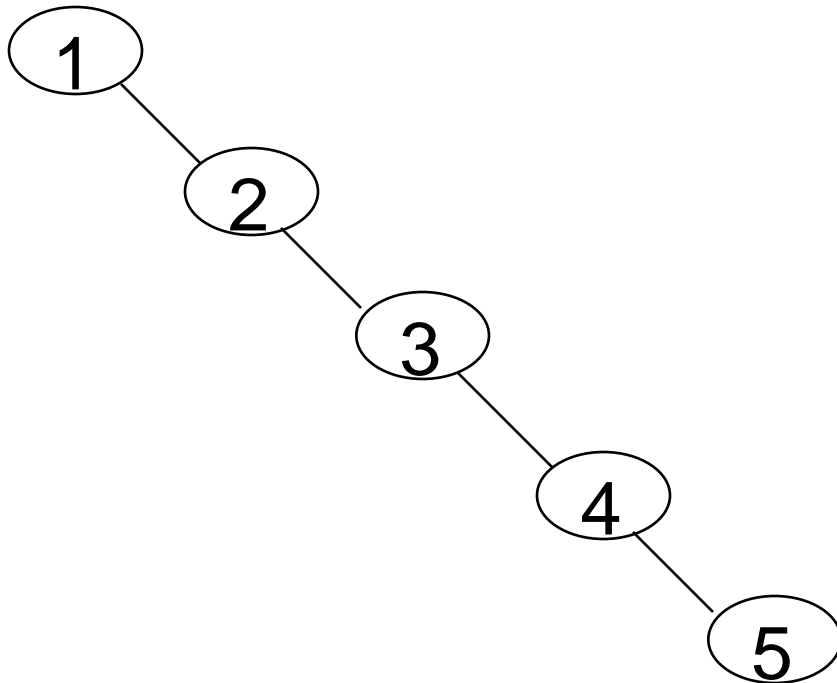
- Tree walks $\Theta(n)$ n = number of nodes in BST
- Queries
 - Search $O(h)$
 - Minimum $O(h)$
 - Maximum $O(h)$ h = height of BST. But what is the value of the height of a BST?
- Modifying
 - Insert $O(h)$
 - Delete $O(h)$

The Height of Binary Search Trees

- Each of the basic operations on a binary search tree runs in $O(h)$ time, where h is the **height** of the tree => **It is desirable that h is small**
- The shape and height of a binary search tree of n nodes depends on the order in which the keys are inserted (insert in order: 1,2,3 vs insert in order 2,1,3)
- The height of a BST with n nodes:
 - **Worst case: $O(n)$ => BST operations are also $O(n)$!!!**
 - Best case: $O(\log n)$
 - Average case $O(\log n)$

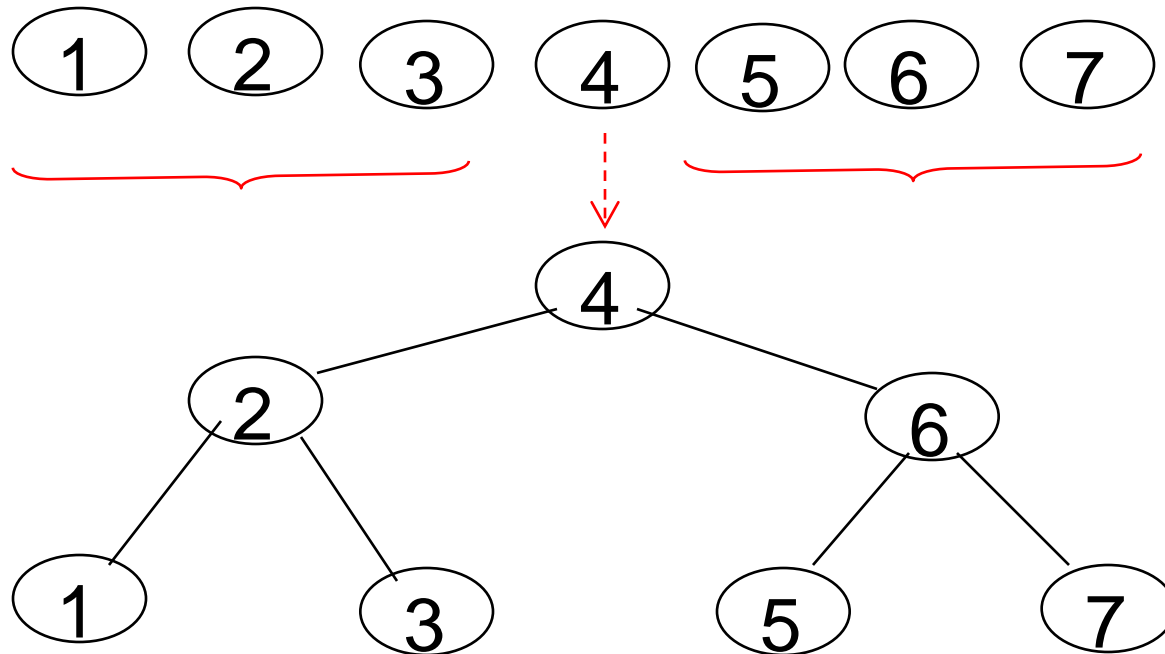
Height of a BST – worst case

- If the n keys are inserted in *strictly increasing* order, the tree will be a chain with height $n-1$.



Height of a BST – best case

- The best case corresponds to a *balanced* tree
- In this case the height is $\log n$



Height of a BST – random case

- It can be proved that: The *expected* height of a *randomly* built binary search tree on n distinct keys is $O(\lg n)$

Keeping the height of BST small

- Different techniques are used in order to keep the height of BST small – after an insertion or deletion some operations are done in order to redo the balance:
 - AVL trees (Adelson-Velskii and Landis)
 - Red-black trees (symmetric binary B-trees, 2-3 trees)

Implementing a Generic BST

- A Binary Search Tree can hold **any** Key and Value types – it should be a **generic type** (with **Key** and **Value** as **type parameters**)
- **Condition:** The Key type must be a **Comparable** !

```
public class GenericBST<K extends Comparable<K>, V> {
```

```
    private class Node {
```

```
        K key;           // sorted by Key
```

```
        V val;          // associated data
```

```
        Node left, right; // left and right subtrees
```

```
        Node(K key, V val) {
```

```
            this.key = key;
```

```
            this.val = val;
```

```
        }
```

```
    }
```

```
    private Node root;           // root of BST
```

```
    public GenericBST() {
```

```
        root = null;           // initializes empty BST
```

```
    }
```

```
// ... etc
```



```
public boolean contains(K key) {  
    return contains(root, key);  
}
```

```
private boolean contains(Node x, K key) {  
    if (x == null) return false;  
    if (key.compareTo(x.key)<0) return contains(x.left, key);  
    else if (key.compareTo(x.key)<0) return contains(x.right, key);  
    else return true;  
}
```

```
public class GenericBSTClient {  
    public static void main(String[] args) {  
        GenericBST<Integer, Integer> bst1 = new GenericBST<>();  
        GenericBST<Integer, String> bst2 = new GenericBST<>();  
        GenericBST<String, City> bst3 = new GenericBST<>();  
  
        bst1.put(5, 10);  
        bst1.put(2, 4);  
        bst1.inorder();  
        bst2.put(4, "four");  
        bst2.put(2, "two");  
        bst2.put(3, "three");  
        bst2.inorder();  
        bst3.put("Timisoara", new City("Timisoara", 230, 300));  
        bst3.put("Arad", new City("Arad", 180, 210));  
        bst3.put("Brasov", new City("Brasov", 200, 280));  
        bst3.inorder();  
    }  
}
```

Source Code

- [IntBST.java](#)
- [GenericBST.java](#), [GenericBSTClient.java](#)