knn

July 26, 2021

```
[]: # This mounts your Google Drive to the Colab VM.
     from google.colab import drive
     drive.mount('/content/drive', force_remount=True)
     # Enter the foldername in your Drive where you have saved the unzipped
     # assignment folder, e.g. 'cs231n/assignments/assignment1/'
     FOLDERNAME = None
     assert FOLDERNAME is not None, "[!] Enter the foldername."
     # Now that we've mounted your Drive, this ensures that
     # the Python interpreter of the Colab VM can load
     # python files from within it.
     import sys
     sys.path.append('/content/drive/My Drive/{}'.format(FOLDERNAME))
     # This downloads the CIFAR-10 dataset to your Drive
     # if it doesn't already exist.
     %cd drive/My\ Drive/$FOLDERNAME/cs231n/datasets/
     !bash get datasets.sh
     %cd /content/drive/My\ Drive/$FOLDERNAME
```

1 k-Nearest Neighbor (kNN) exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the assignments page on the course website.

The kNN classifier consists of two stages:

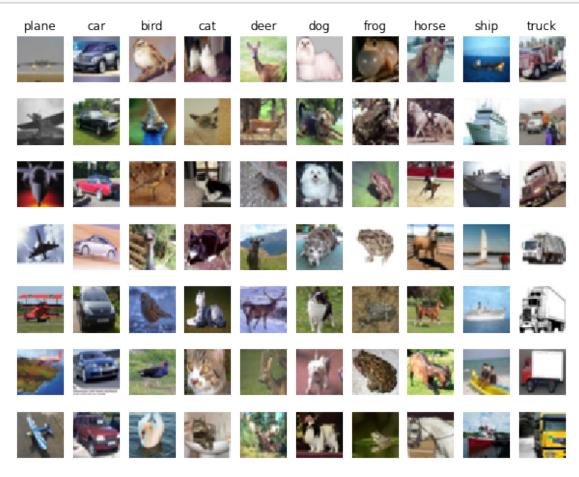
- During training, the classifier takes the training data and simply remembers it
- During testing, kNN classifies every test image by comparing to all training images and transfering the labels of the k most similar training examples
- The value of k is cross-validated

In this exercise you will implement these steps and understand the basic Image Classification pipeline, cross-validation, and gain proficiency in writing efficient, vectorized code.

```
[1]: # Run some setup code for this notebook.
     import random
     import numpy as np
     from cs231n.data_utils import load_CIFAR10
     import matplotlib.pyplot as plt
     # This is a bit of magic to make matplotlib figures appear inline in the
     \rightarrownotebook
     # rather than in a new window.
     %matplotlib inline
     plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
     plt.rcParams['image.interpolation'] = 'nearest'
     plt.rcParams['image.cmap'] = 'gray'
     # Some more magic so that the notebook will reload external python modules;
     # see http://stackoverflow.com/questions/1907993/
     \rightarrow autoreload-of-modules-in-ipython
     %load ext autoreload
     %autoreload 2
[2]: # Load the raw CIFAR-10 data.
     cifar10_dir = 'cs231n/datasets/cifar-10-batches-py'
     # Cleaning up variables to prevent loading data multiple times (which may cause,
      →memory issue)
     try:
        del X_train, y_train
        del X_test, y_test
        print('Clear previously loaded data.')
     except:
        pass
     X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)
     # As a sanity check, we print out the size of the training and test data.
     print('Training data shape: ', X_train.shape)
     print('Training labels shape: ', y_train.shape)
     print('Test data shape: ', X_test.shape)
     print('Test labels shape: ', y_test.shape)
    Training data shape: (50000, 32, 32, 3)
    Training labels shape: (50000,)
    Test data shape: (10000, 32, 32, 3)
```

Test labels shape: (10000,)

```
[3]: # Visualize some examples from the dataset.
    # We show a few examples of training images from each class.
    classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', _
     num_classes = len(classes)
    samples_per_class = 7
    for y, cls in enumerate(classes):
        idxs = np.flatnonzero(y_train == y)
        idxs = np.random.choice(idxs, samples_per_class, replace=False)
        for i, idx in enumerate(idxs):
            plt_idx = i * num_classes + y + 1
            plt.subplot(samples_per_class, num_classes, plt_idx)
            plt.imshow(X_train[idx].astype('uint8'))
            plt.axis('off')
            if i == 0:
                plt.title(cls)
    plt.show()
```



```
[4]: # Subsample the data for more efficient code execution in this exercise
    num_training = 500
    mask = list(range(num_training))
    X_train = X_train[mask]
    y_train = y_train[mask]

    num_test = 50
    mask = list(range(num_test))
    X_test = X_test[mask]
    y_test = y_test[mask]

# Reshape the image data into rows
    X_train = np.reshape(X_train, (X_train.shape[0], -1))
    X_test = np.reshape(X_test, (X_test.shape[0], -1))
    print(X_train.shape, X_test.shape)
```

(500, 3072) (50, 3072)

```
[5]: from cs231n.classifiers import KNearestNeighbor

# Create a kNN classifier instance.
# Remember that training a kNN classifier is a noop:
# the Classifier simply remembers the data and does no further processing classifier = KNearestNeighbor()
classifier.train(X_train, y_train)
```

We would now like to classify the test data with the kNN classifier. Recall that we can break down this process into two steps:

- 1. First we must compute the distances between all test examples and all train examples.
- 2. Given these distances, for each test example we find the k nearest examples and have them vote for the label

Lets begin with computing the distance matrix between all training and test examples. For example, if there are **Ntr** training examples and **Nte** test examples, this stage should result in a **Nte** x **Ntr** matrix where each element (i,j) is the distance between the i-th test and j-th train example.

Note: For the three distance computations that we require you to implement in this notebook, you may not use the np.linalg.norm() function that numpy provides.

First, open cs231n/classifiers/k_nearest_neighbor.py and implement the function compute_distances_two_loops that uses a (very inefficient) double loop over all pairs of (test, train) examples and computes the distance matrix one element at a time.

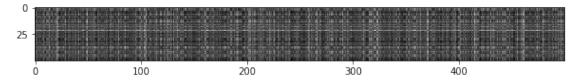
```
[6]: # Open cs231n/classifiers/k_nearest_neighbor.py and implement
    # compute_distances_two_loops.

# Test your implementation:
dists = classifier.compute_distances_two_loops(X_test)
```

```
print(dists.shape)
```

(50, 500)

```
[7]: # We can visualize the distance matrix: each row is a single test example and
    # its distances to training examples
plt.imshow(dists, interpolation='none')
plt.show()
```



Inline Question 1

Notice the structured patterns in the distance matrix, where some rows or columns are visible brighter. (Note that with the default color scheme black indicates low distances while white indicates high distances.)

- What in the data is the cause behind the distinctly bright rows?
- What causes the columns?

YourAnswer: fill this in.

```
[8]: # Now implement the function predict_labels and run the code below:
# We use k = 1 (which is Nearest Neighbor).
y_test_pred = classifier.predict_labels(dists, k=1)

# Compute and print the fraction of correctly predicted examples
num_correct = np.sum(y_test_pred == y_test)
accuracy = float(num_correct) / num_test
print('Got %d / %d correct => accuracy: %f' % (num_correct, num_test, accuracy))
```

Got 13 / 50 correct => accuracy: 0.260000

You should expect to see approximately 27% accuracy. Now lets try out a larger k, say k = 5:

```
[9]: y_test_pred = classifier.predict_labels(dists, k=5)
num_correct = np.sum(y_test_pred == y_test)
accuracy = float(num_correct) / num_test
print('Got %d / %d correct => accuracy: %f' % (num_correct, num_test, accuracy))
```

Got 7 / 50 correct => accuracy: 0.140000

You should expect to see a slightly better performance than with k = 1.

Inline Question 2

We can also use other distance metrics such as L1 distance. For pixel values $p_{ij}^{(k)}$ at location (i, j) of some image I_k ,

the mean μ across all pixels over all images is

$$\mu = \frac{1}{nhw} \sum_{k=1}^{n} \sum_{i=1}^{h} \sum_{j=1}^{w} p_{ij}^{(k)}$$

And the pixel-wise mean μ_{ij} across all images is

$$\mu_{ij} = \frac{1}{n} \sum_{k=1}^{n} p_{ij}^{(k)}.$$

The general standard deviation σ and pixel-wise standard deviation σ_{ij} is defined similarly.

Which of the following preprocessing steps will not change the performance of a Nearest Neighbor classifier that uses L1 distance? Select all that apply. 1. Subtracting the mean μ ($\tilde{p}_{ij}^{(k)} = p_{ij}^{(k)} - \mu$.) 2. Subtracting the per pixel mean μ_{ij} ($\tilde{p}_{ij}^{(k)} = p_{ij}^{(k)} - \mu_{ij}$.) 3. Subtracting the mean μ and dividing by the standard deviation σ . 4. Subtracting the pixel-wise mean μ_{ij} and dividing by the pixel-wise standard deviation σ_{ij} . 5. Rotating the coordinate axes of the data.

Your Answer:

Your Explanation:

```
[10]: # Now lets speed up distance matrix computation by using partial vectorization
      # with one loop. Implement the function compute_distances_one_loop and run the
      # code below:
      dists_one = classifier.compute_distances_one_loop(X_test)
      # To ensure that our vectorized implementation is correct, we make sure that it
      # agrees with the naive implementation. There are many ways to decide whether
      # two matrices are similar; one of the simplest is the Frobenius norm. In case
      # you haven't seen it before, the Frobenius norm of two matrices is the square
      # root of the squared sum of differences of all elements; in other words, \Box
      \rightarrowreshape
      # the matrices into vectors and compute the Euclidean distance between them.
      difference = np.linalg.norm(dists - dists_one, ord='fro')
      print('One loop difference was: %f' % (difference, ))
      if difference < 0.001:</pre>
          print('Good! The distance matrices are the same')
      else:
          print('Uh-oh! The distance matrices are different')
```

```
One loop difference was: 0.000000
Good! The distance matrices are the same
```

```
[11]: # Now implement the fully vectorized version inside compute_distances_no_loops # and run the code dists_two = classifier.compute_distances_no_loops(X_test)
```

```
# check that the distance matrix agrees with the one we computed before:
difference = np.linalg.norm(dists - dists_two, ord='fro')
print('No loop difference was: %f' % (difference, ))
if difference < 0.001:
    print('Good! The distance matrices are the same')
else:
    print('Uh-oh! The distance matrices are different')</pre>
```

No loop difference was: 0.000000 Good! The distance matrices are the same

```
[12]: # Let's compare how fast the implementations are
      def time_function(f, *args):
          Call a function f with args and return the time (in seconds) that it took,
       \rightarrow to execute.
          11 11 11
          import time
          tic = time.time()
          f(*args)
          toc = time.time()
          return toc - tic
      two_loop_time = time_function(classifier.compute_distances_two_loops, X_test)
      print('Two loop version took %f seconds' % two_loop_time)
      one_loop_time = time function(classifier.compute distances_one_loop, X test)
      print('One loop version took %f seconds' % one_loop_time)
      no_loop_time = time_function(classifier.compute_distances_no_loops, X_test)
      print('No loop version took %f seconds' % no_loop_time)
      # You should see significantly faster performance with the fully vectorized
      \rightarrow implementation!
      # NOTE: depending on what machine you're using,
      # you might not see a speedup when you go from two loops to one loop,
      # and might even see a slow-down.
```

Two loop version took 3.284049 seconds One loop version took 3.223999 seconds No loop version took 3.263949 seconds

1.0.1 Cross-validation

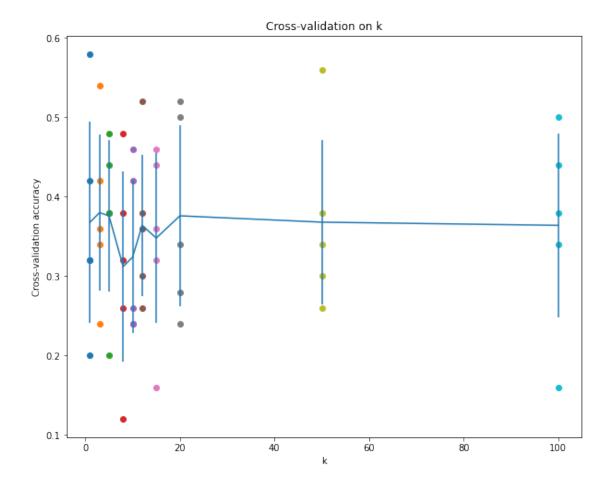
We have implemented the k-Nearest Neighbor classifier but we set the value k=5 arbitrarily. We will now determine the best value of this hyperparameter with cross-validation.

```
[13]: num_folds = 5
     k_{choices} = [1, 3, 5, 8, 10, 12, 15, 20, 50, 100]
     X_train_folds = []
     y_train_folds = []
     # Split up the training data into folds. After splitting, X_train_folds and
                                                                        #
     # y train folds should each be lists of length num folds, where
     # y_train_folds[i] is the label vector for the points in X_train_folds[i].
     # Hint: Look up the numpy array_split function.
     # *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
     X_train_folds = np.array_split(X_train, num_folds)
     y_train_folds = np.array_split(y_train, num_folds)
     # *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
     # A dictionary holding the accuracies for different values of k that we find
     # when running cross-validation. After running cross-validation,
     \# k\_to\_accuracies[k] should be a list of length num_folds giving the different
     # accuracy values that we found when using that value of k.
     k to accuracies = {}
     # TODO:
     \# Perform k-fold cross validation to find the best value of k. For each
     # possible value of k, run the k-nearest-neighbor algorithm num_folds times,
     # where in each case you use all but one of the folds as training data and the #
     # last fold as a validation set. Store the accuracies for all fold and all
     # values of k in the k_to_accuracies dictionary.
     # *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
     cl = KNearestNeighbor()
     for k in k_choices:
        k to accuracies[k] = []
        for i in range(num_folds):
           cl.train(np.concatenate(X_train_folds[:i]+X_train_folds[i+1:]),
                   np.concatenate(y_train_folds[:i]+y_train_folds[i+1:]))
           d = cl.compute_distances_two_loops(X_train_folds[i])
           y_foldi_pred = classifier.predict_labels(d, k=k)
           k_to_accuracies[k].append(float(np.sum(y_foldi_pred ==_
      →y_train_folds[i])) / num_test)
```

```
# *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
 # Print out the computed accuracies
for k in sorted(k_to_accuracies):
    for accuracy in k_to_accuracies[k]:
         print('k = %d, accuracy = %f' % (k, accuracy))
k = 1, accuracy = 0.200000
k = 1, accuracy = 0.320000
k = 1, accuracy = 0.320000
k = 1, accuracy = 0.420000
k = 1, accuracy = 0.580000
k = 3, accuracy = 0.240000
k = 3, accuracy = 0.340000
k = 3, accuracy = 0.420000
k = 3, accuracy = 0.360000
k = 3, accuracy = 0.540000
k = 5, accuracy = 0.200000
k = 5, accuracy = 0.380000
k = 5, accuracy = 0.380000
k = 5, accuracy = 0.440000
k = 5, accuracy = 0.480000
k = 8, accuracy = 0.120000
k = 8, accuracy = 0.320000
k = 8, accuracy = 0.260000
k = 8, accuracy = 0.380000
k = 8, accuracy = 0.480000
k = 10, accuracy = 0.240000
k = 10, accuracy = 0.260000
k = 10, accuracy = 0.240000
k = 10, accuracy = 0.420000
k = 10, accuracy = 0.460000
k = 12, accuracy = 0.260000
k = 12, accuracy = 0.360000
k = 12, accuracy = 0.300000
k = 12, accuracy = 0.380000
k = 12, accuracy = 0.520000
k = 15, accuracy = 0.160000
k = 15, accuracy = 0.320000
k = 15, accuracy = 0.360000
k = 15, accuracy = 0.440000
k = 15, accuracy = 0.460000
k = 20, accuracy = 0.240000
k = 20, accuracy = 0.340000
k = 20, accuracy = 0.280000
```

k = 20, accuracy = 0.500000

```
k = 20, accuracy = 0.520000
     k = 50, accuracy = 0.260000
     k = 50, accuracy = 0.300000
     k = 50, accuracy = 0.340000
     k = 50, accuracy = 0.380000
     k = 50, accuracy = 0.560000
     k = 100, accuracy = 0.160000
     k = 100, accuracy = 0.380000
     k = 100, accuracy = 0.440000
     k = 100, accuracy = 0.340000
     k = 100, accuracy = 0.500000
[14]: # plot the raw observations
      for k in k_choices:
          accuracies = k_to_accuracies[k]
          plt.scatter([k] * len(accuracies), accuracies)
      # plot the trend line with error bars that correspond to standard deviation
      accuracies_mean = np.array([np.mean(v) for k,v in sorted(k_to_accuracies.
      \rightarrowitems())])
      accuracies_std = np.array([np.std(v) for k,v in sorted(k_to_accuracies.
      →items())])
      plt.errorbar(k_choices, accuracies_mean, yerr=accuracies_std)
      plt.title('Cross-validation on k')
      plt.xlabel('k')
      plt.ylabel('Cross-validation accuracy')
      plt.show()
```



```
[15]: # Based on the cross-validation results above, choose the best value for k,
    # retrain the classifier using all the training data, and test it on the test
    # data. You should be able to get above 28% accuracy on the test data.
best_k = 1

classifier = KNearestNeighbor()
classifier.train(X_train, y_train)
y_test_pred = classifier.predict(X_test, k=best_k)

# Compute and display the accuracy
num_correct = np.sum(y_test_pred == y_test)
accuracy = float(num_correct) / num_test
print('Got %d / %d correct => accuracy: %f' % (num_correct, num_test, accuracy))
```

Got 13 / 50 correct => accuracy: 0.260000

Inline Question 3

Which of the following statements about k-Nearest Neighbor (k-NN) are true in a classification setting, and for all k? Select all that apply. 1. The decision boundary of the k-NN classifier is

linear. 2. The training error of a 1-NN will always be lower than or equal to that of 5-NN. 3. The test error of a 1-NN will always be lower than that of a 5-NN. 4. The time needed to classify a test example with the k-NN classifier grows with the size of the training set. 5. None of the above.

Your Answer:

Your Explanation:

svm

July 26, 2021

```
[]: # This mounts your Google Drive to the Colab VM.
     from google.colab import drive
     drive.mount('/content/drive', force_remount=True)
     # Enter the foldername in your Drive where you have saved the unzipped
     # assignment folder, e.g. 'cs231n/assignments/assignment1/'
     FOLDERNAME = None
     assert FOLDERNAME is not None, "[!] Enter the foldername."
     # Now that we've mounted your Drive, this ensures that
     # the Python interpreter of the Colab VM can load
     # python files from within it.
     import sys
     sys.path.append('/content/drive/My Drive/{}'.format(FOLDERNAME))
     # This downloads the CIFAR-10 dataset to your Drive
     # if it doesn't already exist.
     %cd drive/My\ Drive/$FOLDERNAME/cs231n/datasets/
     !bash get_datasets.sh
     %cd /content/drive/My\ Drive/$FOLDERNAME
```

1 Multiclass Support Vector Machine exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the assignments page on the course website.

In this exercise you will:

- implement a fully-vectorized loss function for the SVM
- implement the fully-vectorized expression for its analytic gradient
- check your implementation using numerical gradient
- use a validation set to tune the learning rate and regularization strength
- optimize the loss function with SGD
- visualize the final learned weights

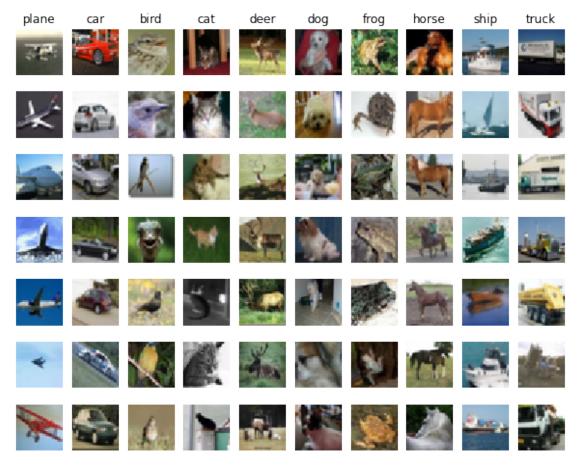
```
[1]: # Run some setup code for this notebook.
import random
```

1.1 CIFAR-10 Data Loading and Preprocessing

[3]: # Visualize some examples from the dataset.

We show a few examples of training images from each class.

```
[2]: # Load the raw CIFAR-10 data.
     cifar10 dir = 'cs231n/datasets/cifar-10-batches-py'
     # Cleaning up variables to prevent loading data multiple times (which may cause_
     →memory issue)
     trv:
       del X_train, y_train
       del X_test, y_test
       print('Clear previously loaded data.')
     except:
       pass
     X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)
     # As a sanity check, we print out the size of the training and test data.
     print('Training data shape: ', X_train.shape)
     print('Training labels shape: ', y_train.shape)
     print('Test data shape: ', X_test.shape)
     print('Test labels shape: ', y_test.shape)
    Training data shape: (50000, 32, 32, 3)
    Training labels shape: (50000,)
    Test data shape: (10000, 32, 32, 3)
    Test labels shape: (10000,)
```



[4]: # Split the data into train, val, and test sets. In addition we will # create a small development set as a subset of the training data; # we can use this for development so our code runs faster.

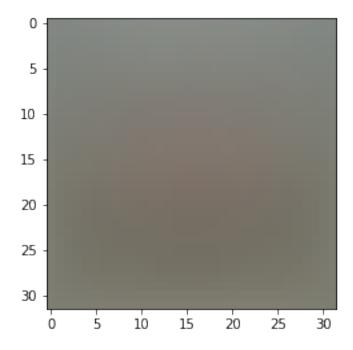
```
num_training = 49000
     num_validation = 1000
     num_test = 1000
     num_dev = 500
     # Our validation set will be num_validation points from the original
     # training set.
     mask = range(num_training, num_training + num_validation)
     X_val = X_train[mask]
     y_val = y_train[mask]
     # Our training set will be the first num_train points from the original
     # training set.
     mask = range(num_training)
     X_train = X_train[mask]
     y_train = y_train[mask]
     # We will also make a development set, which is a small subset of
     # the training set.
     mask = np.random.choice(num_training, num_dev, replace=False)
     X_dev = X_train[mask]
     y_dev = y_train[mask]
     # We use the first num test points of the original test set as our
     # test set.
     mask = range(num test)
     X_{\text{test}} = X_{\text{test}}[mask]
     y_test = y_test[mask]
     print('Train data shape: ', X_train.shape)
     print('Train labels shape: ', y_train.shape)
     print('Validation data shape: ', X_val.shape)
     print('Validation labels shape: ', y_val.shape)
     print('Test data shape: ', X_test.shape)
     print('Test labels shape: ', y_test.shape)
    Train data shape: (49000, 32, 32, 3)
    Train labels shape: (49000,)
    Validation data shape: (1000, 32, 32, 3)
    Validation labels shape: (1000,)
    Test data shape: (1000, 32, 32, 3)
    Test labels shape: (1000,)
[5]: # Preprocessing: reshape the image data into rows
     X_train = np.reshape(X_train, (X_train.shape[0], -1))
     X_val = np.reshape(X_val, (X_val.shape[0], -1))
     X_test = np.reshape(X_test, (X_test.shape[0], -1))
```

```
X_dev = np.reshape(X_dev, (X_dev.shape[0], -1))
     # As a sanity check, print out the shapes of the data
     print('Training data shape: ', X_train.shape)
     print('Validation data shape: ', X_val.shape)
     print('Test data shape: ', X_test.shape)
     print('dev data shape: ', X_dev.shape)
    Training data shape: (49000, 3072)
    Validation data shape: (1000, 3072)
    Test data shape: (1000, 3072)
    dev data shape: (500, 3072)
[6]: # Preprocessing: subtract the mean image
     # first: compute the image mean based on the training data
     mean image = np.mean(X train, axis=0)
     print(mean_image[:10]) # print a few of the elements
     plt.figure(figsize=(4,4))
     plt.imshow(mean_image.reshape((32,32,3)).astype('uint8')) # visualize the mean_i
      \rightarrow image
     plt.show()
     # second: subtract the mean image from train and test data
     X_train -= mean_image
     X_val -= mean_image
     X_test -= mean_image
     X_dev -= mean_image
     # third: append the bias dimension of ones (i.e. bias trick) so that our SVM
     \# only has to worry about optimizing a single weight matrix W.
     X_train = np.hstack([X_train, np.ones((X_train.shape[0], 1))])
     X_val = np.hstack([X_val, np.ones((X_val.shape[0], 1))])
     X_test = np.hstack([X_test, np.ones((X_test.shape[0], 1))])
```

[130.64189796 135.98173469 132.47391837 130.05569388 135.34804082 131.75402041 130.96055102 136.14328571 132.47636735 131.48467347]

X_dev = np.hstack([X_dev, np.ones((X_dev.shape[0], 1))])

print(X_train.shape, X_val.shape, X_test.shape, X_dev.shape)



(49000, 3073) (1000, 3073) (1000, 3073) (500, 3073)

1.2 SVM Classifier

Your code for this section will all be written inside cs231n/classifiers/linear_svm.py.

As you can see, we have prefilled the function svm_loss_naive which uses for loops to evaluate the multiclass SVM loss function.

```
[7]: # Evaluate the naive implementation of the loss we provided for you:
    from cs231n.classifiers.linear_svm import svm_loss_naive
    import time

# generate a random SVM weight matrix of small numbers
W = np.random.randn(3073, 10) * 0.0001

loss, grad = svm_loss_naive(W, X_dev, y_dev, 0.000005)
    print('loss: %f' % (loss, ))
```

loss: 9.512100

The grad returned from the function above is right now all zero. Derive and implement the gradient for the SVM cost function and implement it inline inside the function svm_loss_naive. You will find it helpful to interleave your new code inside the existing function.

To check that you have correctly implemented the gradient correctly, you can numerically estimate the gradient of the loss function and compare the numeric estimate to the gradient that you computed. We have provided code that does this for you:

```
[8]: # Once you've implemented the gradient, recompute it with the code below
     # and gradient check it with the function we provided for you
     # Compute the loss and its gradient at W.
     loss, grad = svm_loss_naive(W, X_dev, y_dev, 0.0)
     # Numerically compute the gradient along several randomly chosen dimensions, and
     \# compare them with your analytically computed gradient. The numbers should
      \rightarrow match
     # almost exactly along all dimensions.
     from cs231n.gradient_check import grad_check_sparse
     f = lambda w: svm_loss_naive(w, X_dev, y_dev, 0.0)[0]
     grad_numerical = grad_check_sparse(f, W, grad)
     # do the gradient check once again with regularization turned on
     # you didn't forget the regularization gradient did you?
     loss, grad = svm loss naive(W, X dev, y dev, 5e1)
     f = lambda w: svm_loss_naive(w, X_dev, y_dev, 5e1)[0]
     grad_numerical = grad_check_sparse(f, W, grad)
```

```
numerical: 9.046056 analytic: 9.046056, relative error: 4.573413e-12
numerical: 4.286889 analytic: 4.286889, relative error: 1.187932e-10
numerical: 16.314747 analytic: 16.314747, relative error: 2.083743e-11
numerical: 16.710556 analytic: 16.710556, relative error: 2.595840e-11
numerical: 14.277324 analytic: 14.277324, relative error: 3.258652e-11
numerical: 6.929901 analytic: 6.929901, relative error: 2.746260e-11
numerical: 21.962377 analytic: 21.962377, relative error: 2.599469e-11
numerical: 5.910411 analytic: 5.910411, relative error: 1.276025e-11
numerical: 12.003329 analytic: 12.003329, relative error: 6.392667e-12
numerical: 30.246592 analytic: 30.246592, relative error: 3.786973e-12
numerical: 36.029453 analytic: 36.029453, relative error: 7.085222e-12
numerical: -3.194105 analytic: -3.194105, relative error: 4.858537e-11
numerical: 8.365455 analytic: 8.365455, relative error: 6.635006e-11
numerical: 2.476916 analytic: 2.476916, relative error: 1.493147e-10
numerical: 13.983320 analytic: 13.983320, relative error: 2.165929e-13
numerical: -6.049671 analytic: -6.049671, relative error: 4.257241e-11
numerical: 40.306341 analytic: 40.306341, relative error: 8.980429e-12
numerical: 28.994138 analytic: 28.994138, relative error: 7.943207e-12
numerical: -2.332442 analytic: -2.332442, relative error: 1.509986e-10
numerical: -5.381436 analytic: -5.381436, relative error: 2.172824e-11
```

Inline Question 1

It is possible that once in a while a dimension in the gradcheck will not match exactly. What could such a discrepancy be caused by? Is it a reason for concern? What is a simple example in one dimension where a gradient check could fail? How would change the margin affect of the frequency of this happening? Hint: the SVM loss function is not strictly speaking differentiable

YourAnswer: fill this in.

Naive loss: 9.512100e+00 computed in 0.110998s Vectorized loss: 9.512100e+00 computed in 0.006002s difference: 0.000000

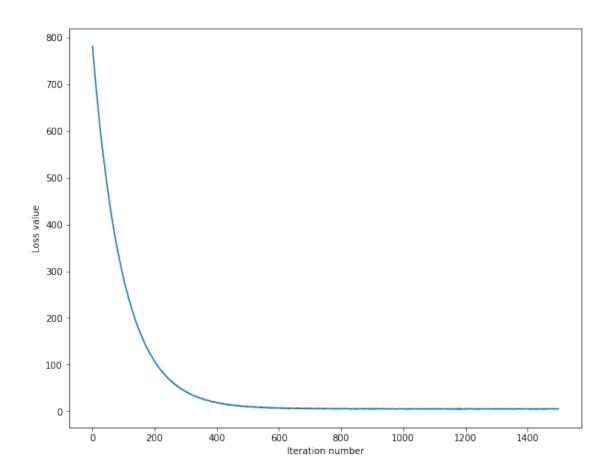
```
[10]: | # Complete the implementation of svm_loss_vectorized, and compute the gradient
      # of the loss function in a vectorized way.
      # The naive implementation and the vectorized implementation should match, but
      # the vectorized version should still be much faster.
      tic = time.time()
      _, grad_naive = svm_loss_naive(W, X_dev, y_dev, 0.000005)
      toc = time.time()
      print('Naive loss and gradient: computed in %fs' % (toc - tic))
      tic = time.time()
      _, grad_vectorized = svm_loss_vectorized(W, X_dev, y_dev, 0.000005)
      toc = time.time()
      print('Vectorized loss and gradient: computed in %fs' % (toc - tic))
      # The loss is a single number, so it is easy to compare the values computed
      # by the two implementations. The gradient on the other hand is a matrix, so
      # we use the Frobenius norm to compare them.
      difference = np.linalg.norm(grad_naive - grad_vectorized, ord='fro')
      print('difference: %f' % difference)
```

Naive loss and gradient: computed in 0.114922s Vectorized loss and gradient: computed in 0.004000s difference: 0.000000

1.2.1 Stochastic Gradient Descent

We now have vectorized and efficient expressions for the loss, the gradient and our gradient matches the numerical gradient. We are therefore ready to do SGD to minimize the loss. Your code for this part will be written inside cs231n/classifiers/linear_classifier.py.

```
[22]: # In the file linear classifier.py, implement SGD in the function
      # LinearClassifier.train() and then run it with the code below.
      from cs231n.classifiers import LinearSVM
      svm = LinearSVM()
      tic = time.time()
      loss_hist = svm.train(X_train, y_train, learning_rate=1e-7, reg=2.5e4,
                            num_iters=1500, verbose=True)
      toc = time.time()
      print('That took %fs' % (toc - tic))
     iteration 0 / 1500: loss 780.700416
     iteration 100 / 1500: loss 283.694914
     iteration 200 / 1500: loss 107.363775
     iteration 300 / 1500: loss 42.205157
     iteration 400 / 1500: loss 19.122201
     iteration 500 / 1500: loss 9.801773
     iteration 600 / 1500: loss 7.194517
     iteration 700 / 1500: loss 5.823311
     iteration 800 / 1500: loss 5.882657
     iteration 900 / 1500: loss 4.666819
     iteration 1000 / 1500: loss 5.381809
     iteration 1100 / 1500: loss 5.687265
     iteration 1200 / 1500: loss 5.471215
     iteration 1300 / 1500: loss 4.902035
     iteration 1400 / 1500: loss 5.492541
     That took 5.728029s
[23]: # A useful debugging strategy is to plot the loss as a function of
      # iteration number:
      plt.plot(loss_hist)
      plt.xlabel('Iteration number')
      plt.ylabel('Loss value')
      plt.show()
```



training accuracy: 0.100265 validation accuracy: 0.087000

```
[31]: # Use the validation set to tune hyperparameters (regularization strength and # learning rate). You should experiment with different ranges for the learning # rates and regularization strengths; if you are careful you should be able to # get a classification accuracy of about 0.39 on the validation set.

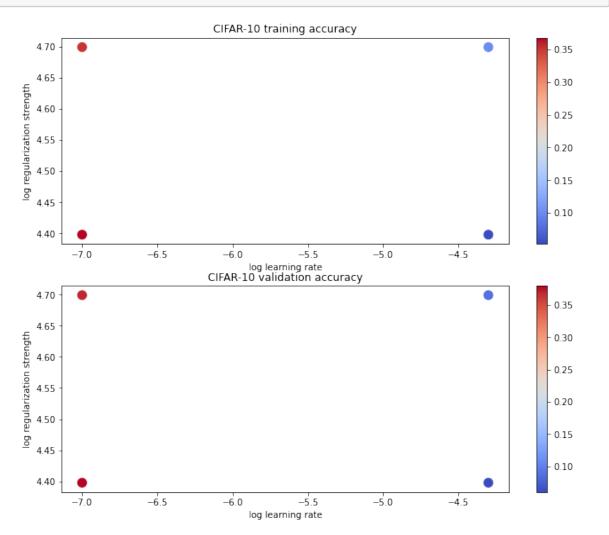
# Note: you may see runtime/overflow warnings during hyper-parameter search. # This may be caused by extreme values, and is not a bug.

# results is dictionary mapping tuples of the form # (learning_rate, regularization_strength) to tuples of the form
```

```
# (training accuracy, validation accuracy). The accuracy is simply the fraction
# of data points that are correctly classified.
results = {}
best_val = -1  # The highest validation accuracy that we have seen so far.
best_svm = None # The LinearSVM object that achieved the highest validation_
\rightarrow rate.
# Write code that chooses the best hyperparameters by tuning on the validation #
# set. For each combination of hyperparameters, train a linear SVM on the
# training set, compute its accuracy on the training and validation sets, and
# store these numbers in the results dictionary. In addition, store the best
# validation accuracy in best_val and the LinearSVM object that achieves this
# accuracy in best sum.
# Hint: You should use a small value for num iters as you develop your
# validation code so that the SVMs don't take much time to train; once you are #
# confident that your validation code works, you should rerun the validation
# code with a larger value for num iters.
# Provided as a reference. You may or may not want to change these_
\rightarrow hyperparameters
learning_rates = [1e-7, 5e-5]
regularization_strengths = [2.5e4, 5e4]
# *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
from itertools import product
for learning_rate, regularization_strength in product(learning_rates, __
→regularization_strengths):
   svm = LinearSVM()
   loss_hist = svm.train(X_train, y_train, learning_rate=learning_rate,
                        reg=regularization_strength, num_iters=1500)
   y_train_pred = svm.predict(X_train)
   y_val_pred = svm.predict(X_val)
   train_acc, val_acc = np.mean(y_train == y_train_pred), np.mean(y_val ==_u
→y_val_pred)
   results[(learning rate, regularization strength)] = (train acc, val acc)
   if val_acc > best_val:
       best_val = val_acc
       best_svm = svm
```

```
[33]: # Visualize the cross-validation results
      import math
      import pdb
      # pdb.set_trace()
      x_scatter = [math.log10(x[0]) for x in results]
      y_scatter = [math.log10(x[1]) for x in results]
      # plot training accuracy
      marker size = 100
      colors = [results[x][0] for x in results]
      plt.subplot(2, 1, 1)
      plt.tight_layout(pad=3)
      plt.scatter(x_scatter, y_scatter, marker_size, c=colors, cmap=plt.cm.coolwarm)
      plt.colorbar()
      plt.xlabel('log learning rate')
      plt.ylabel('log regularization strength')
      plt.title('CIFAR-10 training accuracy')
      # plot validation accuracy
      colors = [results[x][1] for x in results] # default size of markers is 20
      plt.subplot(2, 1, 2)
      plt.scatter(x_scatter, y_scatter, marker_size, c=colors, cmap=plt.cm.coolwarm)
      plt.colorbar()
      plt.xlabel('log learning rate')
      plt.ylabel('log regularization strength')
      plt.title('CIFAR-10 validation accuracy')
```





```
[34]: # Evaluate the best sum on test set
y_test_pred = best_svm.predict(X_test)
test_accuracy = np.mean(y_test == y_test_pred)
print('linear SVM on raw pixels final test set accuracy: %f' % test_accuracy)
```

linear SVM on raw pixels final test set accuracy: 0.354000

```
[35]: # Visualize the learned weights for each class.

# Depending on your choice of learning rate and regularization strength, these

→ may

# or may not be nice to look at.

w = best_svm.W[:-1,:] # strip out the bias

w = w.reshape(32, 32, 3, 10)

w_min, w_max = np.min(w), np.max(w)
```





Inline question 2

Describe what your visualized SVM weights look like, and offer a brief explanation for why they look they way that they do.

 $Your Answer: fill\ this\ in$

softmax

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```
[]: # This mounts your Google Drive to the Colab VM.
     from google.colab import drive
     drive.mount('/content/drive', force_remount=True)
     # Enter the foldername in your Drive where you have saved the unzipped
     # assignment folder, e.g. 'cs231n/assignments/assignment1/'
     FOLDERNAME = None
     assert FOLDERNAME is not None, "[!] Enter the foldername."
     # Now that we've mounted your Drive, this ensures that
     # the Python interpreter of the Colab VM can load
     # python files from within it.
     import sys
     sys.path.append('/content/drive/My Drive/{}'.format(FOLDERNAME))
     # This downloads the CIFAR-10 dataset to your Drive
     # if it doesn't already exist.
     %cd drive/My\ Drive/$FOLDERNAME/cs231n/datasets/
     !bash get_datasets.sh
     %cd /content/drive/My\ Drive/$FOLDERNAME
```

1 Softmax exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the assignments page on the course website.

This exercise is analogous to the SVM exercise. You will:

- implement a fully-vectorized loss function for the Softmax classifier
- implement the fully-vectorized expression for its analytic gradient
- check your implementation with numerical gradient
- use a validation set to tune the learning rate and regularization strength
- optimize the loss function with SGD
- visualize the final learned weights

```
[1]: import random import numpy as np
```

```
[2]: def get_CIFAR10_data(num_training=49000, num_validation=1000, num_test=1000,
      \rightarrownum dev=500):
         11 11 11
         Load the CIFAR-10 dataset from disk and perform preprocessing to prepare
         it for the linear classifier. These are the same steps as we used for the
         SVM, but condensed to a single function.
         11 11 11
         # Load the raw CIFAR-10 data
         cifar10_dir = 'cs231n/datasets/cifar-10-batches-py'
         # Cleaning up variables to prevent loading data multiple times (which may)
      → cause memory issue)
         try:
            del X_train, y_train
            del X_test, y_test
            print('Clear previously loaded data.')
         except:
            pass
         X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)
         # subsample the data
         mask = list(range(num_training, num_training + num_validation))
         X_val = X_train[mask]
         y_val = y_train[mask]
         mask = list(range(num_training))
         X_train = X_train[mask]
         y_train = y_train[mask]
         mask = list(range(num_test))
         X_test = X_test[mask]
         y_test = y_test[mask]
         mask = np.random.choice(num_training, num_dev, replace=False)
         X_dev = X_train[mask]
```

```
y_dev = y_train[mask]
    # Preprocessing: reshape the image data into rows
    X_train = np.reshape(X_train, (X_train.shape[0], -1))
    X_val = np.reshape(X_val, (X_val.shape[0], -1))
    X_test = np.reshape(X_test, (X_test.shape[0], -1))
    X_dev = np.reshape(X_dev, (X_dev.shape[0], -1))
    # Normalize the data: subtract the mean image
    mean_image = np.mean(X_train, axis = 0)
    X train -= mean image
    X_val -= mean_image
    X_test -= mean_image
    X_{dev} = mean_{image}
    # add bias dimension and transform into columns
    X_train = np.hstack([X_train, np.ones((X_train.shape[0], 1))])
    X_val = np.hstack([X_val, np.ones((X_val.shape[0], 1))])
    X_test = np.hstack([X_test, np.ones((X_test.shape[0], 1))])
    X_dev = np.hstack([X_dev, np.ones((X_dev.shape[0], 1))])
    return X_train, y_train, X_val, y_val, X_test, y_test, X_dev, y_dev
# Invoke the above function to get our data.
X_train, y_train, X_val, y_val, X_test, y_test, X_dev, y_dev =_
 →get_CIFAR10_data()
print('Train data shape: ', X_train.shape)
print('Train labels shape: ', y_train.shape)
print('Validation data shape: ', X_val.shape)
print('Validation labels shape: ', y_val.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
print('dev data shape: ', X_dev.shape)
print('dev labels shape: ', y_dev.shape)
Train data shape: (49000, 3073)
Train labels shape: (49000,)
```

```
Train data shape: (49000, 3073)
Train labels shape: (49000,)
Validation data shape: (1000, 3073)
Validation labels shape: (1000,)
Test data shape: (1000, 3073)
Test labels shape: (1000,)
dev data shape: (500, 3073)
dev labels shape: (500,)
```

1.1 Softmax Classifier

Your code for this section will all be written inside cs231n/classifiers/softmax.py.

```
[3]: # First implement the naive softmax loss function with nested loops.
# Open the file cs231n/classifiers/softmax.py and implement the
# softmax_loss_naive function.

from cs231n.classifiers.softmax import softmax_loss_naive
import time

# Generate a random softmax weight matrix and use it to compute the loss.
W = np.random.randn(3073, 10) * 0.0001
loss, grad = softmax_loss_naive(W, X_dev, y_dev, 0.0)

# As a rough sanity check, our loss should be something close to -log(0.1).
print('loss: %f' % loss)
print('sanity check: %f' % (-np.log(0.1)))
```

loss: 2.353239

sanity check: 2.302585

Inline Question 1

Why do we expect our loss to be close to $-\log(0.1)$? Explain briefly.**

YourAnswer: Fill this in

```
[4]: # Complete the implementation of softmax_loss_naive and implement a (naive)
# version of the gradient that uses nested loops.
loss, grad = softmax_loss_naive(W, X_dev, y_dev, 0.0)

# As we did for the SVM, use numeric gradient checking as a debugging tool.
# The numeric gradient should be close to the analytic gradient.
from cs231n.gradient_check import grad_check_sparse
f = lambda w: softmax_loss_naive(w, X_dev, y_dev, 0.0)[0]
grad_numerical = grad_check_sparse(f, W, grad, 10)

# similar to SVM case, do another gradient check with regularization
loss, grad = softmax_loss_naive(W, X_dev, y_dev, 5e1)
f = lambda w: softmax_loss_naive(w, X_dev, y_dev, 5e1)[0]
grad_numerical = grad_check_sparse(f, W, grad, 10)
```

```
numerical: -2.434453 analytic: -2.434453, relative error: 2.190034e-08 numerical: -0.793415 analytic: -0.793415, relative error: 1.123710e-08 numerical: -2.392728 analytic: -2.392728, relative error: 5.213338e-09 numerical: -0.912172 analytic: -0.912173, relative error: 5.554803e-08 numerical: -2.116031 analytic: -2.116031, relative error: 4.187966e-08 numerical: 2.158820 analytic: 2.158819, relative error: 2.305529e-08 numerical: -0.298018 analytic: -0.298018, relative error: 1.535316e-07 numerical: -0.952358 analytic: -0.952358, relative error: 6.015612e-08 numerical: -3.685080 analytic: -3.685079, relative error: 1.970730e-08 numerical: 0.489900 analytic: 0.489900, relative error: 4.865513e-09
```

```
numerical: -2.581717 analytic: -2.581717, relative error: 6.016656e-09
    numerical: -1.047876 analytic: -1.047876, relative error: 9.597189e-09
    numerical: 1.821141 analytic: 1.821141, relative error: 4.131058e-08
    numerical: 0.634785 analytic: 0.634785, relative error: 1.520709e-07
    numerical: 3.437924 analytic: 3.437925, relative error: 4.372568e-09
    numerical: 0.160905 analytic: 0.160905, relative error: 4.677595e-08
    numerical: -2.619809 analytic: -2.619809, relative error: 3.041246e-09
    numerical: 0.683541 analytic: 0.683541, relative error: 1.142027e-08
[5]: # Now that we have a naive implementation of the softmax loss function and itsu
     \hookrightarrow gradient,
     # implement a vectorized version in softmax_loss_vectorized.
     # The two versions should compute the same results, but the vectorized version
     ⇔should be
     # much faster.
     tic = time.time()
     loss_naive, grad_naive = softmax_loss_naive(W, X_dev, y_dev, 0.000005)
     toc = time.time()
     print('naive loss: %e computed in %fs' % (loss_naive, toc - tic))
     from cs231n.classifiers.softmax import softmax_loss_vectorized
     tic = time.time()
     loss vectorized, grad vectorized = softmax loss vectorized(W, X dev, y dev, 0.
     →000005)
     toc = time.time()
     print('vectorized loss: %e computed in %fs' % (loss_vectorized, toc - tic))
     # As we did for the SVM, we use the Frobenius norm to compare the two versions
     # of the gradient.
     grad_difference = np.linalg.norm(grad_naive - grad_vectorized, ord='fro')
     print('Loss difference: %f' % np.abs(loss_naive - loss_vectorized))
     print('Gradient difference: %f' % grad_difference)
    naive loss: 2.353239e+00 computed in 0.142951s
    vectorized loss: 2.353239e+00 computed in 0.008002s
    Loss difference: 0.000000
    Gradient difference: 0.000000
[6]: # Use the validation set to tune hyperparameters (regularization strength and
     # learning rate). You should experiment with different ranges for the learning
     # rates and regularization strengths; if you are careful you should be able to
     # get a classification accuracy of over 0.35 on the validation set.
```

numerical: 2.156390 analytic: 2.156390, relative error: 2.653849e-08 numerical: -3.217517 analytic: -3.217517, relative error: 2.138860e-08

from cs231n.classifiers import Softmax

results = {}

```
best_val = -1
best_softmax = None
# TODO:
# Use the validation set to set the learning rate and regularization strength. #
# This should be identical to the validation that you did for the SVM; save
# the best trained softmax classifer in best_softmax.
# Provided as a reference. You may or may not want to change these
\rightarrowhyperparameters
learning_rates = [1e-7, 5e-7]
regularization_strengths = [2.5e4, 5e4]
# *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
from itertools import product
for learning_rate, regularization_strength in product(learning_rates,_
→regularization strengths):
   softmax = Softmax()
   loss_hist = softmax.train(X_train, y_train, learning_rate=learning_rate,
                           reg=regularization_strength, num_iters=1500)
   y_train_pred = softmax.predict(X_train)
   y val pred = softmax.predict(X val)
   train_acc, val_acc = np.mean(y_train == y_train_pred), np.mean(y_val ==_u
→y_val_pred)
   results[(learning rate, regularization strength)] = (train acc, val acc)
   if val_acc > best_val:
       best_val = val_acc
       best_softmax = softmax
# ****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
# Print out results.
for lr, reg in sorted(results):
   train_accuracy, val_accuracy = results[(lr, reg)]
   print('lr %e reg %e train accuracy: %f val accuracy: %f' % (
              lr, reg, train_accuracy, val_accuracy))
print('best validation accuracy achieved during cross-validation: %f' %⊔
 →best_val)
```

```
lr 1.000000e-07 reg 2.500000e+04 train accuracy: 0.328755 val accuracy: 0.352000
lr 1.000000e-07 reg 5.000000e+04 train accuracy: 0.309122 val accuracy: 0.329000
lr 5.000000e-07 reg 2.500000e+04 train accuracy: 0.330184 val accuracy: 0.343000
lr 5.000000e-07 reg 5.000000e+04 train accuracy: 0.306469 val accuracy: 0.314000
best validation accuracy achieved during cross-validation: 0.352000
```

```
[7]: # evaluate on test set
# Evaluate the best softmax on test set
y_test_pred = best_softmax.predict(X_test)
test_accuracy = np.mean(y_test == y_test_pred)
print('softmax on raw pixels final test set accuracy: %f' % (test_accuracy, ))
```

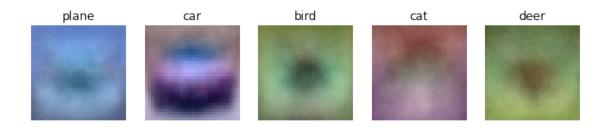
softmax on raw pixels final test set accuracy: 0.335000

Inline Question 2 - True or False

Suppose the overall training loss is defined as the sum of the per-datapoint loss over all training examples. It is possible to add a new datapoint to a training set that would leave the SVM loss unchanged, but this is not the case with the Softmax classifier loss.

Your Answer:

Your Explanation:





[]:

two layer net

July 26, 2021

```
[]: # This mounts your Google Drive to the Colab VM.
     from google.colab import drive
     drive.mount('/content/drive', force_remount=True)
     # Enter the foldername in your Drive where you have saved the unzipped
     # assignment folder, e.g. 'cs231n/assignments/assignment1/'
     FOLDERNAME = None
     assert FOLDERNAME is not None, "[!] Enter the foldername."
     # Now that we've mounted your Drive, this ensures that
     # the Python interpreter of the Colab VM can load
     # python files from within it.
     import sys
     sys.path.append('/content/drive/My Drive/{}'.format(FOLDERNAME))
     # This downloads the CIFAR-10 dataset to your Drive
     # if it doesn't already exist.
     %cd drive/My\ Drive/$FOLDERNAME/cs231n/datasets/
     !bash get_datasets.sh
     %cd /content/drive/My\ Drive/$FOLDERNAME
```

1 Fully-Connected Neural Nets

In this exercise we will implement fully-connected networks using a modular approach. For each layer we will implement a forward and a backward function. The forward function will receive inputs, weights, and other parameters and will return both an output and a cache object storing data needed for the backward pass, like this:

```
def layer_forward(x, w):
    """ Receive inputs x and weights w """
    # Do some computations ...
    z = # ... some intermediate value
    # Do some more computations ...
    out = # the output

cache = (x, w, z, out) # Values we need to compute gradients
    return out, cache
```

The backward pass will receive upstream derivatives and the cache object, and will return gradients with respect to the inputs and weights, like this:

```
def layer_backward(dout, cache):
    """
    Receive dout (derivative of loss with respect to outputs) and cache,
    and compute derivative with respect to inputs.
    """
    # Unpack cache values
    x, w, z, out = cache

# Use values in cache to compute derivatives
    dx = # Derivative of loss with respect to x
    dw = # Derivative of loss with respect to w

return dx, dw
```

After implementing a bunch of layers this way, we will be able to easily combine them to build classifiers with different architectures.

```
[1]: # As usual, a bit of setup
     from __future__ import print_function
     import time
     import numpy as np
     import matplotlib.pyplot as plt
     from cs231n.classifiers.fc net import *
     from cs231n.data_utils import get_CIFAR10_data
     from cs231n.gradient_check import eval_numerical_gradient,__
      →eval_numerical_gradient_array
     from cs231n.solver import Solver
     %matplotlib inline
     plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
     plt.rcParams['image.interpolation'] = 'nearest'
     plt.rcParams['image.cmap'] = 'gray'
     # for auto-reloading external modules
     # see http://stackoverflow.com/questions/1907993/
     \rightarrow autoreload-of-modules-in-ipython
     %load_ext autoreload
     %autoreload 2
     def rel_error(x, y):
       """ returns relative error """
       return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
```

```
[2]: # Load the (preprocessed) CIFAR10 data.
```

```
data = get_CIFAR10_data()
for k, v in list(data.items()):
    print(('%s: ' % k, v.shape))

('X_train: ', (49000, 3, 32, 32))
('y_train: ', (49000,))
('X_val: ', (1000, 3, 32, 32))
('y_val: ', (1000,))
```

2 Affine layer: forward

('X_test: ', (1000, 3, 32, 32))

('y_test: ', (1000,))

Open the file cs231n/layers.py and implement the affine_forward function.

Once you are done you can test your implementaion by running the following:

```
[3]: # Test the affine_forward function
     num inputs = 2
     input\_shape = (4, 5, 6)
     output dim = 3
     input_size = num_inputs * np.prod(input_shape)
     weight_size = output_dim * np.prod(input_shape)
     x = np.linspace(-0.1, 0.5, num=input_size).reshape(num_inputs, *input_shape)
     w = np.linspace(-0.2, 0.3, num=weight_size).reshape(np.prod(input_shape),__
     →output_dim)
     b = np.linspace(-0.3, 0.1, num=output dim)
     out, _ = affine_forward(x, w, b)
     correct_out = np.array([[ 1.49834967, 1.70660132, 1.91485297],
                             [ 3.25553199, 3.5141327, 3.77273342]])
     # Compare your output with ours. The error should be around e-9 or less.
     print('Testing affine_forward function:')
     print('difference: ', rel_error(out, correct_out))
```

Testing affine_forward function: difference: 9.769849468192957e-10

3 Affine layer: backward

Now implement the affine_backward function and test your implementation using numeric gradient checking.

```
[4]: # Test the affine backward function
    np.random.seed(231)
     x = np.random.randn(10, 2, 3)
     w = np.random.randn(6, 5)
     b = np.random.randn(5)
     dout = np.random.randn(10, 5)
     dx_num = eval_numerical_gradient_array(lambda x: affine_forward(x, w, b)[0], x,_
     dw_num = eval_numerical_gradient_array(lambda w: affine_forward(x, w, b)[0], w,__

dout)
     db_num = eval_numerical_gradient_array(lambda b: affine_forward(x, w, b)[0], b,_
     -dout)
     _, cache = affine_forward(x, w, b)
     dx, dw, db = affine_backward(dout, cache)
     # The error should be around e-10 or less
     print('Testing affine_backward function:')
     print('dx error: ', rel_error(dx_num, dx))
     print('dw error: ', rel_error(dw_num, dw))
     print('db error: ', rel_error(db_num, db))
```

Testing affine_backward function: dx error: 5.399100368651805e-11 dw error: 9.904211865398145e-11 db error: 2.4122867568119087e-11

4 ReLU activation: forward

Implement the forward pass for the ReLU activation function in the relu_forward function and test your implementation using the following:

```
Testing relu_forward function: difference: 4.999999798022158e-08
```

5 ReLU activation: backward

Now implement the backward pass for the ReLU activation function in the relu_backward function and test your implementation using numeric gradient checking:

```
[6]: np.random.seed(231)
    x = np.random.randn(10, 10)
    dout = np.random.randn(*x.shape)

    dx_num = eval_numerical_gradient_array(lambda x: relu_forward(x)[0], x, dout)

    _, cache = relu_forward(x)
    dx = relu_backward(dout, cache)

# The error should be on the order of e-12
    print('Testing relu_backward function:')
    print('dx error: ', rel_error(dx_num, dx))
```

Testing relu_backward function: dx error: 3.2756349136310288e-12

5.1 Inline Question 1:

We've only asked you to implement ReLU, but there are a number of different activation functions that one could use in neural networks, each with its pros and cons. In particular, an issue commonly seen with activation functions is getting zero (or close to zero) gradient flow during backpropagation. Which of the following activation functions have this problem? If you consider these functions in the one dimensional case, what types of input would lead to this behaviour? 1. Sigmoid 2. ReLU 3. Leaky ReLU

5.2 Answer:

[FILL THIS IN]

6 "Sandwich" layers

There are some common patterns of layers that are frequently used in neural nets. For example, affine layers are frequently followed by a ReLU nonlinearity. To make these common patterns easy, we define several convenience layers in the file cs231n/layer_utils.py.

For now take a look at the affine_relu_forward and affine_relu_backward functions, and run the following to numerically gradient check the backward pass:

```
[7]: from cs231n.layer_utils import affine_relu_forward, affine_relu_backward np.random.seed(231)
```

```
x = np.random.randn(2, 3, 4)
w = np.random.randn(12, 10)
b = np.random.randn(10)
dout = np.random.randn(2, 10)
out, cache = affine_relu_forward(x, w, b)
dx, dw, db = affine_relu_backward(dout, cache)
dx num = eval numerical gradient array(lambda x: affine relu forward(x, w, )
\rightarrowb)[0], x, dout)
dw num = eval_numerical_gradient_array(lambda w: affine relu_forward(x, w,__
\rightarrowb)[0], w, dout)
db_num = eval_numerical_gradient_array(lambda b: affine_relu_forward(x, w,_
\rightarrowb)[0], b, dout)
# Relative error should be around e-10 or less
print('Testing affine relu forward and affine relu backward:')
print('dx error: ', rel_error(dx_num, dx))
print('dw error: ', rel_error(dw_num, dw))
print('db error: ', rel_error(db_num, db))
```

Testing affine_relu_forward and affine_relu_backward:

dx error: 2.299579177309368e-11
dw error: 8.162011105764925e-11
db error: 7.826724021458994e-12

7 Loss layers: Softmax and SVM

Now implement the loss and gradient for softmax and SVM in the softmax_loss and svm_loss function in cs231n/layers.py. These should be similar to what you implemented in cs231n/classifiers/softmax.py and cs231n/classifiers/linear_svm.py.

You can make sure that the implementations are correct by running the following:

Testing svm_loss:

loss: 8.999602749096233

dx error: 1.4021566006651672e-09

Testing softmax_loss: loss: 2.302545844500738

dx error: 9.483503037636722e-09

8 Two-layer network

Open the file cs231n/classifiers/fc_net.py and complete the implementation of the TwoLayerNet class. Read through it to make sure you understand the API. You can run the cell below to test your implementation.

```
[9]: np.random.seed(231)
     N, D, H, C = 3, 5, 50, 7
     X = np.random.randn(N, D)
     y = np.random.randint(C, size=N)
     std = 1e-3
     model = TwoLayerNet(input_dim=D, hidden_dim=H, num_classes=C, weight_scale=std)
     print('Testing initialization ... ')
     W1_std = abs(model.params['W1'].std() - std)
     b1 = model.params['b1']
     W2_std = abs(model.params['W2'].std() - std)
     b2 = model.params['b2']
     assert W1_std < std / 10, 'First layer weights do not seem right'
     assert np.all(b1 == 0), 'First layer biases do not seem right'
     assert W2_std < std / 10, 'Second layer weights do not seem right'
     assert np.all(b2 == 0), 'Second layer biases do not seem right'
     print('Testing test-time forward pass ... ')
     model.params['W1'] = np.linspace(-0.7, 0.3, num=D*H).reshape(D, H)
     model.params['b1'] = np.linspace(-0.1, 0.9, num=H)
     model.params['W2'] = np.linspace(-0.3, 0.4, num=H*C).reshape(H, C)
```

```
model.params['b2'] = np.linspace(-0.9, 0.1, num=C)
X = np.linspace(-5.5, 4.5, num=N*D).reshape(D, N).T
scores = model.loss(X)
correct_scores = np.asarray(
  [[11.53165108, 12.2917344, 13.05181771, 13.81190102, 14.57198434, 15.
 \rightarrow 33206765, 16.09215096],
   [12.05769098, 12.74614105, 13.43459113, 14.1230412, 14.81149128, 15.
 →49994135, 16.18839143],
   [12.58373087, 13.20054771, 13.81736455, 14.43418138, 15.05099822, 15.
 →66781506, 16.2846319 ]])
scores_diff = np.abs(scores - correct_scores).sum()
assert scores_diff < 1e-6, 'Problem with test-time forward pass'
print('Testing training loss (no regularization)')
y = np.asarray([0, 5, 1])
loss, grads = model.loss(X, y)
correct_loss = 3.4702243556
assert abs(loss - correct_loss) < 1e-10, 'Problem with training-time loss'
model.reg = 1.0
loss, grads = model.loss(X, y)
correct_loss = 26.5948426952
assert abs(loss - correct_loss) < 1e-10, 'Problem with regularization loss'
# Errors should be around e-7 or less
for reg in [0.0, 0.7]:
  print('Running numeric gradient check with reg = ', reg)
  model.reg = reg
  loss, grads = model.loss(X, y)
  for name in sorted(grads):
    f = lambda _: model.loss(X, y)[0]
    grad_num = eval_numerical_gradient(f, model.params[name], verbose=False)
    print('%s relative error: %.2e' % (name, rel_error(grad_num, grads[name])))
Testing initialization ...
Testing test-time forward pass ...
Testing training loss (no regularization)
Running numeric gradient check with reg = 0.0
W1 relative error: 1.83e-08
W2 relative error: 3.31e-10
b1 relative error: 9.83e-09
b2 relative error: 4.33e-10
Running numeric gradient check with reg = 0.7
W1 relative error: 2.53e-07
W2 relative error: 2.85e-08
b1 relative error: 1.56e-08
```

b2 relative error: 7.76e-10

9 Solver

Open the file cs231n/solver.py and read through it to familiarize yourself with the API. You also need to imeplement the sgd function in cs231n/optim.py. After doing so, use a Solver instance to train a TwoLayerNet that achieves about 36% accuracy on the validation set.

```
[21]: input_size = 32 * 32 * 3
   hidden size = 50
   num_classes = 10
   model = TwoLayerNet(input_size, hidden_size, num_classes)
   solver = None
   # TODO: Use a Solver instance to train a TwoLayerNet that achieves about 36% #
   # accuracy on the validation set.
   # *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
   solver = Solver(model, data,
              update_rule='sgd',
              optim_config={
                'learning_rate': 1e-3,
              },
              print_every=100)
   solver.train()
   # *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) *****
   END OF YOUR CODE
    ~~~~~
```

```
(Iteration 1 / 4900) loss: 2.300451

(Epoch 0 / 10) train acc: 0.114000; val_acc: 0.124000

(Iteration 101 / 4900) loss: 1.839884

(Iteration 201 / 4900) loss: 1.625506

(Iteration 301 / 4900) loss: 1.679194

(Iteration 401 / 4900) loss: 1.563544

(Epoch 1 / 10) train acc: 0.442000; val_acc: 0.428000

(Iteration 501 / 4900) loss: 1.704050

(Iteration 601 / 4900) loss: 1.464802

(Iteration 701 / 4900) loss: 1.387461

(Iteration 801 / 4900) loss: 1.442958

(Iteration 901 / 4900) loss: 1.452794

(Epoch 2 / 10) train acc: 0.460000; val_acc: 0.459000

(Iteration 1001 / 4900) loss: 1.442953

(Iteration 1101 / 4900) loss: 1.519110
```

```
(Iteration 1201 / 4900) loss: 1.560716
(Iteration 1301 / 4900) loss: 1.488055
(Iteration 1401 / 4900) loss: 1.393224
(Epoch 3 / 10) train acc: 0.502000; val_acc: 0.465000
(Iteration 1501 / 4900) loss: 1.486725
(Iteration 1601 / 4900) loss: 1.349897
(Iteration 1701 / 4900) loss: 1.365168
(Iteration 1801 / 4900) loss: 1.394354
(Iteration 1901 / 4900) loss: 1.512230
(Epoch 4 / 10) train acc: 0.523000; val_acc: 0.476000
(Iteration 2001 / 4900) loss: 1.472896
(Iteration 2101 / 4900) loss: 1.215415
(Iteration 2201 / 4900) loss: 1.437056
(Iteration 2301 / 4900) loss: 1.324687
(Iteration 2401 / 4900) loss: 1.332958
(Epoch 5 / 10) train acc: 0.497000; val_acc: 0.472000
(Iteration 2501 / 4900) loss: 1.624329
(Iteration 2601 / 4900) loss: 1.486466
(Iteration 2701 / 4900) loss: 1.332735
(Iteration 2801 / 4900) loss: 1.515805
(Iteration 2901 / 4900) loss: 1.204616
(Epoch 6 / 10) train acc: 0.491000; val acc: 0.475000
(Iteration 3001 / 4900) loss: 1.217157
(Iteration 3101 / 4900) loss: 1.268385
(Iteration 3201 / 4900) loss: 1.346691
(Iteration 3301 / 4900) loss: 1.154967
(Iteration 3401 / 4900) loss: 1.458695
(Epoch 7 / 10) train acc: 0.533000; val_acc: 0.492000
(Iteration 3501 / 4900) loss: 1.128183
(Iteration 3601 / 4900) loss: 1.453269
(Iteration 3701 / 4900) loss: 1.188008
(Iteration 3801 / 4900) loss: 1.328329
(Iteration 3901 / 4900) loss: 1.257040
(Epoch 8 / 10) train acc: 0.512000; val_acc: 0.484000
(Iteration 4001 / 4900) loss: 1.458974
(Iteration 4101 / 4900) loss: 1.539508
(Iteration 4201 / 4900) loss: 1.290207
(Iteration 4301 / 4900) loss: 1.216675
(Iteration 4401 / 4900) loss: 1.171401
(Epoch 9 / 10) train acc: 0.564000; val_acc: 0.484000
(Iteration 4501 / 4900) loss: 1.347632
(Iteration 4601 / 4900) loss: 1.457013
(Iteration 4701 / 4900) loss: 1.135937
(Iteration 4801 / 4900) loss: 1.122402
(Epoch 10 / 10) train acc: 0.523000; val_acc: 0.472000
```

10 Debug the training

With the default parameters we provided above, you should get a validation accuracy of about 0.36 on the validation set. This isn't very good.

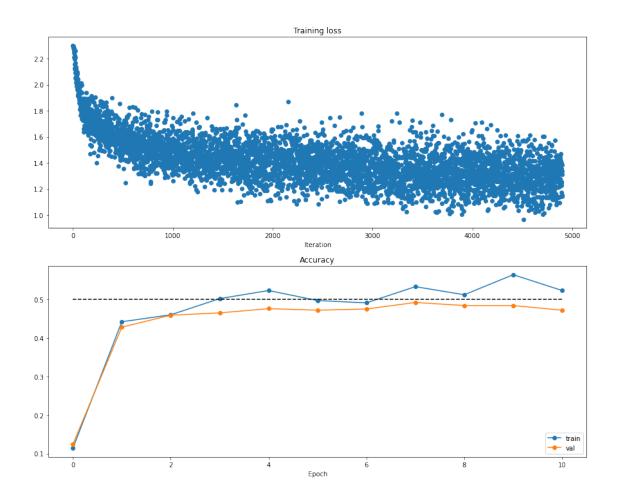
One strategy for getting insight into what's wrong is to plot the loss function and the accuracies on the training and validation sets during optimization.

Another strategy is to visualize the weights that were learned in the first layer of the network. In most neural networks trained on visual data, the first layer weights typically show some visible structure when visualized.

```
[22]: # Run this cell to visualize training loss and train / val accuracy

plt.subplot(2, 1, 1)
plt.title('Training loss')
plt.plot(solver.loss_history, 'o')
plt.xlabel('Iteration')

plt.subplot(2, 1, 2)
plt.title('Accuracy')
plt.plot(solver.train_acc_history, '-o', label='train')
plt.plot(solver.val_acc_history, '-o', label='val')
plt.plot([0.5] * len(solver.val_acc_history), 'k--')
plt.xlabel('Epoch')
plt.legend(loc='lower right')
plt.gcf().set_size_inches(15, 12)
plt.show()
```

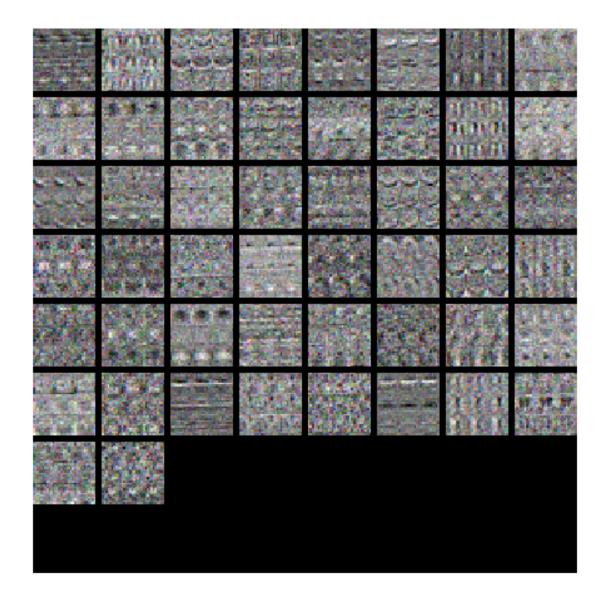


```
[23]: from cs231n.vis_utils import visualize_grid

# Visualize the weights of the network

def show_net_weights(net):
    W1 = net.params['W1']
    W1 = W1.reshape(32, 32, 3, -1).transpose(3, 0, 1, 2)
    plt.imshow(visualize_grid(W1, padding=3).astype('uint8'))
    plt.gca().axis('off')
    plt.show()

show_net_weights(model)
```



11 Tune your hyperparameters

What's wrong? Looking at the visualizations above, we see that the loss is decreasing more or less linearly, which seems to suggest that the learning rate may be too low. Moreover, there is no gap between the training and validation accuracy, suggesting that the model we used has low capacity, and that we should increase its size. On the other hand, with a very large model we would expect to see more overfitting, which would manifest itself as a very large gap between the training and validation accuracy.

Tuning. Tuning the hyperparameters and developing intuition for how they affect the final performance is a large part of using Neural Networks, so we want you to get a lot of practice. Below, you should experiment with different values of the various hyperparameters, including hidden layer size, learning rate, numer of training epochs, and regularization strength. You might also consider

tuning the learning rate decay, but you should be able to get good performance using the default value.

Approximate results. You should be aim to achieve a classification accuracy of greater than 48% on the validation set. Our best network gets over 52% on the validation set.

Experiment: You goal in this exercise is to get as good of a result on CIFAR-10 as you can (52% could serve as a reference), with a fully-connected Neural Network. Feel free implement your own techniques (e.g. PCA to reduce dimensionality, or adding dropout, or adding features to the solver, etc.).

```
[26]: best_model = None
     # TODO: Tune hyperparameters using the validation set. Store your best trained \square
     →#
     # model in best_model.
                                                                         Ш
      →#
     #
                                                                         ш
     →#
     # To help debug your network, it may help to use visualizations similar to the ...
     →#
     # ones we used above; these visualizations will have significant qualitative
     # differences from the ones we saw above for the poorly tuned network.
     →#
     #
     →#
     # Tweaking hyperparameters by hand can be fun, but you might find it useful to u
     # write code to sweep through possible combinations of hyperparameters
     →#
     # automatically like we did on thexs previous exercises.
                                                                         ш
     → #
     # *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
     from itertools import product
     best_accuracy = -1
     input size = 32 * 32 * 3
     num_classes = 10
     learning rates = [1e-3, 1e-4, 1e-5]
     hidden sizes = [50, 60, 70]
     for learning_rate, hidden_size in product(learning_rates, hidden_sizes):
```

```
model = TwoLayerNet(input_size, hidden_size, num_classes)
   solver = Solver(model, data,
               update_rule='sgd',
               optim_config={
                  'learning_rate': learning_rate,
               print_every=10000)
   solver.train()
   if solver.val_acc_history[-1] > best_accuracy:
      best model = model
      best_accuracy = solver.val_acc_history[-1]
print(f'best accuracy:', best_accuracy)
# *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
END OF YOUR CODE
(Iteration 1 / 4900) loss: 2.306009
```

```
(Epoch 0 / 10) train acc: 0.114000; val_acc: 0.133000
(Epoch 1 / 10) train acc: 0.450000; val_acc: 0.425000
(Epoch 2 / 10) train acc: 0.457000; val_acc: 0.455000
(Epoch 3 / 10) train acc: 0.503000; val_acc: 0.471000
(Epoch 4 / 10) train acc: 0.489000; val acc: 0.453000
(Epoch 5 / 10) train acc: 0.509000; val_acc: 0.476000
(Epoch 6 / 10) train acc: 0.530000; val acc: 0.464000
(Epoch 7 / 10) train acc: 0.535000; val_acc: 0.469000
(Epoch 8 / 10) train acc: 0.554000; val acc: 0.480000
(Epoch 9 / 10) train acc: 0.531000; val_acc: 0.492000
(Epoch 10 / 10) train acc: 0.547000; val_acc: 0.494000
(Iteration 1 / 4900) loss: 2.300482
(Epoch 0 / 10) train acc: 0.143000; val_acc: 0.142000
(Epoch 1 / 10) train acc: 0.440000; val_acc: 0.433000
(Epoch 2 / 10) train acc: 0.464000; val_acc: 0.479000
(Epoch 3 / 10) train acc: 0.519000; val_acc: 0.468000
(Epoch 4 / 10) train acc: 0.492000; val_acc: 0.459000
(Epoch 5 / 10) train acc: 0.525000; val_acc: 0.485000
(Epoch 6 / 10) train acc: 0.502000; val_acc: 0.467000
(Epoch 7 / 10) train acc: 0.553000; val_acc: 0.487000
(Epoch 8 / 10) train acc: 0.537000; val_acc: 0.473000
(Epoch 9 / 10) train acc: 0.550000; val acc: 0.502000
(Epoch 10 / 10) train acc: 0.544000; val_acc: 0.493000
(Iteration 1 / 4900) loss: 2.299031
(Epoch 0 / 10) train acc: 0.174000; val_acc: 0.176000
(Epoch 1 / 10) train acc: 0.449000; val_acc: 0.429000
```

```
(Epoch 2 / 10) train acc: 0.496000; val_acc: 0.469000
(Epoch 3 / 10) train acc: 0.509000; val_acc: 0.485000
(Epoch 4 / 10) train acc: 0.512000; val_acc: 0.494000
(Epoch 5 / 10) train acc: 0.509000; val_acc: 0.467000
(Epoch 6 / 10) train acc: 0.542000; val acc: 0.482000
(Epoch 7 / 10) train acc: 0.542000; val_acc: 0.492000
(Epoch 8 / 10) train acc: 0.533000; val acc: 0.487000
(Epoch 9 / 10) train acc: 0.545000; val_acc: 0.479000
(Epoch 10 / 10) train acc: 0.551000; val acc: 0.479000
(Iteration 1 / 4900) loss: 2.302319
(Epoch 0 / 10) train acc: 0.090000; val_acc: 0.093000
(Epoch 1 / 10) train acc: 0.294000; val_acc: 0.301000
(Epoch 2 / 10) train acc: 0.331000; val_acc: 0.354000
(Epoch 3 / 10) train acc: 0.376000; val_acc: 0.401000
(Epoch 4 / 10) train acc: 0.418000; val_acc: 0.427000
(Epoch 5 / 10) train acc: 0.428000; val_acc: 0.428000
(Epoch 6 / 10) train acc: 0.445000; val_acc: 0.441000
(Epoch 7 / 10) train acc: 0.487000; val_acc: 0.465000
(Epoch 8 / 10) train acc: 0.458000; val_acc: 0.452000
(Epoch 9 / 10) train acc: 0.483000; val acc: 0.466000
(Epoch 10 / 10) train acc: 0.487000; val acc: 0.462000
(Iteration 1 / 4900) loss: 2.301289
(Epoch 0 / 10) train acc: 0.117000; val_acc: 0.101000
(Epoch 1 / 10) train acc: 0.286000; val_acc: 0.303000
(Epoch 2 / 10) train acc: 0.373000; val_acc: 0.354000
(Epoch 3 / 10) train acc: 0.382000; val_acc: 0.397000
(Epoch 4 / 10) train acc: 0.411000; val_acc: 0.417000
(Epoch 5 / 10) train acc: 0.437000; val_acc: 0.444000
(Epoch 6 / 10) train acc: 0.424000; val_acc: 0.446000
(Epoch 7 / 10) train acc: 0.478000; val_acc: 0.468000
(Epoch 8 / 10) train acc: 0.468000; val_acc: 0.459000
(Epoch 9 / 10) train acc: 0.513000; val_acc: 0.469000
(Epoch 10 / 10) train acc: 0.463000; val_acc: 0.471000
(Iteration 1 / 4900) loss: 2.303447
(Epoch 0 / 10) train acc: 0.090000; val acc: 0.101000
(Epoch 1 / 10) train acc: 0.322000; val acc: 0.302000
(Epoch 2 / 10) train acc: 0.355000; val acc: 0.366000
(Epoch 3 / 10) train acc: 0.386000; val_acc: 0.401000
(Epoch 4 / 10) train acc: 0.402000; val_acc: 0.429000
(Epoch 5 / 10) train acc: 0.426000; val_acc: 0.439000
(Epoch 6 / 10) train acc: 0.428000; val_acc: 0.448000
(Epoch 7 / 10) train acc: 0.472000; val_acc: 0.461000
(Epoch 8 / 10) train acc: 0.468000; val_acc: 0.461000
(Epoch 9 / 10) train acc: 0.441000; val_acc: 0.473000
(Epoch 10 / 10) train acc: 0.508000; val_acc: 0.474000
(Iteration 1 / 4900) loss: 2.306009
(Epoch 0 / 10) train acc: 0.078000; val_acc: 0.076000
(Epoch 1 / 10) train acc: 0.202000; val_acc: 0.206000
```

```
(Epoch 2 / 10) train acc: 0.241000; val_acc: 0.222000
(Epoch 3 / 10) train acc: 0.215000; val_acc: 0.230000
(Epoch 4 / 10) train acc: 0.229000; val_acc: 0.240000
(Epoch 5 / 10) train acc: 0.234000; val_acc: 0.251000
(Epoch 6 / 10) train acc: 0.285000; val acc: 0.261000
(Epoch 7 / 10) train acc: 0.260000; val_acc: 0.278000
(Epoch 8 / 10) train acc: 0.274000; val acc: 0.286000
(Epoch 9 / 10) train acc: 0.313000; val_acc: 0.286000
(Epoch 10 / 10) train acc: 0.302000; val acc: 0.302000
(Iteration 1 / 4900) loss: 2.303801
(Epoch 0 / 10) train acc: 0.084000; val_acc: 0.077000
(Epoch 1 / 10) train acc: 0.210000; val_acc: 0.224000
(Epoch 2 / 10) train acc: 0.207000; val_acc: 0.245000
(Epoch 3 / 10) train acc: 0.218000; val_acc: 0.252000
(Epoch 4 / 10) train acc: 0.252000; val_acc: 0.257000
(Epoch 5 / 10) train acc: 0.246000; val_acc: 0.267000
(Epoch 6 / 10) train acc: 0.283000; val_acc: 0.283000
(Epoch 7 / 10) train acc: 0.282000; val_acc: 0.287000
(Epoch 8 / 10) train acc: 0.282000; val_acc: 0.292000
(Epoch 9 / 10) train acc: 0.295000; val acc: 0.300000
(Epoch 10 / 10) train acc: 0.321000; val acc: 0.308000
(Iteration 1 / 4900) loss: 2.302039
(Epoch 0 / 10) train acc: 0.089000; val_acc: 0.103000
(Epoch 1 / 10) train acc: 0.174000; val_acc: 0.209000
(Epoch 2 / 10) train acc: 0.215000; val_acc: 0.245000
(Epoch 3 / 10) train acc: 0.240000; val_acc: 0.250000
(Epoch 4 / 10) train acc: 0.260000; val_acc: 0.260000
(Epoch 5 / 10) train acc: 0.250000; val_acc: 0.274000
(Epoch 6 / 10) train acc: 0.270000; val_acc: 0.283000
(Epoch 7 / 10) train acc: 0.273000; val_acc: 0.293000
(Epoch 8 / 10) train acc: 0.285000; val_acc: 0.290000
(Epoch 9 / 10) train acc: 0.311000; val_acc: 0.305000
(Epoch 10 / 10) train acc: 0.326000; val_acc: 0.312000
best accuracy: 0.494
```

12 Test your model!

Run your best model on the validation and test sets. You should achieve above 48% accuracy on the validation set and the test set.

```
[27]: y_val_pred = np.argmax(best_model.loss(data['X_val']), axis=1)
    print('Validation set accuracy: ', (y_val_pred == data['y_val']).mean())

Validation set accuracy: 0.494

[28]: y_test_pred = np.argmax(best_model.loss(data['X_test']), axis=1)
    print('Test set accuracy: ', (y_test_pred == data['y_test']).mean())
```

Test set accuracy: 0.481

12.1 Inline Question 2:

Now that you have trained a Neural Network classifier, you may find that your testing accuracy is much lower than the training accuracy. In what ways can we decrease this gap? Select all that apply.

- 1. Train on a larger dataset.
- 2. Add more hidden units.
- 3. Increase the regularization strength.
- 4. None of the above.

Your Answer:

Your Explanation:

[]:

features

July 26, 2021

```
[]: # This mounts your Google Drive to the Colab VM.
     from google.colab import drive
     drive.mount('/content/drive', force_remount=True)
     # Enter the foldername in your Drive where you have saved the unzipped
     # assignment folder, e.g. 'cs231n/assignments/assignment1/'
     FOLDERNAME = None
     assert FOLDERNAME is not None, "[!] Enter the foldername."
     # Now that we've mounted your Drive, this ensures that
     # the Python interpreter of the Colab VM can load
     # python files from within it.
     import sys
     sys.path.append('/content/drive/My Drive/{}'.format(FOLDERNAME))
     # This downloads the CIFAR-10 dataset to your Drive
     # if it doesn't already exist.
     %cd drive/My\ Drive/$FOLDERNAME/cs231n/datasets/
     !bash get datasets.sh
     %cd /content/drive/My\ Drive/$FOLDERNAME
```

1 Image features exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the assignments page on the course website.

We have seen that we can achieve reasonable performance on an image classification task by training a linear classifier on the pixels of the input image. In this exercise we will show that we can improve our classification performance by training linear classifiers not on raw pixels but on features that are computed from the raw pixels.

All of your work for this exercise will be done in this notebook.

```
[1]: import random import numpy as np from cs231n.data_utils import load_CIFAR10 import matplotlib.pyplot as plt
```

1.1 Load data

Similar to previous exercises, we will load CIFAR-10 data from disk.

```
[2]: from cs231n.features import color_histogram_hsv, hog_feature
     def get_CIFAR10_data(num_training=49000, num_validation=1000, num_test=1000):
         # Load the raw CIFAR-10 data
         cifar10_dir = 'cs231n/datasets/cifar-10-batches-py'
         # Cleaning up variables to prevent loading data multiple times (which may ...
      →cause memory issue)
         trv:
            del X_train, y_train
            del X_test, y_test
            print('Clear previously loaded data.')
         except:
            pass
         X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)
         # Subsample the data
         mask = list(range(num_training, num_training + num_validation))
         X_val = X_train[mask]
         y_val = y_train[mask]
         mask = list(range(num_training))
         X_train = X_train[mask]
         y_train = y_train[mask]
         mask = list(range(num_test))
         X_test = X_test[mask]
         y_test = y_test[mask]
         return X_train, y_train, X_val, y_val, X_test, y_test
```

```
X_train, y_train, X_val, y_val, X_test, y_test = get_CIFAR10_data()
```

1.2 Extract Features

For each image we will compute a Histogram of Oriented Gradients (HOG) as well as a color histogram using the hue channel in HSV color space. We form our final feature vector for each image by concatenating the HOG and color histogram feature vectors.

Roughly speaking, HOG should capture the texture of the image while ignoring color information, and the color histogram represents the color of the input image while ignoring texture. As a result, we expect that using both together ought to work better than using either alone. Verifying this assumption would be a good thing to try for your own interest.

The hog_feature and color_histogram_hsv functions both operate on a single image and return a feature vector for that image. The extract_features function takes a set of images and a list of feature functions and evaluates each feature function on each image, storing the results in a matrix where each column is the concatenation of all feature vectors for a single image.

```
[3]: from cs231n.features import *
     num color bins = 10 # Number of bins in the color histogram
     feature_fns = [hog_feature, lambda img: color_histogram_hsv(img,_
     →nbin=num_color_bins)]
     X_train_feats = extract_features(X_train, feature_fns, verbose=True)
     X val feats = extract features(X val, feature fns)
     X_test_feats = extract_features(X_test, feature_fns)
     # Preprocessing: Subtract the mean feature
     mean_feat = np.mean(X_train_feats, axis=0, keepdims=True)
     X_train_feats -= mean_feat
     X_val_feats -= mean_feat
     X_test_feats -= mean_feat
     # Preprocessing: Divide by standard deviation. This ensures that each feature
     # has roughly the same scale.
     std_feat = np.std(X_train_feats, axis=0, keepdims=True)
     X_train_feats /= std_feat
     X_val_feats /= std_feat
     X_test_feats /= std_feat
     # Preprocessing: Add a bias dimension
     X_train_feats = np.hstack([X_train_feats, np.ones((X_train_feats.shape[0], 1))])
     X_val_feats = np.hstack([X_val_feats, np.ones((X_val_feats.shape[0], 1))])
     X_test_feats = np.hstack([X_test_feats, np.ones((X_test_feats.shape[0], 1))])
```

```
Done extracting features for 1000 / 49000 images
Done extracting features for 2000 / 49000 images
Done extracting features for 3000 / 49000 images
```

```
Done extracting features for 4000 / 49000 images
Done extracting features for 5000 / 49000 images
Done extracting features for 6000 / 49000 images
Done extracting features for 7000 / 49000 images
Done extracting features for 8000 / 49000 images
Done extracting features for 9000 / 49000 images
Done extracting features for 10000 / 49000 images
Done extracting features for 11000 / 49000 images
Done extracting features for 12000 / 49000 images
Done extracting features for 13000 / 49000 images
Done extracting features for 14000 / 49000 images
Done extracting features for 15000 / 49000 images
Done extracting features for 16000 / 49000 images
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Done extracting features for 39000 / 49000 images
Done extracting features for 40000 / 49000 images
Done extracting features for 41000 / 49000 images
Done extracting features for 42000 / 49000 images
Done extracting features for 43000 / 49000 images
Done extracting features for 44000 / 49000 images
Done extracting features for 45000 / 49000 images
Done extracting features for 46000 / 49000 images
Done extracting features for 47000 / 49000 images
Done extracting features for 48000 / 49000 images
Done extracting features for 49000 / 49000 images
```

1.3 Train SVM on features

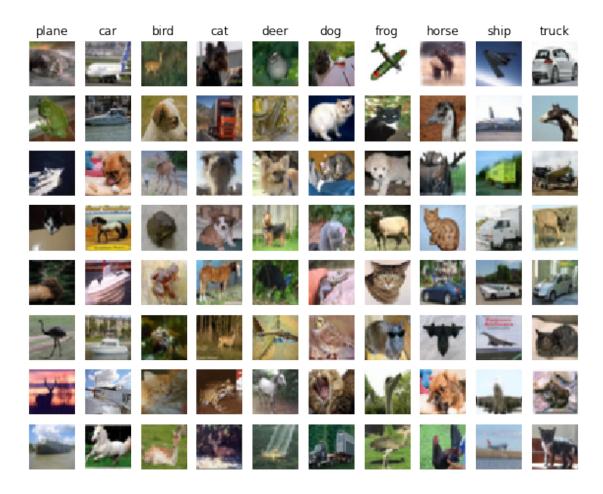
Using the multiclass SVM code developed earlier in the assignment, train SVMs on top of the features extracted above; this should achieve better results than training SVMs directly on top of raw pixels.

```
[7]: # Use the validation set to tune the learning rate and regularization strength
    from cs231n.classifiers.linear_classifier import LinearSVM
    learning rates = [1e-9, 1e-8, 1e-7]
    regularization strengths = [5e4, 5e5, 5e6]
    results = {}
    best_val = -1
    best_svm = None
    # Use the validation set to set the learning rate and regularization strength.
    # This should be identical to the validation that you did for the SVM; save
    # the best trained classifer in best_sum. You might also want to play
    # with different numbers of bins in the color histogram. If you are careful
                                                                           #
    # you should be able to get accuracy of near 0.44 on the validation set.
    # *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) *****
    from itertools import product
    for learning_rate, regularization_strength in product(learning_rates, __
     →regularization_strengths):
        svm = LinearSVM()
        loss_hist = svm.train(X_train_feats, y_train, learning_rate=learning_rate,
                           reg=regularization_strength, num_iters=1500)
        y_train_pred = svm.predict(X_train_feats)
        y_val_pred = svm.predict(X_val_feats)
        train_acc, val_acc = np.mean(y_train == y_train_pred), np.mean(y_val ==_
     →y_val_pred)
        results[(learning_rate, regularization_strength)] = (train_acc, val_acc)
        if val_acc > best_val:
           best_val = val_acc
           best_svm = svm
    # *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
```

```
lr 1.000000e-09 reg 5.000000e+04 train accuracy: 0.100020 val accuracy: 0.090000 lr 1.000000e-09 reg 5.000000e+05 train accuracy: 0.113653 val accuracy: 0.117000 lr 1.000000e-09 reg 5.000000e+06 train accuracy: 0.415306 val accuracy: 0.413000 lr 1.000000e-08 reg 5.000000e+04 train accuracy: 0.119551 val accuracy: 0.134000 lr 1.000000e-08 reg 5.000000e+05 train accuracy: 0.411163 val accuracy: 0.404000 lr 1.000000e-08 reg 5.000000e+06 train accuracy: 0.407347 val accuracy: 0.401000 lr 1.000000e-07 reg 5.000000e+04 train accuracy: 0.414020 val accuracy: 0.415000 lr 1.000000e-07 reg 5.000000e+05 train accuracy: 0.403837 val accuracy: 0.386000 lr 1.000000e-07 reg 5.000000e+06 train accuracy: 0.319082 val accuracy: 0.290000 best validation accuracy achieved: 0.415000
```

0.418

```
[9]: # An important way to gain intuition about how an algorithm works is to
     # visualize the mistakes that it makes. In this visualization, we show examples
     # of images that are misclassified by our current system. The first column
     # shows images that our system labeled as "plane" but whose true label is
     # something other than "plane".
     examples_per_class = 8
     classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', _
     for cls, cls_name in enumerate(classes):
         idxs = np.where((y_test != cls) & (y_test_pred == cls))[0]
        idxs = np.random.choice(idxs, examples_per_class, replace=False)
        for i, idx in enumerate(idxs):
            plt.subplot(examples_per_class, len(classes), i * len(classes) + cls +
      \hookrightarrow 1)
            plt.imshow(X_test[idx].astype('uint8'))
            plt.axis('off')
            if i == 0:
                plt.title(cls name)
     plt.show()
```



1.3.1 Inline question 1:

Describe the misclassification results that you see. Do they make sense?

Your Answer:

1.4 Neural Network on image features

Earlier in this assignment we saw that training a two-layer neural network on raw pixels achieved better classification performance than linear classifiers on raw pixels. In this notebook we have seen that linear classifiers on image features outperform linear classifiers on raw pixels.

For completeness, we should also try training a neural network on image features. This approach should outperform all previous approaches: you should easily be able to achieve over 55% classification accuracy on the test set; our best model achieves about 60% classification accuracy.

```
[10]: # Preprocessing: Remove the bias dimension
# Make sure to run this cell only ONCE
print(X_train_feats.shape)
X_train_feats = X_train_feats[:, :-1]
```

```
X_val_feats = X_val_feats[:, :-1]
     X_test_feats = X_test_feats[:, :-1]
     print(X_train_feats.shape)
    (49000, 155)
    (49000, 154)
[23]: from cs231n.classifiers.fc_net import TwoLayerNet
     from cs231n.solver import Solver
     input_dim = X_train_feats.shape[1]
     hidden_dim = 500
     num classes = 10
     net = TwoLayerNet(input dim, hidden dim, num classes)
     best net = None
     # TODO: Train a two-layer neural network on image features. You may want to
     # cross-validate various parameters as in previous sections. Store your best
     # model in the best_net variable.
     # *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
     from itertools import product
     data = {'X_train': X_train_feats, 'y_train': y_train, 'X_val': X_val_feats,_
     best_accuracy = -1
     solver = Solver(net, data,
                   update_rule='sgd',
                   optim_config={
                      'learning_rate': 9e-3,
                   },
                   lr decay=0.995,
                   num_epochs=75, batch_size=100,
                  print_every=10000)
     solver.train()
     best_net = net
     # learning_rates = [1e-3, 1e-4, 1e-5]
     # for learning_rate in learning_rates:
         solver = Solver(net, data,
                        update_rule='sqd',
```

```
#
                      optim_config={
#
                           'learning_rate': learning_rate,
#
                      },
#
                      num_epochs=20,
#
                      print_every=10000)
#
      solver.train()
#
      if solver.val_acc_history[-1] > best_accuracy:
          best net = net
          best_accuracy = solver.val_acc_history[-1]
# print(f'best accuracy:', best_accuracy)
# *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
```

```
(Iteration 1 / 36750) loss: 2.302588
(Epoch 0 / 75) train acc: 0.113000; val_acc: 0.129000
(Epoch 1 / 75) train acc: 0.116000; val_acc: 0.093000
(Epoch 2 / 75) train acc: 0.238000; val_acc: 0.211000
(Epoch 3 / 75) train acc: 0.272000; val_acc: 0.277000
(Epoch 4 / 75) train acc: 0.310000; val acc: 0.332000
(Epoch 5 / 75) train acc: 0.371000; val_acc: 0.375000
(Epoch 6 / 75) train acc: 0.405000; val_acc: 0.408000
(Epoch 7 / 75) train acc: 0.467000; val_acc: 0.435000
(Epoch 8 / 75) train acc: 0.472000; val_acc: 0.452000
(Epoch 9 / 75) train acc: 0.481000; val_acc: 0.481000
(Epoch 10 / 75) train acc: 0.503000; val_acc: 0.492000
(Epoch 11 / 75) train acc: 0.498000; val acc: 0.496000
(Epoch 12 / 75) train acc: 0.497000; val_acc: 0.504000
(Epoch 13 / 75) train acc: 0.523000; val_acc: 0.507000
(Epoch 14 / 75) train acc: 0.522000; val_acc: 0.509000
(Epoch 15 / 75) train acc: 0.490000; val_acc: 0.511000
(Epoch 16 / 75) train acc: 0.532000; val_acc: 0.512000
(Epoch 17 / 75) train acc: 0.541000; val_acc: 0.516000
(Epoch 18 / 75) train acc: 0.573000; val_acc: 0.516000
(Epoch 19 / 75) train acc: 0.551000; val_acc: 0.513000
(Epoch 20 / 75) train acc: 0.529000; val_acc: 0.514000
(Iteration 10001 / 36750) loss: 1.360653
(Epoch 21 / 75) train acc: 0.539000; val_acc: 0.521000
(Epoch 22 / 75) train acc: 0.524000; val_acc: 0.528000
(Epoch 23 / 75) train acc: 0.527000; val_acc: 0.524000
(Epoch 24 / 75) train acc: 0.545000; val_acc: 0.525000
(Epoch 25 / 75) train acc: 0.529000; val acc: 0.535000
(Epoch 26 / 75) train acc: 0.534000; val_acc: 0.529000
(Epoch 27 / 75) train acc: 0.546000; val acc: 0.528000
(Epoch 28 / 75) train acc: 0.531000; val_acc: 0.531000
(Epoch 29 / 75) train acc: 0.557000; val_acc: 0.535000
```

```
(Epoch 30 / 75) train acc: 0.579000; val_acc: 0.534000
(Epoch 31 / 75) train acc: 0.571000; val_acc: 0.539000
(Epoch 32 / 75) train acc: 0.563000; val_acc: 0.536000
(Epoch 33 / 75) train acc: 0.554000; val_acc: 0.538000
(Epoch 34 / 75) train acc: 0.556000; val acc: 0.542000
(Epoch 35 / 75) train acc: 0.568000; val_acc: 0.541000
(Epoch 36 / 75) train acc: 0.552000; val acc: 0.541000
(Epoch 37 / 75) train acc: 0.572000; val_acc: 0.547000
(Epoch 38 / 75) train acc: 0.572000; val_acc: 0.543000
(Epoch 39 / 75) train acc: 0.600000; val_acc: 0.552000
(Epoch 40 / 75) train acc: 0.592000; val_acc: 0.548000
(Iteration 20001 / 36750) loss: 1.198848
(Epoch 41 / 75) train acc: 0.585000; val_acc: 0.556000
(Epoch 42 / 75) train acc: 0.576000; val_acc: 0.551000
(Epoch 43 / 75) train acc: 0.571000; val_acc: 0.556000
(Epoch 44 / 75) train acc: 0.576000; val_acc: 0.555000
(Epoch 45 / 75) train acc: 0.578000; val_acc: 0.556000
(Epoch 46 / 75) train acc: 0.586000; val_acc: 0.555000
(Epoch 47 / 75) train acc: 0.602000; val_acc: 0.562000
(Epoch 48 / 75) train acc: 0.602000; val acc: 0.559000
(Epoch 49 / 75) train acc: 0.588000; val_acc: 0.564000
(Epoch 50 / 75) train acc: 0.564000; val acc: 0.564000
(Epoch 51 / 75) train acc: 0.616000; val_acc: 0.554000
(Epoch 52 / 75) train acc: 0.581000; val_acc: 0.561000
(Epoch 53 / 75) train acc: 0.567000; val_acc: 0.562000
(Epoch 54 / 75) train acc: 0.594000; val_acc: 0.560000
(Epoch 55 / 75) train acc: 0.603000; val_acc: 0.567000
(Epoch 56 / 75) train acc: 0.602000; val_acc: 0.570000
(Epoch 57 / 75) train acc: 0.574000; val_acc: 0.575000
(Epoch 58 / 75) train acc: 0.614000; val_acc: 0.572000
(Epoch 59 / 75) train acc: 0.619000; val_acc: 0.569000
(Epoch 60 / 75) train acc: 0.621000; val_acc: 0.574000
(Epoch 61 / 75) train acc: 0.628000; val_acc: 0.575000
(Iteration 30001 / 36750) loss: 1.212492
(Epoch 62 / 75) train acc: 0.616000; val acc: 0.580000
(Epoch 63 / 75) train acc: 0.626000; val acc: 0.587000
(Epoch 64 / 75) train acc: 0.629000; val acc: 0.578000
(Epoch 65 / 75) train acc: 0.629000; val_acc: 0.584000
(Epoch 66 / 75) train acc: 0.623000; val_acc: 0.575000
(Epoch 67 / 75) train acc: 0.605000; val_acc: 0.581000
(Epoch 68 / 75) train acc: 0.632000; val_acc: 0.587000
(Epoch 69 / 75) train acc: 0.613000; val_acc: 0.584000
(Epoch 70 / 75) train acc: 0.636000; val_acc: 0.586000
(Epoch 71 / 75) train acc: 0.652000; val_acc: 0.593000
(Epoch 72 / 75) train acc: 0.632000; val_acc: 0.592000
(Epoch 73 / 75) train acc: 0.628000; val_acc: 0.587000
(Epoch 74 / 75) train acc: 0.643000; val_acc: 0.588000
(Epoch 75 / 75) train acc: 0.659000; val_acc: 0.584000
```

```
[24]: # Run your best neural net classifier on the test set. You should be able
# to get more than 55% accuracy.

y_test_pred = np.argmax(best_net.loss(X_test_feats), axis=1)
test_acc = (y_test_pred == y_test).mean()
print(test_acc)
```

0.565