ast 389: Homework 2: Balancing the atlas Humanoid Junette Hsin

Question 1:

$$\frac{1}{2} \begin{bmatrix} w_{1} \| J_{1}\ddot{q} + J_{1}\dot{q}_{m} - \ddot{x}_{1}^{d} \|^{2} + \lambda_{q} \| \ddot{q} \|^{2} + \lambda_{f} \| f_{r} \|^{2} \\
 + \frac{1}{2} [\ddot{q} f_{r}] \begin{bmatrix} A & 0 \\ 0 & B \end{bmatrix} [\ddot{q}] + \begin{bmatrix} \alpha_{1}^{T} [\ddot{q}] \\ 0 \end{bmatrix}^{2} [\ddot{q}_{r}] \\
 + w_{1} (J_{1}\ddot{q}^{2} + J_{1}\ddot{q}) \ddot{q}_{m} - J_{1}\ddot{q}_{n}^{2} d + J_{2}\ddot{q}_{m}^{2} - J_{1}\dot{q}_{m}^{2} \ddot{x}_{1}^{d} + \ddot{x}_{1}^{d^{2}}) + \dots \\
 + w_{1} \ddot{q}^{T} J_{1}\ddot{J}_{1}\ddot{q} + w_{2} \ddot{q}^{T} J_{2}\ddot{J}_{2}\ddot{q} + \dots \\
 + \ddot{q}^{T} (w_{1}J_{1}\ddot{J}_{1} + w_{2}J_{2}\ddot{J}_{2} + \dots) \ddot{q} = \ddot{q}^{T} (\frac{1}{2}A) \ddot{q} \\
 A = w_{1} J_{1}\ddot{J}_{1} + w_{2} J_{2}\ddot{J}_{2} + \dots w_{n}J_{n}\ddot{J}_{n} + \lambda_{q} \\
 2w_{1} [(\dot{q}_{1}^{T} J_{1}^{T} J_{1} - \ddot{x}_{1}^{d} J_{1}) + (\dot{q}_{2}^{T} J_{2}^{T} J_{2} - \chi_{2}^{d} J_{2}) + \dots] \ddot{q} \\
 a = 2w_{1} [(\dot{q}_{1}^{T} J_{1}^{T} J_{1} - \chi_{1}^{d} J_{1}) + (\dot{q}_{2}^{T} J_{2}^{T} J_{2} - \chi_{2}^{d} J_{2}) + \dots \\
 - \dots + (\dot{q}_{n}^{T} J_{n}^{T} J_{1} - \chi_{n}^{d} J_{n})]$$

Question 2:

$$A\ddot{q} + b + g = \begin{bmatrix} 0 & 6 \times 1 \\ T & \text{cmol} \end{bmatrix} + J_{c}^{T} fr \qquad \downarrow \qquad \begin{bmatrix} C & D \end{bmatrix} \begin{bmatrix} \ddot{q} \\ Fr \end{bmatrix} = C$$

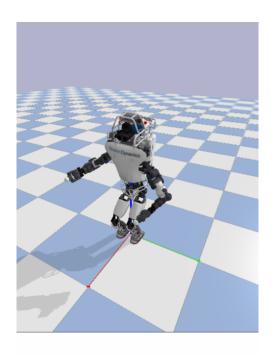
$$A\ddot{q} - J_{c}^{T} fr = \begin{bmatrix} 0 & 6 \times 1 \\ T & \text{cmol} \end{bmatrix} - b - g \qquad \downarrow \qquad C\ddot{q} + Dfr = C$$

$$C = A$$

$$D = -J_{c}$$

$$C = \begin{bmatrix} 0 & 6\pi & 1 \\ T & cnd \end{bmatrix} - b - g$$

Running Otles simulation in pybullet:



Citles remains standing and balanced

```
yaw=120.00 Status: OK

Vendor = VMware, Inc.
Renderer = llympipe (LLVM 10.0.0, 128 bits)
b3Printf: Selected demo: Physics Server
startThreads creating 1 threads.
starting thread 0
started thread 0
MotionThreadFunc thread started
ven = VMware, Inc.

[WalkingState] STAND
ven = VMware, Inc.
[WalkingState] BALANCE
```