

- For a given  $\ddot{\phi}_{max}$  and  $\dot{\phi}_{max}$ , there is a threshold slew angle  $\phi_T$  that determines whether the slew will have a period of coasting. The threshold slew angle is found by:

$$\phi_T = \frac{(\dot{\phi}_{max})^2}{\ddot{\phi}_{max}} \quad (1)$$

- Using the conditions,  $\dot{\phi}(t_1) = \dot{\phi}_{max}$ ,  $\dot{\phi}(t_f) = \dot{\phi}_f$ ,  $\phi(t_f) = \phi_f$ , the switching times can be determined as follows.
- If  $\phi_f < \phi_T$ , the switching times  $t_1$  and final time  $t_f$  are determined thus:

$$t_f = \sqrt{\frac{4\phi_f}{\ddot{\phi}_{max}}} \quad (2)$$

$$t_1 = \frac{t_f}{2} \quad (3)$$

- If  $\phi_f > \phi_T$ , then the slew will have a period of coasting with constant  $\dot{\phi}(t)$ . The switching times  $t_1$ ,  $t_2$ , and final time  $t_f$  are then calculated as:

$$t_1 = t_0 + \frac{\dot{\phi}_{max} - \dot{\phi}_0}{\ddot{\phi}_{max}}, \quad (4)$$

$$t_2 = t_1 + \frac{1}{\dot{\phi}_{max}} \left[ \phi_f - \dot{\phi}_0(t_1 - t_0) - \frac{1}{2} \ddot{\phi}_{max}(t_1 - t_0)^2 - \frac{\dot{\phi}_{max}(\dot{\phi}_{max} - \dot{\phi}_f)}{\ddot{\phi}_{max}} + \frac{(\dot{\phi}_{max} - \dot{\phi}_f)^2}{2\ddot{\phi}_{max}} \right], \quad (5)$$

$$t_f = t_2 - \frac{\dot{\phi}_f - \dot{\phi}_{max}}{\ddot{\phi}_{max}} \quad (6)$$