## $SL(2,\mathbb{R})$ as anti-de Sitter Space

**Introduction:** As we've seen in the lectures, de Sitter and anti-de Sitter space aren't geodesically connected. More precisely, we looked at the geodesics starting at one fixed point p and saw that they missed parts of the space. Another way to put this is that the exponential map  $\exp_p$  isn't surjective.

There is also a (related but different) concept of exponential maps for Lie groups. A standard example of a Lie group whose exponential map isn't surjective is  $SL(2,\mathbb{R})$  – this can be shown directly with some linear algebra<sup>1</sup>.

Our goal here is to show that these two examples of non-surjective exponential maps are in fact one and the same:  $SL(2,\mathbb{R})$  admits a Lorentzian metric making it isometric to 3-dimensional anti-de Sitter space, and the geodesics starting at the unit matrix  $I \in SL(2,\mathbb{R})$  are precisely the one-parameter subgroups.

**A Lorentzian metric on**  $SL(2,\mathbb{R})$ : As in the construction of anti-de Sitter space, we start with a surrounding vector space, the space  $M_2(\mathbb{R})$  of  $2 \times 2$  real matrices. We want to provide  $M_2(\mathbb{R})$  with a semi-Riemannian metric, and since it's a vector space, a scalar product will do. Even simpler than that, we can look for a quadratic form on  $M_2(\mathbb{R})$ , and soon find a very natural one: the determinant  $\det: M_2(\mathbb{R}) \to \mathbb{R}$ ,  $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \mapsto ad - bc$ .

Like any quadratic form, det is represented by a symmetric matrix (with respect to the standard basis), which we can diagonalize. Here we get

$$\begin{pmatrix} & & & 1 \\ & & -1 & \\ & -1 & & \\ 1 & & & \end{pmatrix} = S \begin{pmatrix} -1 & & & \\ & -1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} S^t,$$

where

$$S = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \end{pmatrix} \in O(4).$$

This shows that det corresponds to an index 2 scalar product b (i. e. det(X) = b(X, X)) such that S yields an isometry  $(M_2(\mathbb{R}), b) \cong \mathbb{R}_2^4$ .

Recall that we defined anti-de Sitter space as the Lorentzian submanifold of  $\mathbb{R}^4_2$  consisting of all vectors  $x \in \mathbb{R}^4_2$  with  $||x||^2 = 1$ . Under our isometry,

<sup>&</sup>lt;sup>1</sup>See e.g. the question part in this thread.

these correspond to matrices of determinant 1. We conclude that  $SL(2,\mathbb{R})$  is a Lorentzian submanifold of  $M_2(\mathbb{R})$  isometric to 3-dimensional anti-de Sitter space.

One-parameter subgroups are geodesics: Now that we have a Lie group with a Lorentzian structure, it's very tempting to compare the exponential maps<sup>2</sup>. Both are maps  $\mathfrak{sl}(2,\mathbb{R}) \to SL(2,\mathbb{R})$ , and both are defined via certain curves: geodesics for the semi-Riemannian exponential, and one-parameter subgroups for the Lie group one. Therefore, we can restrict our attention to these curves.

Before we get started, we observe that the metric g on  $SL(2,\mathbb{R})$  induced by b is left-invariant. That is, we have

$$q(L_X, L_Y) = b(X, Y), \quad \forall X, Y \in \mathfrak{sl}(2, \mathbb{R}),$$

where  $L_X$  denotes the left-invariant vector field induced by X. An easy way to see this is to observe that multiplication by  $A \in SL(2,\mathbb{R})$  preserves the determinant:

$$\det(AB) = \det(A) \det(B) = \det(B), \quad \forall B \in M_2(\mathbb{R}).$$

By polarisation, it also preserves b, so we have

$$g(L_X, L_Y)(A) = b(AX, AY) = b(X, Y), \quad \forall A \in SL(2, \mathbb{R}).$$

Now let  $X \in \mathfrak{sl}(2,\mathbb{R})$ , and write  $c:\mathbb{R} \to SL(2,\mathbb{R})$  for the induced one-parameter subgroup:  $c(t) = \operatorname{Fl}_t^{L_X}(I)$ . We want to show that  $c' = L_X \circ c \in \mathfrak{X}(c)$  is parallel. We have

$$(L_X \circ c)'(t) = \nabla_{c'(t)} L_X = (\nabla_{L_X} L_X)(c(t)),$$

so it's sufficient to prove  $\nabla_{L_X} L_X = 0$ .

Clearly, it's enough to show  $g(\nabla_{L_X} L_X, L_Y) = 0$  for all  $Y \in \mathfrak{sl}(2, \mathbb{R})$ . By the Koszul formula, and the fact that  $g(L_X, L_Y)$  is constant, we get

$$2g(\nabla_{L_X} L_X, L_Y) = 0 + 0 - 0 - g(L_X, [L_X, L_Y]) + g(L_X, [L_Y, L_X]) + 0$$

$$= 2g(L_X, [L_Y, L_X])$$

$$= 2g(L_X, L_{[Y,X]})$$

$$= 2b(X, [Y, X]).$$

Hence, c is a geodesic iff b(X, [Y, X]) = 0 for all  $Y \in \mathfrak{sl}(2, \mathbb{R})$ . This can probably be checked by a brute-force computation, but let's do it more conceptually: First, we rewrite [Y, X] as  $\mathrm{ad}_Y(X)$ . This of course is just a change of notation, but in the form  $b(X, \mathrm{ad}_Y(X)) = 0$ , we see that the identity would follow from  $\mathrm{ad}_Y$  being skew-adjoint with respect to b. But that means that ad should map into  $\mathfrak{so}(\mathfrak{sl}(2, \mathbb{R}), b)$ , which is equivalent to Ad mapping into  $SO(\mathfrak{sl}(2, \mathbb{R}), b)$ . This

 $<sup>^{2}</sup>$ based at I in the semi-Riemannian case

is the case precisely if  $Ad_A$  respects the scalar product – or equivalently the quadratic form – on  $\mathfrak{sl}(2,\mathbb{R})$ , for all  $A \in SL(2,\mathbb{R})$ , i. e.

$$\det(\operatorname{Ad}_A(Z)) \stackrel{!}{=} \det(Z), \quad \forall Z \in \mathfrak{sl}(2,\mathbb{R}).$$

But in this matrix group setting we have the simple formula  $Ad_A(Z) = AZA^{-1}$ . Conjugation clearly preserves the determinant<sup>3</sup>, so the above identity is true.

We conclude that  $\nabla_{L_X} L_X = 0$  for arbitrary  $X \in \mathfrak{sl}(2,\mathbb{R})$ , and from this that all one-parameter subgroups are geodesics. This already exhausts all possible geodesics at I, since they are uniquely determined by their initial tangent vector. Thus, the geodesics based at I are precisely the one-parameter subgroups. In particular, the two exponential maps are equal.

Personally, I think of this as a nice explanation for why  $\exp:\mathfrak{sl}(2,\mathbb{R}) \to SL(2,\mathbb{R})$  isn't surjective – the non-surjectivity seems much clearer (certainly easier to visualize) in the Lorentzian setting.

 $<sup>^3{\</sup>rm Conjugation}$  with a determinant 1 matrix preserves it even more. ©