

# Michael Belyaev

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Mathematics student looking for an internship combining mathematics and computer science, with a focus on machine learning and deep learning.

## EDUCATION

**University of Edinburgh** Sep. 2022 - May 2027  
*Mathematics MMath (Integrated Masters)* *Averaging a first (80%)*

**Relevant Courses:** Introduction to Algorithms and Data Structures, Machine Learning, Probability, Stochastic Modeling, Foundations of Data Science, Statistics

## PROGRAMMING SKILLS

- **Programming Languages:** Proficient in **Python**; Experience with **Haskell, Rust**
- **Libraries and Tools:** Git/GitHub, PyTorch, LaTeX

## EXPERIENCE

**LFCS Summer Research Intern** Jun. 2025 - Jul. 2025  
*University of Edinburgh*

- Researched using syntax-guided synthesis (SyGuS) to automatically generate hardware logic for low-precision arithmetic.
- Synthesised an efficient and accurate multiplier and adder for the MXInt data format.

**School of Informatics Research Intern** Jun. 2024 - Aug. 2024  
*University of Edinburgh*

- Implemented and benchmarked dimensionality reduction techniques, including random projections and Locality Sensitive Hashing (LSH), to evaluate performance trade-offs for approximate k-NN search.

**Demonstrator/Marker/Tutor** Sep. 2023 - Nov. 2024  
*University of Edinburgh*

- Taught 8 undergraduate students, leading tutorials and grading assignments for Introduction to Computation (Haskell) and Introduction to Data Structures and Algorithms (Python).

## PROJECTS

**Neural Field Optimization** Jun. 2025 - Aug. 2025  

- Supervised research project exploring the robustness and performance of optimization techniques for neural fields.
- Experimented with fine-tuning training parameters to reduce artifacts in surface reconstruction.

**HYPED Software Team** Sep. 2023 - Jun. 2025  
*University of Edinburgh Hyperloop Team*

- **Localisation Project Manager** — Jan. 2024 - Jun. 2025
- **Localisation Subteam Member** — Sep. 2023 - Jan. 2024
- Led a team developing the pod's real-time state estimation, designing and implementing the localisation system's sensor fusion.
- Engineered a Kalman filter to fuse accelerometer and optical flow data, achieving position estimates with <1% error against ground-truth.
- Ported old code from C++ to Rust.

## AWARDS AND ACHIEVEMENTS

- Scottish Mathematical Challenge Gold in 2020 and Silver in 2021.
- Gold in the Senior UKMT.