

Detection of Temporary Disorders

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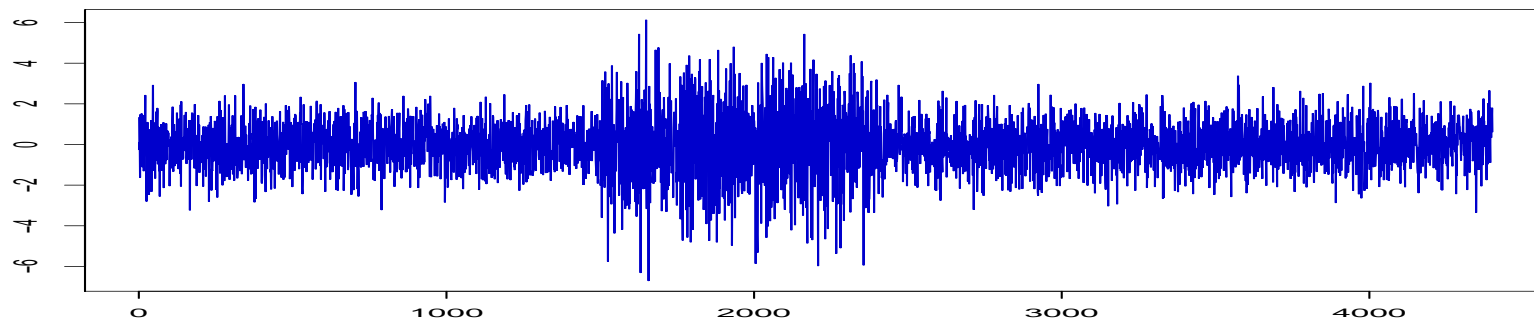
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Introduction: Transient changes

The distribution eventually returns to the initial form,

$$\begin{cases} X_1, \dots, X_a \sim F \\ X_{a+1}, \dots, X_b \sim G \\ X_{b+1}, \dots, X_n \sim F \end{cases}$$



Goals: Detect the change; estimate a and b .

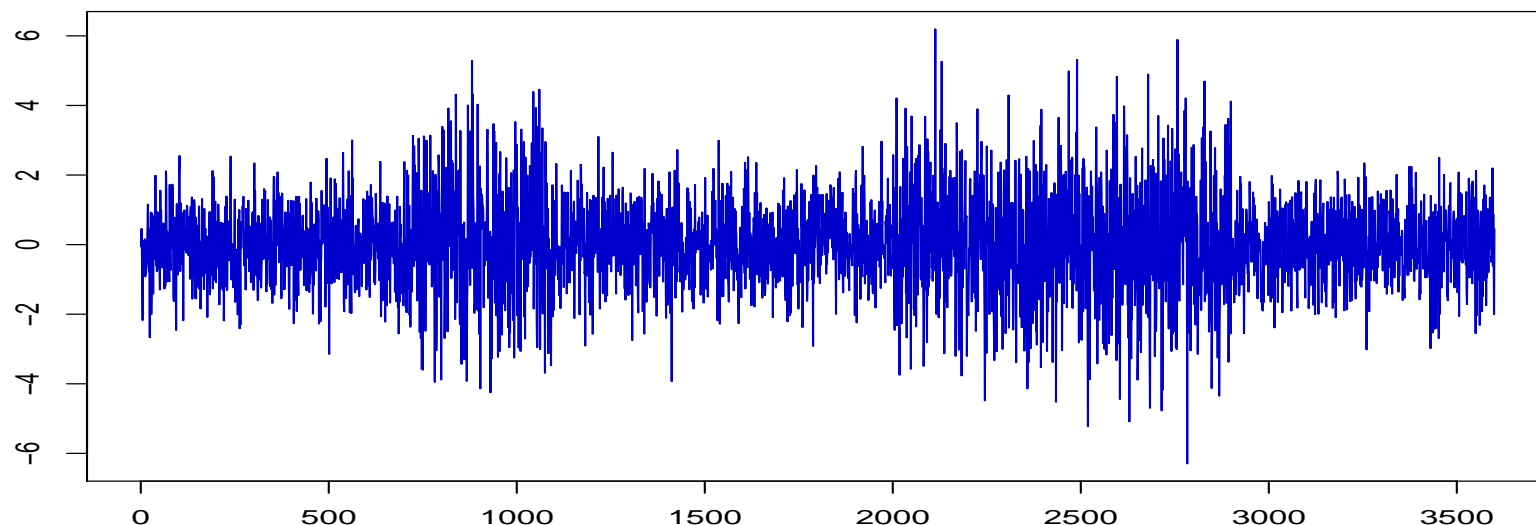
Tartakovsky (1987), Repin (1991), Guépié et al (2012),
Noonan and Zhigljavsky (2020), Tartakovsky et al (2021)

Transient changes may reappear at unknown moments,

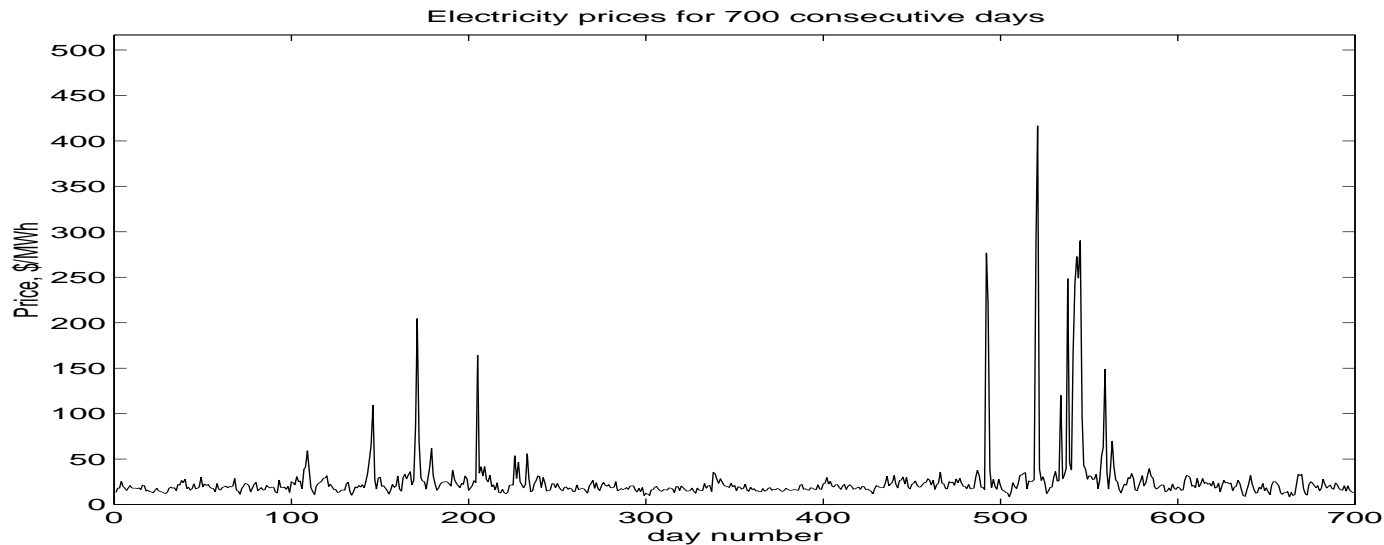
$$\left\{ \begin{array}{l} X_{0:a_1} = X_1, \dots, X_{a_1} \sim F \\ X_{a_1:b_1} = X_{a_1+1}, \dots, X_{b_1} \sim G \\ X_{b_1:a_2} = X_{b_1+1}, \dots, X_{a_2} \sim F \\ X_{a_2:b_2} = X_{a_2+1}, \dots, X_{b_2} \sim G \\ \dots \quad \quad \quad \dots \quad \quad \dots \\ X_{b_K:n} = X_{b_K+1}, \dots, X_n \sim F \end{array} \right.$$

Goals:

- Detect all changes
- estimate all a_k and b_k
- control familywise false alarm rates



Applications: Deregulated Energy Markets



Goals:

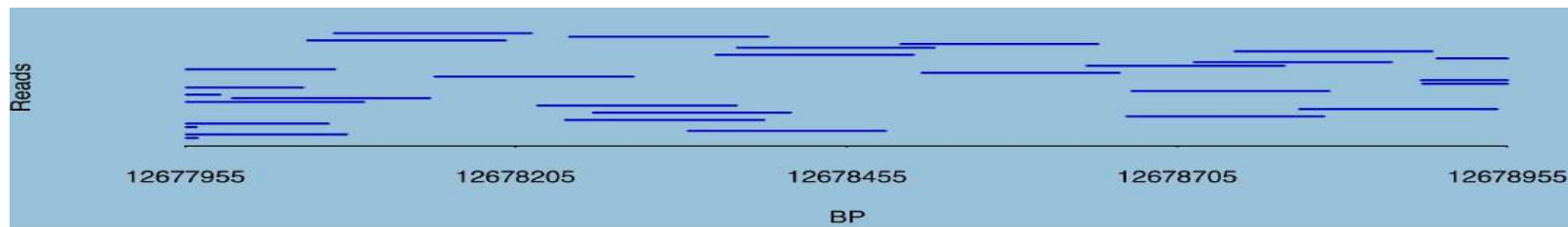
(a) Working stochastic model \Rightarrow Monte Carlo simulation study \Rightarrow valuation of energy derivatives.

(b) Forecast; predictive distribution of electricity prices for any given day.

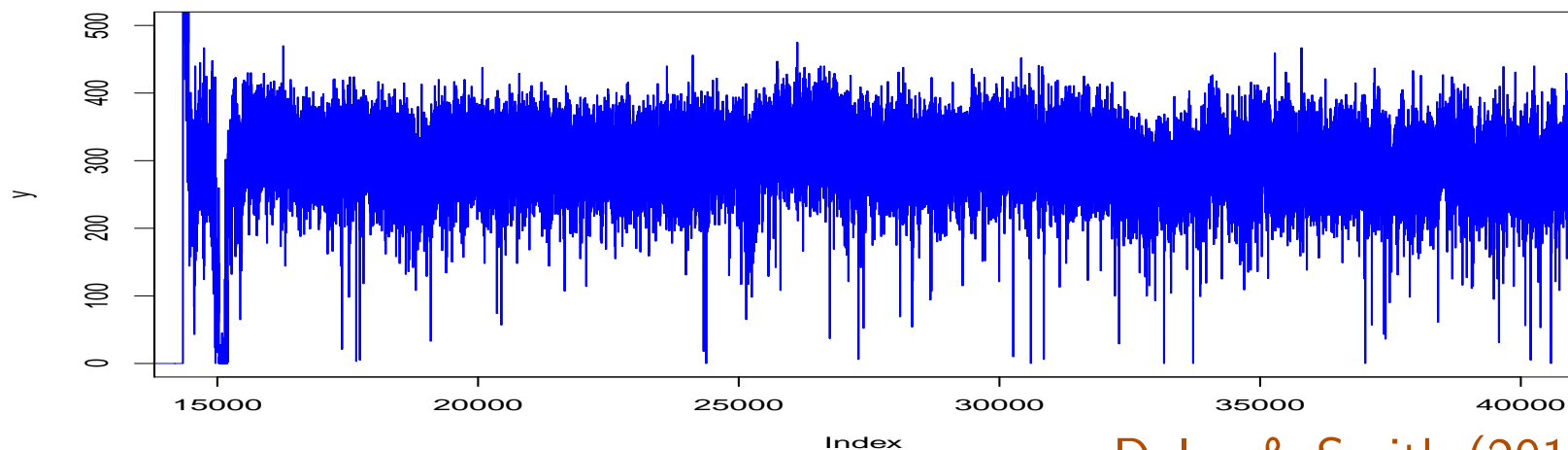
Baron et al (2001)

Applications: Genome coverage process

Reads attach to a chromosome at random locations.



Shifts occur in the coverage depth.



Daley & Smith (2014)

Other Applications

- ▶ Industrial process control
- ▶ Signal processing
- ▶ Image processing
- ▶ Target tracking

One transient change: maximum likelihood estimation

For $\theta = (a, b)$, the log-likelihood is

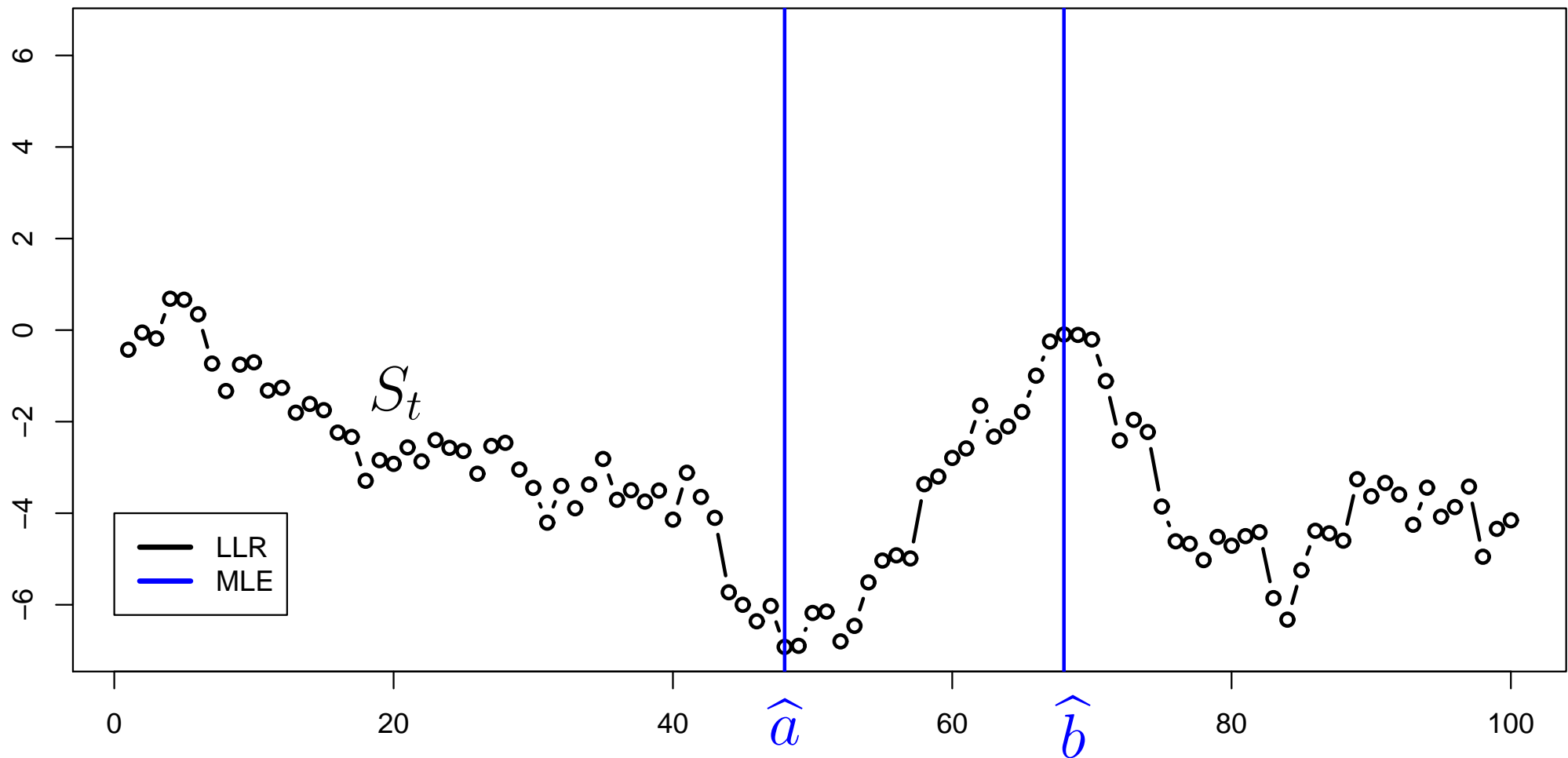
$$\begin{aligned} L(X; \theta) &= \sum_{i=1}^a \log f(X_i) + \sum_{i=a+1}^b \log g(X_i) + \sum_{i=b+1}^n \log f(X_i) \\ &\cong \sum_{i=a+1}^b \log \frac{g(X_i)}{f(X_i)} \end{aligned}$$

Hence, the MLE of θ is $\hat{\theta} = (\hat{a}, \hat{b}) = \arg \max_{a \leq b} (S_b - S_a)$, where $S_t = \sum_{i=1}^t \log \frac{g}{f}(X_i)$

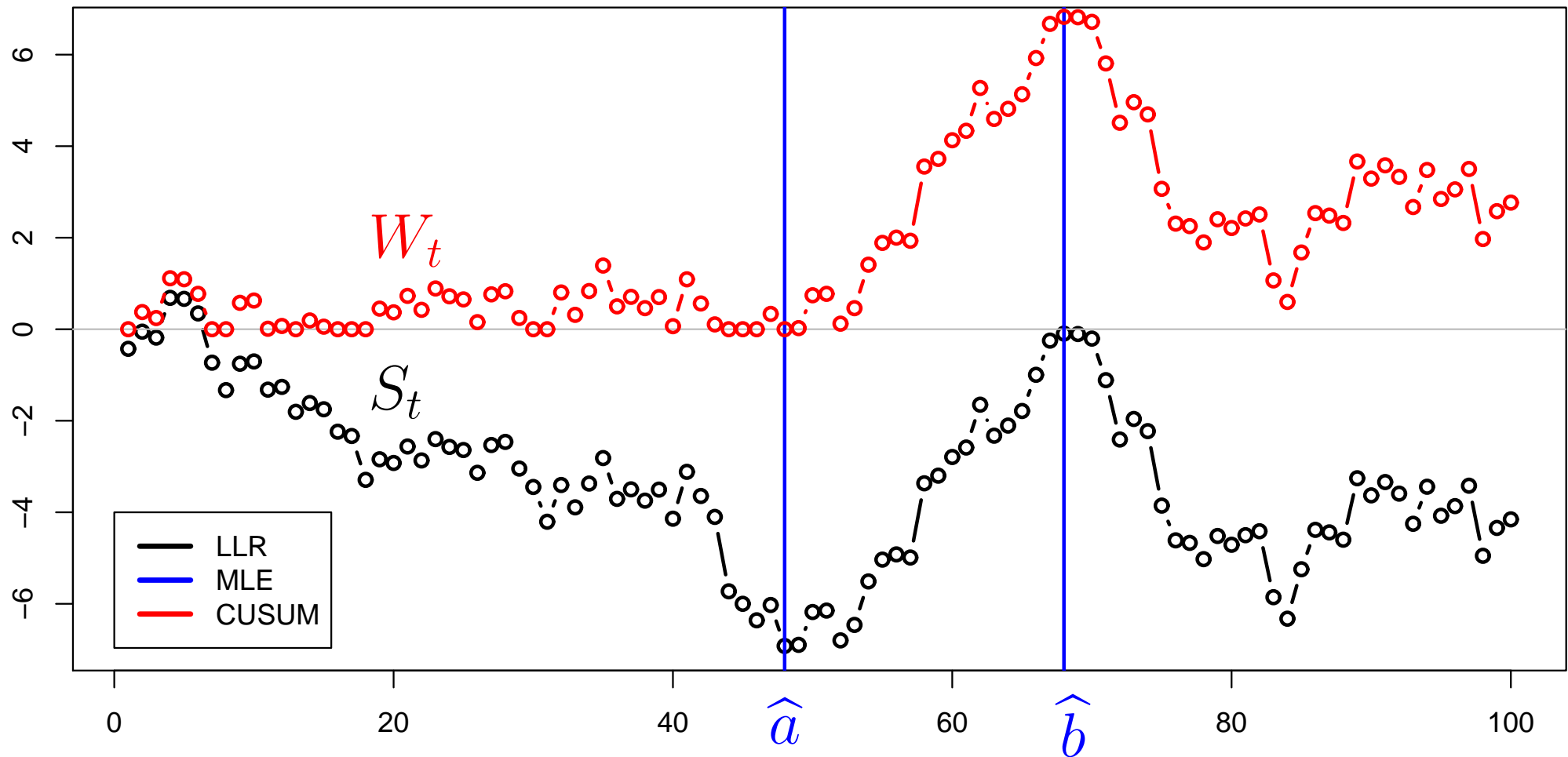
In terms of the CUSUM process $W_t = S_t - \min_{i \leq t} S_i$ with $\text{Ker}(W) = \{t : W_t = 0\}$,

$$\hat{b} = \arg \max W_t, \quad \hat{a} = \max \left\{ \text{Ker}(W) \cap [0, \hat{b}) \right\}$$

LLR random walk and MLE



LLR random walk, CUSUM process, and MLE



Control of the false alarm rate

Decide between $K = 0$ (no change) and $K = 1$ (one change)?

- ▶ Testing

$$H_0 : \begin{array}{l} K = 0 \\ \text{all } \mathbf{X}_{0:n} \sim F \end{array} \quad \text{vs} \quad H_1 : \begin{array}{l} K = 1 \\ \mathbf{X}_{a:b} \sim G \text{ for some } a, b \end{array}$$

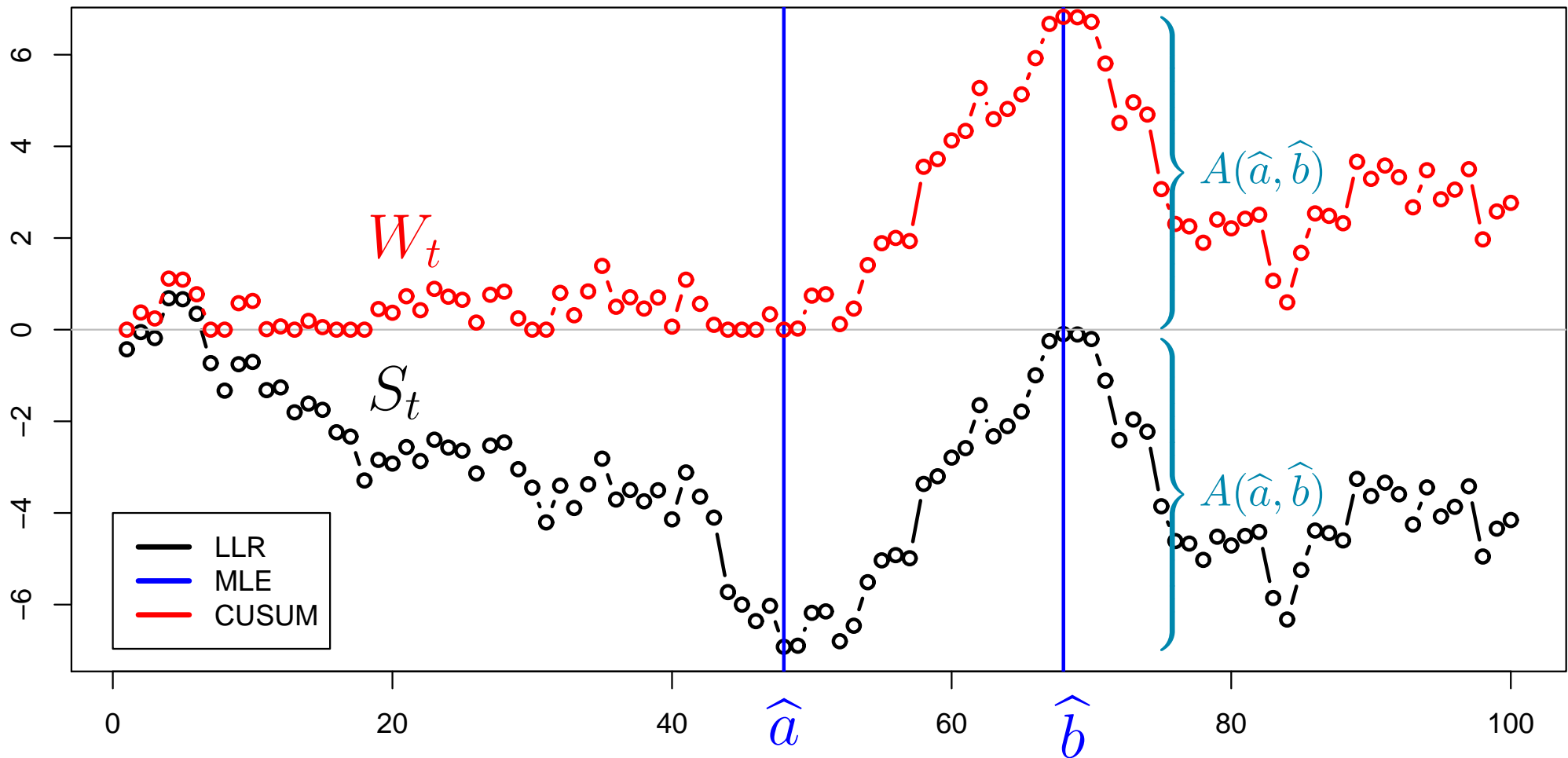
where $\mathbf{X}_{k:m} := (X_{k+1}, \dots, X_m)$.

- ▶ The log-likelihood ratio test statistic is

$$\Lambda = \log \frac{\max_{a < b} f(\mathbf{X}_{0:a})g(\mathbf{X}_{a,b})f(\mathbf{X}_{b:n})}{f(\mathbf{X}_{0:n})} = A(\hat{a}, \hat{b})$$

- ▶ Reject H_0 in favor of H_1 if $\Lambda \geq h$ for some *threshold* h , which controls the balance between the sensitivity and the rate of false alarms.

LLR random walk, CUSUM process, and MLE



Control of the false alarm rate

- By the Doob's maximal inequality,

$$\mathbb{P}_{H_0}\left\{\max_{0 \leq t \leq n} W_t \geq h\right\} = \mathbb{P}_F\left\{\max_{0 \leq t \leq n} e^{W_t} \geq e^h\right\} \leq e^{-h} \mathbb{E}_F(e^{W_n})$$

- Hence, the threshold $h = -\log \frac{\alpha}{\mathbb{E}_F(e^{W_n})}$ for the increment

$$A(\hat{a}, \hat{b}) = S_{\hat{b}} - S_{\hat{a}} = \max_{0 \leq t \leq n} W_t$$

controls the false alarm rate at level α ,

$$\mathbb{P}\{\text{false alarm}\} = \mathbb{P}\{\text{Type I error}\} = \mathbb{P}_F\{A(\hat{a}, \hat{b}) \geq h\} \leq \alpha.$$

- Report a change-point if $A(\hat{a}, \hat{b}) \geq h$.

Known number of changes: maximum likelihood estimation

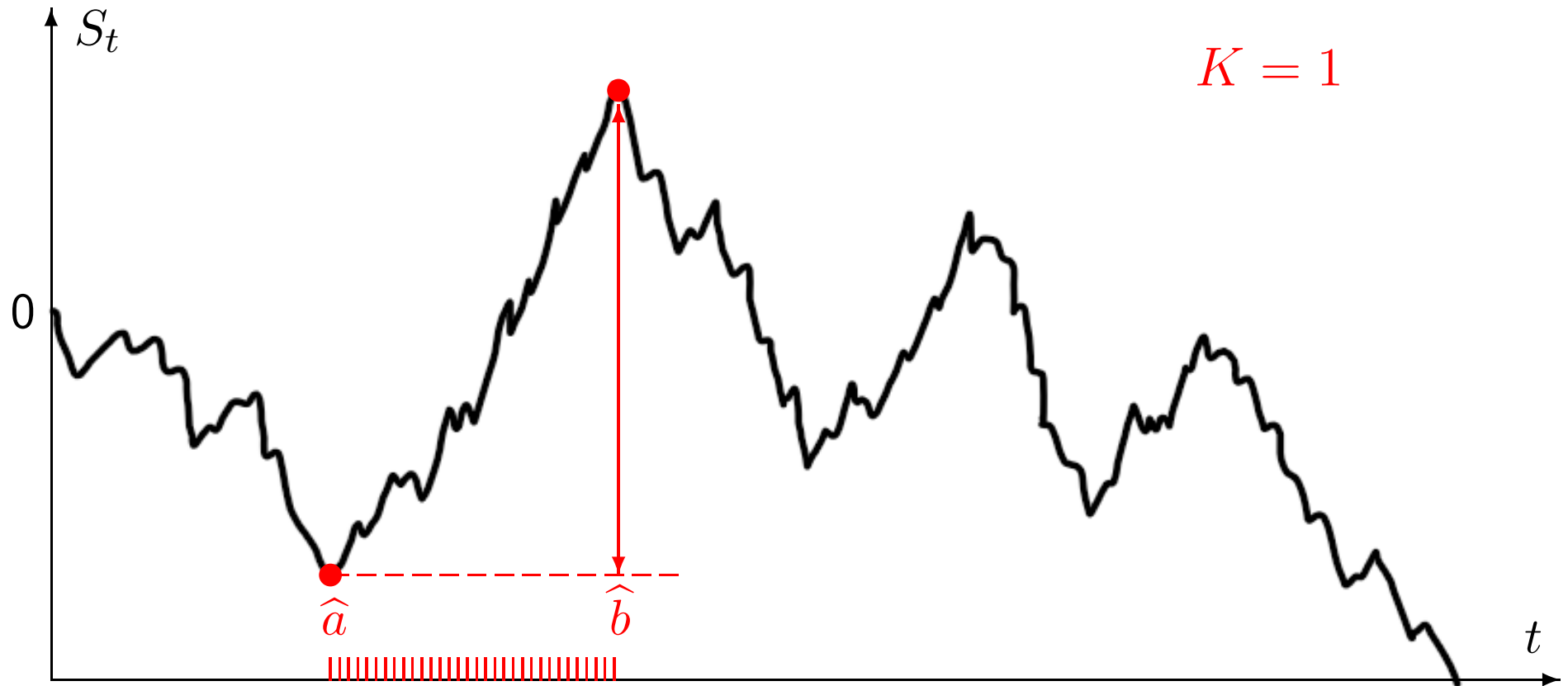
For $\theta = \{(a_k, b_k), k = 1, \dots, K\}$, K known, the log-likelihood is

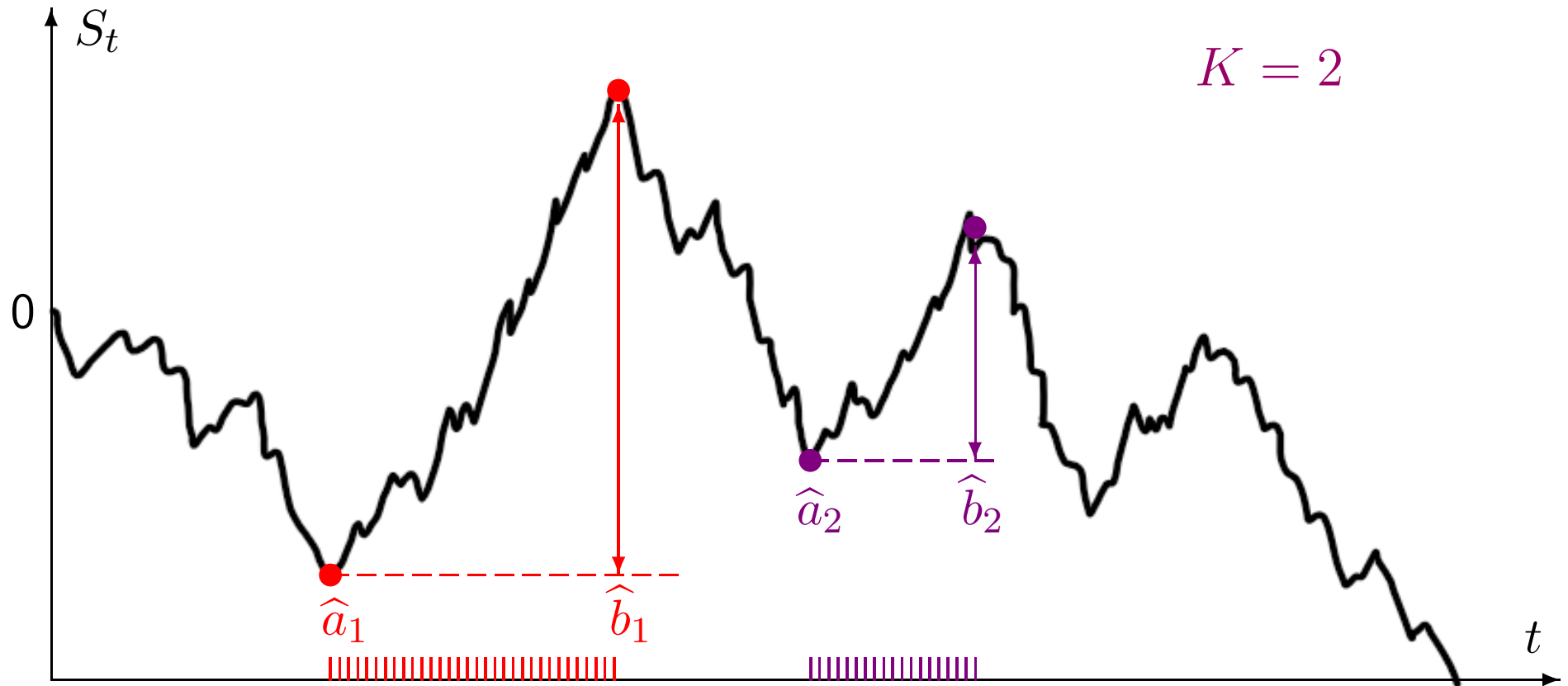
$$L(X; \theta) = \sum_{k=1}^K \sum_{i=a_k+1}^{b_k} \log \frac{g(X_i)}{f(X_i)}$$

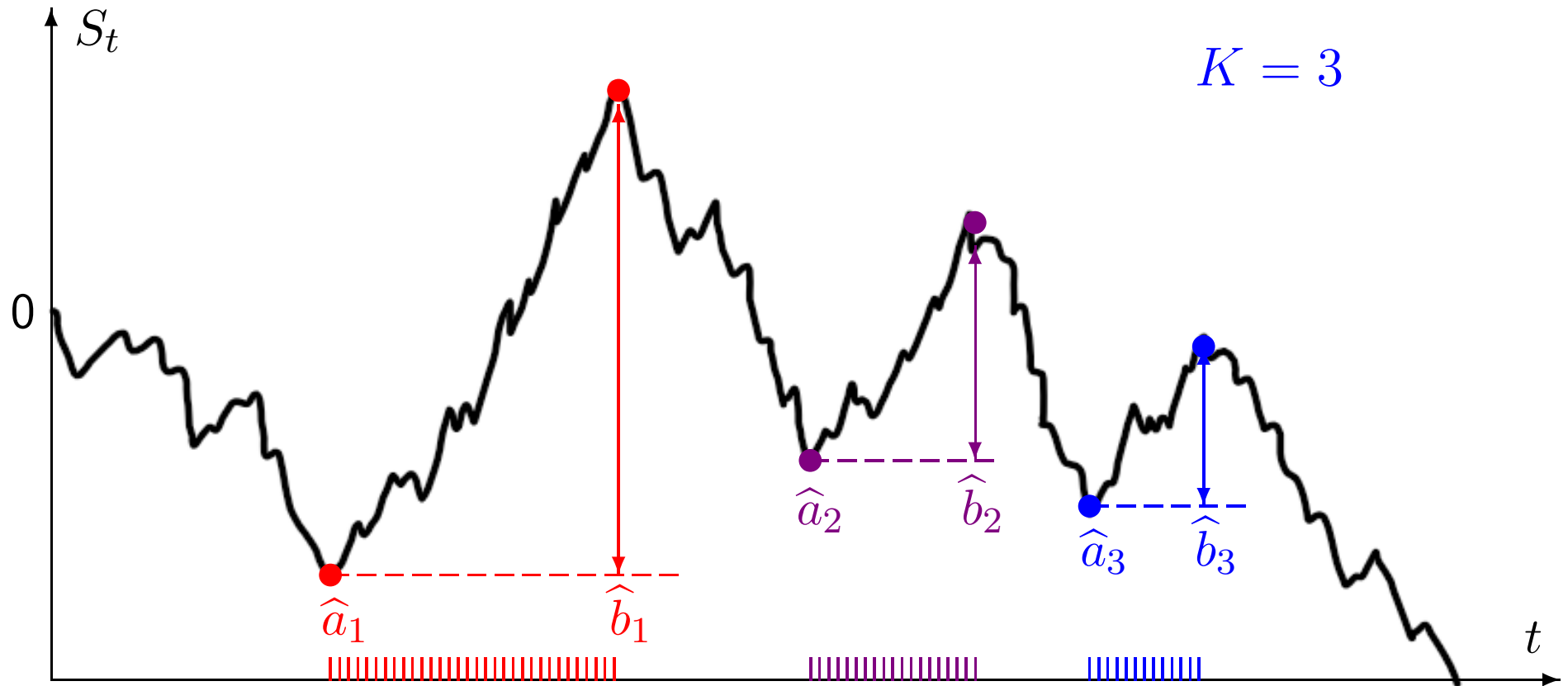
Hence, the MLE of θ is

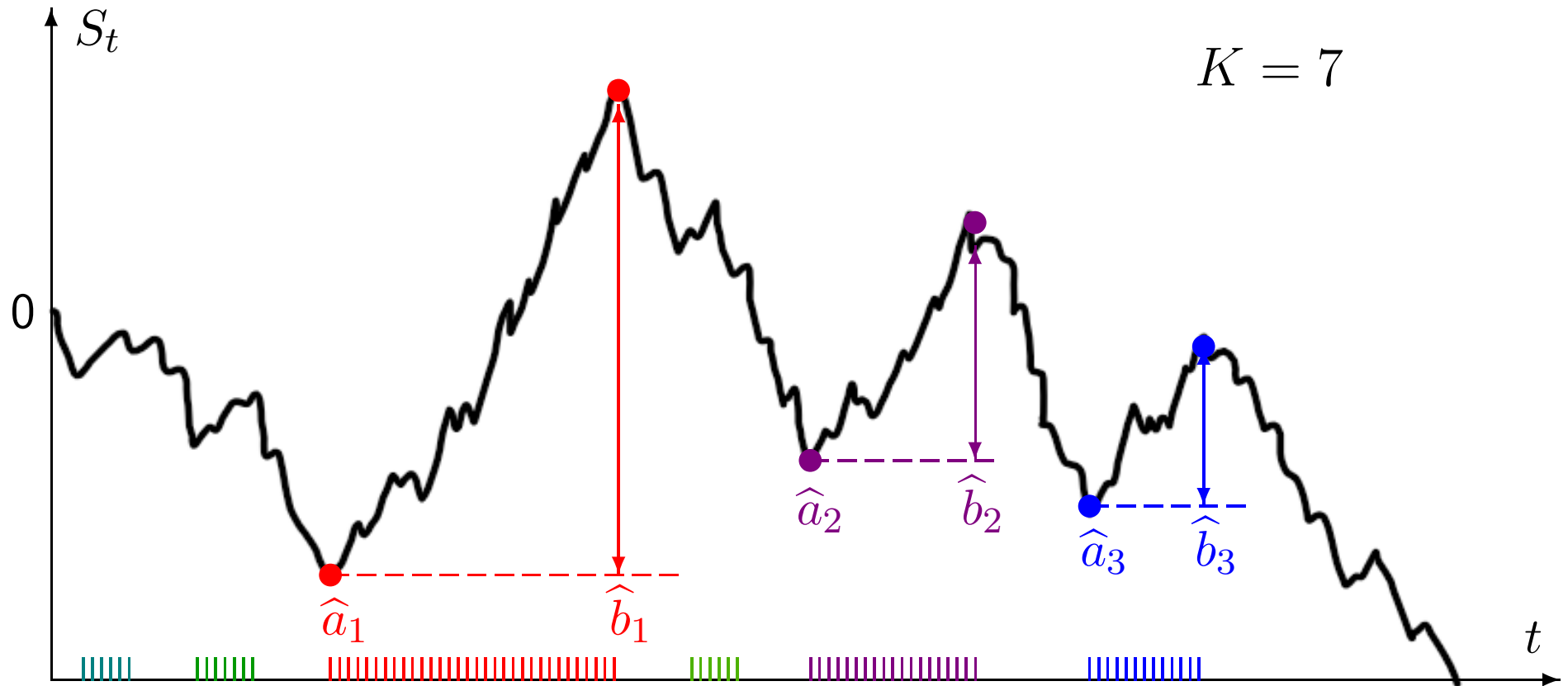
$$\hat{\theta} = \left\{ \hat{\theta}_k \right\}_{k=1}^{k=K} = \left\{ (\hat{a}_k, \hat{b}_k) \right\}_{k=1}^{k=K} = \arg \max_{a_1 < b_1 < \dots < a_K < b_K} \sum_{k=1}^K (S_{b_k} - S_{a_k}),$$

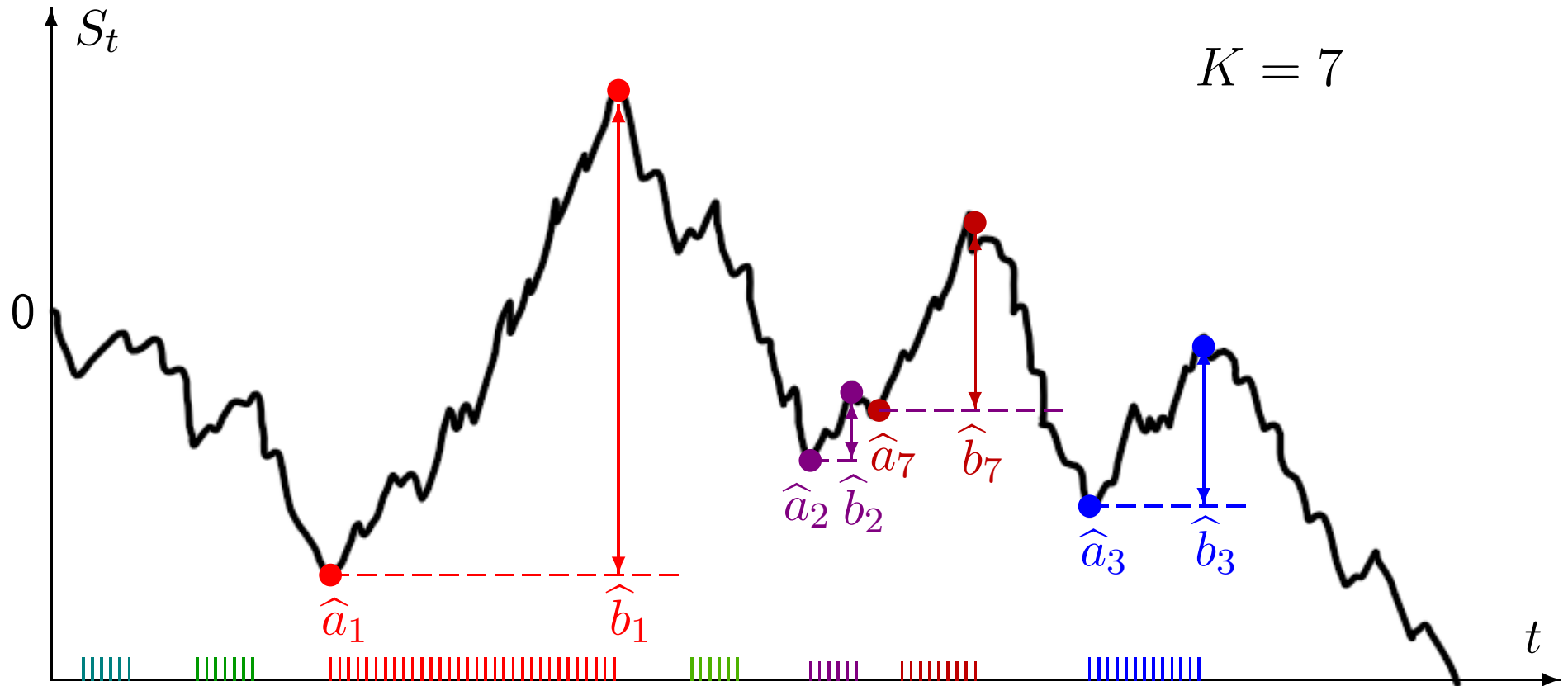
which are K intervals of the biggest growth of S_t .

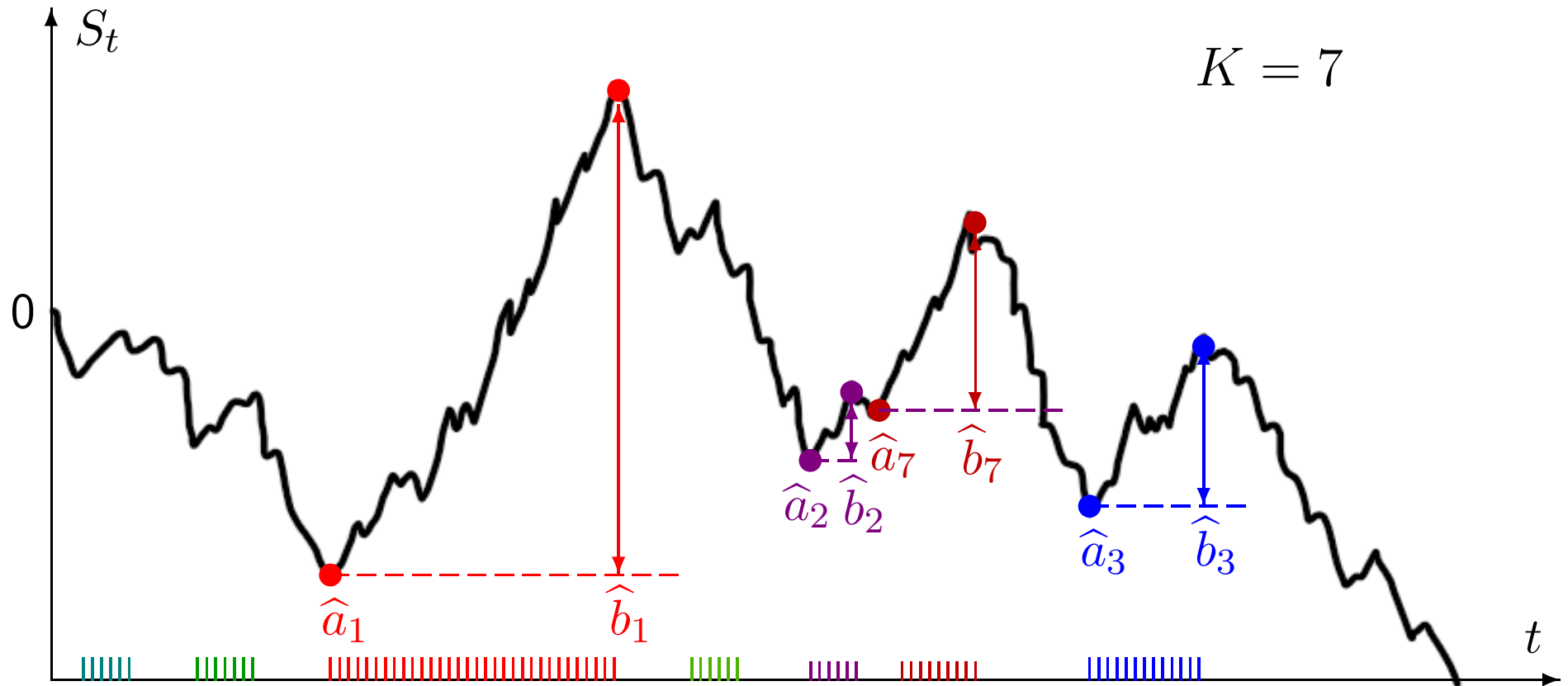












Some detected change-points may be **false alarms**.
Or **false adjustments**.

Controlling the rate of false alarms

- ▶ Some detected change-points may be *false alarms*.
- ▶ $[\hat{a}_k, \hat{b}_k]$ is a *false alarm* if $[\hat{a}_k, \hat{b}_k] \cap (\cup [a_j, b_j]) = \emptyset$
- ▶ Goal: control the *familywise* rate of false alarms,

$$\text{FAR} = \mathbb{P} \left\{ (\cup [\hat{a}_k, \hat{b}_k]) \cap (\cup [a_j, b_j]) = \emptyset \right\} \leq \alpha$$

- ▶ A *false adjustment* occurs when $[\hat{b}_k, \hat{a}_{k+1}] \cap (\cup [b_j, a_{j+1}]) = \emptyset$
- ▶ Control $\mathbb{P} \left\{ (\cup [\hat{b}_k, \hat{a}_{k+1}]) \cap (\cup [b_j, a_{j+1}]) = \emptyset \right\} \leq \beta$

Detection scheme with an unknown number of changes

Simultaneous detection of disorders and adjustments

- ▶ $W_{\tau,t}$ = CUSUM based on $S_{\tau+t}$, renewed at τ
 $\widetilde{W}_{\tau,t}$ = CUSUM based on $(-S_{\tau+t})$, renewed at τ
- ▶ Detection times...

$$\tau_0 = 0 ,$$

$$\tau_k = \inf\{t > \tau_{k-1} : W_{\tau_{k-1},t-\tau_{k-1}} \geq h_\alpha\} \wedge n , \text{ for odd } k,$$

$$h_\alpha = -\log(\alpha \mathbb{E}_F^{-1}(e^{W_n}));$$

$$\tau_k = \inf\{t > \tau_{k-1} : \widetilde{W}_{\tau_{k-1},t-\tau_{k-1}} \geq \widetilde{h}_\beta\} \wedge n , \text{ for even } k,$$

$$\widetilde{h}_\beta = -\log(\beta \mathbb{E}_G^{-1}(e^{\widetilde{W}_n})).$$

- ▶ Restarted and grounded CUSUM process $W_0^{(h)} = 0$,

$$W_t^{(h)} = \begin{cases} W_{\tau_{k-1}, t-\tau_{k-1}} & \text{if } k \leq 2K \text{ is odd,} \\ \widetilde{W}_{\tau_{k-1}, t-\tau_{k-1}} & \text{if } k \leq 2K \text{ is even} \end{cases} \quad \text{for } t \in (\tau_{k-1}, \tau_k]$$

For the last stopping time τ^* before n ,

$$W_t^{(h)} = \begin{cases} W_{\tau^*, t-\tau^*} & \text{if } \tau^* \text{ is even,} \\ \widetilde{W}_{\tau^*, t-\tau^*} & \text{if } \tau^* \text{ is odd} \end{cases} \quad \text{for } t \in (\tau^*, n]$$

- ▶ $\nu_k = \sup \left(\text{Ker}(W_t^{(h)}) \cap [0, \tau_k) \right) = \text{last zero of } W_t^{(h)} \text{ before } \tau_k$
- ▶ $\theta_k = (a_k, b_k)$ is estimated by (ν_{2k-1}, ν_{2k}) for $k = 1, \dots, 2K$.

Detecting *disorders* with familywise $FAR \leq \alpha$ and detecting *adjustments* with familywise $FAR \leq \beta$.

No Bonferroni or Holm type correction is needed!

Estimation precision. How accurate are $\hat{\theta}_k = (\hat{a}_k, \hat{b}_k)$?

Local estimators... For any $t \in [a_k, b_k]$, let

$$\tilde{a}_t = t - \arg \min_{0 \leq i \leq t} S_{t-i} \quad \text{and} \quad \tilde{b}_t = t + \arg \max_{0 \leq i \leq n-t} \tilde{S}_{t+i}$$

These \tilde{a}_t and \tilde{b}_t are independent, with distributions

$$\mathbb{P}(\tilde{b}_t = b + r) = \begin{cases} \tilde{R}_{G,b-t}(0) R_{F,n-b}(0) & \text{for } r = 0 \\ \int_0^\infty \tilde{R}_{G,b-t}(x) B_{F,r,n-b-r}(x) dx & \text{for } r > 0 \\ \int_0^\infty R_{F,n-b}(x) \tilde{B}_{G,-r,b-t+r}(x) dx & \text{for } r < 0 \end{cases}$$

$$\mathbb{P}(\tilde{a}_t = a + l) = \begin{cases} R_{F,a}(0) \tilde{R}_{G,t-a}(0) & \text{for } l = 0 \\ \int_0^\infty \tilde{R}_{G,\gamma-a}(x) B_{F,-l,a+l}(x) dx & \text{for } l < 0 \\ \int_0^\infty R_{F,a}(x) \tilde{B}_{G,l,\gamma-a-l}(x) dx & \text{for } l > 0 \end{cases}$$

where

$$M_k = \max(0, S_1, \dots, S_k),$$

$$\widetilde{M}_k = \max(0, \widetilde{S}_1, \dots, \widetilde{S}_k)$$

$$R_{F,k}(x) = \mathbb{P}_F(M_k \leq x),$$

$$\widetilde{R}_{F,k}(x) = \mathbb{P}_F(\widetilde{M}_k \leq x)$$

$$\begin{aligned} B_{F,k,s}(y)dy &= \mathbb{P}(\arg \max_{0 \leq i \leq k+s} S_i = k, S_k \in [y, y + dy)) \\ &= \mathbb{P}_F(W_k = 0, S_k \in [y, y + dy))\mathbb{P}_F(M_s = 0) \end{aligned}$$

$$\begin{aligned} \widetilde{B}_{G,k,s}(y)dy &= \mathbb{P}_F(\arg \max_{0 \leq i \leq k+s} \widetilde{S}_i = k, \widetilde{S}_k \in [y, y + dy)) \\ &= \mathbb{P}_G(\widetilde{W}_k = 0, \widetilde{S}_k \in [y, y + dy))\mathbb{P}_G(\widetilde{M}_s = 0). \end{aligned}$$

Uniform probability bounds

- ▶ $\sup_{t \in [a, b]} \mathbb{P}(\tilde{b}_t = b + r)$

$$\geq q_r = \begin{cases} \exp\left(-\sum_{m=1}^{\infty} \frac{1}{m} \left(\mathbb{P}_F\left(\sum_{j=1}^m Y_j \geq 0\right) + \mathbb{P}_G\left(\sum_{j=1}^m Y_j \leq 0\right) \right)\right) & \text{for } r = 0 \\ \int_0^{\infty} R_{F,\infty}(x) \tilde{B}_{G,-r,\infty}(x) dx & \text{for } r < 0 \\ \int_0^{\infty} \tilde{R}_{G,\infty}(x) B_{F,r,\infty}(x) dx & \text{for } r > 0 \end{cases}$$
- ▶ $\sup_{t \in [a, b]} \mathbb{P}(\tilde{a}_t = a + l)$

$$\geq p_l = \begin{cases} \exp\left(-\sum_{m=1}^{\infty} \frac{1}{m} \left(\mathbb{P}_G\left(\sum_{j=1}^m Y_j \geq 0\right) + \mathbb{P}_F\left(\sum_{j=1}^m Y_j \leq 0\right) \right)\right) & \text{for } l = 0 \\ \int_0^{\infty} \tilde{R}_{G,\infty}(x) B_{F,-l,\infty}(x) dx & \text{for } l < 0 \\ \int_0^{\infty} R_{F,\infty}(x) \tilde{B}_{G,l,\infty}(x) dx & \text{for } l > 0 \end{cases}$$

Hinkley (1970)

Estimation precision

Now consider events

$$A_k = \bigcup_{j=1}^K [a_j, b_j) \cap [\nu_{2k-1}, \nu_{2k}) \neq \emptyset; \quad \text{with } \mathbb{P}(A_k) \geq 1 - \alpha$$

$$B_k = \bigcup_{j=1}^{K-1} [b_j, a_{j+1}) \cap [\nu_{2k}, \nu_{2k+1}) \neq \emptyset \quad \text{with } \mathbb{P}(B_k) \geq 1 - \beta$$

On A_k , there exists $t \in [a_j, b_j) \cap [\nu_{2k-1}, \nu_{2k})$ for some j .

On B_k , there exists $t \in [a_j, b_j) \cap [\nu_{2k}, \nu_{2k+1})$ for some j .

Hence,

$$\mathbb{P}(\inf_j |\hat{a}_k - a_j| > u) \leq 1 - \sum_{-u}^u p_k + \alpha$$

$$\mathbb{P}(\inf_j |\hat{b}_k - b_j| > v) \leq 1 - \sum_{-v}^v q_k + \beta$$

for all θ . One-sided probabilities are bounded as

$$\mathbb{P}(\inf_j (\hat{a}_i - a_j) \geq u) \leq \sum_u^n p_k + \alpha \quad \mathbb{P}(\inf_j (\hat{a}_i - a_j) \leq -u) \leq \sum_{-n}^{-u} p_k + \alpha$$

$$\mathbb{P}(\inf_j (\hat{b}_i - b_j) \geq v) \leq \sum_v^n q_k + \beta \quad \mathbb{P}(\inf_j (\hat{b}_i - b_j) \leq -v) \leq \sum_{-n}^{-v} q_k + \beta$$

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Thank you!