# Assignment 2 - FOL Theory Mihael Zlatev - 1MI3400543

This report presents a logical theory approach for solving a maze problem using a Forward Chaining and Backward chaining algorithm. The problem is described in terms of First-Order Logic (FOL), and the process of inference through logical rules is demonstrated. The maze is represented as a grid with cells that may have obstacles (cells in the maze which can't be visited)

# **Forward Chaining**

### Facts are defined to represent the state of the maze:

- MazeCell(row, col)
  - Example for the 2 x 2 maze:

MazeCell(0, 0), MazeCell(0, 1), MazeCell(1, 0), MazeCell(1, 1)

- Obstacle(row, col) each MazeCell which contains an obstacle.
- Start(n, m) ↔ (MazeCell(n, m) ∧ ¬Obstacle(n, m))
  For example Start(0, 0)
- End(n, m) ↔ (MazeCell(n, m) ∧ ¬Obstacle(n, m))
  For example Start(4, 5)

### Rules describe how new facts are inferred:

- ValidMove ∀x,y,dx,dy (InMaze(x,y) ∧ InMaze(x+dx, y+dy) ∧
  ¬Obstacle(x+dx, y+dy)) → ValidMove(x+dx, y+dy)
- 2. **Neighbours**  $\forall$ x1,y1,x2,y2 (ValidMove(x1,y1)  $\land$  ValidMove(x2,y2)  $\land$  (|x1-x2| + |y1-y2| = 1))  $\rightarrow$  Neighbours(x1,y1,x2,y2)
- 3. Explorable:

 $\forall x,y (Start(x,y) \rightarrow Explorable(x,y))$ 

 $\forall$ x1,y1,x2,y2 (ValidMove(x1,y1)  $\land$  ValidMove(x2,y2)  $\land$  Neighbours(x1,y1,x2,y2)  $\land$  Explorable(x1, y1))  $\rightarrow$  Explorable(x2, y2)

## Forward chaining - Pseudo code:

The Forward Chaining algorithm iteratively applies rules to infer new facts until no new facts can be derived, or the goal is reached:

- 1. Initialize:
  - Mark Start cell as Explorable
- 2. Inference Process:
  - Repeat until no new Reachable cells can be found: For each known Explorable cell (x1,y1) Examine all neighboring cells (x2,y2) If (x2,y2) is a ValidMove add (x2,y2) to Explorable set
- 3. Termination:
  - Stop when no new Explorable cells can be added or Path is constructed through Explorable

## **Backward Chaining**

#### **Facts**

- Reusing the same facts as forward chaining

### Rules

1. Predecessor:

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\forallx1,y1,x2,y2 ( ValidMove(x1,y1) \land ValidMove(x2,y2) \land (x2 = x1 - dx \land y2 = y1 - dy) \land ( (dx == 1 \land dy= 0) \lor (dx == 0 \land dy= 1) \lor (dx == -1 \land dy= 0) \lor (dx == 0 \land dy == -1) )) \rightarrow Predecessor(x2,y2,x1,y1)
```

2. Path Existence:

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\forall x,y (End(x,y) \rightarrow PathExists(x,y))
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 $\forall$ x1,y1,x2,y2 ( ValidMove(x1,y1)  $\land$  ValidMove(x2,y2)  $\land$  Predecessor(x1,y1,x2,y2)  $\land$  PathExists(x2,y2)  $\rightarrow$  PathExists(x1,y1) )

#### Pseudo code:

- 1. Initialize:
  - Set that Path exists to goal
- 2. Inference process:
  - Recursively check if PathExistence rule applies for predecessors (Build path backwards from goal to start)
- 3. Termination:
  - stop when current cell is Start and path is constructed though the PathExistence rule

### **Unification of formulas**

Unification is the process of finding a consistent substitution of variables in logical formulas, enabling general rules to match specific facts. However, **unification is not necessary in this maze-solving problem** because the algorithm works by directly matching specific facts and rules without needing to generalize them.