

Advanced Topics in SAT-Solving

Part III: Implementation Techniques

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Outline

1. Basic Data Structures
2. Efficient Unit Propagation
3. Literal Selection Strategies
4. Clause Learning
5. Parallelization

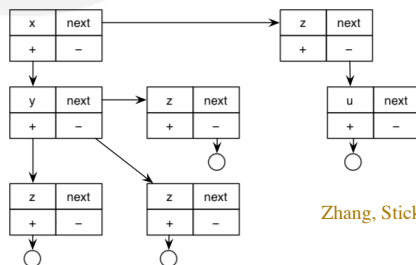
Data Structures for CNF Representation

How to represent a set of clauses?

A) As a clause list



B) As a trie data structure



Zhang, Stickel (1994)

Repetition: DPLL Algorithm

boolean DPLL(ClauseSet S)

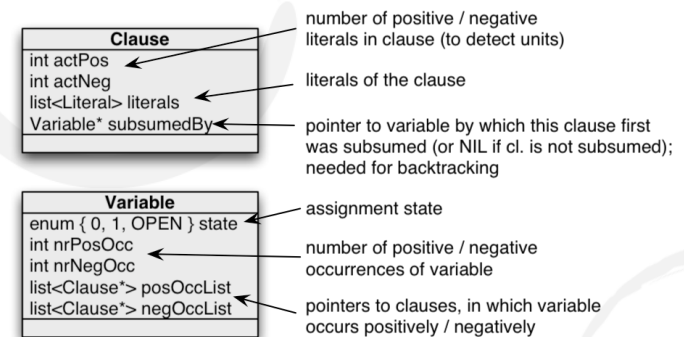
```

{
  while (S contains a unit clause {L}) { // unit propagation
    delete from S all clauses containing L; // u. subsumption
    delete ¬L from all clauses in S; // u. resolution
  }
  if (∅ ∈ S) return false;
  if (S = ∅) return true;
  choose a literal L occurring in S;
  if (DP(S ∪ {{L}}) return true;
  else return DP(S ∪ {{¬L}});
}
  
```

Data Structures for DPLL: Requirements

- Allow for fast unit propagation
 - Detection of new units
 - Propagation of units
- Support back-tracking (restoration of clause data)
 - Implementation alternatives:
 - Save copy of clause set data structure on each level
 - Remember changes (undo-stack)
 - Goal: Minimize restore effort
- Compact representation of large clause sets

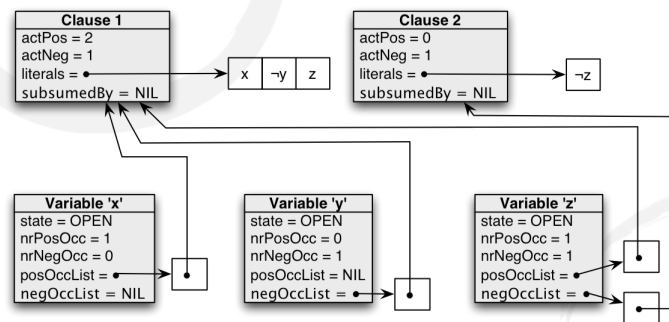
"Traditional" Approach



Crawford, Auton (1993)

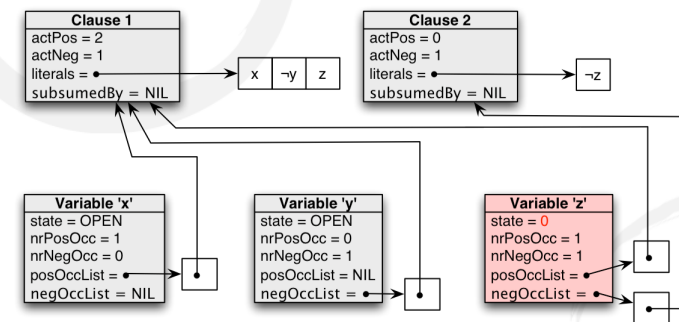
Traditional Approach: Example

$$F = \{\{x, \neg y, z\}, \{\neg z\}\}$$



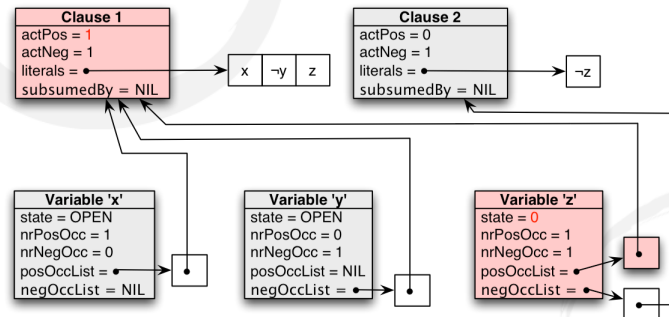
Example: Unit Propagation

$$F = \{\{x, \neg y, z\}, \{\neg z\}\} \quad \text{Unit propagation: set } z=0$$



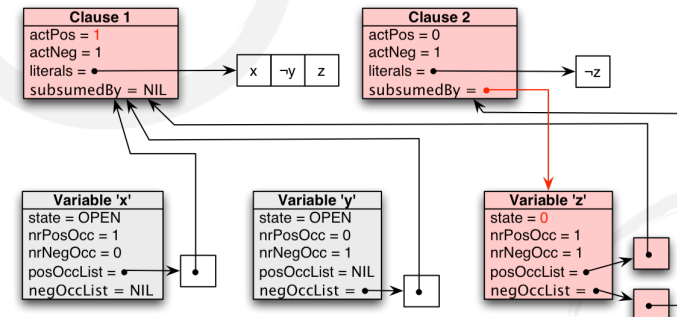
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Algorithm Unit-Propagation

```

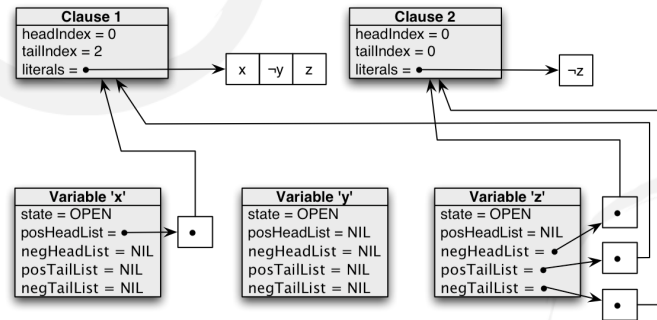
boolean UnitProp(Literal L)    // L: open literal; 'UnitProp' returns
{ if(L.isPositive()) {        // false on contradiction
    v = L.var(); v.state = 1;
    for(it = v.posOccList.begin(); it != v.posOccList.end(); it++) {
        clause = *it;
        if(clause.subsumedBy == NIL) clause.subsumedBy = v;
    }
    for(it = v.negOccList.begin(); it != v.negOccList.end(); it++) {
        clause = *it; if(clause.subsumedBy == NIL) {
            clause.actPos--; // shorten clause
            if(v.actPos + v.actNeg == 1) { // new unit clause detected
                ok = HandleNewUnit(clause);
                if(!ok) return false; // conflicting units?
            }
        }
    }
}
else {...}
return true;
}
    
```

UP Alg.: Complexity and Improvements

- Setting variable x (to true) ...
 - subsumes $|\text{posOccList}(x)|$ clauses
 - shortens $|\text{negOccList}(x)|$ clauses
 - thus: requires a total of $\#occ(x)$ clause modifications
- Can we improve on this?
 - We only have to detect unit clauses
 - Idea (Zhang, Stickel (1996)):
 - Delay testing for subsumption
 - 'subsumedBy' is not used any more; instead, the test for a new unit has to check whether clause is subsumed
 - Restrict unit resolution to first and last open literal in clause
 - maintain pos/negHeadList and pos/negTailList instead of pos/negOccList

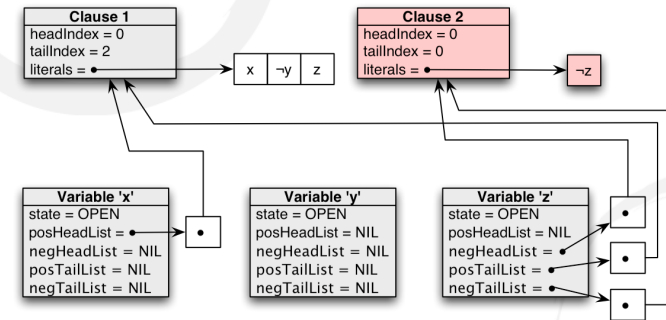
Head and Tail Lists: Example

$$F = \{\{x, \neg y, z\}, \{\neg z\}\}$$



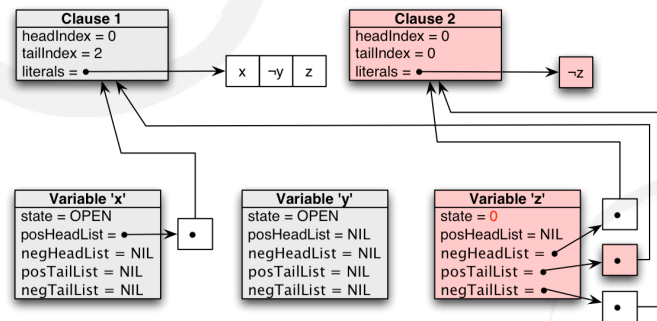
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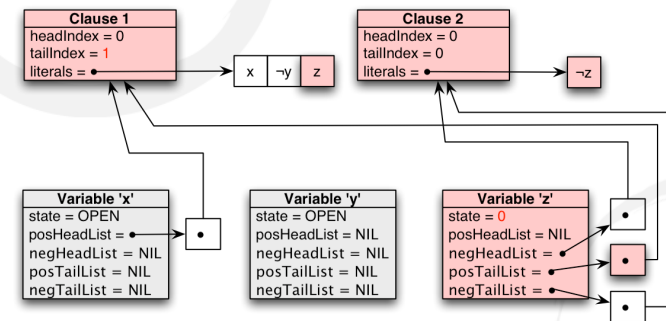
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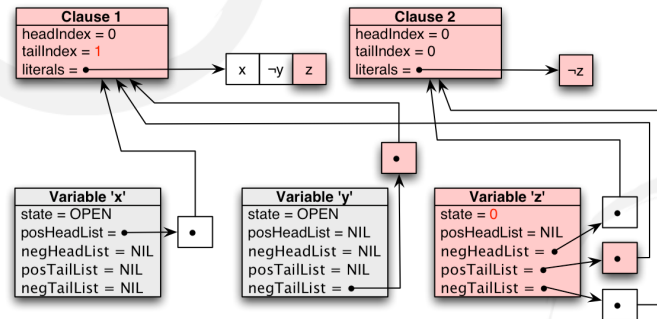
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Head and Tail Lists: Unit Propagation

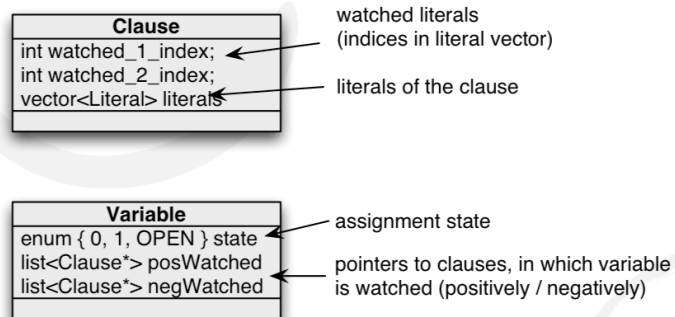
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H/T Lists: Pros, Cons, Improvements

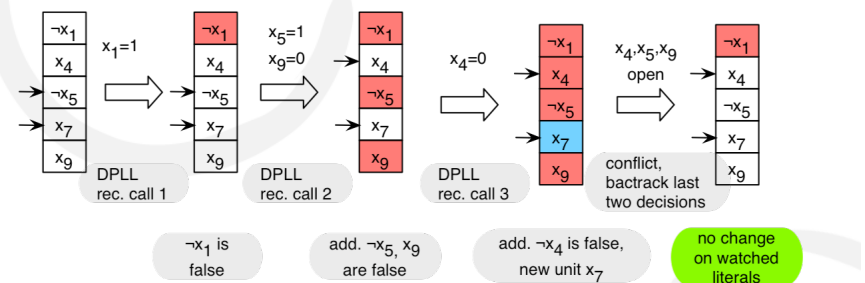
- **Positive:** Faster unit propagation
- **Negative:** Backtracking becomes more complicated (head and tail lists have to be restored)
- Further improvement: **watched literals**
 - Instead of head/tail literals: 2 **watched literals** per clause
 - Watched literals point to *arbitrary* open (different) literals
 - on backtracking: no update of data structure needed
 - First implemented in **chaff** (Moskewicz *et al.*, 2001)

Watched Literals: Data Structures



Moskewicz *et al.* (2001)

Watched Literals: Example



Literal Selection Strategies

- Which literal to select best in case-distinction step?
 - Size of search space (and thus run-time) can drastically depend on literal selection heuristics
 - Highly problem-dependent, no general “best” strategy
- Ideas for selection heuristics:
 - Maximal simplification**, e.g. maximize number of subsumed (deleted) clauses
 - Try to reach tractable subclass of SAT**, e.g. 2-SAT, Horn-SAT, only positive clauses
 - Based on conflict analysis / clause learning (with preference for literals in recently learned clauses)

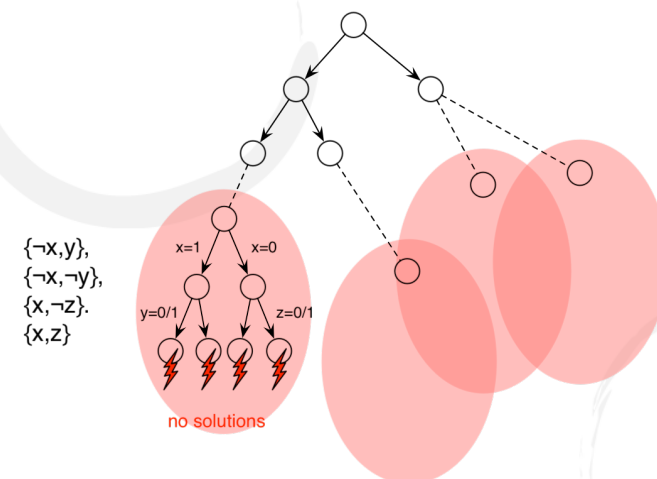
Literal Selection Strategies

- MOM** (maximum occurrences in minimal clauses):
 maximize $(occ_2(l) + occ_2(\neg l)) \cdot 2^\alpha + occ_2(l) \cdot occ_2(\neg l)$
 (where α is a ‘large enough’ number)
- SATO**: build test set of k shortest positive clauses and choose literal that maximizes $(po(l)+1)(no(l)+1)$
 (where $po(l)$ ($no(l)$) denotes number of positive (negative) occurrences of literal l)
- VSIDS** (variable state independent decaying sum):
 initial score is number of literal occurrences; for each learned clause, increase score by constant c for all literals in clause; periodically divide all scores by a factor f ; choose literal with highest score

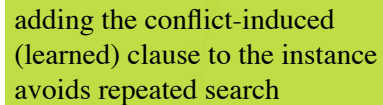
Conflict Analysis & Clause Learning

- Try to avoid repeated search of parts of the search tree with no solutions
- Compensate for badly selected case distinction literals
- Method**: find **weakest assumption** under which a contradiction arises
 - Each selected branching literal counts as an ‘atomic’ reason
 - Find minimal necessary condition (i.e. minimal literal set) that produces the same conflict
- Also called “no-good learning” in the CSP community

Conflict Analysis: Example



(Marques-Silva, Sakallah, 1996)



Non-Chronological Back-Jumping

1st conflict-induced clause: $\{v, \neg x, y\}$

2nd conflict-induced clause: $\{\neg x, y\}$

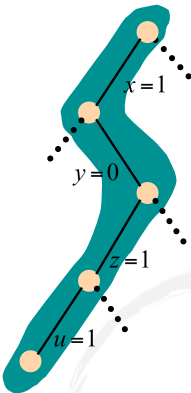
Parallelization

- Allow **several processors** work collaboratively on the same SAT instance
- Questions to answer:
 - How to **partition search space** between processors?
 - Once at the beginning or on demand during search?
 - How to deal with unreliable communication / network failure / shutdown of computers
 - **Exchange learned clauses** between processes?
 - **Effects** of combining clause learning and parallelization
- Experimental results:
 - Good speed-ups attainable on n processors ($n \approx 8-32$)
 - Parallel learning and clause exchange highly problem dependent

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Dynamic Search Space Splitting

- **Guiding path** (H. Zhang *et al.* 1996) describes state of search, e.g.
 $((x, B), (\bar{y}, N), (z, B), (u, B))$
- **Partitioning of search-space** at each $(_, B)$ entry possible, e.g.
 $((x, N), (\bar{y}, N), (z, B), (u, B))$
 $((\bar{x}, N))$



The diagram illustrates a guiding path through a search space. A teal, irregularly shaped region represents the search space. A black line with four orange circular nodes represents the guiding path. The nodes are labeled from top to bottom: $x=1$, $y'=0$, $z=1$, and $u=1$. Dotted lines extend from the top and bottom nodes, suggesting the path continues beyond the shown segment.

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$((\bar{x}, N))$

Combining Learning and Parallelization

- Acceleration by lemma generation may limit speed-ups attainable by parallelization:

