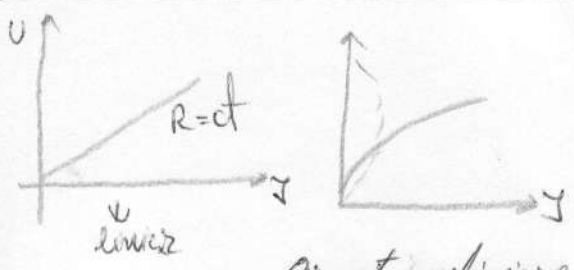
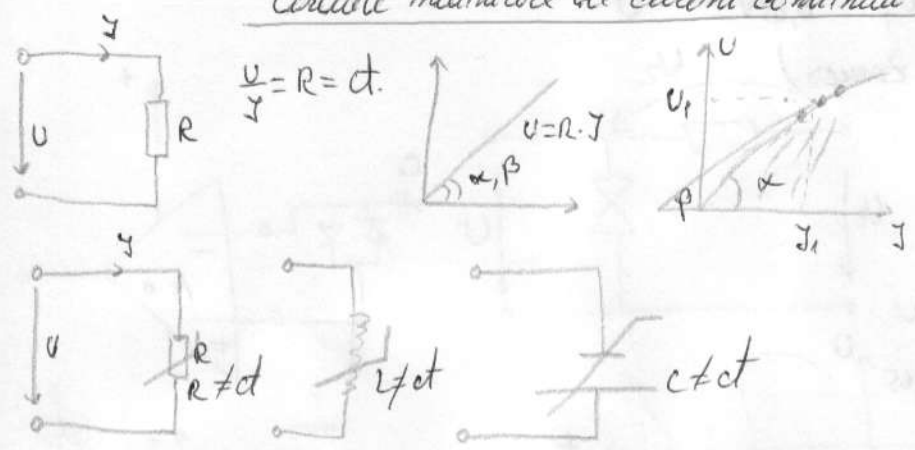


# Încălzire liniară de curent continuu



## Circuite liniare de curent continuu

Curso6

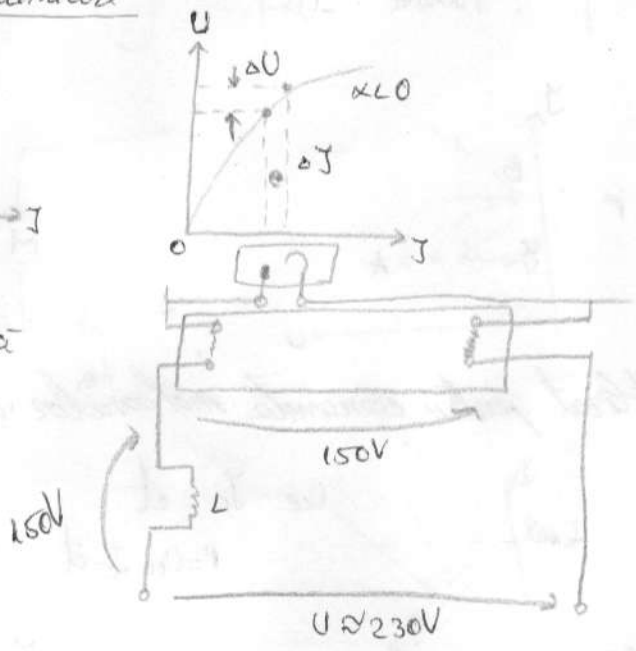
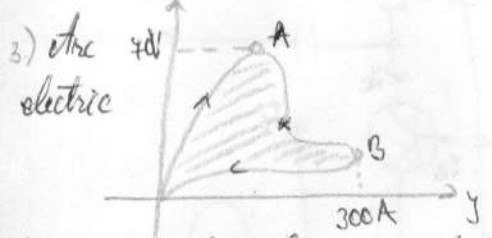
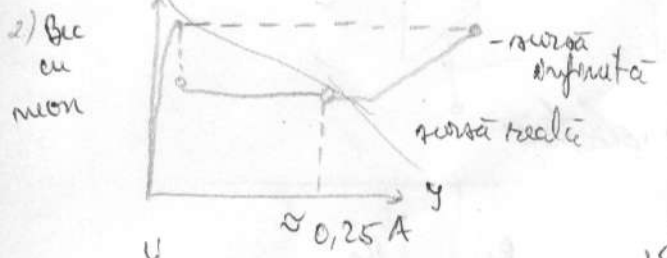
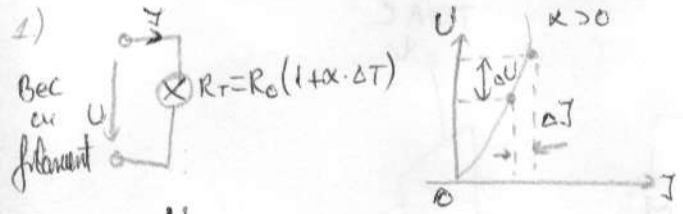


$$R_1 = \frac{U_1}{I_1} = I_1 \alpha$$

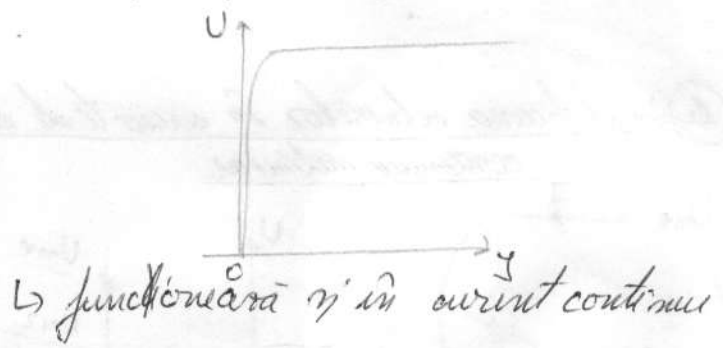
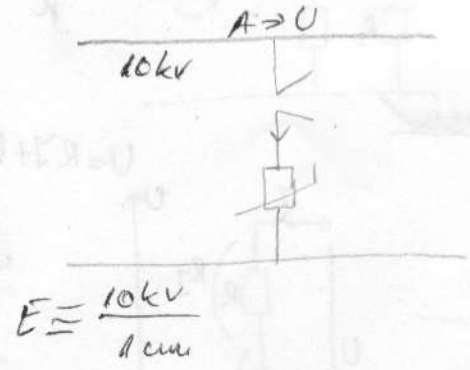
$$\frac{U}{I} = R_{ct} = I_1 \alpha$$

$$\frac{\Delta U}{\Delta I} = R_d = I_1 \beta$$

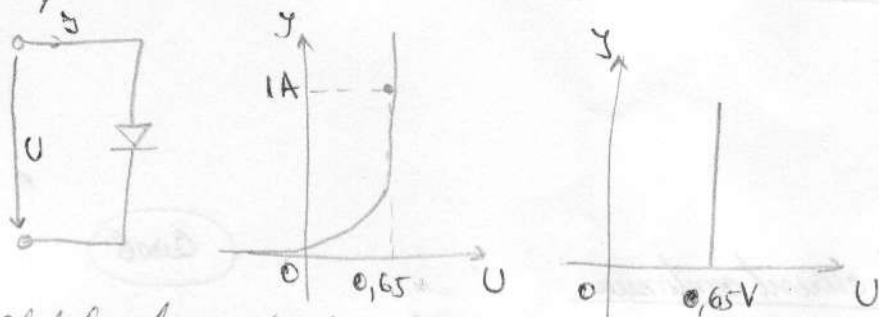
## (A) Exemple de circuite liniare



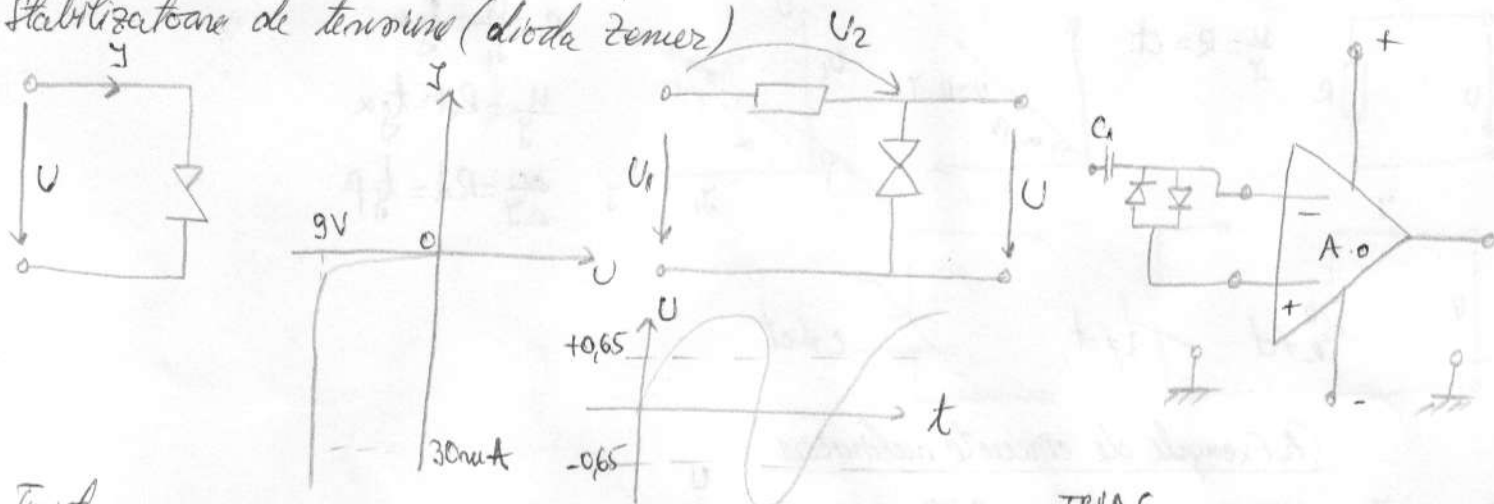
## 4) Încălzirea și utilizarea în electrică pt. a preluc supraîncălzirea



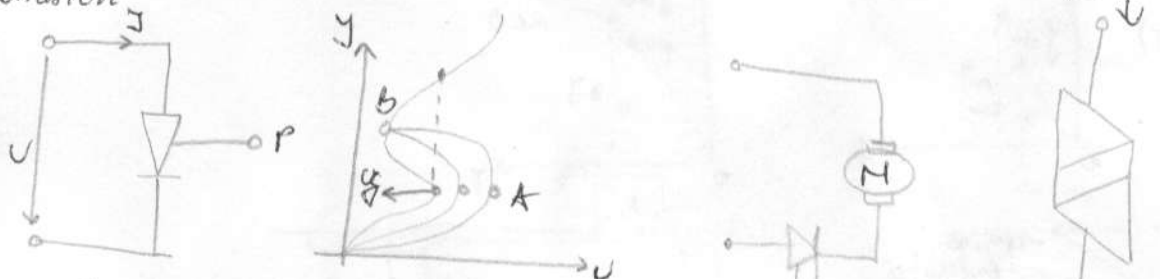
5) Dispozitive care au la bază mliu:



6) Stabilizatoare de tensiune (diode Zener)

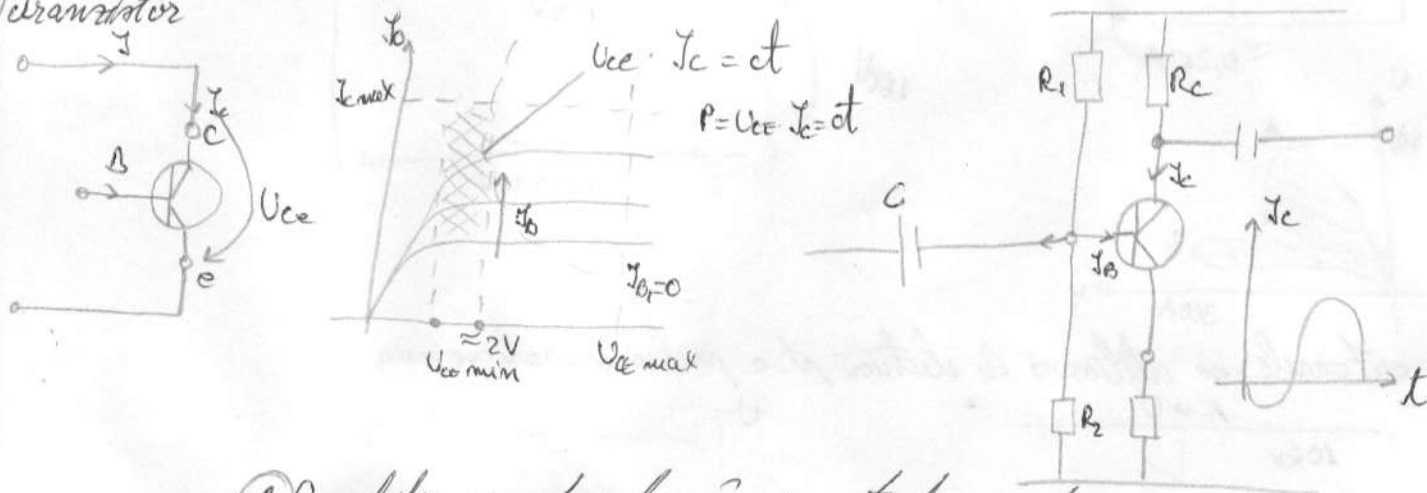


7) Tiristor

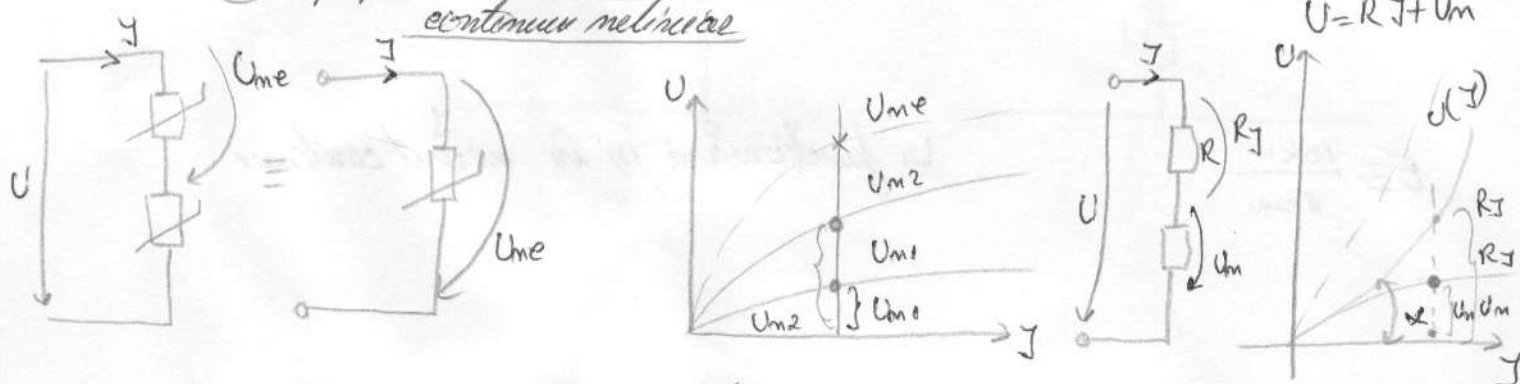


Tiristorul este utilizat pentru comanda motoarelor electrice

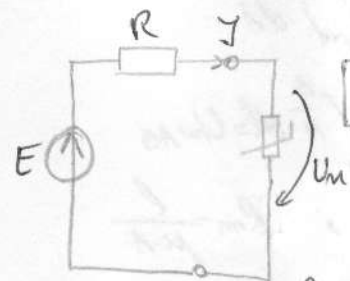
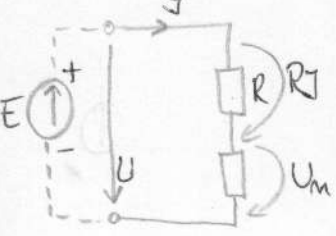
8) Transistor



B. Simplificarea schemelor în circuite de curent continuu mliu

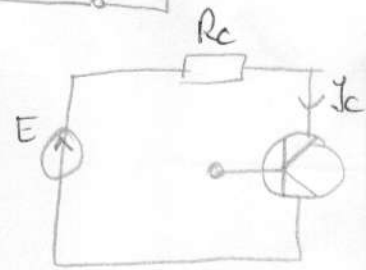
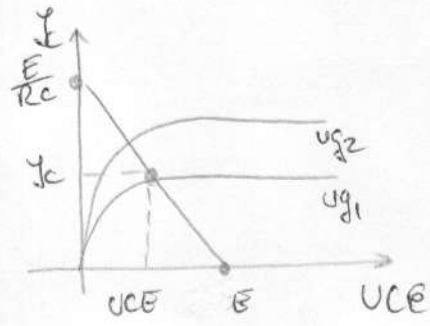
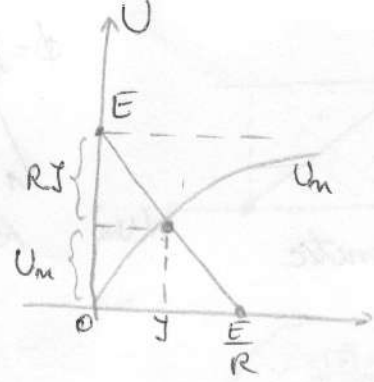


Observație:

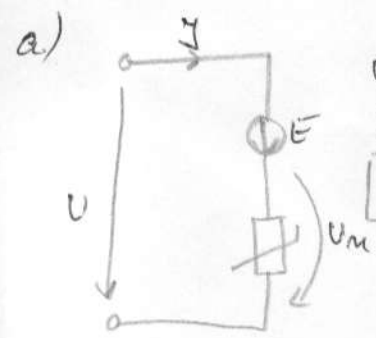


$$E = R \cdot I + U_m$$

$$U_m = E - R \cdot I$$



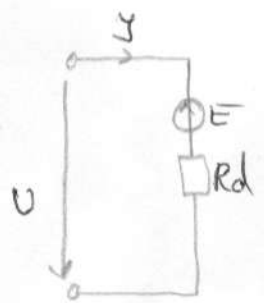
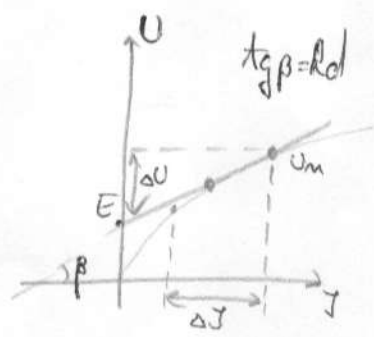
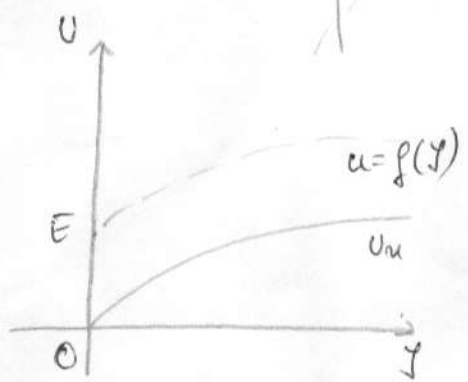
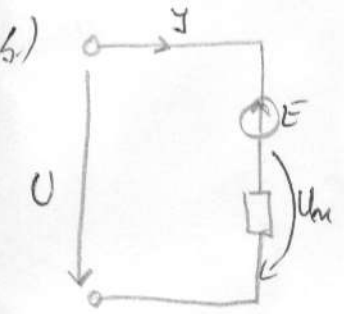
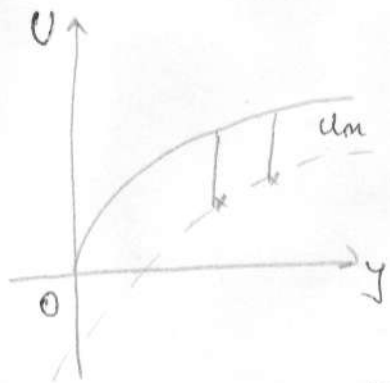
### Elemente neliniare în serie cu un element



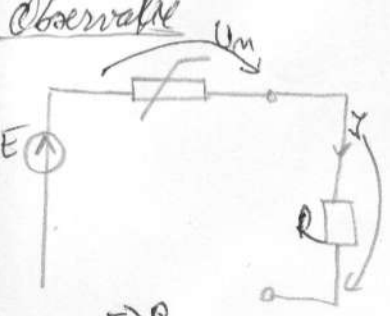
$$U + E = R \cdot I$$

$$U + E = U_m$$

$$U = U_m - E$$



Observație

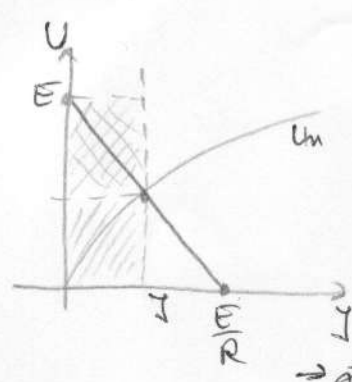


$$E = R \cdot I + U_m$$

$$R \cdot I = E - U_m$$

$$R \cdot I^2 = I(E - U_m)$$

$$P_2 = R \cdot I^2 = I(E - U_m)$$



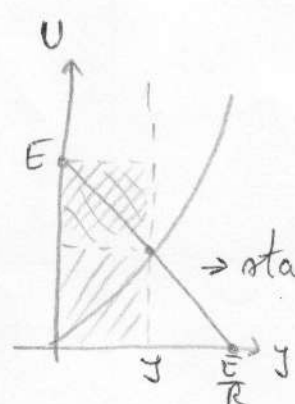
$$\frac{\partial P_2}{\partial I} = 0$$

$$E - U_m - \frac{\partial U_m}{\partial I} \cdot I = 0$$

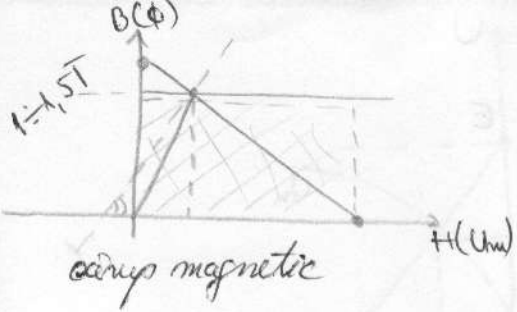
$$R \cdot I = I \cdot \frac{\partial U_m}{\partial I} \Rightarrow R = R_d$$

Condiția transparenței  
maxim de putere

→ stabilizator de tensiune



→ stabilizator de curent



$$\Phi = \int_S \vec{B} \cdot d\vec{A} \Rightarrow \lambda = \int_S \vec{J} \cdot d\vec{A}$$

$$\int_A^B \vec{E} \cdot d\vec{l} = U_{AB} \Rightarrow \int_A^B \vec{H} \cdot d\vec{l} = U_{mAB}$$

$$R = \rho \cdot \frac{l}{A} = \frac{e}{\sigma A} ; R_m = \frac{l}{\mu \cdot A}$$

