

# Math 406 Homework 5

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**Question 1a.** For all functions  $v$  in some class, the following must be true:

$$\int_0^1 v(u'' + k^2 u - f) dx = 0.$$

Integrating by parts:

$$\int_0^1 -u'v' + k^2 uv - f v dx + v(1)\beta - v(0)u'(0) = 0 \implies \int_0^1 u'v' dx = k^2 \int_0^1 uv dx - \int_0^1 f v dx + \beta v(1).$$

Thus the weak form is to find  $u \in H_\alpha^1$  such that  $\int_0^1 u'v' dx = k^2 \int_0^1 uv dx - \int_0^1 f v dx + \beta v(1) \forall v \in H_0^1$ .

**Question 1b.** Since we used the strong form to derive the weak form while relaxing constraints, the strong form always implies the weak form.

**Question 1c.** Let  $u^h(x) = \sum_{n=0}^N u_n N_n(x)$ , where  $N_n(x)$  are the basis functions. Similarly let  $v^h(x) = \sum_{m=1}^N v_m N_m(x)$ . Using the weak form derived above, we need to find  $u^h \in V_\alpha^h$  such that:

$$\begin{aligned} \int_0^1 \left( \alpha N_0' + \sum_{n=1}^N u_n N_n' \right) \left( \sum_{m=1}^N v_m N_m' \right) dx &= k^2 \int_0^1 \left( \alpha N_0 + \sum_{n=1}^N u_n N_n \right) \left( \sum_{m=1}^N v_m N_m \right) dx \\ &\quad - \int_0^1 f \left( \sum_{m=1}^N v_m N_m \right) dx + \sum_{m=1}^N v_m N_m(1) \beta = 0. \\ \implies \sum_{m=1}^N v_m \left[ \alpha \int_0^1 N_0' N_m' dx + \sum_{n=1}^N u_n \int_0^1 N_n' N_m' dx - k^2 \left( \alpha \int_0^1 N_0 N_m dx + \sum_{n=1}^N u_n \int_0^1 N_n N_m dx \right) \right. \\ &\quad \left. + \int_0^1 f N_m dx - N_m(1) \beta \right] = 0. \\ \implies \sum_{n=1}^N u_n (K_{mn} - k^2 M_{mn}) &= \delta_{mn} \beta - \alpha (K_{0m} - k^2 M_{0m}) + \int_0^1 f N_m dx \implies (K - k^2 M) = b. \end{aligned}$$

Here  $K$  is the stiffness matrix and  $M$  is the mass matrix. This derivation was done in class and in the notes so most of the algebra is taken from there.

**Question 1d.** To use piecewise linear basis functions with discretization size  $h$ , all we have to do is construct the stiffness and mass matrices. Consider just a single element  $e$  along with the change

of coordinates  $x(\xi) = x_{e-1}N_1(\xi) + x_eN_2(\xi)$  where  $N_1$  and  $N_2$  are the two linear basis functions in  $[-1, 1]$  (with corresponding  $N_a(x), N_b(x)$  in the  $x$  domain):

$$\begin{aligned} \int_{x_{e-1}}^{x_e} N'_m(x)N'_n(x)dx &= \int_{-1}^1 \frac{dN_a}{d\xi} \frac{d\xi}{dx} \frac{dN_b}{d\xi} \frac{d\xi}{dx} \frac{dx}{d\xi} d\xi = \frac{2}{h} \int_{-1}^1 \frac{\xi_a \xi_b}{4} d\xi = \frac{\xi_a \xi_b}{h} \\ \implies K_{ab}^e &= \frac{1}{h} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}. \end{aligned}$$

Similarly for the mass matrix:

$$\begin{aligned} M_{mn}^e &= \int_{x_{e-1}}^{x_e} N_m N_n dx = \int_{-1}^1 \frac{1}{4} (1 + \xi_a \xi) (1 + \xi_b \xi) \frac{dx}{d\xi} d\xi = \frac{h}{4} \left( 1 + \frac{\xi_a \xi_b}{3} \right) \\ \implies M^e &= \frac{h}{6} \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}. \end{aligned}$$

Putting these together and summing over all the elements (and being careful about summing the correct conditions at the boundary, we get the final matrices to be:

$$\begin{aligned} K &= \frac{1}{h} \begin{pmatrix} 2 & -1 & 0 & 0 & 0 & \cdots \\ -1 & 2 & -1 & 0 & 0 & \cdots \\ 0 & 0 & -1 & 2 & -1 & \cdots \\ \vdots & & & & & \\ 0 & 0 & 0 & 0 & \cdots & -1 & 2 & -1 \\ 0 & 0 & 0 & 0 & \cdots & 0 & -1 & 1 \end{pmatrix} \\ M &= \frac{h}{6} \begin{pmatrix} 4 & 1 & 0 & 0 & 0 & \cdots \\ 1 & 4 & 1 & 0 & 0 & \cdots \\ 0 & 0 & 1 & 4 & 1 & \cdots \\ \vdots & & & & & \\ 0 & 0 & 0 & 0 & \cdots & 1 & 4 & 1 \\ 0 & 0 & 0 & 0 & \cdots & 0 & 1 & 2 \end{pmatrix}. \end{aligned}$$

Finally we have also have:

$$b = \begin{pmatrix} -\left(\frac{1}{h} - \frac{k^2 h}{6}\right) \alpha - (f, N_1) \\ -(f, N_2) \\ -(f, N_3) \\ \vdots \\ \beta - (f, N_N) \end{pmatrix} \quad \text{where } (f, N_m) = \int_0^1 f N_m dx.$$

Thus the finite element discretization is to solve the equation  $(K - k^2 M)u = b$  with  $K, M$  and  $b$  defined as above.

**Question 1e.** The solution to the homogeneous equation  $u'' + 10^2 u = 0$  is  $u = A \sin 10x + B \cos 10x$ . For the nonhomogeneous equation assume that  $u = a_1 + a_2 x + a_3 x^2 + a_4 x^3$ , then we have  $a_3 + a_4 x + 100a_1 + 100a_2 x + 100a_3 x^2 + 100a_4 x^3 = x^3 \implies u = -\frac{6x}{10^4} + \frac{x^3}{10^2}$ . Thus plugging in boundary conditions, the analytic solution is  $u(x) = \frac{\sin 10x}{10 \cos 10} \left( 1 + \frac{6}{10^4} - \frac{3}{10^2} \right) - \frac{6x}{10^4} + \frac{x^3}{10^2}$ .

As for the numerical solution, the matrices described above were construction for  $N = 10, 20, 30$  and solved. The results can be seen in figure .

**Question 1f.** All of the work for the previous parts have been to reduce the problem to one in the given form. Here  $f = \alpha = \beta = 0$  so  $b = 0$ , and thus  $Ku = k^2 Mu$ . Letting  $x = u, A = K, B = M$  and  $\lambda = k^2$ , we see that this is the desired eigenvalue problem.

**Question 2a.** From the main boundary value problem, we have that  $\frac{D}{r}(rp_r)_r = 0$ , which has solutions in the form  $p(r) = A + B \log r$ . The boundary conditions forces  $\lim_{r \rightarrow 0} r \frac{\partial p}{\partial r} = B = -\frac{Q_0}{2\pi D}$ , and  $u(R(t), t) = 0 \implies A = \frac{Q_0}{2\pi D} \log R(t)$ . Putting this together we have  $p(r, t) = \frac{Q_0}{2\pi D} \log \frac{R(t)}{r}$ .

Using the Stefan condition for front velocity:

$$\dot{R}(t) = -\frac{w_0^2}{\mu'} \frac{dp}{dr} \Big|_{r=R(t)} = \frac{w_0^2}{\mu'} \frac{Q_0}{2\pi D R(t)}.$$

Finally using separation of variables we can solve this differential equation:

$$\int_0^t R(t) dR(t) = \int_0^t \frac{w_0^2}{\mu'} \frac{Q_0}{2\pi D} dt \implies R(t) = \sqrt{\frac{w_0^2 Q_0 t}{\mu' \pi D}}.$$

**Question 2bi.** Expanding, the equation to solve is  $Lp = p_{rr} + \frac{1}{r}p_r = g(r, t)$ . We can find the adjoint operator:

$$\int_0^{R(t)} G f r dr = \int_0^{R(t)} G \cdot (Lu) \cdot r dr = \int_0^{R(t)} G (ru'' + u') dr.$$

From this point the self adjoint operator and associated boundary terms were derived in class (lecture 14), they are:

$$\begin{aligned} &= [Ga_0 u' + Ga_1 u - (a_0 G)' u]_0^{R(t)} + \int_0^{R(t)} u ((a_0 G)'' - (a_1 G)' + a_2 G) dr \\ &= - + \int_0^{R(t)} u (rG'' + G') dr. \end{aligned}$$

Thus under the radial integration  $L$  acts as self adjoint (there's probably some deeper reason for the way the algebra works out with the extra  $r$ , but from the algebra it works out at least). Thus we want to find  $G(s, r)$  such that  $sG_{ss}(s, r) + G_s(s, r) = \delta(s - r)$ . We already determined that the solution to the homogeneous equation is  $p(r) = A + B \log r$ . Thus we can split the Green's function into two parts:

$$G(s, r) = \begin{cases} A_- + B_- \log s & 0 < s < r \\ A_+ + B_+ \log s & r < s < R(t) \end{cases}.$$

The boundary conditions force  $B_- = -\frac{Q_0}{2\pi D}$  and  $A_+ = -B_+ \log R(t)$ . Continuity forces that  $A_- - \frac{Q_0}{2\pi D} \log r = B_+ \log \frac{r}{R(t)} \implies A_- = B_+ \log \frac{r}{R(t)} + \frac{Q_0}{2\pi D} \log r$ . Thus we can write  $G$  once again as

$$\begin{aligned} G(s, r) &= \begin{cases} B_+ \log \frac{r}{R(t)} + \frac{Q_0}{2\pi D} \log \frac{r}{s} & 0 < s < r \\ B_+ \log \frac{s}{R(t)} & r < s < R(t) \end{cases} \\ G_s(s, r) &= \begin{cases} -\frac{Q_0}{2\pi D s} & 0 < s < r \\ \frac{B_+}{s} & r < s < R(t) \end{cases}. \end{aligned}$$

The only condition left is the jump condition:

$$\begin{aligned} \int_{r-\epsilon}^{r+\epsilon} sG_{ss} + G_s ds &= \int_{r-\epsilon}^{r+\epsilon} (sG_s)_s ds = sG_s \Big|_{r-\epsilon}^{r+\epsilon} = r (G_s(r_+, r) - G_s(r_-, r)) = \int_{r-\epsilon}^{r+\epsilon} s\delta(r-s)ds = r \\ \implies 1 &= \frac{1}{r}B_+ + \frac{Q_0}{2\pi D r} \implies B_+ = r - \frac{Q_0}{2\pi D}. \end{aligned}$$

We can then get a final formulation for  $G$ :

$$G(s, r) = \begin{cases} r \log \frac{r}{R(t)} + \frac{Q_0}{2\pi D} \log \frac{R(t)}{s} & 0 < s < r \\ \left(r - \frac{Q_0}{2\pi D}\right) \log \frac{s}{R(t)} & r < s < R(t) \end{cases} = -\frac{Q_0}{2\pi D} \log \frac{s}{R(t)} + \begin{cases} r \log \frac{r}{R(t)} & 0 < s < r \\ r \log \frac{s}{R(t)} & r < s < R(t) \end{cases}.$$

Putting this together we can determine an expression for  $p(r, t)$  in terms of  $R(t)$  and  $g(r, t)$ :

$$p(r, t) = \int_0^r r \log \frac{r}{R(t)} g(s) s ds + \int_r^{R(t)} r \log \frac{s}{R(t)} g(s) s ds - \int_0^{R(t)} \frac{Q_0}{2\pi D} \log \frac{s}{R(t)} g(s) s ds.$$

**Question 2bii.** Plugging in  $r = R(t)$ :

$$p(R(t), t) = .$$