Non-Linear Data Structures

Binary Trees

Abstract representation of a binary tree

Binary trees can be stored in static array.

Each node contains:

- Left pointer
- Data
- Right pointer

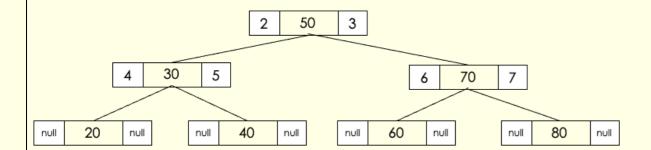
A binary tree can be stored as objects

Each node has a left pointer, a right pointer and the data being stored.

This is the node class and this is used to create a new_node object.

class node:

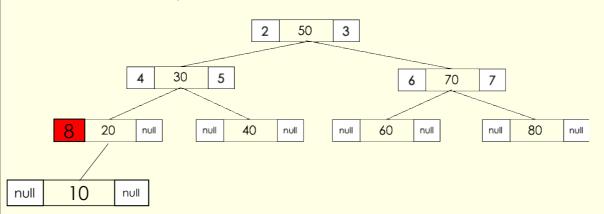
data = None left_pointer = None right_pointer = None



Position	Left Pointer	Value	Right Pointer
1	2	50	3
2	4	30	5
3	6	70	7
4	null	20	null
5	null	40	null
6	null	60	null
7	null	80	null

Adding a node

- Create a new node
- Search the tree to find the location in of the new node
- Add a pointer from parent node to the new node
- Make new node point to null



Position	Left Pointer	Value	Right Pointer
1	2	50	3
2	4	30	5
3	6	70	7
4	8	20	null
5	null	40	null
6	null	60	null
7	null	80	null
8	null	10	null

Inserting a node to a binary tree

- 1. Check there is free memory for a new node if no free memomirt output error
- 2. Create a new node and insert data into it

Removing an item from a binary tree

Find the node to be deleted

1. Start at the root node and set it as the current node.

3. If the binary tree is empty:	2. While the current node exists and it is not the one to be deleted:
New node becomes first itemSet start pointer	a. Set the previous node variable to be the same as the current node.
4. If the binary tree is empty:	b. If the item to be deleted is less than the current node, follow the left pointer and set the discovered node as the current node.
 Start at the root node If the new node should be placed before the current node, follow the left pointer If the new node should be placed after the current node, follow the right position Repeat until left node reached (pointer is NULL) 	c. If the item to be deleted is greater than the current node, follow the right pointer and set the discovered node as the current node.
 If the new node should be placed before the current node, set the left pointer to the be the new node 	The node to be deleted has no children
 If the new node should be placed after the current node, set the right pointer to the be the new node 	3. If the previous node is greater than the current node, the previous node's left pointer is set to null.
	4. If the previous node is less than the current node, the previous node's right pointer is set to null.
	The node to be deleted has one child
	5. If the current node is less than the previous node:
	a. Set the previous node's left pointer to the current node's left child.
	6. If the current node is greater than the previous node:
	a. Set the previous node's right pointer to the current node's right child.
	The node to be deleted has two children
	7. If a right node exists and it has a left sub-tree, find the smallest leaf node in the right sub-tree:
	a. Change the current node to the smallest leaf node.
	b. Remove the smallest leaf node.
	8. If a right node exists and it has no left sub-tree:
	a. Set the current node to be the current node's right pointer.
	b. Set the current node's right pointer to null.

Binary Tree Traversals

Pre-order is used to create a copy of a tree.

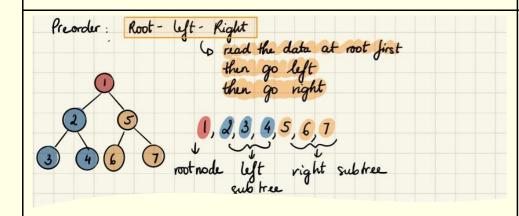
- 1. Visit the root.
- 2. Traverse the left subtree,
- 3. Traverse the right subtree

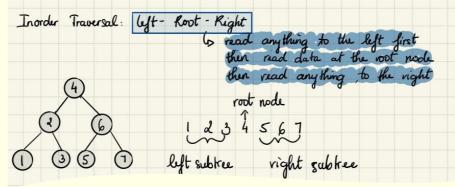
In-order traversal gives nodes in nondecreasing order.

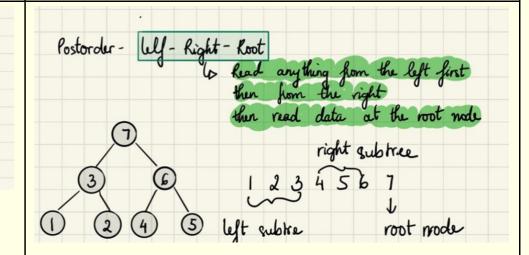
- 1. Traverse the left subtree.
- 2. Visit the root.
- 3. Traverse the right subtree

Post-order delete a tree

- 1. Traverse the left subtree
- 2. Traverse the right subtree
- 3. Visit the root.







Algorithm Preorder

procedure preorder(current_node)

if current_node != None:

#Visit each node: NLR

print(current_node.data)

if current_node.left_pointer != None:

preorder(current_node.left_pointer)

if current_node.right_pointer!= None:

preorder(current_node.right_pointer)

Algorithm Inorder

procedure inorder(current_node)

if current_node != None:

#Visit each node:

if current_node.left_pointer != None:

inorder(current_node.left_pointer)

print(current_node.data)

if current_node.right_pointer!= None:

.norder(current_node.right_pointer)

Algorithm Postorder

procedure postorder(current_node):

if current_node != None:

#Visit each node: LRN

if current_node.left_pointer != None:

postorder(current_node.left_pointer)

if current_node.right_pointer != None:

postorder(current_node.right_pointer)

print(current_node.data)

Graphs

node

Adjacency List With No Weighting

Weighted graph

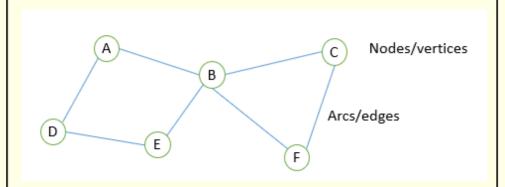
Directed Graph

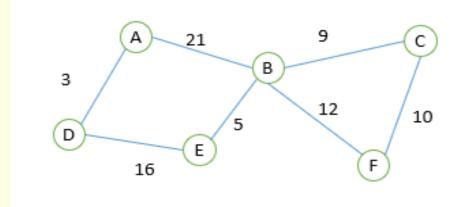
Weighted graphs add a value to an arc.
This might represent the distance between places or the time

taken between train stations

Directed graphs only apply in one direction and are represented with edges with arrow heads on one end.

Graphs with no weights are given a value of 1 for connected nodes.





D E F

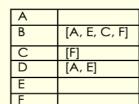
First)					
		Α	[D, B]	, ,		
node is		В	[A, E, C,F]		The next	`
the	[С	[B, F]		nodes should	
parent/p		D	[A, E]			
revious		Е	[D, B]		be in	

alphabetical

order

Ad	jacency	List

Α	{D:3, B:21}
В	{A:21, E:5, C:9, F:12}
С	{B:9, F:10}
D	{A:3, E:16}
Е	{D:16, B:5}
F	(B-12 C-10)



	Α	В	O	D	Е	F
Α	-	1	-	1	1	-
В	1	-	1	-	1	1
С	-	1	-	-	-	1
D	1	-	-	-	1	-
E	-	1	-	1	-	-
F	-	1	1	-	-	-

[B, C]

Adjacency Matrix

	Α	В	С	D	Е	F
Α	1	21	-	3	1	-
В	21	-	9	-	5	12
С	1	9	1	1	1	10
D	3	-	1	1	16	-
Е	-	5	-	16	-	-
F	-	12	10	-	-	-

	То						
		Α	В	С	D	Е	F
From	Α						
	В	1		1		1	1
	С						1
	D	1				1	
	E						
	F						

Depth-first search	Breadth-First search
Uses a stack to manage traversal	Uses a queue to manage traversal
Visits padas by avalaring as far down one branch as possible before backtracking	Visits nodes level by level exploring all neighbours before moving to the next level