### Deep Neural Networks - Lecture 3

Marcin Mucha

March 15, 2017

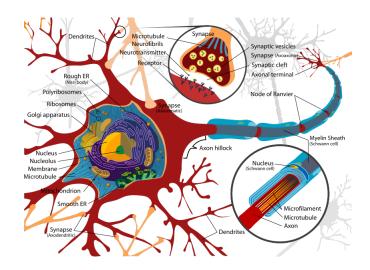
Neural Networks and Backpropagation

Trouble with neural networks

# Where it all begins

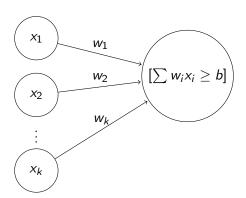
- ▶ Many settings where humans outperform best algorithms.
- ▶ Idea: Emulate the human brain.
- ▶  $10^{11}$  neurons,  $10^{14}$  connections in the brain. Trouble?
- ► Compare: a 10 TB drive can store 10<sup>14</sup> bytes.

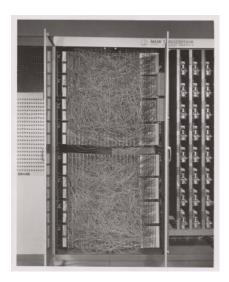
# Where it all begins



The perceptron is a function that, given inputs  $x_1, \ldots, x_k$  outputs  $[\sum_i w_i x_i + b \ge 0]$  (or a specific GD-like algo for fitting these).

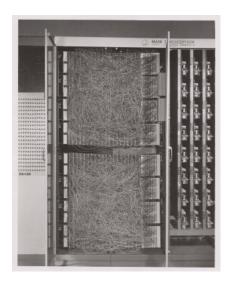
Think:  $x_i$  are factors contributing to a decision, they are weighted and the perceptron makes a decision automatically!





#### Mark I Perceptron (1957)

- Funded by US Navy.
- Photo recognition.
- 20x20 photo-cells.
- Weights in potentiometers.
- Trained with the perceptron algorithm - weights updated by electric motors.



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...the embryo of an electronic computer that [the Navy] expects will be able to walk, talk, see, write, reproduce itself and be conscious of its existence...

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Many smooth step functions possible, e.g. the sigmoid function  $\sigma(x) = \frac{1}{1+e^{-x}}$ . Rings a bell?



Perceptrons can only separate half-spaces.

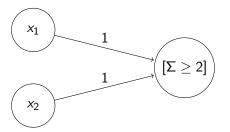
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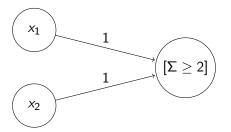
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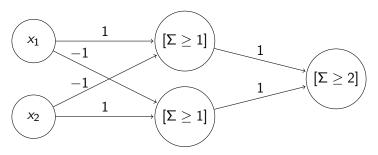


**Exercise:** Can a perceptron compute XOR?

**Exercise:** Show that a DAG of perceptrons can compute XOR.

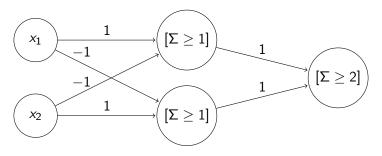
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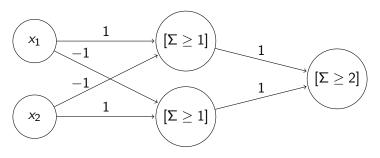
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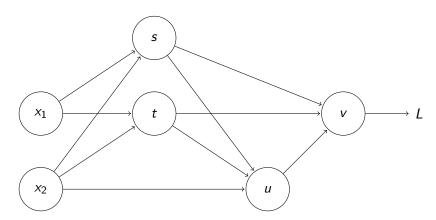
Note that this DAG can be very large (think: SAT).



...but can we train DAGs of perceptrons?

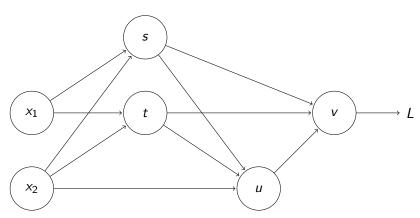
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More specifically: Given a DAG of sigmoid approximations to the perceptron, can we compute gradients of the loss function?

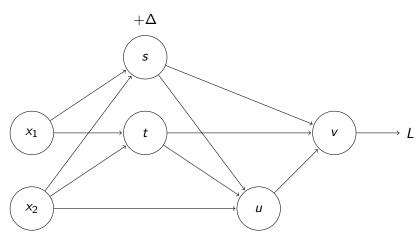


#### Theorem

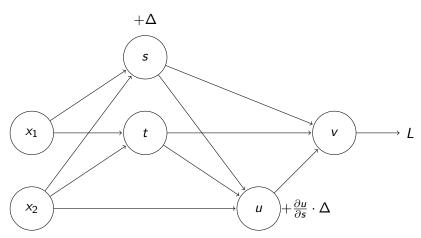
#### **Theorem**



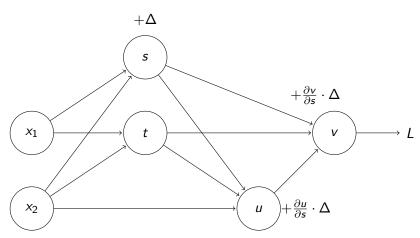
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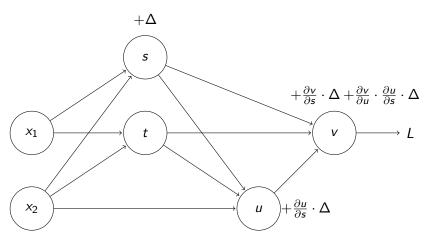
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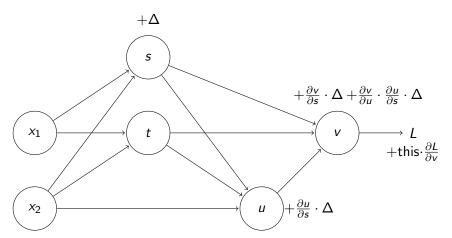
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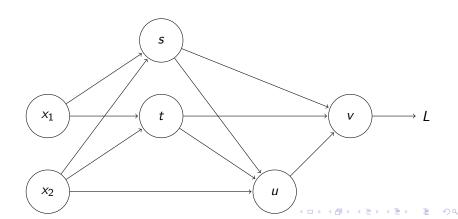


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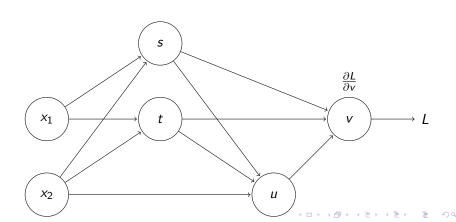


$$\frac{\partial L}{\partial z} = \sum_{z=z_0 \to \dots \to z_l = L} \prod_{i=1}^{l-1} \frac{\partial z_{i+1}}{\partial z_i}.$$

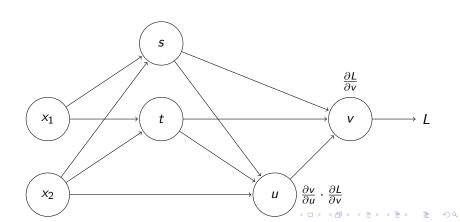
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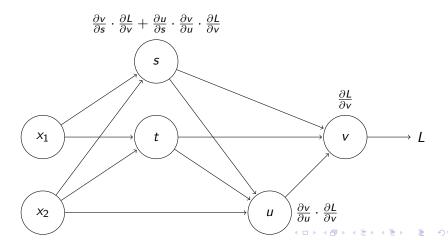
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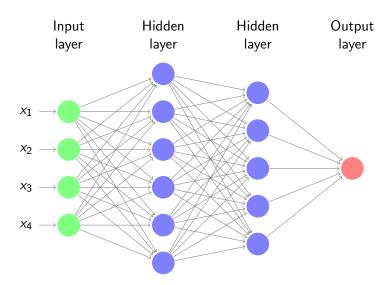
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Computing the derivatives of nodes over their parameters is trivial.

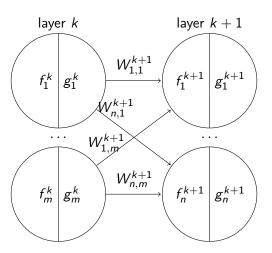
# Multilayer Perceptron (MLP)

- Multilayer Perceptron (MLP), or a Feedforward Neural Network consists of several layers of units (sigmoid or other), each connected with previous and next.
- ▶ Number of layers (excluding inputs) is called the *depth*.
- ▶ The inner layers are called *hidden*.

# Multilayer Perceptron (MLP)



## Matrix algebra - notation



Regular structure of MLPs facilitates algebraic shortcuts both in forward and backward pass.

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$$\frac{\partial L}{\partial g^{k-1}} = W^{\mathsf{T}} \frac{\partial L}{\partial f^k}.$$

Again,  $\frac{\partial L}{\partial g^{k-1}}$  and  $\frac{\partial L}{\partial f^k}$  can be vectors or matrices.

**Exercise:** Relate  $\frac{\partial L}{\partial f^k}$  and  $\frac{\partial L}{\partial g^k}$ , if  $g^k = \sigma(f^k)$  (coordinate-wise).

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**Solution:** 

$$\frac{\partial L}{\partial f^k} = \frac{\partial L}{\partial g^k} \circ g^k \circ \left(1 - g^k\right).$$

 $A \circ B$  is the Hadamard (element-wise) product.

**Exercise:** Relate  $\frac{\partial L}{\partial f^k}$  and  $\frac{\partial L}{\partial W^k}$  (this is the matrix of partial derivatives over all elements of  $W^k$ ).

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#### **Solution:**

$$\frac{\partial L}{\partial W^k} = \frac{\partial L}{\partial f^k} \left( g^{k-1} \right)^T.$$

Note that for batches summing up happens automagically!

#### The art of neural networks

In the non-modern setting, setting the parameters of neural networks was more art than science:

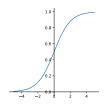
- Choosing the architecture.
- Choosing the units.
- Controlling the learning rate.
- Initializing the weights.
- And other (regularization, mini-batch size, etc.)

These issues were addressed by recent developments.

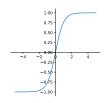
#### Architecture

- Bigger network is more expressive.
- Bigger networks take longer to train.
- Deeper networks are much harder to train.
- ► Modern variants of SGD are much better at training deep nets. And we have stronger hardware.
- ▶ Confront: If your deep neural net is not overfitting you should be using a bigger one! – G. Hinton

### Units



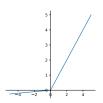
sigmoid: 
$$\sigma(x) = \frac{1}{1+e^{-x}}$$



$$tanh: tanh(x) = \frac{e^x + e^{-x}}{e^x + e^{-x}}$$



ReLU: ReLU(x) = max(0, x)



leaky ReLU: 
$$LReLU(x) = max(ax, x)$$

### Learning rate

- ▶ If the learning rate is too small, convergence is very slow.
- ▶ Learning rate that is too high results in oscillations.
- ▶ Some modern variants of SGD can automatically adapt.

#### Initialization

- Very small initial weights slow down learning initially, or even completely vanish.
- ▶ Very large initial weights can lead to oscillations and random-like behaviour or even blow-up with no regularization.
- ▶ Heuristics, e.g. Glorot initialization: draw a weight from normal distribution with variance  $\frac{2}{n_{in}+n_{out}}$ .
- Modern techniques like batch normlization make initialization less of an issue.

### Recap

- ▶ Perceptron and its biological and computational motivation.
- ▶ Multilayer perceptron and how to compute its gradients fast.
- Tricky decisions when tuning MLPs.

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- Tricky decisions when tuning MLPs.

#### But do not worry:

- Sometimes MLPs work well even without excessive tuning.
- ▶ Next lecture, we will make things much more stable.