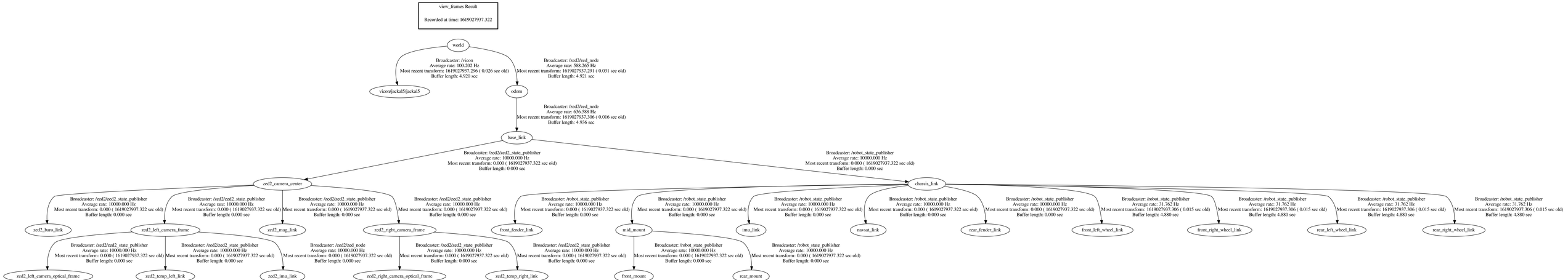
view_frames Result
Recorded at time: 1619027937.322
world
Broadcaster: /vicon
Average rate: 100.202 Hz
Most recent transform: 1619027937.296 (0.026 sec old)
Buffer length: 4.920 sec
Broadcaster: /zed2/zed_node
Average rate: 588.265 Hz
Most recent transform: 1619027937.291 (0.031 sec old)
Buffer length: 4.921 sec
vicon/jackal5/jackal5
odom
Broadcaster: /zed2/zed_node
Average rate: 636.588 Hz
Most recent transform: 1619027937.306 (0.016 sec old)
Buffer length: 4.936 sec
base_link
Broadcaster: /zed2/zed2_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1619027937.322 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1619027937.322 sec old)
Buffer length: 0.000 sec
zed2_camera_center
chassis_link
Broadcaster: /zed2/zed2_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1619027937.322 sec old)
Buffer length: 0.000 sec
zed2_baro_link
zed2_left_camera_frame
zed2_mag_link
zed2_right_camera_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1619027937.322 sec old)
Buffer length: 0.000 sec
front_fender_link
mid_mount
imu_link
navsat_link
rear_fender_link
Broadcaster: /robot_state_publisher
Average rate: 31.762 Hz
Most recent transform: 1619027937.306 (0.015 sec old)
Buffer length: 4.880 sec
front_left_wheel_link
front_right_wheel_link
rear_left_wheel_link
rear_right_wheel_link
Broadcaster: /zed2/zed2_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1619027937.322 sec old)
Buffer length: 0.000 sec
zed2_left_camera_optical_frame
zed2_temp_left_link
zed2_imu_link
Broadcaster: /zed2/zed_node
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1619027937.322 sec old)
Buffer length: 0.000 sec
zed2_right_camera_optical_frame
zed2_temp_right_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1619027937.322 sec old)
Buffer length: 0.000 sec
front_mount
rear_mount