

Cimple: Instruction and Memory Level Parallelism DSL

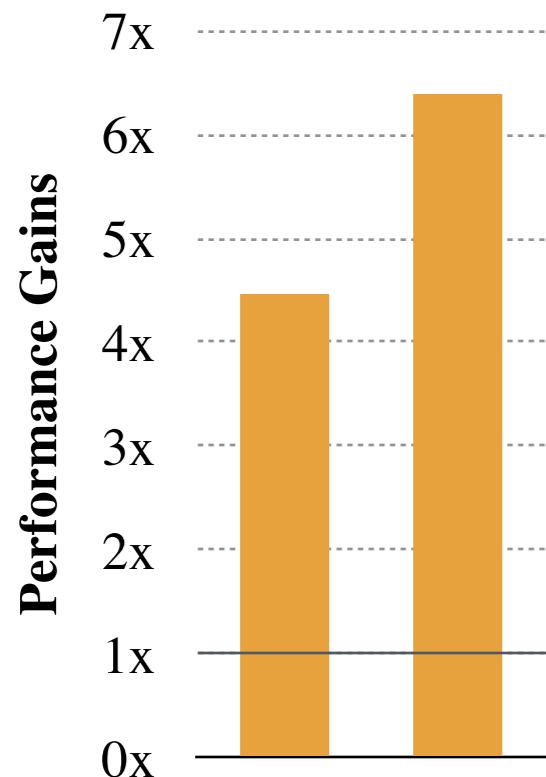
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Martin Rinard, Saman Amarasinghe

PACT'18

November 3, 2018
Limassol, Cyprus



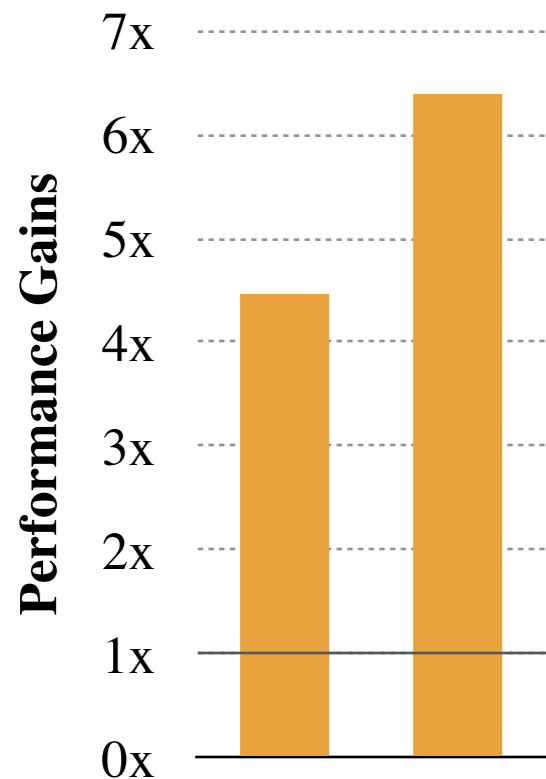
Cimple Performance Gains



Binary Binary
Search Tree

[Haswell]

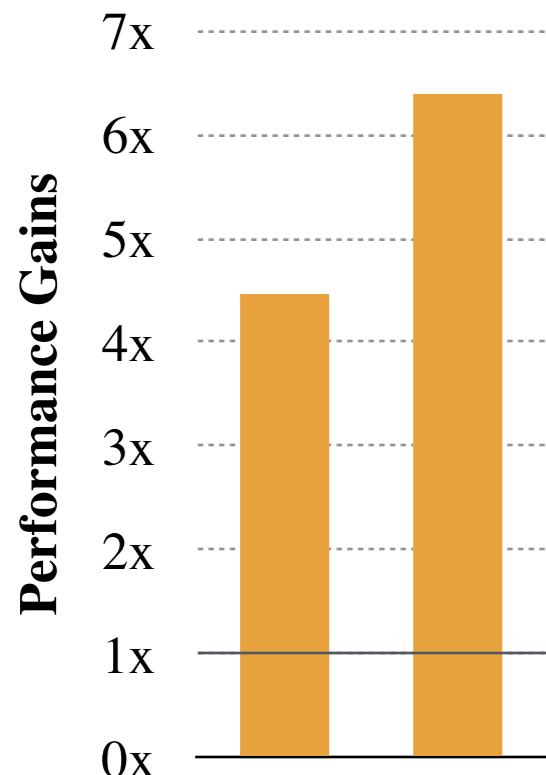
Cimple Performance Gains



- Are we teaching the wrong algorithms?

[Haswell]

Cimple Performance Gains



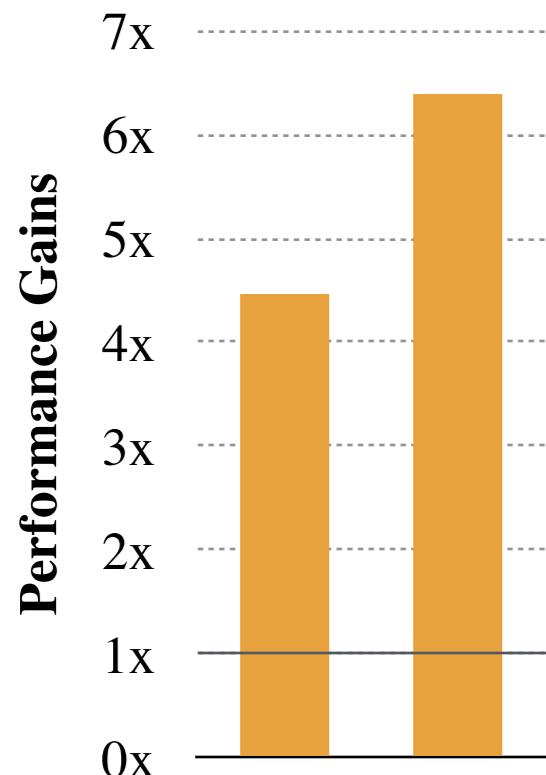
Binary Search Tree

STL

[Haswell]

- Are we teaching the wrong algorithms?

Cimple Performance Gains



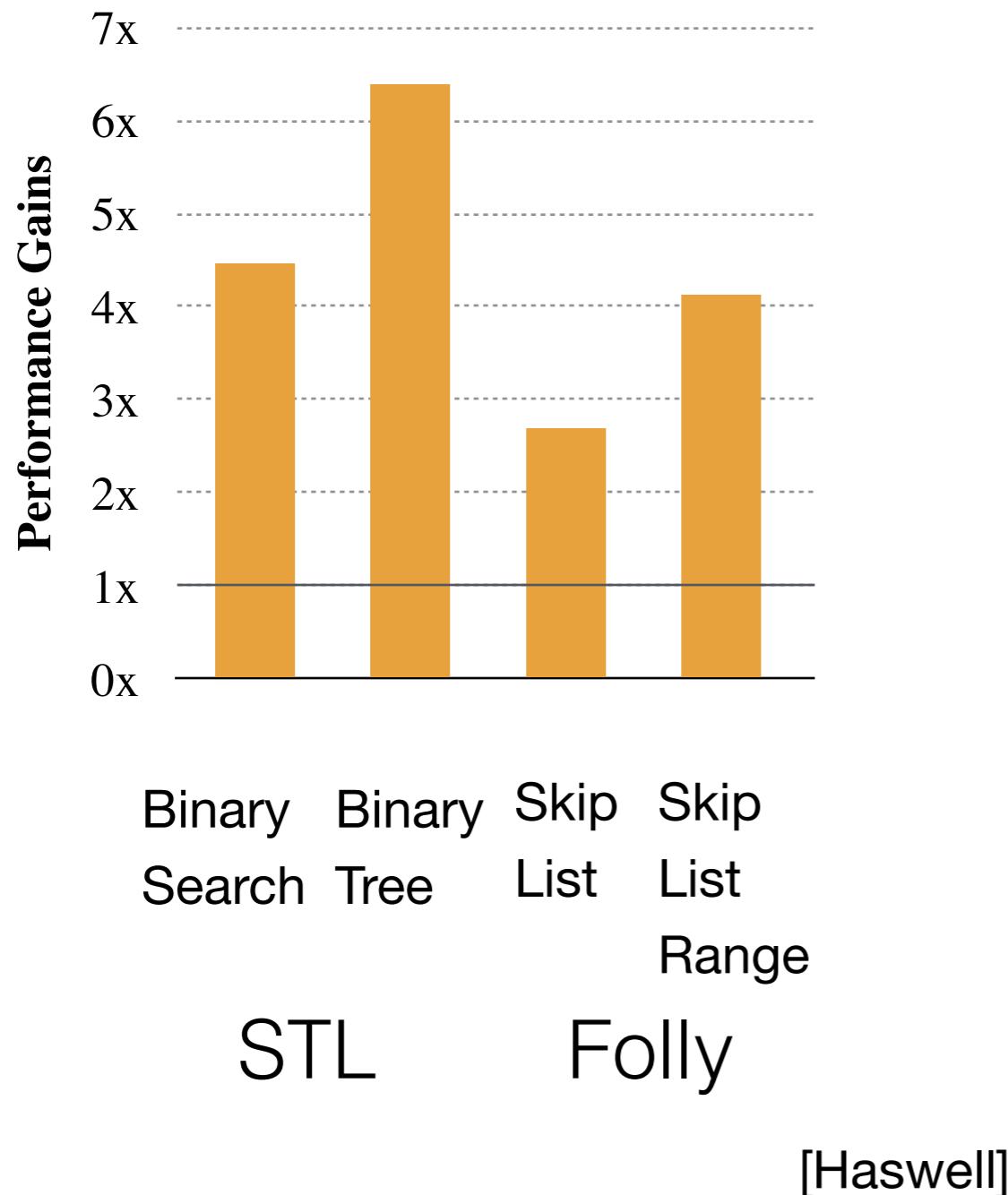
- Are we teaching the wrong algorithms?
- Is STL using bad implementations?

Binary Search Tree

STL

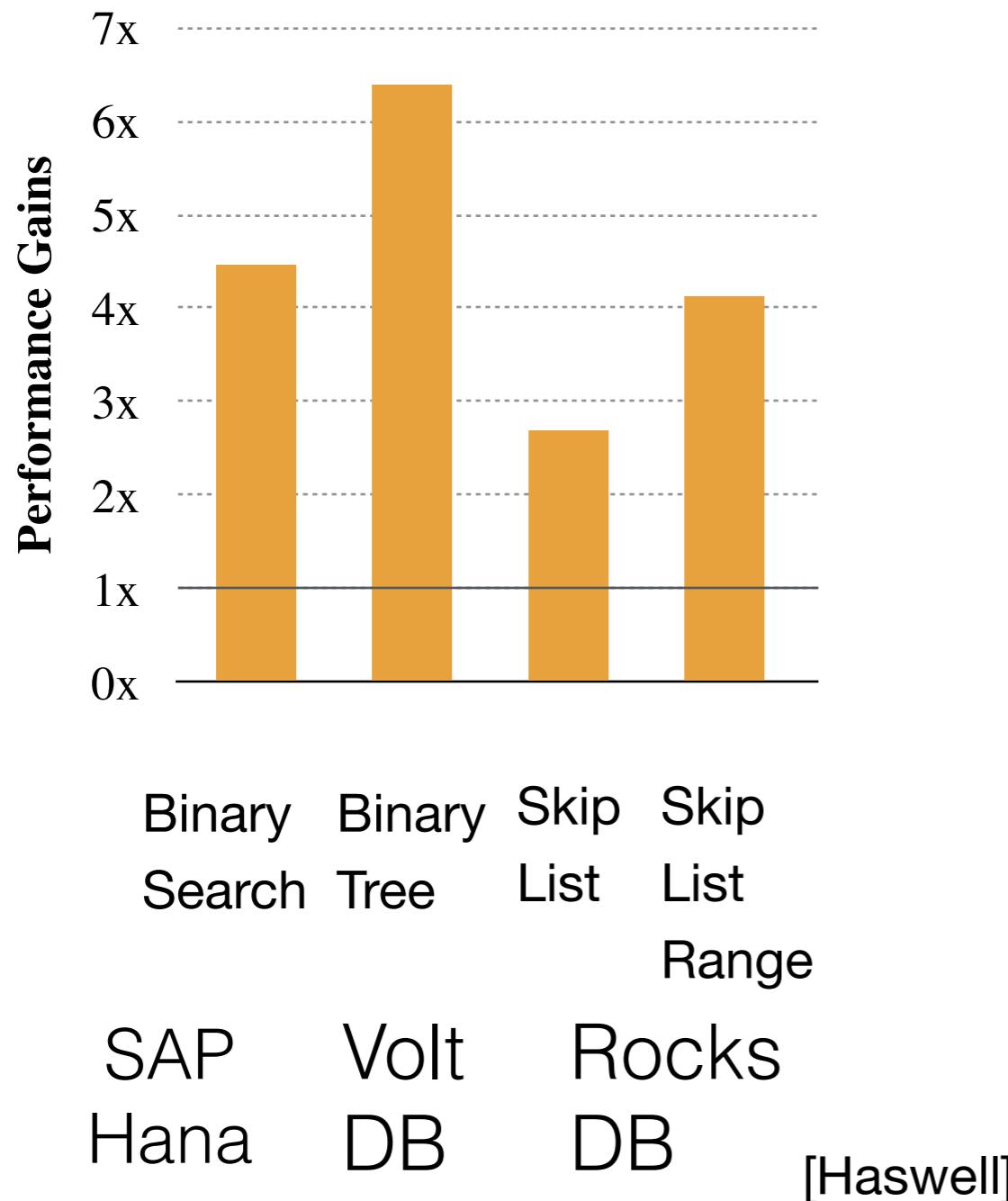
[Haswell]

Cimple Performance Gains



- Are we teaching the wrong algorithms?
- Is STL using bad implementations?

Cimple Performance Gains

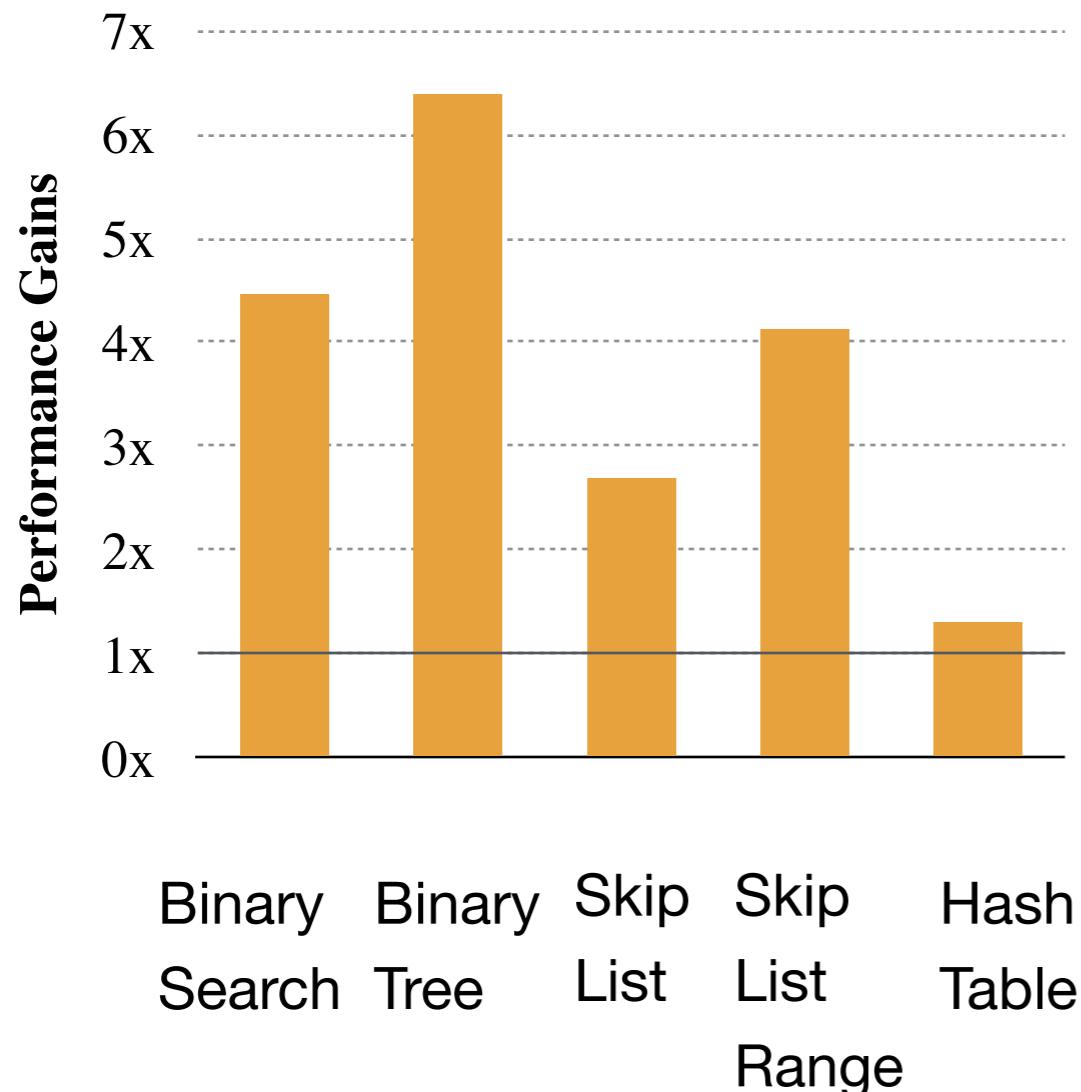


- Are we teaching the wrong algorithms?
- Is STL using bad implementations?

In-Memory Databases

- Terabyte Working Sets
 - AWS 12 TB VM
- Binary Search
 - SAP Hana
- Binary Tree (partitioned)
 - VoltDB
- Skip List (shared)
 - RocksDB, MemSQL

Cimple Performance Gains



- Are we teaching the wrong algorithms?
- Is STL using bad implementations?
- Does our programming model match hardware?

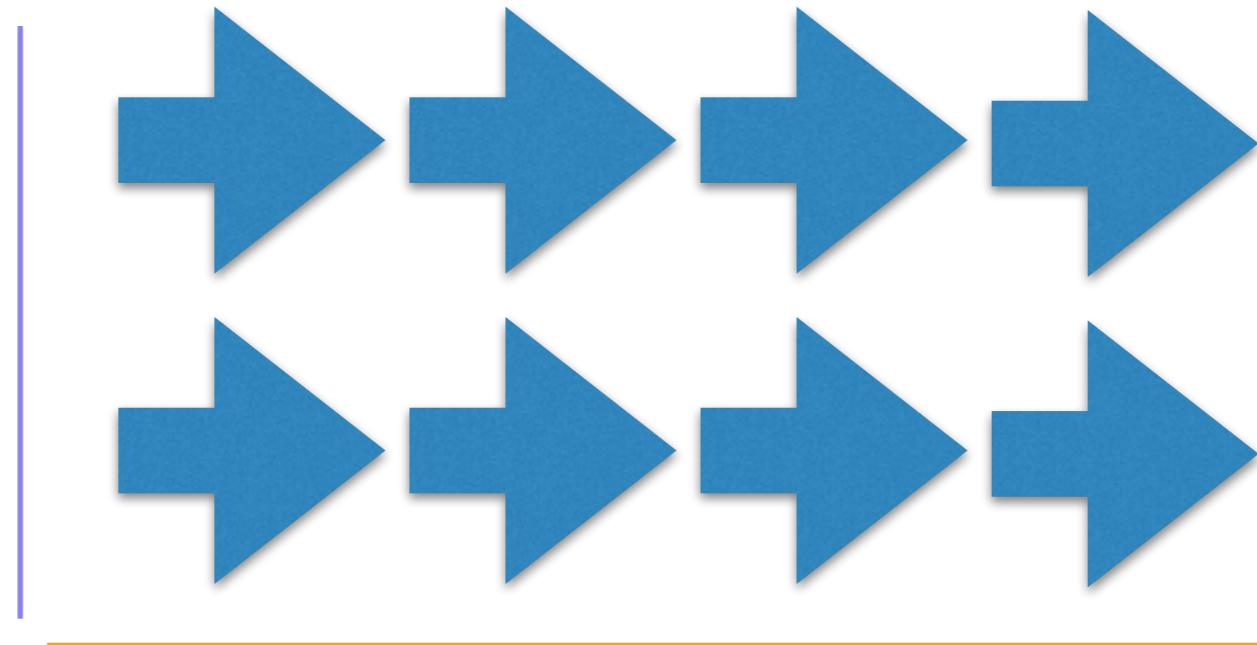
[Haswell]

Little's Law

$$L = \lambda W$$

Arrival
Rate

$$\lambda$$



Concurrency

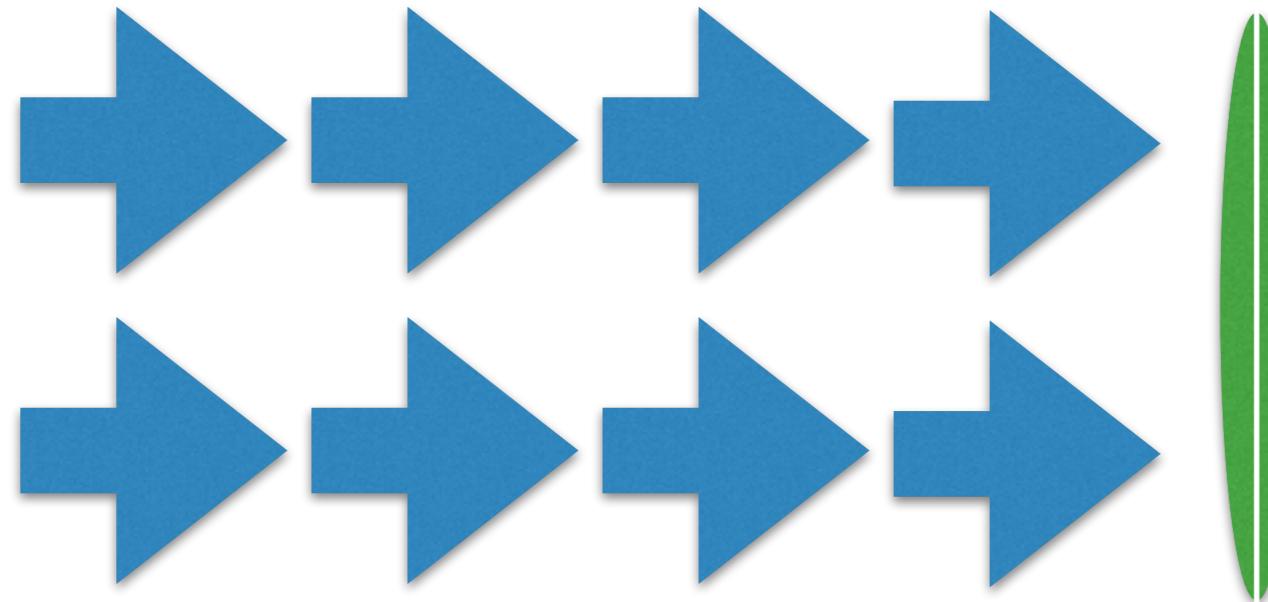
$$L$$

Latency

$$W$$

Little's Law

$$L = \lambda W$$



Concurrency

$$L = 8$$

Latency

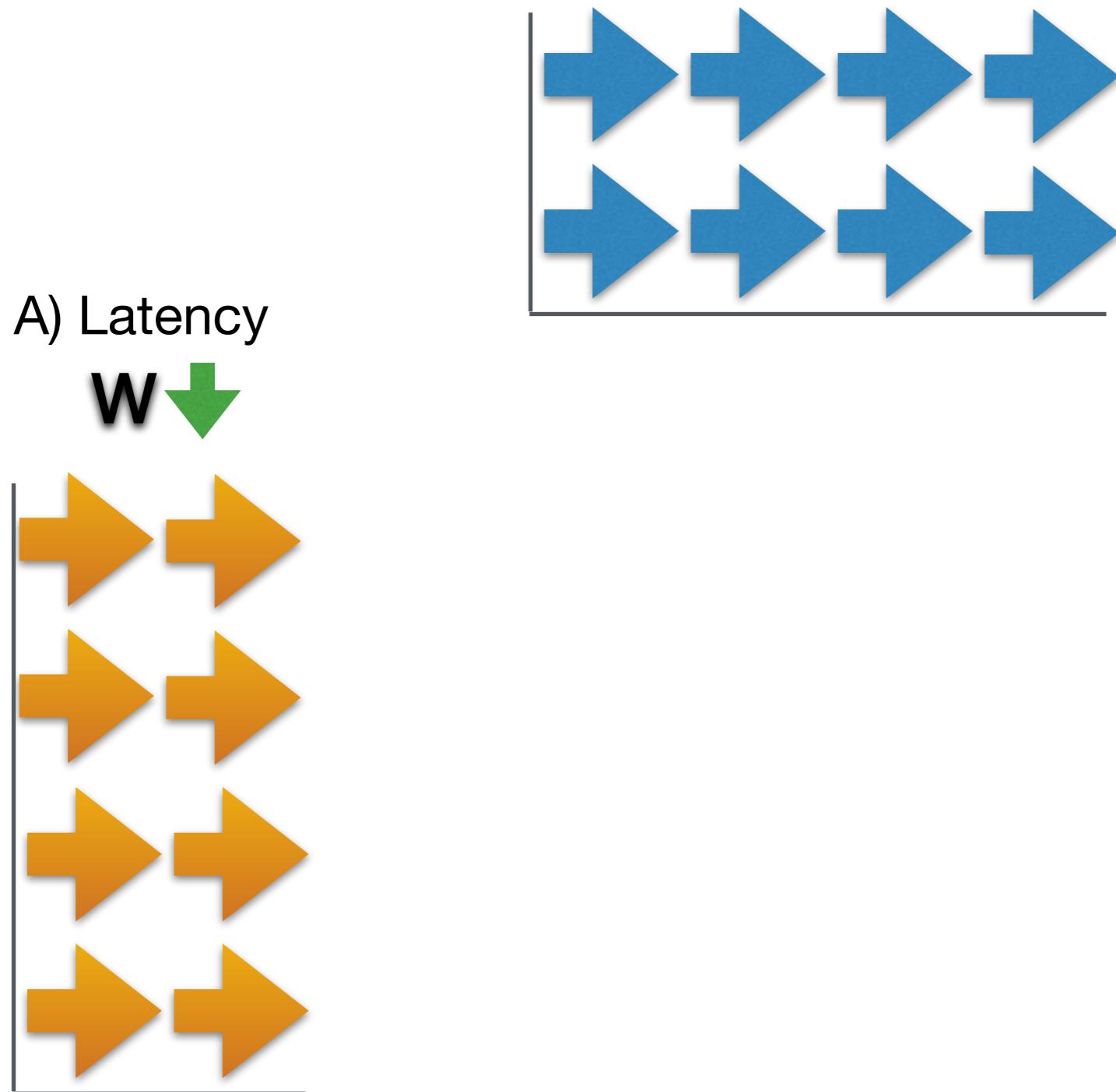
$$W = 4$$

Arrival =
Departure

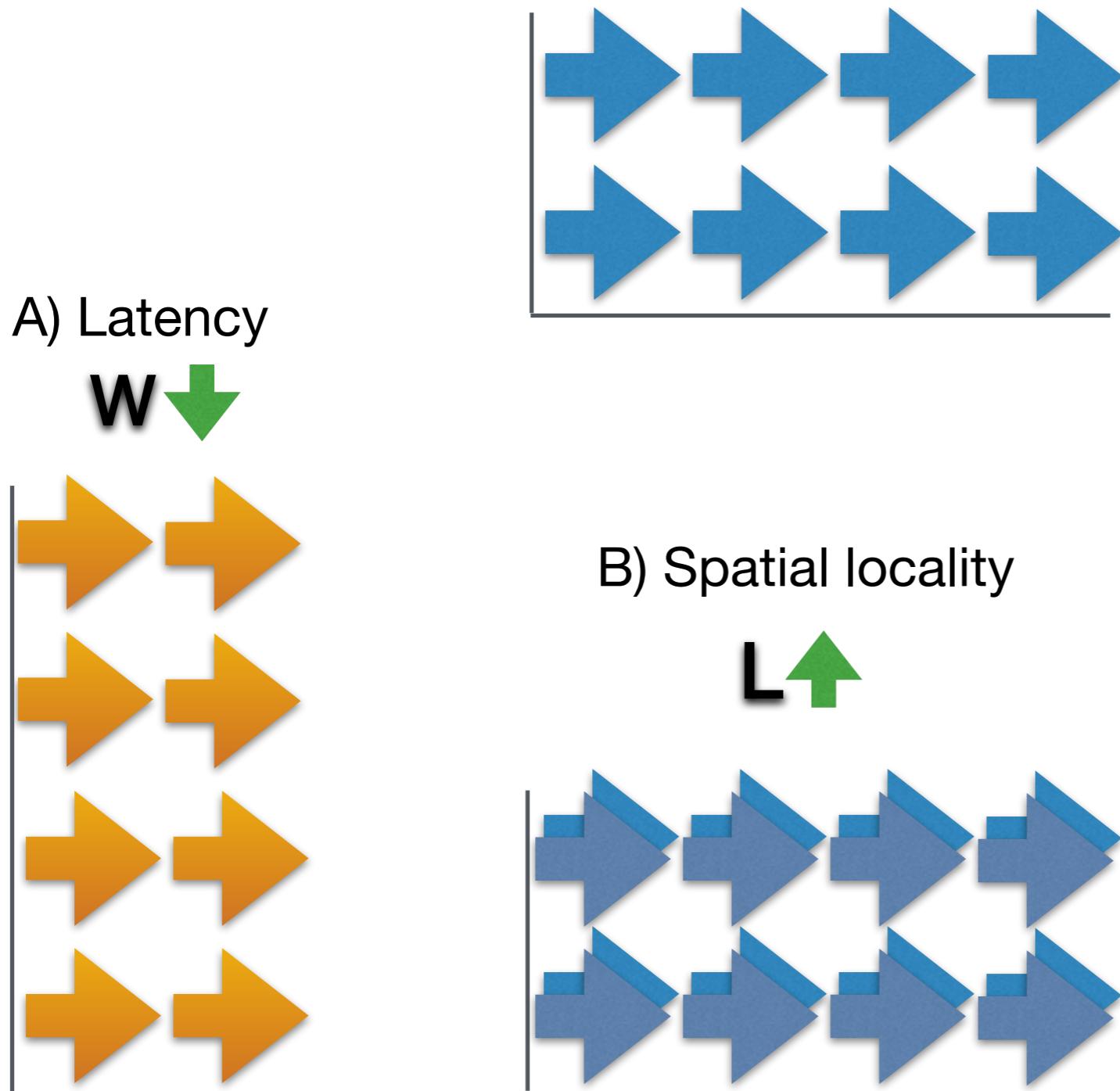
$$\lambda = X = 2$$

Bandwidth

Three Improvement Paths

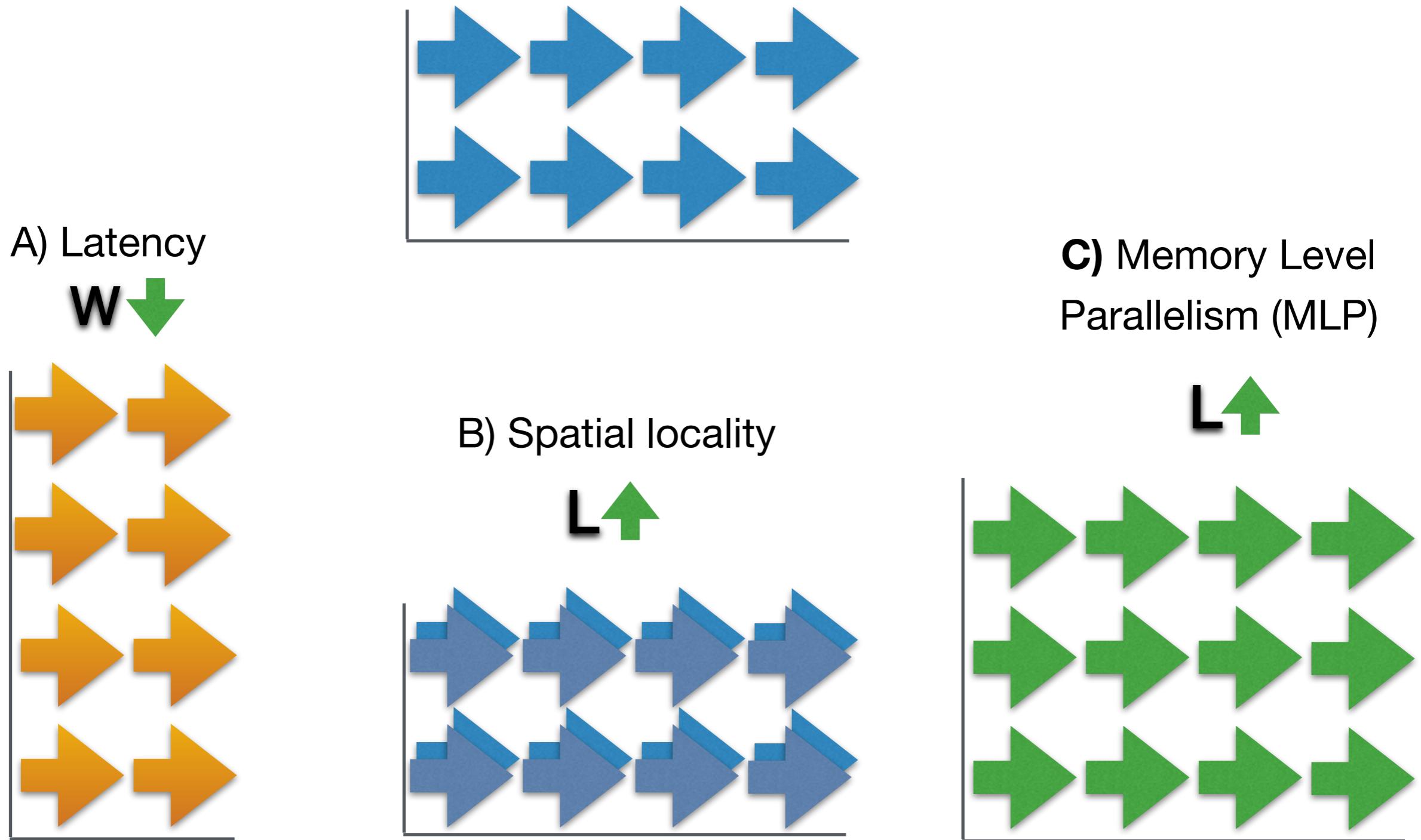


Three Improvement Paths



milk [Kiriansky et al, PACT'16]

Three Improvement Paths





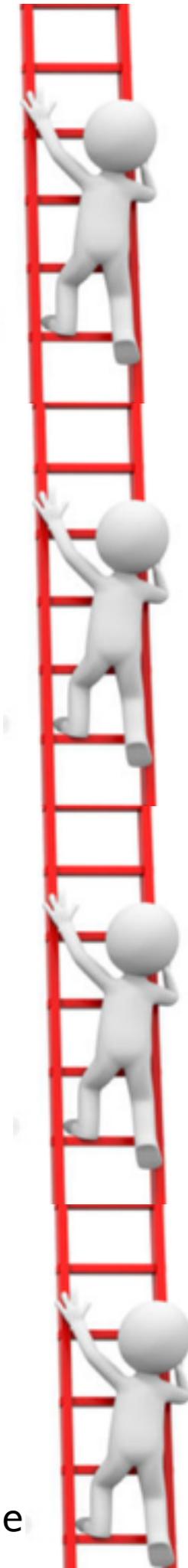
Memory Wall

- Speculative out-of-order processors:
automatically discover MLP



Memory Wall

- Speculative out-of-order processors: automatically discover MLP
- Non-blocking caches - Miss Status Handling Registers (MSHRs)
- Large Instruction Windows

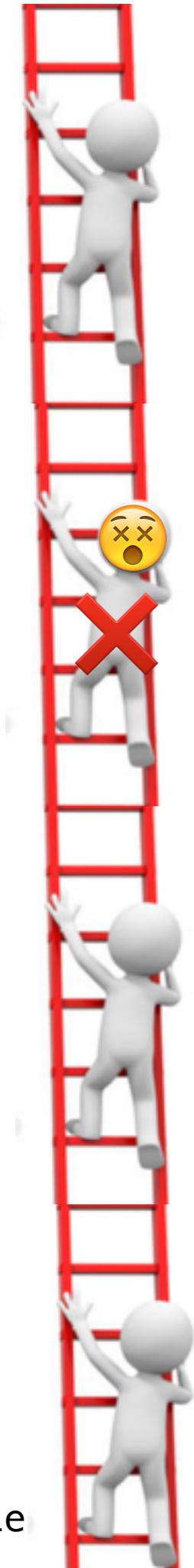


Memory Wall Conquered?

- Speculative out-of-order processors: automatically discover MLP
- Non-blocking caches - Miss Status Handling Registers (MSHRs) = 10 misses
- Large Instruction Windows ~200 instructions

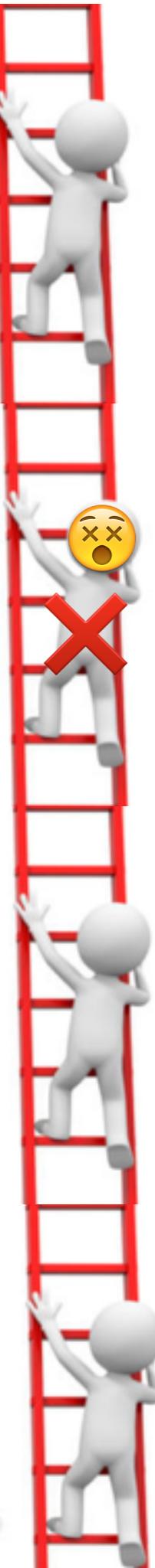
Branch Mispredictions





Memory Wall Conquered?

- ✗ Branch Misprediction



Memory Wall Conquered?

✗ Branch Misprediction

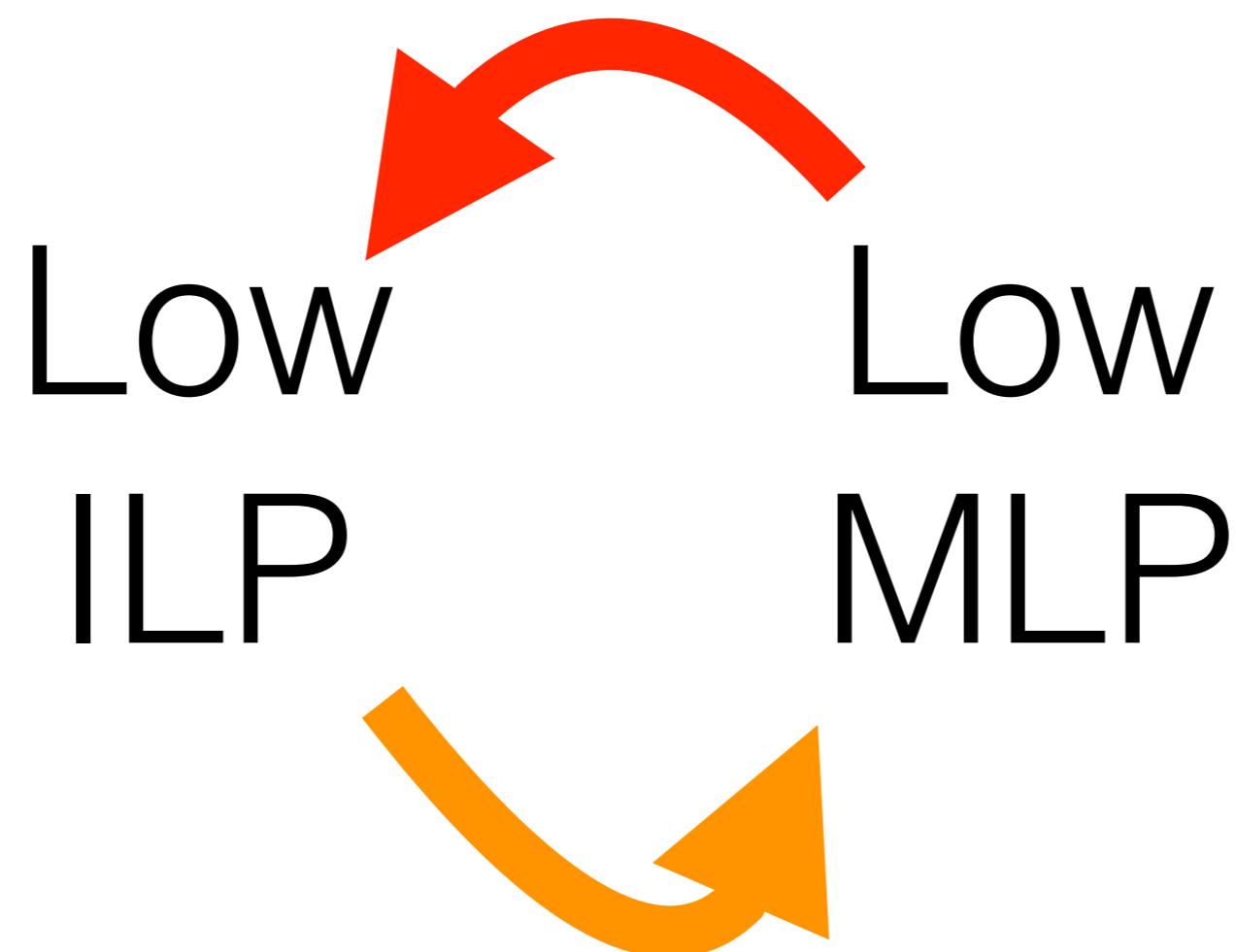




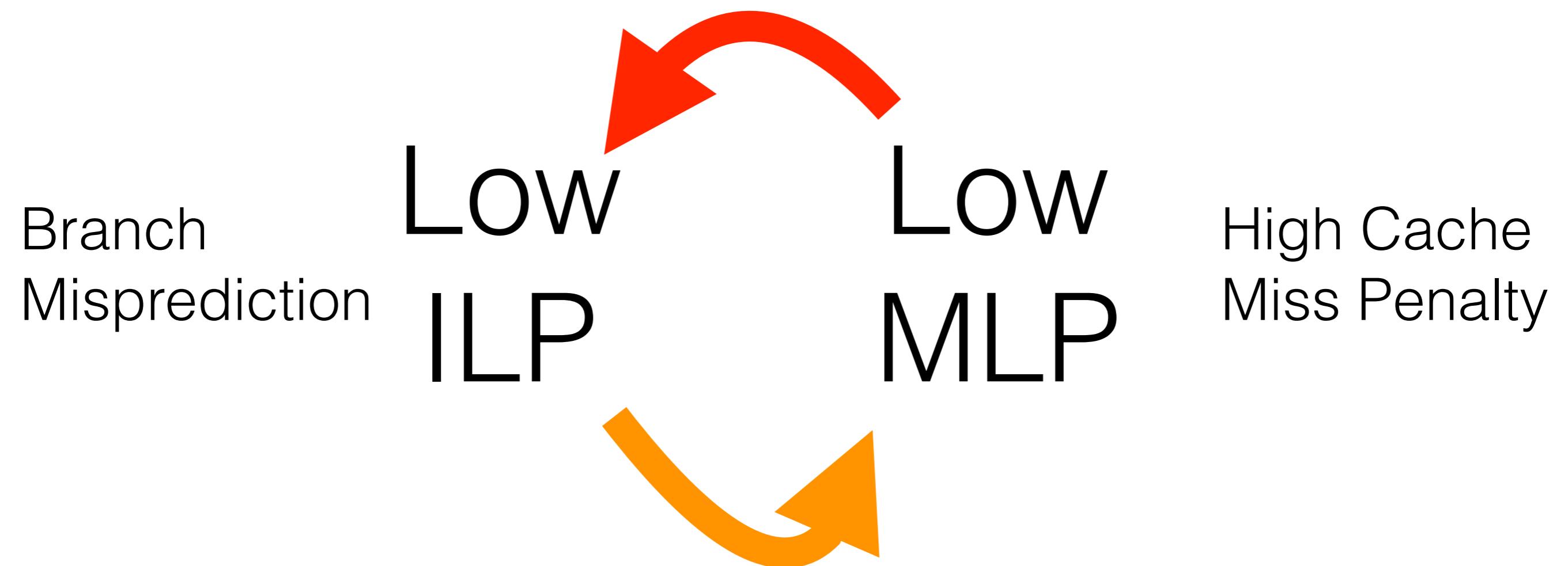
Memory Wall

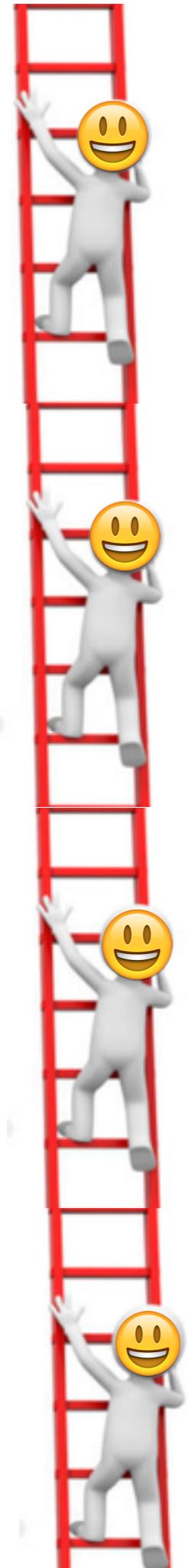
- ✖ Branch Misprediction
- ✖ Re-execution of correct path of independent tasks

ILP / MLP Vicious cycle



ILP / MLP Vicious cycle





Cimple Alternative

- Avoid speculation for MLP - harness Request Level Parallelism (RLP)
- Tasks pipelined on one thread
- Cooperatively context switch on *likely* cache miss

Outline

- Cimple Co-Routines Overview
- Static and Dynamic Schedulers
- Related Work
- Cimple DSL and Code Generation
- Performance Evaluation
- Conclusion & Q/A

Cimple Overview

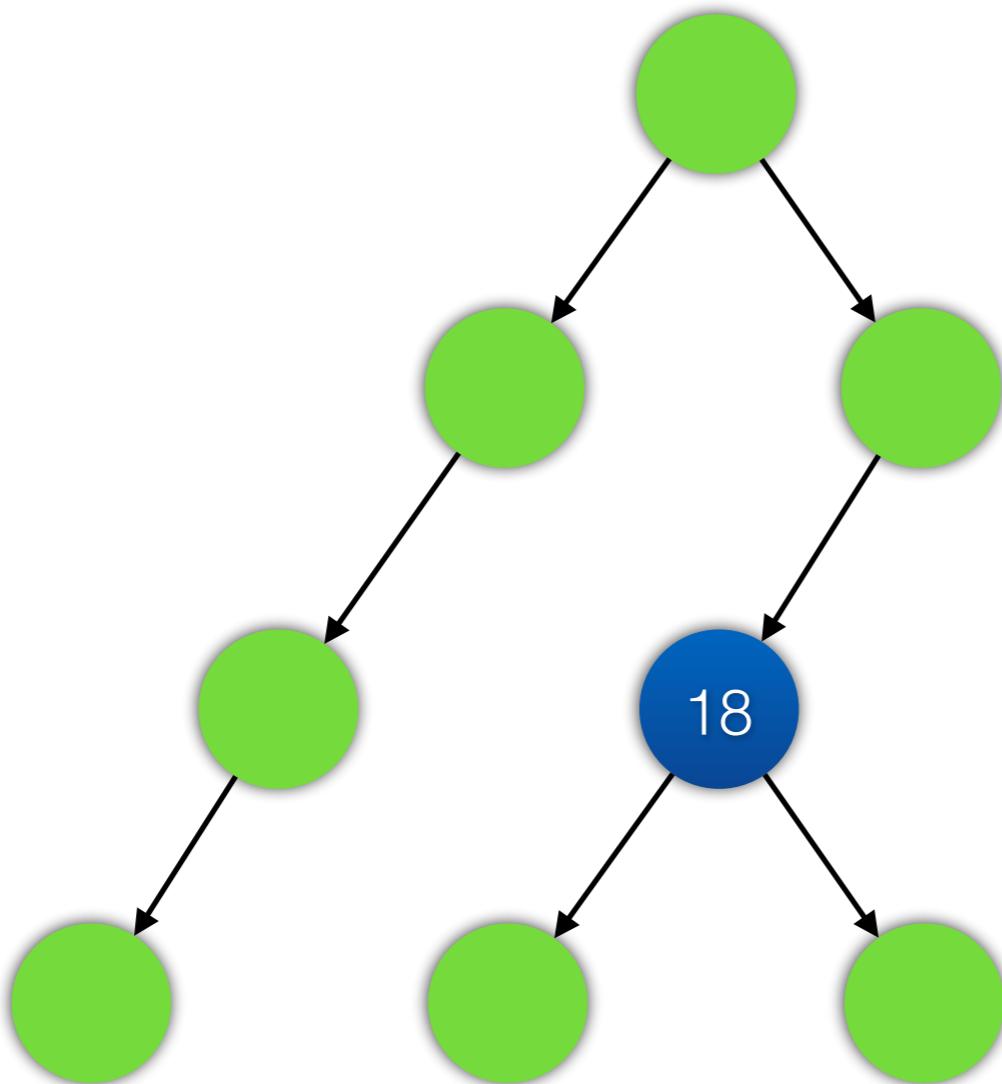
Traditional

One task per thread

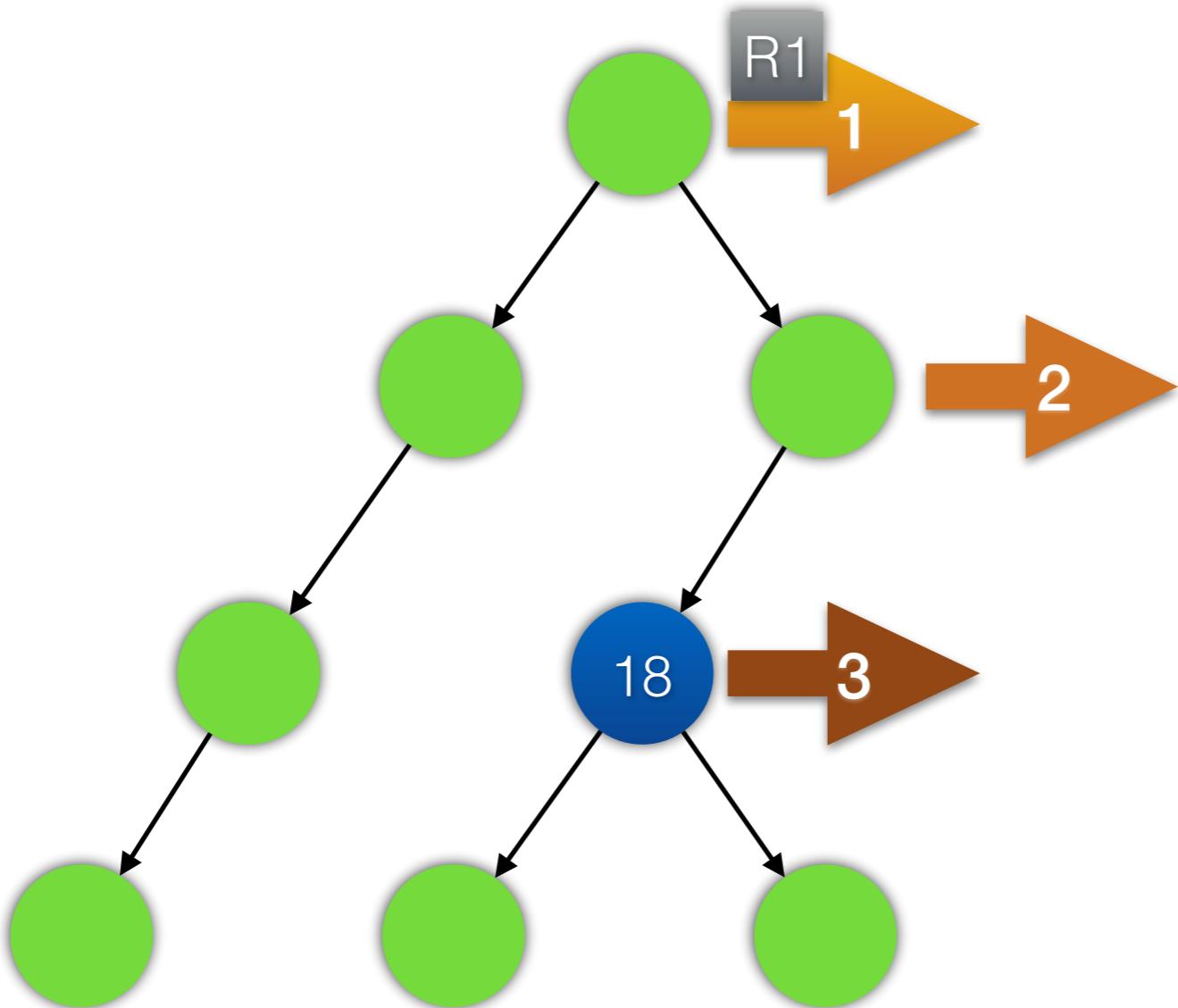
- Traditional dependence chain
- Request 1 executed to completion



Binary Tree



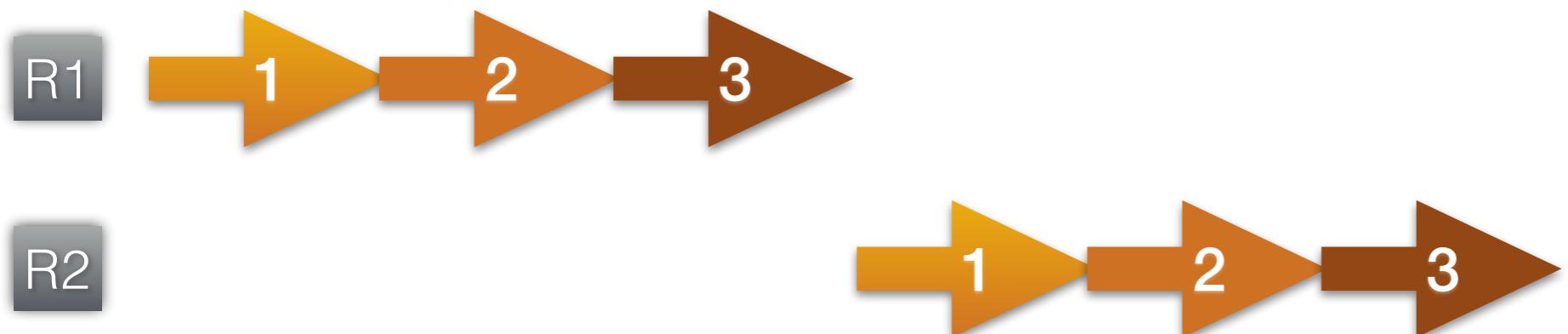
Binary Tree



Traditional

One task per thread

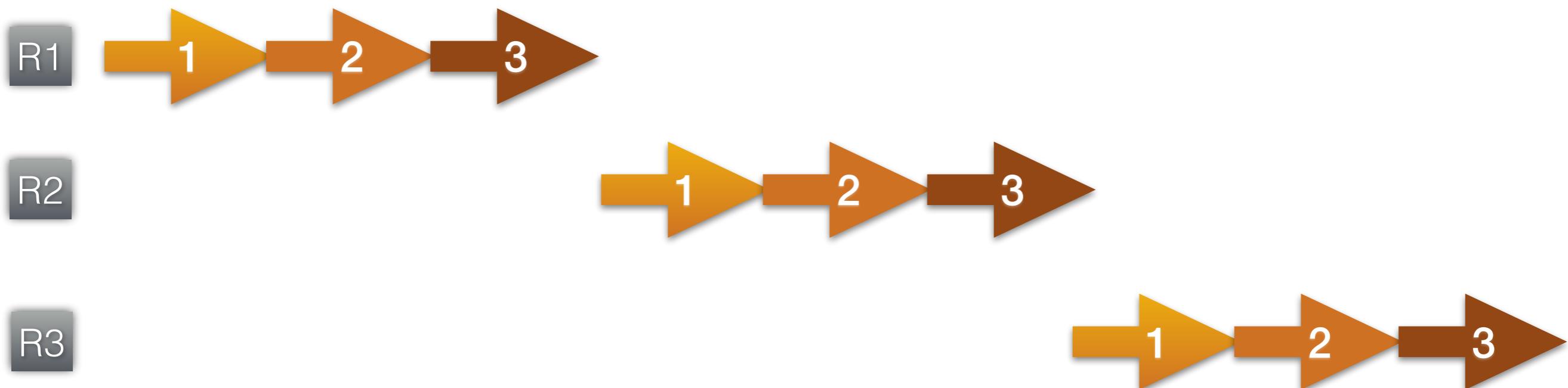
- Traditional dependence chain
- When Request 1 is complete, start Request 2



Traditional

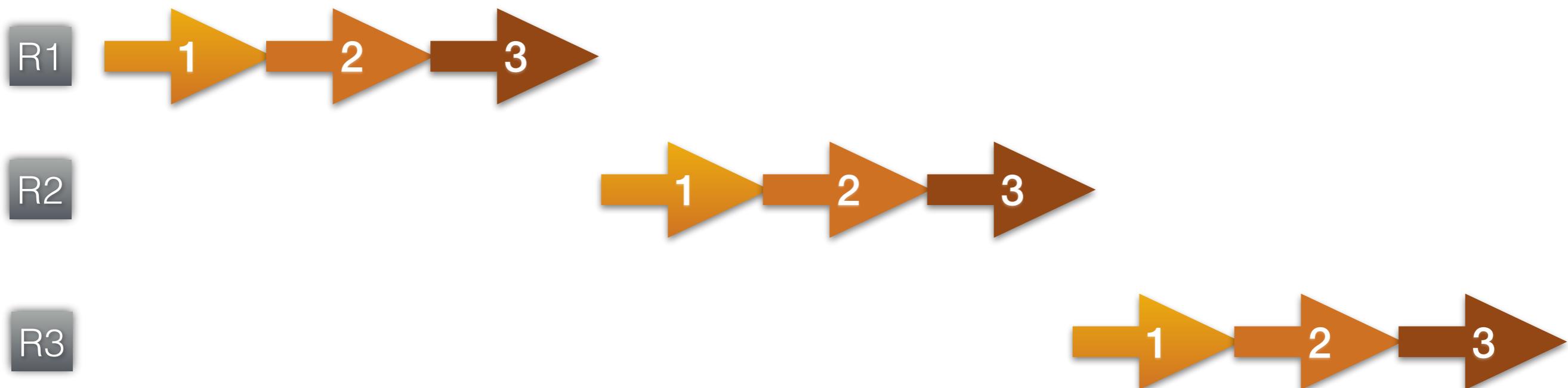
One task per thread

- Traditional dependence chain
- When Request 2 is complete, start Request 3



Traditional Limited HW Reordering

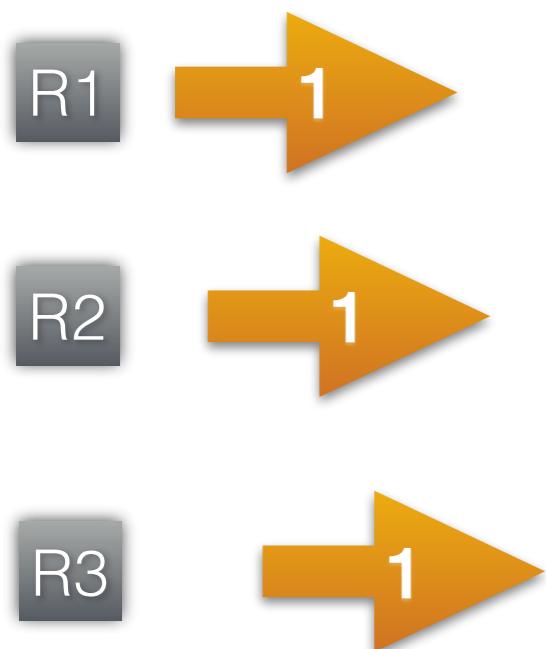
- Traditional dependence chain
- HW out-of-order execution only if predictable&short



Cimple Co-routines

Co-operative Scheduling

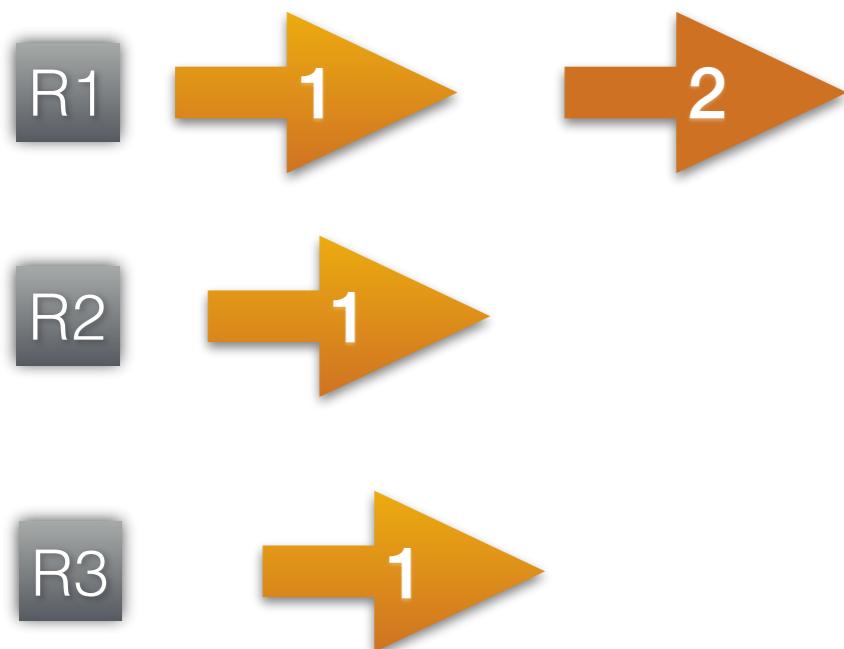
- Voluntary context switches after memory access



Cimple Co-routines

Co-operative Scheduling

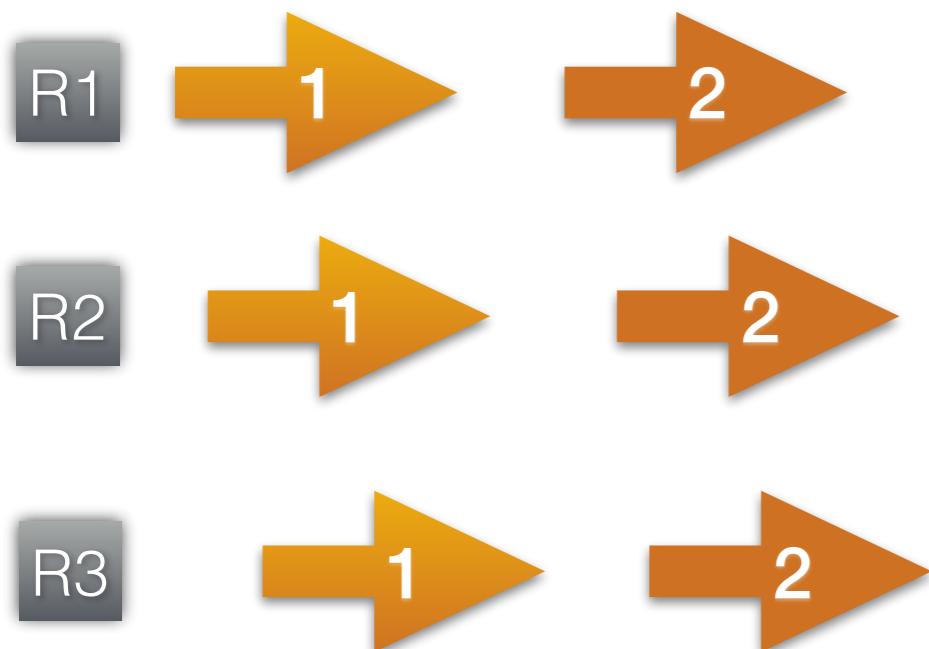
- Voluntary context switches after memory access
- No wait for completion - assume latency is hidden



Cimple Co-routines

Co-operative Scheduling

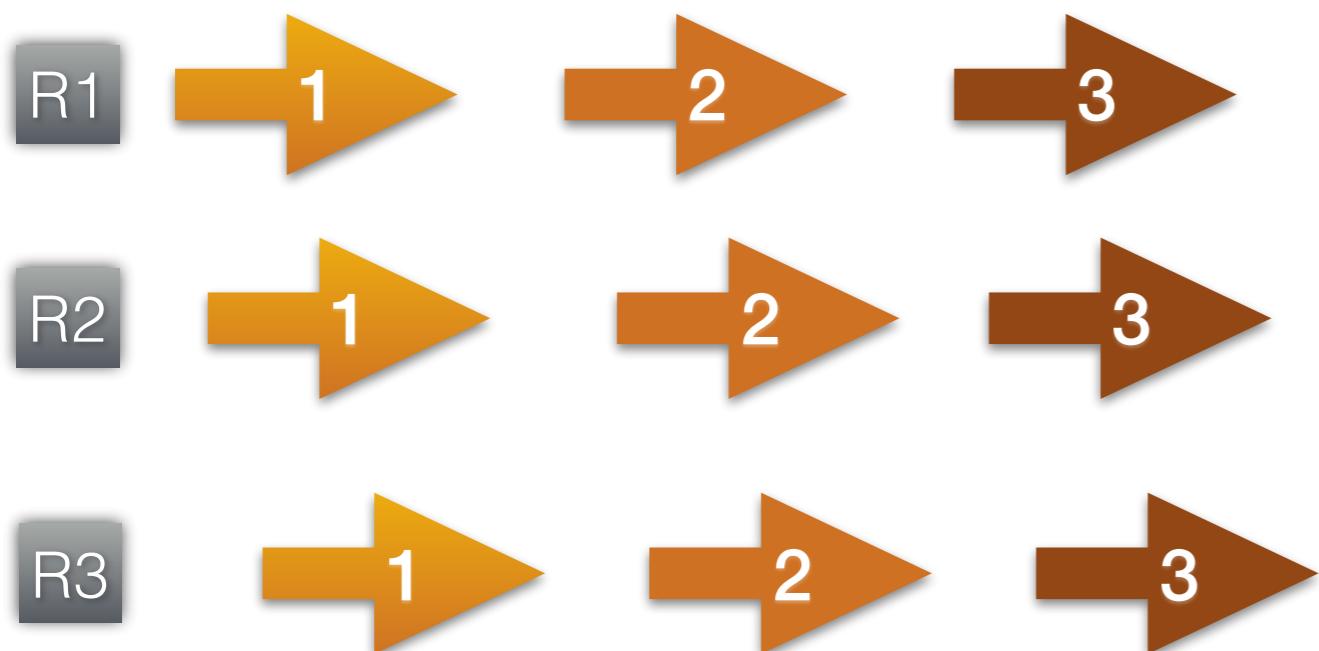
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Cimple Co-routines

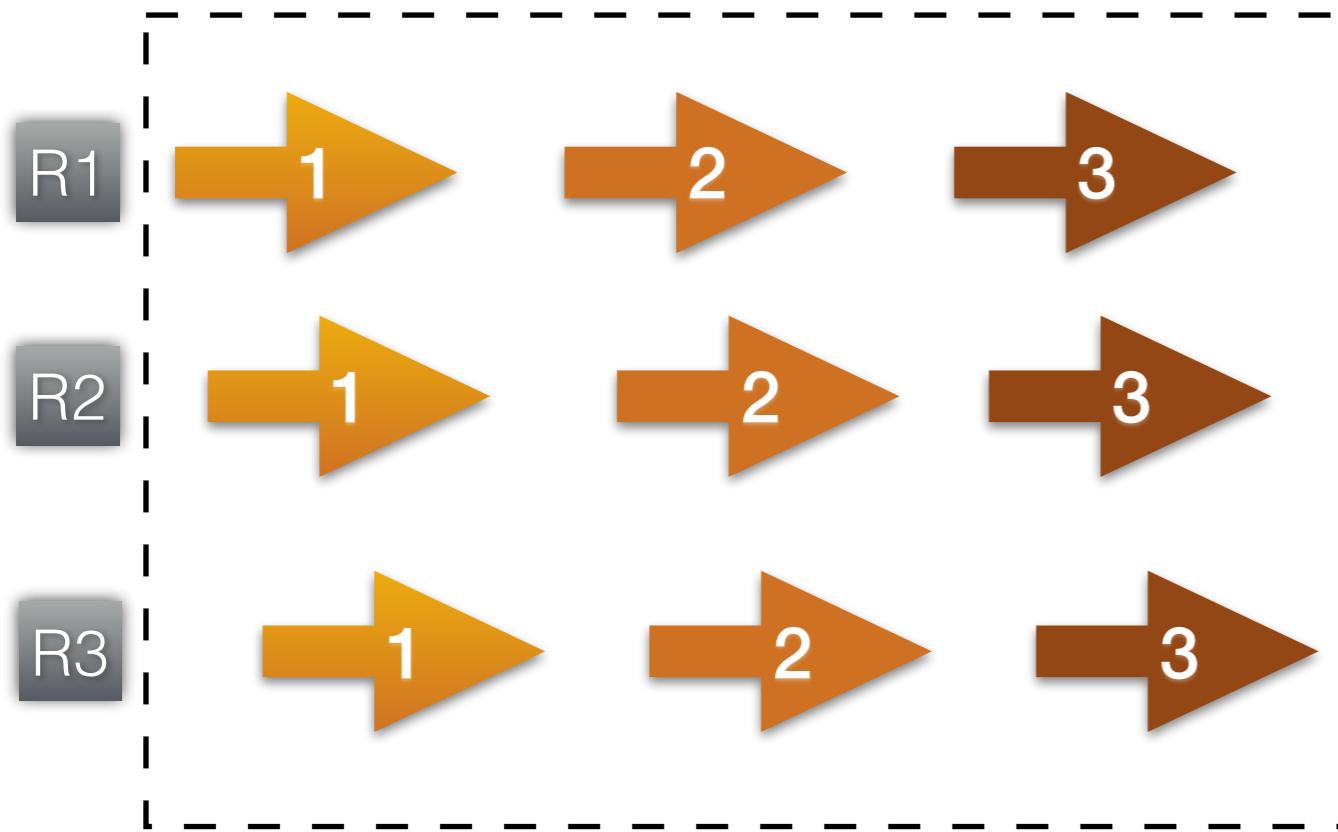
Co-operative Scheduling

- Voluntary context switches after memory access
- Mark explicitly with **yield**



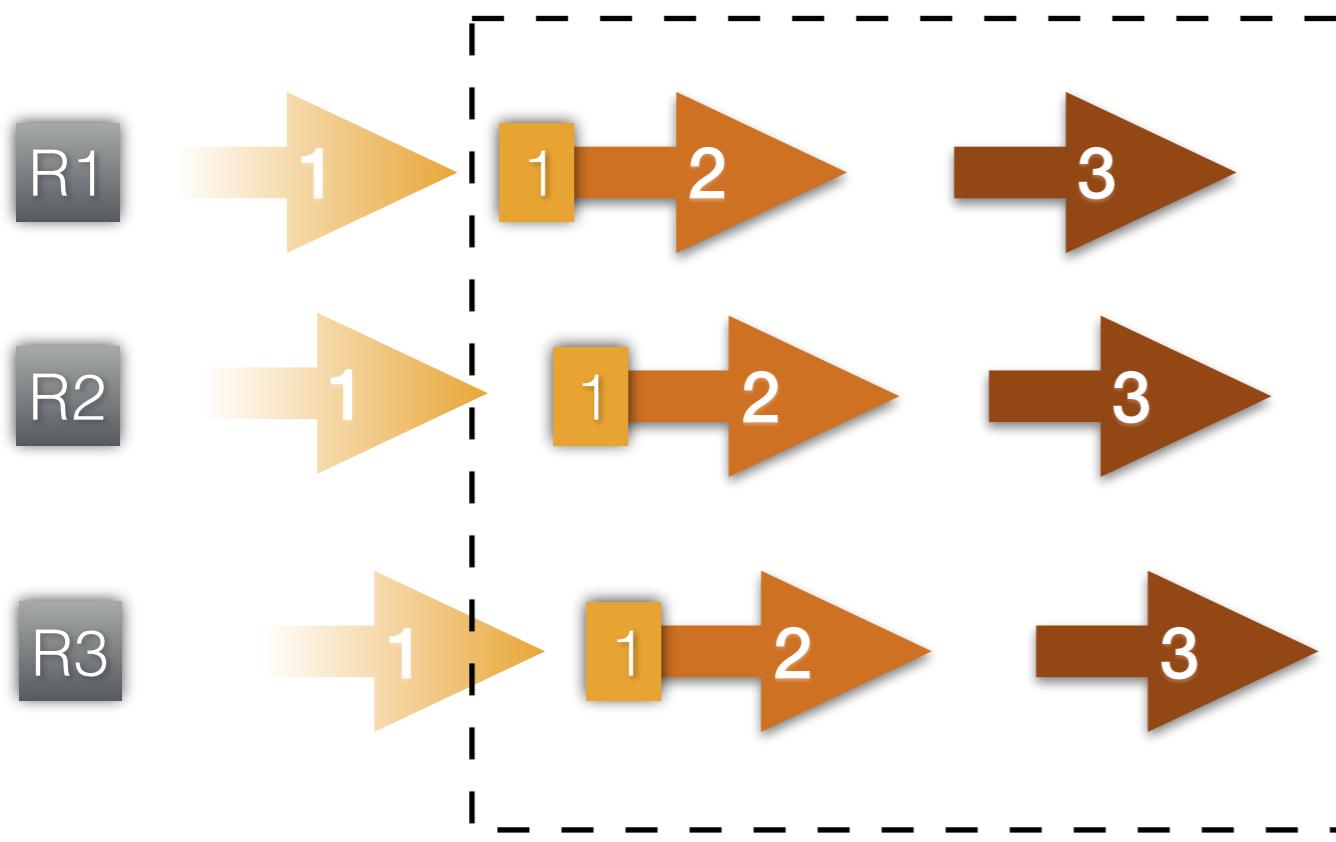
Co-routine Yield

- Mark voluntary context switches with **Yield**
- Must fit all in instruction window



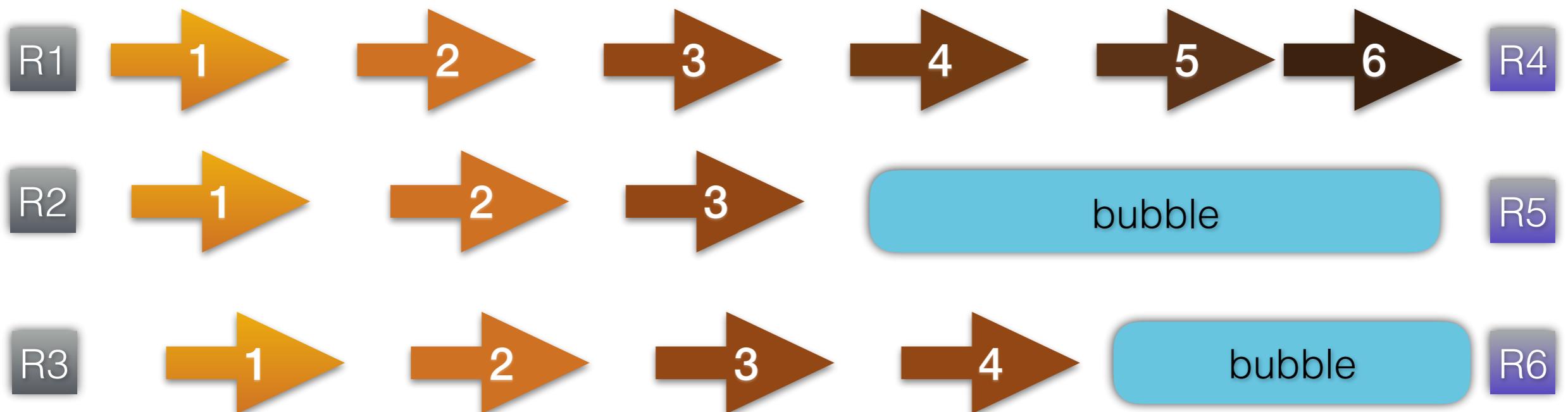
Co-routine + Prefetch

- **Prefetch** - Overlaps loads and computation
- More requests fit the instruction window



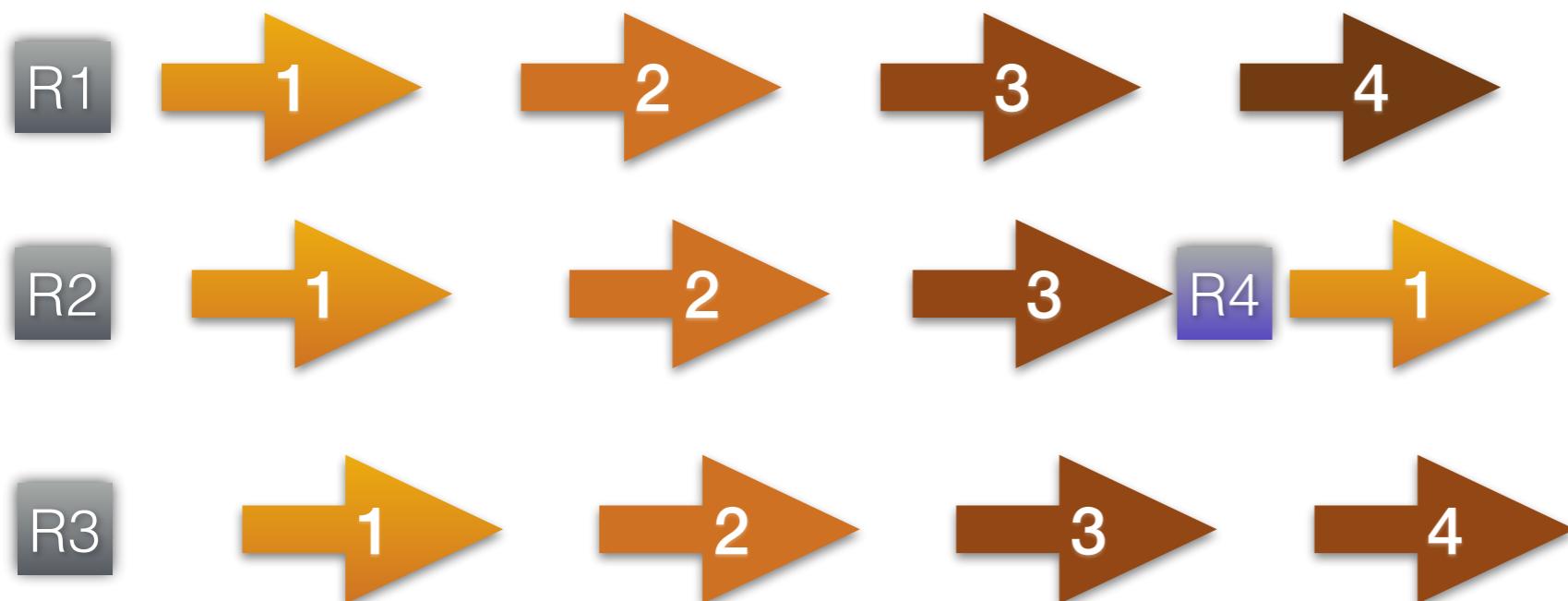
Co-routine Static Scheduling

- Execute a group at a time
- Wait until all tasks complete



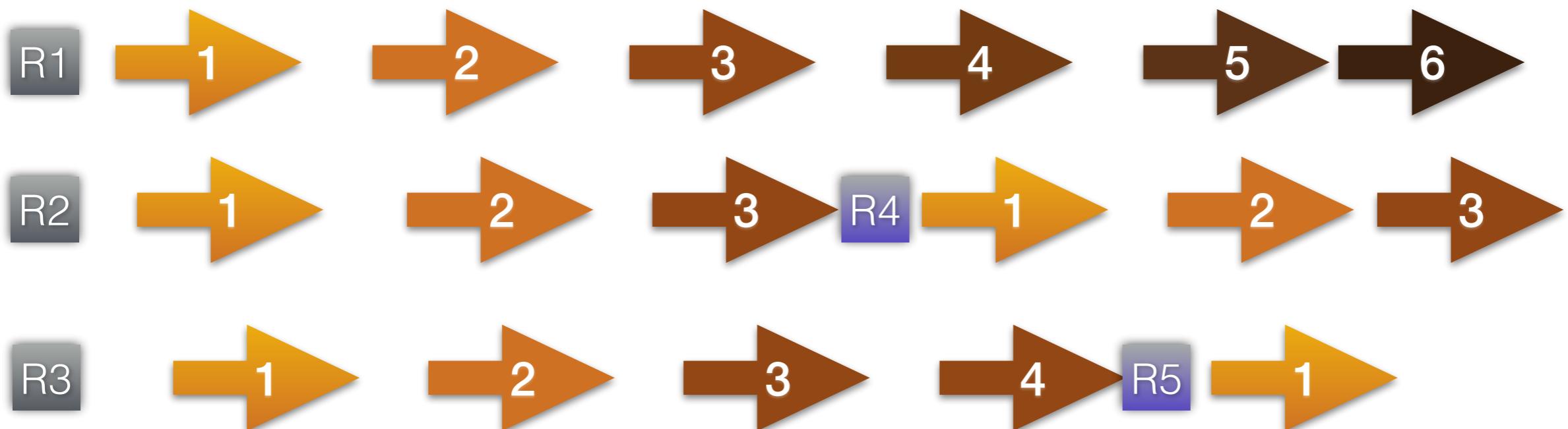
Co-routine Dynamic Scheduling

- Refill one task at a time
- Refill R4 as soon as R2 completes



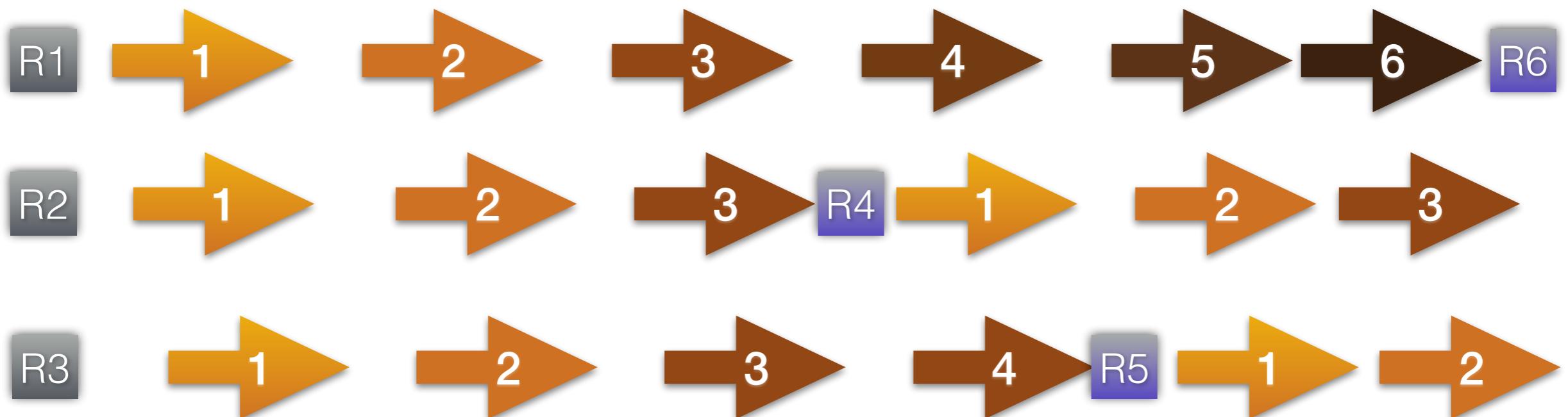
Co-routine Dynamic Scheduling

- Refill one task at a time
- Refill R5 as soon as R3 completes



Co-routine Dynamic Scheduling

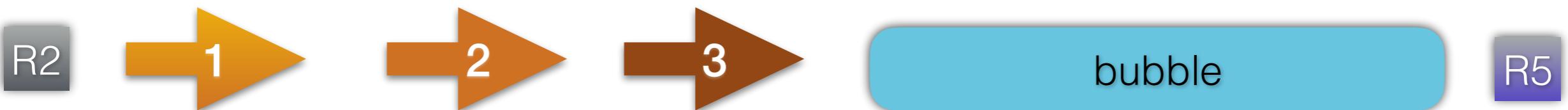
- Refill one task at a time
- Refill R6 as soon as R1 completes



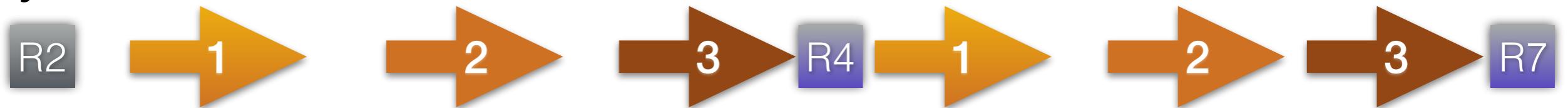
Static vs Dynamic

- Is Dynamic always better?

Static

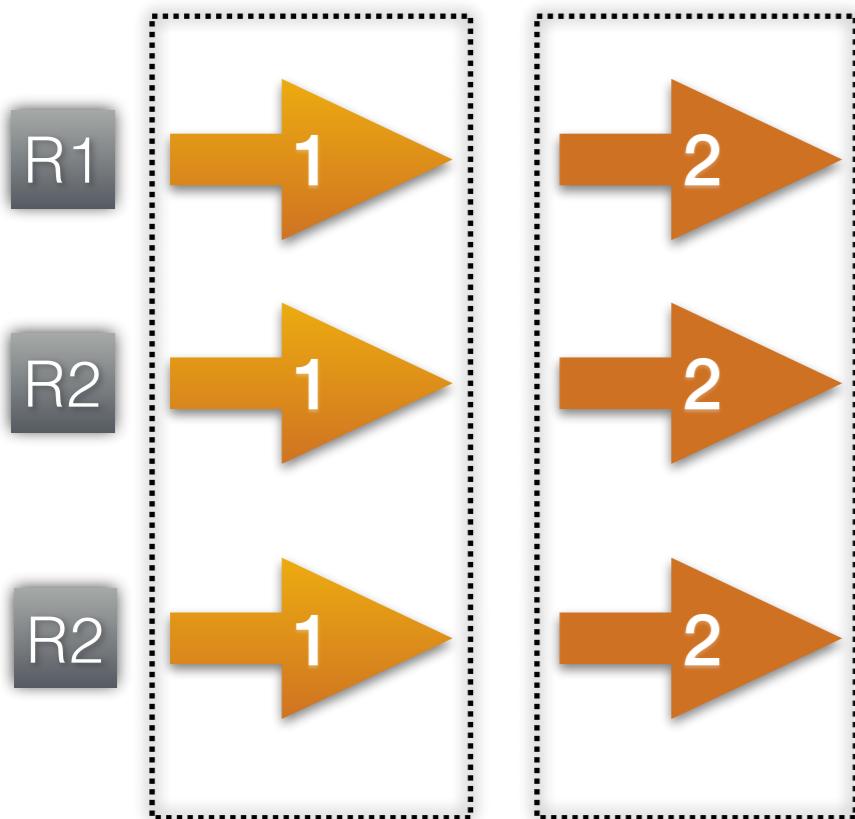


Dynamic



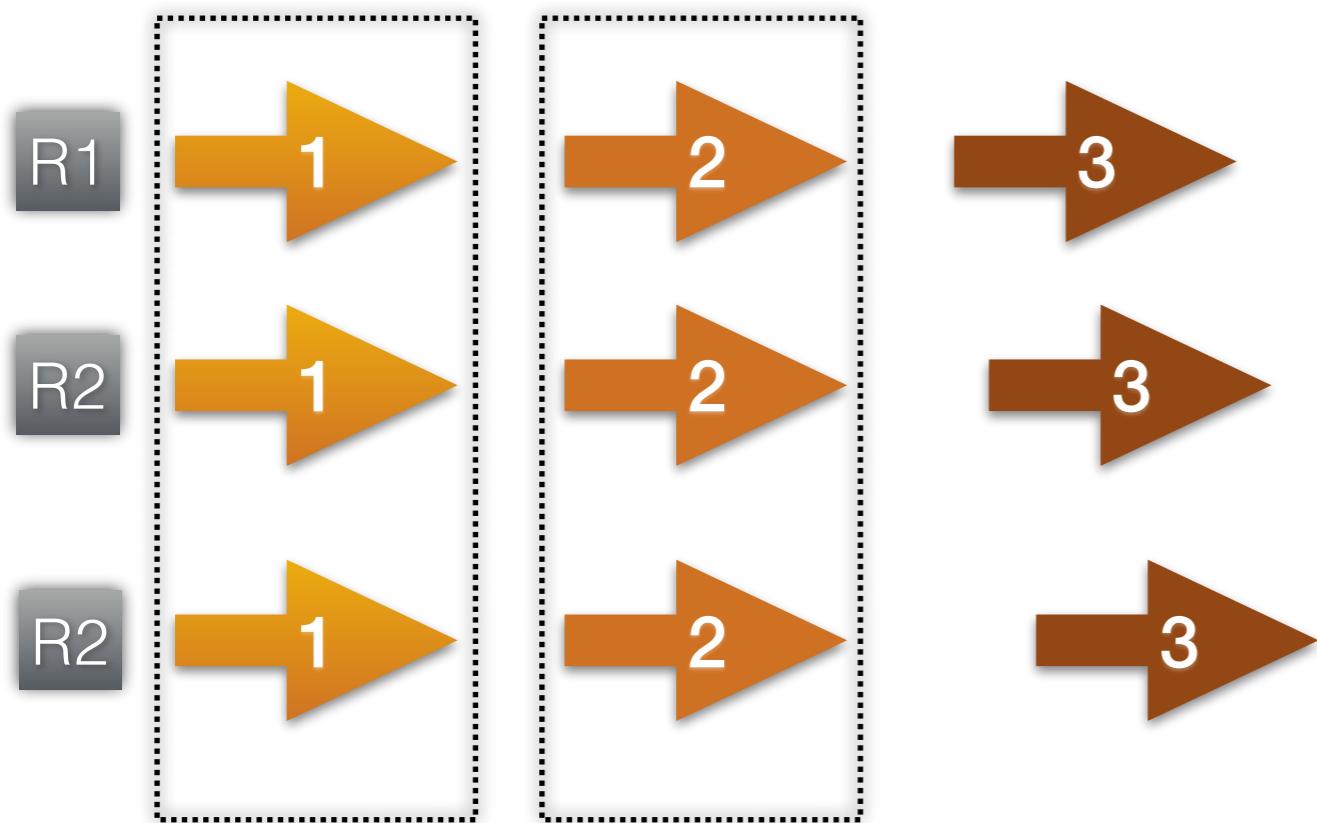
Co-routine Vectorization

- Static Scheduling



Co-routine Vectorization

- Hybrid Static+Dynamic Scheduling

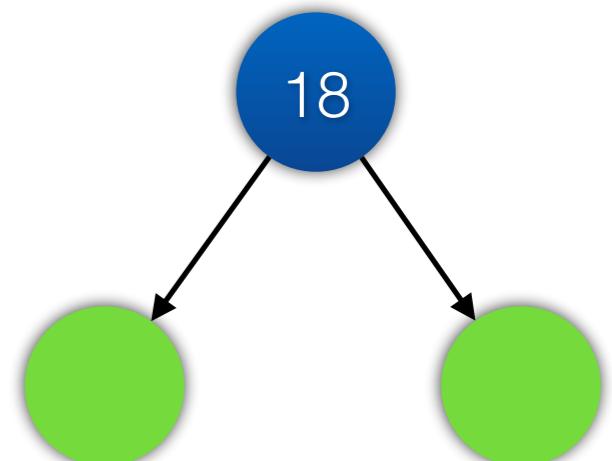


Three Keys to High MLP

- 🔑 Cooperative scheduling of co-routines
Yield at memory requests
- 🔑 Non-blocking loads overlap with computation
Prefetch avoids instruction window overflow
- 🔑 Branch misprediction penalty minimized
If/Switch grouping, and *branchless* code

Binary Tree Lookup

```
node* BinaryTree::find(node* n, Key key) {  
    while (n) {  
        if (n->key == key)  
            return n;  
  
        if (n->key < key)  
            n = n->right;  
        else  
            n = n->left;  
    }  
    return n;  
}
```



Binary Tree Hotspots

```
node* BinaryTree::find(node* n, Key key) {
    while (n) {
        if ( n->key == key ) // 1. cache miss
            return n;

        if ( n->key < key )
            n = n->right;
        else
            n = n->left;
    }
    return n;
}
```

Binary Tree Hotspots

```
node* BinaryTree::find(node* n, Key key) {
    while (n) {
        if (n->key == key) // 1. cache miss
            return n;

        if (n->key < key) // 2. branch
            n = n->right; // misprediction
        else
            n = n->left;
    }
    return n;
}
```

Binary Tree Branchless

```
node* BinaryTree::find(node* n, Key key) {
    while (n) {
        if (n->key == key)
            return n;

        n = n->child[n->key < key];
    }
    return n;
}
```

Today: Cimple DSL for Experts

If it is fast and ugly, they will use it and curse you;
if it is slow, they will not use it.

- *David Cheriton*

[Jain, *The Art of Computer Systems Performance Analysis*]

Today: Cimple DSL for Experts

If it is fast and ugly, they will use it and curse you;
if it is slow, they will not use it.

- *David Cheriton*

- Performance critical database indices:
Replace LLVM IR builders in JIT query engines
- C++ Standard Template Library replacement

Past: Related Work

- GP: Group prefetching - [Chen et al'04]
manual *static scheduling* for hash-join
- AMAC: Asynchronous Memory Access Chaining
[Kocberber et al, VLDB'15]
manual *dynamic scheduling*

Concurrent: C++20 co_routines

- SAP Hana [Psaropoulos et al, VLDB'18]
- Microsoft SQLServer [Jonathan et al, VLDB'18]
automated *dynamic scheduling*
- Slower than manual GP!
Pretty front-end, high-overhead backend
- Dynamic schedule only, no vectorization

Binary Tree Lookup

```
node* BinaryTree::find(node* n, Key key) {  
    while (n) {  
        if (n->key == key)  
            return n;  
  
        n = n->child[n->key < key];  
    }  
    return n;  
}
```

Cimple DSL: Binary Tree

```
6  While (n) .Do (  
8      If( n->key == key ) .  
9          Then ( Return (n) ) .  
10         Stmt ( n = n->child[n->key < key] ; )  
11     ) .  
12     Return (n) ;
```

Cimple DSL: Binary Tree

```
6  While (n) .Do (
7      Prefetch (n) .Yield () .
8      If ( n->key == key ) .
9          Then ( Return (n) ) .
10         Stmt ( n = n->child[n->key < key] ; )
11     ) .
12     Return (n) ;
```

Cimple DSL: Binary Tree

```
1  auto c = Coroutine(BST_find);
2  c.Result(node*).
3  Arg(node*, n).
4  Arg(KeyType, key).
5  Body().
6  While(n).Do(
7    Prefetch(n).Yield().
8    If( n->key == key ).
9    Then( Return(n) ).  

10   Stmt( n = n->child[n->key < key]; )
11   ).  

12   Return(n);
```

Co-routine State

Arg(node*, n).
Arg(KeyType, key).

- **Arguments,
Variables**

```
1 struct Coroutine_BST_Find {  
2     node* n;  
3     KeyType key;
```

Co-routine State

```
c.Result(node*).  
Arg(node*, n).  
Arg(KeyType, key).
```

- **Result**

```
1  struct Coroutine_BST_Find {  
2      node* n;  
3      KeyType key;  
4      node* _result;
```

Co-routine State

```
c.Result(node*).  
Arg(node*, n).  
Arg(KeyType, key).
```

- Dynamic Schedule
Finite State Machine
_state

```
1  struct Coroutine_BST_Find {  
2      node* n;  
3      KeyType key;  
4      node* _result;  
5      int _state = 0;
```

Dynamic Schedule: Co-routine with **switch**



```
8     bool Step() {
9         switch (_state) {
10            case 0:
11
12                return false;
13
14            case 1:
15
16                return true;
17
18            case _Finished:
19                return true;
20
21
22
23
24
```

Dynamic Schedule: Co-routine with **switch**



```
8     bool Step() {
9         switch (_state) {
10            case 0:
11                return false;
12            case 1:
13                return true;
14            case _Finished:
15                return true;
16        }
17    }
```

Duff's device
co-routine

Scheduler Width

- **Width** high to hide latency, low to fit state in L1

```
1 template<int Width = 48>
2
3     using Next = CoroutineState_SkipList_next_limit;
4
5     SimplestScheduler<Width, Next>(len,
6         [&](Next* cs, size_t i) {
7             *cs = Next(&answers[i], IterateLimit,
8                         iter[i]);
9         });
10
```

Static Schedule: **for**

Vectorization friendly Struct-of-Arrays



```
1  bool SuperStep() {
2      for(int _i = 0; _i < _Width ; _i++) {
3          KeyType& k = _soa_k[_i];
4          HashType& hash = _soa_hash[_i];
5
6
7      }
```

Static Schedule: **for**

Vectorization friendly Struct-of-Arrays

```
1  bool SuperStep() {
2      for(int _i = 0; _i < _Width ; _i++) {
3          KeyType& k = _soa_k[_i];
4          HashType& hash = _soa_hash[_i];
5
6      }
7
8      for(int _i = 0; _i < _Width ; _i++) {
9          KeyType& k = _soa_k[_i];
10         HashType& hash = _soa_hash[_i];
11
12     }
```

Applications

Binary Search

```
1 Arg(ResultIndex*, result).
2 Arg(KeyType, k).
3 Arg(Index, l).
4 Arg(Index, r).
5 Body().
6 While( l != r ).Do(
7     StmtS(R""( {
8         int mid = (l+r)/2;
9         bool less = (a[mid] < k);
10        l = less ? (mid+1) : l;
11        r = less ? r : mid;
12    } )"").
13    Prefetch(&a[ (l+r)/2 ]).Yield()
14).
15 Stmt( *result = l; );
```



Binary Search

```
1 Arg(ResultIndex*, result).
2 Arg(KeyType, k).
3 Arg(Index, l).
4 Arg(Index, r).
5 Body().
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12    } )"").
13    Prefetch(&a[ (l+r)/2 ]).Yield()
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```

!|

Binary Search

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4 Arg(Index, r).
5 Body().
6 While( l != r ).Do(
7     StmtS(R""( {
8         int mid = (l+r)/2;
9         bool less = (a[mid] < k);
10        l = less ? (mid+1) : l;
11        r = less ? r : mid;
12    } )"").
13    Prefetch(&a[ (l+r)/2 ]).Yield() .
14).
15 Stmt( *result = l; );
```



Skip List Lookup

```
1 VariableInit(SkipListNode*, n, {}).
2 VariableInit(uint8, ht, {pred->height}).
3 While(true).Do(
4     While(ht > 0).Do( // down
5         Stmt( n = pred->skip[ht - 1]; ). |
6         Prefetch(n).Yield().
7         If(!less(k, n->key)).Then(Break()). |
8         Stmt( --ht; )
9     ). |
10    If (ht == 0).Then( Return( nullptr ) ). |
11    Stmt( --ht; ). |
12    While (greater(k, n->key)).Do(
13        Stmt( pred = n; n = n->skip[ht]; ). |
14        Prefetch(n).Yield(). |
15    ). |
16    If(!less(k, n->key)).Then(
17        Return( n ) );
```

Skip List Lookup

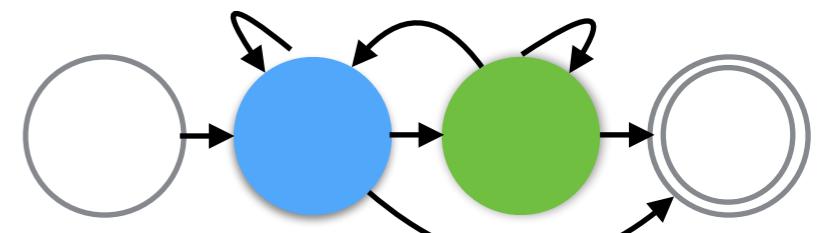
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11    Stmt( --ht; ).  

12    While (greater(k, n->key)).Do(
13        Stmt( pred = n; n = n->skip[ht]; ).  

14        Prefetch(n).Yield().
15    ).  

16    If (!less(k, n->key)).Then(
17        Return( n ));
```



Down Right

Skip List Iteration

```
1  While( limit-- ).Do(           |
2      Prefetch(n).Yield().        |
3      Stmt( n = n->skip[0]; )   |
4  ).                           |
5  Prefetch(n).Yield().          |
6  Return( n->key );
```

- Pointer chasing

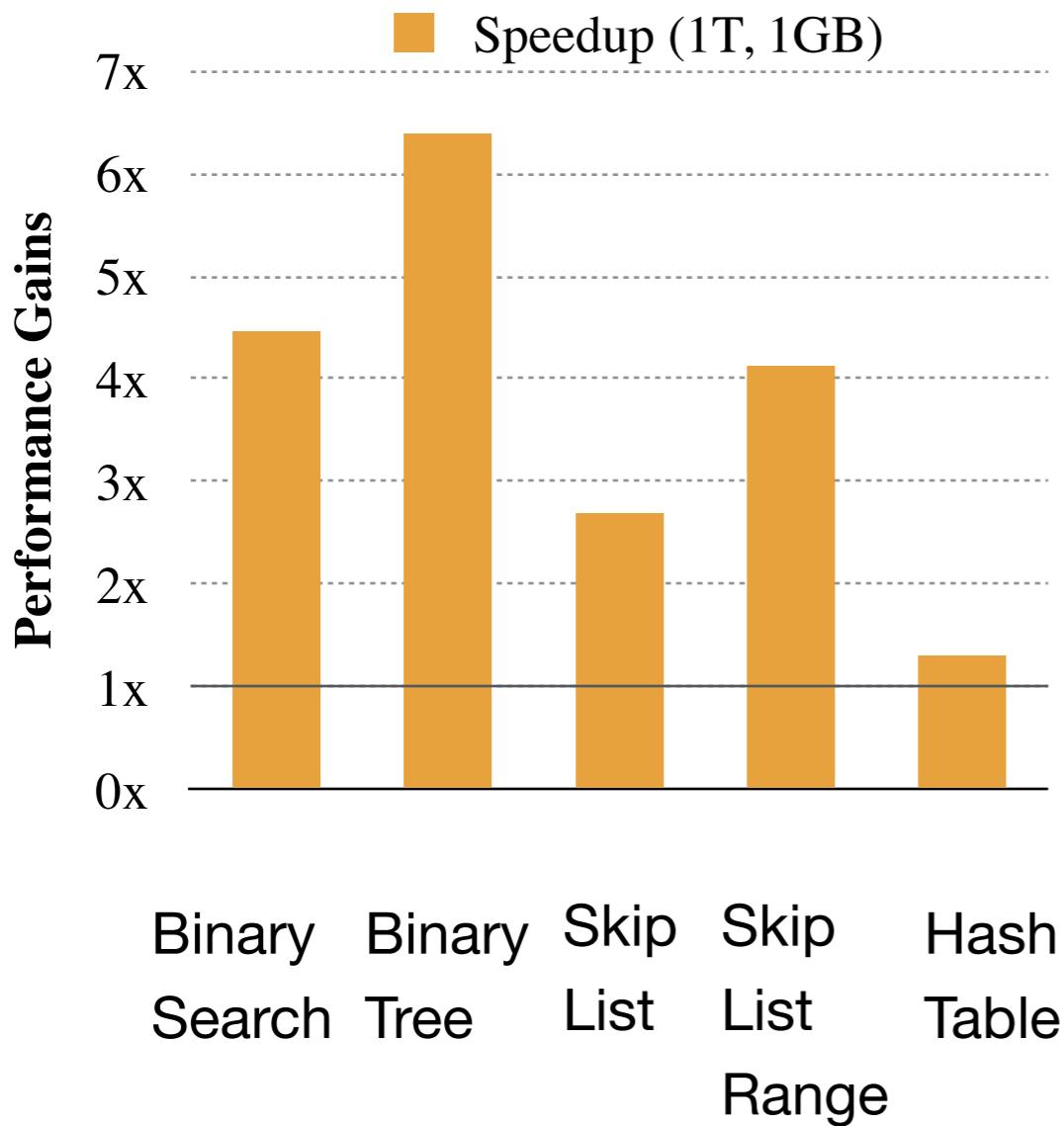
Hash Table Lookup (Linear Probing)

```
1 Result (KeyValue*) .  
2 Arg (KeyType, k) .  
3 Variable (HashType, hash) .  
4 Body () .  
5 Stmt ( hash = Murmur3::fmix (k) ; ) .  
6 Stmt ( hash &= this->size_1; ) .Yield () .  
7 Prefetch ( &ht [hash] ) .Yield ()  
8 << R"\""  
9 while ( ht [hash] .key != k &&  
10       ht [hash] .key != 0 ) {  
11     hash++;  
12     if ( hash == size ) hash = 0;  
13   } ) "" <<  
14 Return ( &ht [hash] ) ;
```

- SIMD
- One cache line

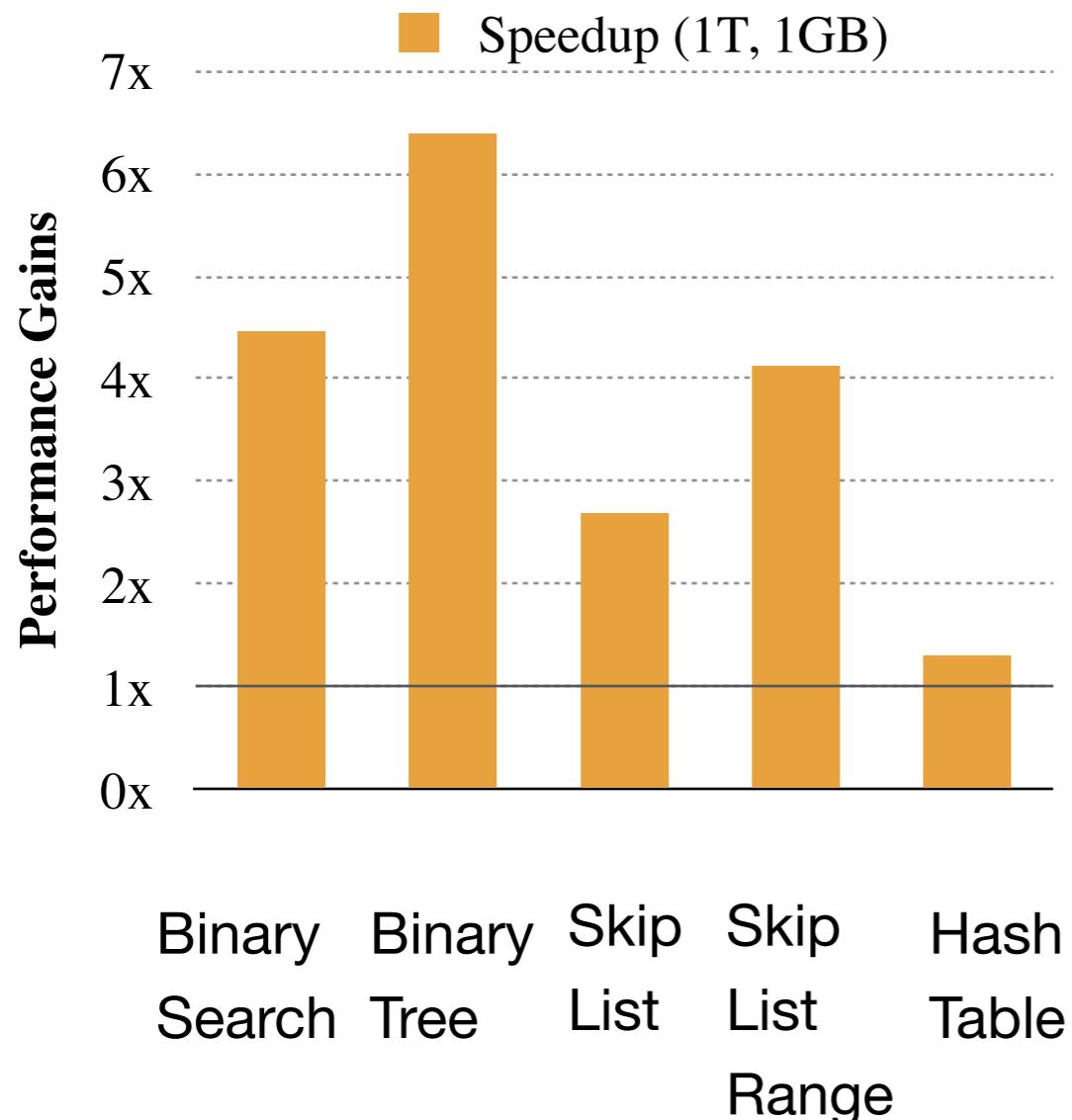
Performance Evaluation

Performance

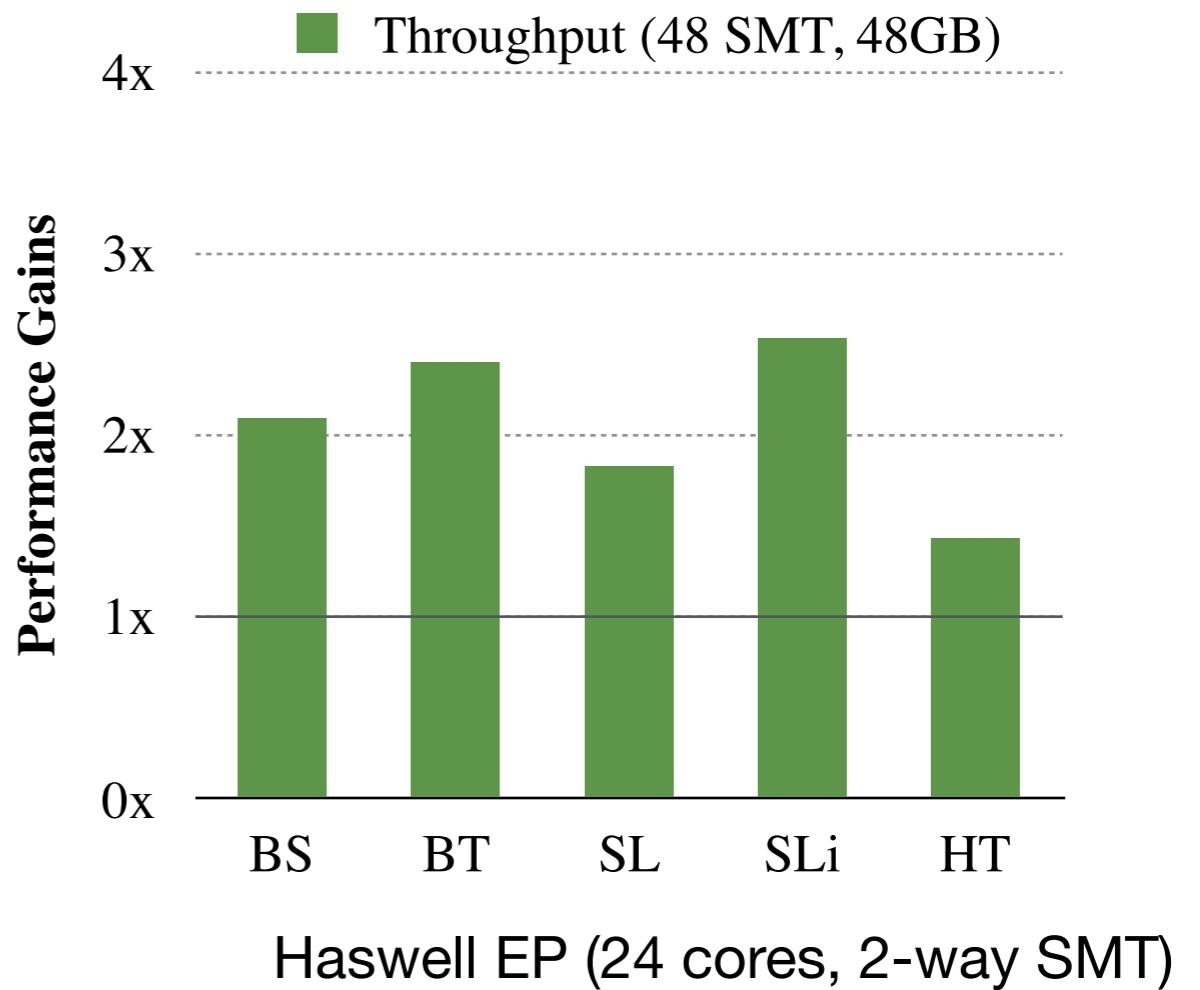


[Default indices of
VoltDB/RocksDB]

Performance



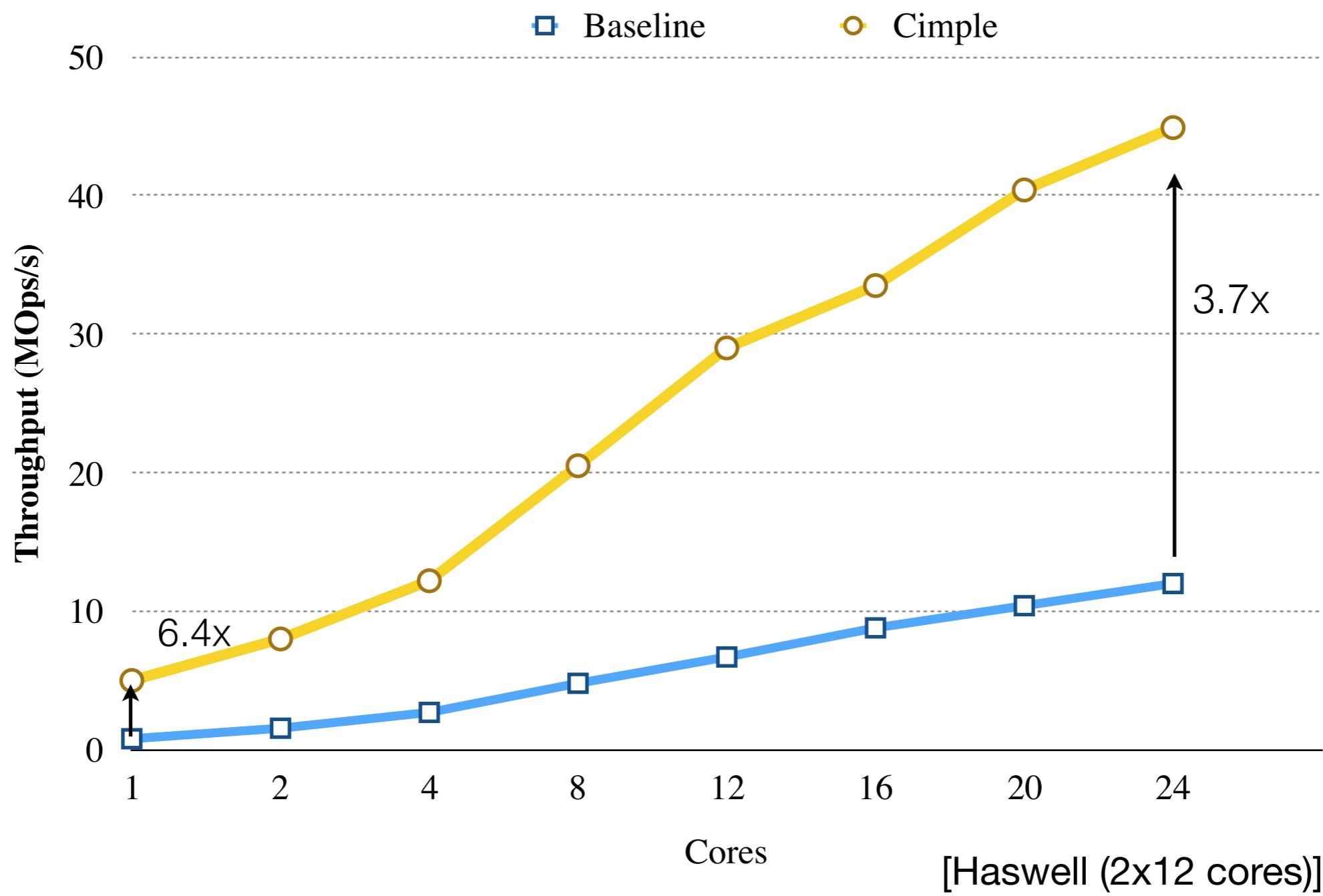
[Default indices of
VoltDB/RocksDB]



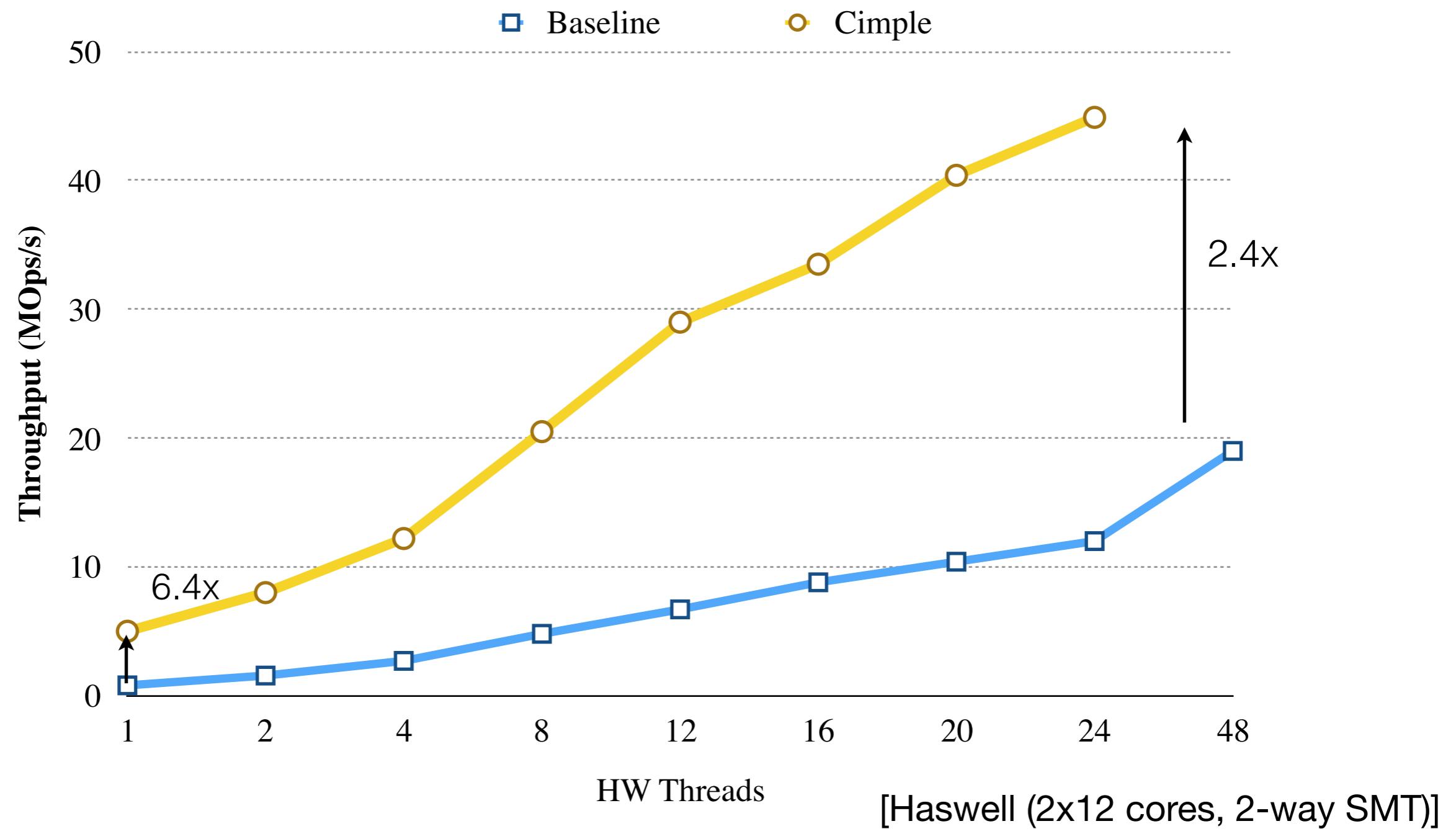
Thread Level Parallelism

- ✓ Multi-core
- ✓ SMT hardware thread
- ✗ Single-thread OS context switching?
50x slower

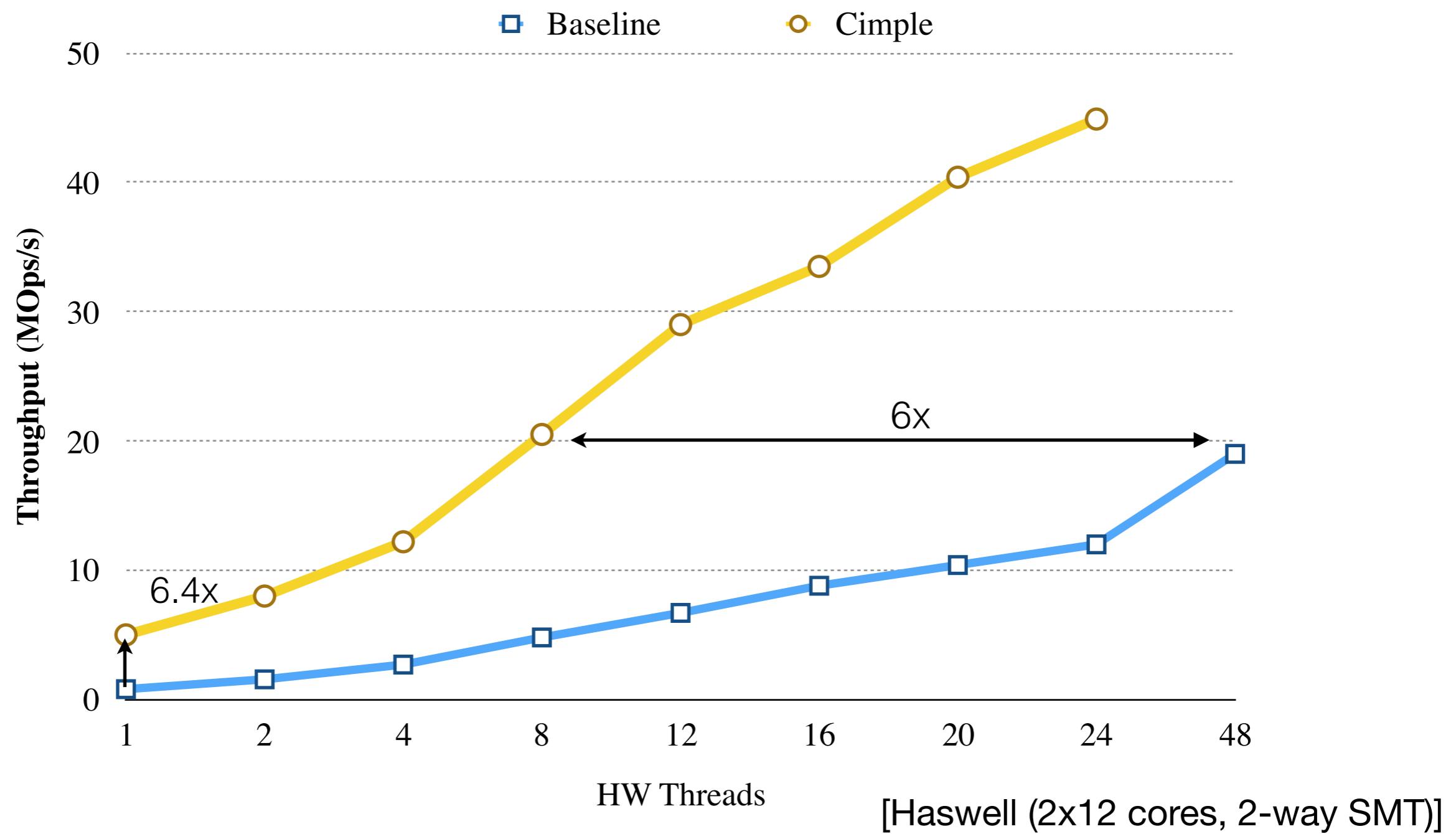
Cimple Throughput Gains on Multicore



Cimple Throughput Gains vs Hyper-threading



Cimple Throughput Gains vs Hyper-threading

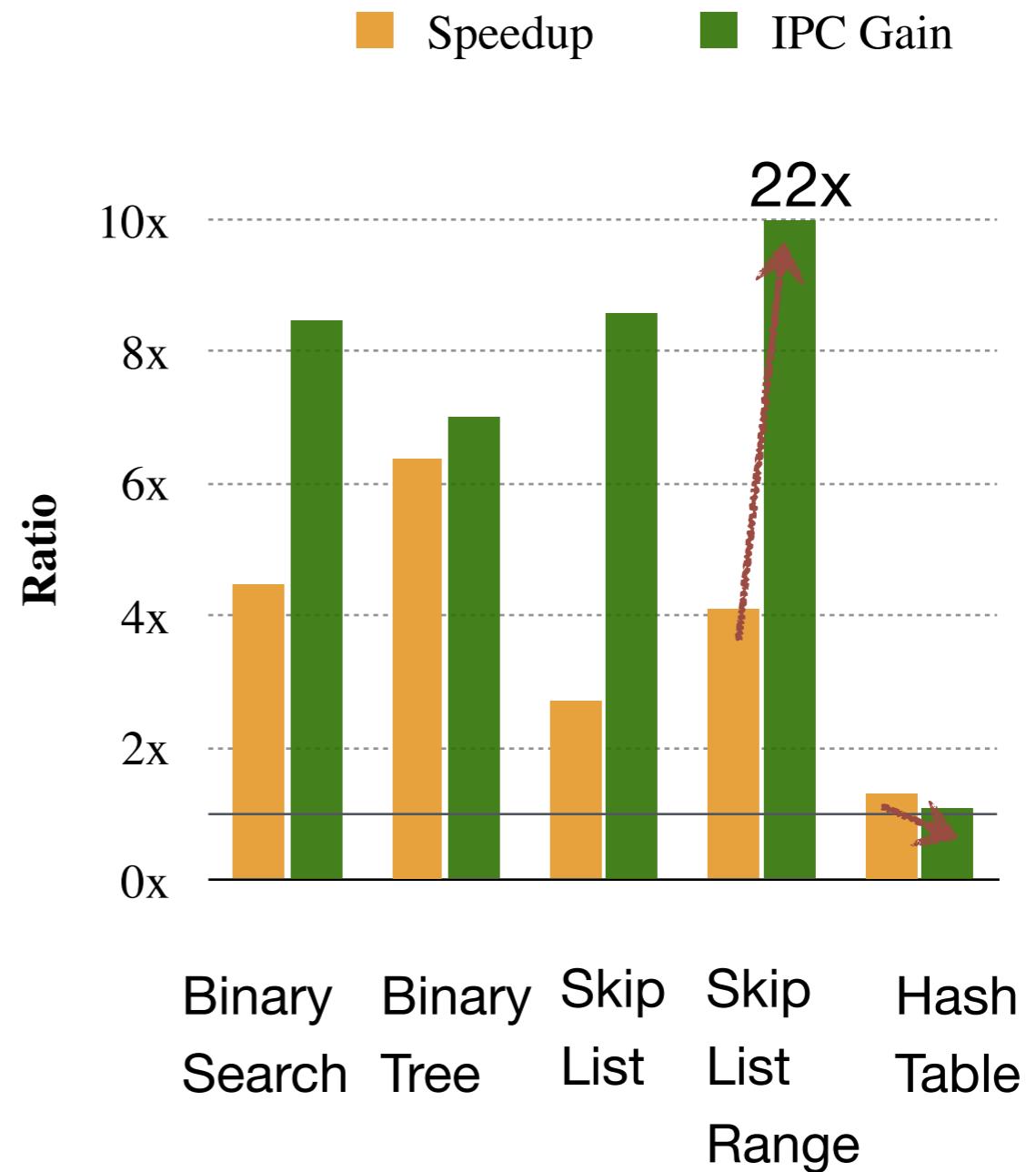


IPC Analyzed

- SkipList Range:
scheduler overhead

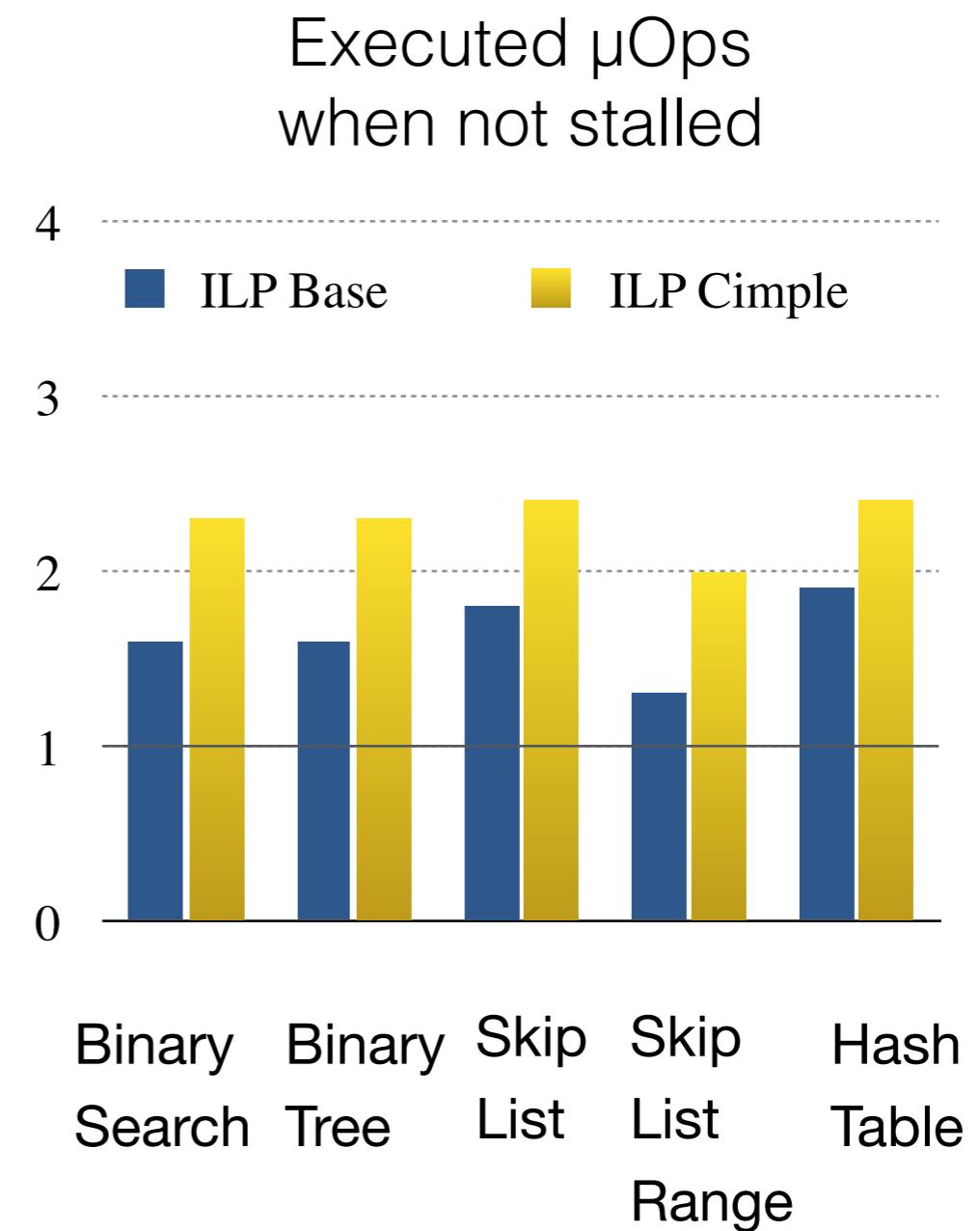
```
p = p->next;
```

- HashTable:
SIMD vectorization



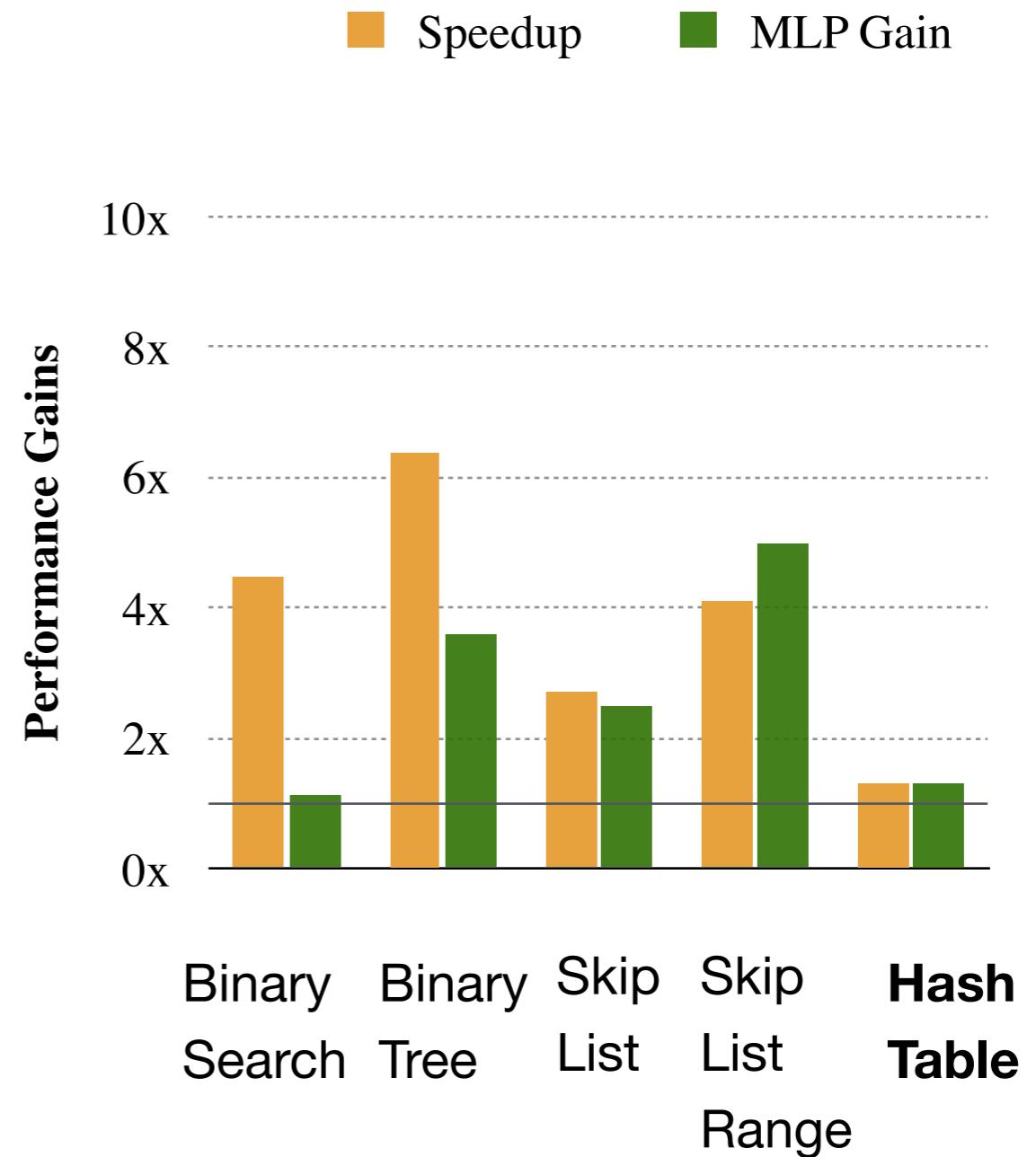
ILP Analyzed

- Uncovered more parallelism
- Absorbed scheduler overhead



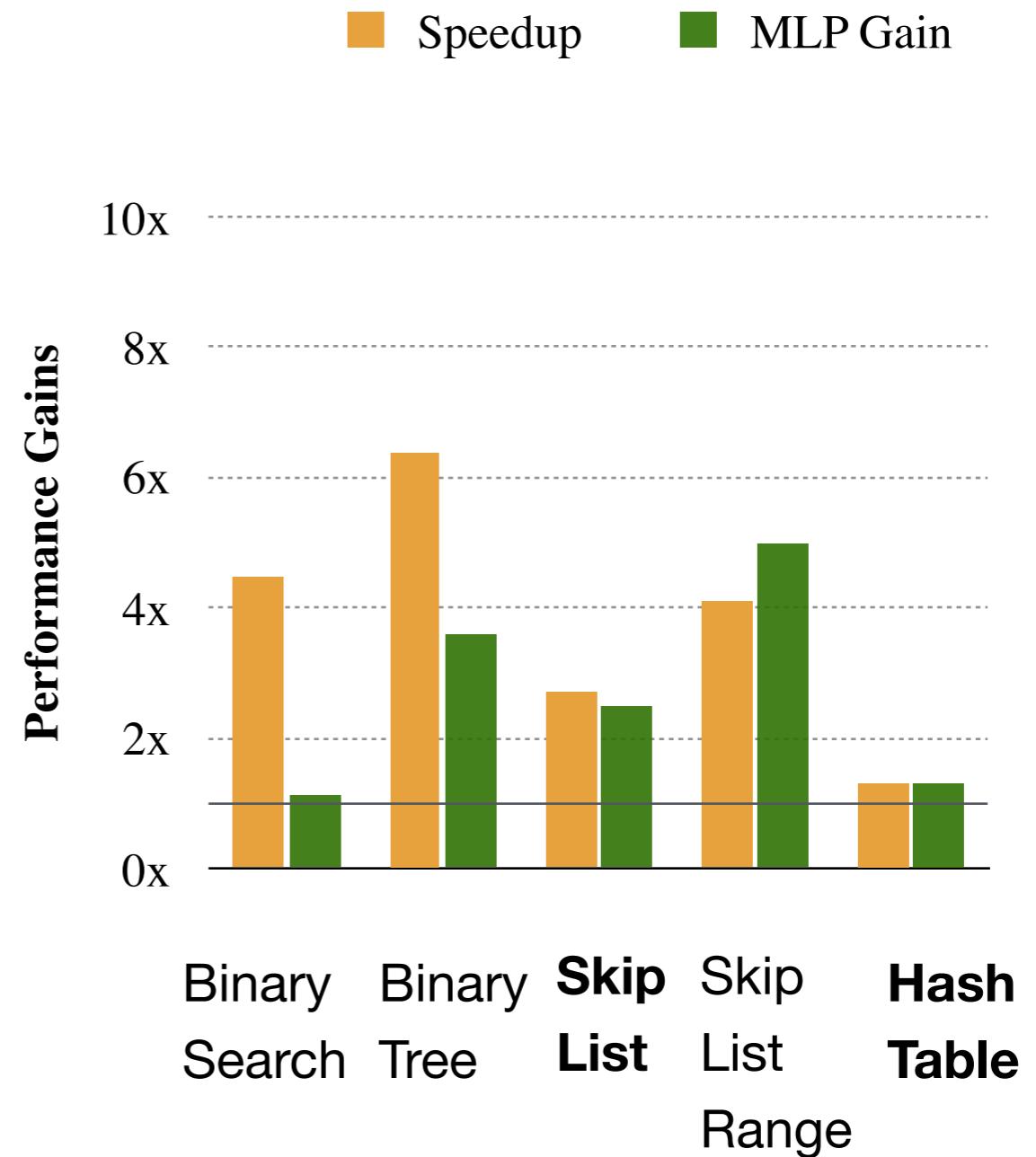
MLP Analyzed

- HashTable -
OoO HW extracts MLP

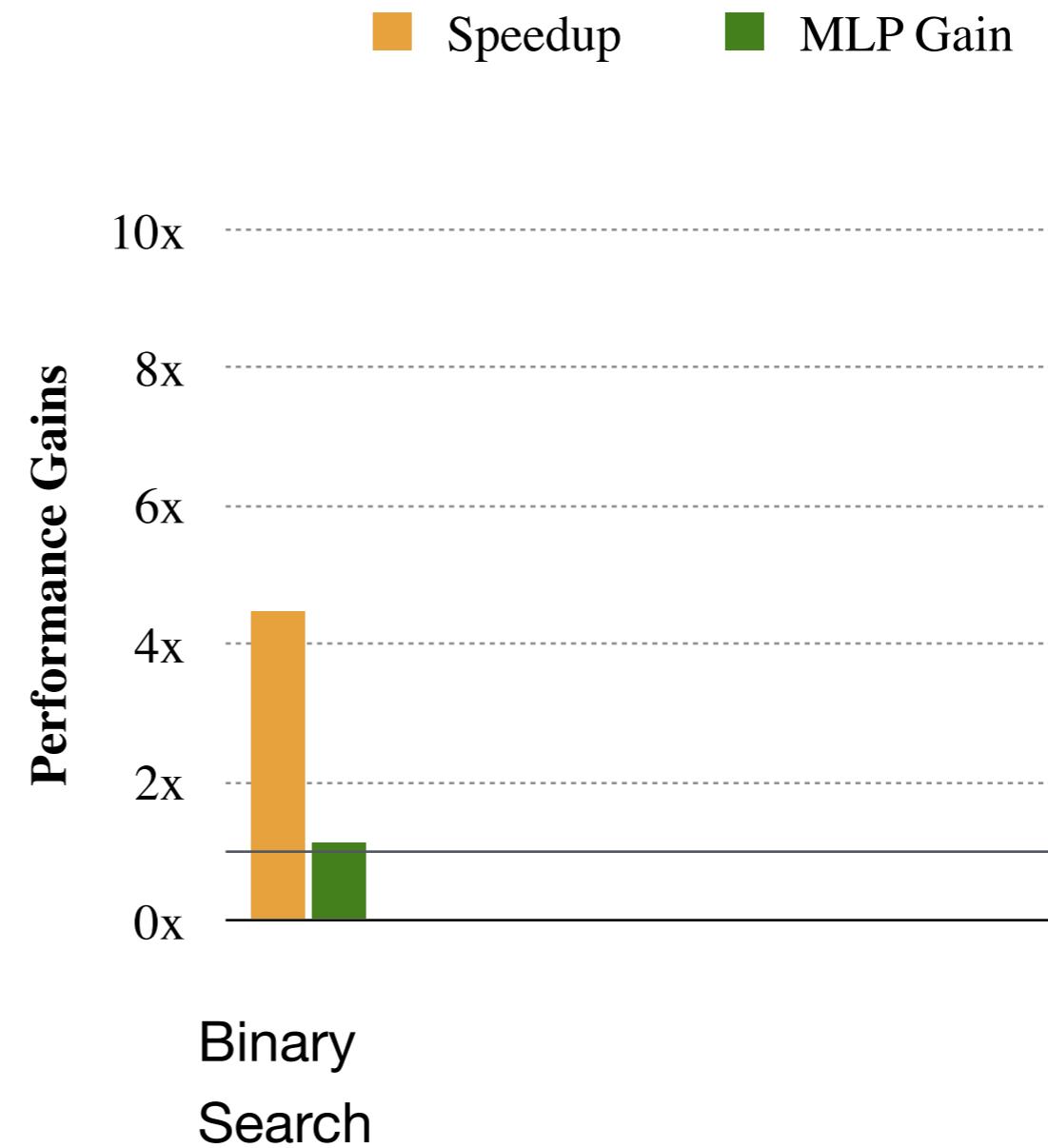
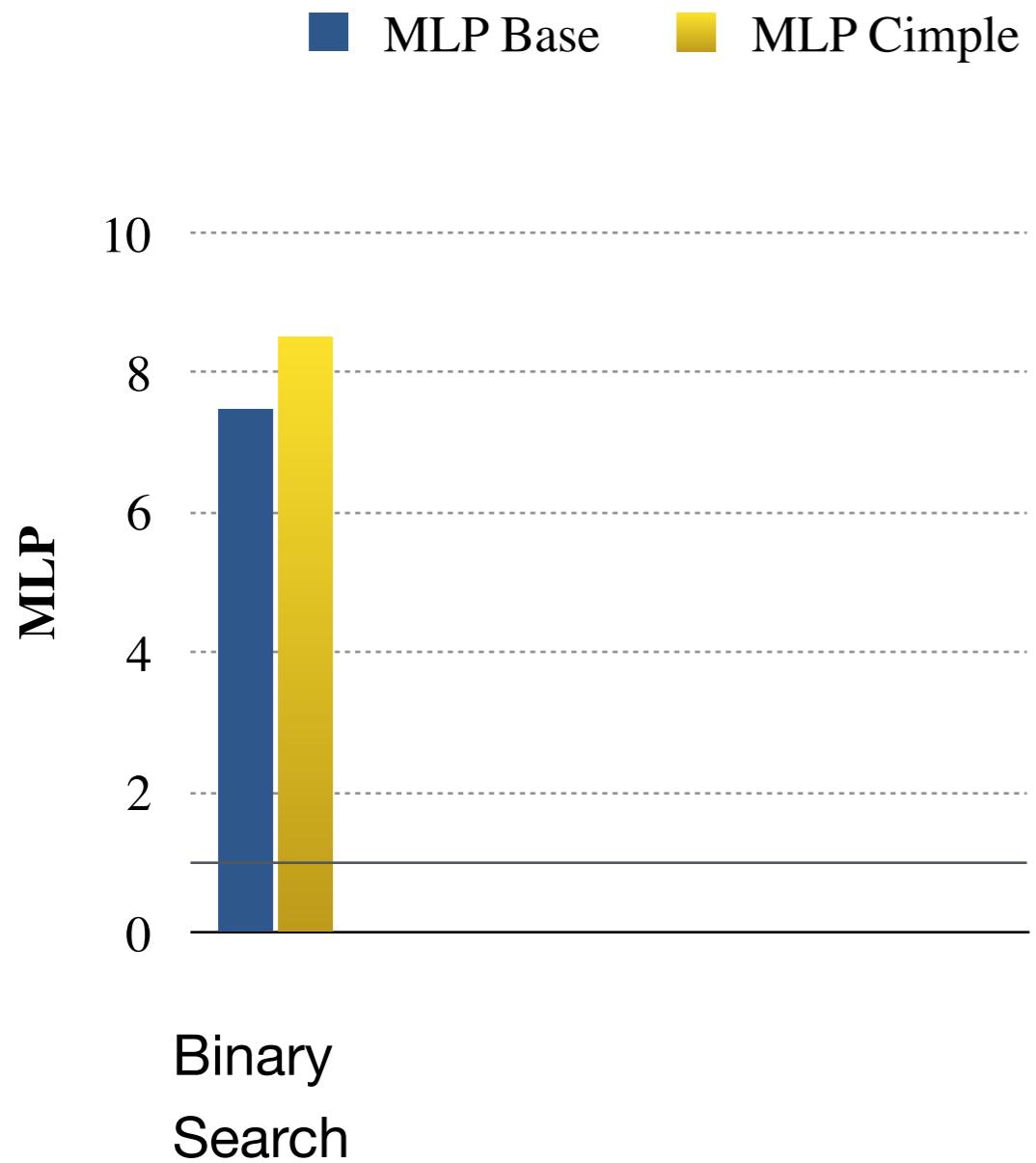


MLP Analyzed

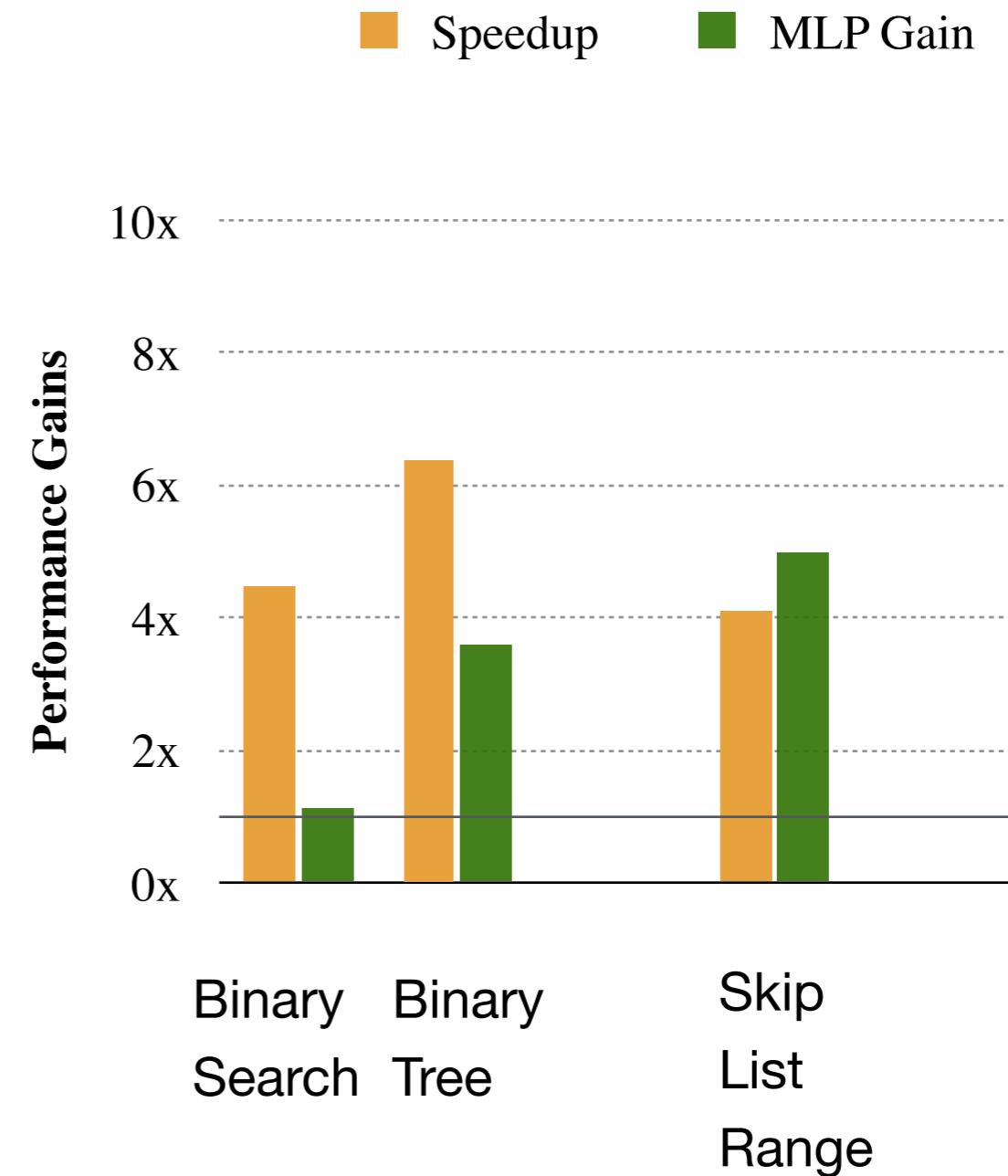
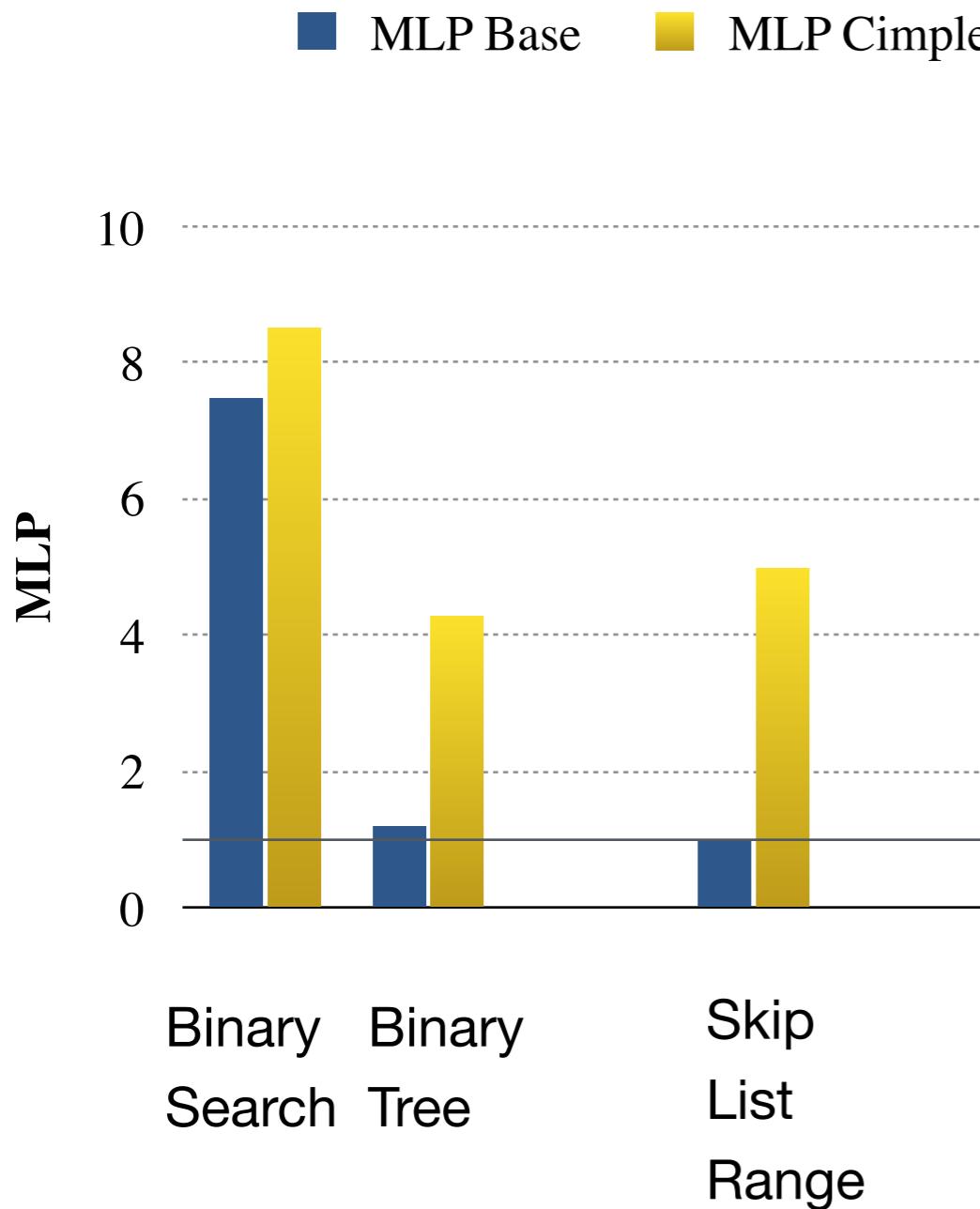
- HashTable -
OoO HW extracts MLP
- SkipList - speedup
matching MLP gains



MLP: Ineffective or Low

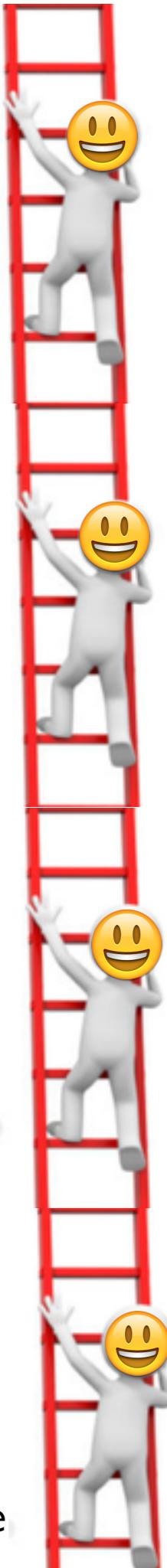


MLP: Ineffective or Low



MLP Improvement Paths

- Increased Efficiency
 - Static scheduling
 - Vectorization
- Increased Effectiveness
 - Dynamic scheduling: no bubbles
 - Branchless code



Conclusion

- Fast
 - up to 6.4× speedup
- Portable DSL (*for Stephanies*)
 - template libraries
 - database query engines
- Next: C++ standards (*for Joes*)

Thanks

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