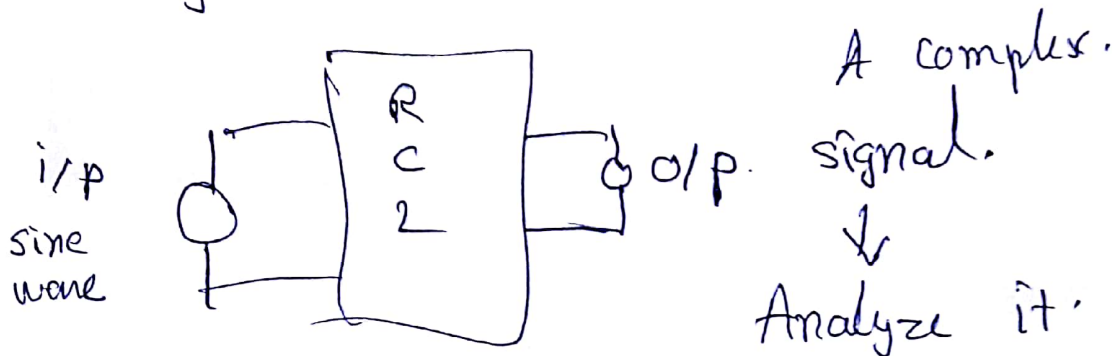


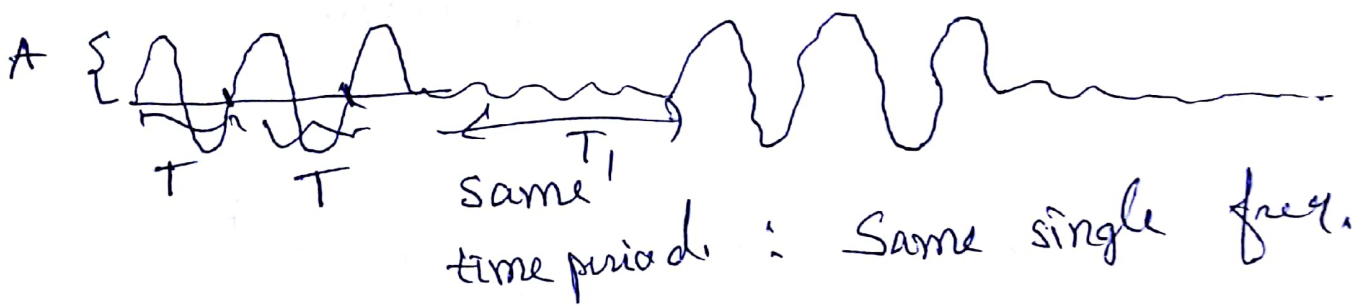
Where is Fourier Transform useful?

Akash: Electrical circuits, to analyze signals.



Fourier transform tells you frequencies present & amplitudes associated with those frequencies.

Tangent: In a kayak. signal.



$2\frac{1}{2}$ sine waves T_1 noise, again

Sum of two sine waves with nearby frequencies. Useful in music.

$$S(t) = A \sin 2\pi f_1 t + A \sin 2\pi f_2 t$$

f_1 & f_2 are very close

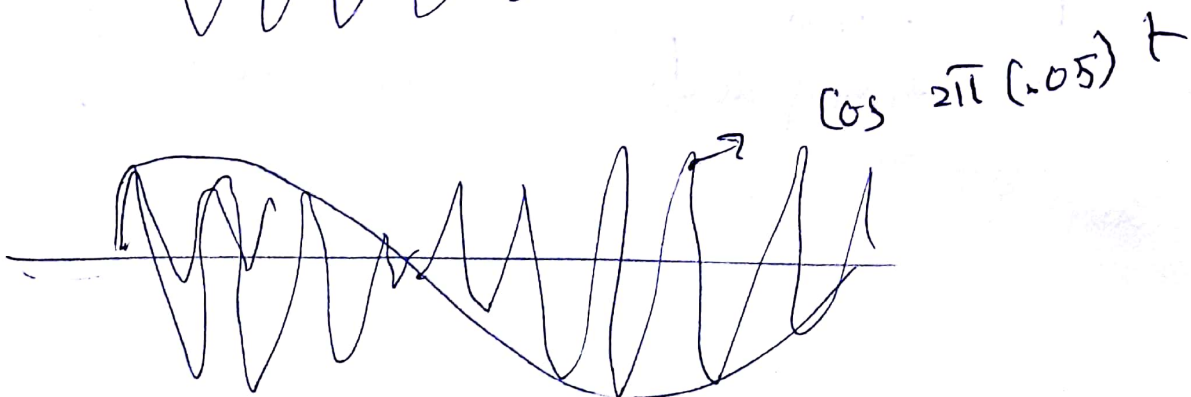
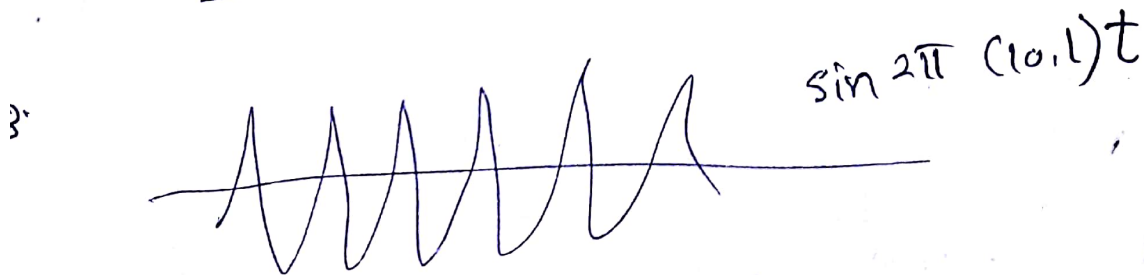
Beats:

$$S(t) = A \sin 2\pi \left(\frac{f_1 + f_2}{2} \right) t \cos 2\pi \left(\frac{f_1 - f_2}{2} \right) t$$

take $f_1 = 10$ $f_2 = 10.1$

$$\frac{f_1 + f_2}{2} = 10.05$$

$$\frac{f_2 - f_1}{2} = 0.05$$



Revise L-29

2

$$f(x) = \sum_{n=0}^{\infty} a_n e^{inx}$$

→ Can this always be done?

Try writing $\sin x$.

$$\sin x = \frac{1}{2i} e^{ix} + \frac{1}{(-2i)} e^{-ix}$$

→ No. Negative exponents are needed.

→ For real functions, is there a relationship between a_n & a_{-n} ?

$$[a_n = a_{-n}^*] \Rightarrow [a_n^* = a_{-n}]$$

→ why? ↑ True?

Real functions have the property that $f^* = f$.

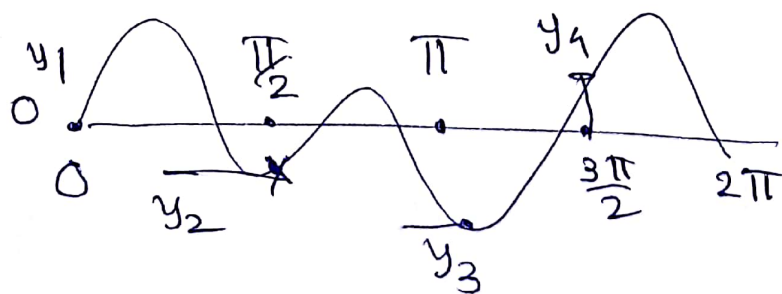
$$\begin{aligned} \text{Take } f(x) &= a_{-n} e^{-inx} + a_n e^{inx} \\ f^*(x) &= (a_{-n})^* e^{inx} + a_n^* e^{-inx} \end{aligned}$$

$a_n^* = a_{-n}$ for real functions.

(3)

An example of a Fourier series.

$$f(x) = c_0 + c_1 e^{ix} + c_2 e^{2ix} + c_3 e^{3ix}$$



$$c_0 + c_1 + c_2 + c_3 = f(0) = y_1$$

$$c_0 + c_1 e^{\frac{i\pi}{2}} + c_2 e^{i\pi} + c_3 e^{\frac{3i\pi}{2}} = f\left(\frac{\pi}{2}\right) = y_2$$

$$c_0 + c_1 e^{i\pi} + c_2 e^{2i\pi} + c_3 e^{3i\pi} = f(\pi) = y_3$$

$$c_0 + c_1 e^{\frac{3i\pi}{2}} + c_2 e^{3i\pi} + c_3 e^{\frac{9i\pi}{2}} = f\left(\frac{3\pi}{2}\right) = y_4$$

The question is given the data y_1, y_2, y_3, y_4 , find the amplitudes c_0, c_1, c_2, c_3 corresponding to the frequencies $n=0, 1, 2, 3$.

(4)

The corresponding matrix eqn. is

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & e^{\frac{j\pi}{2}} & e^{j\pi} & e^{\frac{3j\pi}{2}} \\ 1 & e^{j\pi} & e^{2j\pi} & e^{3j\pi} \\ 1 & e^{\frac{3j\pi}{2}} & e^{3j\pi} & e^{\frac{9j\pi}{2}} \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}$$

known. : Assumed frequencies

Unknowns.

known.

Find inverse of the matrix & multiply on both sides to get the amplitudes,

→ For inverse Fourier transform, given the amplitudes one can find the data.

(5)

In general for an n point data

$$F \vec{c} = \vec{y}$$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega & \omega^2 & \dots & \omega^{(n-1)} \\ 1 & \omega^2 & \omega^4 & \dots & \omega^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{n-1} & \omega^{2(n-1)} & \dots & \omega^{(n-1)^2} \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_{n-1} \end{bmatrix} = \begin{bmatrix} y_0 \\ \vdots \\ y_{n-1} \end{bmatrix}$$

$$\omega = e^{\frac{2\pi i}{n}}$$

↓
The Fourier matrix F

$$\vec{c} = F^{-1} \vec{y}$$

$$F^{-1} = \frac{1}{n} \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega^{-1} & \omega^{-2} & \dots & \omega^{-(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{-(n-1)} & \omega^{-2(n-1)} & \dots & \omega^{-(n-1)^2} \end{bmatrix}$$

Mathematically correct but rarely used
computationally why?

A more efficient technique is to use FFT (the fast Fourier Transform)

Mayank: Fast.

Insight From Prashti: Accuracy.

Less resources: memory:

Shubham.

In FFT n is always taken as an integer power of 2.

$$y_j = \sum_{k=0}^{n-1} \omega_n^{jk} C_k.$$

A single eqn. from the matrix multiplication.

Rewriting the sum with even and odd parts -

$$m = \frac{n}{2}.$$

$$y_j = \sum_{k=0}^{m-1} \omega_n^{2jk} C_{2k} + \sum_{k=0}^{m-1} \omega_n^{(2k+1)j} C_{2k+1}$$

Use $\omega_n^2 = \omega_m$.

(7)

$$\Rightarrow Y_j = \left[\sum_{k=0}^{m-1} \omega_m^{jk} C_k^I \right] + \omega_m^j \left[\sum_{k=0}^{m-1} \omega_m^{jk} C_k^{II} \right]$$

A new name for k^{th} coefficient

Note that

if $N = 64$

$$\omega_N = e^{\frac{2\pi j}{64}}$$

$m = 32$

$$\omega_m = e^{\frac{2\pi j}{32}}$$

$$\omega_m = \omega_N^2$$

* Note that an $n \times n$ matrix equation now "reduces" (in some sense) to two $\frac{n}{2} \times \frac{n}{2}$ ($m \times m$) matrix eqn.s.

* Since m is also a power of two. The same process can be repeated.

FFT requires $\frac{K}{2} N$ operations

against N^2 operations of a Fourier transform.

$$N = 2^k \Rightarrow k = \log_2 N$$

If N is 1024

$$N^2 \approx 10^6$$

Fourier transform

For FFT

$$\frac{N}{2} k = 5 \cdot 1024$$

FFT is approx 200 times faster than the Fourier transform.