

Use of linear algebra.

## ① Representation of networks.

Akash: Networks have some thing to do with nodes & edges.

Angali: Connections between things.

A collection of nodes & edges.

Nodes: Entities being connected

Edges: Connections.

Examples:

\* A Road network

Nodes: Cities (or places).

Edges: Roads.

\* Railway.

\* Internet

Nodes: Webpages.

Edges: links.

\* Face book

Nodes: people

Edges: Friendships.

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\* Food chain

Nodes: Animals

Edges: A connection if one eats the other.

\* Power distribution:

Nodes: Transformers.

Edges: Electrical connection

\* Water distribution network

Nodes: Sources. (tanks) sinks.

Edges: Pipe lines.

\* Chemical Eng.

Molecular interactions.

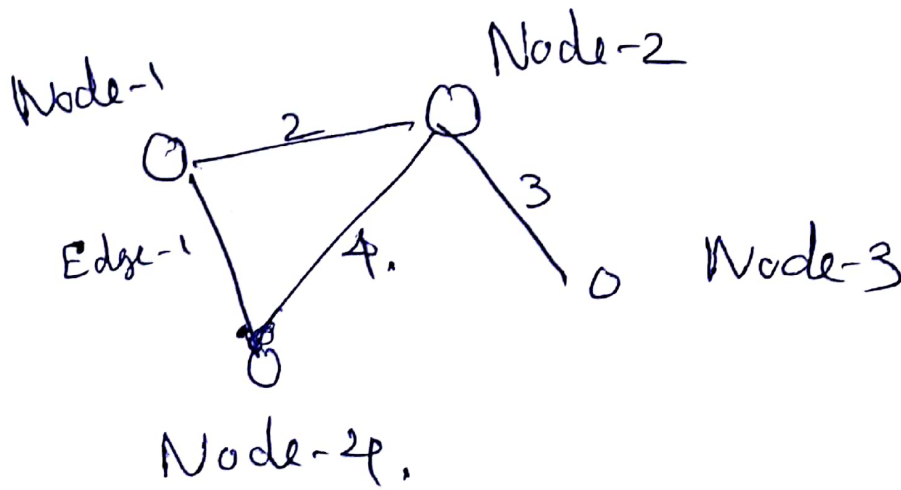
Nodes: Atomic elements.

Edges: bonds.

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The adjacency matrix of a network.



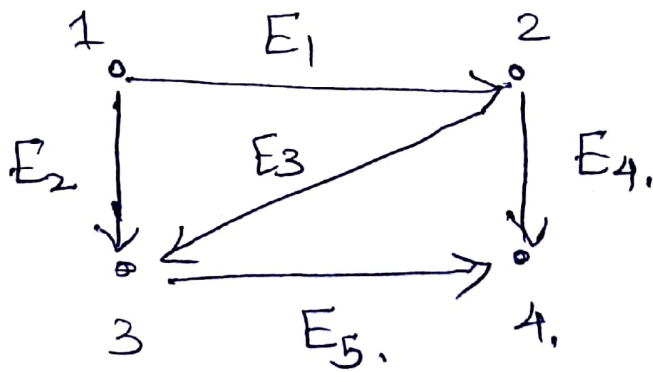
Inside a computer, one of the ways in which the network gets represented is in terms of the adjacency matrix.

$a_{ij} = 1$  if  $i^{\text{th}}$  &  $j^{\text{th}}$  nodes are connected

$a_{ij} = 0$  otherwise.

$$A = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \end{bmatrix}$$

## Electrical circuit



Edge node matrix is used to represent this network.

Edges

$$\begin{array}{c}
 1 \\
 2 \\
 3 \\
 4 \\
 5
 \end{array}
 \begin{bmatrix}
 -1 & 1 & 0 & 0 \\
 -1 & 0 & 1 & 0 \\
 0 & -1 & 1 & 0 \\
 0 & -1 & 0 & 1 \\
 0 & 0 & -1 & 1
 \end{bmatrix}$$

Nodes : 1 2 3 4.

If a node has an outgoing edge the edge entry is -1

An incoming edge entry is +1

No edge of the given index, the entry is 0.

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The meaning of the matrix equation

$$A x^T = b^T$$

The entries in  $b^T$  are potential differences across the edges.

The entries in  $x^T$  are potentials at the node

Given the potential differences, find the potentials on the nodes.

$$\begin{bmatrix} -1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \\ b_5 \end{bmatrix}$$

$x_2 - x_1 = b_1$  The potential difference between node 2 & node 1 is  $b_1$ .

What would  $N(A)$  mean?

Find the  $N(A)$ .

$$x_1 = x_2 = x_3 = x_n$$

A general null vector

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_n \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$



The Null space is 1 dimensional.

(one free variable), it is the

line  $x_1 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$ .

How does the  $N(A)$  affect the solution of  $Ax = b$ ?

Given a solution  $x^*$ , another solution  $y^*$  can be found by adding a null vector to  $x^*$ .

$$\text{If } Ax^* = b$$

$$\text{then } A(x^* + x_n) = Ay^* = b$$

$$\text{because } Ax_n = 0$$

You can find all the infinite solutions by knowing only one solution.

Tangent: An example of gauge transformation. Potentials can be defined only upto an arbitrary constant.

⑥

what is  $C(A)$ ?

All such vectors  $b \uparrow$  for which  
 $Ax \uparrow = b \uparrow$  is solvable.

\* Exercise find  $C(A)$   
in terms of conditions on  $b_1$  to  $b_5$