Probabilistic Program Analysis

 ${\sf Symbolic\ Execution\ +\ Model\ Counting\ +\ Reinforcement\ Learning}$

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Summer 2014



How do you tell if your program works correctly?

(hint: this is a two part answer)



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Specify what it means to be correct



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- Specify what it means to be correct
- Provide evidence that the program's behavior matches the specification



How can you specify what it means to be correct?



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$$completeTriple(a, b) = c \iff \sqrt{a^2 + b^2} = c \lor \sqrt{a^2 + c^2} = b \lor \dots$$



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- testing: $completeTriple(3,4) = c \iff \sqrt{3^2 + 4^2} = \sqrt{25} = 5 = c \lor \dots$



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Wouldn't it be nice if you could systematically check all/most of the program's behavior against the specification?



Consider the following program fragment:

```
lint classify(int a, int b, int c) {
  if (a==b)
    type+=1;
  if (a==c)
    type+=2;
  if (b==c)
    type+=3;
  assert type != 6; ...
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tree
           program
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A graph of program traces
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Graphs can encode large sets of program traces



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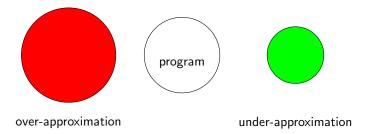
- exploit well-understood graph algorithms for analysis
- e.g., DFS, intersection/union over prefixes/suffixes of paths, etc.



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missing behavior



Where is the overapproximation?

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Underapproximating Symbolic Execution

```
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Basic symbolic execution algorithm

```
Algorithm 1 symbolicExecute(I, \phi, m)
```

```
while \neg branch(I) do m \leftarrow m \langle v, e \rangle I \leftarrow next(I) end while c \leftarrow m[cond(I)] if SAT(\phi \wedge c) then symbolicExecute(target(I), \phi \wedge c, m) end if if SAT(\phi \wedge \neg c) then symbolicExecute(next(I), \phi \wedge \neg c, m) end if
```



A simple example ...

```
int classify(int a, int b, int c) {
  if (a \le 0 \mid | b \le 0 \mid | c \le 0) return 4;
  int type=0:
  if (a=b) type+=1:
  if (a=c) type+=2;
  if (b=c) type+=3:
  if (type==0) {
    if (a+b \le c | b+c \le a | a+c \ge b) type=4;
    else type=1:
    return type;
  if (type>3) type=3;
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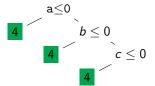


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Symbolic execution tree



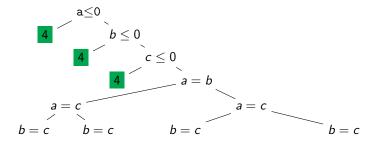


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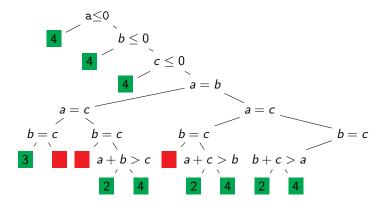


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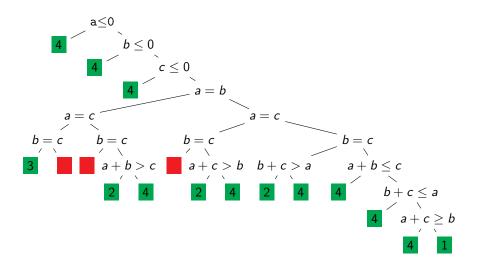


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Symbolic execution tree





Some observations

- There are 14 distinct paths (Green): from 1 to 9 branches
- 1 path returns "scalene" (1); 3 return "isoscelese" (2); and 1 returns "equilateral" (3)
- 3 paths are pruned because constraints are unsat (Red)
- Interesting symmetries are involved in the "isoscelese" and unsat cases



Analyzing program behavior

The symbolic execution could be used to ...

- check contracts, e.g., if a = b = c then return = 3
- generate a suite of 14 thorough tests
- ullet demonstrate that it is possible to return values [1,4]

... and support answering other yes/no questions about program behavior.



Moving beyond yes/no questions

We are interested in exploring how to ...

- determine the chance that a contract holds (1 is a special case)
- focus testing on rare paths (likely ones are easy to hit)
- determine how frequently a given value is returned



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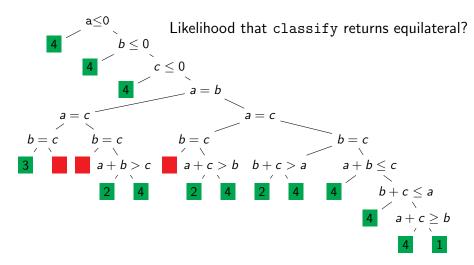
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When yes/no questions cannot be answered can we quantify what was discovered during program analysis?

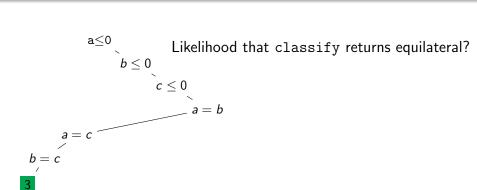


Assume ints are drawn uniformly from [-1000, 1000]





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Likelihood that classify returns equilateral?
$$b \leq 0$$

$$c \leq 0$$

$$a = b$$

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$$3 \quad \neg (a \leq 0) \land \neg (b \leq 0) \land \neg (c \leq 0) \land (a = b) \land (a = c) \land (b = c)$$

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Likelihood that classify returns equilateral?
$$b \leq 0 \qquad c \leq 0 \qquad 1.25e^{-7}$$

$$a = b$$

How many inputs satisfy this path condition?

1000



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 - returns a value, reaches a statement, ...



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- We want to calculate the probability that a program's execution ...
 - returns a value, reaches a statement, ...
- Adapting symbolic execution to perform these computations involves ...
 - calculating the paths of interest
 - calculating the probability of taking those paths
 - combining those probabilities appropriately



Probabilistic symbolic execution algorithm

Algorithm 2 probSymbolicExecute (I, ϕ, m, p)

```
while \neg branch(I) do
   m \leftarrow m \langle v, e \rangle
   I \leftarrow next(I)
end while
c \leftarrow m[cond(I)]
 \phi' \leftarrow slice(\phi, c)
 p_c \leftarrow prob(\phi' \wedge c)/prob(\phi')
if p_c > 0 then
   probSymbolicExecute(target(I), \phi \land c, m, p * p_c)
end if
if p_c < 1 then
   probSymbolicExecute(next(I), \phi \land \neg c, m, p * (1 - p_c))
end if
```



Key algorithmic features

Slicing the path condition, i.e., $slice(\phi, c)$

- ullet reduces formula size which reduces cost of $prob(\cdot)$
- ullet exposes opportunities for reusing computation in $prob(\cdot)$



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Calculating the conditional probability p_c of c

- requires model counting of path condition
- ullet determines satisfiability of branches, i.e., $p_c>0 \implies SAT(\phi \wedge c)$
- allows inference of off-branch probability, i.e., $p * (1 p_c)$
- ullet depth-first nature of symbolic execution ensures that $prob(\phi')$ will be reused
- ullet slicing assures independence in computing p_c , i.e., $\phi-\phi'$ factored out



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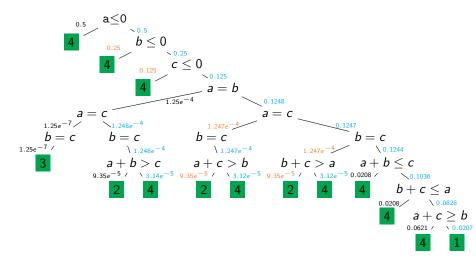
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Calculating the conditional probability p_c of c

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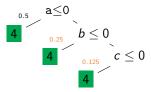
This allows the algorithm to compute path probabilities cost-effectively.

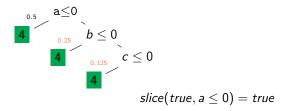


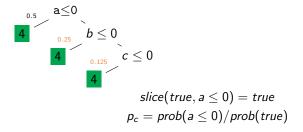


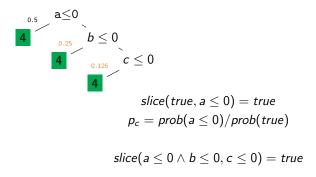
29 branches: 8 counting queries, 6 reused, 15 inferred

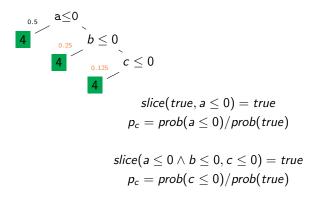












$$a \leq 0$$

$$0.25 \qquad b \leq 0$$

$$slice(true, a \leq 0) = true$$

$$p_c = prob(a \leq 0)/prob(true)$$

$$slice(a \leq 0 \land b \leq 0, c \leq 0) = true$$

$$p_c = prob(c \leq 0)/prob(true)$$

Normalization of constraints, e.g., $a\mapsto v_1$, $c\mapsto v_1$, enables reuse in calculating p_c



Calculating $prob(\cdot)$

We report on support for linear integer arithmetic (LIA) constraints using LattE

- computes the number of *lattice* points in a convex polytope;
- constraints encoded as system of inequalities, $Ax \leq B$;
- does not support disjunction or disequality constraints, i.e., $x \neq c$



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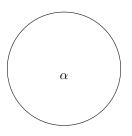
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Our calculation relies on "counting" the number of solutions of a set of related constraints using LattE and combining the results.

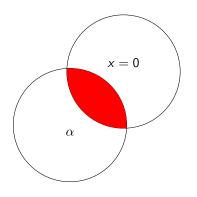
- $count = count_{\land}(\bigwedge_{ineqSet}) count_{\lor}(\bigvee_{exSet})$
- return $count/\prod_{v \in vars} dom(v)$





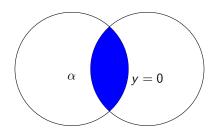
Count the solutions to α





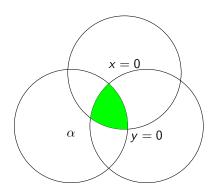
Remove the count of solutions to $\alpha \wedge (x = 0)$





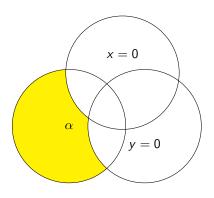
Remove the count of solutions to $\alpha \wedge (y = 0)$



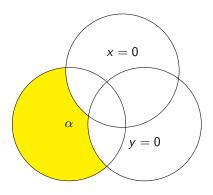


Add back the count of solutions to $\alpha \wedge (x = 0) \wedge (y = 0)$





This results in the count of $\alpha \wedge (x \neq 0) \wedge (y \neq 0)$



This results in the count of $\alpha \wedge (x \neq 0) \wedge (y \neq 0)$ Complexity is exponential in number of disequality constraints



Optimizing $count_{\wedge}(\cdot)$

Our experience with LattE revealed that its execution time

- is not dependent on the size of variable domains;
- is highly dependent on the number of variables (dimension of the polytope);
- is highly dependent on the number of constraints (faces of the polytope);



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- sliced PCs, if normalized, recur throughout the symbolic execution tree



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Our implementation of $count_{\wedge}(\cdot)$

- normalizes the inequality system
- caches the counts computed for each system; and
- checks the cache before invoking LattE.



How well does this work?

Our ISSTA 2012 paper describes several usage scenarios ...

- finding a bug by looking at anomalies in path probabilities;
- assessing the probability of covering lines of code; and
- characterizing the likelihood of detected bugs



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I'll focus on the necessity of the optimizations we've developed.



Memoization and Slicing are key

- Ran on Binomial Heap and TreeMap collections with all possible input sequences (adds, removes, etc.) of length 4;
- times reported in seconds



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Subject	Memoize	Slice	PC	Var	$prob(\cdot)$	LattE	Reused	LattE	Total
			Red.	Red.	, ,			time	time
Binomial	~	~	55%	67%	634	518	370	35	57
	×	~	55%	67%	634	888	0	61	84
	~	×	0%	0%	634	3160	698	388	414
TreeMap	~	~	44%	55%	766	2264	562	118	145
	×	~	44%	55%	766	2826	0	150	178
	~	X	0%	0%	766	12108	4965	1028	1056



Non-deterministic choice is used to model a lack of information

• e.g., details of OS scheduling algorithm



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Two additional challenges

- What conditional probability should we use for a non-deterministic choice?
- State space explosion

We use a sampling-based analysis with reinforcement learning



View program's behavior as a tree-structured Markov Decision Process

• symbolic execution tree with non-deterministic choice nodes



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Randomly sample paths, but unlike Monte Carlo methods

- ullet each sampled path, p, contributes mass proportional to $count(PC_p)$
- a sampled path is biased against being revisited



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- calculation is bottom up like value-iteration



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Fastest and most precise method to date (submitted to ASE 2014)



Availability and Ongoing work

An SPF extension that implements our approach is available

- http://probsym.googlecode.com
- improved over results in paper; uses the Green solver interface
- http://green-solver.googlecode.com
- multiple MDP-based algorithms (exact and sampling based)



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We have added ...

- confidence-based model counting when exact counters are inefficient (PLDI'14);
- support for user defined input probability distributions; and
- parallelism to exploit sample independence



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