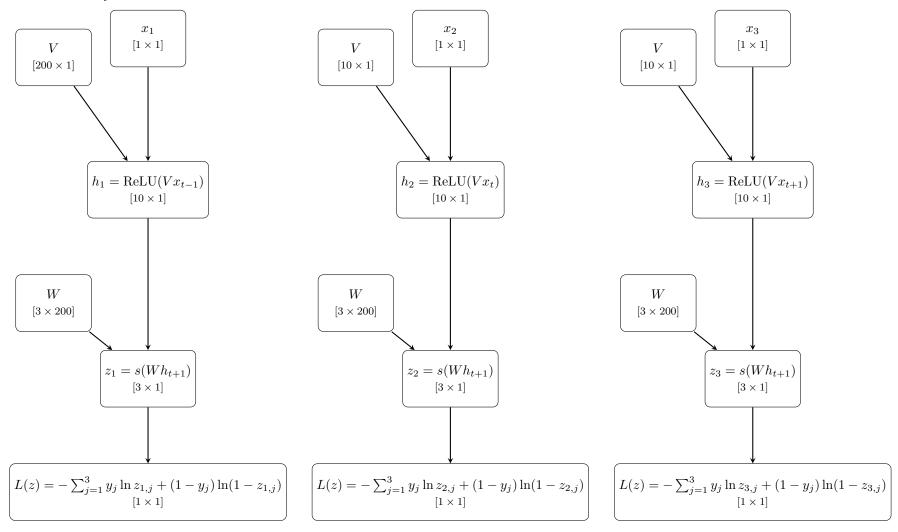
## RNN Diagram - ReLU Activation on Hidden Layer

The constructed neural net follows the diagram below.  $x \in \mathbb{R}^{24}$ , a feature vector with  $(4 \text{ hours} \times 6 \text{ intervals}) = 24 \text{ features corresponding to occupancies}$  every 10 minutes for 4 hours before the current time. For clarity, shapes of the solutions are given in brackets. Subscript j denotes a row index.  $A_j^T$  indicates the transpose of  $A_j$ .



$$A_k = Vx_k$$

```
\nabla_V L =
(\nabla_{z_t} L)(\nabla_V z_{t+1}) =
(\nabla_{z_t}L)(\nabla_{h_{t+1}}z_{t+1})(\nabla_V h_{t+1}) =
\left(\frac{1-y_j}{1-z_j} - \frac{y_j}{z_j}\right) \left(z_j(1-z_j)W_j^T\right) \left(\nabla_V h_{t+1}\right) =
(z_i - y_i) W_i^T (\nabla_V h_{t+1}) =
W_i^T (z_i - y_i) (\nabla_V h_{t+1}) =
W^T(z-y)(\nabla_V h_{t+1}) =
W^{T}(z-y) (\nabla_{A_{t+1}} h_{t+1}) (\nabla_{V} A_{t+1}) =
W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) \left( \nabla_{V} V x_{t+1} \right) =
W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) \left( \nabla_{V} U h_{t} \right) + W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) \left( \nabla_{V} V x_{t+1} \right) =
W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) \left( U \nabla_{V} h_{t} \right) + W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) \left( I^{[200 \times 200]} x_{t+1} \right) =
W^{T}(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)U\left(\nabla_{A_{t}}h_{t}\right)\left(\nabla_{V}A_{t}\right) + W^{T}(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)\left(I^{[200\times200]}x_{t+1}\right) =
W^{T}(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)U\left(\nabla_{A_{t}}h_{t}\right)\left(\nabla_{V}Uh_{t-1}+\nabla_{V}Vx_{t}\right)+W^{T}(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)\left(I^{[200\times200]}x_{t+1}\right)=
W^{T}(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)U\left(\nabla_{A_{t}}h_{t}\right)\left(\nabla_{V}Uh_{t-1}\right) + W^{T}(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)U\left(\nabla_{A_{t}}h_{t}\right)\left(\nabla_{V}Vx_{t}\right) + W^{T}(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)\left(I^{[200\times200]}x_{t+1}\right) = 0
W^{T}(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)U\left(\nabla_{A_{t}}h_{t}\right)U\left(\nabla_{V}h_{t-1}\right)+W^{T}(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)U\left(I^{[200\times200]}x_{t}\right)\left(\nabla_{A_{t}}h_{t}\right)+W^{T}(z-y)\left(I^{[200\times200]}x_{t+1}\right)\left(\nabla_{A_{t+1}}h_{t+1}\right)=0
\nabla_U L =
(\nabla_{z_{t+1}}L)(\nabla_{U}z_{t+1}) =
\left(\nabla_{z_{t+1}}L\right)\left(\nabla_{h_{t+1}}z_{t+1}\right)\left(\nabla_{U}h_{t+1}\right) =
 \left(\frac{1-y_j}{1-z_i} - \frac{y_j}{z_i}\right) \left(z_j(1-z_j)W_j^T\right) \left(\nabla_U h_{t+1}\right) =
(z_i - y_i) W_i^T (\nabla_U h_{t+1}) =
W_i^T (z_i - y_i) (\nabla_U h_{t+1}) =
W^T(z-y)(\nabla_U h_{t+1}) =
W^T(z-y)(\nabla_{A_{t+1}}h_{t+1})(\nabla_U A_{t+1}) =
W^{T}(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)\left(\nabla_{U}Uh_{t}\right) =
W^T(z-y)\left(\nabla_{A_{t+1}}h_{t+1}\right)\left[U\nabla_Uh_t+h_t\right]=
W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) U \left( \nabla_{U} h_{t} \right) + W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) h_{t} =
W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) U \left( \nabla_{A_{t}} h_{t} \right) \left( \nabla_{U} A_{t} \right) + W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) h_{t} =
W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) U \left( \nabla_{A_{t}} h_{t} \right) \left( \nabla_{U} U h_{t-1} \right) + W^{T}(z-y) \left( \nabla_{A_{t+1}} h_{t+1} \right) h_{t} =
W^{T}(z-y) (\nabla_{A_{t+1}} h_{t+1}) U (\nabla_{A_{t}} h_{t}) [U \nabla_{U} h_{t-1} + h_{t-1}] + W^{T}(z-y) (\nabla_{A_{t+1}} h_{t+1}) h_{t} =
W^{T}(z-y) \left(\nabla_{A_{t+1}} h_{t+1}\right) U\left(\nabla_{A_{t}} h_{t}\right) U\left(\nabla_{U} h_{t-1}\right) + W^{T}(z-y) \left(\nabla_{A_{t+1}} h_{t+1}\right) U\left(\nabla_{A_{t}} h_{t}\right) h_{t-1} + W^{T}(z-y) \left(\nabla_{A_{t+1}} h_{t+1}\right) h_{t} = 0
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$$\begin{split} \nabla_W L &= \\ \left(\nabla_{z_f} L\right) \left(\nabla_W z_f\right) \\ \left(\nabla_{z_j} L\right) \left(\nabla_{W_j} z_j\right) \\ \left(\frac{1-y_j}{1-z_j} - \frac{y_j}{z_j}\right) z_j (1-z_j) h_f^T \\ \left(z_j - y_j\right) h_f^T \\ \left(z - y\right) h_f^T \quad [3 \times 200] \end{split}$$

$$\nabla_{z_j} L = \frac{1 - y_j}{1 - z_j} - \frac{y_j}{z_j}$$

$$\nabla_{W_j} z_j = z_j (1 - z_j) h^T \quad [1 \times 200]$$

$$\nabla_h z_j = z_j (1 - z_j) W_j^T \quad [201 \times 1]$$

$$\nabla_A h = \text{(elementwise)} \begin{cases} 1, & h_j > 0 \\ 0, & h_j < 0 \end{cases}$$

$$\nabla_U h = \text{recursive expansion}$$

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We can substitute the following expressions:

$$\nabla_h z_j = z_j (1 - z_j) W_j^T \quad [201 \times 1]$$
$$\nabla_{V_j} h_j = \operatorname{sech}^2(V_j x) x^T \quad [1 \times 785]$$

We can also use backpropagation to show:

$$\nabla_{W_{j}} L = \left(\frac{1 - y_{j}}{1 - z_{j}} - \frac{y_{j}}{z_{j}}\right) \left(z_{j}(1 - z_{j})h^{T}\right) \quad [1 \times 201]$$

$$\nabla_{h} L = \sum_{j=1}^{26} \left(\frac{1 - y_{j}}{1 - z_{j}} - \frac{y_{j}}{z_{j}}\right) \left(z_{j}(1 - z_{j})W_{j}^{T}\right) \quad [201 \times 1]$$

$$\nabla_{V_{j}} L = (\nabla_{h} L)_{j} \operatorname{sech}^{2}(V_{j} x)x^{T} \quad [1 \times 785]$$

To enhance calculation efficiency, we can reduce some of these equations into matrices. First, let  $\mathcal{Q}$  be the matrix

$$Q = \begin{bmatrix} z_1(1-z_1) \left(\frac{1-y_1}{1-z_1} - \frac{y_1}{z_1}\right) \\ z_2(1-z_2) \left(\frac{1-y_2}{1-z_2} - \frac{y_2}{z_2}\right) \\ \vdots \\ z_{26}(1-z_{26}) \left(\frac{1-y_{26}}{1-z_{26}} - \frac{y_{26}}{z_{26}}\right) \end{bmatrix} = \begin{bmatrix} z_1 - y_1 \\ z_2 - y_2 \\ \vdots \\ z_{26} - y_{26} \end{bmatrix}$$

With this, we can reexpress the above equations.

$$\nabla W_j L = \mathcal{Q}_j h^T \qquad [1 \times 201]$$
or

$$\nabla_W L = \begin{bmatrix} \mathcal{Q}_1 h^T \\ \mathcal{Q}_2 h^T \\ \vdots \\ \mathcal{Q}_{26} h^T \end{bmatrix} = \mathcal{Q} h^T = \mathcal{Q} \otimes h \quad [26 \times 201]$$

(2) 
$$\nabla_h L = \sum_{j=1}^{26} \mathcal{Q}_j W_j^T \quad [201 \times 1]$$
 or

$$\nabla_h L = \left[ \mathcal{Q}_1 W_1^T + \mathcal{Q}_2 W_2^T + \dots + \mathcal{Q}_{26} W_{26}^T \right]$$
$$\nabla_h L = \left[ W_1^T \mathcal{Q}_1 + W_2^T \mathcal{Q}_2 + \dots + W_{26}^T \mathcal{Q}_{26} \right]$$

$$\nabla_h L = \begin{bmatrix} W_1^T & W_2^T & \dots & W_{26}^T \end{bmatrix} \begin{bmatrix} \mathcal{Q}_1 \\ \mathcal{Q}_2 \\ \vdots \\ \mathcal{Q}_{26} \end{bmatrix} = W^T \mathcal{Q} \quad [201 \times 1]$$

(3) Additionally, let

$$S = \begin{bmatrix} \operatorname{sech}^{2}(V_{1}x) \\ \operatorname{sech}^{2}(V_{2}x) \\ \vdots \\ \operatorname{sech}^{2}(V_{200}x) \end{bmatrix} = \operatorname{sech}^{2}(Vx)$$

Then,  $\nabla_{V_j} L = (W^T \mathcal{Q})_j \operatorname{sech}^2(V_j x) x^T$  [1 × 785]

$$\nabla_{V}L = \begin{bmatrix} (W^{T}Q)_{1} \operatorname{sech}^{2}(V_{1}x)x^{T} \\ (W^{T}Q)_{2} \operatorname{sech}^{2}(V_{2}x)x^{T} \\ \vdots \\ (W^{T}Q)_{200} \operatorname{sech}^{2}(V_{200}x)x^{T} \end{bmatrix} = \begin{bmatrix} (W^{T}Q)_{1} \operatorname{sech}^{2}(V_{1}x) \\ (W^{T}Q)_{2} \operatorname{sech}^{2}(V_{2}x) \\ \vdots \\ (W^{T}Q)_{200} \operatorname{sech}^{2}(V_{200}x) \end{bmatrix} x^{T}$$

$$\nabla_V L = \left( \begin{bmatrix} (W^T \mathcal{Q})_1 \\ (W^T \mathcal{Q})_2 \\ \vdots \\ (W^T \mathcal{Q})_{200} \end{bmatrix} \circ \begin{bmatrix} \operatorname{sech}^2(V_1 x) \\ \operatorname{sech}^2(V_2 x) \\ \vdots \\ \operatorname{sech}^2(V_{200} x) \end{bmatrix} \right) x^T = (W^T \mathcal{Q}) \circ \mathcal{S} x^T$$

Since we are updating our matrices V and W using stochastic gradient descent, we repeat the following process:

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V,W \leftarrow weight matrices initialized randomly from normal distribution with mean \mu=0 and \sigma^2=(\ldots) while (continue = True or L(z)>0)

Forward calculation [h=\tanh(Vx) \rightarrow z=s(Wh) \rightarrow L(z)]

Backward calculation to return \nabla_V L and \nabla_W L

V \leftarrow V - \epsilon \nabla_V L)

W \leftarrow W - \epsilon \nabla_W L

return V,W

where, using our derived equations from above, the update rules are more specifically

V \leftarrow V - \epsilon(W^T Q) \circ \mathcal{S}x^T

W \leftarrow W - \epsilon(Q \otimes h).
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$$\begin{split} h &= \text{ReLU}(Uh_{t-1} + Vx_t) \\ \partial h/\partial h_{t-1} &= \text{RLD}(Uh_{t-1} + Vx_t)U^T \\ \partial h/\partial V &= \text{RLD}(Uh_{t-1} + Vx_t)(\partial(Uh_{t-1})/\partial V + \partial(Vx_t)/\partial V) = \text{RLD}(Uh_{t-1} + Vx_t)(U^T \frac{\partial h_{t-1}}{\partial h_{t-2}}(...) \frac{\partial h_0}{\partial V} + Ix_t) \\ \partial h_0/\partial V &= \\ \partial h/\partial U &= \text{RLD}(Uh_{t-1} + Vx_t)(\partial(Uh_{t-1})/\partial U + \partial(Vx_t)/\partial U) = \text{RLD}(Uh_{t-1} + Vx_t)(U^T \frac{\partial h_{t-1}}{\partial h_{t-2}}(...) \frac{\partial h_0}{\partial V} + Ix_t) \end{split}$$

$$y = \sin(Ax)$$
  

$$\partial y/\partial x = \frac{\partial (Ax)}{\partial x}\cos(Ax) = A^T\cos(Ax)$$
  

$$[200 \times 200] = [200 \times 1](...)$$