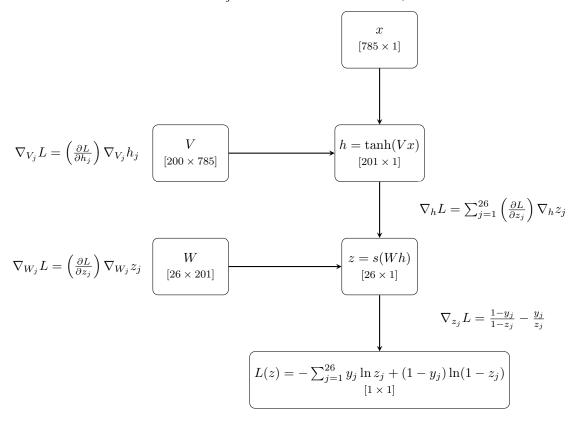
Problem 1

The constructed neural net follows the diagram below. $x \in \mathbb{R}^{785}$. For clarity, shapes of the solutions are given in brackets. Subscript j denotes a row index. A_j^T indicates the transpose of A_j .



We can substitute the following expressions:

$$\nabla_{W_{j}} z_{j} = z_{j} (1 - z_{j}) h^{T}$$
 [1 × 201]

$$\nabla_{h} z_{j} = z_{j} (1 - z_{j}) W_{j}^{T}$$
 [201 × 1]

$$\nabla_{V_{j}} h_{j} = \operatorname{sech}^{2}(V_{j} x) x^{T}$$
 [1 × 785]

We can also use backpropagation to show:

$$\nabla_{W_{j}} L = \left(\frac{1 - y_{j}}{1 - z_{j}} - \frac{y_{j}}{z_{j}}\right) \left(z_{j}(1 - z_{j})h^{T}\right) \quad [1 \times 201]$$

$$\nabla_{h} L = \sum_{j=1}^{26} \left(\frac{1 - y_{j}}{1 - z_{j}} - \frac{y_{j}}{z_{j}}\right) \left(z_{j}(1 - z_{j})W_{j}^{T}\right) \quad [201 \times 1]$$

$$\nabla_{V_{j}} L = (\nabla_{h} L)_{j} \operatorname{sech}^{2}(V_{j} x)x^{T} \quad [1 \times 785]$$

To enhance calculation efficiency, we can reduce some of these equations into matrices. First, let \mathcal{Q} be the matrix

$$Q = \begin{bmatrix} z_1(1-z_1) \left(\frac{1-y_1}{1-z_1} - \frac{y_1}{z_1} \right) \\ z_2(1-z_2) \left(\frac{1-y_2}{1-z_2} - \frac{y_2}{z_2} \right) \\ \vdots \\ z_{26}(1-z_{26}) \left(\frac{1-y_{26}}{1-z_{26}} - \frac{y_{26}}{z_{26}} \right) \end{bmatrix} = \begin{bmatrix} z_1 - y_1 \\ z_2 - y_2 \\ \vdots \\ z_{26} - y_{26} \end{bmatrix}$$

With this, we can reexpress the above equations.

 $\nabla_{W_j} L = \mathcal{Q}_j h^T \qquad [1 \times 201]$ or

$$abla_W L = \begin{bmatrix} \mathcal{Q}_1 h^T \\ \mathcal{Q}_2 h^T \\ \vdots \\ \mathcal{Q}_{26} h^T \end{bmatrix} = \mathcal{Q} h^T = \mathcal{Q} \otimes h \quad [26 \times 201]$$

(2)
$$\nabla_{h}L = \sum_{j=1}^{26} \mathcal{Q}_{j}W_{j}^{T} \quad [201 \times 1]$$
 or
$$\nabla_{h}L = \left[\mathcal{Q}_{1}W_{1}^{T} + \mathcal{Q}_{2}W_{2}^{T} + \dots + \mathcal{Q}_{26}W_{26}^{T}\right]$$

$$\nabla_{h}L = \left[W_{1}^{T}\mathcal{Q}_{1} + W_{2}^{T}\mathcal{Q}_{2} + \dots + W_{26}^{T}\mathcal{Q}_{26}\right]$$

$$\nabla_{h}L = \left[W_{1}^{T} \quad W_{2}^{T} \quad \dots \quad W_{26}^{T}\right] \begin{bmatrix} \mathcal{Q}_{1} \\ \mathcal{Q}_{2} \\ \vdots \\ \mathcal{Q}_{26} \end{bmatrix} = W^{T}\mathcal{Q} \quad [201 \times 1]$$

(3) Additionally, let

$$S = \begin{bmatrix} \operatorname{sech}^{2}(V_{1}x) \\ \operatorname{sech}^{2}(V_{2}x) \\ \vdots \\ \operatorname{sech}^{2}(V_{200}x) \end{bmatrix} = \operatorname{sech}^{2}(Vx)$$

Then, $\nabla_{V_j} L = (W^T \mathcal{Q})_j \operatorname{sech}^2(V_j x) x^T$ [1 × 785]

$$\nabla_{V}L = \begin{bmatrix} (W^{T}Q)_{1} \operatorname{sech}^{2}(V_{1}x)x^{T} \\ (W^{T}Q)_{2} \operatorname{sech}^{2}(V_{2}x)x^{T} \\ \vdots \\ (W^{T}Q)_{200} \operatorname{sech}^{2}(V_{200}x)x^{T} \end{bmatrix} = \begin{bmatrix} (W^{T}Q)_{1} \operatorname{sech}^{2}(V_{1}x) \\ (W^{T}Q)_{2} \operatorname{sech}^{2}(V_{2}x) \\ \vdots \\ (W^{T}Q)_{200} \operatorname{sech}^{2}(V_{200}x) \end{bmatrix} x^{T}$$

$$\nabla_{V}L = \begin{pmatrix} \begin{bmatrix} (W^{T}\mathcal{Q})_{1} \\ (W^{T}\mathcal{Q})_{2} \\ \vdots \\ (W^{T}\mathcal{Q})_{200} \end{bmatrix} \circ \begin{bmatrix} \operatorname{sech}^{2}(V_{1}x) \\ \operatorname{sech}^{2}(V_{2}x) \\ \vdots \\ \operatorname{sech}^{2}(V_{200}x) \end{bmatrix} \end{pmatrix} x^{T} = (W^{T}\mathcal{Q}) \circ \mathcal{S}x^{T}$$

Since we are updating our matrices V and W using stochastic gradient descent, we repeat the following process:

```
\begin{array}{l} V,W \leftarrow \text{weight matrices initialized randomly from normal distribution with mean } \mu=0 \text{ and } \sigma^2=(\ldots) \\ \text{while (continue} = \text{True or } L(z)>0) \\ \text{Forward calculation [} h=\tanh(Vx) \ \rightarrow \ z=s(Wh) \ \rightarrow \ L(z) \text{]} \\ \text{Backward calculation to return } \nabla_V L \text{ and } \nabla_W L \\ V \leftarrow V - \epsilon \nabla_V L) \\ W \leftarrow W - \epsilon \nabla_W L \\ \text{return } V,W \end{array}
```

where, using our derived equations from above, the update rules are more specifically

$$V \leftarrow V - \epsilon(W^T \mathcal{Q}) \circ \mathcal{S}x^T$$
$$W \leftarrow W - \epsilon(\mathcal{Q} \otimes h).$$

Problem 2

Implemenation & Results:

1) Hyperparameters

Manually tested values of learning rate ϵ between 1 and and 1×10^{-5} . Settled on 0.1 as an optimal value.

2) Training Accuracy

88.94% training accuracy was achieved after 20 epochs of stochastic gradient descent training.

3) Validation Accuracy

86.63% validation accuracy was achieved on the 20% of data that was initially withheld.

4) Loss vs. Iterations

(...)

5) Kaggle

Display Name: mitch Score: 0.87106

6) Code

See appendix for full implementation in NeuralNet class

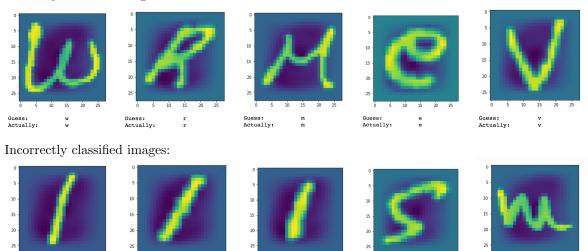
Guess: Actually:

Problem 3

Visualization

Correctly classified images:

Guess: Actually:



Problem 4

No extra bells and whistles were tested, though the neural network was designed to be flexible. The code currently operates using stochastic gradient descent, though it is designed to be able to take in multiple points (or the complete dataset) for easy conversion to batch/mini-batch gradient descent.

Furthermore, the modular structure allows the neural network to be adapted for any number of layers and any number of hidden units per layer. To do this, the code takes in the following sequences as arguments: layers, number of hidden units per layer, and activation functions per layer. Two modules are necessary to run this code, one containing activation functions to be included in the input sequence, and one containing a "gradient calculator" class which computes appropriate gradients for the desired neural network configuration.

Appendix

```
neuralnet.pv
Train a neural network and predict on test data
This python module contains the neural network class, which can be trained on
labeled data (input as numpy arrays: for data, an Nxd matrix with N rows
corresponding to {\tt N} sample points and d columns corresponding to d features; for
labels, an N vector with labels corresponding to each of the N sample points)
**NOTE: Use of this class requires the activationfns.py and gradients.py modules
import numpy as np
class NeuralNet:
    Train and store a neural network, based on supplied training data.
    Use this network to predict classifications.
    def __init__(self,nlayers=3,unitsperlayer=None,actfns=[af.sigmoid,af.sigmoid],Gradients=None,verbose=False):
        Initialize the neural network
        - nlayers:
                          the number of layers in the neural network (includes input and output layers)
        - unitsperlayer: a list specifying (in order) the number of units in all sequential layers except input
                        a list specifying (in order) the activation function used by all sequential layers except input
        - actfns:
         - Gradient:
                          a class providing optimized gradient calculations for the given sequence of
                           activation functions
                           a boolean for descriptive output
        if unitsperlayer == None:
             unitsperlayer = 3*np.ones(nlayers)
         elif nlayers == len(unitsperlayer)+1:
             self.nlayers = nlayers-1
             self.unitsperlayer = unitsperlayer
         elif nlayers > len(unitsperlayer)+1:
              \textbf{print('ERROR:} \ _{\square} \textbf{The} \ _{\square} \textbf{number} \ _{\square} \textbf{of} \ _{\square} \textbf{units} \ _{\square} \textbf{per} \ _{\square} \textbf{layer} \ _{\square} \textbf{were} \ _{\square} \textbf{not} \ _{\square} \textbf{given} \ _{\square} \textbf{for} \ _{\square} \textbf{at} \ _{\square} \textbf{least} \ _{\square} \textbf{one} \ _{\square} \textbf{layer} \ . \ ') 
         elif nlayers < len(unitsperlayer)+1:</pre>
             print('ERROR: More layers were given units than were specified by input "nlayers".')
        if nlayers == len(actfns)+1:
             self.actfns = actfns
         elif nlayers > len(actfns)+1:
             print('ERROR: "The activation function was not given for at least one layer.')
         elif nlayers < len(actfns)+1:</pre>
             if Gradients == None:
             \label{eq:print} \textbf{print('ERROR:} \_A\_gradient\_generator\_class\_must\_be\_included.')}
         self.gradients = Gradients
        self.weight_matrices = []
    def initialize_weights(self,shape,mu=0,var=1):
        Initialize weight matrix from normal distribution.
         - shape: tuple specifying desired shape of weight matrix
         - mu:
                  mean value of normal distribution
         - var:
                  variance of normal distribution
        weight_matrix = np.random.normal(loc=mu,scale=np.sqrt(var),size=shape)
        return weight matrix
    def weight_matrix_shape(self,layer_n,nfeatures):
        Create weight matrix with the proper number of rows and columns for this layer
                       the layer which will employ an activation function on the
                       product of the weight matrix and values
         - nfeatures: an integer specifying the number of features in the dataset
        if layer_n != 0 and layer_n != range(self.nlayers)[-1]:
             WM_nrows = self.unitsperlayer[layer_n]-1
             WM_ncols = self.unitsperlayer[layer_n-1]
         elif layer_n == 0:
             WM_nrows = self.unitsperlayer[layer_n]-1
             WM_ncols = nfeatures
         else:
             WM_nrows = self.unitsperlayer[layer_n]
```

```
WM ncols = self.unitsperlayer[layer n-1]
    return WM_nrows, WM_ncols
def forward(self.data):
    Perform forward pass through neural network by multiplying data by weights
    and enforcing a nonlinear activation function for each layer.
    - data:
                      \ensuremath{\mathtt{Nxd}} numpy array with N sample points and d features
    - weightmatrices: ordered list of sequential weight matrices corresponding to layers
                      ordered list of sequential activation functions corresponding to layers
                     (functions are defined in activationfuncs.py)
    Returns layeroutputs, a list of the outputs from each layer. The last entry
    is an CxN numpy array with hypotheses for each sample N_i being in class C_j.
    H = data.T
    layeroutputs = []
    for i in range(self.nlayers):
        W = self.weight_matrices[i]
        actfn = self.actfns[i]
        H = actfn(np.dot(W,H))
        # If the layer is not the output layer, add a fictitious unit for bias terms
        if i != self.nlayers-1:
            fictu = np.array([np.ones_like(H[0])])
            H = np.concatenate((H,fictu),axis=0)
        layeroutputs.append(H)
    return layeroutputs
def backward(self,layeroutputs,labelrange,gradients=None):
    Perform backward pass through neural network by computing gradients of
    input weight matrices with respect to the loss function comparing hypotheses
    to true values. Classes for gradients are provided in gradients.py module
    (a unique gradient class is required for neural networks with different
    numbers of layers and/or different activation functions)
    if gradients == None:
        Gradients = self.gradients
    gradients = Gradients.calculate(self.weight_matrices,layeroutputs,labelrange)
    return gradients
def classify_outputs(self,finaloutputs):
    Convert final outputs into classifications
    -finaloutputs: a CxN numpy array with hypotheses for each sample N_i being in
                   class C_j.
    Returns a 1D, length-N array with values corresponding to point classifications
    if len(finaloutputs) == 1:
    classifications = np.around(finaloutputs[0]).astype(int)
    if len(finaloutputs) > 1:
        # Add one for 1-indexing in classification labels
        {\tt classifications = (np.argmax(final outputs, axis=0) + np.ones(len(final outputs[0]))).astype(int)}
    return classifications
def train(self, data, labels, epsilon=0.1):
    Train the neural network on input data
    - data: Nxd numppy array with N sample points and d features
    - labels: 1D, length-N numpy array with labels for the N sample points
    # Ensure labels are integers and that data and labels are the same length
    labels = labels.astype(int)
    if len(data) != len(labels):
        print('ERROR: Data and labels must be the same length.')
    # Add fictitious unit for bias terms
    fictu = np.array([np.ones(len(data))]).T
    data = np.concatenate((data,fictu),axis=1)
    # Initialize Weights
    nfeatures = len(data[0])
    for layer_n in range(self.nlayers):
        WM_nrows, WM_ncols = self.weight_matrix_shape(layer_n, nfeatures)
        # Variance of weight matrix determined by fan-in (eta), the number of units in the previous layer
        # (or the number of data features when initializing the first weight matrix)
        eta = WM_ncols
        weight_matrix = self.initialize_weights((WM_nrows,WM_ncols),mu=0,var=(1/eta))
        self.weight_matrices.append(weight_matrix)
```

```
# Begin loop
    epochcounter = 0
    while epochcounter < 20:</pre>
        # Stochastic gradient descent: Loop over points randomly, one at a time
        # (Execute gradient class overhead before beginning)
        self.gradients.prepare(data, labels, self.unitsperlayer[-1])
        for datapoint_i in range(len(data)):
            X_i = np.array([data[datapoint_i]])
            layeroutput_i = self.forward(X_i)
            gradients = self.backward(layeroutput_i,[datapoint_i,datapoint_i+1])
            for n in range(self.nlayers):
                self.weight_matrices[n]=self.weight_matrices[n]-epsilon*gradients[n]
        epochcounter+=1
        DL = np.concatenate((data,labels),axis=1)
        np.random.shuffle(DL)
        data = DL[:,:-1]
        labels = np.array([DL[:,-1]]).T epsilon *=0.75
def predict(self,testdata):
    Predict classfications for unlabeled data points using the previously
    trained neural network.
    - testdata: Nxd numpy array with N sample points and d features
                *Note, dimension d must match that used for the data array in NeuralNet.train*
    Returns a 1D, length-N numpy array of predictions (one prediction per point)
    # Add fictitious unit to input to match dimensions
    fictu = np.array([np.ones(len(testdata))]).T
    testdata = np.concatenate((testdata,fictu),axis=1)
    npoints = len(testdata)
    predictions = np.empty(npoints)
layeroutputs = self.forward(testdata)
    predictions = self.classify_outputs(layeroutputs[-1])
    return predictions.astype(int)
```

```
gradients.py
-----
Python module containing Gradient classes
This module contains gradient classes which calculate gradients for neural
net backpropagation quickly. A new, unique gradient class must be constructed
for neural networks with different numbers of layers, and/or different orderings
of activation functions.
(New gradient classes do not need to be created for neural networks that only differ
in the number of units per layer.)
import numpy as np
import activationfns as af
class tanhsig2layer:
    Gradient class for a two layer neural network. The first layer employs a tanh
    activation function, the second layer employs a sigmoid activation function, and the
    neural network uses a cross-entropy loss function.
    def __init__(self,verbose=False):
        self.V = None
        self.W = None
        self.h = None
        self.z = None
        self.X = None
        self.y = None
        self.grad_WL = None
        self.grad_VL = None
        self.verbose = verbose
    def prepare(self,data,labels,noutunits):
        self.X = data
        self.y = np.zeros((len(labels),noutunits))
for 1 in range(len(labels)):
            self.y[1,int(labels[1,0])-1] += 1
    def calculate(self, weight_matrices, layeroutputs, labelrange):
        c = 0
        for listset in [weight_matrices,layeroutputs]:
            if len(listset) != 2:
                if len(listset) > 2:
                    estring = 'More
                elif len(listset) < 2:</pre>
                    estring = 'Less'
                if not c:
                    lstring = 'weight_matrices'
                else:
                    lstring = 'layer outputs'
                print('ERROR: \_This\_gradient\_is\_for\_a\_two-layer\_neural\_network.\_\%s\_than\_two\_\%s\_were\_provided.''\% (estring,lstring,lstring))
                return
            c+=1
        self.V = weight_matrices[0]
        self.W = weight_matrices[1]
self.h = layeroutputs[0]
        self.z = layeroutputs[1]
        rangemin,rangemax = labelrange[0],labelrange[1]
        X = self.X[rangemin:rangemax]
        y = self.y[rangemin:rangemax]
        Q = self.z - y.T
        n = len(y)
        self.grad_VL = np.zeros_like(self.V)
        self.grad_WL = np.zeros_like(self.W)
        for i in range(n):
            S = np.array([1/np.square(np.cosh(np.dot(self.V,X[i])))]).T
            X_iTranspose = np.array([X[i]])
self.grad_VL += np.dot((np.dot(self.W.T,Q)[:-1]*S),X_iTranspose)
            self.grad_WL += np.outer(Q,self.h[:,i])
        # Optional output of intermediate steps
        if self.verbose:
            print('V\n',self.V)
            print('W\n',self.W)
            print('h\n',self.h)
```