

MicroBooNE

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ABSTRACT: This paper describes the design and construction of the MicroBooNE liquid argon time projection chamber and associated systems. Details of design specifications, assembly procedures, and acceptance tests are reported.

KEYWORDS: Time projection chambers; Noble liquid detectors; Neutrino detectors.

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1. Introduction and Physics Motivation

2 The potential of liquified noble gases to be employed as the detection media in particle detectors
3 with high spatial resolution was recognized in the 1960's [1]. Large calorimeters for the mea-
4 surement of particle energy were then realized by using cryogenic noble liquids as active compo-
5 nents [2]. The Liquid Argon Time Projection Chamber (LArTPC) was then proposed at CERN by
6 C. Rubbia in 1977 [3] as a detector capable of providing uniform and precise imaging of neutrino
7 interactions in large volumes. Since then, neutrino detection has entered a new era with a num-
8 ber of large precision neutrino detectors, LArTPCs, now in design, construction, data taking, and
9 analysis, both for long and short baseline neutrino oscillation experiments.

10 The implementation of the LArTPC idea was extensively developed within the ICARUS ex-
11 periment through an intense R&D program. Various prototype detectors were realized and operated
12 to develop the systems needed for larger physics experiments. Techniques for purification, signal
13 readout electronics, and cryogenics were developed [4–6].

14 The largest LArTPC detector built so far is the 600-ton ICARUS T600 detector, which was
15 operated first on the surface exposed to cosmic rays [7] before deployment underground at LNGS
16 for operation in the CNGS neutrino beam. ICARUS measurements have shown that the technique
17 is viable at large scales with a drift length as long as 1.5 m [8–12].

18 In the US, the first LArTPC to be successfully operated in a neutrino beam was the ArgoNeuT
19 detector [13] that, despite the relatively small mass of ~ 170 kg, has been able to perform a series
20 of detailed studies on the interaction of medium-energy neutrinos[14–17].

21 The US-based program has built on these past successes taking advantage of the large scale,
22 precision capabilities of the LArTPC detection technique for the Short Baseline Neutrino (SBN)
23 program and the long baseline programs leading to the DUNE experiment.

24 The **Micro Booster Neutrino Experiment**, henceforth referred to as MicroBooNE, is the first
25 large (~ 100 tons) LArTPC to operate in the United States and the second only after ICARUS to
26 operate worldwide. It is the first of three experiments comprising the SBN program. MicroBooNE
27 combines a physics program of short-baseline oscillations and neutrino cross-section measurements
28 with development goals to inform larger scale construction of LArTPCs for the short and long-
29 baseline programs.

30 MicroBooNE's principal physics goal is to address short baseline neutrino oscillations, specif-
31 ically the MiniBooNE low energy excess result [18], at Fermi National Accelerator Laboratory
32 (Fermilab). MicroBooNE will be exposed to the 0.5-2 GeV on-axis Booster Neutrino Beam (BNB),
33 the same beam used for the MiniBooNE experiment, at a ~ 500 m baseline, also the same as Mini-
34 BooNE, but by employing the LArTPC technology to efficiently separate signal electrons from
35 background photons.

36 In addition to MicroBooNE's signature oscillation analyses, a suite of precision cross-section
37 measurements will be performed, critical both for future LArTPC oscillation experiments and for
38 what can be learned about neutrino interactions in general. In the neutrino interactions from the
39 BNB, multiple interaction processes (quasi-elastic, resonances, deep inelastic scattering) are pos-
40 sible, and complicated nuclear effects in neutrino interactions on argon result in a variety of final
41 states. These can range from the emission of several nucleons to more complex topologies with
42 multiple pions, all in addition to the leading lepton in charged-current events. The LArTPC tech-

1 nology employed by MicroBooNE is particularly well suited for complicated topologies because
2 of its excellent particle identification capability and calorimetric energy reconstruction down to
3 very low detection thresholds. MicroBooNE will also be supernova live and capable of detecting
4 a galactic supernova, and prepare the analysis of the search for proton decays. For a proton decay
5 search, the experiment will not have a competitive sensitivity due to too small target mass. How-
6 ever, this will be an important proof of principle measurement towards future searches in larger
7 detectors.

8 MicroBooNE is located 470 m from the BNB production target and 600 m from the NuMI pro-
9 duction target. MicroBooNE began operations in late 2015 for an anticipated ~ 3 year data taking
10 run. The next phase of the SBN program at Fermilab includes continued operation of MicroBooNE
11 along with the SBND and ICARUS experiments, located at 110 m and 600 m respectively from
12 the BNB target. SBND and ICARUS are now under construction [19] with operations to begin in
13 ~ 2018 . MicroBooNE will definitively address whether or not the MiniBooNE low energy excess
14 in neutrino mode is due to electrons or photons in its initial run. SBND will look for this low
15 energy excess at the near location and ICARUS, with its larger mass, will enable the three detector
16 program to cover the entire LSND allowed region in neutrino parameter space to 5σ through ν_e
17 appearance.

18 More information on the LArTPC technology can be found in existing reviews (see, e.g., [20]
19 and references therein).

20 **Organization of Document** This document describes the design, construction, and technical
21 details of MicroBooNE. Section 2 gives a brief review of the LArTPC technique and its imple-
22 mentation in MicroBooNE. Section 3 describes the cryogenic and purification systems which are
23 required for maintaining a stable volume of highly purified liquid argon. The LArTPC detector de-
24 scribed in section 4 is the centerpiece of the experiment, providing fine-grained images of neutrino
25 interactions. A light collection system, described in section 5, provides precise timing information
26 by viewing the detector volume and recording signals from the scintillation light that is produced
27 therein. Signals from the light collection system and from the LArTPC are amplified, sampled, and
28 recorded by a custom-designed electronic and readout system, as described in section 6. Section 7
29 describes the auxiliary instrumentation that monitor and control the detector and all of its associated
30 systems, as well as provide an electrically quiet environment for the experiment to operate. Finally,
31 one of the main calibration sources for the experiment is an ultraviolet laser system, described in
32 section 8, that provides the capability to map out the performance of the LArTPC detector. A cos-
33 mic ray tagger system, under construction at the time of the writing of this paper, will surround
34 the detector to improve cosmic ray identification and rejection. This system will be described in a
35 subsequent publication.

36 **2. Experiment Overview**

37 The MicroBooNE detector at Fermilab in Batavia, Illinois is sited on axis on the BNB, 470 m
38 downstream from the neutrino production target. The BNB delivers a beam of predominantly
39 muon neutrinos with energies peaking at 700 MeV produced primarily from pion decays[21]. Mi-
40 croBooNE is also exposed to an off-axis component of the NuMI beam [22] produced from pion

and kaon decays with average neutrino energies of about 2 GeV and 0.5 GeV respectively. MicroBooNE is located about 600 m downstream from the NuMI neutrino production target. The characteristics of the BNB beamline are well measured and understood from many years of data taking and analysis on the MiniBooNE experiment [23], which operated directly downstream of the MicroBooNE location. Figure 1 shows the arrangement of MicroBooNE with respect to the BNB beamline at Fermilab. The physics program of MicroBooNE will utilize both BNB and NuMI samples. MicroBooNE will also collect data that is out-of-time with either beam, which will be useful for developing analyses (e.g. proton decay searches) relevant for next-generation detectors.

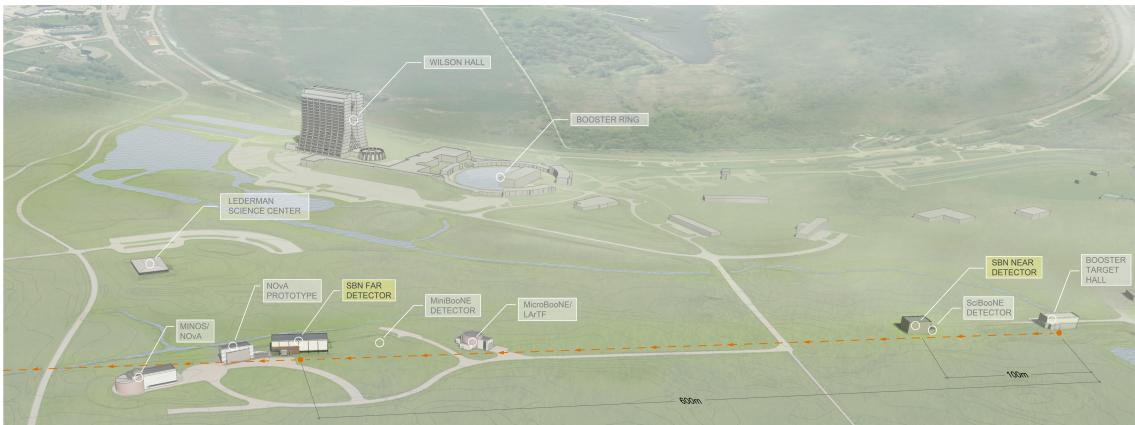


Figure 1: Aerial diagram showing location of MicroBooNE along the BNB (orange dashed line) at Fermilab.

2.1 The MicroBooNE LArTPC

Charged particles traversing a volume of highly-purified liquid argon leave trails of ionization electrons in their wake and also create prompt vacuum ultraviolet (VUV) scintillation photons. In a LArTPC the liquid argon is highly purified and the ionization trails are transported practically undistorted over distances of the order of meters [24] under the influence of a uniform electric field in the detector volume, until they reach anode planes located along one side of the active volume. The uniform electric field is created by introducing voltage onto a cathode plane and gradually stepping that voltage down in magnitude across a field cage, which is formed from a series of equipotential rings surrounding the drift volume. The anode plane is arranged parallel to the cathode plane, and in MicroBooNE, parallel to the beam direction. There are three planes comprised of sense wires with a characteristic pitch, held at a predetermined bias voltage, that continuously sense the signals induced by the ionization electrons drifting towards them. The electrostatic potentials of the sequence of anode planes allow ionization electrons to pass undisturbed by the first two planes before ultimately ending their trajectory on a wire in the last plane. The drifting ionization thus induces signals on the first planes (referred to as Induction planes) and directly contributes to the signals in the final plane (referred to as the Collection plane). Figure 2 depicts the arrangement of the MicroBooNE LArTPC.

The charged particle trajectory is reconstructed using the known positions of the anode plane wires and the recorded drift time of the ionization. The drift time is the difference between the

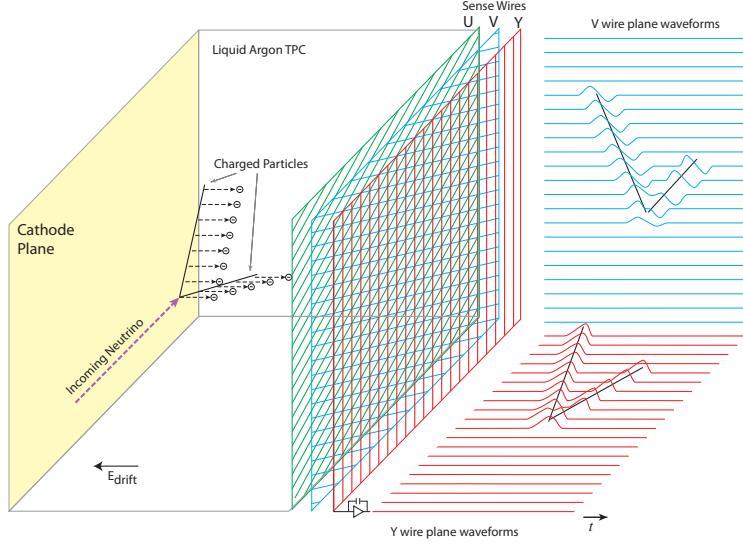


Figure 2: Operational principle of the MicroBooNE LArTPC.

1 arrival times of ionization signals on the wires and the time the interaction took place in the detector
 2 (t_0) which is provided by an accelerator clock synced to the beam (e.g. - BNB or NuMI) or from
 3 a trigger provided by the light collection system. The characteristics of the waveforms observed
 4 by each wire provide a measure of the energy deposition of the traversing particles near that wire,
 5 which, when taken as a whole for each contained particle's trajectory, allow for determination of
 6 momentum and particle identity.

7 The scintillation photons are detected by a light collection system that is immersed in the liquid
 8 argon and faces into the detector volume. This system provides signals that can establish the event
 9 t_0 and supplies trigger information to an electronic readout system. The light collection system
 10 signals are vital in distinguishing detector activity that is in-time with the beam (e.g. originating
 11 from beam interactions) from that which is out-of-time (e.g. likely not originating from beam-
 12 related interactions), benefiting event reconstruction. Spatial information transverse to the drift
 13 direction can also be inferred from the light collection signals, further aiding in the reconstruction
 14 of the activity occurring inside the detector.

15 The choice of liquid argon as both the neutrino target and detector medium in LArTPCs is well
 16 motivated, though not without introducing unique considerations for experimental design. Liquid
 17 argon as a target for neutrinos is attractive due to its density, allowing a more compact detector with
 18 a substantial boost in event rate over a comparable detector using less dense media, such as water.
 19 A tradeoff to this aspect is the short radiation length (14 cm) and that the complicated structure
 20 of the argon atom, relative to simpler targets such as hydrogen or helium, does introduce nuclear
 21 effects that must be considered during data analysis. The cryogenic temperatures at which the
 22 noble elements are in the liquid phase also introduces the need for additional design considerations
 23 to ensure stable and safe operations.

1 Table 1 lists some of the properties of liquid argon that are salient for LArTPC design. The
 2 noble liquids are all characterized by their excellent dielectric properties, able to maintain high volt-
 3 ages without suffering electrical breakdown. The long drift lengths over which ionization electrons
 4 must travel in large LArTPC detectors requires the presence of a uniform electric field over that
 5 distance. This is achieved via the introduction of extremely high voltage ($\mathcal{O}(100$ kV) magnitude)
 6 onto the LArTPC cathode; this voltage is suitably maintained due to the dielectric properties of
 7 liquid argon and by ensuring the detector components have no sharp edges. The noble liquids are
 8 all very bright scintillators, with wavelengths deep in the UV, and also produce copious amounts
 9 of ionization. Both the scintillation and the ionization signals are necessary for a robust accounting
 10 of the activity occurring inside the LArTPC. Finally, the desire to build LArTPCs on increasingly
 11 larger scales, such as those necessary in neutrino experiments, is bolstered by the abundance (1%
 12 of atmosphere) and low cost of argon.

Table 1: Selected properties of liquid argon.

Property	Value	Reference
Atomic number	18	
Atomic weight [g/mol]	39.95	
Boiling point [K] @ 1 atm	87.3	[25]
Density [g/cm ³] @ 1 atm	1.4	[25]
Dielectric constant	1.505	[26]
Radiation length [cm]	14.0	[27]
Molière radius [cm]	10.0	[27]
W-value for ionization [eV/pair]	23.6	[28, 29]
Minimum specific energy loss [MeV/cm]	2.12	[27]
Electron transverse diffusion coef. [cm ² /s]	13	[30, 31, 5]
Electron longitudinal diffusion coef. [cm ² /s]	5	[5, 32]

13 The successful implementation of the LArTPC technique depends critically on several factors.
 14 The liquid argon must be purified of any electronegative contaminants, such as water or oxygen, to
 15 accommodate the very long drift path of ionization through a MicroBooNE-sized LArTPC without
 16 significant charge loss. The signals that the ionization electrons create on the anode wires are very
 17 small, requiring low-noise electronics to discern signal pulses. The MicroBooNE collaboration
 18 has designed and constructed an experiment that addresses all of these considerations, providing
 19 critical technological development for the next generation of LArTPC experiments to build upon.

20 2.2 MicroBooNE LArTPC Implementation

21 MicroBooNE’s LArTPC active volume, which is defined as the volume immediately within the
 22 confines of the LArTPC field cage, is a rectangular liquid argon volume with dimensions 2.3 m
 23 vertical x 2.6 m horizontal x 10.4 m along the beam direction. This is the maximum volume that
 24 can be used for physics analyses. The cathode (anode) defines the beam-left (beam-right) side of
 25 the active volume. The end of the LArTPC that the beam first encounters is referred to as the
 26 “upstream” end, while the opposite end is referred to as “downstream.” Anode plane-to-plane
 27 spacing is 3 mm, and each plane has 3 mm wire pitch. The induction plane wires are oriented at

¹ $\pm 60^\circ$ relative to vertical, and the collection plane has vertically oriented wires. Field cage loops
² are employed to maintain uniformity of the electric field across the entire width of the detector,
³ and these loops also act to define the top, bottom, upstream, and downstream sides of the active
⁴ volume.

⁵ MicroBooNE uses a right-handed Cartesian coordinate system, with the origin defined to be
⁶ located on the upstream face of the LArTPC, centered halfway up the vertical height of the active
⁷ volume and horizontally centered on the anode plane closest to the cathode (the innermost anode
⁸ plane). In this system, x ranges from 0.0 m at the innermost anode plane to +2.6 m at the cathode,
⁹ y ranges from -1.15 m on the bottom of the active volume to +1.15 m at the top of the active
¹⁰ volume, and z ranges from 0.0 m at the upstream end of the active volume to +10.4 m at the
¹¹ downstream end.

¹² The light collection system, which is an array of photomultiplier tubes (PMTs) and lightguide
¹³ paddles, is located directly behind the anode planes on beam-right, facing the detector volume
¹⁴ through the anode planes. The LArTPC and light collection system are immersed in liquid argon
¹⁵ contained within a single-walled cryostat with a 170 ton capacity. Electronics mounted directly
¹⁶ on the LArTPC amplify the signals on the wires, which are then passed out of the cryostat for
¹⁷ further processing and storage on disk. Table 2 lists the primary detector design parameters of
¹⁸ MicroBooNE, and figure 3 shows a schematic of the cross section of the detector. Details of these
¹⁹ design parameters and construction of all detector subsystems will be provided in the subsequent
²⁰ sections.

Table 2: Primary detector design parameters for MicroBooNE.

Parameter	Value
LArTPC Dimensions	2.325 m vertically
	2.560 m horizontally
	10.368 m longitudinally
LArTPC argon mass	90 tons
Total Number of Wires	8256
Drift field	500 V/cm
Light collection	30 200 mm (8 in) diameter PMTs 4 lightguide paddles
Cryostat liquid argon capacity	170 tons
Operating temperature	87 K
Operating pressure	0.14 bar

²¹ 3. Cryogenic System

²² The use of large quantities of highly-purified liquid argon as a detector medium in MicroBooNE
²³ requires a sophisticated cryogenic infrastructure that can maintain stable operations for years at a
²⁴ time. Not only must the purity of the liquid argon be maintained, but the pressure and temperature
²⁵ gradients within the LArTPC active volume must be tightly controlled as the drift velocity of elec-

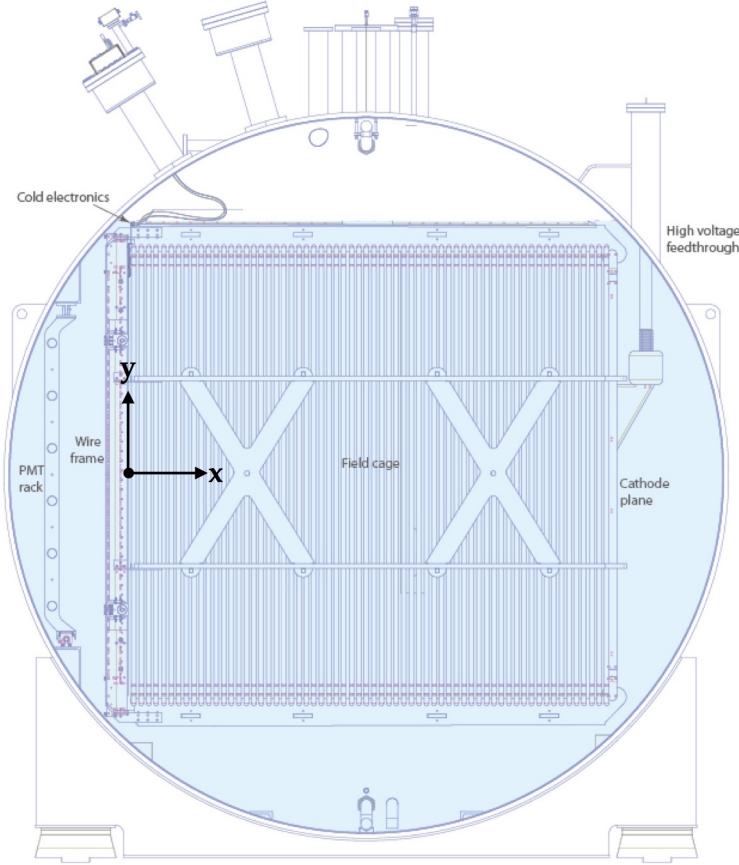


Figure 3: Schematic of the cross section of the MicroBooNE LArTPC. In this view, the beam would be directed out of the page (in the z direction).

trons is dependent on these quantities. A customized cryogenic system that serves these purposes has been built, and the requirements for this system are shown in table 3.

Table 3: Primary design requirements for MicroBooNE cryogenic and purification systems.

Parameter	Value	Motivation
Argon purity	<100 ppt O ₂	MIP identification at longest drift
Argon purity	<2 ppm N ₂	Scintillation light output
LAr Temperature gradient	<0.1 K	Drift-velocity uniformity
LAr recirculation rate	1 volume change/day	Maintain purity
Cryostat heat load	<15 W/m ²	Minimize convection currents and bubbles
Cryogenic capacity	10 kW	Capacity to deal with expected heat load
Cryostat maximum pressure	2.1 bar	Determines relief sizing

The MicroBooNE cryogenic system is represented in figure 4. The central component of the system is a cryostat that houses the complete LArTPC and light-collection detector systems. The cryostat is supported by three major subsystems: the argon purification system, the nitrogen re-

1 refrigeration system, and the controls and monitoring system. These systems each represent the next
2 generation of LArTPC cryogenic system after the Liquid Argon Purity Demonstrator (LAPD) [33]
3 and make considerable use of the expertise gained during the design and implementation of that
4 apparatus.

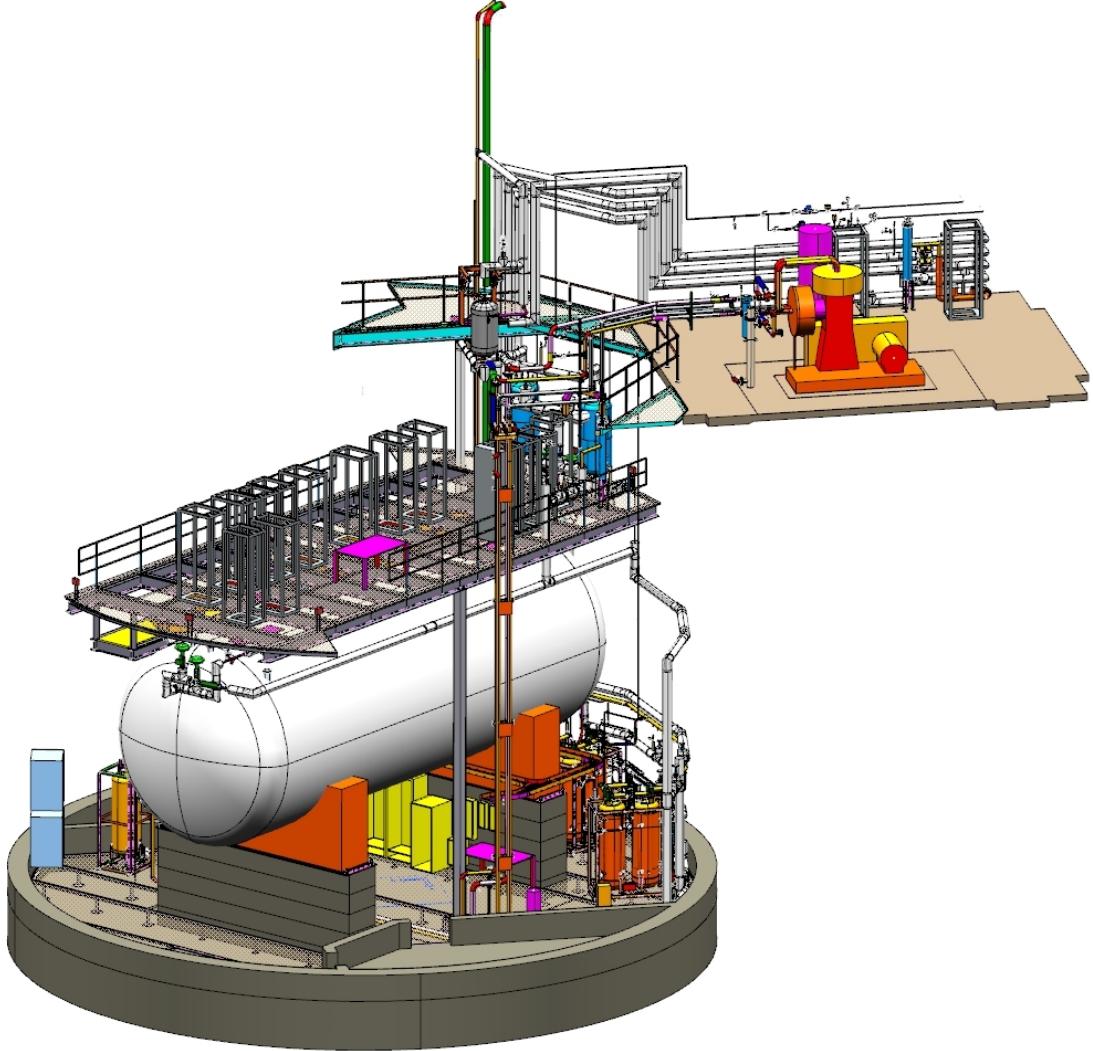


Figure 4: Three-dimensional renderings of the MicroBooNE cryogenic system installed at LArTF.

5 **3.1 Cryostat Design Overview**

6 Three major components make up the MicroBooNE cryostat: a type 304 stainless steel vessel to
7 contain the liquid argon and all the active detector elements, front and rear supports to carry the
8 weight of the fully loaded cryostat, and foam insulation covering the cryostat outer surfaces. The
9 foam insulation serves to reduce heat input from the ambient environment to a sufficiently low
10 level to prevent large temperature gradients and boiling of the liquid argon. The cryostat and the
11 cryogenic systems are designed to achieve the high-purity liquid argon needed to allow ionization
12 electrons to drift to the anode wires with low probability of capture, and the high degree of thermal

1 homogeneity needed to avoid the introduction of non-constant drift velocities for the ionization
2 electrons. Finally, the outer diameter of the vessel is designed to be the maximum standard size for
3 over-the-road transport.

4 Ionization electrons must not be significantly attenuated, via attachment to electronegative
5 contaminants in the liquid argon, as they drift up to 2.5 m across the active volume. This dictates
6 that the argon be kept free of electronegative contaminants to the level of 100 parts-per-trillion
7 (ppt). The cryostat is designed to minimize outgassing (desorption) and to avoid leakage and
8 diffusion of air into the system. This requirement imposes strict quality assurance demands on all
9 welds for penetrations into the cryostat and on cleaning and handling procedures for the finished
10 vessel. Achieving the required level of purity is accomplished with a purification system, described
11 in section 3.2, that removes electronegative contaminants from the argon during the initial fill and
12 those introduced over time by leaks and outgassing of system components.

13 The electron drift velocity ($v_d = 1600$ m/s at an electric field of 500 V/cm, with a liquid argon
14 temperature dependence $\Delta v_d/v_d = -0.019\Delta T$) must remain constant in magnitude and direction
15 throughout the active liquid argon volume to avoid distortion of the mapping of drift time into the
16 position along the drift (\hat{x}) direction. This requirement limits the allowable temperature variations
17 of the liquid argon to less than 0.1 K and the laminar and turbulent flow rate of liquid argon to
18 less than 1 m/s. These requirements limit fractional errors in velocity, and therefore in the drift-
19 coordinate determination, to be less than 0.1%. The constraints on constancy of drift velocity affect
20 the design by imposing limits on the acceptable heat flux through the insulation.

21 The cryostat is constructed to the latest American Society of Mechanical Engineers (ASME)
22 boiler code requirements [34] and features a single-walled construction, cylindrical shape, and
23 domed caps closing each end, as shown in figure 5. One end was removed for installation of the
24 active detectors, welded back in place upon completion of that task, and then recertified to the
25 ASME code requirements. Upon installation of the sealed cryostat in its final location at the Liquid
26 Argon Test Facility (LArTF), 41 cm of spray-on, closed cell, Polyurethane insulation was applied
27 to the exterior of the cryostat, as shown in figure 6. At LArTF, to avoid ground loops that could
28 interfere with the LArTPC signals, the cryostat vessel is grounded in only one place, allowing it to
29 act as a Faraday cage. This grounding scheme is explained further in section 7.1.

30 The vessel surface has 34 nozzle penetrations for cryogenic and electrical services, detailed in
31 table 4. All nozzles are sealed with feedthroughs, flanges, or pipes that are suitable for operation at
32 the nominal pressure and temperature of the cryostat.

33 **3.2 Liquid Argon Purification Subsystem**

34 The heart of the cryogenic system is the liquid argon purification subsystem. The primary require-
35 ment of this subsystem is to keep the level of electronegative contamination to below 100 ppt of
36 oxygen-equivalent contaminants. This requirement was determined by the physics needs of the
37 experiment, namely the need to keep the attenuation of ionization electrons to less than 20% over
38 the longest drift distance in the LArTPC. In addition to the requirement on the electronegative con-
39 tamination, the system must maintain the level of nitrogen contamination in the argon at less than
40 2 parts per million (ppm) [35] to keep the attenuation of the scintillation photons in the argon to a
41 minimum.

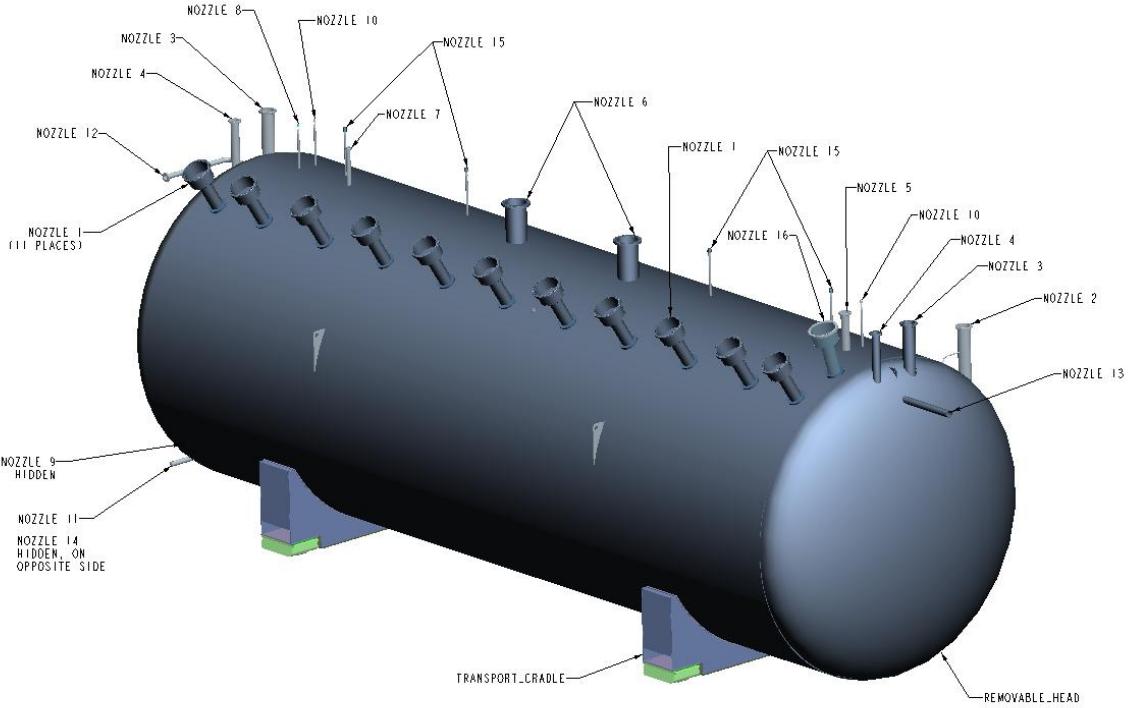


Figure 5: MicroBooNE cryostat with nozzle penetrations labeled.

1 The MicroBooNE argon purification subsystem consists of liquid argon pumps and filters that
 2 serve to circulate the argon and remove impurities that degrade the quality of the data collected by
 3 the active detectors. There are two pumps in the system arranged in parallel in order to allow for
 4 continuous recirculation while one pump is being serviced. Similarly, there are two sets of filters
 5 arranged in parallel in the system. Figure 7 schematically depicts the flow of liquid and gaseous
 6 argon in the MicroBooNE cryogenic system.

7 The recirculation pumps are Barber-Nichols [36] BNCP-32B-000 magnetically-driven partial-
 8 emission centrifugal pumps. Each pump isolates the liquid argon from the electric motor. The
 9 impeller, inducer, and driving section of the magnetic coupling each have their own bearings that
 10 are lubricated by the liquid argon at the impeller. The motor is controlled by a variable frequency
 11 drive (VFD) that allows adjustment of the pump speed to produce the desired head pressure and
 12 flow within the available power range of the motor.

13 Each filter skid contains two filters, each having identically-sized filtration beds of 77 liters.
 14 The first filter that the argon stream enters contains a 4A molecular sieve supplied by Sigma-
 15 Aldrich [37] that primarily removes water contamination but can also remove small amounts of
 16 nitrogen and oxygen. The second filter contains BASF CU-0226 S, a highly-dispersed copper ox-
 17 ide impregnated on a high-surface-area alumina, which removes oxygen [38] and, to a lesser extent,
 18 water. Thus, the oxygen filter is placed downstream of the molecular sieve to maximize oxygen fil-
 19 tration. The oxygen-filtering media must be reduced to copper with the procedure described below
 20 before it can remove oxygen from the liquid argon. The filters are insulated with vacuum jackets
 21 and aluminum radiation shields. The metallic radiation shields were chosen because the filter re-

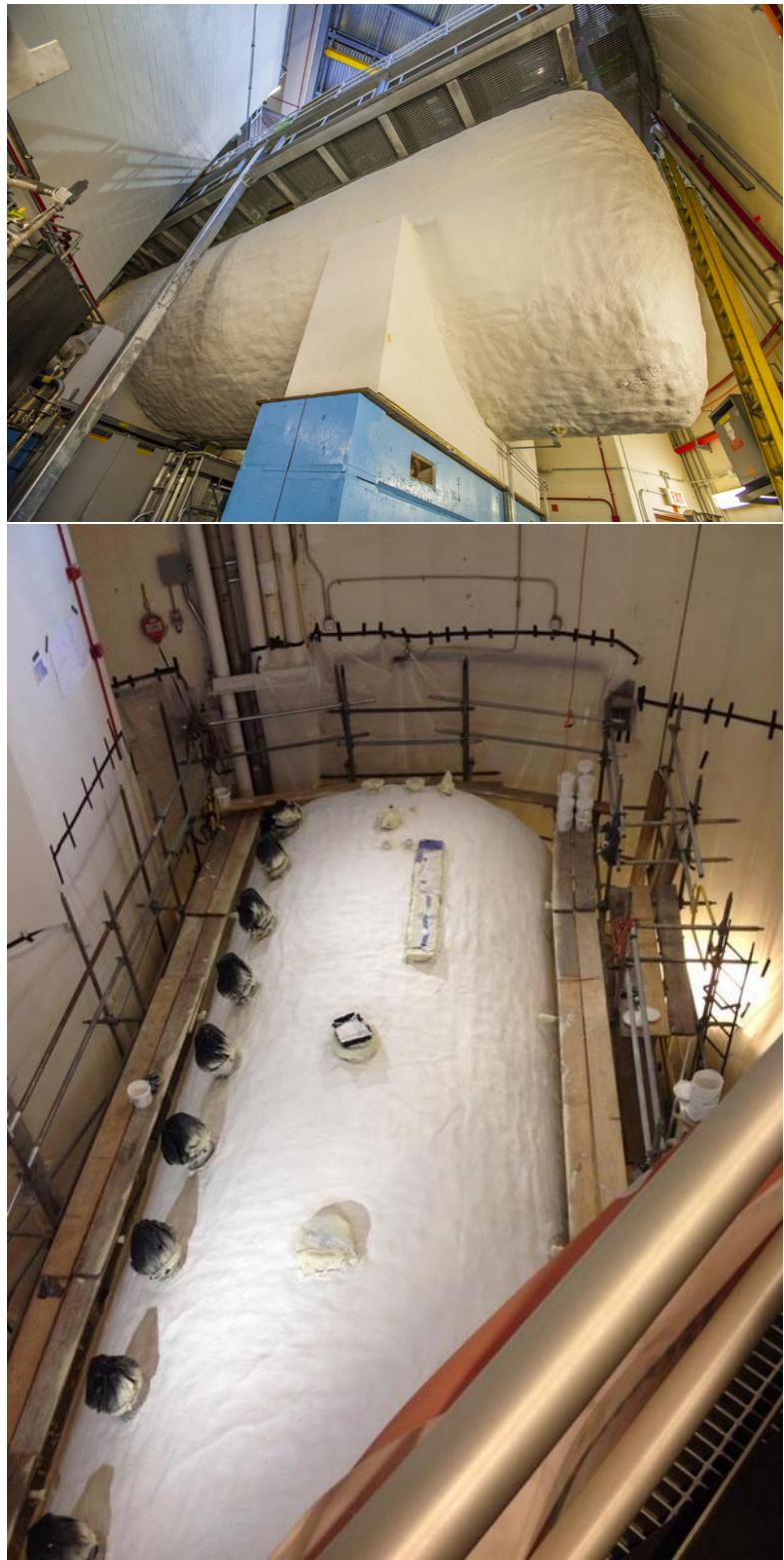


Figure 6: Photographs of the cryostat after application of exterior foam insulation.

Table 4: List of nozzle penetrations in MicroBooNE cryostat, their function, and their flange/pipe type and outer-diameter dimension. CF=ConFlat flanges, RFWN=raised face weld neck flanges, SS = stainless steel pipe.

Nozzle ID	Function	Flange
N1A-N1K	LArTPC Signal Feedthrough	356 mm CF
N2	LArTPC HV Feedthrough	203 mm CF
N3A-N3B	Purity Monitor	203 mm CF
N4	Temperature Signals	152 mm CF
N5	Safety Vent	102 mm RFWN
N6A-N6B	Vacuum Pump-Out	254 mm RFWN
N7	Condensor	76 mm SS
N8	Top Instrument Port	19 mm SS
N9	Bottom Instrument Port	19 mm SS
N10A-N10B	Liquid Level Probe	19 mm SS
N11	Gas Circulation In	51 mm SS
N12	Gas Circulation Out	51 mm SS
N13	From LAr Filters	76 mm SS
N14	To LAr Pumps	51 mm SS
N15A-N15B	Laser Calibration	70 mm CF
N16	PMT Signal Feedthrough	356 mm CF
N17	Spare	152 mm CF
N18	Temperature Signals	152 mm CF
N19	Spare	152 mm CF

¹ generation temperatures, described below, would damage traditional aluminized mylar insulation.
² Pipe supplying the filter regeneration gas is insulated both inside the filter vacuum-insulation space
³ and outside the filter with Pyrogel XT which is an aerogel-based insulation [39] that can withstand
⁴ temperatures up to 920 K.

⁵ The filters are regenerated *in situ* using heated gas, by a procedure developed for LAPD. The
⁶ filters are regenerated using a flow of argon gas that is heated to 473 K, supplied by a commercial
⁷ 500 liter liquid argon dewar. Once the argon gas reaches 473 K, a small flow of hydrogen is mixed
⁸ into the primary argon flow and exothermically combines with oxygen captured by the filter to
⁹ create water. Too much hydrogen mixed in with the primary argon flow would induce temperatures
¹⁰ that are sufficiently high to damage the copper-based filter media. The damage is induced by
¹¹ sintering of the copper, which reduces the available filter surface area. Thus, precautions are taken
¹² to maintain a hydrogen fraction below 2.5% of the heated gas mixture. During the heated gas
¹³ regeneration, five filter-bed temperature sensors monitor the filter-material temperature and the
¹⁴ water content of the regeneration exhaust gas is measured. To remove any remaining trace amounts
¹⁵ of water, the filters are then evacuated using turbomolecular vacuum pumps while they cool.

¹⁶ A particulate filter with an effective filtration of 10 microns, positioned between the cryostat
¹⁷ and the filter skids, prevents any debris in the piping from being introduced into the cryostat.
¹⁸ The particulate filter consists of a commercial stainless steel sintered-metal cylinder mounted in a

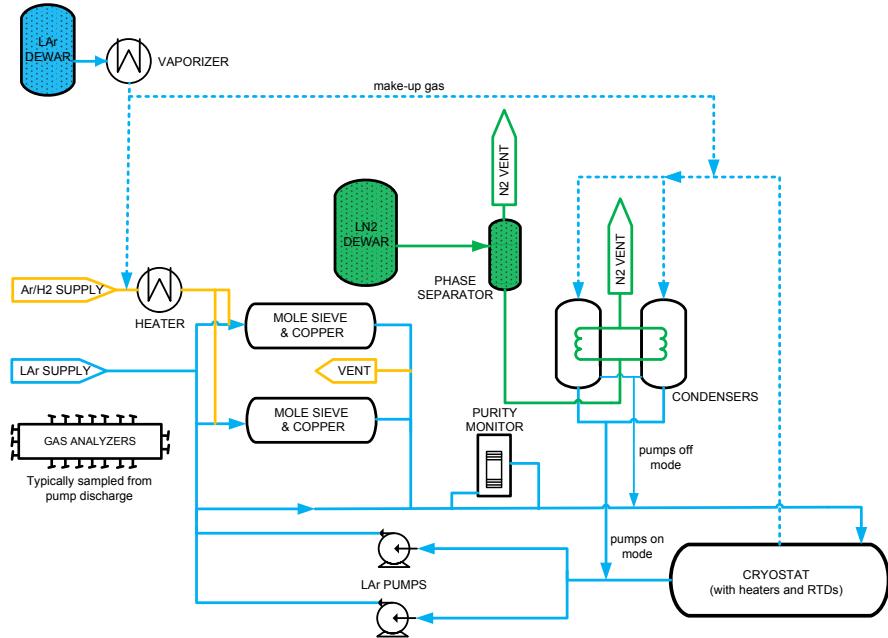


Figure 7: Flow diagram of argon in MicroBooNE, showing direction of liquid and gaseous argon in the cryogenic system. Gaseous argon from the cryostat is condensed and directed through the purification subsystem. Liquid argon drawn from the cryostat volume is directed into the purification subsystem.

1 custom cryogenic housing and vacuum jacket. Filtration is accomplished by flowing liquid argon
 2 to the interior, then outward through the walls, of the sintered-metal cylinder. Flanges on the argon
 3 piping, along with flanges and edge-welded bellows on the vacuum jacket, allow removal of the
 4 particulate filter.

5 The argon-purification piping is 2.54 cm diameter stainless steel that was pre-insulated by the
 6 manufacturer with 10.2 cm of polyurethane foam. During the fabrication process, all piping was
 7 washed with distilled water and detergent to remove oil and grease, then cleaned with ethanol.
 8 All valves associated with the argon-purification piping utilize a metal seal with respect to am-
 9 bient air, either through a bellows or a diaphragm, to prevent the diffusion of oxygen and water
 10 contamination. The exhaust side of each relief valve is continuously purged with argon gas to
 11 prevent diffusion of oxygen and water from ambient air across the o-ring seal. Where possible,
 12 ConFlat flanges with copper seals are used on both cryogenic and room-temperature argon piping.
 13 Pipe flanges in the system are sealed using spiral-wound graphite gaskets. Smaller connections are
 14 made with VCR fittings with stainless steel gaskets.

15 **3.3 Nitrogen Refrigeration**

16 The cryostat and purification systems that contain the liquid argon are subject to heat load from
 17 the environment, as well as from the active detectors that have electrical power enabled. To keep

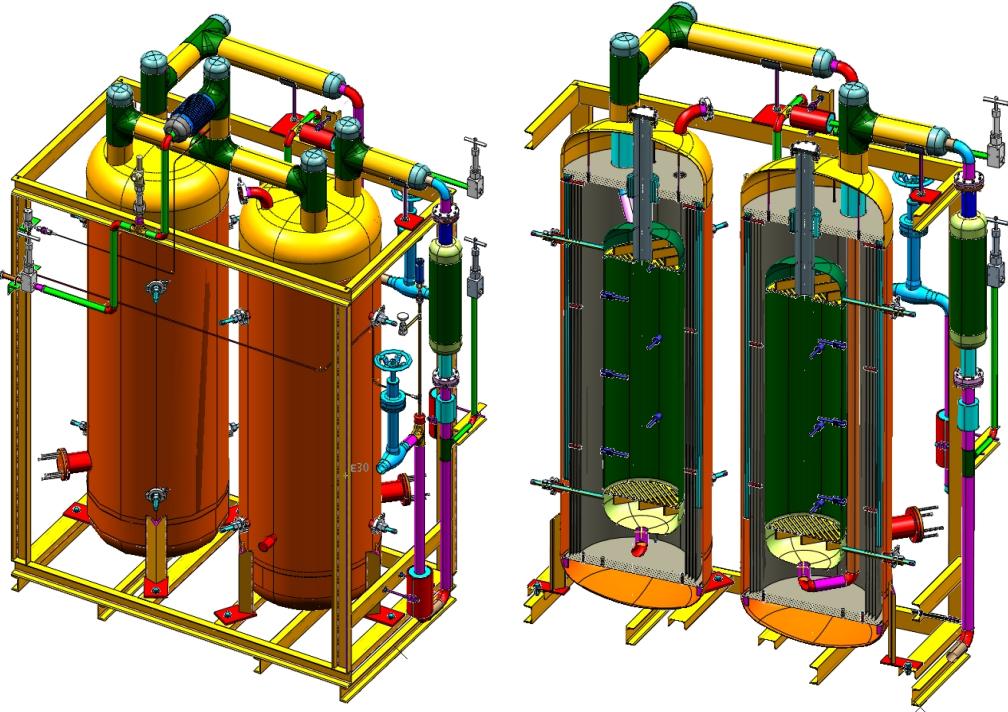


Figure 8: Three-dimensional rendering of a MicroBooNE filter skid. The left drawing shows the full skid, while the right drawing shows a cut-away of the vessels.

these systems operating at a stable temperature and pressure, a liquid nitrogen refrigeration system is present to provide the necessary cooling power. The liquid nitrogen system contains two condensers that are arranged in parallel. One of these is utilized for normal operations and one serves as a backup on standby. Each condenser contains two liquid nitrogen coils, an inner and an outer, with the gas argon on the shell side, as shown in figure 9. Typically only one coil is actively running and the second can be manually activated during situations where the system heat load is higher than usual. Each condenser is sized to handle a heat load of approximately 9.5 kW. With the vessel full of liquid argon and no pump or liquid argon circulation running, the condenser uses ~ 2350 liters of liquid nitrogen per day, which equates to a 3.9 kW system heat load. Once liquid argon begins circulating using the pumps, this usage rate will increase by 50-100%.

3.4 Controls and Purity Monitoring

MicroBooNE makes use of resistive thermal devices (RTDs) to measure temperatures throughout the experimental infrastructure. Twelve RTDs are located along the walls of the cryostat, and another ten RTDs are mounted inside screws attached to the structure of the LArTPC. Each of the filter vessels in the purification system contain nine RTDs. The RTDs within the filter vessels prevent overheating which could potentially occur during filter regeneration with heated argon-hydrogen gas.

Liquid argon contaminations ranging between 300 and 50 ppt oxygen equivalent can be measured using double-gridded ion chambers, henceforth referred to as purity monitors, immersed in liquid argon. The design of the purity monitors is based on the design presented by Carugno et

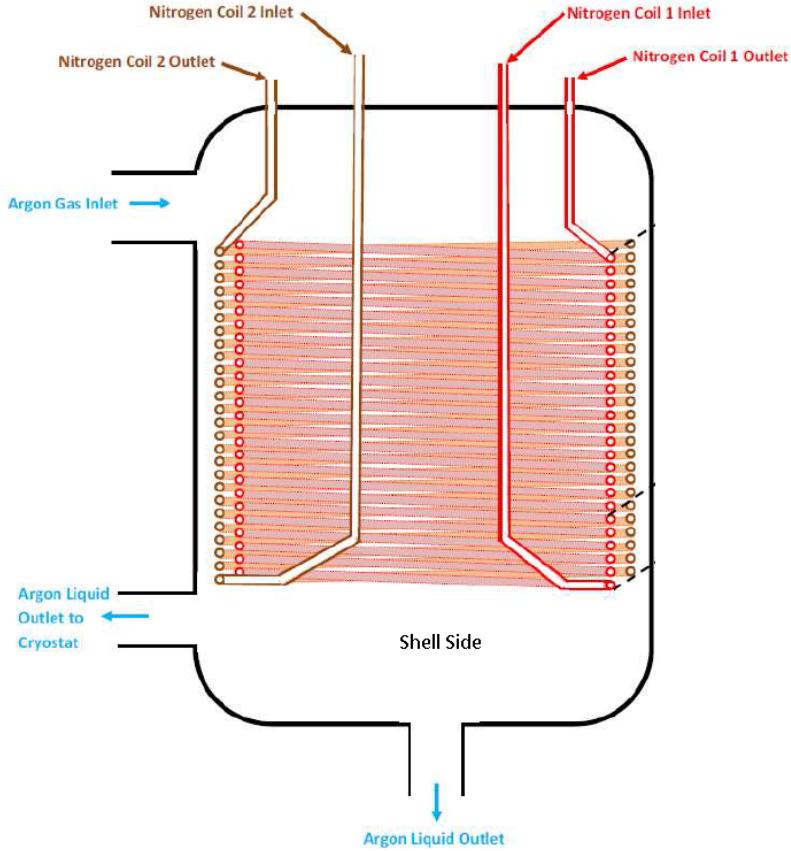


Figure 9: Diagram of a condenser.

1 al. [40]. A thorough description of the purity monitors, the data-acquisition hardware and software
2 used in LAPD can be found in [33]. MicroBooNE uses the same type of purity monitors, and the
3 same data-acquisition hardware and software.

4 A measure of the electronegative impurities is made with the purity monitor by examining the
5 fraction of electrons generated at the purity monitor cathode that subsequently arrive at the purity
6 monitor anode (Q_A/Q_C) after a drift time t . The ratio of (Q_A/Q_C) is related to electron lifetime, τ ,
7 such that

$$Q_A/Q_C = e^{-t/\tau}. \quad (3.1)$$

8 Measurement of liquid argon purity in the MicroBooNE cryogenic system are provided by
9 three purity monitors of varying lengths. One purity monitor with a drift distance of 50 cm sits
10 in a vessel just downstream of the filters and is used to monitor filter effectiveness. Two purity
11 monitors, one with a drift distance of 19 cm and the other with a drift distance of 50 cm, sit within
12 the primary MicroBooNE vessel at each end of the LArTPC.

4. Liquid Argon Time Projection Chamber

The MicroBooNE LArTPC drifts and collects charge to produce fine-grained images of the ionization that is liberated by charged particles traversing a volume of highly-purified liquid argon. This section describes the design and implementation of the LArTPC in the experiment.

The LArTPC is composed of three major structures: the cathode, the field cage, and the anode. A negative voltage is introduced via a feedthrough passing through nozzle N2 on the cryostat and applied at the cathode, which defines an equipotential surface. This cathode voltage is incrementally stepped down in magnitude by means of a voltage divider chain spanning the field cage, creating a region of uniform electric field within the LArTPC. Opposite the cathode, and oriented parallel to it, are the anode wire planes: two induction planes (referred to as the “U” and “V” planes) with wires oriented at $\pm 60^\circ$ from vertical, followed by one collection plane (referred to as the “Y” plane) with vertically-oriented wires. The wires of the anode planes are the sensitive elements that detect the ionization created by charged particles traveling through the LArTPC. Figure 10 depicts the assembled MicroBooNE LArTPC after insertion into the cryostat, showing details of the cathode, field cage, and anode plane. Table 5 lists the main parameters of the MicroBooNE LArTPC, which will be described in detail in this section.

Table 5: MicroBooNE LArTPC design parameters and nominal operating conditions.

Parameter	Value
LArTPC (active) dimensions ($h \times w \times l$)	2.325 m \times 2.560 m \times 10.368 m
LArTPC (active) mass	90 tons
# Anode planes	3
Anode planes spacing	3 mm
Wire pitch	3 mm
Wire type	SS, diam. 150 μm
Wire coating	2 μm Cu, 0.1 μm Ag
# wires (total)	8256
# Induction0 plane (U) wires	2400
# Induction1 plane (V) wires	2400
# Collection plane (Y) wires	3456
Wire orientation (w.r.t. vertical)	+60 $^\circ$, -60 $^\circ$, 0 $^\circ$ (U,V,Y)
Cathode voltage (nominal)	-128 kV
Bias voltages (U,V,Y)	-200 V, 0 V, +440 V
Drift-field	500 V/cm
Max. Drift Time, Cathode to U (at 500 V/cm)	1.6 ms
# Field-cage steps	64
Ring-to-ring voltage step	2.0 kV

4.1 Cathode

The cathode is assembled from 9 individual stainless steel sheets (Type 304, 2.3 mm thick) that are fastened to a supporting frame by hex button head stainless steel screws. The outer edge of

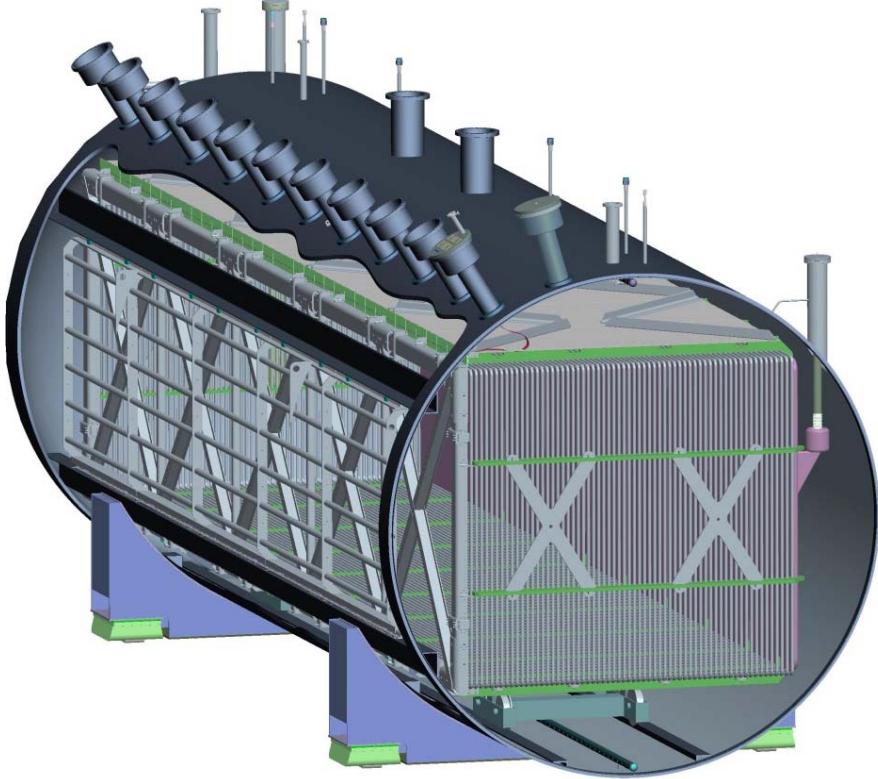


Figure 10: Schematic diagram of the MicroBooNE LArTPC , depicted as it is arranged inside the cryostat.

the cathode frame consists of round stainless steel tubes of 5.08 cm outer diameter and 3.18 mm wall thickness. Within this outer edge, square tubes with 5.08 cm \times 5.08 cm cross-sectional area, and 3.18 mm wall thickness, are fastened together with button head screws, forming a support structure upon which the cathode sheets are attached. The individual components of the support structure are further welded together to eliminate sharp features from this high-potential surface. The exterior frame and support structure of the cathode, and also an interior view, are shown in figure 11. The cathode plane sheets are shimmed according to survey data to make the cathode as flat and as parallel to the anode frame as possible. Flatness of the cathode is evaluated relative to a best fit plane of survey data (more than 10000 survey points recorded with a laser tracker). The largest deviations of the cathode from the best fit plane are +6.6 mm and -6.5 mm. Approximately 55% of the measured survey points fall within +/- 3 mm of the best fit plane, and more than 90% of the points fall within ± 5 mm. Figure 12 shows the results of the survey, with deviations from flat represented as color-coded data extending away from the nominal plane of an ideal cathode.

4.2 Field Cage

The field cage encloses the volume between the cathode plane and the anode wire planes, and in doing so creates a region with a uniform electric field. The volume defined by the interior of the field cage, bounded by the anode and cathode planes, is referred to as the “active” volume. The field cage structure consists of 64 individual thin-walled stainless steel tubes (2.54 cm OD, 0.51



Figure 11: Top: Exterior view showing the cathode frame and structural supports to which cathode sheets are fastened. Bottom: Interior view of cathode plane as viewed from the upstream end of the LArTPC , showing cathode sheets.

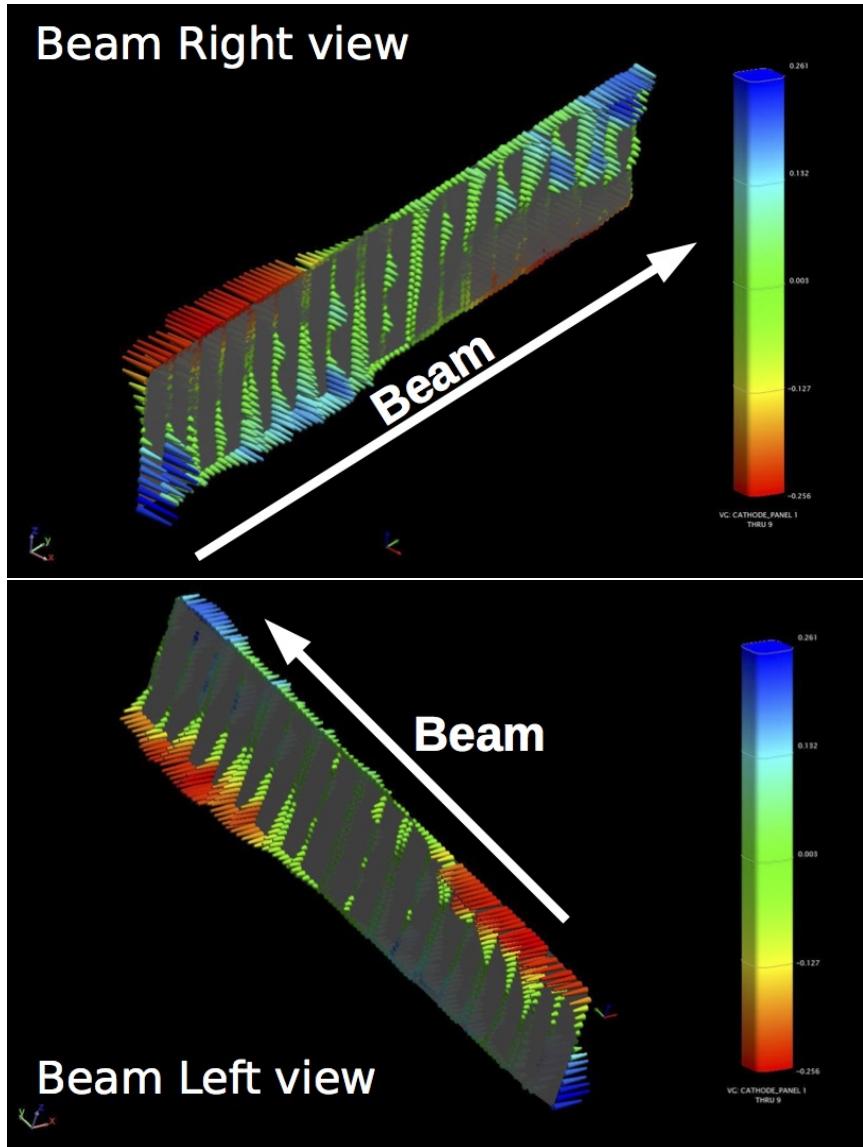


Figure 12: Survey results for interior (top) and exterior (bottom) of the cathode after shimming. Color scale extends from -0.256 cm (red) to +0.261 cm (blue).

1 mm wall thickness), each shaped into a rectangular loop framing the perimeter of the active volume.
 2 These 64 loops are mounted parallel to the cathode and anode planes, as shown in figure 11, and
 3 are held in place by a G-10 rib support structure. Each field cage loop is electrically connected
 4 to its neighbors via a resistor divider chain (described in following section), causing each loop to
 5 operate at a different electrical potential which in turn maintains a uniform electric field between
 6 the cathode and anode planes. For a nominal -128 kV cathode voltage, the difference in potential
 7 between adjacent field cage loops is 2 kV, ramping down the total potential in equidistant steps
 8 from cathode to anode. The distance from center-to-center of adjacent field cage loops is 4.0 cm.
 9 Each field cage loop is assembled from 2.07 m long vertical pipes on the upstream and down-
 10 stream ends of the LArTPC , and on the top and bottom from two 5.18 m long horizontal pipes

1 connected by a stainless steel coupling in the center. Each tube has venting holes approximately
2 every 15 cm so that they fill with liquid argon and allow air and gaseous argon to escape during
3 cryostat cool down and filling.

4 The four corners of each field cage loop are curved with a radius of 5.24 cm. Each corner is
5 formed by three parts: two couplings and an elbow, shown in figure 13. The couplings make the
6 connections between the pipes and the elbow. The thin-walled tubes and elbows slip-fit over the
7 ends of the couplings with a 2.2 cm overlap. Each coupling has two 6-32 NC tapped holes and the
8 connections to the adjoining pieces are made by hex head button screws and lock washers.

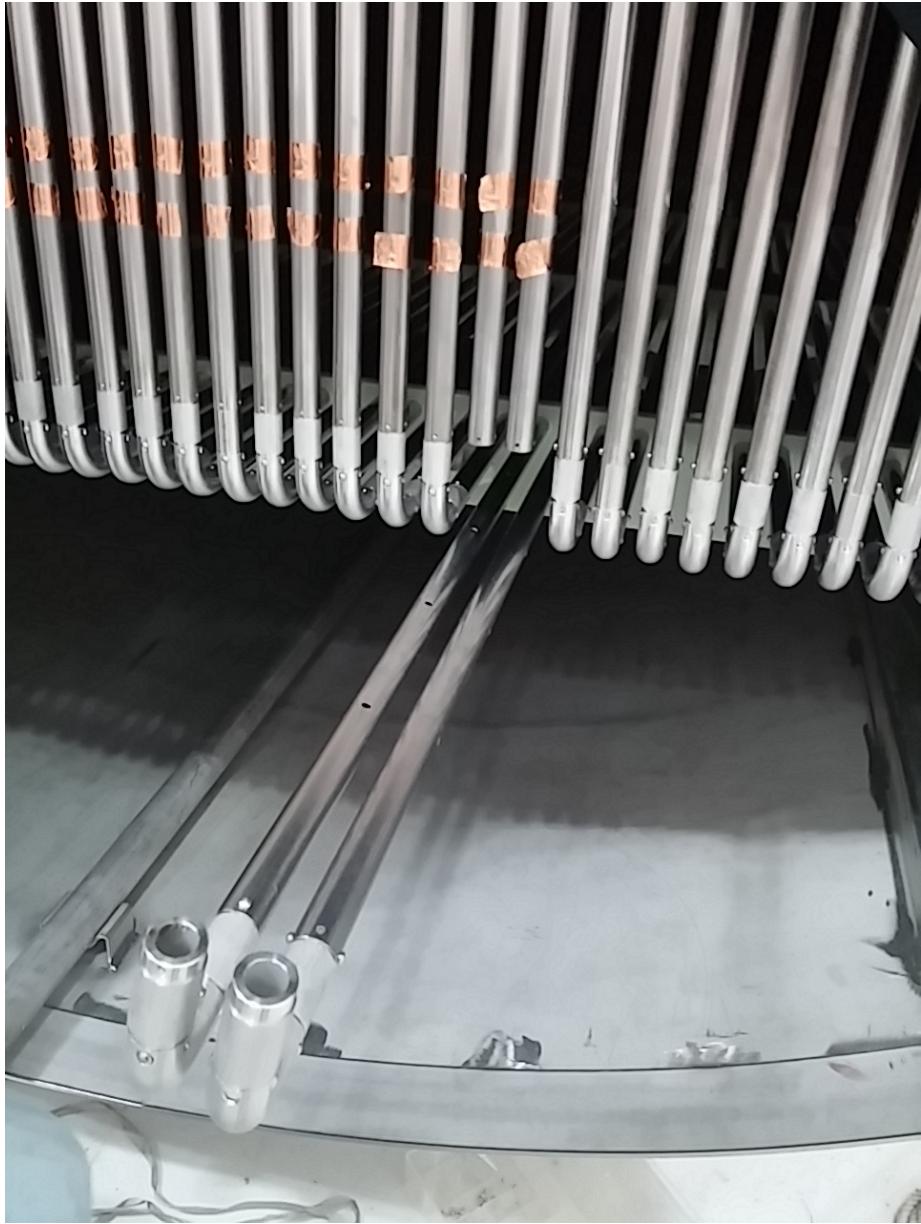


Figure 13: Field cage loops, with two partially disassembled to show elbow and couplings.

9 In order to avoid electrical breakdown between the inner cryostat surface and field cage parts

at high potential on or near the cathode, the electric field strength is minimized at the corners and edges of the field cage. Loops 0, 1, and 2 are each designed differently than the other field cage loops. Loop 0 is a special case in that it is made from larger diameter piping of 5.08 cm OD, and frames the cathode and also acts as its mechanical support. It operates at the same electrical potential as the cathode plane sheets attached to it. Loop 0 has a slightly smaller area than the other field cage loops, as shown in figure 14. Loop 1 is the first of the 64 loops in the field cage with 2.54 cm OD tube, and is the edge of the cathode, operating at the same electrical potential as loop 0. The elbow of loop 1 has a specially designed geometry in order to minimize the electric field potential. The elbow of loop 2 has a softer radius of curvature than the standard elbows, also for the purpose of minimizing the electric field potential. For all three of these loops (loop 0, 1, and 2), connections at corners and joints are made by welding instead of screws to avoid sharp edges that would result in higher electric fields and greater chance of electrical breakdown.

Another precaution to minimize the electrical field between the loops and the cryostat surface is the positioning of the coupling screws: for the first 20 loops, the screws are positioned on the sides facing the screws of the neighboring loops instead of facing inward to the LArTPC active volume and outward toward the grounded cryostat surface. Hex head button screws and lock washers are also used here in order to minimize sharp metal edges.

Figure 15 shows the simulated electric field values inside the MicroBooNE LArTPC , and some of the surrounding volume inside the cryostat, when the cathode is set to an operating voltage of -128 kV.

4.2.1 Resistor Divider Chain

A resistor divider chain installed across the field cage loops steps the voltage down in magnitude from the cathode plane to the anode wire plane in equidistant steps. For a nominal value of -128 kV on the cathode, this results in a potential difference of 2 kV between each pair of loops. The value of the equivalent resistance between loops within the divider chain was chosen to be low enough such that the current flow through the divider circuit is much greater than the signal current flowing through the LArTPC . The signal current in this case is the total energy deposited by cosmic rays, and is estimated to be <50 nA. An equivalent resistance of 250 M Ω between each pair of field cage loops, corresponding to a current flow of 8 μ A, was chosen.

The voltage divider chain is mounted on the inside of the field cage at the upstream end of the detector. The couplings at the top corner of each field cage loop have additional holes facing the inside of the field cage, where the resistors are mounted. On the first 16 field cage loops, pairs of Metallux HVR 969.23 499 M Ω resistors (rated to 23 W, 48 kV in air) are mounted electrically in parallel to establish the beginning of the voltage divider chain. On the remaining loops, thick-film Ohmite Slim-Mox 104E metal-oxide epoxy-coated resistors with a lower power and voltage rating (1.5 W, 10 kV in air) are used. Extensive testing was done on these two types of resistors [41]. For redundancy, the desired 250 M Ω total resistance between each pair of field cage loops is composed of four individual 1 G Ω Slim-Mox 104E resistors placed electrically in parallel and attached to a printed circuit board. Printed circuit boards span across eight field cage gaps and therefore have eight 250 M Ω resistances in series, shown in figure 16. The electrical connection between the boards and each field cage loop is made by metal contact pads on the back side of the boards, held in electrical contact with the field cage tube by a button-head hex screw and lock washer.



Figure 14: Field cage loops closest to (and including) the cathode are modified to reduce sharp edges that would result in higher electric fields.

1 While the designed operating voltage difference across each resistor in the detector is 2 kV
2 with a power flow of 4 mW, there is a slight possibility that these values could temporarily exceed
3 the rating of the resistors in the case of discharge between the cathode plane or field cage loops and
4 the cryostat wall, through the bulk liquid argon. Recent studies [42] have shown that the value of
5 the minimum breakdown electrical field decreases with the increasing argon purity; for purities as
6 high as that required in the MicroBooNE detector, breakdown has been observed at electric fields
7 as low as 40 kV/cm.

8 The field cage behaves like a capacitance network at high frequencies. Based on measurements

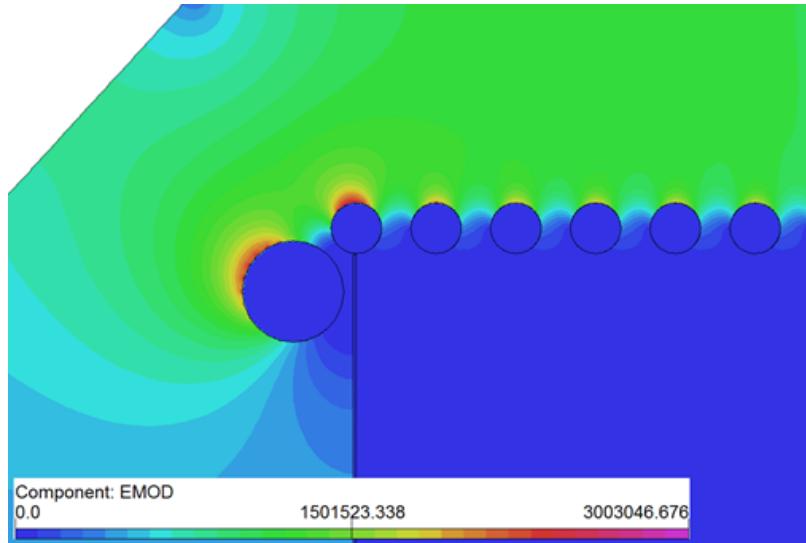


Figure 15: Cross-section view showing electric field simulation inside the field cage when the cathode is set to a voltage of -128 kV. Loop 0 is represented by the larger diameter circle on the left of the image. The legend shows the absolute values of electric field modulus in units of V/m.

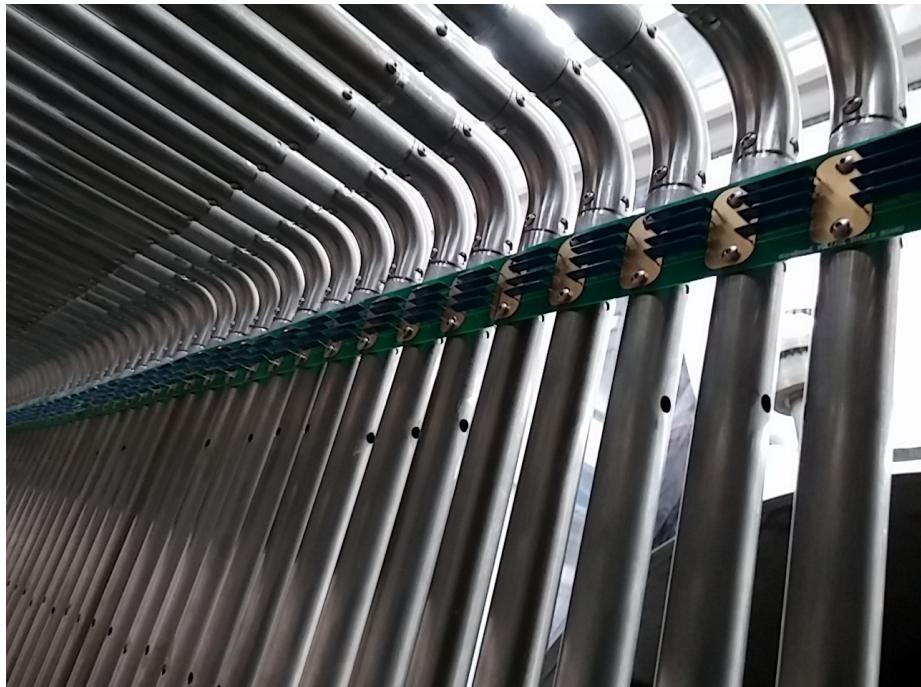


Figure 16: The Ohmite Slim-Mox 104E resistors arranged in parallel sets of four on printed circuit boards that span eight field cage tubes.

¹ and simulations, the total energy stored inside the field cage when fully charged is estimated to be approximately 24 J. In the case of a discharge between the cryostat and the cathode or one of the field cage loops close to the cathode, simulations show that voltages of up to 80 kV peak, with

1 a discharge time constant of a few seconds, can develop across the resistors. The observed peak
2 voltages in such discharge scenarios decrease the further the breakdown occurs from the cathode,
3 such that discharges occurring between the cryostat and field cage loops 32 through 63 do not
4 exceed the 10 kV rating of the resistors.

5 In order to protect the resistors near the cathode from damage which could potentially render
6 the field cage inoperable, two strategies have been implemented. First, due to the knowledge
7 obtained in the breakdown electrical field studies mentioned before, on the first 16 field cage loops
8 near the cathode the Ohmite Slim-Mox 104E resistors are replaced by 499 M Ω Metallux HVR
9 969.23 resistors that have a higher voltage rating of 48 kV. An extensive study of resistor breakdown
10 in liquid argon of several resistor brands and models [41] has revealed that the breakdown voltage
11 observed in liquid argon exceeds the rating in air substantially for all resistors. No breakdown
12 has been observed up to 32 kV for the Ohmite Slim-Mox 104E resistor. For the Metallux HVR
13 969.23 resistors, no breakdown has been observed up to the limit of the test apparatus of 130 kV.
14 Since the Metallux HVR 969.23 resistors are significantly larger physically than the loop-to-loop
15 distance, they are mounted diagonally between each pair of field cage loops. They are held by
16 copper brackets, which are attached to studs welded onto the field cage tubes, shown in figure 17.



Figure 17: The Metallux HVR 969.23 resistors mounted on the 16 field cage loops closest to the cathode.

17 The second type of protection installed for all resistors on field cage loops 1 through 32 is a
18 surge protection circuit. The chosen surge protection devices are designed to short the circuit in
19 the case of a voltage spike, which protects any other electrical components installed in parallel.
20 Below their clamping voltage, they exhibit a very high resistance and do not influence the circuit.
21 The behavior of Gas Discharge Tubes (GDTs) and varistors in liquid argon has been studied exten-

sively for application in the MicroBooNE field cage [43]. The surge protection device chosen is a Panasonic ERZ-V14D182 varistor with a clamping voltage of 1700 V. In order to obtain a very high resistance in normal operation and a clamping voltage above the 2 kV in normal operation mode, three of these devices are mounted in series across a block of four Slim-Mox 104E or two Metallux 969.23 resistors. These additional varistor boards make electrical contact with the field cage via brass mounting brackets that are fastened to the field cage with button head screws, as shown in figure 18.

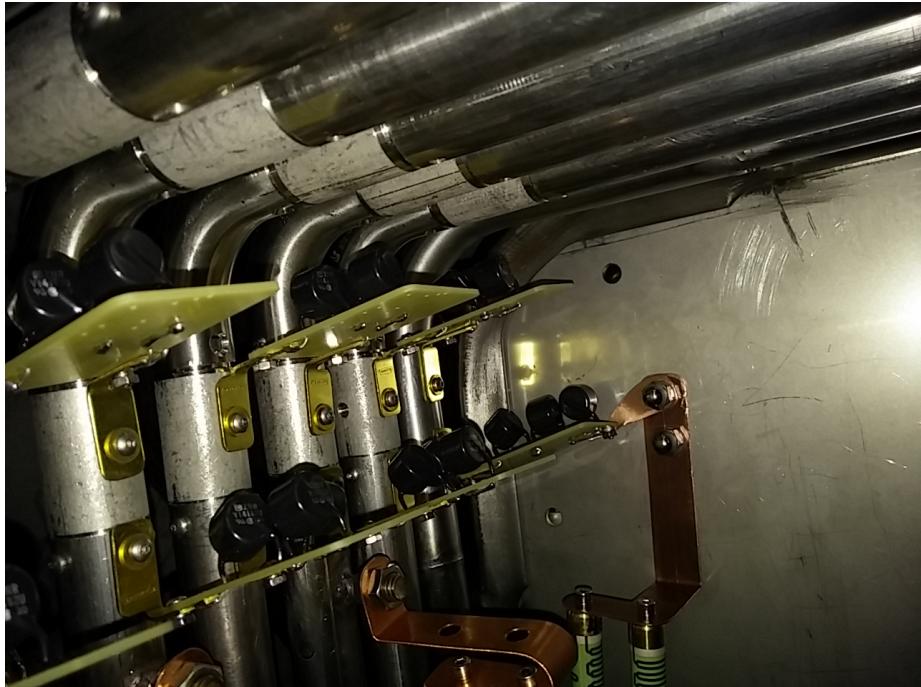


Figure 18: Surge-protecting varistors are installed in parallel with the voltage divider resistors for the first 32 field cage loops. Here, they are shown mounted on small boards in sets of 3, and attached to the field cage by means of 6-32 hex button head screws.

4.3 Anode

The anode frame holds the induction and collection plane sense wires at tension and provides overall structural support for the beam-right side of the LArTPC. Individual sense wires for all anode planes are held in place by wire carrier boards, which are printed circuit board assemblies that locate the wires as well as provide the electrical connection to the electronic readout system of the experiment.

4.3.1 Mechanical structure

The anode frame is comprised of a stainless steel C-channel hosting adjustable tensioning bars to which the wire carrier boards are attached. The C-channel and tensioning bar assembly is depicted for one corner of the anode frame in figure 19. Wire carrier boards attach to precision alignment pins distributed along the length of the tensioning bars.

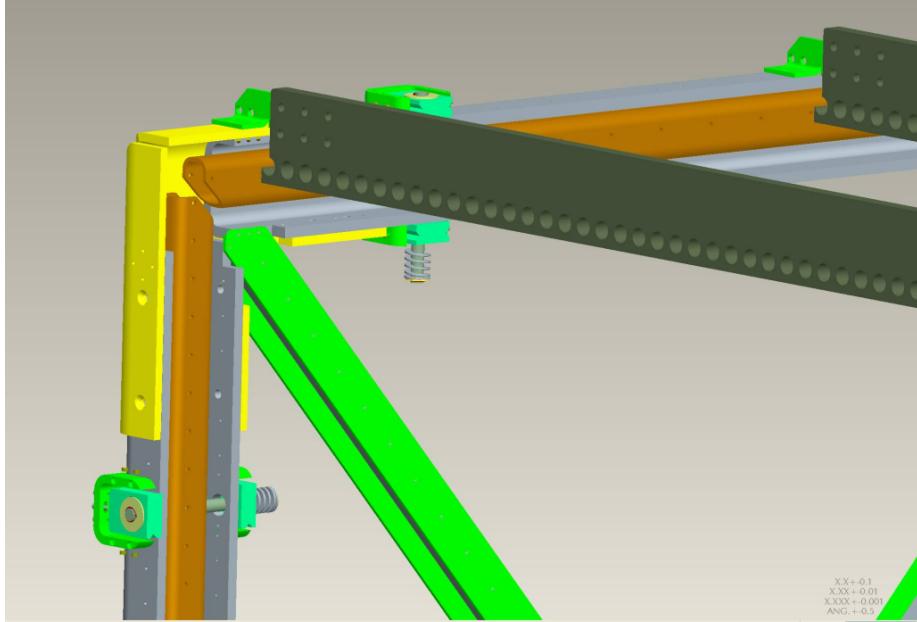


Figure 19: Rendering of the anode frame assembly. The C-channel is depicted in gray, and the adjustable tensioning bar assembly is shown in orange.

4.3.2 Wire winding and quality assurance

The three anode planes are constructed from wire carrier boards that have had individually-prepared wires attached to them in groups of 16 (for the U- and V- angled planes) or 32 (for the vertical Y-plane). Consistent quality in wire preparation was achieved by a semi-automated winding machine, which terminated the ends of each wire via wrapping around 3 mm diameter brass ferrules as shown in figure 20. Each wire was tested for strength by being placed on a tensioning stand where a load of 2.5 kg (more than 3 times the nominal load of 0.7 kg) was applied for 10 minutes, ensuring that the wire preparation did not leave any weaknesses that could result in a breakage later on. Upon successful completion of the quality assurance testing for each wire, it was placed onto a wire carrier board, shown in figure 21

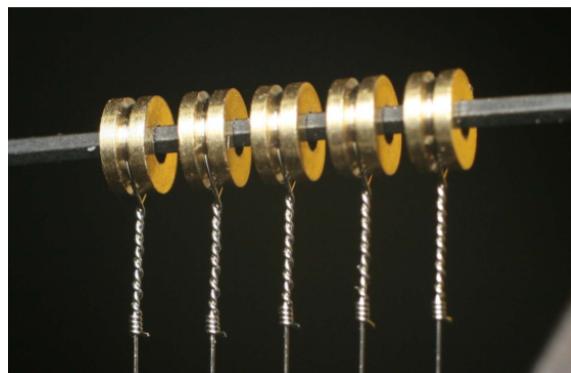


Figure 20: Photograph of the wire termination on the brass ferrules. Each ferrule is 3 mm in diameter, and 1.5 mm thick.

When installed, the wires make contact with gold pins positioned on the wire carrier board, and these pins are connected to a trace that routes to the cold electronics described in section 6.1. After fully filling a wire carrier board with wires, a cover plate was installed and press-fit rivets were installed to hold the assembly together. The assembled wire carrier board was then placed onto a tension stand, to reapply a 2.5 kg tension/wire to the whole board for 10 minutes. This is to ensure that the wires were not weakened during the board assembly process. The tension stand is depicted in figure 22. A comprehensive description of the MicroBooNE wire preparation and associated quality assurance studies can be found in [44].

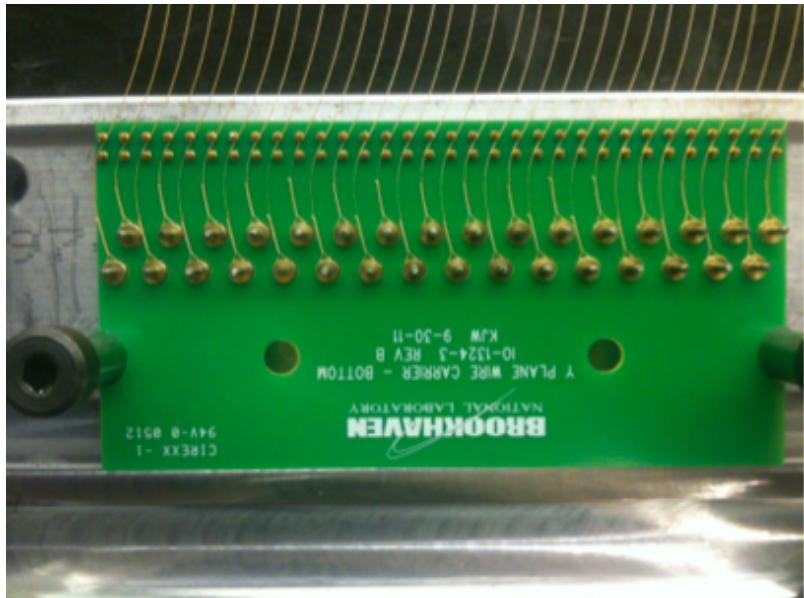


Figure 21: Photograph of a collection plane wire carrier board that has been filled with wires, but has not yet had the cover plate installed.

4.3.3 Wire installation and tension measurements

During detector construction the completed wire carrier assemblies were manually installed onto the adjustable tensioning bars residing in the C-channel of the supporting anode frame. A team of two people installed each assembly (consisting of wires and supporting carrier boards on either end) onto the anode frame. The collection plane was the first installed, followed by the middle induction plane, and then finally the inner induction plane. Once all three anode planes were completely installed, the tensioning bars were adjusted and a survey was taken of the tension of all anode wires. Tension was measured via measuring the resonant frequency of a laser beam reflected off of a plucked wire and incident on a photodiode connected to a spectrum analyzer program [45]. The tension measuring equipment was developed and produced by the University of Wisconsin Physical Sciences Laboratory. The tensioning bars were adjusted iteratively until the surveyed tension of all wires was within a range, approximately ± 1.0 N of the nominal value of 6.9 N, where no single wire was too taught or loose to create detector performance issues. Figure 23 shows the final surveyed tension of the wires within the LArTPC.



Figure 22: Photograph of a collection plane wire carrier board on the tension stand.

4.4 Parts Preparation

The majority of the parts that make up the LArTPC are either stainless steel or G-10. These two material types, as well as any others used in the LArTPC, were tested in the Fermilab Materials Test Stand (MTS) [46], whose purpose was to investigate the suitability of materials for use in LArTPCs. The MTS confirmed that none of the materials used in the LArTPC assembly would contaminate the liquid argon. Before assembly, all LArTPC parts were cleaned according to the procedures described in the following sections.

4.4.1 Cleaning stainless steel

The delivered stainless steel parts were often greasy due to machining, and those with holes or interior cavities generally had a significant amount of trapped metal shavings due to the machining processes. Many of the pieces also had markings from permanent ink pens, dirt smears, rust spots,

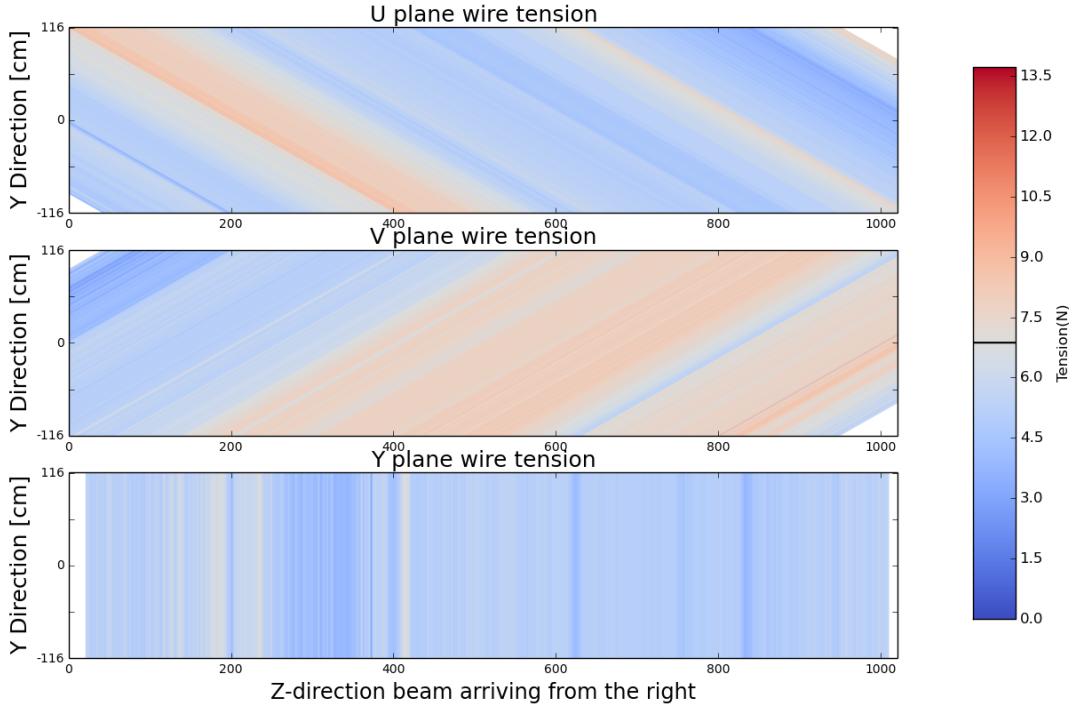


Figure 23: Final survey results for wire tension of the MicroBooNE LArTPC.

and/or dried oil from machining. These pieces were scrubbed with ScotchBrite 7447 general-purpose hand pads before cleaning.

Parts that were small enough to fit in an ultrasonic bath were prepared according to the following prescription. A pre-rinse with tap water was performed to remove particulate matter, followed by deburring of sharp edges. The first ultrasonic wash was 15 minutes in heated distilled water with a 3% solution of Citranox acid detergent [47]. After a first rinse in distilled water, a second ultrasonic wash was performed, again for 15 minutes, but using heated distilled water with a weak solution of Simple Green detergent [48]. A second rinse in distilled water was performed, followed by a final rinse in a fresh bath of distilled water. The parts were then wiped dry with lint-free cloths, air dried completely, and wrapped in plastic film for storage.

Stainless steel parts that were too large to fit in the ultrasonic bath were prepared by a simpler prescription out of necessity. A pre-rinse with tap water was followed by deburring to remove sharp edges. Both the first and second washes were done with tap water and a weak solution of Simple Green detergent, scrubbing with brushes and lint-free sponges. Two tap water rinses were done, and the parts were then wiped dry with lint-free cloths. As a final additional step, each part was wiped with 200-proof ethyl alcohol, and then air dried completely. These parts were also wrapped in plastic film for storage.

4.4.2 Cleaning G-10

G-10 is known to absorb large quantities of water, which would outgas in the argon and could inhibit reaching the required argon purity in the detector. For this reason all G-10 parts were cleaned and then baked to remove moisture. The largest G-10 parts on the detector are beams that

1 span the distance between the cathode and anode. These were washed in 1900-liter ultrasonic baths
2 that are overseen by Fermilab Accelerator Division, typically used for cleaning large sections of
3 accelerator beam pipes. An initial pre-wash was done with tap water to remove as much particulate
4 matter as possible, since the machining process left a large amount of dust on the machined edges.
5 Pieces were then placed in the ultrasonic bath with heated deionized water and a 2% solution of
6 Elma Clean 65 (EC 65) neutral cleanser [49]. Two ultrasonic bath rinses were performed, and
7 the pieces were then sealed in plastic bags with clean dry nitrogen gas. In order to remove the
8 absorbed water, the large G-10 parts were then transported to Fermilab Technical Division where
9 they underwent an outgassing procedure to remove any remaining absorbed moisture. They were
10 baked in a large oven under vacuum until a plateau in the outgassing was reached, as reported by a
11 monitor inside the oven. Upon completion of the outgassing procedure, the parts were resealed in
12 plastic bags for storage.

13 **4.5 Assembly**

14 The full mechanical structure of the LArTPC is shown in figure 24, with the top image depicting
15 the cathode frame on the left, made semi-transparent to show the support structures on which the
16 cathode sheets are attached. The anode frame is on the right of this image, with I-beams configured
17 in a crossed pattern to maintain the shape and rigidity of the outer C-channel structure. Ribs of G-
18 10 connect the anode and cathode, electrically isolating them from each other while also providing
19 mounting holes to hold in place each of 64 field cage loops that define the active volume of the
20 LArTPC. The field cage loops are visible in the photograph in the bottom frame of figure 24.

21 Assembly was done inside of a clean tent, shown in figure 25, on a flat surface made up of
22 adjustable-height metal platforms that were installed on the assembly room floor. These platforms
23 were leveled to better than 0.5 mm before beginning assembly. The anode frame was the first part
24 of the detector to be assembled on this surface, shown in figure 26. It was temporarily placed
25 aside, and the cathode frame was assembled on the same set of platforms along with the G-10 ribs,
26 which stood vertically with the help of temporary unistrut support pieces. The combined cathode
27 and G-10 frame was then lifted and rotated to the proper orientation, with G-10 ribs extending
28 horizontally from the cathode to the anode, as shown in figure 27. Finally, the anode frame was
29 brought back over and attached to the G-10 ribs, and the stainless steel tubes that make up the field
30 cage loops were fed through the holes in the G-10 ribs to complete the mechanical structure of the
31 LArTPC.

32 **4.6 High Voltage System**

33 To create the drift field, negative voltage (referred to as the “high-voltage” or “HV”) is supplied to
34 the LArTPC cathode. This potential is generated outside of the cryostat by a Glassman LX150N12
35 power supply. Before entering the cryostat, the output of the power supply is passed through a
36 current-limiting resistor series that serves as both a low-pass filter for the power supply ripple, and
37 a partition for the stored energy in the system. The resistor series is a set of eight $10\text{ M}\Omega$ resistors
38 submerged in a transformer oil in an aluminum container. This assembly was successfully tested
39 to -200 kV.

40 The potential is introduced into the cryostat by a custom-designed HV feedthrough. The
41 feedthrough is based on an ICARUS design [7]; a 2.54 cm diameter stainless steel inner conduc-

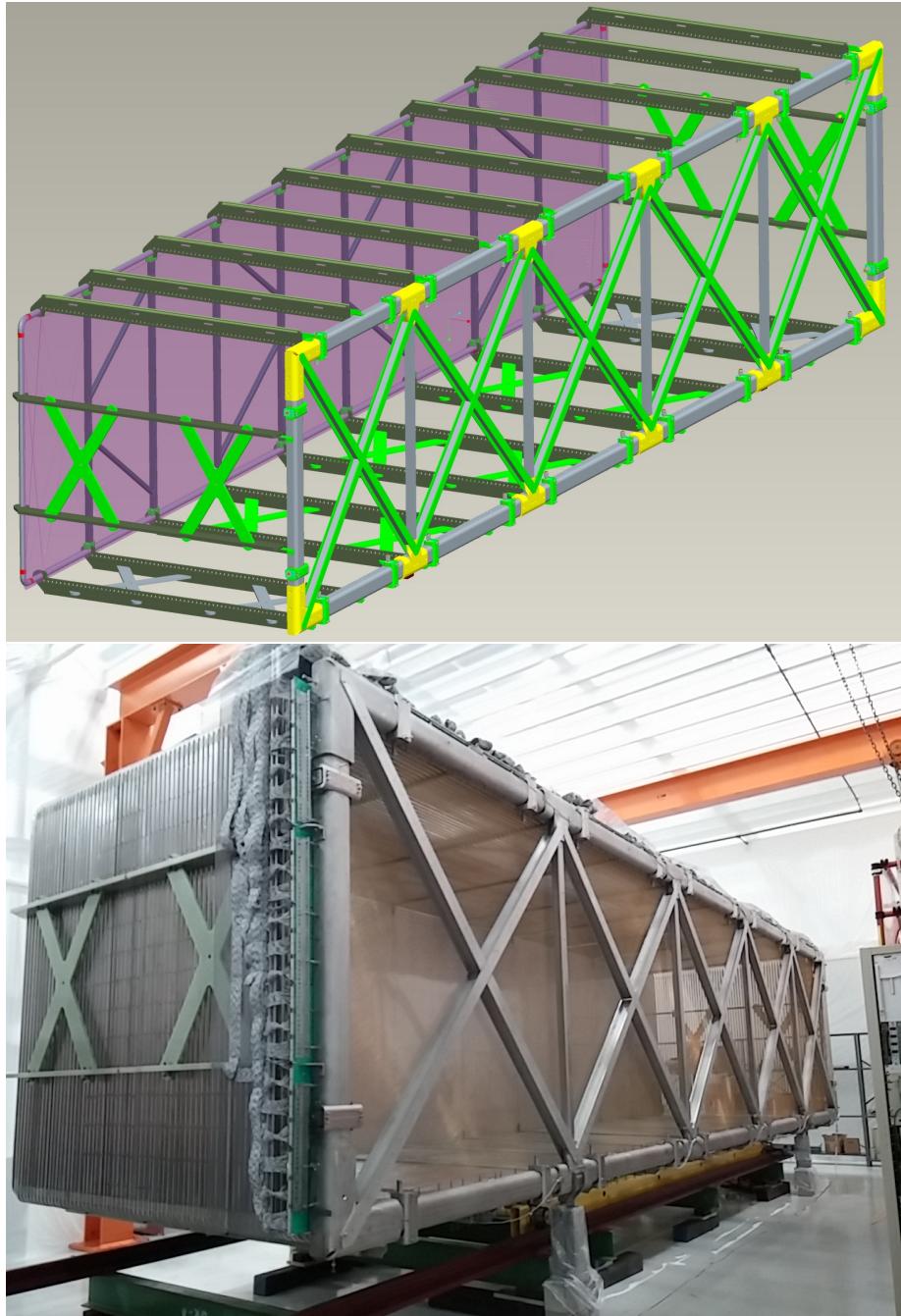


Figure 24: Top: Rendering of the full LArTPC frame assembly. Bottom: Assembled LArTPC after wire and electronics installation.

¹ tor is surrounded by a 5.08 cm outer diameter ultra-high molecular weight polyethylene (UHMW
² PE) tube that is encased in an outer ground tube. A photograph and drawing of the production
³ feedthrough are shown in figure 28.

⁴ Figure 29 shows the HV feedthrough extending into its receptacle cup attached to the LArTPC
⁵ cathode. The lower termination of the outer ground tube is a torus chosen to reduce the electric



Figure 25: Clean tent where MicroBooNE LArTPC assembly was conducted.



Figure 26: Anode frame in the process of being moved from the metal assembly platforms.

1 field between both the feedthrough and the cathode plane and along the feedthrough itself. The
2 electrical connection to the cathode is made with a hemispherical spring-loaded tip attached to the
3 inner conductor of the feedthrough. The UHMW PE tube is machined with grooves and extends



Figure 27: Cathode frame and G-10 ribs on metal assembly platforms.

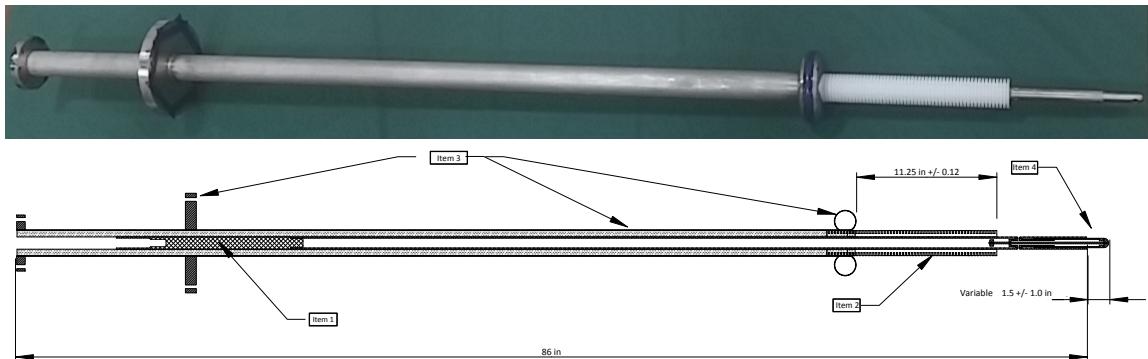


Figure 28: Photograph and drawing of the production HV feedthrough. The spherical probe tip is attached to the end of the inner conductor, on the right side of these figures.

¹ into the receptacle cup attached to the cathode.

² 5. Light Collection System

³ Liquid argon is a very bright scintillator, and collecting the light produced when charged particles
⁴ travel through the LArTPC is a critical aspect of fully understanding the interactions taking place in
⁵ the detector. The light collection system is designed to meet MicroBooNE's physics goals for light
⁶ collection, which are twofold. First, for accelerator-induced events, the light collection system is
⁷ designed to trigger on 40 MeV kinetic energy protons produced in neutrino interactions. Second,



Figure 29: The production HV feedthrough inserted into the cathode receptacle cup inside the cryostat.

1 for non-beam events, the system is designed for efficient observation of 5 to 10 MeV electrons from
 2 supernova neutrinos.

3 The light produced by neutrino interactions in MicroBooNE is an important input for both
 4 event selection and reconstruction. One of the critical capabilities the light collection system pro-
 5 vides is the ability to form a beam-event trigger when a pulse of light is observed in coincidence
 6 with the beam spill. Because a vast majority of beam spills will not produce a neutrino interaction
 7 in the detector, such a trigger will substantially reduce the data output rate. For non-beam physics
 8 studies, the light system provides triggering and an event t_0 . For accelerator-induced events, the
 9 start time of a beam spill is, in principle, sufficient. However, because of the long window over
 10 which the ionization electrons of an event drift (about 1.6 ms maximum drift time at 500 V/cm
 11 field), there are many accelerator-induced events in which a cosmic ray muon crosses the detector
 12 during the drift time. Utilizing the position of hits in the photodetectors, one can better reject cos-
 13 mic ray muon tracks. The light can also be used to trigger and select specific types of cosmic-ray
 14 calibration events (Michel electrons, straight-through muons, etc.) and non-beam events (super-
 15 nova neutrinos, cosmic background events to proton decay studies, etc.).

16 The light collection system consists of primary and secondary sub-systems. The primary light

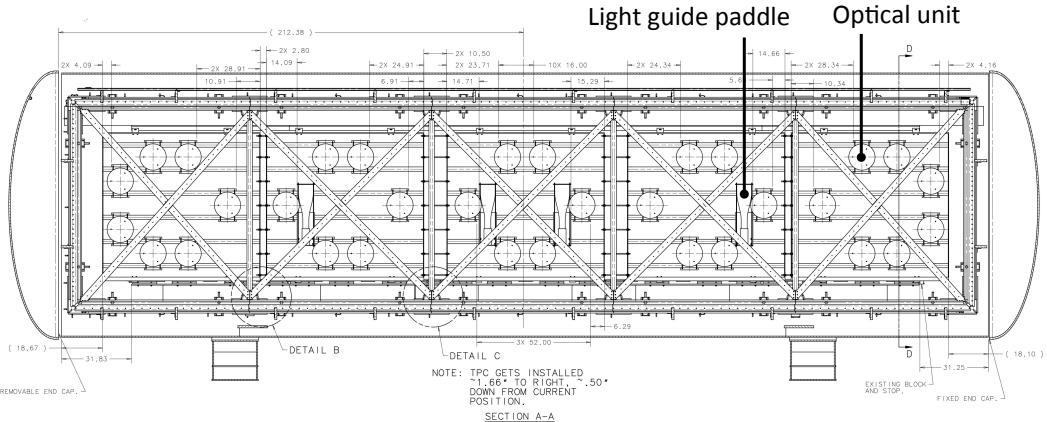


Figure 30: The MicroBooNE light collection system consists of a primary system of 32 optical units and a secondary optical system of four lightguide paddles [56]. These are mounted behind the anode wire planes such that the view is not obscured by structural cross bars of the LArTPC.

1 collection system is made up of “optical units,” each one consisting of a PMT located behind a
 2 wavelength-shifting plate. In total, 32 optical units were installed, yielding 0.85% photocathode
 3 coverage. The secondary system consists of four light guide paddles. These paddles are introduced
 4 for R&D studies for future LArTPCs, and are placed near the primary optical units to allow a
 5 comparison of their performances. A flasher system, used for calibration, consists of optical fibers
 6 bringing visible light from an LED to each PMT face.

7 The light collection detectors are located in the y - z plane behind the anode planes of the
 8 LArTPC, as shown in figure 30. The combined transparency of the three anode planes is 86%
 9 for light at normal incidence. This transparency value assumes 100% of VUV photons impinging
 10 on the wires (150 μm diameter and 3 mm pitch) are absorbed. The detectors were placed so as
 11 not to be obscured by the LArTPC structural cross-bars, shown in figure 30. Locating the light
 12 detectors behind the anode plane places them in a very weak electric field due to the +440 V bias of
 13 the collection plane. To test for an effect from weak electric fields, the response of a PMT placed
 14 between a +700 V mesh and ground, separated by 50 cm, was studied. The PMT zenith was 25 cm
 15 from the HV. No effects on the signal were observed. This was expected, as the photocathode is
 16 held at ground, effectively acting as a Faraday cage.

17 Throughout the design and construction of the light collection system, substantial R&D was
 18 performed. The reader should refer to [35, 50–59] for detailed results of these studies. A useful
 19 overall review is available in [60].

20 Figure 31 shows the light observed in two sequential events, consistent with a muon entering
 21 the detector followed by a Michel electron from the decay. One can see that the light is relatively
 22 well localized. This allows the light to be correlated with specific tracks in the detector. This
 23 “flash-track matching” is used to identify and reconstruct the tracks that are in time with the beam
 24 spill—an important goal of the light collection system.

25 **5.1 Light Production in Argon**

26 Light produced in liquid argon arises from two processes: scintillation and Cherenkov radiation.

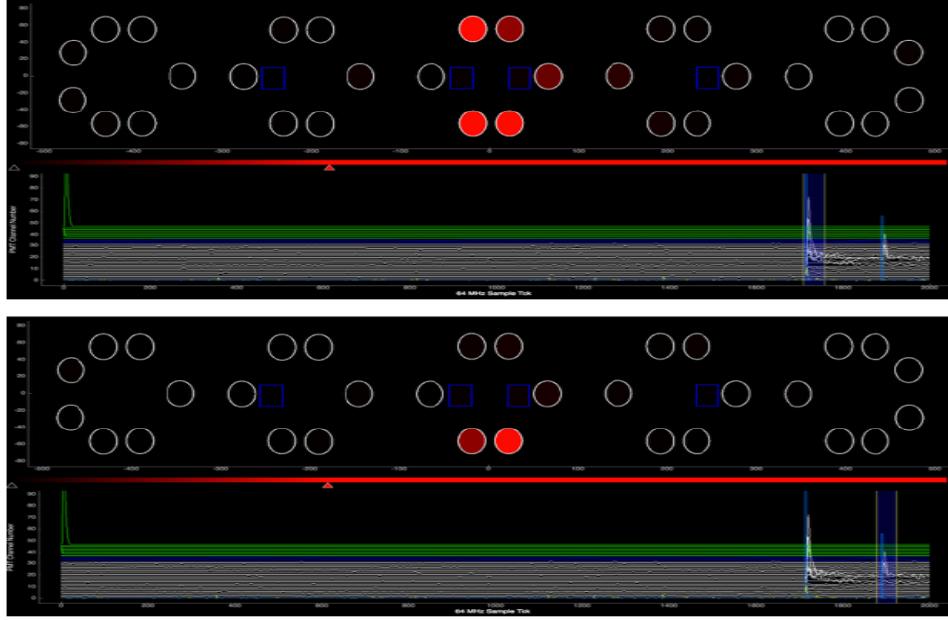


Figure 31: Two sequential event displays for the light collection system. The sequence is consistent with a muon that stops (top) and decays (bottom). The circles correspond to the optical units. Red circles indicate those units with hits. The waveforms versus time are shown below.

Table 6: Important properties of scintillation light in liquid argon that affect detection in MicroBooNE.

Property	Value	Reference
Wavelength	128 nm	[61]
Singlet, Triplet state time constants	6 ns, 1.6 μ s	[62]
Photons/MeV for $E = 500$ V/cm	24000	[7]
Triplet lifetime quench due to N ₂ at 1 ppm	20%	[63]
Attenuation length due to N ₂ at 1 ppm	66 m	[35]
Rayleigh Scattering Length	\sim 90 cm	[64]
Transparency of the wireplanes at normal incidence	86%	-

¹ Scintillation light is produced by the formation and eventual radiative decay of excited argon dimers (or eximers) and is emitted in an isotropic distribution. Liquid argon is an excellent scintillator: it produces a large amount of light per unit energy deposited (about 24,000 photons per MeV at 500 V/cm drift field) and is transparent to its own scintillation. The scintillation light has a prompt and slow component with decay times of about 6 ns and 1.6 μ s, respectively. The two lifetimes

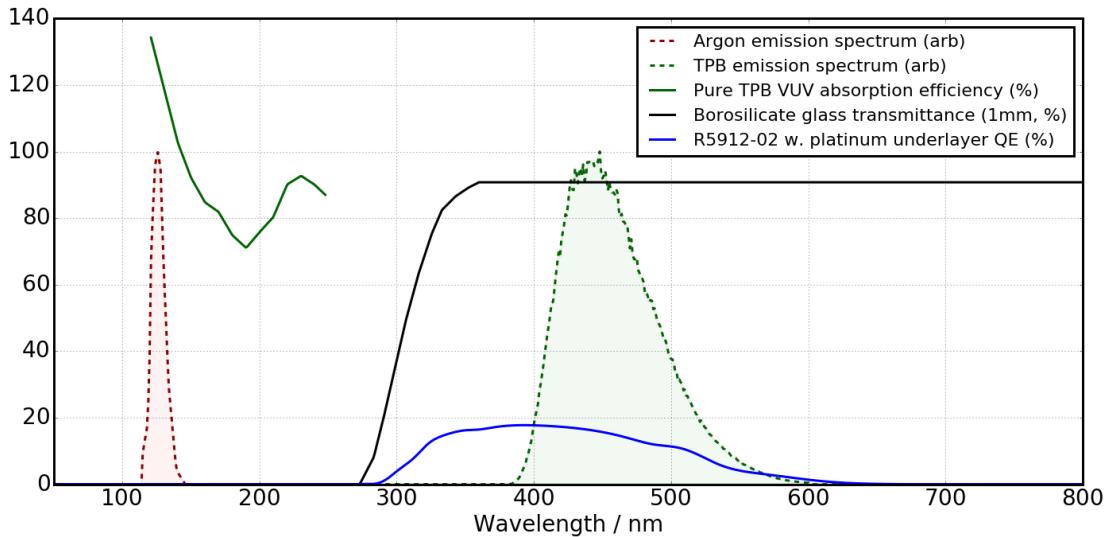


Figure 32: Scintillation light emission spectrum (red) and TPB re-emission spectrum (green), in arbitrary units. Superimposed are important efficiencies (see y axis): Dark green line – absorption of VUV light by TPB; Black line – transmission of borosilicate glass; Blue line – efficiency of a R5912-02mod cryogenic PMT [60]

1 correspond to the two lowest-lying eximer states with the prompt component coming from the
 2 decay of a singlet state and the slow from the decay of a triplet state. The prompt to slow ratio is
 3 about 1:3 for minimum ionizing particles and varies with ionization density and particle type. Both
 4 components consist of photons with a wavelength of 128 nm.

5 There is a significant uncertainty on the expected triplet lifetime [62] and this may be further
 6 modified by quenching (non-radiative dissociation of excimers by impurities) [63]. Other factors
 7 that can affect the arrival of the light include Rayleigh scattering, absorption by impurities, and
 8 obstructions. For detailed discussion of the physics of scintillation light production and propagation
 9 in MicroBooNE, see [60]. Table 6 summarizes information about the scintillation light.

10 Because scintillation photons have a wavelength of 128 nm they are very difficult to detect
 11 using conventional photodetectors. Figure 32 summarizes the challenges involved in detection of
 12 the 128 nm scintillation light. In order to detect the scintillation light, with spectrum shown in
 13 red, the VUV photons must be shifted into the visible region. MicroBooNE employs tetraphenyl-
 14 butadiene (TPB). This organic fluor absorbs in the UV (green line) and emits in the visible with
 15 a peak at 425 ± 20 nm (green hatched region), the peak wavelength having a slight dependence
 16 on the micro-environment of the fluors. This is a favorable wavelength for detection by the PMTs
 17 employed by MicroBooNE. The efficiency for transmission through borosilicate PMT glass (black)
 18 and the quantum efficiency of the cryogenic tubes used in MicroBooNE (blue) are overlaid on the
 19 TPB spectrum.

20 5.2 The Primary Light Collection System

21 Each of the 32 optical units of the primary light collection system consist of a cryogenic Ham-

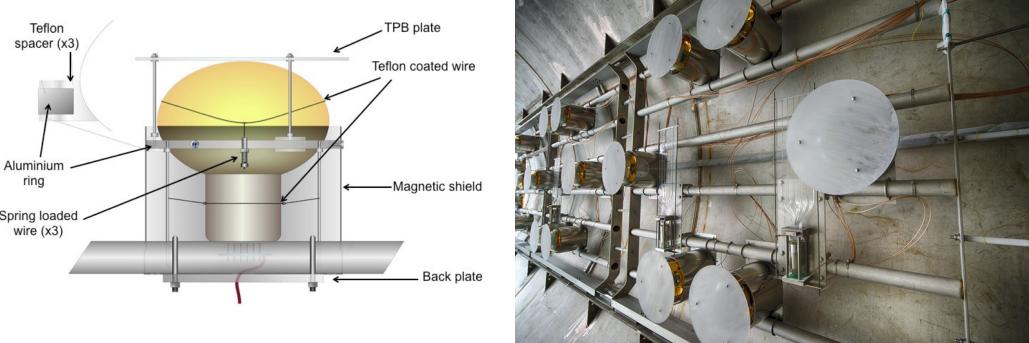


Figure 33: Left: diagram of the optical unit; Right: units mounted in MicroBooNE, immediately prior to LArTPC installation.

matsu 5912-02MOD PMT seated behind an acrylic plate coated with a TPB-rich layer and surrounded by a mu-metal shield. Figure 33 shows a diagram of one unit (left) and a photograph of installed units (right). Past experiments have directly coated PMTs with wavelength shifter [7]. However, the MicroBooNE design separates the PMT from the wavelength-shifting plate for simplicity of quality control and installation. This proved important, as R&D indicated that TPB is particularly vulnerable to environmental degradation (see section 5.2.3). In this section, description is provided for each component of the optical unit, as well as for the overall assembly.

5.2.1 Photomultiplier Tubes and Bases

Reference [54] provides detailed information on the selection and testing of the 8" Hamamatsu R5912-02mod cryogenic PMTs employed in MicroBooNE. In this section a brief summary of the findings from this testing is presented.

The R5912-02mod employs a bi-alkali photocathode. Because the PMT is designed for cryogenic use, the R5912-02mod also features a thin platinum layer between the photocathode and the borosilicate glass envelope to preserve the conductance at low temperatures. While this allows the PMT to function below 150 K, absorption in the platinum reduces the efficiency of the PMT by 20%. Figure 34 provides quantum efficiency curves for the 8 inch PMTs. The manufacturer's specifications do not include the effects of the platinum photocathode coating, but a wavelength dependent quantum efficiency was provided by Hamamatsu for 4 of the 32 installed PMTs. The mean and standard deviation of these curves are shown in figure 34.

The R5912-02mod is a 14-stage PMT. The high gain at room temperature (10^9 at ~ 1700 V), compensates for known reduced gain at 87 K in the liquid argon. The high gain also has the additional advantage of allowing operation at lower than nominal voltage which reduces heat-loss in the cables and the potential for high voltage breakdown at the feedthroughs.

The PMT base is designed such that the photocathode is grounded and the last dynode in the chain is held at large, positive voltage. Thus the PMT bulb, which is closest to the LArTPC anode plane, is at ground and does not disturb the electric field on the wires. The result is that the high voltage (HV) can be provided and the signal can be extracted from the PMT using a single cable,

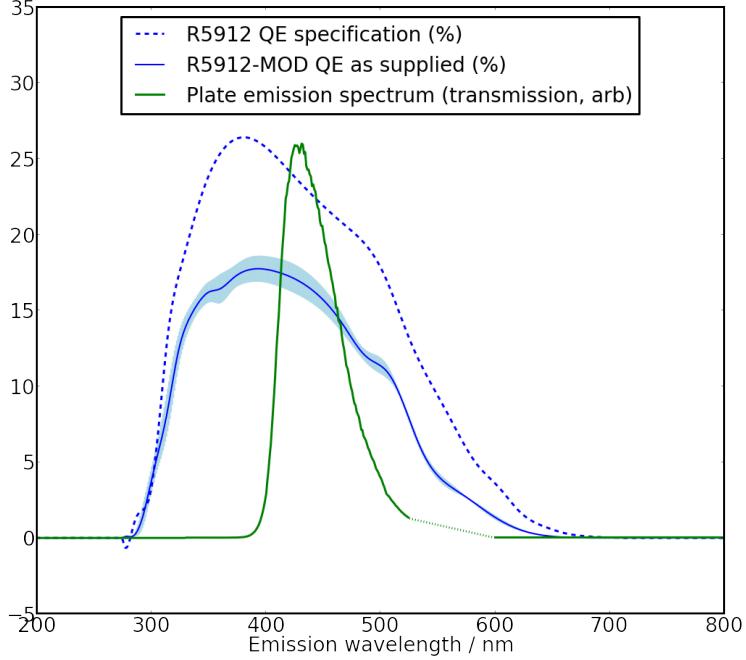


Figure 34: The specification for the non-platinum undercoated PMT from [65]. The blue band shows the mean and standard deviation of the four quantum efficiency curves provided by Hamamatsu for installed MicroBooNE PMTs. Also shown is the measured emission spectra of MicroBooNE wavelength-shifting coatings, discussed in section 5.2.2. [60]

1 reducing the cable volume in the vapor region and removing a possible source of out-gassing water
2 impurity.

3 The flat PC-board base was made of Rogers RO4000-series woven glass-reinforced laminate,
4 which is the same material with the LArTPC cryogenic front end boards. Use of Rogers 4000 series
5 as the base material avoids the potential risk of contamination of the liquid argon. The Rogers
6 material has a similar temperature expansion coefficient as the surface mounted components which
7 enhances the reliability of the electronics assembly when operated at cryogenic temperatures. The
8 base is attached ~ 1 cm from the bottom of the PMT and is the closest possible distance of safe
9 approach to the PMT vacuum seal tip. A schematic and photos of the PMT base are provided in
10 reference [54]. The passive components include only metal film resistors and C0G/NPO capacitors,
11 which have the minimum temperature coefficients, and the performance at cryogenic temperatures
12 were tested. Because the supplied HV and return signal share a single cable, the signal must be
13 split from the HV through an AC-coupling capacitor, as is discussed in section 5.2.5.

14 All installed PMTs were tested in a PMT test stand, both at room temperature and in liquid
15 nitrogen which is at 77 K. The details are described in reference [54]. In brief, the test stand
16 consisted of a light-tight 346 L, liquid nitrogen filled dewar into which up to four PMTs could be
17 installed. The PMTs were immersed and maintained in the dark environment for up to three days
18 before most measurements of the dark rate and gain were performed. A fiber brought in light from
19 a pulsed blue LED, which was tested for linearity with bias voltage.

20 Among the important results from cryogenic testing were the following [54]:

- The PMTs could be ramped to voltage quickly in the cold environment, and after 30 minutes, the gains were found to be stable.
- If the room temperature PMTs were immersed in liquid nitrogen, dramatic changes in the gain were observed after initial turn-on. The PMT gain remained high in the first \sim 5 hours after immersion, and then suddenly dropped by more than a factor of two, afterwards reaching a stable value with a small drift.
- The PMT response showed good linearity up to 100 photoelectrons (PE), which was the maximum attainable by the PMT test stand LED.
- The HV for each PMT was selected to produce a gain of 3×10^7 in liquid nitrogen, and was typically chosen to be \sim 1300 V.
- The dark current plateaus extended up to 1800 V in liquid nitrogen, and the dark current is higher in liquid nitrogen than at room temperature.
- The PMT performance depended on rate of the pulsed LED.

No PMTs were rejected on the basis of the testing. However, there were three unexpected results to note here.

The first unexpected behavior was that, at room temperature, most of the PMTs showed gains that were 10 to 30% higher than manufacturer's specifications. As expected at cryogenic temperatures, the gain is reduced by \sim 10% to 50%. To measure the PMT gain, the LED was set to produce one to two PEs. The gain was found from the separation of the single PE peak from the pedestal, where the single PE response was fit using the procedure described in [66].

Second, it was found that the PMTs are noisier in the cryogenic environment. It would typically be expected that thermal emission is suppressed at cryogenic temperatures and one would expect a lower dark current for PMTs operating in this regime. However, the dark current measured in the liquid nitrogen is higher than at room temperature. Although the cause is unknown, this phenomenon has previously been observed[67]. A proposed explanation is provided in [68].

Third, an LED pulse-rate-dependent gain shift was found during testing, as shown on figure 9 of reference [54]. This behavior is described qualitatively in [69]. With 10 kHz LED pulsing, the gains of cold and dark-adapted PMTs were shown to steadily increase, requiring nearly 24 hours from turn-on to stabilize. The effect was not observable at 10 Hz. This is relevant to MicroBooNE because the cosmic muon rate in the MicroBooNE detector is \sim 5 kHz. Therefore a similar effect is expected in the MicroBooNE detector. Preliminary results from measurements of the PMTs installed in the LAr-filled MicroBooNE cryostat shows the expected effect.

5.2.2 Wavelength-Shifting Plates

In order to be sensitive to 128 nm VUV liquid argon scintillation photons, the optical assemblies use a wavelength-shifting coating to convert this VUV light to visible wavelengths that are detectable by PMTs. In MicroBooNE, the active ingredient of this coating is TPB, an organic fluor which absorbs efficiently in the vacuum ultraviolet with an emission spectrum peaked around 425 nm [70] as shown in figure 32.

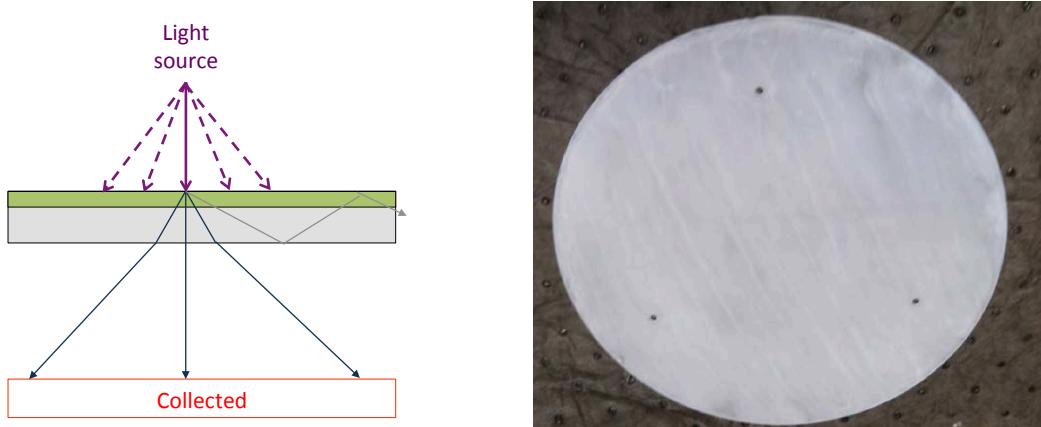


Figure 35: Left : Illustration of transmission mode, used by the optical units. Right: photograph of a coated plate.

1 The optical unit PMTs observe light transmitted through TPB-coated, 12-inch diameter acrylic
 2 plates (see figure 35). The coating consists of a 1:1 TPB-to-polystyrene ratio, with 1 g of each
 3 dissolved in 50 ml of toluene. A small amount of ethyl alcohol is added as a surfactant. The coating
 4 is applied to the acrylic plate in three layers by brush-coating. The solution dries in air at room
 5 temperature. This leads to a final layer which is oversaturated with TPB, and white crystals form
 6 on the surface as the coating dries. The presence of surface crystallization gives the MicroBooNE
 7 plates a white, opaque finish. Details of the process are described in reference [71].

8 The emission spectrum in figure 34 was measured using a Hitachi F-4500 fluorescence spec-
 9 trophotometer with an incident beam of wavelength 270 nm, selected by a diffraction grating from
 10 a xenon lamp. A standard rhodamine dye calibration sample was used to correct for drift in the
 11 lamp and spectrometer. The measurement was made in transmission mode, and an artifact peak at
 12 a harmonic of the twice incident wavelength was observed between 525 and 600 nm. This region
 13 is omitted from the reported spectrum of figure 34.

14 As shown in figure 34, although the absolute quantum efficiency for the platinum-undercoated
 15 cryogenic PMT is lower than the non-cryogenic version, the wavelength dependence is similar,
 16 and overlap between the TPB emission spectrum and the sensitive wavelength range of the PMT
 17 remains high. Using the measured TPB emission spectrum for plate coatings and the PMT quantum
 18 efficiency curve provided, the spectrum-averaged PMT quantum efficiency is $15.3\% \pm 0.8\%$ per
 19 visible photon incident on the photocathode.

20 The wavelength-shifting performance of the coating was measured at 128 nm relative to evap-
 21 orative coatings of the type studied in [72]. Coating efficiencies were measured as a function
 22 of wavelength between 128 and 250 nm using a vacuum monochromator at room temperature.
 23 They were also measured in liquid argon using 128 nm scintillation light, relative to the same
 24 evaporatively coated plate. These data are shown in figure 36, and more information about these
 25 measurements can be found in [71].

26 The absolute efficiency of the MicroBooNE coatings can be obtained by multiplying the rela-
 27 tive efficiencies of figure 36 by the measured absolute efficiencies from [72], and accounting for the
 28 temperature dependence in the wavelength-shifting efficiency of pure TPB reported in [73]. The

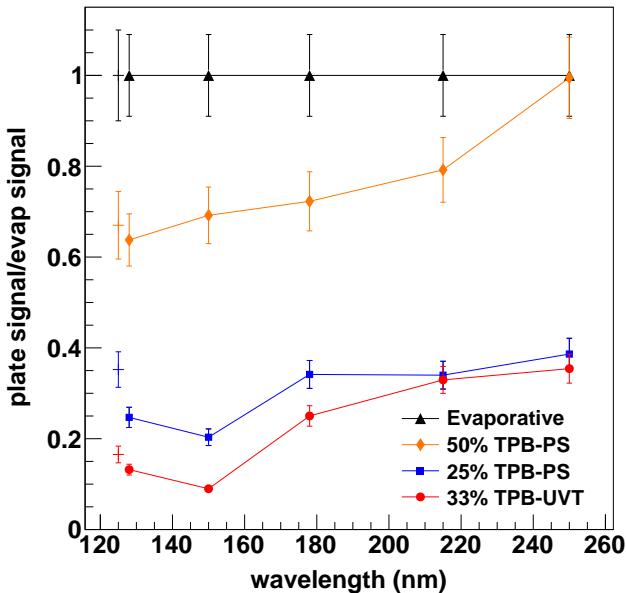


Figure 36: Measured efficiencies of various wavelength-shifting coatings, from [71]. In this plot, 50%TPB-PS is the MicroBooNE plate coating used in the optical units. The 33%TPB-UVT is the light guide coating for the secondary light collection system described below. Connected points were measured in a vacuum monochromator at room temperature, and non-connected points were measured in liquid argon with 128 nm scintillation light. All points are normalized to the performance of an evaporatively coated plate.

¹ expected efficiency of MicroBooNE coatings is found to be 0.98 ± 0.17 emitted visible photons per
² incident 128 nm photon for the plate coating.

³ 5.2.3 UV Light Protection for the Wavelength-Shifting Plates

⁴ TPB coatings have been shown to degrade under exposure to ultraviolet light [52] through a radical mediated photo-oxidation to the UV-blocker and photo-initiator benzophenone [74]. Several
⁵ measures were taken to ensure that degradation was minimized during the construction of the ex-
⁶ periment. The TPB powder and coated elements were stored in the dark at all times, with coated
⁷ plates and light guides being kept wrapped in foil and stored in a dark container before installation.
⁸ The detector construction area was covered with a UV blocking plastic [75], and test plates were
⁹ placed at various positions in the clean tent to check for degradation from stray light. After sev-
¹⁰ eral weeks of exposure, one test plate with a clear line of sight to the tent entrance demonstrated
¹¹ a few percent degradation, and all others showed no observable loss of efficiency. The open end
¹² of the MicroBooNE cryostat was shielded from light by a black curtain after installation, and the
¹³ feedthroughs of the cryostat were blocked when not in use to prevent stray light from entering. The
¹⁴ coated plates were the final component of the optical system to be installed into the detector to give
¹⁵ the minimum possible light exposure during the detector construction process.
¹⁶

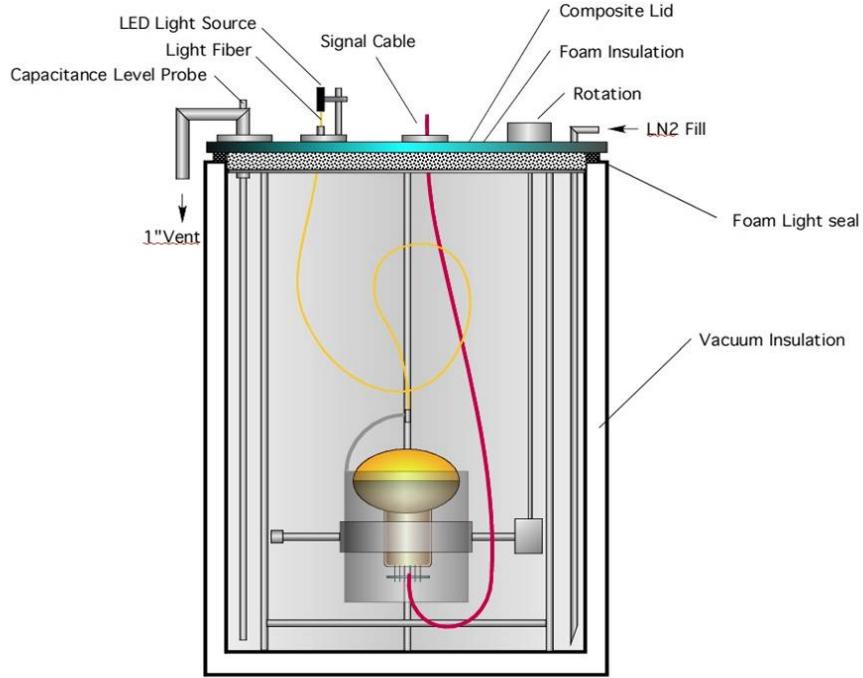


Figure 37: Schematic of the system used to study the mu-metal shields. The design allows rotation along all three axes.

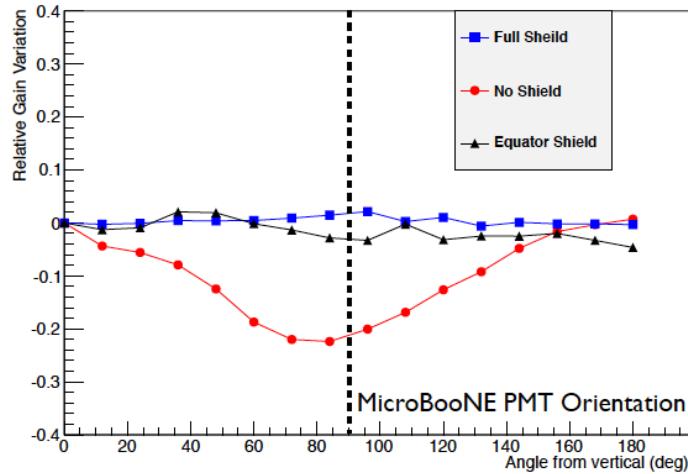


Figure 38: Red: Angular dependence of a PMT response with no shield; Black: for a shield that reaches the tube equator; Blue: for a shield that fully covers the tube to the zenith.

5.2.4 Cryogenic Mu Metal Shields

The trajectories of electrons within the 8" PMT can be deflected by the Earth's magnetic field. This effect can be reduced or removed by surrounding the PMT with mu metal, a metal of low magnetic permeability. Commonly used mu-metal fails to provide shielding at cryogenic temperatures. Two types of cryogenic mu metal, Cryoperm 10 and A4K, both products of Amuneal, were identified

1 that did provide shielding at cryogenic temperature.

2 The mu metal shields were tested in the apparatus shown in figure 37. The system allowed for
3 the PMT to be positioned at an angle relative to the vertical axis, with the rotator set to 30 positions
4 from 0 to 348° . The set-up was on a dolly that allowed for rotation about the vertical axis. PMT
5 tests were performed in air and in liquid nitrogen. PMTs were dark adapted for 5 hours before
6 testing. A blue LED provided 1 to 2 single PEs of light through an optical fiber. The fiber was
7 fixed to the PMT mount such that the endpoint was stationary with respect to the tube as the system
8 was rotated.

9 The mean charge from the PMT as a function of angle was recorded. The error was primarily
10 systematic. The $\sim 10^6$ LED pulses per data point give $< 1\%$ statistical error on the mean.
11 However, 24-hour studies of a single point showed $\sim 5\%$ variations in collected charge due to
12 gain drift. Results showed that A4K and Cryoperm function essentially identically, to within the
13 measurement error, and so MicroBooNE chose A4K, based on significant cost savings. A plot of
14 the relative PMT gain variation versus angle from vertical, figure 38, shows that adding the shield
15 significantly improves PMT performance. This plot shows the effect of the A4K shield with the
16 height aligned with the equator of the PMT (black) and aligned with the zenith of the bulb (blue),
17 compared to no shield (red) as a function of PMT azimuthal angle. Given the 5% systematic error,
18 the two shield positions are indistinguishable.

19 As a result of these tests, the A4K shields were designed to extend just past the equator of the
20 PMT. The shield has small holes in the backplate that allows the PMT cables to exit the shield.
21 MicroBooNE is the first LArTPC to use cryogenic mu metal shields in its light collection system.

22 **5.2.5 Implementation of the Primary System**

23 The light collection system is composed of optical units assembled as shown in the top picture
24 of figure 39. The PMT is seated within the mu metal shield on three teflon pads attached to an
25 equatorial support ring. The neck of the tube slides inside a loose wire guide-loop that prevents
26 the PMT from tipping. The PMT is held within this assembly using teflon-encased wires that
27 extend across the bulb and connect to wire hooks attached to the equatorial ring with stainless
28 steel springs. Legs extending from the support at the equator are screwed into a backplate for final
29 mounting. Concern about differences in contraction of the materials led to this design which holds
30 the PMT in place, but with only moderate rigidity. The units were tested to ensure the PMTs would
31 not be displaced during installation and filling. Three posts extend upward from the equatorial
32 ring to hold the plate 3.0 cm above the apex of the bulb. The optical units slide into a cylindrical
33 mu-metal shield, which screws into the equatorial ring. The unit is then mounted on stainless steel
34 back-plates affixed to a support rack, as shown in the bottom picture of figure 39.

35 The support rack consists of five stainless steel components, or modules, for ease of instal-
36 lation. Each module has vertical height 1.83 m and horizontal length 2.07 m, resulting in a total
37 horizontal length of 10.36 m. Unlubricated Thomson bearings fitted to the lower edge allow each
38 module to slide into the cryostat on rails mounted in the vessel. The system was designed to allow
39 the light detection system to slide into the vessel after the LArTPC was installed. However, in the
40 end, scheduling permitted installation of the system before the LArTPC installation. This had the
41 advantage of making installation and surveying easier, but the drawback that the system would be
42 exposed to UV light for a long period. Therefore, the units were installed with dummy clear acrylic

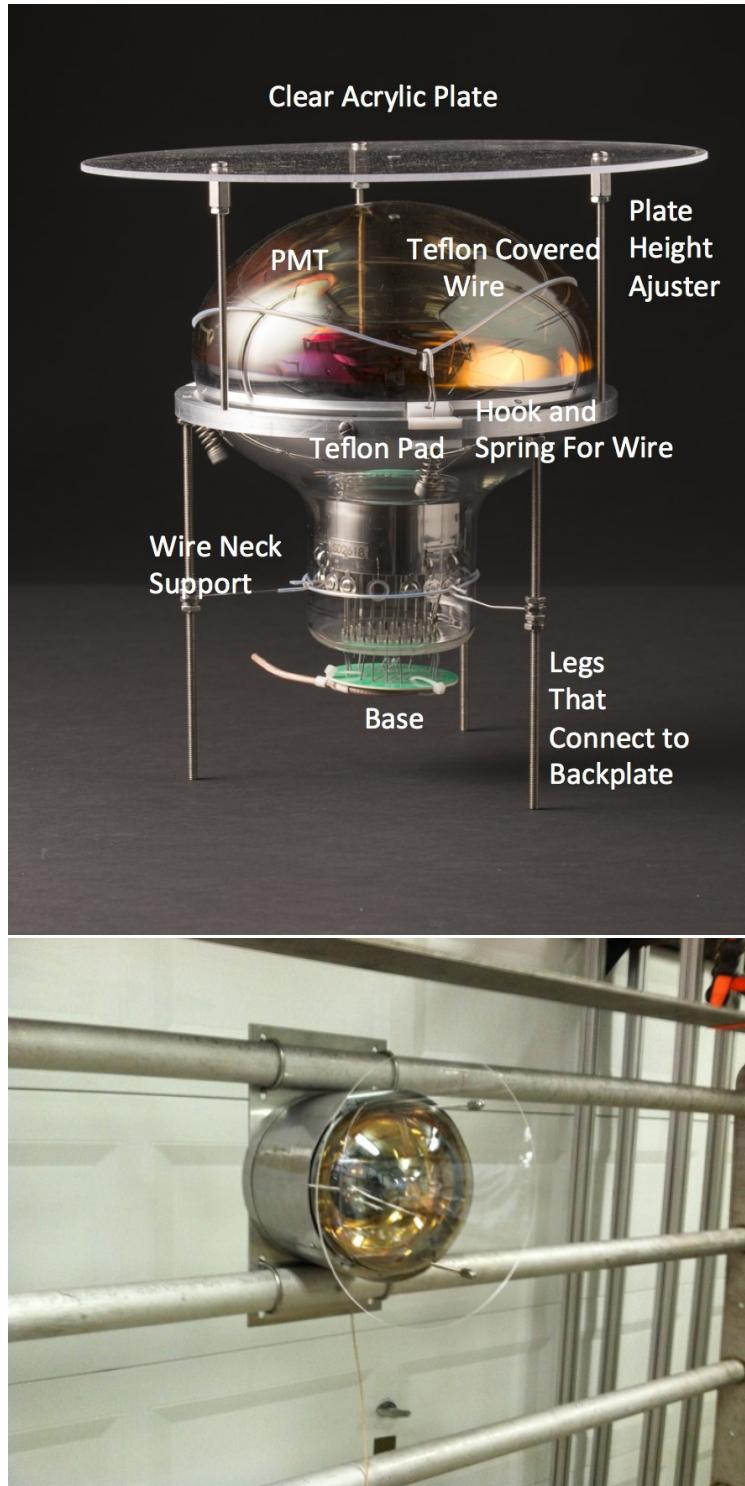


Figure 39: Top The optical unit mount internal to the shield, with components labeled; Bottom: Unit mounted on rails. The clear plates were replaced with TPB-coated plates immediately before LArTPC installation, as discussed in the text [54, 56].

1 plates, and the TPB coated plates were installed only just before the LArTPC was moved in and
 2 the detector could be easily protected from light. During optical unit installation, each rack module
 3 was supported by a temporary mounting rail. The optical units were then mounted in positions
 4 chosen to avoid obstruction by the LArTPC cross-bars, as shown in figure 30. As the units were
 5 mounted and slid into the cryostat, the cables were loosely tied to the bars of the rack for support
 6 and constraint.

7 The “splitter” circuit, located outside of the cryostat, is shown in figure 40. The splitter sepa-
 8 rates the HV of the PMT from its output signal which is subsequently split into a high-gain (HG)
 9 and a low-gain (LG) channel. The HG and LG channels respectively carry 18% and 1.8% of the
 10 output signal. This allows a wide dynamic range for ADC readout of the PMT pulses. The ca-
 11 pacitance was chosen to minimize reflections, since the bases are not back-terminated. The HV is
 12 supplied to the splitter using BiRa Corporation, Model 4877PS modules.

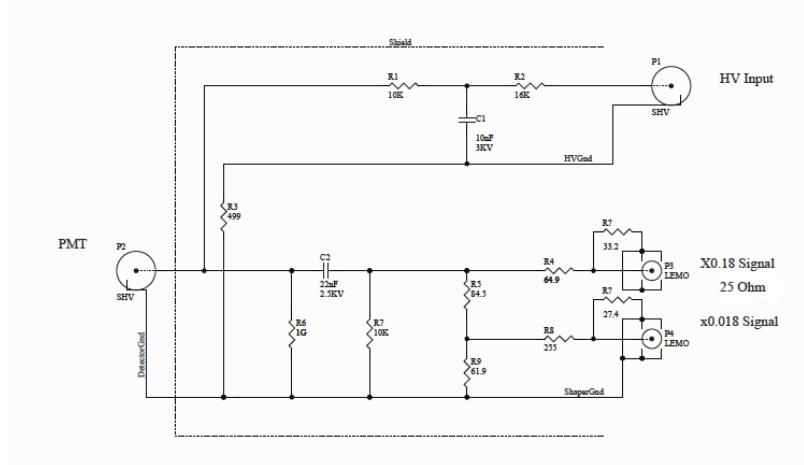


Figure 40: The “splitter” circuit. The circuit connects the HV source to the PMT. It also provides a pathway for signal pulses from the PMT to reach the readout electronics via an AC-coupling capacitor (C2). The signal is split into two copies, one provided with an attenuation factor of 0.18 and another at 0.018. Both signal sources are recorded by the readout electronics in order to provide two dynamic ranges.

13 The PMT cable system delivers HV and returns signals between the external splitter and the
 14 optical unit in the cryostat. A single cable runs from an external connector, through the feedthrough
 15 filled with Stycast 2850 epoxy [76], into the cryostat and to the PMT base. The RG316/U coaxial
 16 cable has 50 Ohm impedance. Cables were terminated with Pasternack PE4498 SHV to accom-
 17 modate that the cable carries HV to the tube as well as signals from the tube. The cable carries
 18 an AC voltage rating of 1100 V; however tests showed the DC rating to be at least three times
 19 higher and so suitable for this use. The cables were routed through feedthroughs consisting of a
 20 pipe filled with solidified epoxy mounted on a conflat disk. On the warm side of the feedthrough,
 21 the cables were terminated at a patch panel with SHV connectors. The SHV connector impedance
 22 has a negligible effect on the 20-30 ns PMT signals. SHV cables connect the patch panels to the
 23 splitters. The impedance of every channel was tested at the feedthrough patch panel for a stable

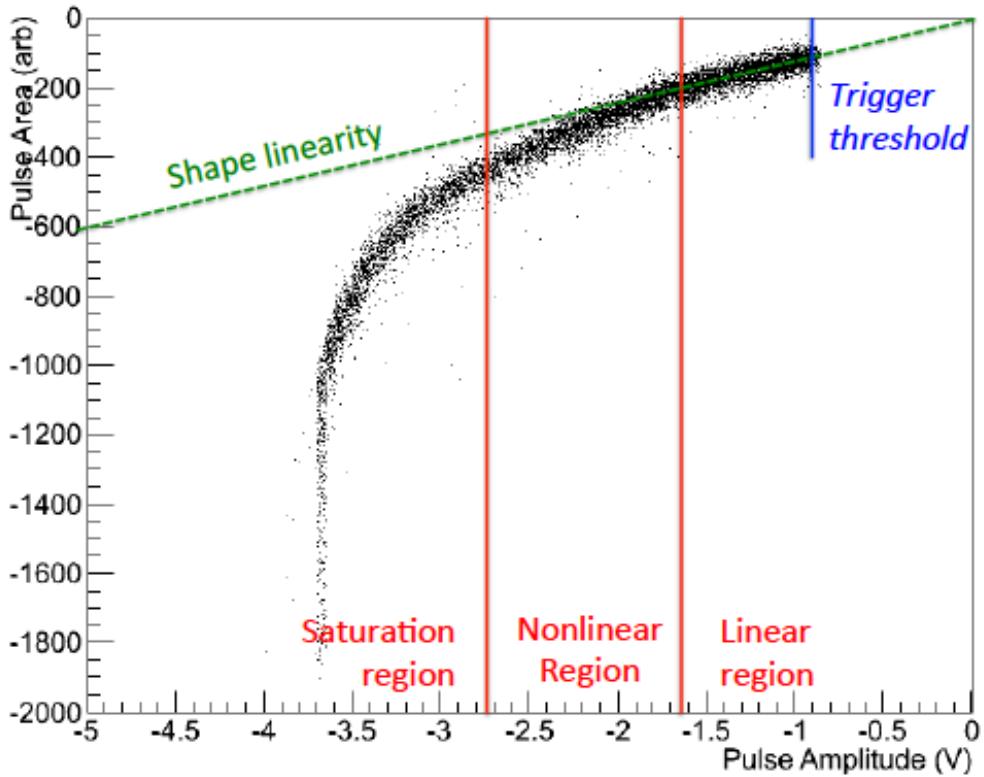


Figure 41: As shown by the VST, linearity of cosmic-ray induced PMT pulses is maintained up to amplitudes of around 1.7 V (300 PE), and amplitude saturation occurs at 3.7 V (670 PE) [60]

1 and correct value for the base resistance, which was 4.04 ± 0.02 M Ω for the 8-inch PMTs.

2 **5.3 PMT Testing and Quality Assurance**

3 The PMTs were tested and characterized before installation in the detector in the “Bo” cryostat at
4 Fermilab. The Bo cryostat is a 250-liter vacuum-insulated vessel with an inner diameter 22 inches
5 and a depth of 40 inches used for R&D studies, and, relevant to this paper, a vertical slice test of
6 the MicroBooNE optical units. The system is described in detail in reference [60]. The cryostat
7 can be filled with purified LAr with parts per billion level contamination of oxygen and water and
8 parts per million level of nitrogen. The light collection system was tested with light from visible
9 (420 nm) and UV (250 nm) LEDs piped in via fiber, as well as scintillation light from ^{210}Po alpha
10 sources and cosmic rays.

11 A vertical slice test (VST) of the MicroBooNE optical system was performed in the Bo Cryo-
12 stat. The slice consisted of two 8 inch PMTs with base electronics, mu-metal shield, TPB plates,
13 cable feed throughs, splitters, the HV power supply and the interlock system. Tests were performed
14 without and with the mu-metal shield. The test made use of the DAQ components described in sec-
15 tion 6, including the shaper, FEM, trigger card, control card, and server. The MicroBooNE trace
16 impurity monitors were also used.

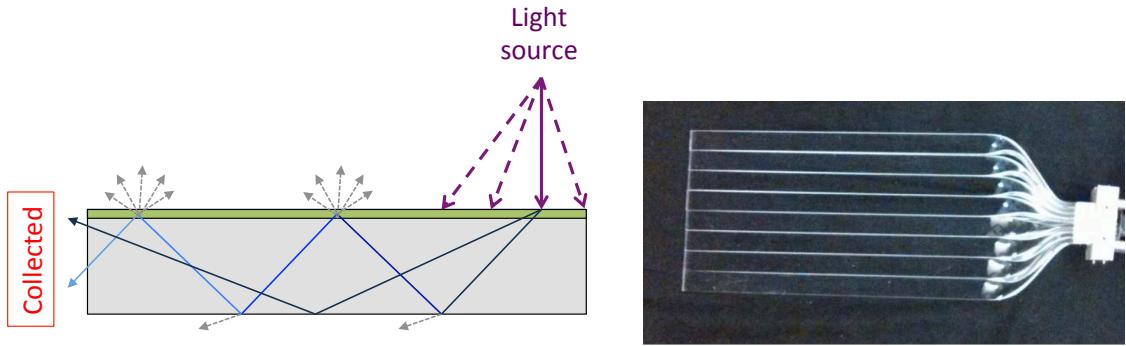


Figure 42: Left : Illustration of guiding mode, used by the paddles. Right: photograph of a coated paddle.

1 The VST informed the final design of many components, as well as producing results relevant
 2 to understanding the running conditions and performance expectations. For example, during studies
 3 of the response of the slice to 128 nm scintillation light from the alpha source, valuable information
 4 was gathered on the single photo-electron dark rate and cosmic ray rate that could be scaled to the
 5 MicroBooNE detector expectations. As a second example, these runs allowed characterization of
 6 the pulse shape nonlinearities of the optical units, as seen in figure 41. These were shown to be
 7 significant at \sim 300 photo-electron in pulse amplitude. Full amplitude saturation occurred at \sim 670
 8 PE. Thus, it is concluded that for pulses of more than 300 PE, pulse shape cannot be described by
 9 linear superposition of single photoelectron pulses.

10 5.4 Secondary System: Acrylic Light Guides for R&D

11 A secondary light collection system consisting of four lightguide paddles was also installed. This
 12 concept has several advantages for future large detectors such as DUNE. First, the collection area
 13 per channel is larger than the optical units, providing more coverage for the same number of elec-
 14 tronics channels, cables, and feedthroughs. Second, the detectors have a flat profile so they can
 15 be slid between chambers in a multi-LArTPC detector, minimizing space requirements of the light
 16 collection system. In the case of MicroBooNE, the design gradually guides light in bent acrylic
 17 bars to a PMT. This design was an early alternative to a perfectly flat design that guides the lights
 18 to SiPMs. Running this system will provide long-term information on performance of lightguide
 19 based systems. It also enhances the MicroBooNE dynamic range, since the lightguide detectors
 20 saturate at a much higher light level than the optical units.

21 In the case of the lightguides, the 128 nm light is absorbed and shifted by a clear wavelength-
 22 shifting coating, and the re-emitted light is guided to a 2-inch Hamamatsu R7725-MOD PMT, as
 23 illustrated in figure 42, left. The installed paddles consist of six bars. A photograph of one coated
 24 paddle with eight bars is shown in figure 42, right. The active length of each bar is 20 inches. This
 25 system was added for R&D purposes and made use of 8 spare channels available of HV, cables,
 26 feedthroughs, and electronics. The impedance of the 2 inch PMTs, tested at the feedthrough, was

1 $4.89 \pm 0.01 \text{ M}\Omega$. As shown in figure 30, each paddle is installed next to an optical unit for direct
2 comparison of performance.

3 The coating requirements for plate assemblies and light guides are different, and so the com-
4 position and coating methods for each were separately optimized. In the case of the light guide
5 coatings, the figure of merit is the light emitted in guided mode. Guided mode light is the light
6 that is detected at one of the ends of a test sample, which is orthogonal to the illuminated face of
7 the sample. In addition to the wavelength-shifting efficiency of the active layer, the detected light
8 yield is affected by the reabsorptive and scattering losses in the coating as visible light propagates
9 along the bar. The light guide assemblies have a TPB coating of 33% TPB to 67% UVT acrylic
10 by mass, also with ethanol surfactant. The coating is applied as a single layer and the TPB re-
11 mains suspended in the acrylic matrix as the coating dries, leading to a smooth, visibly transparent
12 surface. The performance and attenuation behavior of similar light guides to those installed in Mi-
13 croBooNE were studied experimentally in [53]. The reported non-exponential attenuation suggests
14 that surface losses dominate over bulk losses as the attenuation mechanism, and that the fractional
15 loss per reflection within the light guide is of order 2-3% [74].

16 In the light guide coatings, the TPB is suspended in an acrylic matrix which leads to a slight
17 broadening of the emission spectrum compared to the spectrum from the plates. This is an ex-
18 pected effect—TPB fluorescence has been shown to have dependence upon its microenvironment
19 [77, 78, 73, 79, 80], and reference [73] demonstrated spectral broadening in the presence of a
20 polystyrene substrate. Using the monochromator described for the plate spectrum studies, the light
21 guide coating spectrum was measured in guided mode. A 10 cm section of light guide, with the
22 incident beam perpendicular to the TPB coated surface, was used. Based on reference [73] it is ex-
23 pected that the emission spectrum for the light guide coating, with TPB embedded in the substrate,
24 will not change significantly as it cools to 87 K. The expected efficiency for the light guide coating
25 is found to be 0.25 ± 0.05 emitted visible photons per incident 128 nm photon.

26 **5.5 Calibration**

27 The flasher system for the optical units and the light guides is described in reference [58]. This
28 system was developed to check the timing of the installed optical units, exercise the optical units
29 during construction and commissioning, and to calibrate them once the detector is operational. The
30 reference provides engineering drawings and details. The system is briefly summarized here.

31 A control board pulses an array of 400 nm LEDs, each of which is coupled through an optical
32 feedthrough to 10 m optical fibers within the cryostat. The custom feedthrough/patch panel design
33 encases the fibers in Arathane CW 5620 blue with HY 5610 hardener. The internal fibers are Molex
34 FVP polyimide fibers with diameter of 600 mm, cladding of $30 \mu\text{m}$, and an additional buffer layer
35 of $25 \mu\text{m}$. Each PMT has an individual calibration fiber. Each fiber is routed along the rack and
36 attached to the PMTs by a fiber holder constructed of an aluminum standoff with a nylon-tipped
37 set screw at a distance of about 2 inches from the PMT glass.

38 Figure 44 shows the results of flasher tests on all 32 optical units and four PMTs on the paddles.
39 Time is along the x axis and PMT channel number is along the y axis. The white region separating
40 the optical unit PMTs from the paddle PMTs represents unused channels. The colored bars indicate
41 charge detected in the PMTs during flashing. One can see that all tubes respond properly.

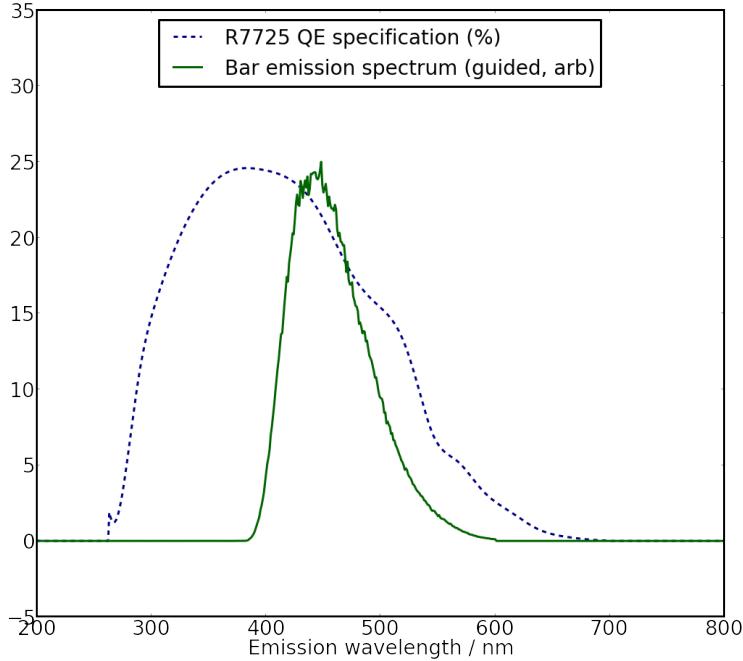


Figure 43: Measured emission spectra of the light guide coating in guided mode, and the R7725 quantum efficiency. Only the quantum efficiency of the non-undercoated PMT model is shown, from [81].

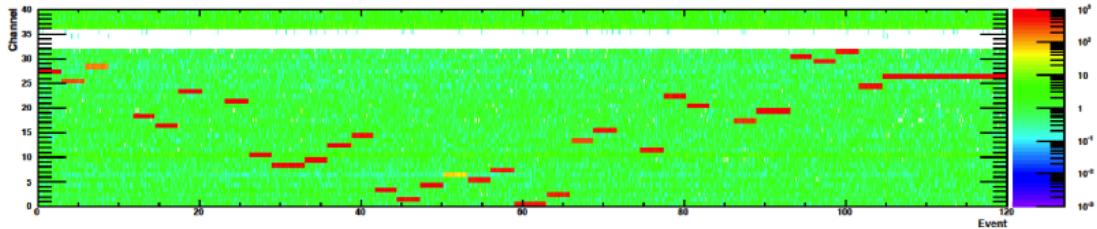


Figure 44: Charge detected in each PMT due to flasher tests, shown as a function of time. Each PMT is flashed for a short period. The white band indicates unused channels.

5.6 Coupling of PMT Signals to the Anode Wires

The ICARUS detector has observed an unexpected cross-talk between their PMTs and collection wire plane [82]. The Argontube test stand at the University of Bern also observed this effect [83]. Therefore, while the LArTPC was under final testing, before being rolled into the cryostat, an experiment was devised in order to determine the implication of this cross-talk for MicroBooNE. One of the production 8" Hamamatsu R5912-02mod PMTs was placed 5" from the LArTPC collection wire plane. This PMT was encased in a dark box with an optical fiber delivering light from a LED flasher. The collection wire plane was read out using a DAQ test-stand that reflects the final DAQ design.

A clear signal was observed on the collection plane when the LED fired. The magnitude of the

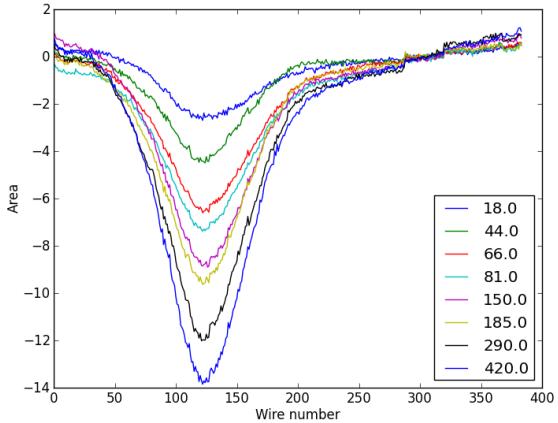


Figure 45: Area of signal pulses recorded on collection plane (in arbitrary units) as a function of wire number (arb. offset). The legend indicates the calibrated photo-electron count. The signal pulses are averaged over 50,000 repetitions. The plots are pinned together at wire 300, as the distribution baseline fluctuated over the course of the experiment due to intermittent noise.

1 signal was characterized as a function of photo-electron count (figure 45) and separation between
 2 the PMT and wire-plane. The signal induced on the collection plane was estimated to be no more
 3 than ~ 10 ADC counts for a cosmic ray under normal operating conditions. This was reduced
 4 to ~ 2 ADC counts when the PMT was encased in the μ -metal shields. This was deemed an
 5 acceptably small amount that further shielding was not required.

6 The effect appears to saturate with photo-electron count, and is reduced when shorting the
 7 resistors between the anode and last dynode. A later test with Argontube showed that the signal
 8 was drastically amplified when using capacitors not able to withstand cryogenic temperatures in
 9 the PMT base [83]. This suggests that the effect is electrostatic in nature, and probably due to
 10 capacitive coupling between the PMT and wire-plane. This is also suggested by the similarity
 11 between the signals observed and those produced by anode-coupled readout of a light collection
 12 system [59].

13 **5.7 Initial Performance of the MicroBooNE Light Collection System**

14 The system was first powered on after the cryostat had been filled with liquid argon. All the PMTs
 15 in both the primary and secondary system were found to be operational. Figure 46 shows the
 16 waveforms for all the PMT channels around the time that a large pulse, potentially from a cosmic
 17 ray muon, is observed. After initial checks of the system's health, the single photoelectron response
 18 of each PMT was set such that a one photo-electron pulse has an amplitude of 20 ADC counts as
 19 seen by the PMT readout system. The flasher LED system, described previously, is used to set this
 20 response. Figure 47 shows a candidate single photoelectron pulse following arrival of a TTL logic
 21 pulse driving the LED flasher system. The LED light level is set so that the majority (about 80%)
 22 of waveforms see no response in the region where pulses from the LED are expected to occur. This
 23 ensures that for windows with pulses, the pulses are of single photoelectrons. Figure 48 shows an
 24 example of the area vs. maximum amplitude of such pulses seen by a PMT during the flasher runs.

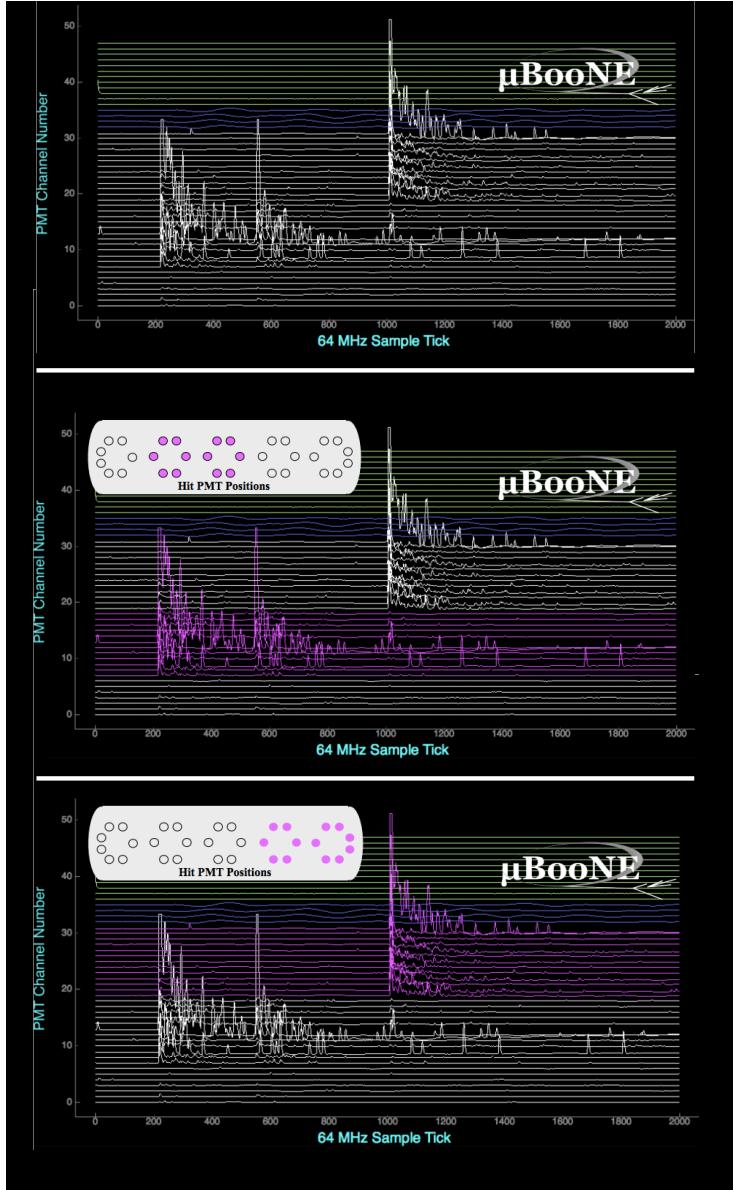


Figure 46: Top: Example waveforms from all 32 PMTs of the primary light collection system over a 31.25 microsecond readout window. The waveforms from the PMTs are in white. The blue waveforms are from the secondary lightguide PMTs, which are off in this picture. Waveforms from channels reserved for logic inputs are shown in green. In this image, the PMTs see two successive flashes of light at different parts of the detector. Middle and Bottom: Magenta highlights the early and late pulse, with the insets showing the PMTs which fired. Each pulse is likely from two cosmic ray muons traveling through the detector.

6. Electronics and Readout Systems

The analog signals that develop on a LArTPC during its operation must be amplified, digitized, and written to disk for use in analysis. Custom low-noise electronics that are capable of operating

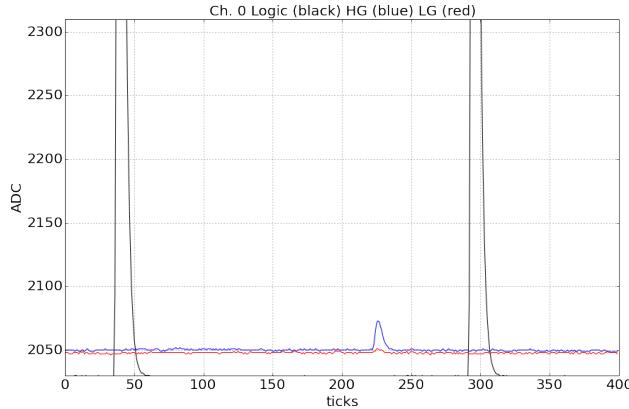


Figure 47: Example waveform captured by the PMT readout electronics during single photoelectron calibrations. The black waveform is of logic pulses that mark time at which an LED in the flasher system is driven. After some delay coming from PMT cable lengths and the flasher system, a candidate single photoelectron pulses is seen.

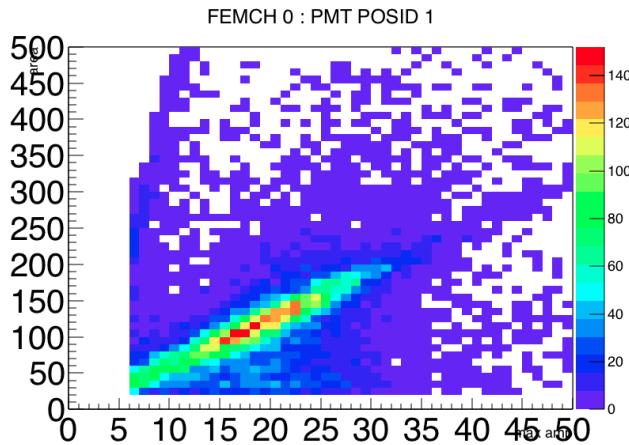


Figure 48: Distribution of the maximum amplitude and charge of pulses collected during an LED flasher calibration run. The central distribution of events is due to single photoelectron pulses.

in the liquid argon environment have been developed for this purpose in MicroBooNE. The data from these LArTPC electronic channels, as well as from the PMTs, is sent to a readout system that digitizes and organizes the information before passing it along to a Data Acquisition (DAQ) system that stores it on disk. The stages of signal processing are illustrated in figure 49. The following subsections describe the LArTPC cold electronics, the LArTPC and PMT readout electronics systems, and the DAQ system in more detail. Details of triggering capabilities available in MicroBooNE are also provided in this section.

6.1 Cryogenic Low-Noise Electronics

To obtain optimum detector performance, MicroBooNE uses cryogenic low-noise front-end electronics for readout of the LArTPC. To reduce electronic noise, the interconnection length between the LArTPC wires and preamplifier should be as short as possible thus minimizing the total capaci-

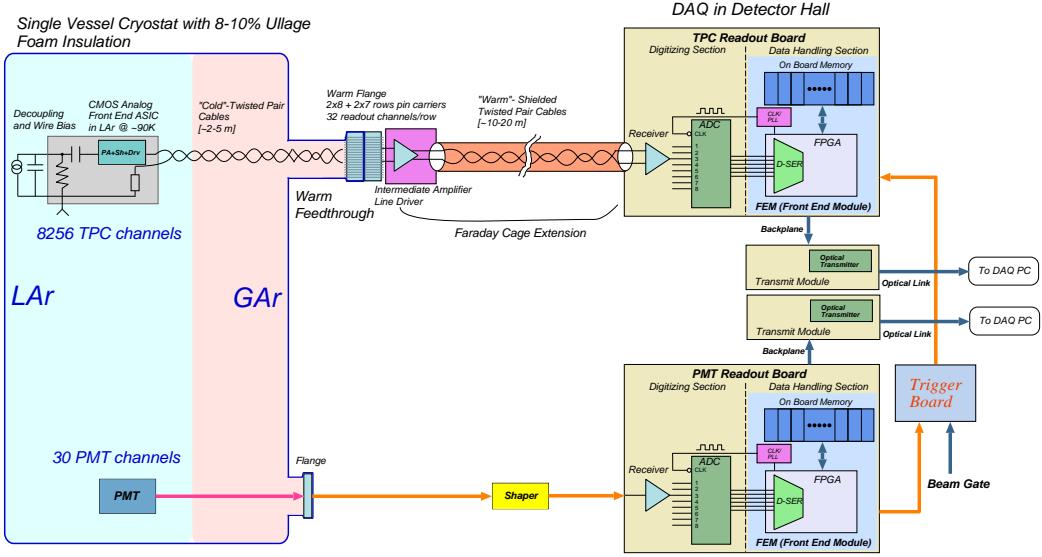


Figure 49: MicroBooNE LArTPC and PMT signal processing and readout stages.

1 tance seen at the preamplifier input. To accomplish this, the analog front-end ASICs, which include
 2 a preamplifier, shaper, and signal driver are located inside the cryostat in addition to the wire bias
 3 voltage distribution system, decoupling capacitors, and calibration networks. The front-end ASIC
 4 and associated circuits are implemented on a cold mother board which is directly attached to wire
 5 carrier boards on the LArTPC itself. Cold cables are used to transmit output signals from cold
 6 motherboards to warm interface electronics installed on the top of signal feed-through flanges.

7 6.1.1 CMOS ASIC

8 The analog front end ASIC is designed in 180 nm CMOS technology, which integrates both the
 9 preamplifier and shaper on a single chip. Each chip has 16 channels to read out signals from 16
 10 wires. Each channel also has a charge injection capacitor for precision calibration. In MicroBooNE,
 11 the shaper has four programmable gain settings (4.7, 7.8, 14 and 25 mV/fC) and four programmable
 12 peaking time settings (0.5, 1.0, 2.0 and 3.0 μ s) that provide increased flexibility to the readout
 13 system. The ASIC also has programmable baseline settings (200 or 900 mV) to accommodate
 14 different detection wire configurations: either collection or induction plane. It has a selectable
 15 AC/DC coupling mode with a 100 μ s time constant for the AC coupling mode which can be used
 16 to reduce low frequency noise. The ASIC also has built-in band-gap reference and temperature
 17 sensors to facilitate biasing and monitoring.

18 The CMOS ASICs consume only 6 mW/channel in its default configuration. The front end
 19 ASICs of the entire detector generate 50 W of heat load that is easily handled by the cryogenics
 20 system. Design guidelines that constrain the electric field and the current density to address the
 21 lifetime of CMOS devices operated at cryogenic temperatures have been applied to every single
 22 transistor (total \sim 15,000 transistors) in the ASIC design. A picture of the layout of the CMOS
 23 ASIC is shown in figure 50. Test results agree well with simulations and indicate that the ana-

- ¹ log and the digital circuits (including the digital interface) operate as expected in the cryogenic
² environment.

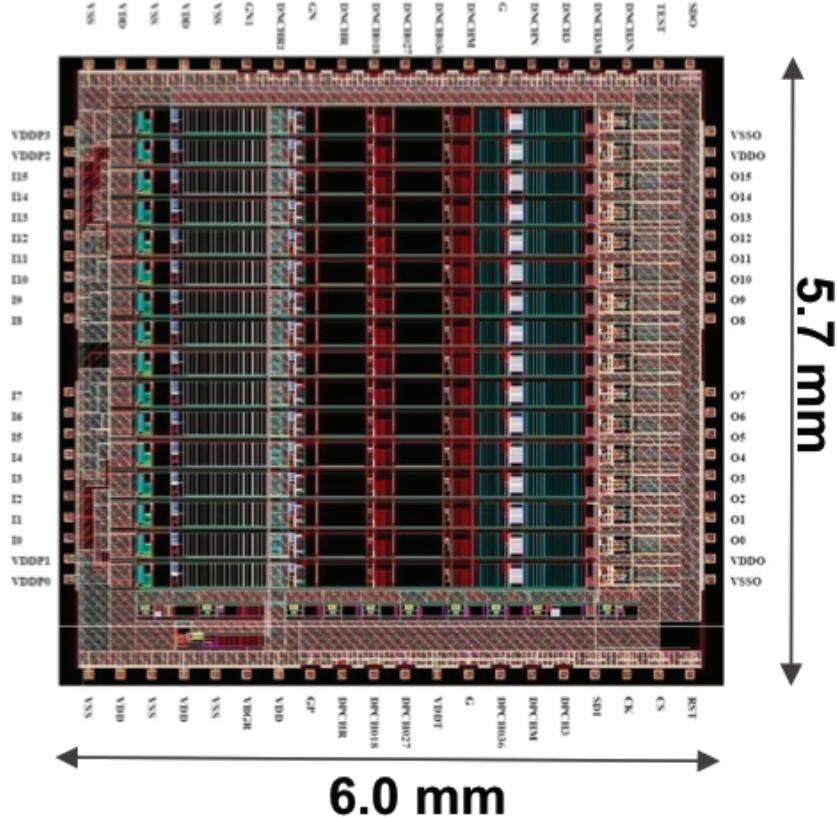


Figure 50: Layout of the CMOS analog front end ASIC

The MicroBooNE LArTPC has 8,256 readout channels and a total of 516 CMOS ASICs are required to fully instrument the detector. The production testing of the CMOS ASICs required two steps: both a warm and cold test. The warm test was performed with a dedicated test board housed in a Faraday box containing a socket to house the ASIC for ease in chip exchange. All programmable parameters (gain, peaking time, baseline, AC/DC coupling etc.) were exercised with the warm test setup for careful screening at room temperature. The yield of the warm testing of the ASICs was 89%. ASICs must have passed the warm test before going through cold testing. The cold test was performed with a dedicated test board containing 6 sockets to facilitate testing of multiple chips in liquid nitrogen at the same time. A total of 201 ASICs went through cold testing with a yield of 97%. Based on this high yield, it was decided not to continue the cold screening test on the rest of the production chips, as they were tested cold after being installed on the motherboard. After enough (\sim 600) ASICs passed the production screening test, they were sent to an assembly house to equip the cold motherboard.

16 6.1.2 Cold Motherboards

¹⁷ A cold motherboard was designed to house the MicroBooNE CMOS ASICs. In this capacity,
¹⁸ the motherboard provides signal interconnections both between the detector wires and preampli-

fier inputs as well as between the driver outputs and cold cables to the signal feed-through. The
 2 cold motherboard design provides sufficient protection of the ASICs against electrostatic discharge
 3 during installation. It also provides a calibration network and bias voltage distribution for the
 4 wire planes. Specifically, a calibration signal enters the cryostat via a feed-through and reaches
 5 the preamplifiers through the motherboard. Each preamplifier channel in the ASIC has a built-in
 6 switch to individually cycle the calibration injection. The bias voltage reaches the LArTPC wires
 7 via a two-fold redundant path on the motherboard that allows the detector to operate normally even
 8 if one bias voltage channel fails. As with the PMT bases, the cold motherboards use Rogers 4000
 9 series as the PC-board material due to the cleanliness and thermal properties previously described
 10 in section 5.2.1. The different positions of the wire attachments along the top and sides of the
 11 LArTPC requires 2 types of cold motherboard. The top version of the motherboard has 192 read-
 12 out channels that includes 96 Y channels, 48 U channels, and 48 V channels. The side version
 13 of the motherboard has 96 readout channels that are either U or V channels. A picture of the top
 14 version of a cold motherboard with 12 mounted ASIC chips is shown in figure 51.

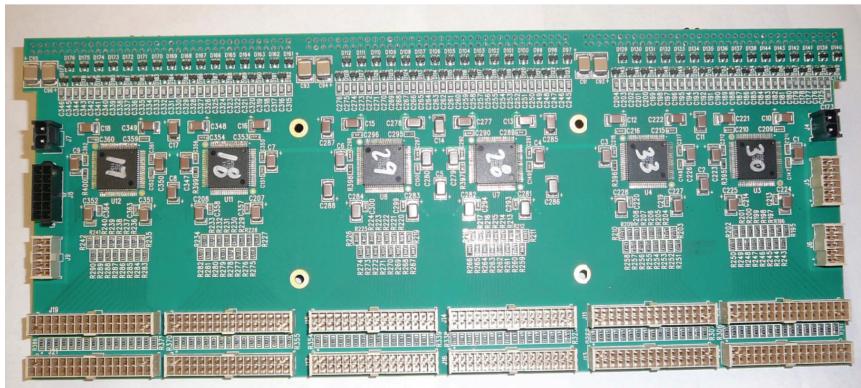


Figure 51: Top version of cold motherboard with 12 ASIC chips, including 6 chips mounted on top layer and 6 chips on bottom layer.

15 The MicroBooNE LArTPC required a total of 36 top version motherboards and 14 side version
 16 motherboards to instrument the full detector. A test stand was built for testing of the front end
 17 electronics. This test stand included a full readout chain from the cold motherboard, cold cable,
 18 signal feed-through, warm interface electronics, warm cable and Receiver ADC board to a DAQ
 19 board based on a Xilinx ML605 FPGA evaluation board which sends acquired data to a PC over
 20 a Gigabit Ethernet. The production test of each motherboard also involved both a warm and cold
 21 test. Both tests used the same test stand, except the motherboard was placed in a Faraday box for
 22 the warm test and submerged in a liquid nitrogen dewar for the cold test. Noise, gain, peaking
 23 time, and linearity parameters were measured in both warm and cold to screen the motherboard.
 24 Motherboards had to pass both tests before being installed on the detector.

25 **6.1.3 Cold Cables**

26 Cold cables transmit the detector signals from the cold motherboard to an intermediate amplifier
 27 on top of the signal feed-through and distribute power to the CMOS ASICs. The cold cable is a
 28 custom-built 32-pair twisted pair flat ribbon cable with Teflon FEP insulation and $100\ \Omega$ ($\pm 10\%$)

1 impedance, using AWG 26 stranded wire with silver-plated copper. Custom designed shells with
2 jack screws used in the cable assembly ensured proper alignment of the insertion on the signal feed-
3 through pin carriers. Cold cables of two different formats were assembled by an assembly house:
4 signal cables and service cables. Signal cables are used to transmit amplified detector signals while
5 the service cable is used to transmit calibration pulses and slow control/monitoring signals. Signal
6 cables were produced in three different lengths: 203 cm, 254 cm, and 457 cm to accommodate
7 the different lengths between the cold motherboards and the signal feedthroughs, while the service
8 cables were produced in two different lengths: 254 cm and 457 cm. All of the cold cable assemblies
9 were tested with a cable tester in the assembly house before they were shipped out. In addition,
10 10% of the cold cables were tested in the test stand at BNL to confirm the quality of the cable
11 assembly.

12 **6.1.4 Electronic Calibration**

13 The MicroBooNE cold electronics include a precision charge calibration system. Through the cold
14 cable and calibration network on the motherboard, a calibration signal enters the cryostat via a
15 feed-through and reaches the preamplifiers. A built-in switch in the ASIC makes it possible to
16 power cycle the calibration injection for every channel individually. The electronics calibration is
17 based on charge injection through known capacitances (180 fF) in the ASIC. This system enables
18 gain (charge sensitivity) calibration, verification of sense wire integrity and noise measurements.
19 The built-in electronics calibration capability is an important tool in testing and characterizing the
20 overall performance of the detector readout system. It was extensively used in the cold electronics
21 production testing and the electronics checkout during installation, commissioning, and data taking.

22 **6.1.5 Performance Tests**

23 The development of the analog front end ASICs was initiated using 180 nm CMOS technology
24 and 300 K models, though the performance parameters are extracted at 77 K. CMOS was found
25 to function at cryogenic temperatures with increased gain and lower noise. The noise, gain, and
26 pulse shaping were found to be as expected in evaluation tests of the ASICs. Extensive testing of
27 the ASICs mounted on the motherboards was performed; these tests were done in liquid nitrogen
28 rather than at room temperature, since noise levels and characteristics of the ASIC performance in
29 liquid nitrogen are similar to the performance in liquid argon. Thus, cold tests were performed on
30 all production cold motherboards fully populated with 12 chips. A total of \sim 2,200 chip-immersions
31 were accumulated in liquid nitrogen without any failures due to thermal contraction or expansion.

32 The test results show the noise of the front end readout electronics system decreasing uni-
33 formly for all 768 channels from \sim 1,200 e^- at 293 K to less than 600 e^- at 77 K with 150 pF
34 detector (sense wire) capacitance. A plot of noise versus temperature of 12 ASICs for a total of
35 192 channels is shown in figure 52. The response of the front end electronics exhibits excellent uni-
36 formity at cryogenic temperatures. As shown in figure 53, the gain variation of a cold motherboard
37 with 12 ASICs is only 7% peak-to-peak across 192 channels. The spread of the gain variation is
38 only 1% of the gain setting.

39 **6.2 Warm Electronic Amplification**

40 Signals from the cold electronics are carried over the cold cables to dedicated feedthroughs mounted

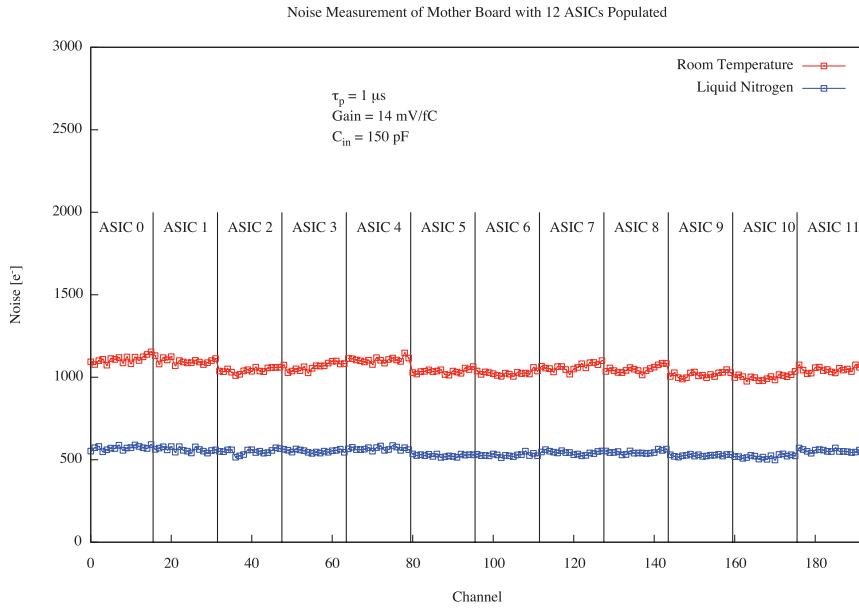


Figure 52: Plot of noise vs. channel number for 192 channels (12 ASICS) and at two different temperatures. Noise is $\sim 1,200 \text{ } e^-$ at 293 K, and $\sim 550 \text{ } e^-$ at 77 K with $150 \text{ pF } C_d$

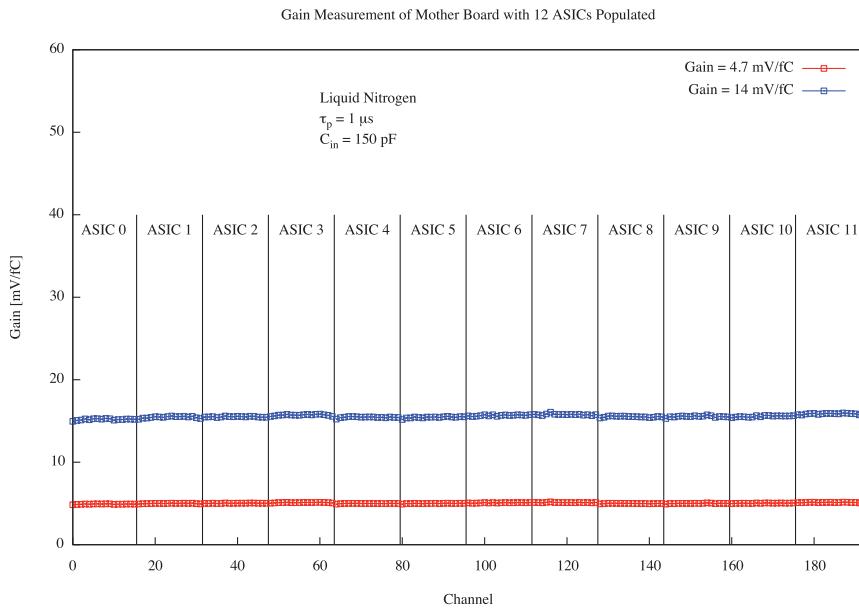


Figure 53: Plot of gain uniformity of 12 ASICs, total 192 channels, at 77 K with two different gain settings

- ¹ on the cryostat. The cold cables are connected to pin-carriers located on 356 mm outer-diameter
- ² CF signal feedthrough flanges that are mounted on nozzles N1A-N1K of the cryostat (see figure

1 5). The signal feedthrough design must accommodate 100% hermeticity and high signal density.
 2 A design based on the ATLAS pin carrier style was developed for this purpose. Two 8-row pin
 3 carriers and two 7-row pin carriers are welded onto the CF flange, as shown in figure 54, and create
 4 a vacuum-tight seal. Nine of the 11 signal feedthroughs receive signals from the three LArTPC an-
 5 ode planes (384 Y-plane, 192 U-plane, 192 V-plane), while the remaining two on the extreme ends
 6 of the cryostat only receive signals from one of the angled induction planes (672 U-plane on one
 7 feedthrough, 672 V-plane on the other).

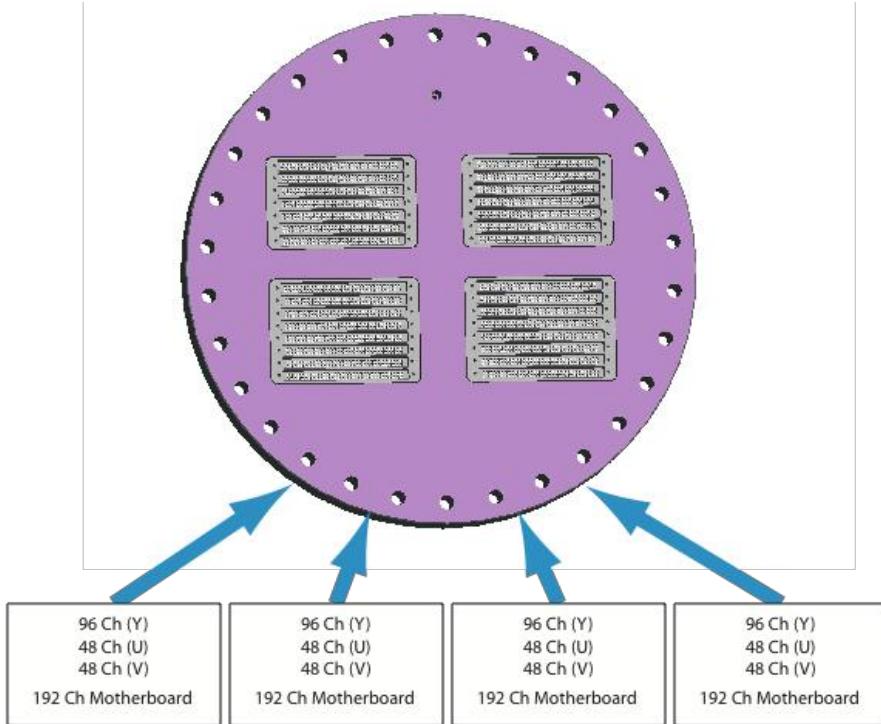


Figure 54: Signal feedthrough flange consisting of a 356 mm CF flange with two 8-row and two 7-row pin carriers welded in place.

8 A Faraday cage is mounted on the external, warm, side of the signal feedthroughs to provide
 9 shielding for the intermediate amplifiers located inside. The bias voltage feedthrough, which sup-
 10 plies anode plane bias voltages into the cryostat, is built onto a small 70 mm CF flange welded
 11 onto the signal feedthrough flange. A filter board mounted on the bias voltage flange filters noise
 12 and ensures a good ground connection. Figure 55 shows details of the signal feedthrough assembly
 13 with electronics boards, bias voltage feedthrough, and Faraday cage.

14 The intermediate amplifiers provide \sim 12 dB gain to the LArTPC signals to make them suit-
 15 able for transmission over a 20 m long cable to the readout electronics (see section 6.3). Each
 16 intermediate amplifier has 32 channels installed on the signal feedthrough flange and housed inside
 17 the Faraday cage to provide noise isolation. Figure 56 shows a picture of a prototype interme-
 18 diate amplifier plugged on the signal feedthrough pin carrier. The intermediate amplifier uses a 68-pin
 19 SCSI-3 connector to drive the 32 channels of signal differentially for better noise immunity. The

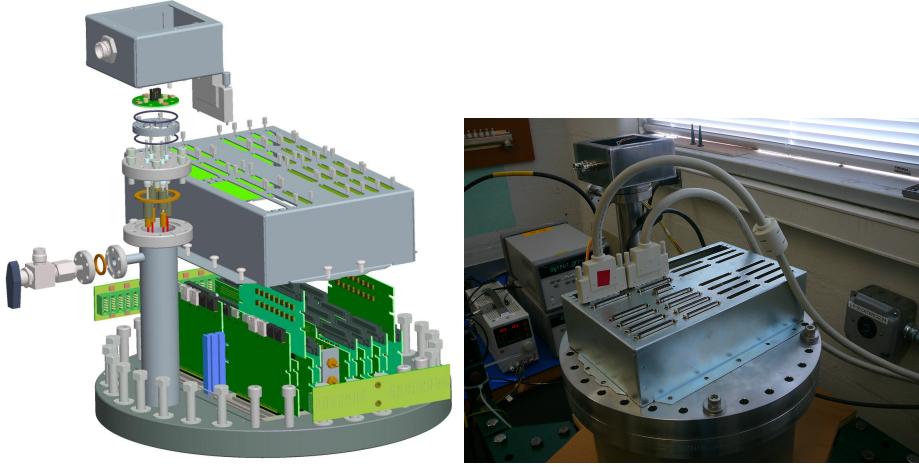


Figure 55: Left: Diagram of the signal feedthrough assembly, which includes intermediate amplifiers, Faraday cage, bias-voltage feedthrough and filtering circuit. Right: Photograph of one of the feedthrough assembly, partially constructed and being tested.

1 layout and connector position have been carefully designed to ensure the card can be plugged on
2 the pin carrier in either direction. This efficiently utilizes the limited available space on the top of
3 the feedthrough, which also makes the design of the Faraday cage easier.

4 In addition to the intermediate amplifiers, there are two service boards mounted on the top of
5 each signal feedthrough. The service board provides regulated low voltage, control and monitoring
6 signals to the analog front end ASICs. It also provides pulse injection to the preamplifiers for
7 precision calibration. The control, monitoring, and calibration signals are provided to the front end
8 electronics with two-fold redundancy. Should one set of signals become defective the detector can
9 still operate normally with the redundant set. Each service board plugs onto a 64-pin carrier row.
10 Figure 56 shows a picture of a prototype service board.



Figure 56: Left: Photograph of one of the intermediate amplifier boards plugged into a pin carrier during testing. Right: Photograph of a prototype service board.

1 6.3 Readout Electronics

2 The MicroBooNE readout electronics system consists of two subsystems: the LArTPC and PMT
3 readout electronics. The LArTPC readout electronics are responsible for the readout, digitization,
4 and processing of the induction and collection wire signals after amplification. The PMT readout
5 electronics are responsible for the amplification, shaping, digitization, and handling of PMT sig-
6 nals, as can be used to provide a trigger signal for the readout and data acquisition systems. While
7 the LArTPC and PMT readout systems share the same back-end design that organizes and packages
8 the data for delivery to the DAQ system, they employ different analog front-end and digitization
9 designs, which are described in this and the following subsection.

10 The LArTPC readout electronics are responsible for processing the signals from the 8,256
11 wires in MicroBooNE after pre-amplification and shaping in the cold electronics, as described in
12 section 6.1. The pre-amplified and shaped analog signals from the cold electronics are transmitted
13 to the warm electronics outside the cryostat, as described in section 6.2, and then passed to custom-
14 designed LArTPC readout modules distributed evenly over nine readout crates. The readout mod-
15 ules digitize the analog signals and then process and prepare them for shipping to designated DAQ
16 machines (one per readout crate), described in section 6.6.

17 The LArTPC readout crates communicate with the DAQ machines via three duplex 3.125 GB/s
18 optical links that connect to a crate controller module and data transmitter (XMIT) module on the
19 crate end, and to three PCI Express boards on the DAQ machine end. The controller is responsible
20 for configuration, trigger and run control command distribution as well as the slow monitoring of
21 each readout crate. The controller occupies one of the optical links while the XMIT is responsible
22 for sending two separate streams of readout data to the DAQ machines via the two other optical
23 links. The first XMIT stream contains losslessly compressed LArTPC data associated with event
24 triggers received by the LArTPC readout crates, such as the BNB trigger, and is referred to as the
25 “NU” data stream. The second stream is a continuous LArTPC data stream which is compressed
26 with some data loss. The continuous data stream is used for beam-unrelated physics analyses, such
27 as the study of potential supernova neutrino events, and is referred to as the “SN” data stream. The
28 compression schemes used in the NU and SN streams are described in section 6.3.3.

29 All readout crates are synchronized to a common 16 MHz clock. The clock sync is provided
30 by a clock fanout board which shares the same ground as all readout crates, and is sent via coaxial
31 cable to a distribution board which is mounted on each crate backplane. The readout frame size
32 is set to 1.6 ms, which is equivalent to the time it takes for charge produced on the far end of the
33 LArTPC to drift to the wire planes at the design cathode voltage of -128 kV.

34 6.3.1 Data Digitization

35 The amplified and shaped analog LArTPC signals are differentially received and digitized in the
36 first section of the readout modules. Each ADC module holds 8 AD9222 octal-channel 12-bit
37 ADCs. Each ADC module handles signals from 64 wires. The wire signals are grouped in two
38 sets of 32 consecutive wire channels: either 32 induction wires plus 32 collection wires or two sets
39 of 32 induction wires. The induction channel sequence alternates wires between the two induction
40 planes. The ADC module digitizes the signals continuously at 16 MHz. Each channel has a config-
41 urable baseline, which is either set low (450 ADC counts) for collection channels or at the middle

1 of the dynamic range (2055 ADC counts) for induction channels, thus ensuring that both the collection
2 plane unipolar differential signals and the induction plane bipolar differential signals can make
3 use of the full ADC analog input range. The requirement to observe a MIP produced at the far end
4 of the LArTPC in the induction plane determines the lower end of the dynamic range, while the
5 requirement to observe a highly-ionizing stopping proton at the close end of the LArTPC without
6 saturation sets the upper end. The digitized outputs from the ADC board are passed directly to a
7 Front End Module (FEM) in the second section of the LArTPC readout module. The FEM houses
8 an FPGA for data processing, data reduction, and preparation for readout by the DAQ system as
9 described in the following section.

10 **6.3.2 Data Handling**

11 The FEM board consists of a 14-layer printed circuit board which is mechanically integrated with
12 the ADC board as illustrated in figure 57. The choice of a smaller board allows for short trace
13 lengths which is beneficial for high speed signals. The full assembly comes together as a standard
14 VME 9U card in height, with a 280 mm depth. Differential outputs from the ADCs connect to the
15 FPGA through HM-Zd connectors that have individual ground shielding on each differential pair.

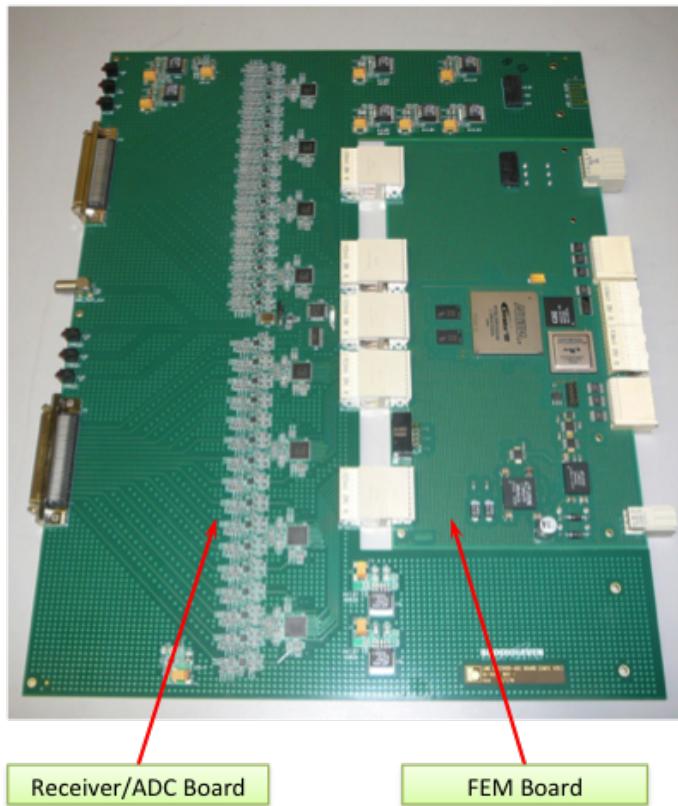


Figure 57: LArTPC ADC+FEM board.

16 The digitized data stream moves from the ADCs to a Stratix III Altera FPGA, which reduces
17 the sampling rate of the ADC from 16 MHz to 2 MHz. The 2 MHz sampling rate is optimized by
18 taking into consideration the expected pulse shape provided by the convolution of the cold electron-

ics, the expected LArTPC field responses, and the $O(1\mu s)$ diffusion effects which govern charge drift within the liquid argon. The FPGA stores the data from all 64 wires per board sequentially in time in a $1M \times 36$ bit 128 MHz SRAM, grouping two ADC words together in each 36 bit memory word. This requires a data storage rate of $(64/2) \times 2$ MHz = 64 MHz. The SRAM chip size and memory access speed allow for continuous readout of the LArTPC data. Since data reduction and compaction algorithms rely on the sequential time information of a given wire, the data readout out from this SRAM takes place in wire order in alternate clock cycles, again at the rate of 64 MHz. This read in/out sequence is illustrated in figure 58.

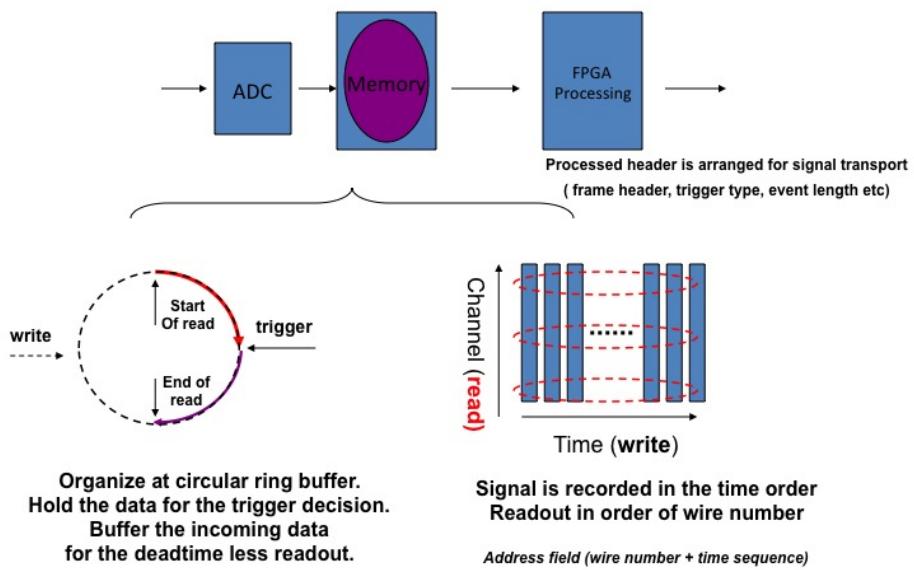


Figure 58: LArTPC readout sequence in the TPC FEM.

Separate DRAM multi-event buffers on the FEM store the NU and SN data streams. The data divert into the NU readout stream when a trigger is issued and received (as shown in figure 59) which signals, for example, an accelerator neutrino-induced event. When an event trigger is received, 4.8 ms worth of data, relevant to that event, are packeted per channel and sent to the DAQ through the NU data stream. The 4.8 ms readout size is governed by the maximum drift time and spans three or four frames. In order to reduce the amount of data being transmitted, the FPGA trims the three or four frames to span the exact 4.8 ms required, 1.6 ms before the trigger plus 3.2 ms after the trigger. In parallel, the data is continually sent out through the SN data stream, frame by frame. The compression and data reduction algorithms applied to each of the two streams are described in the following section.

After processing by the FPGA, the data passes to the crate backplane dataway on connectors shown in figure 57. A token-passing scheme is utilized to transfer data from each FEM board to the data transmitter module (XMIT) in a controlled way, whereby each FEM, in the order of closest to furthest from the XMIT module, receives a token, transmits its data to the XMIT, and passes the

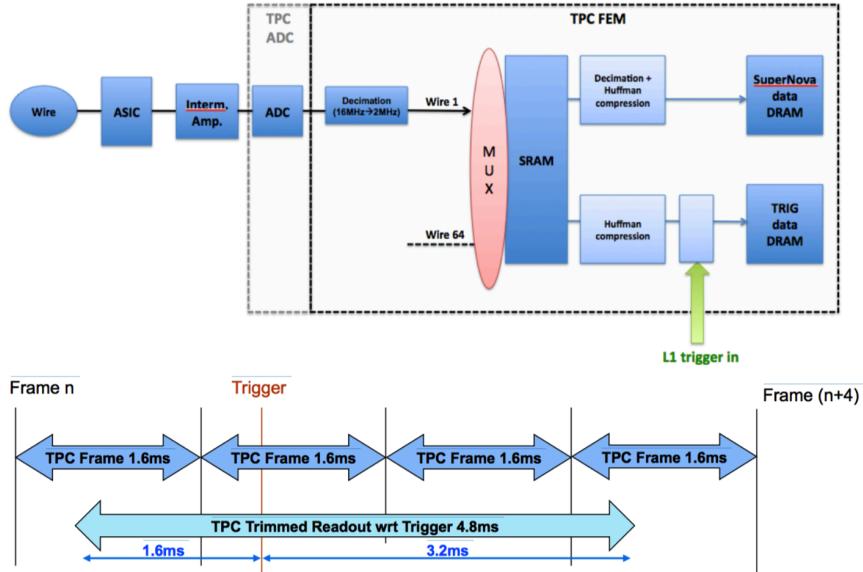


Figure 59: LArTPC trigger readout.

1 token on to the next FEM in the sequence. For the NU stream, each FEM sends all data associated
 2 with a particular trigger number; while for the SN stream, each FEM sends all data associated with
 3 a particular frame number. This data transfer is relayed via the otherwise passive crate backplane,
 4 and is limited to 512 MB/s. In the XMIT module, the data is buffered temporarily and sent to the
 5 DAQ machine through the two streams, SN and NU, which proceed effectively in parallel.

6 6.3.3 Compression Schemes

7 In the case of the NU data stream, a lossless Huffman coding scheme implemented in the FEM
 8 FPGA compresses the data by approximately a factor of five. Further reduction in the overall
 9 rate is achieved by exploiting a PMT trigger in coincidence with the BNB trigger, as described in
 10 section 6.5. Huffman coding provides for lossless data compression by taking advantage of the
 11 slow variation of the waveform TPC data in any given channel. In particular, this compression
 12 scheme relies on the fact that successive data samples on any given wire vary relatively slowly in
 13 time. As such, when noise levels are low, any two adjacent data samples either coincide or differ
 14 by 1 ADC count. The most frequent values for the difference in ADCs between successive data
 15 samples are assigned pre-specified bit patterns with the lowest number of bits possible. Those
 16 bit patterns are encoded in the 16-bit data words that would otherwise be used for a single 12-bit
 17 ADC sample value. As such, data reduction of up to a factor of 14 is theoretically possible (the
 18 uppermost two bits are always reserved for header information, in each 16-bit word). In practice,
 19 the data reduction is sensitive to noise levels and LArTPC activity, and is also dependent on the
 20 gain setting. The compression factor achieved by MicroBooNE is shown in figure 60.

21 Because of the low trigger rate (the BNB trigger dictates an upper bound on the trigger rate of
 22 15 Hz), lossless Huffman coding compression proves sufficient for the NU data stream. However,
 23 for the continuous SN stream, further compression becomes necessary, resulting in unavoidable

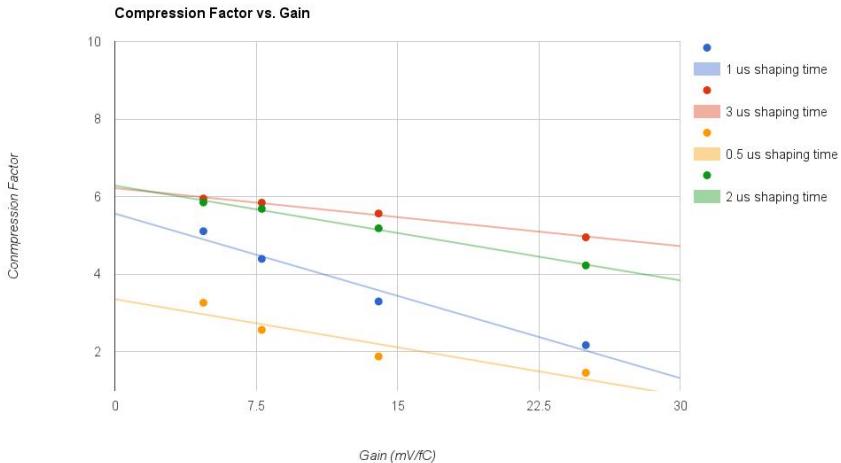


Figure 60: Compression factors achieved on ADC data with Huffman compression.

1 data loss. A method called “dynamic decimation” (DD) handles this case. The DD scheme relies
 2 on recognizing regions of interest (ROI) in the data stream that contain waveforms corresponding
 3 to drift ionization charges. Portions of the data stream not containing ROI contribute to pedestal
 4 determination, and ROI are identified as deviations from the continually-updated pedestal, buffered,
 5 and read out to disk. At the time of this writing, the MicroBooNE SN stream compression scheme
 6 is being finalized and the SN readout stream will be commissioned in September 2016.

7 **6.4 PMT Readout Electronics**

8 The PMT readout electronics are responsible for processing signals from the 32 PMTs described
 9 in section 5 and identifying light signatures coincident with the BNB and NuMI beam spills. The
 10 coincidences generate PMT triggers that can be later mixed with other triggers in the Trigger Board
 11 (TB). Signals from the 4 light paddle guides installed in the LArTPC are also recorded by the PMT
 12 readout electronics, but these signals do not participate in the PMT trigger generation.

13 The stages of signal processing are illustrated in figure 61. First, each PMT signal (with the
 14 exception of the light paddle guide signals) is split into two different gains, as described in sec-
 15 tion 5.2.5, with the HG channel carrying 18% of the PMT signal and the LG channel carrying
 16 1.8% of the PMT signal. Each gain is split once again into HG1 and HG2, and LG1 and LG2, in
 17 order to allow different processing of beam-related and beam-unrelated PMT signals. All $32 \times 2 \times 2$
 18 plus 4 signals are pre-amplified and shaped in 16-channel pre-amp/shaper boards (section 6.4.1).
 19 Four PMT readout modules receive the analog shaped signals differentially and digitize them (sec-
 20 tion 6.4.2) at 64 MHz. The PMT readout modules then process the signals in order to prepare them
 21 for shipping to a designated DAQ machine and to form a possible PMT trigger (section 6.4.3).

22 Each one of the 4 PMT ADC+FEM readout boards used in the PMT readout system handles
 23 one of the following:

- 24 • Readout of and PMT trigger generation using the HG1 PMT signals associated with neutrino
1 beam events. The paddle signals are also readout by this board.
- 2 • Readout of and PMT trigger generation using the HG2 PMT signals that are out of beam
3 time (i.e. cosmic rays and other cosmogenic backgrounds)
- 4 • Readout of the LG1 PMT signals associated with neutrino beam events
- 5 • Readout of the LG2 PMT signals that are out of beam time

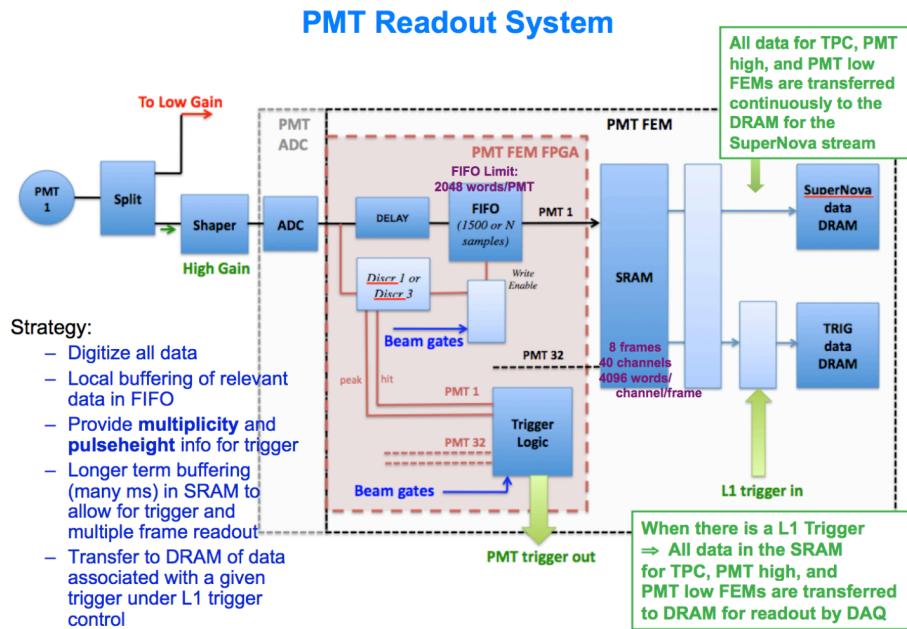


Figure 61: Signal processing in PMT FEM.

6 After signal processing, the data is sent to a designated DAQ machine via a transmitter (XMIT)
7 module in the same way as is done for LArTPC data. Two data streams are provided: a NU data
8 stream associated with event triggers and a SN data stream which a continuous version of the NU
9 stream readout.

10 6.4.1 Signal Amplification and Shaping

11 The preamp/shaper boards read raw PMT signals from the PMT HV/signal splitters and shape them
12 into unipolar signals with a 60 ns rise time. The shaped signals are sent to the LArTPC readout
13 boards differentially via short front-panel cables, in order to minimize noise, where they are digi-
14 tized at 64 MHz. The 60 ns peaking time allows digitization of two or three samples on the rising
15 edge. This in turn enables an accurate determination of the event t_0 needed to determine the x co-
16 ordinates of ionization signals along the drift direction. An accurate time measurement also helps
17 reject other tracks, such as cosmic rays, that cross the detector during the drift time.

¹⁸ **6.4.2 PMT Data Digitization**

¹ The ADC (Texas Instruments, ADS5272) module part of the PMT readout board (figure 62) is
² responsible for digitization of up to 48 differentially-driven input signals. The differential signals
³ are digitized at 64 MHz. The 64 MHz clock used by the PMT readout is generated starting from
⁴ the 16 MHz clock that is common to all readout crates (LArTPC and PMT).

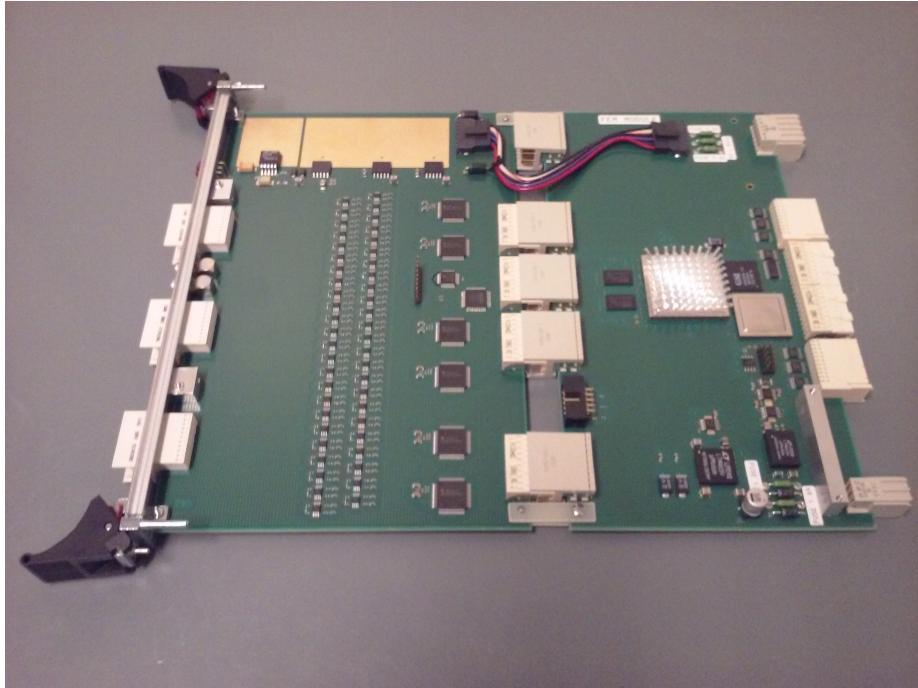


Figure 62: The PMT readout board digitizes 48 input signals.

⁵ In addition to HG and LG waveforms from the PMTs, each readout board also receives, digitizes,
⁶ and processes beam gate signal markers which arrive 4 μ s before the BNB 1.6 μ s and NuMI
⁷ 10 μ s beam gates. These gates are used to (a) specially mark regions of interest where PMT data
⁸ are read out continuously with no compression and (b) look for coincident PMT light signatures
⁹ for trigger generation.

¹⁰ **6.4.3 Data Handling and PMT Trigger Generation**

¹¹ PMT information is recorded in the NU data stream for four 1.6 ms frames associated with an event
¹² trigger: the frame containing the (asynchronous) trigger, the frame preceding the trigger frame,
¹³ and two frames following the trigger frame. To avoid the inordinate amount of data that would
¹⁴ be generated at a 64 MHz sampling rate, the FEM applies a zero-suppression immediately after
¹⁵ digitization, retaining only samples above a given threshold as well as enough information before
¹⁶ and after this useful data to establish a local baseline value; this collection of information is referred
¹⁷ to as a PMT readout ROI. An exception is formed for beam-related or other likewise-triggered data
¹⁸ where, for example, the 4 μ s-early BNB and NuMI beam gates mentioned in section 6.4.2 instruct
¹⁹ readout of 1500 consecutive samples (23.4 μ s) surrounding and including the beam gates regardless
²⁰ of signal activity.

21 Two different discriminators are used: one that is active inside the beam gate(s), and one that
1 is also active outside the beam-gate-surrounding $23.4 \mu\text{s}$. The latter discriminator governs the
2 readout activity due to cosmic rays and other non-beam related activity. The first discriminator
3 enables PMT channels with pulse heights above a configurable threshold (e.g. corresponding to 1
4 photoelectron) to participate in trigger multiplicity and pulse height sum conditions, as described
5 in the following section. The thresholds for those two discriminators are set to different levels and
6 configured with different dead times for the HG and LG signals.

7 **6.5 Level-1 Trigger Generation**

8 The TB, which physically resides in the PMT readout crate, issues a “Level-1” trigger in order to
9 flag frames that must be treated differently. In the case of the LArTPC readout, the TB flags the 4
10 frames that must be trimmed and readout through the NU data stream and, in the case of the PMT
11 readout, it flags the 4 frames that must be readout in full through the NU data stream.

12 The inputs to the TB include a BNB trigger input (maximum rate of 15 Hz), a NuMI trigger
13 input (1.25 Hz), a Fake Beam trigger input (configurable), a PMT trigger input, and two calibra-
14 tion trigger inputs, provided by the laser calibration system and the cosmic ray muon telescope,
15 respectively. The TB also has the ability to receive, via the crate controller, DAQ-issued calibration
16 triggers, which are used explicitly for cold electronics and PMT calibration. The various input
17 triggers can be independently pre-scaled, masked, and mixed together (OR or AND) to generate an
18 event trigger.

19 The FPGA firmware in the PMT FEM can generate two different types of PMT triggers based
20 on the PMT signals: a cosmic PMT trigger and a beam gate PMT trigger. Beam gate PMT triggers
21 are configured in the same way for the BNB, NuMI, and Fake Beam. The nominal criteria for these
22 triggers are (1) PMT multiplicity ≥ 1 and (2) summed PMT pulse-height ≥ 2 PE summed over all
23 32 HG1 PMT channels. Both criteria must be met during any 100 ns time interval coincident with
24 the beam spill duration ($1.6 \mu\text{s}$ in the case of the BNB and Fake Beam gates and $10 \mu\text{s}$ in the case
25 of the NuMI gate), and only channels enabled by the beam gate discriminator can participate in
26 the active pulse-height and multiplicity sums. The criteria for a cosmic PMT trigger are (1) PMT
27 multiplicity ≥ 1 and (2) summed PMT pulse-height ≥ 40 PE summed over any one of 28 preset
28 groups of 5 HG2 PMT channels that are grouped based on their spatial correlation. Again, only
29 channels enabled by the cosmic discriminators can participate in the trigger generation.

30 In addition, a software-based algorithm has been written to mimic the capabilities of the beam
31 gate PMT trigger performed in the FPGA and provide more flexibility in trigger criteria settings.
32 Details of this higher-level software trigger are described in section 6.7.

33 Figure 63 diagrams the PMT readout and trigger logic. Activation or masking of each of the
34 trigger inputs and outputs is DAQ-controlled. The trigger condition and explicit PMT trigger type,
35 if applicable, is available for every event in the NU data stream at both the event-building stage and
36 offline; this information is read out via a dedicated optical data stream, directly from the TB. The
37 trigger number and trigger time are also propagated and available in the NU data streams arriving
38 independently at the assembler DAQ machine from each LArTPC and PMT crate, and can therefore
39 be used to correctly associate data from the same event.

40 The readout control sequence is illustrated in figure 64. When a trigger is generated by the
41 TB it is passed to a fan-out module on a single cable and from there it is distributed to all crate

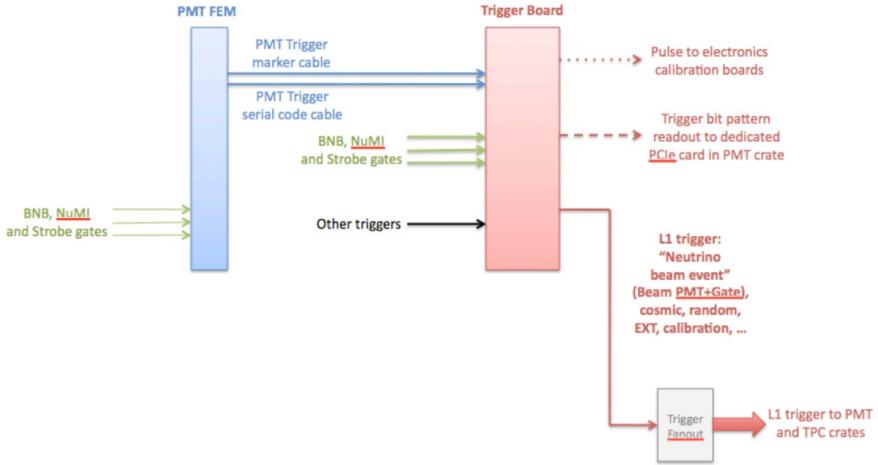


Figure 63: PMT readout and trigger logic.

42 controllers (LArTPC and PMT). Through the crate backplane, the trigger gets propagated to each
 1 FEM. An FEM that receives a trigger temporarily inhibits the SN stream with its associated deci-
 2 mation and initiates the loss-less readout scheme to direct the data to the appropriate readout path.
 3 SN readout resumes once the XMIT is done sending all NU data associated with an event to the
 4 DAQ.

5 6.6 DAQ Design

6 The MicroBooNE DAQ system acquires data from the readout electronics, writes data to local disk
 7 before transferring it to long-term storage, configures and controls the readout electronics during
 8 data-taking periods, and monitors the data flow and detector conditions. These tasks are performed
 9 on a network of commodity servers running both custom and open-source software.

10 The data from each crate of the backend electronics is sent to a dedicated server (called the
 11 sub-event buffer, or SEB) via an optical fiber, arriving in a card on the SEB's PCIe bus. A real-time
 12 application places these data in an internal buffer, collects all segments belonging to an event, and
 13 creates a sub-event fragment that may be routed to a specified destination. For the NU stream,
 14 in which the data arrives with every trigger, these fragments are sent to a single event-building
 15 machine (EVB) over an internal network. Full events are checked for consistency and written to
 16 local disk on the EVB before being sent offline for further processing. A high-level software trigger,
 17 described in section 6.7, is applied to the data to determine whether events should be written locally
 18 or ignored. For the SN stream the data remains on the SEB where it is written to disk and only sent
 19 for offline analysis on explicit requests.

20 Data writing to either triggered or SN streams is limited by the RAID6 disk write speeds
 21 which are roughly 300 MB/s. This is much less than the network bandwidth bottleneck, which is
 22 10 GB/s. The 300 MB/s disk write speed therefore sets the maximum aggregate rate at which all
 23 SEB fragments can ship data to the EVB without loss of data. With Huffman compression, which
 24 gives a data reduction of approximately a factor of five (figure 60) and the PMT trigger, which
 25 reduces the data rates by another factor of > 70 , this is more than sufficient for MicroBooNE's

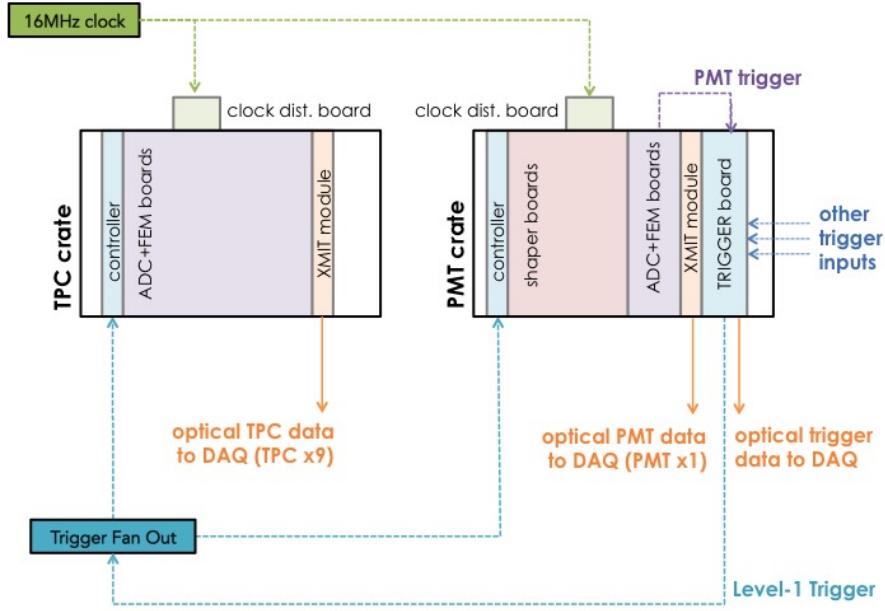


Figure 64: Readout control sequence. The MicroBooNE Level-1 trigger is a hardware trigger which consists of the OR between a BNB, NuMI, and EXT (strobe) trigger. Once received, the Level-1 trigger is propagated to all readout crates and instructs PMT and TPC data readout into ten dedicated sub-event buffer DAQ machines. The data across different DAQ machines is correlated at event building stage by the trigger number and corresponding trigger frame and sample numbers recorded in each data stream, per event. All readout crates are synchronized and correlated to the same 16 MHz clock.

maximum 15 Hz beam spill rate. MicroBooNE expects a total triggered write rate of around 12 MB/s. The SN stream circular buffers, which will be aggressively (non-losslessly) compressed beyond what the triggered stream experiences, will fill each server's 14 TB in on the order of one day, which is ample time to respond to a Super Nova Early Warning System (SNEWS) alert [84].

After data is written to disk, it is then copied to another server on the internal DAQ network, where the raw data is further compressed, shipped, and queued to be stored on in tape and disk cache using the Fermilab central data management system known as SAM. Offline applications then begin processing the raw data, converting the binary data format into a LArSoft [85] ROOT-based format which can be used as input for reconstruction algorithms. LArSoft is a common framework of software tools utilized by many LArTPC experiments at Fermilab and elsewhere. A separate process collects beam data and, during binary to LArSoft conversion, inserts that data into the built events. A duplicate copy of the data is also stored offsite at Pacific Northwest National Laboratory (PNNL). This collection of approximately 15 “projects” and the database which holds and monitors the state of the data flow is known as the Python/Postgres for MicroBooNE Scripting system (PUBS), and is patterned after a similar database state machine that the Double Chooz experiment used for data management. As PUBS pushes the data through this process, the progress of

16 each project is monitored and viewable via GUI. PUBS can also monitor the state of the SN stream
 1 data, held locally on the SEBs. A separate offline PUBS instance controls the processing of the
 2 data, including applying newly calculated calibration constants as part of data quality management.
 3 Figure 65 schematically depicts the flow of data throughout the MicroBooNE DAQ system.

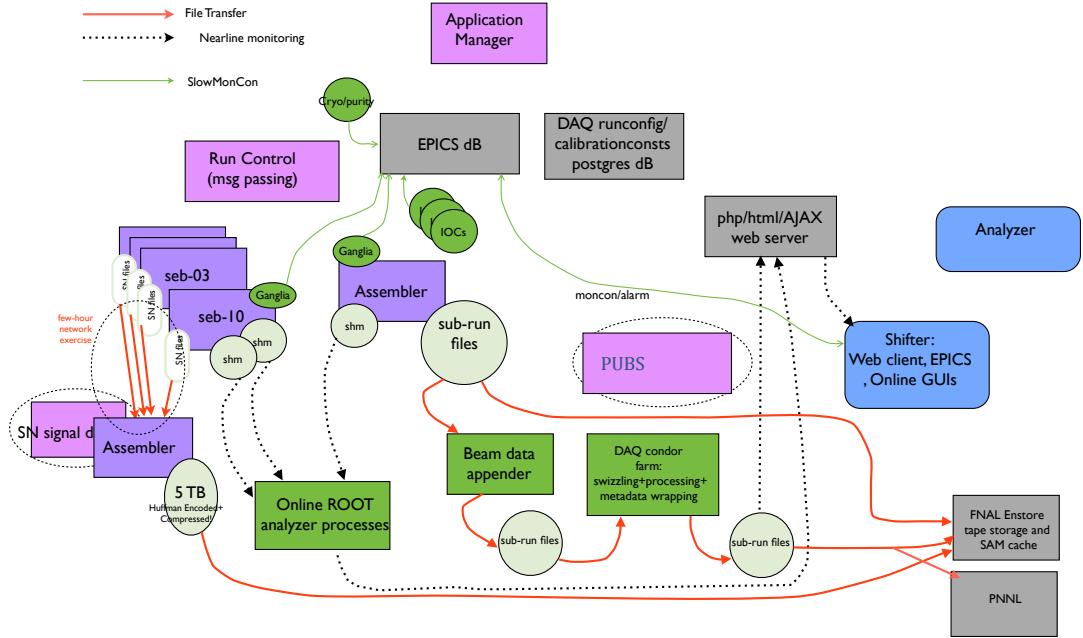


Figure 65: Data flow for MicroBooNE DAQ from raw to processed.

4 Additional software components handle the management of the main DAQ processes moving
 5 the data. A run control application issues configuration and state-progressing commands to the
 6 SEBs and EVB. Configuration states are stored in a dedicated run configuration database, which
 7 allows for the setting and preserving of configuration information for the DAQ, readout, and addi-
 8 tional components. This database not only allows for creating the large (~ 200 parameters) intricate
 9 DAQ run configuration files, but also enforces certain conditions which must hold for consistency.
 10 For example, the configuration that initiates the ASICS charge-injection calibration also dials and
 11 captures the settings on the external pulser that drives the calibration signal and assures that ASICS
 12 gains and peaking time parameters are enforced and recorded.

13 Another important aspect of the system is monitoring the health of the DAQ. Monitoring of
 14 DAQ components is accomplished through Ganglia which monitors basic system states (such as
 15 CPU, memory, and network usage) as well as allows use of custom metrics to monitor the data
 16 flow and status of the readout electronics [86]. These metrics are sampled and collected by the Ex-
 17 perimental Physics and Industrial Control System (EPICS) slow monitoring and control processes,
 18 which archives desired quantities and provides alarms when pre-defined thresholds are exceeded

[87]. Some examples of Ganglia metrics that are monitored and alarmed in EPICS are the rates of growth of the SEB data buffers, the fragment rates leaving each SEB, and fragment arrival rates at the EVB. Figure 66 shows examples of Ganglia metrics.

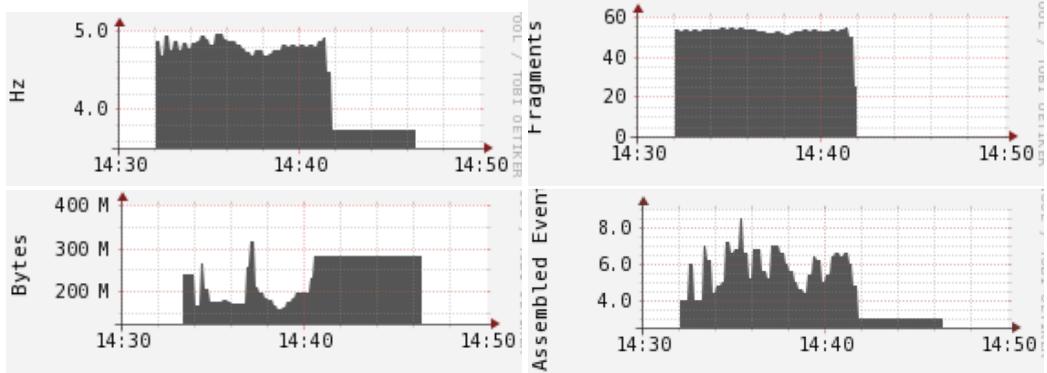


Figure 66: Ganglia metrics showing data flow on the EVB machine during a 5 Hz test run. Shown are the external trigger rate (top-left), the received fragment rate (top-right), the disk data write rate (bottom-left), and the number of assembled queued-up events waiting to be written (bottom-right). (11 fragments constitute a complete event in the MicroBooNE DAQ.)

Additional online monitoring exists to check data quality in more detail, through both programmed checks and visual checks including a real-time event display. The online monitoring takes snapshots into shared memory segments on the SEBs and the EVB, and thus provides the desired low latency checks of newly-arriving data. It continually walks through these ≈ 150 MB snap-shotted events and outputs histograms of occupancies and rates which are saved in ROOT files [88]. The histograms are then displayed in a web-based monitoring system that is easily accessible by the shift crew. Channels are aggregated in a variety of formats, including the order in which they appear in crates or across the wires and PMTs themselves. In this way, potential problems across connectors or crates, for example, may be more readily identified. Noisy, quiet, and unresponsive channels are easily marked and displayed to the shift crew. Figure 67 shows an example of available online monitoring information.

6.7 High-Level Software Trigger

After events are collected on the DAQ event-builder server, a suite of trigger algorithms are applied to the data. Currently, these algorithms mimic the PMT readout electronics' FPGA-based beam gate trigger algorithms, described in section 6.5. A search over the PMT digitized waveforms from the beam-spill period is performed, and if there is a significant amount of light in coincidence with the expected arrival time of the neutrinos, the event is marked and saved. This selection is performed on data that passes the Level-1 trigger, which typically includes data from the BNB and NuMI beams, and randomly selected off-beam data from an “external” trigger. A fraction of the data from each of these Level-1 trigger input streams is also retained via a random prescale, which provides a selection of data that has not been biased by the trigger. The high-level trigger algorithms take approximately 10 ms to return a result, a latency that is well-below the event-taking

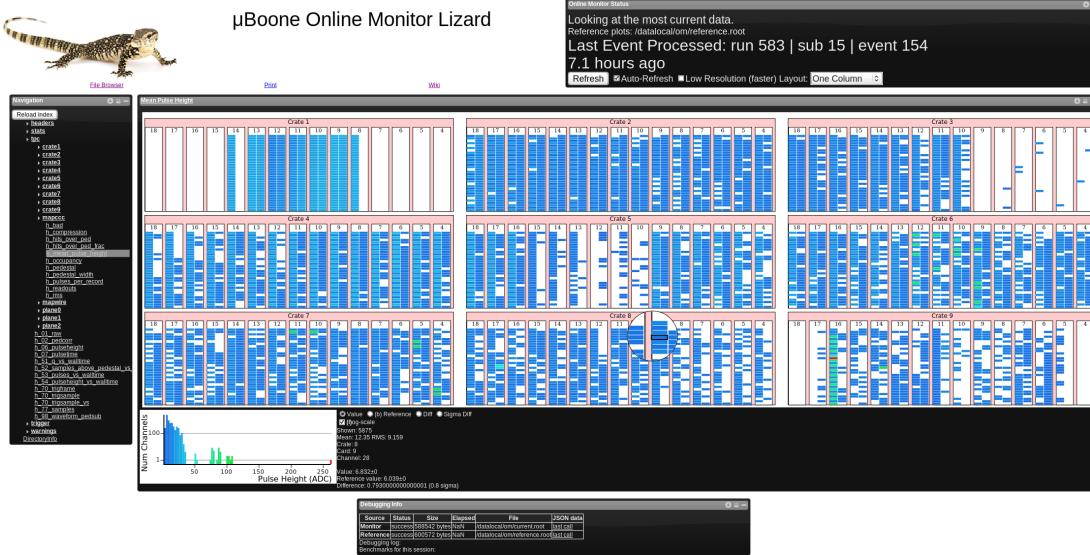


Figure 67: The online monitoring GUI (Lizard). The pedestal-subtracted ADC values for all 8256 wires in one minimum bias event are shown. Each box is a channel. Not all crates are fully populated with electronics.

rate and so does not impact data-taking performance. The average pass rate for data-events in the PMT beam gate trigger algorithm is roughly 5%.

7. Infrastructure and Monitoring Systems

MicroBooNE is housed at LArTF, which is located on-axis to the BNB. Complete knowledge of the electrical and cryogenic systems housed within LArTF is necessary to maintain acceptable operating conditions for the experiment. Continuous monitoring of the beam being delivered to LArTF is also necessary for subsequent physics analyses. This section describes the details of infrastructure within LArTF, as well as monitoring of the experiment and beam conditions.

7.1 Electronics Infrastructure at LArTF

This section describes the electronics infrastructure of the experiment, which is essential for proper operation of the electronics that control the functioning of and extract data from the LArTPC, PMTs, and other detector subsystems. Figure 68 shows a diagram of this system at LArTF, depicting racks located on a platform directly above the cryostat that house electronics for: LArTPC control and readout, light collection system, drift high voltage, purity monitor, calibration laser, trigger, and cryogenic control systems. Additional server racks containing the data acquisition, beam timing, and external network electronics are located in a separate computer room above and adjacent to the above-cryostat platform. The distribution of power, data, and network connections to and from all of these racks are also presented in figure 68, and is described in more detail in the following sections, as are electronics safety systems and interlocks.

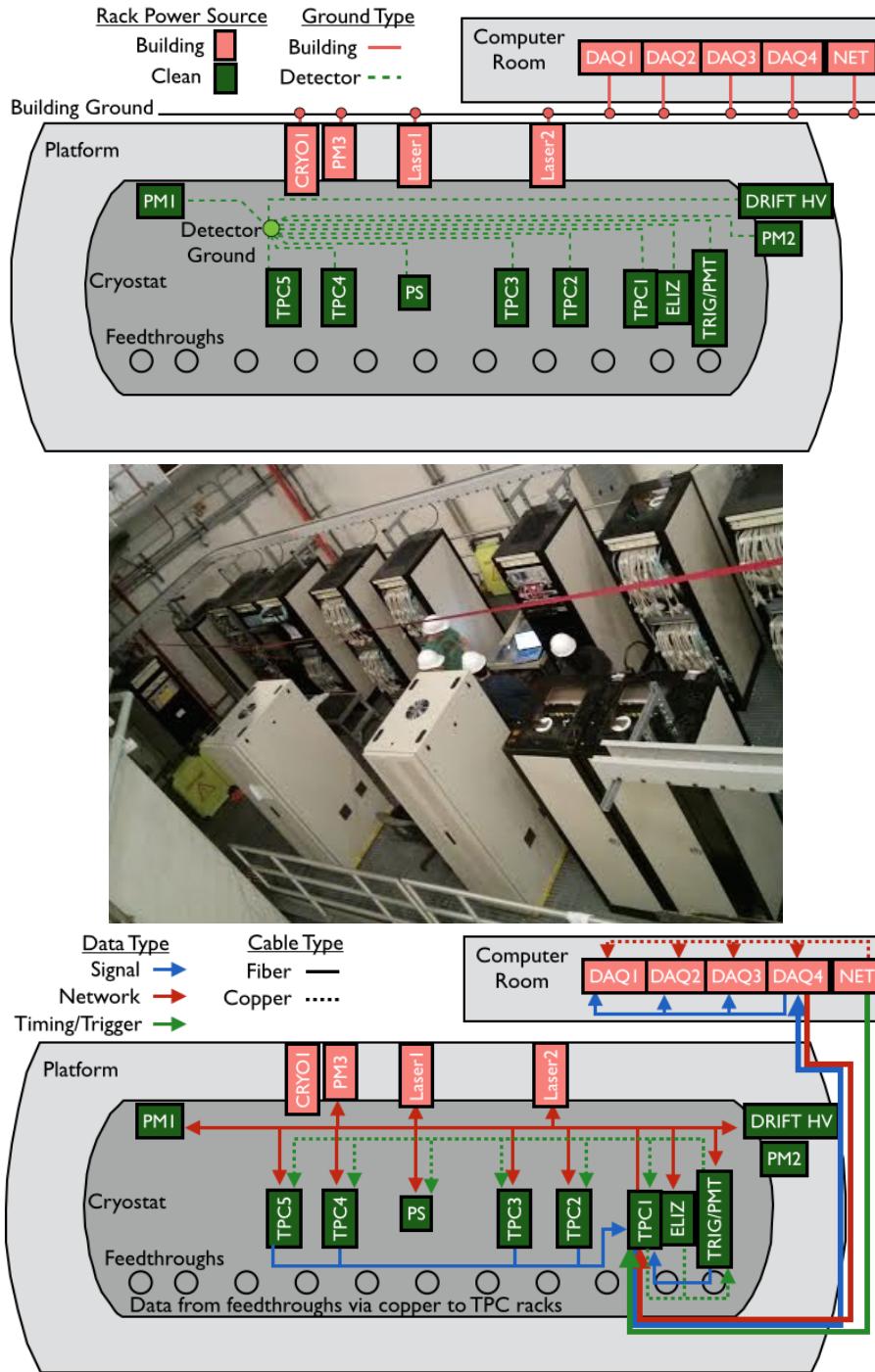


Figure 68: Top: Diagram illustrating location of deployed electronics racks and separation of detector and building grounds and clean and building power for differing racks. Middle: Photograph of installed electronics racks on the LArTF platform. Bottom: A diagram illustrating the general scheme of signal, network, and timing signal cabling in the LArTF computer room and platform.

19 **7.1.1 AC Power Distribution and Grounding for Low-Noise LArTF Data-taking**

1 As with any large detector operating with a high dynamic range, prevention of electromagnetic
2 interference and its attendant effects on MicroBooNE data is an essential aspect of detector design.
3 MicroBooNE’s strategy for producing a low-noise environment for the LArTPC and associated
4 readout electronics can be largely summarized in a few key points. AC power distribution-related
5 items will be described here, while cabling, connections, and shielding will be described in a
6 following section.

- 7 • “Clean power,” or AC power electrically isolated from AC power for the rest of LArTF
8 (“building power”), is supplied to all sensitive electronics via an isolation transformer.
- 9 • Highly sensitive electronics are housed inside the Faraday cage provided by the detector
10 cryostat or inside Faraday cages directly grounded to the cryostat.
- 11 • The detector cryostat is grounded to a “detector ground,” which is physically and electrically
12 isolated from the ground provided to all other LArTF power circuits, or “building ground.”
- 13 • No direct electrical connections are present between detector ground and building ground.
14 This is accomplished through the use of insulating platform and cryostat saddle materials,
15 insulating cable trays and cables, and by inserting insulating “breaks” (i.e. fiber data links
16 or insulating cryo pipe sections) when connections between sensitive and potentially noisy
17 detector components are necessary.
- 18 • Indirect pickup on clean signals through capacitive coupling to adjacent noise sources is
19 minimized through use of detector-grounded shielding and electrically-insulating cable trays.
- 20 • Ground loops on detector ground are avoided wherever possible by connecting all electronics
21 racks directly to the cryostat and by minimizing direct electrical connections between racks.
- 22 • Direct or capacitive couplings between building and detector ground are constantly moni-
23 tored during installation and operation with a custom-designed impedance monitor.

24 A line drawing describing the production of clean power and clean ground is shown in fig-
25 ure 69. A pair of 200 A clean power circuits produced at isolation transformers are used to power
26 all sensitive racks, which are indicated in figure 68. All racks containing LArTPC readout electron-
27 ics are placed on one circuit, while all other sensitive equipment is placed on the alternate circuit.
28 On the platform, all racks utilize clean power with the exception of the calibration laser and in-line
29 purity monitor racks, which either contain noise-producing elements or support building-grounded
30 components. All racks in the LArTF computer room utilize building power.

31 208-3 phase power is distributed to each individual electronics rack. For racks with signifi-
32 cant power requirements or a large number of components, this power is delivered to a Fermilab-
33 designed “AC switch box,” which distributes power to an Eaton Power Distribution Unit (PDU)
34 only upon receiving an interlock signal from a smoke detection system in each rack, which will be
35 described in more detail below. Rack components then receive power from one of the three phases
36 on this PDU. For racks with fewer requirements, power is supplied to components directly from an

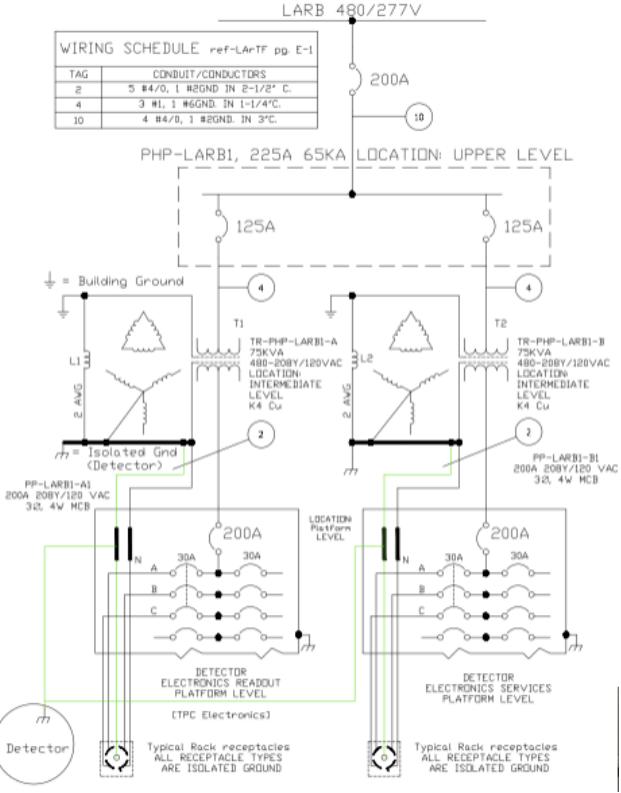


Figure 69: Line drawing of clean power generation and distribution and connections to detector ground.

37 interlocked simplified AC switch box or SurgeX SX-1120-RT PDU. Racks with sensitive electronics
 1 are grounded to the cryostat via copper sheeting running throughout insulated cable trays above
 2 the cryostat. Sensitive components within each rack are connected to a tin-plated copper grounding
 3 bar electrically connected to the rack bottom and running the height of the rack. Mechanical at-
 4 tachments to the rack provide grounding for less sensitive rack components. As mentioned before,
 5 any unintentional direct connection between building and detector ground can be quickly identi-
 6 fied by the impedance monitor located on the LArTF platform. Figure 70 shows pictures of this
 7 equipment.

8 7.1.2 DC Power Distribution to the MicroBooNE Detector

9 DC power is provided to the LArTPC and readout electronics by power supplies in clean-powered,
 10 detector-grounded racks for a variety of purposes:

- 11 • Holding the LArTPC cathode plane at voltage to produce the desired ionization electron drift
 12 speed
- 13 • Holding the two ungrounded anode planes at the proper constant voltage to ensure the planes
 14 are transparent to drifting electrons
- 15 • Operating the light collection system PMTs

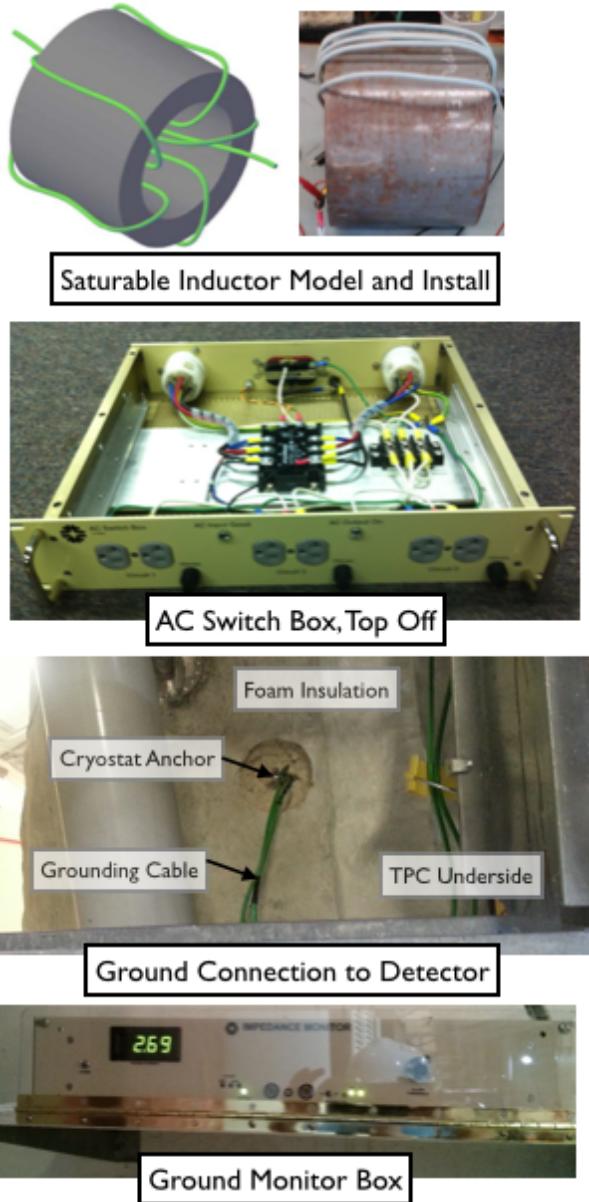


Figure 70: Pictures of the installed saturable inductor (top), AC switch box (top middle), detector ground strap and connection (bottom middle), and impedance monitor (bottom).

- ¹⁶ • Powering the cold electronics located inside the LArTPC
- ¹ • Powering the warm electronics located in the LArTPC readout electronics racks
- ² • Powering auxiliary systems, such as LArTPC temperature sensors and purity monitors
- ³ Table 7 summarizes the required voltages or currents for each of these purposes as well as the
- ⁴ power supply make and model utilized in each case. Power supplies are located in the relevant
- ⁵ subsystem's electronics rack, with power and grounding connections as dictated by that rack.

Table 7: Overview of MicroBooNE DC power distribution. Delivered voltages or currents are listed, along with power supply makes and models and whether each supply utilizes clean or building power.

Subsystem	Supplied Value	Supply Made/Model	Clean Power?
Drift High Voltage	120 kV	Glassman LX150N12	Y
Anode Plane Voltage	1 kV / 8 mA	Wiener MPOD ISEG_EHS 82 10X_805F	Y
PMT High Voltage	2 kV / 3 mA	BIRA T4	Y
Cold Electronics Power	8 V / 10 A	MPOD MPV 800I	Y
Warm LArTPC/PMT Electronics	+/-5 V MDH 2-8 V/25 A +12 V MEH 8-15 V/92 A +3.3 V MEH 2-7 V/115 A	Wiener PL508	Y
Auxiliary Systems Power	Various	Various	Laser: N Inline PM: N Cryostat PM: Y

6 DC supply power consumption is minimal in most cases, with the exception of the warm
1 LArTPC electronics PL-508 supplies. Care was taken to distribute the AC power load by limiting
2 the number of high-draw PC supplies per electronics rack.

3 **7.1.3 Network, Timing, and Data Distribution for Low-Noise LArTF Data-taking**

4 Network, timing, and data connections must be made between the detector, building-ground, and
5 detector-ground racks to properly read out MicroBooNE data. However, as described above, these
6 connections must be made while maintaining strict detector-building electrical isolation. Deployed
7 interconnections meeting both of these requirements are displayed in figure 68.

8 Timing and LArTF-external network signals are brought into LArTF via electronics in the
9 computer room, where all racks are building grounded and powered. These signals are distributed
10 and processed in the computer room via copper cable, while network and processed timing sig-
11 nals to be sent to the platform are converted onto fiber cables and aggregated into a central fiber
12 termination box. A fiber trunk line then delivers these signals to the platform, where another fiber
13 termination box on a detector-ground rack is used to fan out these signals. Network connections are
14 fanned out via fiber to a network switch in each platform rack, while timing signals are re-converted
15 to copper and further processed for use by the trigger system on a different detector-grounded rack.
16 All rack-to-rack cables are run in insulating cable trays beneath the platform.

17 PMT and LArTPC data are transferred from each detector feedthrough to readout crates in
18 detector-ground racks via insulated copper cable whose shield is tied to detector ground. Digitized
19 crate output is then sent to the aforementioned platform fiber termination box, where these signals
20 are sent via fiber trunk line to the computer room. In the computer room, these fibers are then
21 fanned out to the appropriate DAQ computer. Readout crate and cold electronics control commands
22 are transmitted in the opposite direction utilizing a similar scheme, with crate controls delivered
23 directly via fiber, and cold electronics commands delivered via fiber to a copper fanout in a detector-

24 ground rack.

1 Clock and trigger signals must also be sent from a central trigger rack to all detector-ground
2 LArTPC/PMT readout racks. These signals are transmitted via copper connections, and represent
3 the only source of ground loops on detector ground. To further reduce the possible impact of
4 induced noise in these and all copper cables mentioned above, all insulating cable trays beneath
5 the platform are lined with copper sheeting grounded to the detector. As an additional precaution,
6 all LArTPC signal copper cables are run in separate cable trays from power and auxiliary cabling
7 beneath the platform as well as inside every rack.

8 All cables between all detector components have been uniquely labelled with serial number,
9 source, and destination to allow for ease of replacement and reconnection. Ample fiber and copper
10 spares for every major cable type are also installed along with the production cables to allow for
11 quick replacement of any failed cable.

12 **7.1.4 Interlocks and Safety Systems**

13 All electronics racks contain smoke-sensing and temperature-monitoring systems, which, when
14 interlocked with AC and DC power transmission in each rack, constitute a rack protection system
15 (RPS) designed to meet Fermilab safety requirements and reduce the risk of fire and related damage
16 in LArTF and to individual rack components.

17 The RPS principally consists of a smoke sensor connected to a Fermilab-designed rack pro-
18 tection box. This box produces and outputs a 12 V interlock signal when the rack protection box is
19 on and receiving a “no-smoke” signal from the smoke sensor. This 12 V signal can be sent to the
20 AC distribution box located in each rack, as described above, to allow AC transmission to all rack
21 components only if the RPS is on and not detecting smoke. A similar 12 V “RPS Status” signal
22 is also produced by the RPS box for input into the MicroBooNE slow control box, which will be
23 described in following sections. Alternate contacts are available on the rear of the RPS box for
24 coupling the status of additional subsystems, such as the DAQ and calibration laser uninterruptible
25 power supply (UPS), to smoke sensor or rack power status.

26 Temperature sensors deployed in two or three locations in each electronics rack sample air
27 temperature within each rack. Temperatures at each sensor are read out and recorded in the slow-
28 control database by the slow-control monitoring box. In addition, the box also produces a 5 V
29 interlock signal if all sampled temperatures are within pre-programmed thresholds. In electronics
30 racks distributing PMT- or LArTPC-related DC power these temperature interlock signals are input
31 into each relevant power supply, allowing DC power distribution only when this interlock signal is
32 present, for safety purposes.

33 Additional hardware interlocks ensure the non-simultaneous operation of particular subsys-
34 tems. In particular, the PMT system is disabled when cryogenic system liquid level sensors detect
35 a level below that of the highest PMT bases, or when the UV laser system is active. The former
36 requirement is enforced with a dry-contact hardware interlock, while the latter is enforced with a
37 software interlock in the MicroBooNE online software.

38 **7.1.5 Performance Measurements**

39 The proper operation of each production electronics rack’s AC and DC distribution and RPS sys-
40 tems has been tested prior to installation at LArTF. Furthermore, test stands exercising function-

41 ability of DAQ, PMT and LArTPC electronics, trigger, and drift HV systems have successfully in-
1 corporated and tested various aspects of these same AC and DC distribution and RPS systems.
2 Impedances between detector and building grounds were recorded throughout the installation of
3 the rack infrastructure at LArTF using the impedance monitor located on the LArTF platform.

4 **7.2 Slow monitoring and control system**

5 MicroBooNE uses EPICS for controlling and monitoring most devices and conditions important
6 to the experiment. These include power supply controls, temperatures, fan speeds, rack protec-
7 tion interlock status, and various environmental conditions. The DAQ, cryogenics systems, and
8 beam data collection systems operate independently of the EPICS slow monitoring, but export data
9 which are imported into EPICS for archiving and status displays. Applications from the Control
10 System Studio software collection [89] are used for providing displays, alarm notifications, and
11 data archiving.

12 An EPICS system consists of any number of server programs implementing the EPICS Chan-
13 nel Access (CA) protocol [90] to provide client programs access to any number of process vari-
14 ables, where each process variable represents a quantity being controlled (an output) or measured
15 (an input). The EPICS base distribution provides a standard type of channel access server called an
16 Input/Output Controller (IOC), which can be extended to support specific hardware as desired.

17 Most power supplies are controllable over the network through the NetSNMP protocol [91].
18 Several EPICS driver modules are available for SNMP, and MicroBooNE utilizes one written at
19 NSCL [92]. An IOC with this SNMP module runs on a central computer and contacts the power
20 supplies over a private network for monitoring and control. The photomultiplier power supplies are
21 reused from the DØ experiment and have custom IOCs running in their own controllers. The main
22 high voltage power supply has only a simple RS-232 serial interface; control and monitoring for it is
23 provided by a nearby computer running an IOC with the EPICS asynDriver [93] and StreamDevice
24 [94] modules.

25 MicroBooNE has a number of racks in various positions above the detector and in an adjacent
26 server room. Each is equipped with a rack-protection system and multiple digital temperature sen-
27 sors, and most contain one or two fan packs, each containing 6 fans. To monitor and control these
28 devices, each rack has an 1U rack-mount enclosure containing an ARM-based single-board com-
29 puter (SBC) running Linux. An off-the-shelf GESBC-9G20 from Glomation Inc. [95] is utilized
30 for the SBC. A custom interface board [96] connects the SBC to front panel LEDs, temperature
31 probes, fan packs, and rack-protection-status input. The temperature sensors are DS1621 chips,
32 controlled and read out over an I2C bus by the SBC's I2C controller. The DS1621 also has a ther-
33 mostat output with programmable trip and reset temperatures, which are connected via the interface
34 board to outputs that can be used to interlock devices in the racks, such as power supplies. The fans
35 provide pulse-per-rotation outputs, which are monitored by a 12-channel tachometer implemented
36 via a PIC16F887 microcontroller, and also read out by the I2C bus. An EPICS IOC runs in each
37 SBC, with custom device drivers for reading all status information and controlling the heartbeat
38 LED and temperature sensor trip and reset points.

39 Data are imported into EPICS channels from a number of external sources. The primary rea-
40 son for duplicating these data in EPICS is to integrate displays and warnings into one system for
41 the experiment operators, and to provide integrated archiving for sampled data in the archived

42 database. An IOC running on a central computer provides “soft” process-variables channels for
1 these data. The data acquisition system provides many metrics describing its operation via the
2 Ganglia system[86, 97], which makes the data available in an XML format easily read by a Python
3 script, which in turn writes to EPICS using the PyEPICS module [98]. The hardware and system
4 status of the DAQ computers is monitored through the industry standard Intelligent Platform Man-
5 agement Interface (IPMI); rather than writing a script to import data from IPMI directly into EPICS,
6 a IPMI-to-Ganglia interface provided by the FreeIPMI’s “ipmi-sensors” package [99] is used, al-
7 lowing data to be imported via the same mechanism used for the DAQ metrics. Separate Python
8 scripts periodically retrieve data about outside weather conditions from various sources, cryogen-
9 ics system data from a file retrieved non-intrusively from the IFIX cryogenics control system, and
10 beam data from Fermilab’s Intensity Frontier Beam Database (IFDB) [100].

11 **7.3 Beam Monitoring**

12 The primary source of neutrinos for the MicroBooNE experiment is the BNB. The primary beam-
13 line is lined with instrumentation including toroids which indicate beam intensity, “multiwires”
14 showing beam profile in the horizontal and vertical planes, and beam position monitors measuring
15 the mean beam position. Data from these monitors are stored on a spill-by-spill basis in the IFDB.
16 Many of MicroBooNE’s physics analyses require that beam data are recorded for each spill and
17 matched to detector events.

18 Primary beam monitoring in MicroBooNE is done using a “dashboard” interface to IFDB.
19 By using the IFBD instead of the accelerator control system, the experiment can also verify that
20 data are being acquired by the IFBD. The dashboard is accessible over the network using a web
21 browser. The final monitoring step includes a post-data-merge check, ensuring that beam data are
22 successfully matched with detector data for all beam spills. This is done once the detector DAQ
23 binary data file is closed.

24 The dashboard presents a graphic representation of the data, allowing for easy error identifica-
25 tion, as shown in figure 71. The experiment monitors: two toroids which indicate beam intensity;
26 three multiwires, each of which shows beam profile in each plane; and beam position monitors
27 along the beamline which show the vertical and the horizontal position. Parameters pertaining to
28 the target and horn, such as cooling air temperature and horn current, can also be monitored. The
29 dashboard allows the experiment to easily add additional devices if experience demonstrates the
30 need for their monitoring.

31 Data are monitored in near real-time. A reasonable history is also kept so that changes are
32 easily identified. The accelerator control system provides detailed diagnostics tools to experts and
33 can be used in case of any problems.

34 **8. UV Laser System**

35 The knowledge of the electric field inside the drift volume of a LArTPC is a necessary aspect
36 for performing subsequent event reconstruction. Distortions of particle tracks due to field non-
37 uniformities affect the accuracy of the particle momentum reconstruction based on multiple scat-
38 tering. Deviations from a uniform drift field may arise mainly due to accumulation of positive

Booster Neutrino Beamline Status Display (e,1d events) - Historical data for 2015-07-01 11:15:03

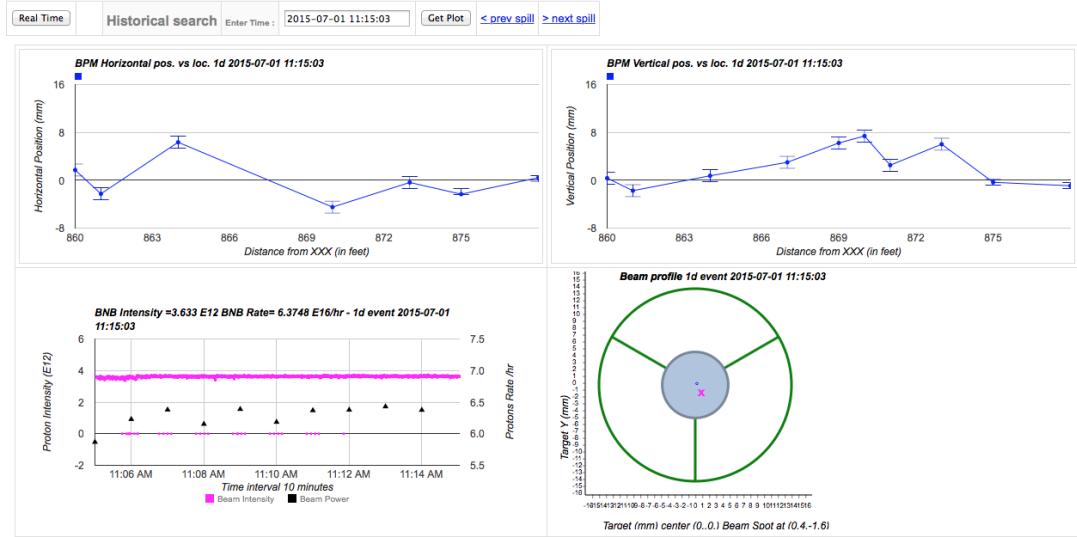


Figure 71: The BNB dashboard, showing graphical representation of beam instrumentation data, is used to monitor the beam. The top box shows the timestamp of the beam spill and indicates if data is stale by changing the color. The two top plots show the primary proton beam position along the BNB. The bottom left plot shows the recent beam spill intensity and rate. The bottom right plot shows the beam as projected onto the Beryllium target (the grey circle in the middle with radius of 0.5cm). The dashboard is accessible via web page providing both real time updates and the review of past data. The page can be easily extended to monitor additional beam devices.

39 argon ions in the drift volume. These ions are produced by ionizing particles from neutrino interactions,
 1 as well as by cosmic rays. While electrons produced by ionizing particles are quickly (within
 2 few milliseconds) swept towards the readout system, ions have significantly lower mobility. Their
 3 drift velocity in the MicroBooNE detector at nominal drift field is of the order of 0.8 cm/s. The
 4 rate of cosmic muons in the LArTPC volume is calculated to be 11,000 muons/s within the active
 5 volume (assuming no overburden, and a cosmic rate of 200 muons/m²/s through a horizontal plane
 6 at the earth's surface and 63 muons/m²/s through a vertical plane), traversing a combined length
 7 of 1.9×10^4 m through the liquid argon [101, 102]. Assuming that cosmic muons are minimum-
 8 ionizing (2.1 MeV/cm) and produce 23.6 eV per ion pair, positive ion charge is produced at a
 9 rate of 2.8×10^{-8} C/s in the MicroBooNE LArTPC. These ions are continuously neutralized at the
 10 cathode. The resulting charge distribution in equilibrium is shown in figure 72. Such accumulated
 11 space charge leads to noticeable distortion of the drift field and, consequently, to deviations of re-
 12 constructed track coordinates by up to 10 cm (see figure 73). The ion drift velocity is comparable
 13 to local argon flow velocities, produced by global argon recirculation flow and thermal convec-
 14 tion. Therefore the distribution of positive space charge inside the drift volume may be not only
 15 nonuniform (figure 74), but also non-stationary.

16 A nonuniform drift field in the LArTPC leads to the apparent bending of truly straight tracks of
 17 high-momentum ionizing particles. In principle, a set of events from such particles allows for the

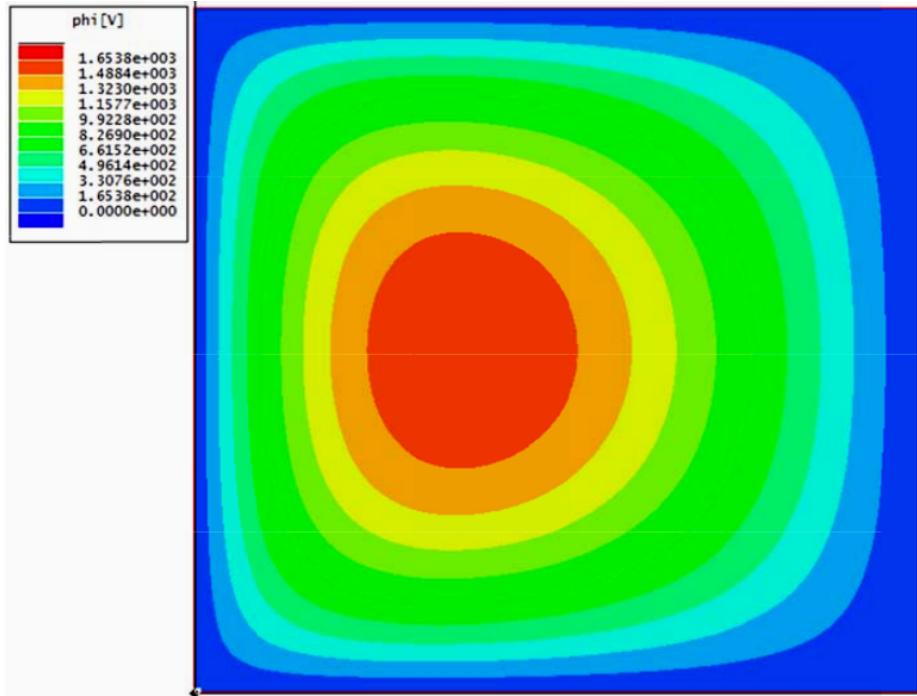


Figure 72: Distorting potential distribution due to positive space charge in equilibrium in the MicroBooNE detector.

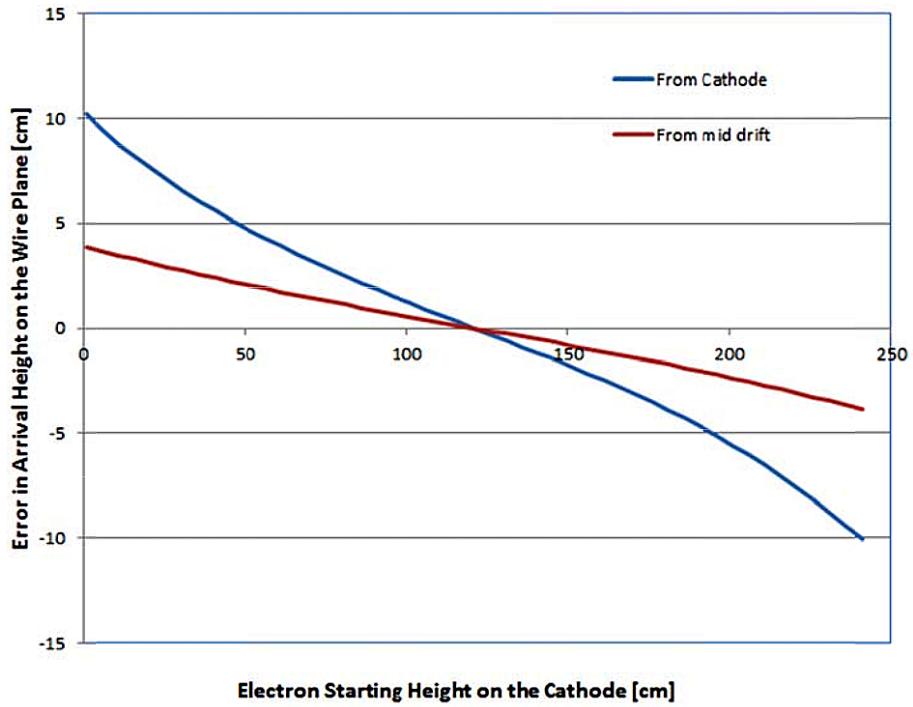


Figure 73: Deviation of a crossing track from its true coordinates due to positive ion space charge.

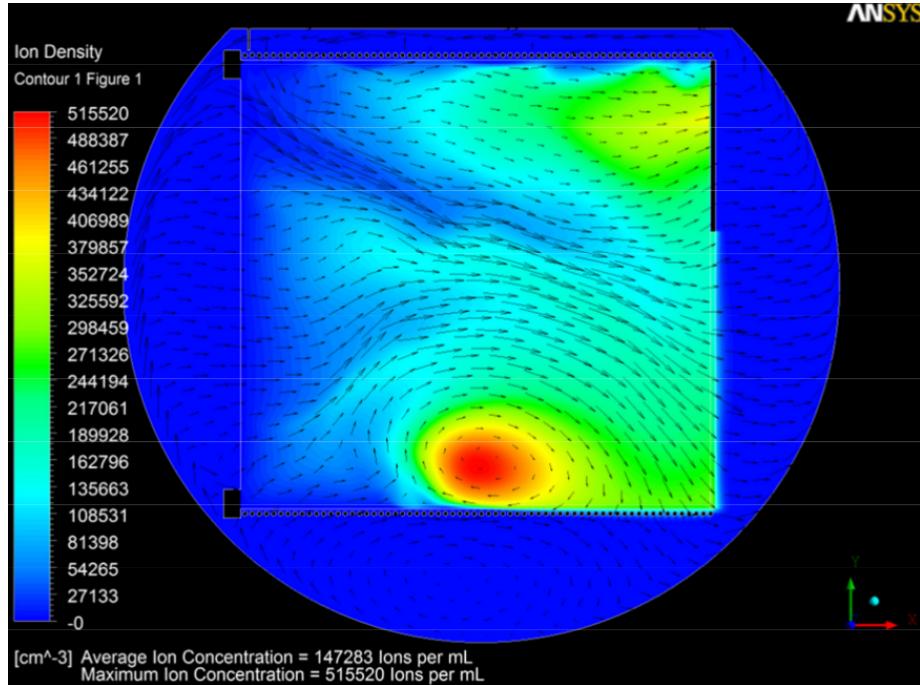


Figure 74: Distribution of the positive space charge in presence of argon circulation.

reconstruction of the field in any small region of the LArTPC drift volume, using the systematic apparent curvature of tracks at different angles passing through that region. In practice, the rate of such events from cosmic muons is too low to acquire sufficient statistics in reasonable time. A method to generate straight ionization tracks at a defined location in liquid argon is described in [103]. A collimated photon beam from a pulsed UV laser with $\lambda=266$ nm can ionize liquid argon via multi-photon absorption. The resulting ionization track is straight, characterized by low electron density, therefore featuring little charge recombination loss, unlike cosmic muon tracks. Laser tracks are also free from δ -electrons, which complicate track reconstruction in the case of muons. The method was successfully exploited in the Argontube long drift LArTPC [104 – 106] to derive the non-uniformity of the electric field along its 5 m long drift volume [107].

The MicroBooNE LArTPC requires a set of such tracks in order to cover the whole sensitive volume to reconstruct field distortions. This is the purpose of the laser calibration system, which features two UV lasers, one on either end of the LArTPC. Tracks are generated by steering a pulsed laser beam, introduced to the cryostat via a custom-designed opto-mechanical feedthrough [108], through the LArTPC active volume.

8.1 UV Laser Calibration

In order to unambiguously reconstruct a drift field vector at any point within the detector fiducial volume, a minimum of two ionization tracks are required to cross in the region of interest. The total number of crossing points is determined by the required reconstruction granularity. In MicroBooNE the initial scenario is to acquire 100 tracks from each direction, producing a reconstructed 3-D map with voxels that are approximately $10 \times 10 \times 50$ cm 3 in volume. This map provides a rough picture of the space charge distribution. Depending on the results of this measurement, areas of

22 interest can be studied in more detail. Repetitive study of small volumes may reveal dynamics in
 1 the space charge distribution due to turbulent circulation, and should further inform an optimized
 2 scenario for a standard UV laser calibration procedure.

3 An algorithm of drift field calibration utilizes an input array of detector events with one straight
 4 ionization track in each element of the array. The result of the calibration is a coordinate correction
 5 map, to be applied to each track, which converts apparently curved track images back to the true
 6 coordinate system where they are straight. The algorithm is iterative with an optimizable iteration
 7 step and required accuracy. An example of simulated reconstruction in 2-D space is depicted in
 8 figure 75, showing that the magnitude of the field distortions is reduced from 10 cm down to several
 9 millimeters in 99% of the detector volume.

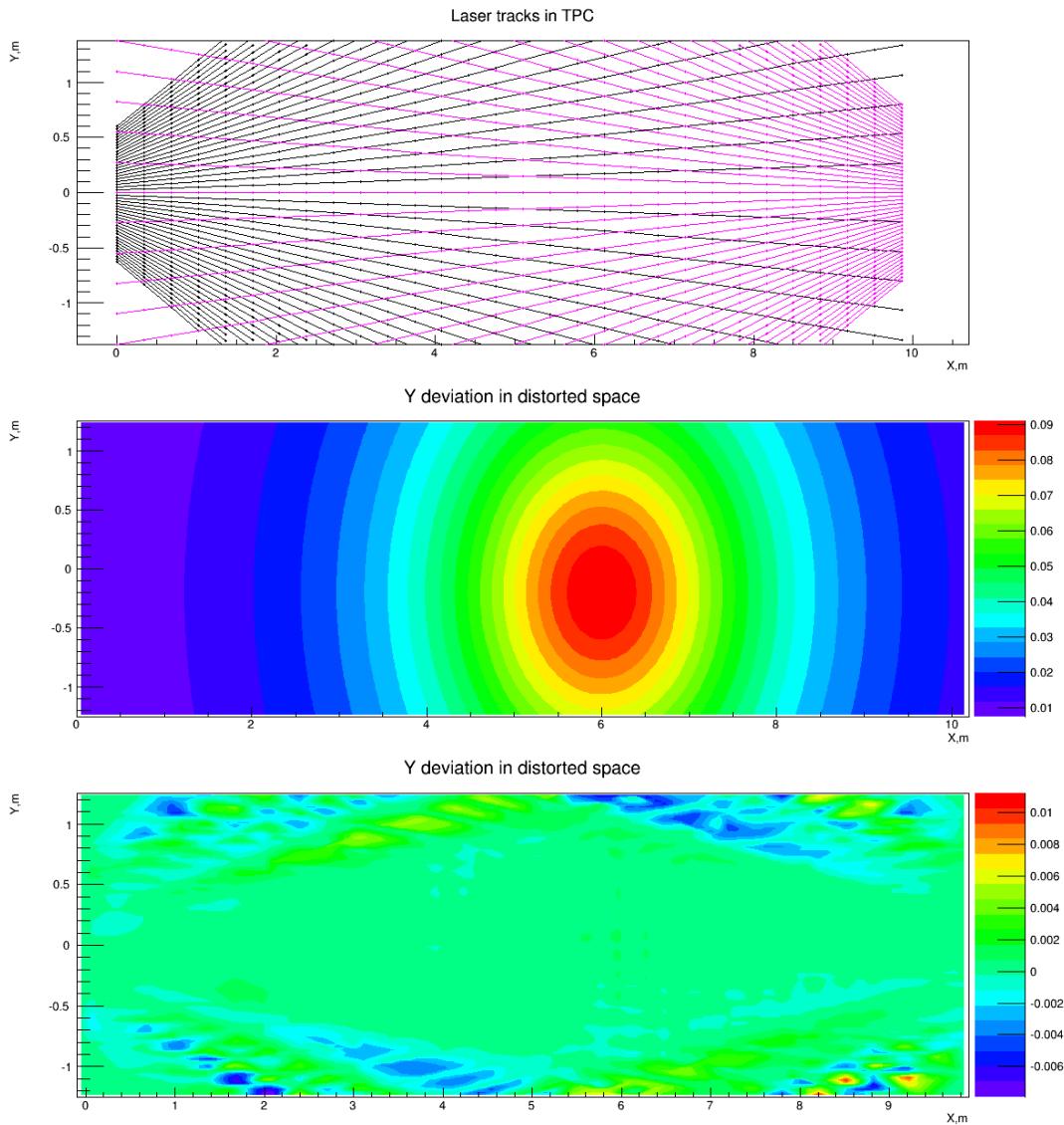


Figure 75: Top: Simulated true laser beam trajectories in the detector; Middle: map of Y coordinate of track deviation under influence of non-uniform electric field; Bottom: residual map of reconstructed track Y-coordinates versus true ones.

¹⁰ **8.2 Laser Source and Optics**

¹ A Nd:YAG laser emitting light at a wavelength of 1024 nm is used as the primary light source [109].
² Inside the laser head, nonlinear crystals are installed in the beam line for frequency doubling and
³ summing, resulting in a wavelength of 266 nm needed for ionization of liquid argon. For this
⁴ wavelength, the Nd:YAG laser is specified to produce an output energy of 60 mJ for each 4 to 6 ns
⁵ long pulse and a horizontal polarization. The maximal repetition rate is 10 Hz; the beam has a
⁶ divergence of 0.5 mrad.

⁷ An optical table, as seen in figure 76, was developed to introduce the necessary parts in a
⁸ stable and compact environment. With regard to the operation of the optical table on MicroBooNE,
⁹ the parts were chosen to be accessible remotely where necessary. The emitted laser beam contains
¹⁰ not only ultraviolet light but also all other harmonics generated in the crystal and the primary light
¹¹ of 1024 nm. Dichroic Mirrors optimized to reflect only wavelengths in the UV region are used
¹² to filter higher wavelengths out. To absorb the transmitted wavelength behind the mirrors, glass-
¹³ ceramic plates are installed. The beam leaving the laser head is reflected by the first 45°-mirror
¹⁴ into an attenuator. For optical adjustment and verification of the non-visible UV-beam, a green
¹⁵ alignment laser is placed behind this mirror and adjusted such that its path is coincident with the
¹⁶ UV-laser beam. In the attenuator (Altechna Wattpilot) a turnable $\lambda/2$ -plate enables rotation of the
¹⁷ orientation of the laser beam polarization. Behind the attenuator two parallel plates are installed
¹⁸ such that the angle of the incident beam matches the Brewster angle of the reflector. Modulating
¹⁹ the polarization of the beam adjusts the intensity of the reflected beam. An aperture is placed in
²⁰ the optical path of the beam after the attenuator to control the beam diameter. The last part in the
²¹ beam line is a remotely-controllable mirror mount (Zaber T-OMG), which directs the beam to the
²² laser feedthrough on the cryostat. A photodiode (Thorlabs DET10A/M), which is sensitive in the
²³ ultraviolet region, detects the scattered light when a laser pulse is fired. Its signal is then used as a
²⁴ trigger for data taking. Both the UV-laser head and the optical table are mounted on a 15 mm thick
²⁵ aluminum plate.

²⁶ **8.3 Steering System**

²⁷ One of the main challenges of the laser calibration system is the introduction of a steerable laser
²⁸ beam into the detector. Earlier, an evacuated quartz-glass [110] was utilized to introduce a laser
²⁹ beam into liquid argon, however this beam had a fixed path through the detector. For the purpose of
³⁰ scanning the full detector a fully steerable mirror in liquid argon is necessary. In the MicroBooNE
³¹ detector, this is achieved by mounting a mirror on a horizontally-rotatable support structure. A
³² rack and pinion construction, where the mirror is mounted on the frontside of a half gear (pin-
³³ ion), provides the necessary freedom for the vertical movement (see figure 77 right). To steer
³⁴ the horizontal movement from outside the cryostat, a commercial differentially-pumped rotational
³⁵ feedthrough is deployed (see figure 77 left). The rack and pinion construction is attached to a linear
³⁶ feedthrough. Both feedthroughs are motorized to allow for remote control and automation of the
³⁷ mirror movement. The mirror support structure was fabricated out of polyamide-imide (Duratron
³⁸ T4301 PAI), which has a very low outgassing rate and low thermal expansion coefficient, and is
³⁹ certified for operation at 87 K. To minimize the probability of discharges due to the close loca-
⁴⁰ tion of the feedthrough to the field cage structure in MicroBooNE, no conductive parts were used

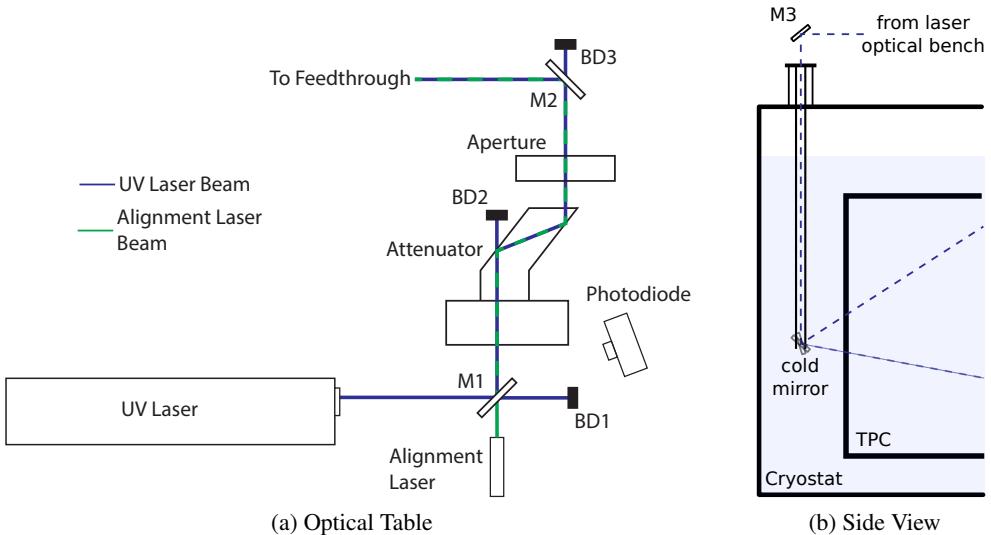


Figure 76: (a) A schematic drawing (not to scale) of the components used for laser beam configuration. An alignment laser (visible light) is introduced along the UV-laser path at the first dichroic mirror (M1), such that the paths overlap. In the attenuator the UV-laser beam intensity can be adjusted to the desired level, and the diameter of the beam is controlled by an aperture. A motorized mirror (M2) deflects the light into the direction of the feedthrough. Beam dumps (BD) are installed behind all mirrors to absorb the non-reflected laser light. (b) Side view of the cryostat indicating the mirror support structure with respect to the LArTPC.

41 in the support structure. The support structure has a total length of 2.5 m in MicroBooNE. Both
 1 feedthroughs are equipped with high precision position encoders from Heidenhain. The accuracy
 2 of the encoders is chosen such that a position accuracy of 2 mm for the laser beam spot over 10 m
 3 distance is achieved. An external interface box controls the encoders and records a position reading
 4 upon receiving a trigger signal from the photodiode. The DAQ computer accesses the position in-
 5 formation over an ethernet connection. The same computer is also used for steering the two motors
 6 via a motor driver system (over a RS232 interface).

7 **8.4 Performance Tests and Initial Operation**

8 A full performance test of the laser calibration system identical to the one installed in the Micro-
 9 BooNE LArTPC was performed prior to the final installation. Apart from the general proof-of-
 10 principle of the laser calibration system, several operationally relevant parameters were identified.
 11 These include scanning speed, positioning accuracy, positioning limits, optimal laser beam in-
 12 tensity, beam diameter, and the minimal achievable field distortion which can be resolved. The
 13 test system consists of a LArTPC equipped with 64 readout channels and an active area of about
 14 400 cm², with a drift distance of 40 cm (see [111] for further details).

15 Several tests of the motorized feedthrough were performed under warm conditions before cold
 16 tests were conducted. One crucial parameter for the quality of the electric field calibration is the
 17 resolution at which laser tracks can be aimed in the detector. For the rotational axis this angle
 18 is directly measured on a circular scale. For the vertical movement the linear displacement of

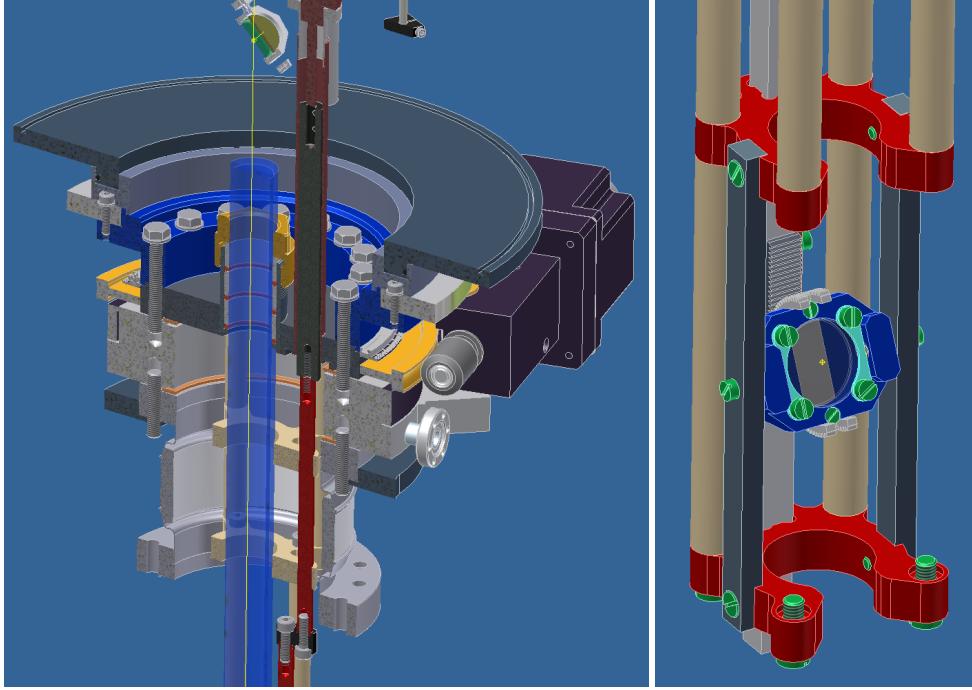


Figure 77: Left: CAD cutaway drawing of the feedthrough construction is shown. The yellow line indicates the laser path. Right, CAD drawing of the cold mirror including the support structure.

the bellow is translated into a rotation inside the cryostat, as can be seen in the CAD drawing in figure 77. This construction introduces uncertainties to the measurement position and backlash. The backlash can be compensated by always approaching positions from the same direction. For the translation of the linear movement ΔL into a rotation $\Delta\phi$ the translation ratio s according to $\Delta L = s \cdot \Delta\phi$ was measured with a Bosch GPL3 laser alignment device. The obtained ratio is $s = 0.3499 \pm 0.0002 \text{ mm/}^\circ$. The dominant uncertainty in the vertical position measurement is the accuracy of the encoder $\sigma_{\text{linear}} = \pm 1 \mu\text{m}$, which translates into a vertical rotation measurement accuracy $\sigma_{\text{vertical}} = 26.1 \text{ cm}$.

Horizontal movement limitations arise from the construction of the feedthrough system, namely the warm mirror support structure. This limitation originates in the manner the laser table is mounted relative to the feedthrough on the MicroBooNE cryostat. Vertically the mirror can be rotated more than 45° relative to the horizon in both directions. In an upward looking configuration, no limitations arise which would affect the coverage of the detector with the beam. When the mirror faces the opposite downward direction and the laser is properly aligned onto the center of the mirror, only the laser diameter and the size of the mirror limit the achievable coverage. However slight misalignment will affect this, since the beam will not be in the optimal spot anymore. In warm tests a maximal downward angle of the beam of 52.5° with respect to the horizon was achieved. During the cold tests the horizontal and vertical movement speeds were set to $2.6^\circ/\text{s}$ and $1^\circ/\text{s}$, respectively, and horizontal and vertical angles of 81° and 22° , respectively, were covered. Warm tests of the fully expanded setup showed vibrations if the chosen movement speed was too large. The vibrations are expected to be damped with a more stable installation on the detector,

21 and with the immersion of the setup in liquid argon.

1 Modulation of the beam energy with respect to the vertical alignment of the cold mirror was
2 found to be crucial for obtaining sufficient ionization in the detector. Investigations showed that
3 the reflectivity of the selected dielectric mirrors, which were optimized for 45° in air, are very
4 sensitive to the angle of incidence in liquid argon. Therefore during a calibration run, the beam
5 energy has to be controlled. The emitted UV-laser beam has a diameter of 6 mm and will spatially
6 diverge during propagation. A beam with this diameter will produce an ionization signal larger
7 than the wire spacing, which will limit the capabilities of the full system. With the aperture a small
8 as possible diameter of the laser was selected to enter the detector. Measurements of the diameter
9 were performed with thermal paper (used for thermal printing) on which the selected beam spot
10 burns in. The minimal achieved diameter was 1 mm.

11 **9. Conclusion**

12 The MicroBooNE detector is the culmination of several years of development and construction. It
13 is the largest LArTPC ever constructed in the U.S., and represents a major technological advance
14 that future experiments will build upon.

15 **Acknowledgments**

16 We gratefully acknowledge...

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