

Mathematical Analysis II

Felix Chen

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§0.1 Applications of Fubini's theorem

Definition 0.1 (Product measure). Let (X, \mathcal{F}, m) and (Y, \mathcal{G}, m) be measure spaces, define a measure on $X \times Y$: The measure m induces an outer measure on $X \times Y$, and complete it to a normal measure by using Caratheodory conditions. This measure is called the **product measure** on $X \times Y$.

Theorem 0.2

Let $\mathbb{R}^d = \mathbb{R}^{d_1} \times \mathbb{R}^{d_2}$, E_1, E_2 are subsets of $\mathbb{R}^{d_1}, \mathbb{R}^{d_2}$, respectively.

- If E_1, E_2 are measurable, then E is measurable as well, and $m(E) = m(E_1)m(E_2)$.
- If E is measurable, then E_1, E_2 are measurable, and $m(E) = m(E_1)m(E_2)$, unless one of E_1, E_2 is null set, which means E is null as well.

Proof. First it's easy to note that

$$m^*(E) \leq m^*(E_1)m^*(E_2).$$

So we directly conclude that if one of E_1, E_2 is null set, E must be null.

Thus we may assume below that E_1, E_2 have finite nonzero measure. By taking the equimeasure hull of E_1, E_2 (denoted by F_1, F_2), let $Z_1 = F_1 \setminus E_1, Z_2 = F_2 \setminus E_2$, we have

$$(F_1 \times F_2) \setminus (Z_1 \times F_2 \cup F_1 \times Z_2) \subset E \subset F_1 \times F_2,$$

so E is measurable.

Conversely, if E is measurable, consider the measurable function χ_E , by definition $\chi_E = \chi_{E_1}\chi_{E_2}$, hence by Tonelli's theorem, for x almost everywhere, $\chi_{E_1}(x)\chi_{E_2}$ is measurable on $\mathbb{R}^{d_2} \implies E_2$ is measurable.

Therefore we have the equation

$$m(E) = \int_{\mathbb{R}^d} \chi_E = \int_{\mathbb{R}^{d_1}} \left(\int_{\mathbb{R}^{d_2}} \chi_{E_1}\chi_{E_2} \right) = m(E_1)m(E_2).$$

This proves the theorem. □

Corollary 0.3

Let $f(x)$ be a measurable function on \mathbb{R}^{d_1} , we have $g(x, y) = f(x)$ is measurable on \mathbb{R}^{d_2} .

Proof. It's sufficient to prove that $\{(x, y) | f(x) > t\}$ is measurable in \mathbb{R}^d . This follows from the fact that

$$\{(x, y) | f(x) > t\} = \{x | f(x) > t\} \times \mathbb{R}^{d_2},$$

and the previous theorem. \square

Proposition 0.4

Let L be a linear map $\mathbb{R}^d \rightarrow \mathbb{R}^d$, $E \subset \mathbb{R}^d$ a measurable set, then $L(E)$ is measurable, and

$$m(L(E)) = |\det L| m(E).$$

Proof. In fact we only need to prove it for cuboids E and elementary linear transformation L .

Now we only need to look at the case where $L = \begin{pmatrix} 1 & c & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{pmatrix}$ since the other cases are

trivial or similar to this case.

Thus by Fubini's theorem, WLOG E is the unit cube,

$$m(L(E)) = \int \chi_{L(E)} = \int_{\mathbb{R}^{d-1}} \left(\int_{\mathbb{R}} \chi_{L(E)} dx_1 \right) = \int_{\mathbb{R}^{d-1}} \chi_{E'} \cdot 1 = 1 = |\det L| m(E),$$

where $E' = \{(x_2, \dots, x_n) | 0 \leq x_i \leq 1\}$. \square

From this transformation formula we deduce the integral version:

Let f be an integrable function on \mathbb{R}^d , then $f(L(x))$ is also integrable, and

$$\int f(L(x)) = \frac{1}{|\det L|} \int f(x).$$

Here we require $L \in \text{GL}(n)$, since if $\det L = 0$, the function $f(L(x))$ need not be measurable.

At last we take a look at Fubini's theorem with the convolution product.

Definition 0.5 (Convolution). Let f, g be smooth functions with compact support, define their **convolution** to be

$$f * g = \int f(x - y)g(y) dy.$$

Then $f * g$ is also a smooth function with compact support.

In fact we can generalize this definition for $f, g \in L^1$.

First note that $f(x - y), g(y)$ are measurable functions on \mathbb{R}^{2d} , by Tonelli's theorem,

$$\int_{\mathbb{R}^{2d}} |f(x - y)| |g(y)| dx dy = \int_{\mathbb{R}^d} \left(\int_{\mathbb{R}^d} |f(x - y)| |g(y)| dx \right) dy = \|f\|_{L^1} \|g\|_{L^1} < +\infty.$$

This shows that $f(x - y)g(y)$ is integrable on \mathbb{R}^{2d} . Hence by Fubini's theorem $f(x - y)g(y)$ is integrable as a function of y , and $f * g$ is integrable on \mathbb{R}^d .

Moreover we have

$$\|f * g\|_{L^1} \leq \|f\|_{L^1} \|g\|_{L^1}.$$

The equality holds when both f and g are non-negative.

Fubini's theorem is also useful when computing integrals.

Example 0.6 (Gauss integral)

Recall the Gauss integral:

$$\int_0^\infty e^{-x^2} dx = \frac{\sqrt{\pi}}{2}.$$

Here we give a different proof:

$$\begin{aligned} \int e^{-x^2} dx \int e^{-y^2} dy &= \iint_{\mathbb{R}^2} e^{-(x^2+y^2)} dx dy \\ &= \int_0^{+\infty} e^{-r^2} dr^2 \cdot \pi = \pi. \end{aligned}$$

§1 Lebesgue differentiation

The most important theorem in calculus is no doubt the Fundamental theorem of Calculus (which is also called Newton-Lebniz formula). Since we generalized the integrals, there must be a generalized version of this theorem:

Theorem 1.1 (Lebesgue differentiation theorem, part 1)

If f is integrable on \mathbb{R}^d , for any ball $B \subset \mathbb{R}^d$, we have

$$\lim_{x \in B, |B| \rightarrow 0} \frac{1}{m(B)} \int_B f(y) dy = f(x), a.e.$$

This theorem clearly holds for continuous points of f .

Our basic idea is to take a continuous g , such that $\|g - f\|_{\mathcal{L}^1} < \varepsilon$, and to prove

$$\left\{ x : \limsup_{x \in B, |B| \rightarrow 0} \frac{1}{m(B)} \int_B |f(y) - f(x)| dy \geq \varepsilon_0 \right\}$$

is a null set.

Now we estimate

$$\begin{aligned} \frac{1}{m(B)} \int_B |f(y) - f(x)| dy &\leq \frac{1}{m(B)} \int_B (|f(y) - g(y)| + |g(y) - g(x)| + |g(x) - f(x)|) dy \\ &= |f(x) - g(x)| + \varepsilon + \frac{1}{m(B)} \int_B |f(y) - g(y)| dy \end{aligned}$$

We find that the last term is pretty hard to deal with, so we'll introduce some new tools:

Definition 1.2 (Hardy-Littlewood maximal function). Let f be an integrable function on \mathbb{R}^d . Define

$$Mf(x) = \sup_{x \in B} \frac{1}{m(B)} \int_B |f(y)| dy.$$

to be the **maximal function** of f .

Theorem 1.3 (Hardy-Littlewood)

The maximal function Mf satisfies:

- Mf is measurable;
- For x almost everywhere, $|f(x)| \leq Mf(x) < +\infty$.
- There exists a constant C s.t.

$$|\{x : Mf > \alpha\}| \leq \frac{C}{\alpha} \|f\|_{\mathcal{L}^1}.$$

Proof. First we prove $\{Mf > \alpha\}$ is measurable. If $Mf(x_0) > \alpha$, then exists an open ball $B \ni x_0$,

$$\int_B |f(y)| dy > \alpha m(B).$$

This implies that $B \subset \{Mf > \alpha\} \implies \{Mf > \alpha\}$ is an open set.

For the second part, we'll prove for $\forall \varepsilon_0 > 0, N > 0$,

$$m(\{x : Mf(x) + \varepsilon_0 < |f(x)| \leq N\}) = 0.$$

Otherwise denote the above set as E , for $\forall 0 < \lambda < 1$, $\exists B$ s.t. $|E \cap B| > \lambda|B|$.

Thus for $x \in E$,

$$\begin{aligned} Mf(x) &\geq \frac{1}{m(B)} \int_B |f(y)| dy \\ &\geq \frac{1}{m(B)} \int_{E \cap B} |f(y)| dy \\ &\geq \frac{1}{m(B)} \int_{E \cap B} \varepsilon_0 + Mf(y) dy \\ &= \frac{m(E \cap B)}{m(B)} \varepsilon_0 + \frac{1}{|B|} \int_{E \cap B} Mf(y) dy. \end{aligned}$$

Taking the integral with respect to x :

$$\left(1 - \frac{|E \cap B|}{|B|}\right) \int_{E \cap B} Mf \geq \frac{|E \cap B|^2}{|B|} \varepsilon_0.$$

This implies $(1 - \lambda)N \geq \lambda \varepsilon_0$, which is impossible as $\lambda \rightarrow 1$.

Now for the last part, since $\{Mf > \alpha\}$ is open, $\forall x \in \{Mf > \alpha\}$, $\exists B$ s.t.

$$\int_B |f(y)| dy > \alpha m(B).$$

Hence for disjoint balls B_{i_k} ,

$$\|f\|_{\mathcal{L}^1} \geq \sum_{l=1}^k \int_{B_{i_l}} |f(y)| dy > \alpha \sum_{l=1}^k |B_{i_l}|.$$

If we could select B_{i_l} 's such that their measure achieves say 1% of E , then we're done.

Lemma 1.4

Let B_1, \dots, B_n be open balls in \mathbb{R}^d . There exists i_1, \dots, i_k such that B_{i_j} 's are pairwise disjoint, and

$$\bigcup_{i=1}^n B_i \subset \bigcup_{j=1}^k 3B_{i_j}.$$

Here $3B$ means to multiply the radius of the ball by 3.

Proof of lemma. Trivial, just take the largest ball first and using greedy algorithm. \square

Remark 1.5 — For countable many balls, the conclusion holds with 3 replaced by 5.

In particular, for all compact sets $K \subset \{Mf > \alpha\}$, there exists a finite open cover B_1, B_2, \dots, B_n of K . By lemma we can select B_{i_j} 's satisfying

$$\sum_{i=1}^k m(B_{i_j}) \geq \frac{1}{3^d} m\left(\bigcup_{i=1}^n B_i\right) \geq \frac{1}{3^d} m(K).$$

Combining with our previous discussion we get $\|f\|_{\mathcal{L}^1} \geq \frac{\alpha}{3^d} m(K)$. \square

Returning to the proof of [Theorem 1.1](#), we can assume g is continuous with compact support,

$$\frac{1}{m(B)} \int_B |f(y) - g(y)| dy \leq M(f - g)(x)$$

Hence by taking B sufficiently small s.t. $|g(y) - g(x)| \leq \varepsilon_0$ for all $x, y \in B$,

$$\begin{aligned} \frac{1}{m(B)} \int_B f(y) dy &\geq 3\varepsilon_0 \\ \iff |f(x) - g(x)| + M(f - g)(x) &\geq 2\varepsilon_0. \end{aligned}$$

But

$$m\{|f(x) - g(x)| \geq \varepsilon_0\} + m\{M(f - g) > \varepsilon_0\} \leq \frac{\|f - g\|_{\mathcal{L}^1}}{\varepsilon_0} + \frac{3^d}{\varepsilon_0} \|f - g\|_{\mathcal{L}^1} \leq \frac{3^d + 1}{\varepsilon_0} \varepsilon.$$

This completes the proof.

Definition 1.6 (Lebesgue points). Let $|f(x)| < \infty$, f is *locally integrable*. If x satisfies

$$\lim_{|B| \rightarrow 0, B \ni x} \frac{1}{|B|} \int_B |f(y) - f(x)| dy = 0,$$

we say x is a **Lebesgue point** of f .

Remark 1.7 — Here “locally integrable” means for all bounded measurable sets E , $f\chi_E \in \mathcal{L}^1$. This is denoted by $f \in \mathcal{L}_{loc}^1$.

Let E be a measurable set, χ_E locally integrable, If point x is called a **density point** of E if it's a Lebesgue point of χ_E .

Theorem 1.8

Let E be a measurable set, then almost all the points in E are density points of E , almost all the points outside of E are not density points of E .

Proof. This is a direct corollary of [Theorem 1.1](#). □

The differentiation theorem has some applications in convolution:

$$\begin{aligned} \frac{1}{|B|} \int_B f(y) \, dy &= c_d^{-1} \varepsilon^{-d} \int_{B(x, \varepsilon)} f(y) \, dy \\ &= \int f(x - y) \cdot c_d^{-1} \varepsilon^{-d} \chi_{B(0, \varepsilon)}(y) \, dy \\ &= f * K_\varepsilon. \end{aligned}$$

where $K_\varepsilon = c_d^{-1} \varepsilon^{-d} \chi_{B(0, \varepsilon)}$, c_d is the measure of a unit sphere in \mathbb{R}^d .

By differentiation theorem, $\lim_{\varepsilon \rightarrow 0} f * K_\varepsilon = f(x)$, a.e.. In the homework we proved that there doesn't exist a function I s.t. $f * I = f$ for all $f \in \mathcal{L}^1$, but the functions K_ε is approximating this “convolution identity”.

Definition 1.9. In general, if $\int K_\varepsilon = 1$, $|K_\varepsilon| \leq A \min\{\varepsilon^{-d}, \varepsilon|x|^{-d-1}\}$ for some constant A , we say K_ε is an [approximation to the identity](#).

“convolution kernel”

Let φ be a smooth function whose support is in $\{|x| \leq 1\}$, and $\int \varphi = 1$. The function $K_\varepsilon := \varepsilon^{-d} \varphi(\varepsilon^{-1}x)$ is called the Friedrichs smoothing kernel.

Theorem 1.10

If K_ε is an approximation to the identity, f integrable,

$$\lim_{\varepsilon \rightarrow 0} \|f * K_\varepsilon - f\|_{\mathcal{L}^1} = 0.$$

Proof.

$$\begin{aligned} |(f * K_\varepsilon)(x) - f(x)| &= \left| \int f(x - y) K_\varepsilon(y) \, dy - f(x) \right| \\ &\leq \int |f(x - y) - f(x)| |K_\varepsilon(y)| \, dy \\ &\leq \int_{|y| \leq R} |f(x - y) - f(x)| A \varepsilon^{-d} \, dy + \int_{|y| > R} |f(x - y) - f(x)| A \varepsilon |y|^{-d-1} \, dy. \end{aligned}$$

Taking the integral over \mathbb{R}^d :

$$\begin{aligned} \|K_\varepsilon * f - f\|_{\mathcal{L}^1} &\leq A \varepsilon^{-d} \int \int_{|y| \leq R} |f(x - y) - f(x)| \, dy \, dx + A \varepsilon \int \int_{|y| > R} |f(x - y) - f(x)| |y|^{-d-1} \, dy \, dx \\ &\leq A \varepsilon^{-d} \int \int_{|y| \leq R} |\tau_{-y} f(x) - f(x)| \, dy \, dx + A \varepsilon \int_{|y| > R} |y|^{-d-1} \int |\tau_{-y} f(x)| + |f(x)| \, dx \, dy \\ &\leq A \varepsilon^{-d} \int_{|y| \leq R} \|\tau_{-y} f - f\|_{\mathcal{L}^1} \, dy + A \varepsilon \int_{|y| > R} |y|^{-d-1} 2 \|f\|_{\mathcal{L}^1} \, dy. \end{aligned}$$

By the continuity of translation, $\forall \varepsilon_0$, let R be sufficiently small we have

$$\|\tau_{-y}f - f\|_{\mathcal{L}^1} < \varepsilon_0, \forall |y| < R.$$

$$\|K_\varepsilon * f - f\|_{\mathcal{L}^1} \leq A\varepsilon^{-d} R^d c_d \varepsilon_0 + \varepsilon R^{-1} C$$

where C is a constant.

Take suitable $\varepsilon, \varepsilon_0$ s.t. $R = \varepsilon \varepsilon_0^{-\frac{1}{2d}}$, then $LHS \leq C_1 \varepsilon_0^{\frac{1}{2}} + C_2 \varepsilon_0^{\frac{1}{2d}} \rightarrow 0$. \square

Theorem 1.11

Let K_ε be an approximation to the identity, f integrable,

$$\lim_{\varepsilon \rightarrow 0} f * K_\varepsilon = f(x)$$

holds for Lebesgue points x of f .

Proof. WLOG $x = 0$, let

$$\omega(r) = \frac{1}{r^d} \int_{B(0,r)} |f(y) - f(0)| \, dy,$$

we have $\lim_{r \rightarrow 0} \omega(r) = 0$, and ω is continuous.

$$\omega(r) \leq \frac{\|f\|_{\mathcal{L}^1}}{r^d} + |f(0)|,$$

Thus ω is bounded.

Therefore we can compute

$$\begin{aligned} |K_\varepsilon * f(x) - f(x)| &\leq \int |K_\varepsilon(y)| |f(x-y) - f(x)| \, dy \\ &\leq \int_{B(0,r)} |K_\varepsilon(y)| |f(x-y) - f(x)| \, dy + \sum_{k \geq 0} \int_{2^k r \leq |y| < 2^{k+1} r} |K_\varepsilon(y)| |f(x-y) - f(x)| \, dy \\ &\leq A\varepsilon^{-d} \cdot r^d \omega(r) + \sum_{k \geq 0} \int_{2^k r \leq |y| < 2^{k+1} r} A\varepsilon |y|^{-d-1} |f(x-y) - f(x)| \, dy \\ &\leq A\varepsilon^{-d} r^d \omega(r) + \sum_{k \geq 0} A\varepsilon 2^{-k(d+1)} r^{-d-1} \cdot 2^{(k+1)d} r^d \omega(2^{k+1} r) \\ &= A\varepsilon^{-d} r^d \omega(r) + A2^d \varepsilon r^{-1} \sum_{k \geq 0} 2^{-k} \omega(2^{k+1} r). \end{aligned}$$

Let $r = \varepsilon$, since $\omega(r)$ is continuous and bounded, we're done. \square

§1.1 Lebesgue Differentiation theorem part 2

Recall that Fundamental theorem of Calculus has a second part, Given any differentiable function $F(x)$, if $F'(x)$ Riemann integrable, then

$$F(b) - F(a) = \int_a^b F'(x) \, dx.$$

When F has nice properties (smooth), then it has a generalization to higher dimensions (Stokes' theorem).

But in Lebesgue integration theory, the derivative of a function is hard to define. Hence we'll find an alternative for $F'(x)$.

Example 1.12

Consider Heaviside function $H(t) = \begin{cases} 1, & t > 0 \\ 0, & t \leq 0 \end{cases}$

Then H is differentiable almost everywhere, but $\int_{-1}^1 H'(t) dt = 0 \neq H(1) - H(-1)$.

Example 1.13

Consider Cantor-Lebesgue function F , similarly we have $F'(x) = 0, a.e.$, but $\int_0^1 F'(x) dx = 0 \neq F(1) - F(0)$.

Definition 1.14 (Dini derivatives). Let $f(x)$ be a measurable function, define

$$D^+(f)(x) = \limsup_{h>0, h \rightarrow 0} \frac{f(x+h) - f(x)}{h}, \quad D^-(f)(x) = \limsup_{h<0, h \rightarrow 0} \frac{f(x+h) - f(x)}{h}.$$

$$D_+(f)(x) = \liminf_{h>0, h \rightarrow 0} \frac{f(x+h) - f(x)}{h}, \quad D_-(f)(x) = \liminf_{h<0, h \rightarrow 0} \frac{f(x+h) - f(x)}{h}.$$

Theorem 1.15 (Lebesgue Differentiation theorem for increasing functions)

Let f be an increasing function on $[a, b]$, then $F'(x)$ exists almost everywhere, and

$$\int_a^b F'(x) dx \leq F(b) - F(a).$$

Sketch of the proof. The outline of the proof is as follows:

Step 1: Decompose $F = F_c + J$, where F_c is continuous, J is a jump function.

Step 2: Prove F_c increasing and $J' = 0, a.e.$

Step 3: Prove $D^+(F) < +\infty, a.e.$, $D^+(F) \leq D_-(F), a.e.$, and $D^-(F) \leq D_+(F), a.e.$ □

We proceed step by step.

Step 1 Denote $F(x+0) = \lim_{h \rightarrow 0^+} F(x+h)$, $F(x-0) = \lim_{h \rightarrow 0^-} F(x+h)$.

Since F increasing, let $\{x_n\}$ be all the discontinuous points of F . Define:

$$j_n(x) = \begin{cases} 0, & x < x_n \\ \beta_n, & x = x_n \\ \alpha_n, & x > x_n \end{cases}$$

where $\alpha_n = F(x_n+0) - F(x_n-0)$, $\beta_n = F(x_n) - F(x_n-0)$.

Hence the jump function

$$J_F(x) = \sum_{n=1}^{+\infty} j_n(x) \leq \sum_{n=1}^{+\infty} \alpha_n = \sum_{n=1}^{+\infty} (F(x_n + 0) - F(x_n - 0)) \leq F(b) - F(a)$$

is well-defined and increasing.

Theorem 1.16

$F - J_F$ is continuous and increasing.

Proof. First note that

$$\lim_{h \rightarrow 0^+} (F(x+h) - J_F(x+h)) = F(x+0) - \lim_{h \rightarrow 0^+} J_F(x+h) = F(x-0) - \lim_{h \rightarrow 0^+} J_F(x-h)$$

This can be derived from the definition of J_F : If F is continuous at x , the equality is obvious;

If $x = x_n$ for some n ,

$$\begin{aligned} \lim_{h \rightarrow 0^+} J_F(x+h) &= \sum_{x_k \leq x_n} \alpha_k + \lim_{h \rightarrow 0^+} \sum_{x_n < x_k \leq x_n+h} j_k(x+h) = \sum_{x_k \leq x_n} \alpha_k \\ \lim_{h \rightarrow 0^+} J_F(x-h) &= \lim_{h \rightarrow 0^+} \sum_{x_k < x_n-h} \alpha_k + \lim_{j \rightarrow 0^+} \sum_{x_k = x_n-h} \beta_k = \sum_{x_k < x_n} \alpha_k \end{aligned}$$

Note that $\alpha_n = F(x_n + 0) - F(x_n - 0)$, thus $F - J_F$ is continuous.

Secondly,

$$F(x) - J_F(x) \leq F(y) - J_F(y), \quad \forall a \leq x \leq y \leq b.$$

Because

$$J_F(y) - J_F(x) = \sum_{x < x_j < y} \alpha_j + \sum_{x_k = y} \beta_k - \sum_{x_k = x} \beta_k \leq \sum_{x < x_j < y} \alpha_j + F(y) - F(y-0) \leq F(y) - F(x).$$

which means $F - J_F$ is increasing. \square