# Course 3: Unsupervised Learning



# Summary

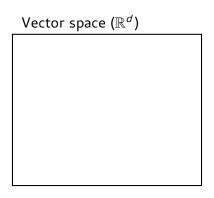
#### Last session

- Supervised learning learning from labeled examples
- Bias/variance tradeoff
- Overfitting and cross-validation
- 4 VC Dimension and curse of dimensionality

#### Today's session

- Learning from Unlabeled examples
- Clustering, decomposition and dimensionality reduction

### **Notations**



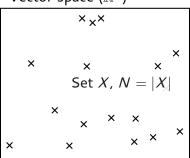
### **Notations**

Vector space 
$$(\mathbb{R}^d)$$

Vector  $\mathbf{x} \ (\in \mathbb{R}^d)$ 

### **Notations**

## Vector space ( $\mathbb{R}^d$ )



#### Goal

Discover patterns/structure in X,

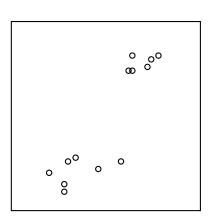
- Unsupervised = no expert, no labels,
- Two main approaches:
  - Clustering = find a partition of X in K
    subsets
  - Decomposition using K vectors.
- Applications :
  - Quantization
  - Visualization...



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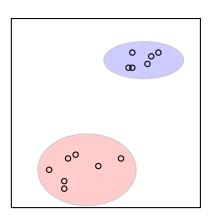
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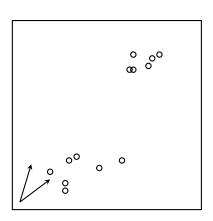
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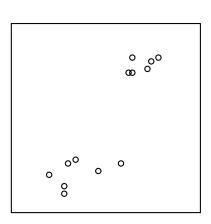
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## Example: clustering using $L_2$ norm (1/6)

An example to perform clustering is to rely on distances to centroids. We define K cluster centroids  $\Omega_k, \forall k \in [1..K]$ 

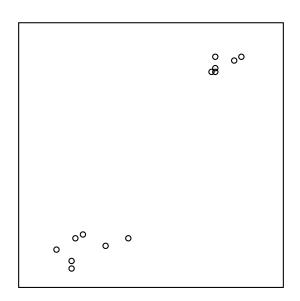
#### **Definitions**

We denote  $q : \mathbb{R}^d \to [1..K]$  a function that associates a vector  $\mathbf{x}$  with the index of (one of) its closest centroid  $q(\mathbf{x})$ . Formally:

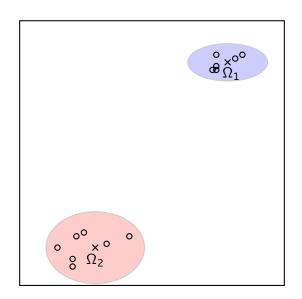
- $\forall k \in [1..K], \Omega_k \in \mathbb{R}^d$
- $\forall \mathbf{x} \in X, \forall j \in [1..K], \|\mathbf{x} \Omega_{q(\mathbf{x})}\|_2 \le \|\mathbf{x} \Omega_j\|_2$
- Error  $E(q) \triangleq \sum_{\mathbf{x} \in X} \|\mathbf{x} \Omega_{q(\mathbf{x})}\|_2$
- $X = \bigcup_k \{ \mathbf{x} \in X, q(\mathbf{x}) = k \}$

cluster k

## Example: clustering using $L_2$ norm (2/6)



## Example: clustering using $L_2$ norm (2/6)



# Clustering using $L_2$ norm (3/6)

#### **MNIST Dataset**

- "Toy" dataset (=small and easy)
- 60000 + 10000 handwritten digits

## Clustering MNIST

Using K-means algorithm with K = 10

- 00011112223
- 33444555666
- 6771888999











# Clustering using $L_2$ norm (4/6)

### Quantizing MNIST

- Replace **x** by  $\Omega_{k(\mathbf{x})}$
- Compression factor  $\kappa = 1 K/N$



# Clustering using $L_2$ norm (5/6)

## Optimal clustering

- Define  $E_{opt_{\mathcal{K}}}(q^*) \triangleq \arg\min_{q:\mathbb{R}^d o [1..\mathcal{K}]} E(q)$ ,
- Finding an optimal clustering is an NP-hard problem.

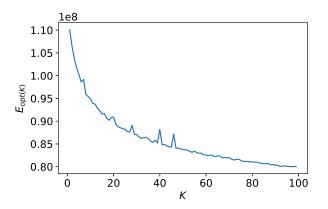
#### **Properties**

- $lacksquare 0 = E_{opt_N}(q^*) \le E_{opt_{N-1}}(q^*) \le \cdots \le E_{opt_1}(q^*) = var(X),$ 
  - Proof: monotonicity by particularization, extremes with identity function (left) and variance (right).
- $0 \le \kappa \le \frac{N-1}{N}$ .

# Clustering using $L_2$ norm (6/6)

## Choosing K

- Finding a compromise between error and compression,
- Simple practical method : "elbow".

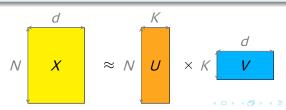


# Example 2: Sparse Dictionary Learning (1/4)

#### **Definitions**

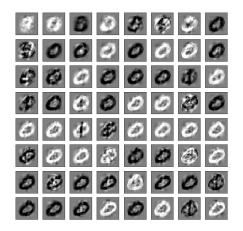
Dictionary learning solves the following matrix factorization problem:

- The set X is considered as a matrix  $X \in \mathcal{M}_{N \times d}(\mathbb{R})$ ,
- We consider decompositions using a dictionary  $V \in \mathcal{M}_{K \times d}(\mathbb{R})$  and a code  $U \in \mathcal{M}_{N \times k}(\mathbb{R})$ , with the lines of V being with norm 1,
- Error  $E(U, V) \triangleq ||X UV||_2 + \alpha ||U||_1$
- Training: find  $U^*$ ,  $V^*$  that minimizes  $E(U^*, V^*)$
- lpha is a sparsity control parameter that enforces codes with soft  $(\ell_1)$  sparsity



## Example: Sparse Dictionary Learning (2/4)

Learning a dictionary on MNIST with K=64



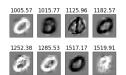
# Example 2: Sparse Dictionary Learning (3/4)

Reconstruction  $\tilde{\mathbf{x}} = UV$  of  $\mathbf{x}$ 



#### 8 atoms with largest absolute values:









# Example 2: Sparse Dictionary Learning (4/4)

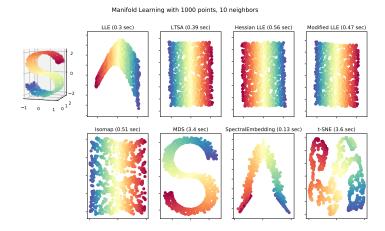
### Optimal error

■  $E_{opt}(K) \triangleq \arg \min_{U,V} E(U,V)$ .

#### Some results

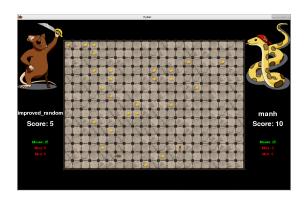
- For  $\alpha = 0$  and  $K \ge d$ ,  $E_{opt}(K) = 0$ ,
  - One can choose any completion of a basis.
- For K = N,  $\forall \alpha, E_{opt}(K) = \alpha N$ ,
  - If vectors of X are with norm 1, one can choose V = X and  $U = I_N$ .

## Example 3: Manifold Learning



Approaches to uncover lower dimensional structure of high dimensional data. Source: Manifold module, sklearn website

## Non-symmetric PyRat without walls / mud



Can you find patterns in Lost and Draw games using Unsupervised learning?

## Lab Session 3 and assignments for Session 5

## TP Unsupervised Learning (TP2)

- K-means, Dictionary Learning and Manifold Learning
- Application on Digits and PyRat

### Project 2 (P2)

You will choose an unsupervised learning method. You have to prepare a Jupyter Notebook on this method, including:

- A brief description of the theory behind the method,
- Advanced tests and analysis on your own PyRat Datasets.

During Session 5 (May 16) you will have 7 minutes to present your notebook.