



# Understanding stereo-opacity bias in MISR and CAMP2Ex P3 observations



## Understanding stereo-opacity bias in MISR and CAMP2Ex P3 observations

*Arka Mitra<sup>1</sup>, Larry Di Girolamo<sup>1</sup>, Yulan Hong<sup>1</sup>, Yizhe Zhan<sup>1,2</sup>, Kevin J. Mueller<sup>3</sup>, Dongwei Fu<sup>1</sup>, Jesse Ray Loveridge<sup>1</sup>, Bastiaan van Diedenhoven (RSP Team)<sup>4</sup>, Chris Hostetler (HSRL2 Team)<sup>5</sup>, Sebastian Schmidt (All-sky Camera Team)<sup>6</sup>, Susan C. van den Heever (Dropsonde Team)<sup>7</sup>*

<sup>1</sup>University of Illinois, Urbana-Champaign, Illinois, USA

<sup>2</sup>Metservice, New Zealand

<sup>3</sup>Jet Propulsion Laboratory, California Institute of Technology, California, USA

<sup>4</sup>NASA Langley Research Center, USA

<sup>5</sup>NASA's Goddard Institute for Space Studies, USA

<sup>6</sup>University of Colorado, Boulder, USA

<sup>7</sup>Colorado State University, Fort Collins, USA

# Contents

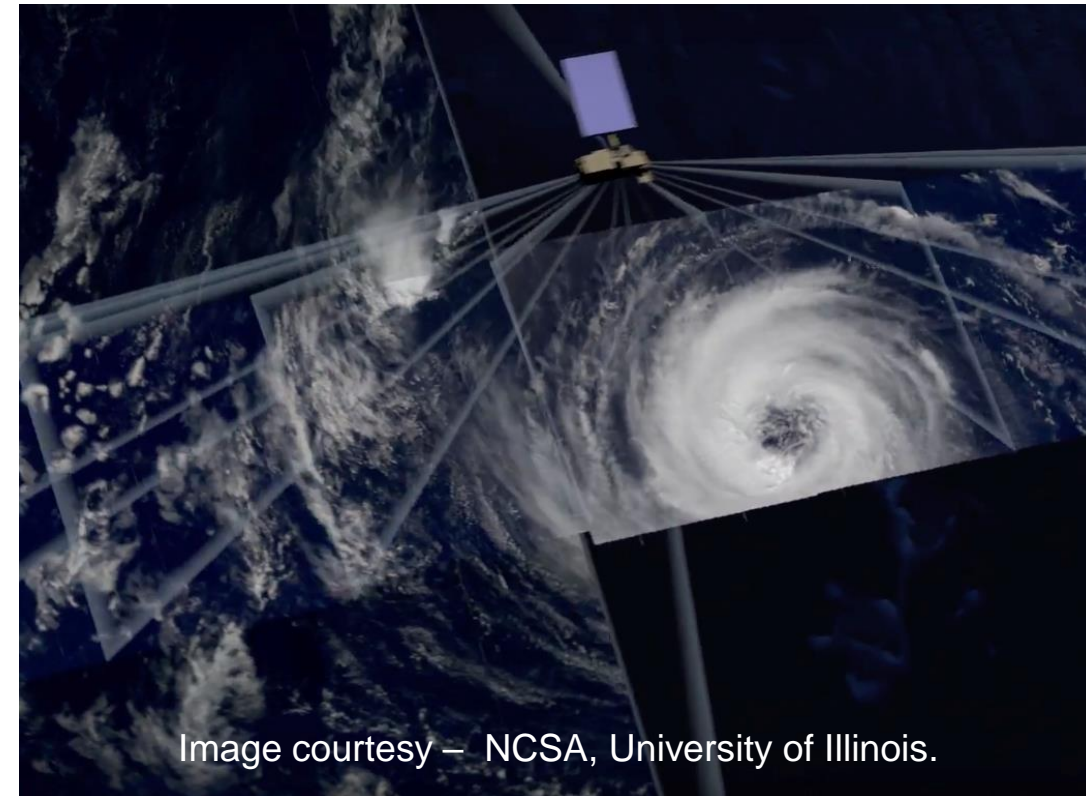
1. Motivation and Background
2. Terra Record and MISR
3. Comparison with CATS lidar
4. Methodology and Findings
5. Stereo-Opacity and Wind-related Bias
6. CAMP2Ex P3 estimates of Stereo Bias
7. Conclusions and Future work

# 1. Motivation and Background

- Stereo CTH retrieval is a *purely geometric*, free from radiometric calibration and forward model issues.
- *Stereoscopic CTH detection in the visible to near-IR is very sensitive to low clouds* (highly reflective and textured).
- Stereo CTH errors arise from primarily 3 sources :
  - a) Multi-angular radiance co-registration bias
  - b) Wind-related errors
  - c) Stereo-opacity bias
- This study aims to estimate these errors from satellite and CAMP2Ex retrievals.

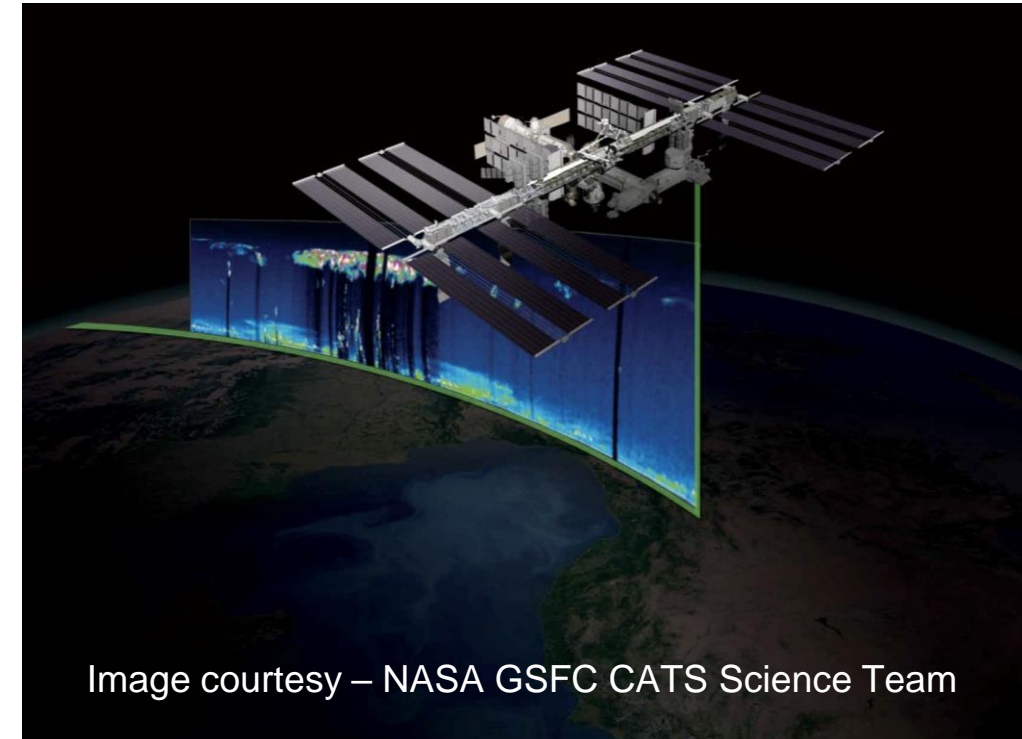
## 2. Terra Record and MISR

- NASA's 20-year-long mission – TERRA – has on-board, the Multiangle Imaging Spectroradiometer (MISR).
- Terra has exhibited great *orbital stability*.
- MISR stereo CTH is an important climate record. The first stereo instrument where *heights and winds were simultaneously retrieved*.
- Global validation not done previously for lack of active sensor to compare against.



# 3. Comparison with CATS lidar

- CATS lidar operated out of the International Space Station (ISS) between 2015-2017.
- *Concurrent (<5 minutes) and collocated (<1 km) cloudy data points* from CATS and MISR were chosen for our study.
- CATS *top-layer height* = “True” CTH.
- Opacity of cloud layer is given by the *layer-integrated attenuated backscatter* ( $\gamma$ ) from CATS.
- Terra MODIS CTH were also compared.

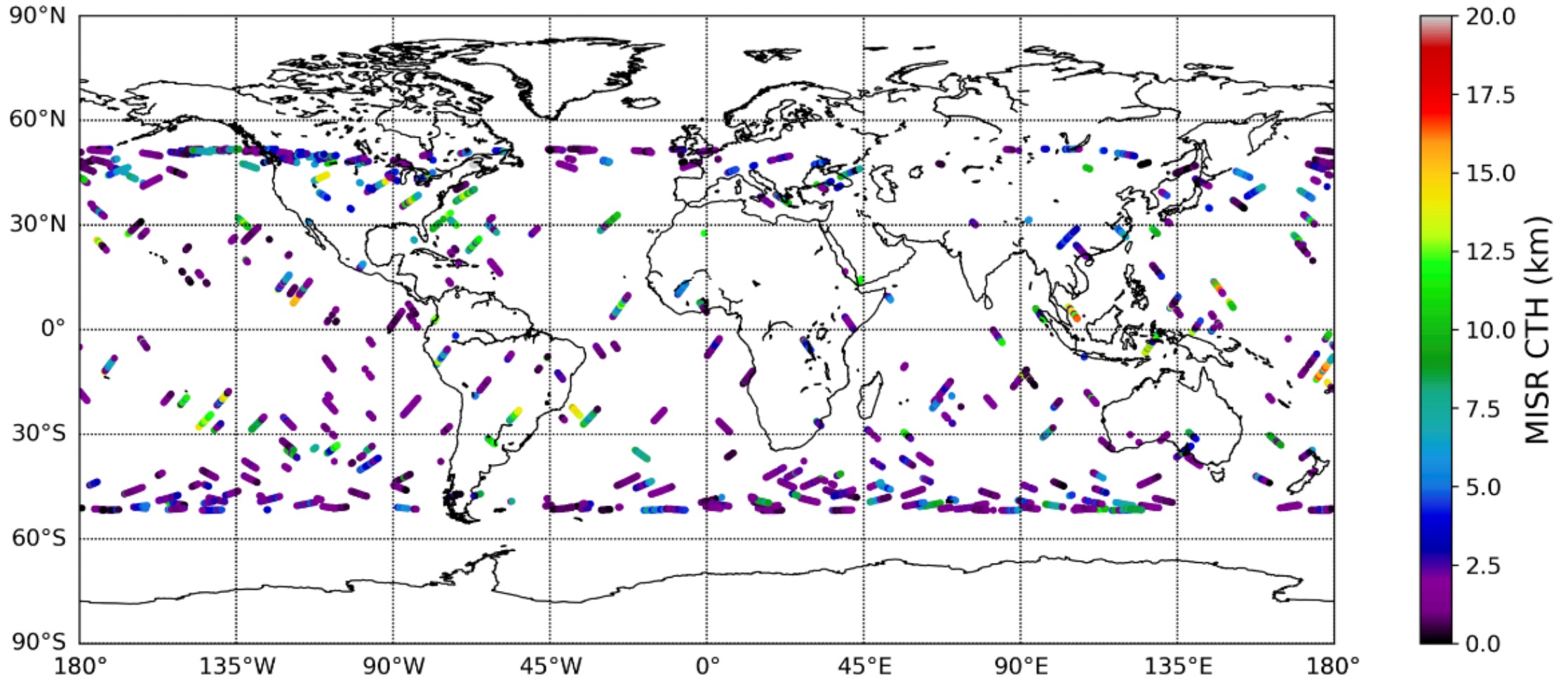


## Level 2 Data

- (a) MISR – TC\_CLOUD v001 (1.1 km resolution)
- (b) CATS - Version 2.01 Product (5 km horizontal, 60 m vertical resolution)



# 3. Comparison with CATS lidar



**Global Map of CATS-MISR collocations with MISR CTH**

Recording may be in progress - By joining this telecon, you automatically consent to such recording.

### 3. Comparison with CATS lidar

#### Key Questions :

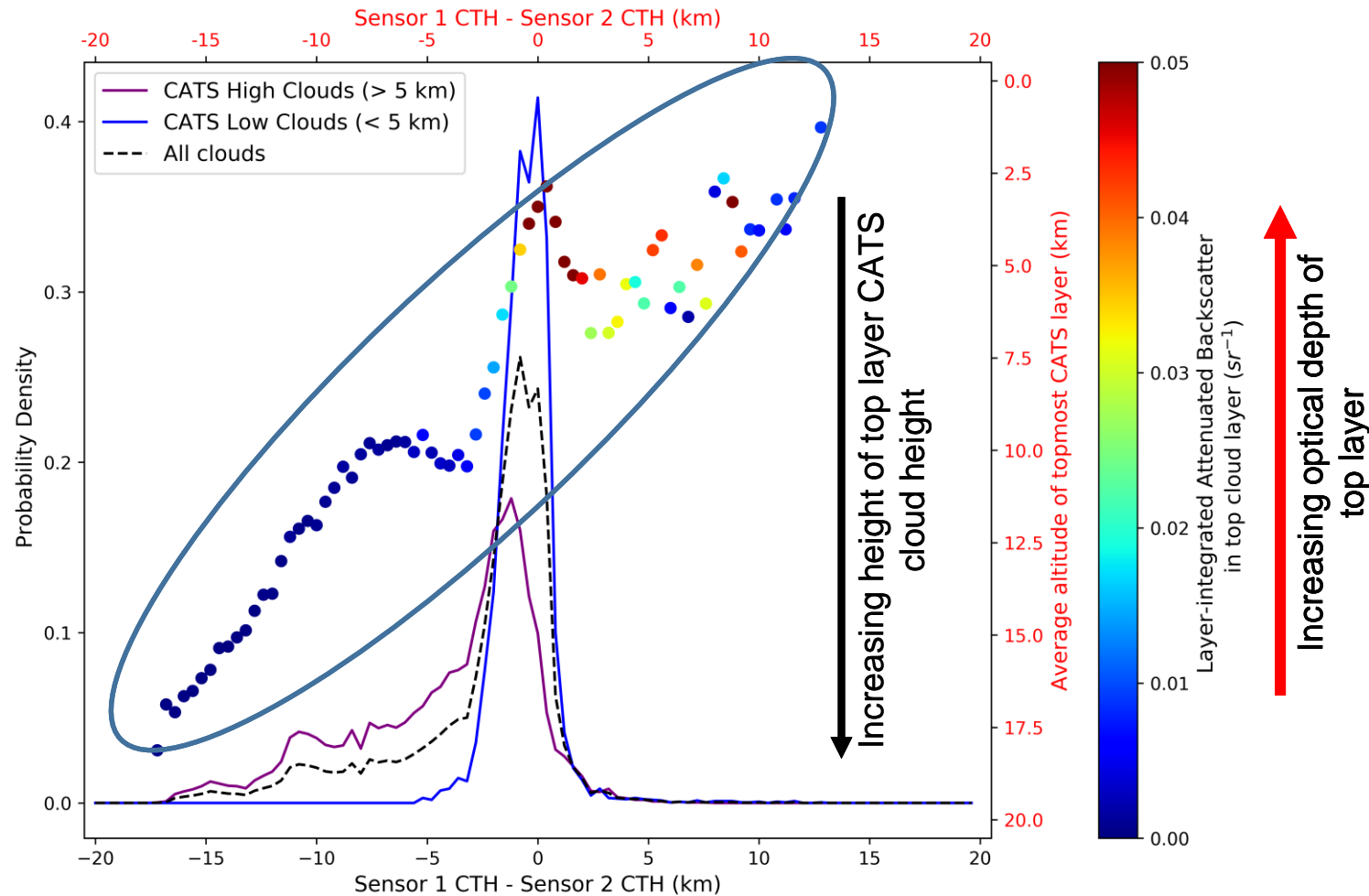
MISR is extremely sensitive to low-level clouds.

- What is the estimated bias and precision?
- How does CTH bias vary with cloud type?

MISR retrieves low-level CTH even in the presence of high cirrus.

- How thick does the cirrus have to be before stereo can detect it?

# 4. Methodology and Findings



Histograms are *approximately Gaussian*.

**Bias** : Deviation of peak or mode from zero.

**Precision** :  $\text{FWHM}/(2 \log 2)$ , where FWHM is the full-width at half maximum.

These statistics are not susceptible to outliers, unlike mean and SD.



# 4. Methodology and Findings

- **MISR CTH errors:**
  - (a) **Cloud altitude :**
    - *Low clouds (CATS CTH < 5 km) :  $-320 \pm 254$  m*
    - *High clouds (CATS CTH > 5 km) :  $-540 \pm 593$  m*
  - (b) **Cloud opacity for low clouds:**
    - *'Optically thin' (OD < ~1) :  $-320 \pm 309$  m*
    - *'Optically thick' (OD > ~1) :  $-280 \pm 257$  m*
- MISR is *sensitive to lower layer in a 2-layered system, if upper-layer OD < ~0.4*, hinting at the possibility of an **"opacity threshold"** required for detection.

# 5. Stereo-Opacity and Wind-related Bias

Only unbroken and single-layered clouds

Instrument	Overall		High (CATS CTH > 10 km)		Mid-level (10 km > CTH > 5 km)		Low (CATS CTH < 5 km)	
	Bias (m)	Precision (m)	Bias (m)	Precision (m)	Bias (m)	Precision (m)	Bias (m)	Precision (m)
MISR	-282	373	-305	396	-373	401	-237	302

**MISR overall CTH bias : -282 m.**

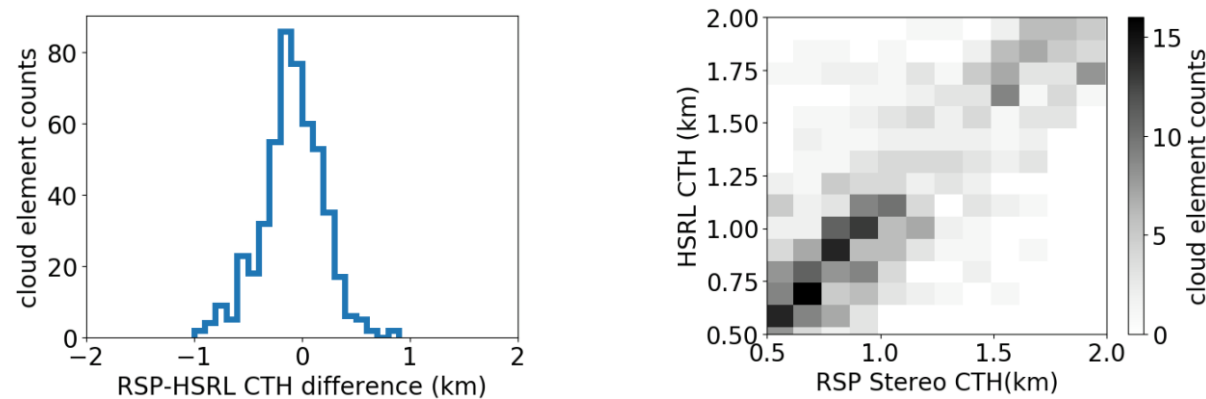
**Contributors :**

- **Radiance Co-registration error** : -28 m
- **Wind-driven bias** (*based on wind-height biases reported in Horvath 2013, compared to METEOSAT motion vectors*) :  
**Low clouds**: -144 m  
**High clouds**: -72 m
- **Stereo-Opacity Bias** (*limits estimated by first assuming biases to be free from wind-driven bias, and then including wind-driven bias*)\*:  
**Low clouds** : -65 to -209 m  
**High clouds** : -205 to -277 m

\* First estimate of a stereo-opacity CTH bias

# 6. CAMP2Ex P3 estimates of Stereo Bias

**(a) Stereo-Opacity Bias** – Redo similar analysis using *RSP* & *HSRL* (Dongwei Fu) ~ -104 m.



**(b) Wind-driven bias** – Stereo reconstruction using all-sky camera (Jesse Ray Loveridge)

Wind estimates will be obtained from dropsondes and mini-reanalysis.

Near-surface retrievals can be used to inform co-registration errors.

# 7. Conclusions and Future Work

- **MISR vs CATS CTH Comparison**
  - First robust quasi-global validation of MISR Stereo CTH.
  - MISR *bias* (-282 m) and *precision* (373 m) are robust for decadal climate analysis.
  - *First estimate of stereo-opacity CTH bias* (-65 to -277 m).
  - Independent estimates of global *wind-driven stereo CTH bias* (-72 to -144 m), *first against a lidar*.
- **Future work:**
  - Independent validation of findings against CAMP2Ex P3 observations, free from geo-collocation issues.
  - Radiative transfer simulation investigation into the physical nature of “opacity threshold” for stereo detection of a cloud layer.