

To understand the derivation of the Hebbian, anti-Hebbian network written in the paper, I derived it again by myself.

The cost function we would like to optimize is:

$$y_T = \arg \min_{y_T \geq 0} \|X'X - Y'Y\|_F^2 + \lambda \text{rank}(Y) \quad (1)$$

$$y_T = \arg \min_{y_T \geq 0, \text{Card}(y_T) \geq \text{Card}(y_{T-1})} \left[\sum_{t=1}^T \sum_{s=1}^T (x'_t x_s - y'_t y_s)^2 + \lambda \text{Card}(y_T) \right] \quad (2)$$

$$= \arg \min_{y_T \geq 0, \text{Card}(y_T) \geq \text{Card}(y_{T-1})} \left[2 \sum_{t=1}^{T-1} (x'_t x_T - y'_t y_T)^2 + (x'_T x_T - y'_T y_T)^2 + \lambda \text{Card}(y_T) \right] \quad (3)$$

$$= \arg \min_{y_T \geq 0, \text{Card}(y_T) \geq \text{Card}(y_{T-1})} \left[2 \sum_{t=1}^{T-1} ((x'_t x_T)^2 - 2x'_t x_T y'_t y_T + (y'_t y_T)^2) + \right. \\ \left. ((x'_T x_T)^2 - 2x'_T x_T y'_T y_T + (y'_T y_T)^2) + \lambda \text{Card}(y_T) \right] \quad (4)$$

We can remove terms which are not related with y_T , so

$$= \arg \min_{y_T \geq 0, \text{Card}(y_T) \geq \text{Card}(y_{T-1})} \left[2 \sum_{t=1}^{T-1} (-2x'_t x_T y'_t y_T + (y'_t y_T)^2) \right. \\ \left. - 2x'_T x_T y'_T y_T + (y'_T y_T)^2 + \lambda \text{Card}(y_T) \right] \quad (5)$$

$$= \arg \min_{y_T \geq 0, \text{Card}(y_T) \geq \text{Card}(y_{T-1})} \left[\sum_{t=1}^{T-1} (-4x'_t x_T y'_t y_T + 2(y'_t y_T)^2) \right. \\ \left. - 2x'_T x_T y'_T y_T + (y'_T y_T)^2 + \lambda \text{Card}(y_T) \right] \quad (6)$$

x is n -dim vector and y is m -dim vector.

$$\begin{aligned}
= & \arg \min_{y_T \geq 0, \text{Card}(y_T) \geq \text{Card}(y_{T-1})} \left[\sum_{t=1}^{T-1} \left\{ \left(-4 \sum_{j=1}^n x_{tj} x_{Tj} \right) \left(\sum_{i=1}^m y_{ti} y_{Ti} \right) + 2 \left(\sum_{i=1}^m y_{ti} y_{Ti} \right)^2 \right\} \right. \\
& - 2 \left(\sum_{j=1}^n x_{Tj} x_{Tj} \right) \left(\sum_{i=1}^m y_{Ti} y_{Ti} \right) + \left(\sum_{i=1}^m y_{Ti} y_{Ti} \right)^2 + \\
& \left. + \lambda \text{Card}(y_T) \right] \tag{7}
\end{aligned}$$

$$\begin{aligned}
= & \arg \min_{y_T \geq 0, \text{Card}(y_T) \geq \text{Card}(y_{T-1})} \left[-4 \sum_{i=1}^m y_{Ti} \sum_{j=1}^n x_{Tj} \sum_{t=1}^{T-1} y_{ti} x_{tj} \right. \\
& + 2 \sum_{i=1}^m y_{Ti} \sum_{k=1}^m y_{Tk} \sum_{t=1}^{T-1} y_{ti} y_{tk} \\
& - 2 \sum_{i=1}^m \|x_T\|_2^2 y_{Ti}^2 + \\
& \sum_{i=1}^m y_{Ti}^2 \sum_{k=1}^m y_{Tk}^2 + \\
& \left. + \lambda \text{Card}(y_T) \right] \tag{8}
\end{aligned}$$

$$\begin{aligned}
= & \arg \min_{y_T \geq 0, \text{Card}(y_T) \geq \text{Card}(y_{T-1})} \sum_{i=1}^m \left[-4 y_{Ti} \sum_{j=1}^n x_{Tj} \sum_{t=1}^{T-1} y_{ti} x_{tj} \right. \\
& + 2 y_{Ti} \sum_{k=1}^m y_{Tk} \sum_{t=1}^{T-1} y_{ti} y_{tk} \\
& - 2 \|x_T\|_2^2 y_{Ti}^2 + \\
& y_{Ti}^2 \sum_{k=1}^m y_{Tk}^2 \\
& \left. \right] + \lambda \text{Card}(y_T) \tag{9}
\end{aligned}$$

We think about optimizing this by applying coordinate descent for each dimension of y_T .

$$y_{Ti} = \arg \min_{y_{Ti} \geq 0, \text{Card}(y_T) \geq \text{Card}(y_{T-1})} \left[-4y_{Ti} \sum_{j=1}^n x_{Tj} \sum_{t=1}^{T-1} y_{ti} x_{tj} \right. \quad (10)$$

$$+ 4y_{Ti} \sum_{k=1, k \neq i}^m y_{Tk} \sum_{t=1}^{T-1} y_{ti} y_{tk} + 2y_{Ti}^2 \sum_{t=1}^{T-1} y_{ti}^2$$

$$- 2 \|x_T\|_2^2 y_{Ti}^2 +$$

$$2y_{Ti}^2 \sum_{k=1, k \neq i}^m y_{Tk}^2 + y_{Ti}^4 \left. \right]$$

$$= \arg \min_{y_{Ti} \geq 0, \text{Card}(y_T) \geq \text{Card}(y_{T-1})} \left[-4y_{Ti} \sum_{j=1}^n x_{Tj} \sum_{t=1}^{T-1} y_{ti} x_{tj} \right. \quad (11)$$

$$+ 4y_{Ti} \sum_{k=1, k \neq i}^m y_{Tk} \sum_{t=1}^{T-1} y_{ti} y_{tk} + 2y_{Ti}^2 \sum_{t=1}^{T-1} y_{ti}^2$$

$$\left(2 \sum_{k=1, k \neq i}^m y_{Tk}^2 - 2 \|x_T\|_2^2 \right) y_{Ti}^2 + y_{Ti}^4 \left. \right]$$

If the i -th node of output y_T has not been utilized during $t = 1$ to $T - 1$, i.e. $\sum_{t=1}^{T-1} y_{ti}^2 = 0$, we adjust the output as

$$y_{Ti} = \arg \min_{y_{Ti} \geq 0} \left[\left(\|x_T\|_2^2 - \sum_{k=1, k \neq i}^m y_{Tk}^2 \right) - y_{Ti}^2 \right]^2 + \lambda \|y_{Ti}\|_0 = \quad (12)$$

$$\begin{cases} 0, & \left(\|x_T\|_2^2 - \sum_{k=1, k \neq i}^m y_{Tk}^2 \right)^2 \leq \lambda \\ \left(\|x_T\|_2^2 - \sum_{k=1, k \neq i}^m y_{Tk}^2 \right)^{1/2}, & \left(\|x_T\|_2^2 - \sum_{k=1, k \neq i}^m y_{Tk}^2 \right)^2 > \lambda \end{cases}$$

Once the i -th output node becomes active, then $\sum_{t=1}^{T-1} y_{ti}^2 > 0$, so can write the equation as

$$y_{Ti} = \arg \min_{y_{Ti} \geq 0} \sum_{t=1}^{T-1} y_{ti}^2 \left[-\frac{4y_{Ti} \sum_{j=1}^n x_{Tj} \sum_{t=1}^{T-1} y_{ti} x_{tj}}{\sum_{t=1}^{T-1} y_{ti}^2} \right. \quad (13)$$

$$\begin{aligned} & + \frac{4y_{Ti} \sum_{k=1, k \neq i}^m y_{Tk} \sum_{t=1}^{T-1} y_{ti} y_{tk}}{\sum_{t=1}^{T-1} y_{ti}^2} + 2y_{Ti}^2 \\ & \left. \frac{2 \left(\sum_{k=1, k \neq i}^m y_{Tk}^2 - \|x_T\|_2^2 \right) y_{Ti}^2}{\sum_{t=1}^{T-1} y_{ti}^2} + \frac{y_{Ti}^4}{\sum_{t=1}^{T-1} y_{ti}^2} \right] \\ & = \arg \min_{y_{Ti} \geq 0} \sum_{t=1}^{T-1} y_{ti}^2 \left[-4y_{Ti} \sum_{j=1}^n \left(\frac{\sum_{t=1}^{T-1} y_{ti} x_{tj}}{\sum_{t=1}^{T-1} y_{ti}^2} \right) x_{Tj} \right. \quad (14) \\ & + 4y_{Ti} \sum_{k=1, k \neq i}^m \left(\frac{\sum_{t=1}^{T-1} y_{ti} y_{tk}}{\sum_{t=1}^{T-1} y_{ti}^2} \right) y_{Tk} + 2y_{Ti}^2 \\ & \left. \frac{2 \left(\sum_{k=1, k \neq i}^m y_{Tk}^2 - \|x_T\|_2^2 \right) y_{Ti}^2}{\sum_{t=1}^{T-1} y_{ti}^2} + \frac{y_{Ti}^4}{\sum_{t=1}^{T-1} y_{ti}^2} \right] \end{aligned}$$

At the large T limit, $\sum_{t=1}^{T-1} y_{ti}^2$ in the denominators of the 3rd and 4th term become large. So we can ignore the 3rd and 4th term.

$$y_{Ti} \approx \arg \min_{y_{Ti} \geq 0} \sum_{t=1}^{T-1} y_{ti}^2 \left[-4y_{Ti} \sum_{j=1}^n \left(\frac{\sum_{t=1}^{T-1} y_{ti} x_{tj}}{\sum_{t=1}^{T-1} y_{ti}^2} \right) x_{Tj} \right. \quad (15) \\ \left. + 4y_{Ti} \sum_{k=1, k \neq i}^m \left(\frac{\sum_{t=1}^{T-1} y_{ti} y_{tk}}{\sum_{t=1}^{T-1} y_{ti}^2} \right) y_{Tk} + 2y_{Ti}^2 \right] \end{aligned}$$

$$\approx \arg \min_{y_{Ti} \geq 0} \sum_{t=1}^{T-1} y_{ti}^2 \left[-4y_{Ti} \sum_{j=1}^n W_{Tij} x_{Tj} \right. \quad (16) \\ \left. + 4y_{Ti} \sum_{k=1, k \neq i}^m M_{Tik} y_{Tk} + 2y_{Ti}^2 \right] \end{aligned}$$

Here we used the substitution of W, M as

$$\begin{aligned}
W_{Tij} &= \frac{\sum_{t=1}^{T-1} y_{ti} x_{tj}}{\sum_{t=1}^{T-1} y_{ti}^2} \\
M_{Tik \neq i} &= \frac{\sum_{t=1}^{T-1} y_{ti} y_{tk}}{\sum_{t=1}^{T-1} y_{ti}^2}; M_{Tii} = 0
\end{aligned} \tag{17}$$

This optimization can be treated as

$$y_{Ti} \approx \arg \min_{y_{Ti} \geq 0} (W_{Ti} x_{Tj} - M_{Ti} y_T - y_{Ti})^2 \tag{18}$$

And we obtain,

$$y_{Ti} = \max(W_{Ti} x_T - M_{Ti} y_T, 0) \tag{19}$$