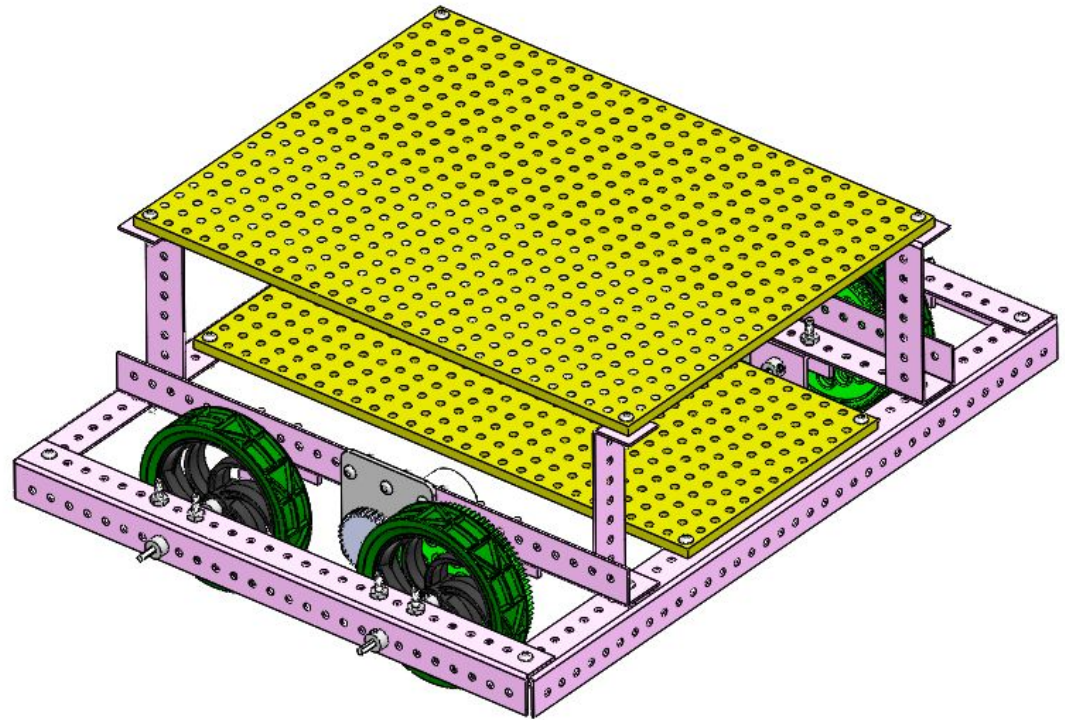


# BASE KIT MANUAL

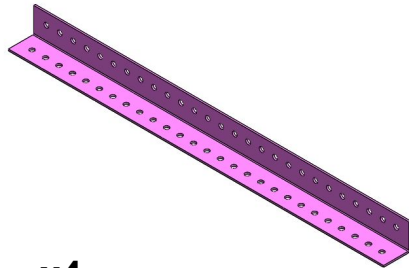


THE BUILD

# PIONEERS IN ENGINEERING

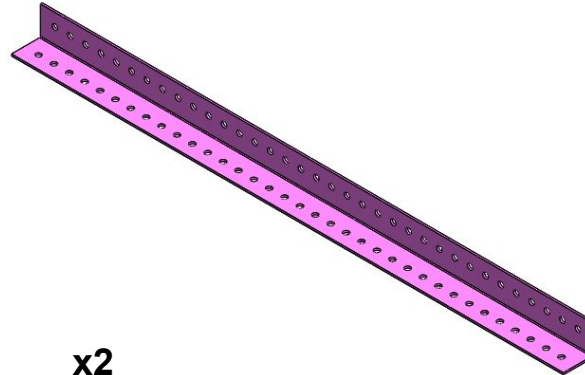
## PARTS

\*COLORS ARE FOR ILLUSTRATION



x4

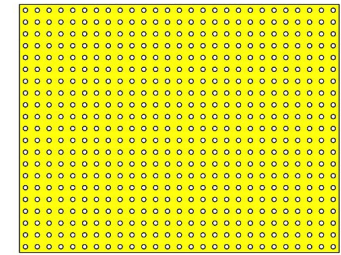
27-Hole PiE Metal



x2

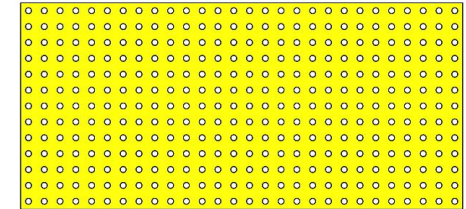
35-Hole PiE Metal

x1



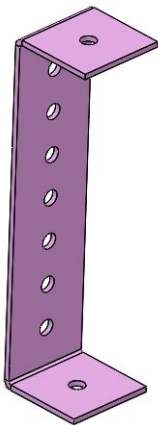
6.5" x 13.5" Plastic

x1



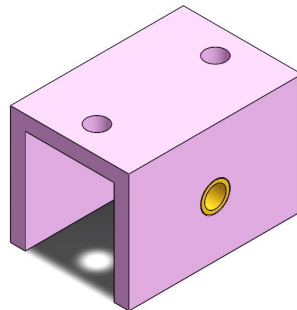
10.5" x 13.5" Plastic

x4



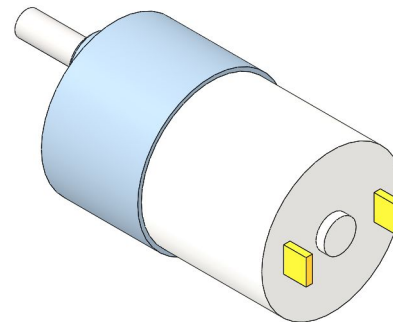
Standoff

x8



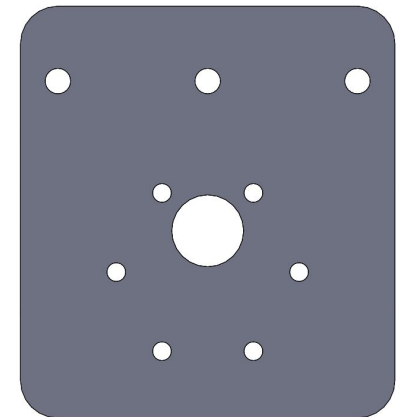
Bearing Block

x2



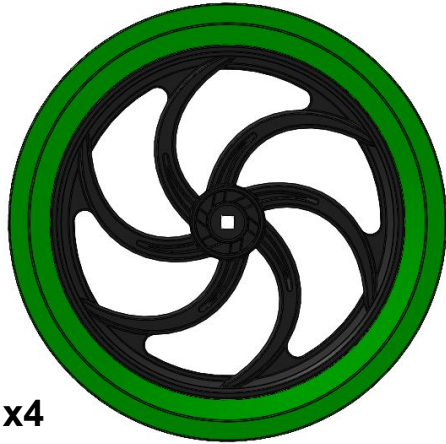
Motor

x2



Motor Mount

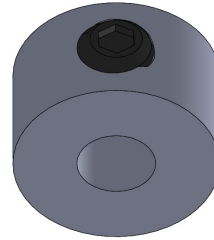
# PIONEERS IN ENGINEERING



x4

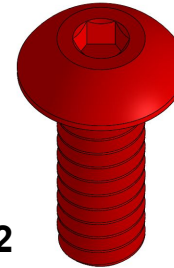
Wheel

Shaft Collar



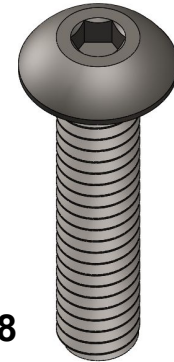
x16

M3 Screws

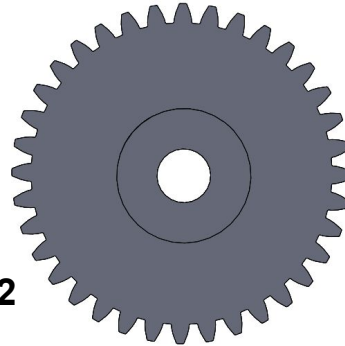


x12

8-32 Screws



x38



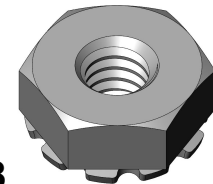
x2

Hub Gear



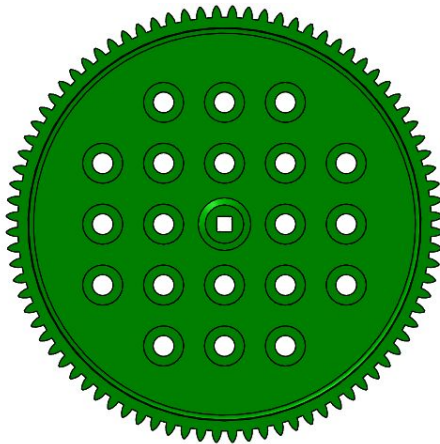
x2

Gear Set Screw



x38

Hex Nut



x2

VEX Gear



x4

Shaft

# PIONEERS IN ENGINEERING

## REFERENCE



3/32" Hex Key



11/32" Wrench



1/16" Hex Key



2-mm Hex Key

Note: parts and tools are roughly in true size

Used For

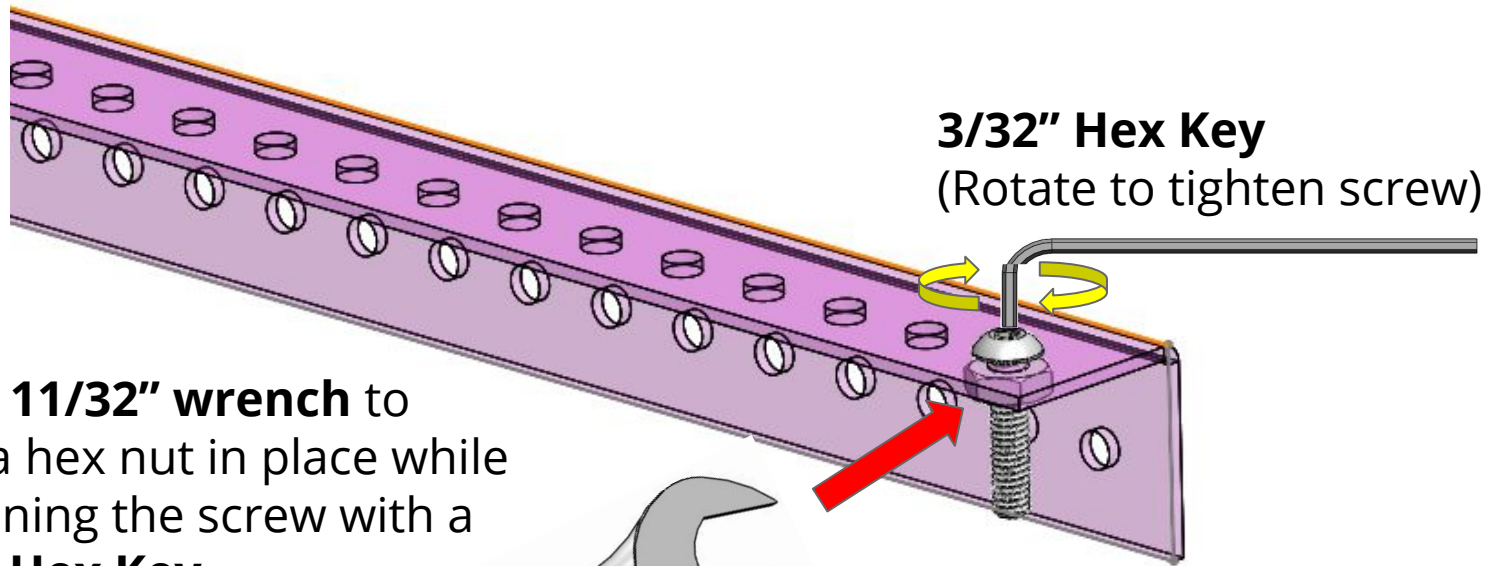




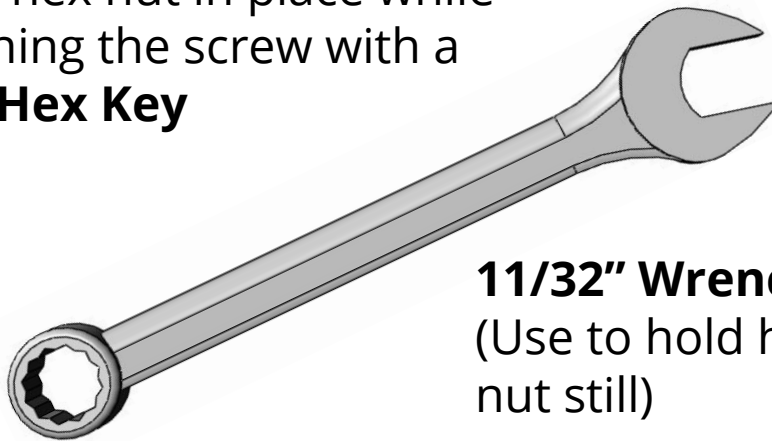
# SCREW TIGHTENING TECHNIQUE

## Applied Physics

To tighten the screw extra well, insert the shorter side of the Hex Key into the screw and rotate it by pushing on the longer side. This technique will help you maximize torque!



Use a **11/32" wrench** to hold a hex nut in place while tightening the screw with a **3/32" Hex Key**



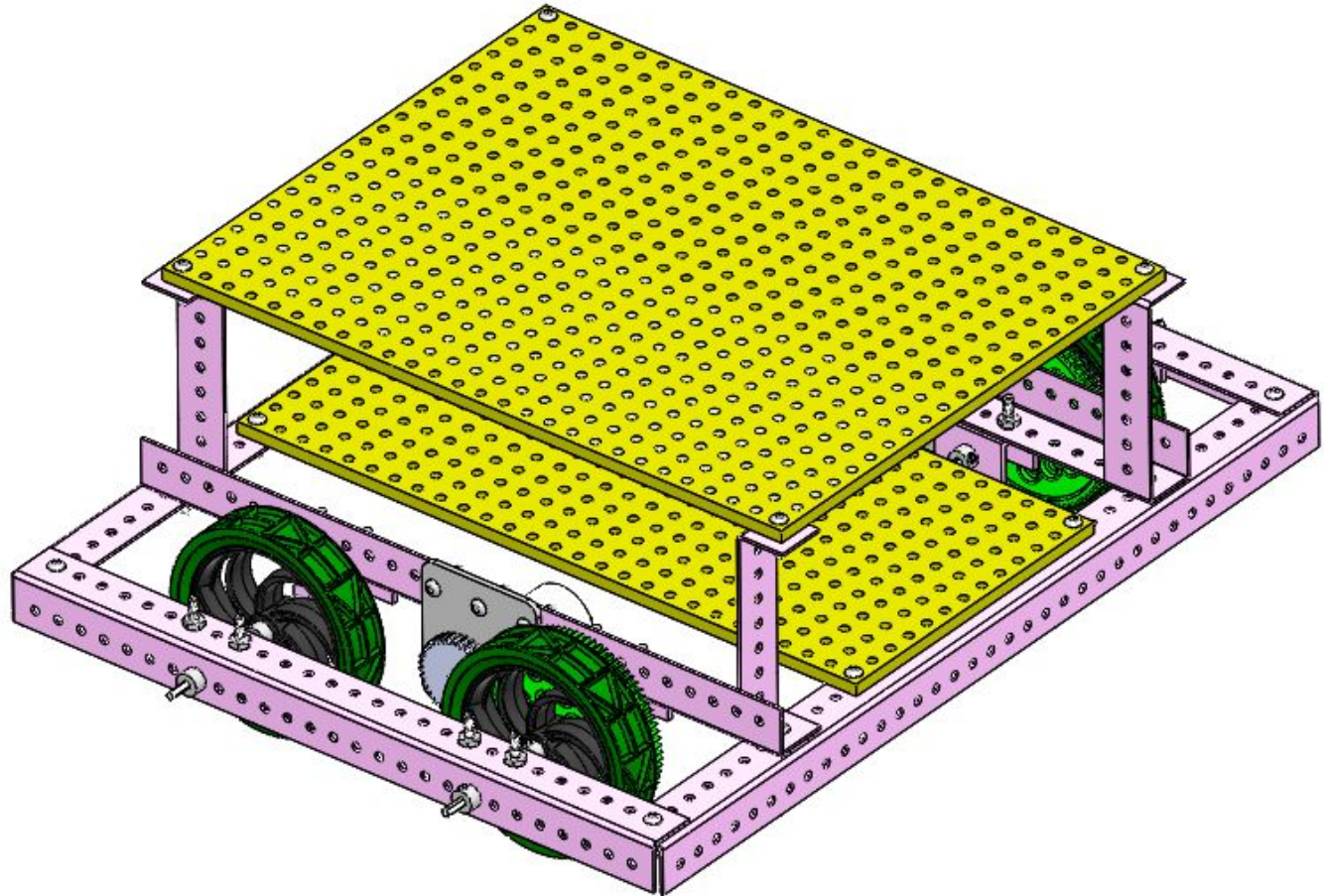
**11/32" Wrench**  
(Use to hold hex nut still)

**\*First hand-tighten the screw, and then use the Hex Key to tighten.\***

## INSTRUCTIONS

- Read all text on a page before attempting a step.
- First get the “parts” (pictures and quantities of parts on lower right of Assembly pages).
- On the Assembly pages, use the upper right “views” to find where to apply “step instructions”, which are on the left side.
- If you are confused, reference the end page (has views of a completed base kit), the next few Assembly pages, or ask a PiE mentor for help.

# PIONEERS IN ENGINEERING



## ASSEMBLY

# PIONEERS IN ENGINEERING

NOTE: Nuts are not as illustrated; IRL the nuts have a star-studded side. The star side should face the screw

- 1 Insert through hole
- 2 Place on screw

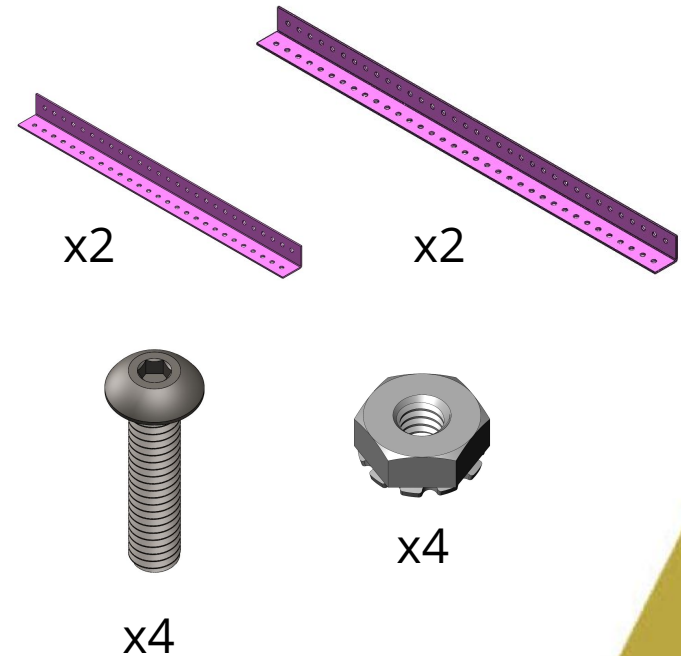
- 3 Tighten nut
- 4 Tighten screw in nut

Make sure short frames go on top!

STEP

1

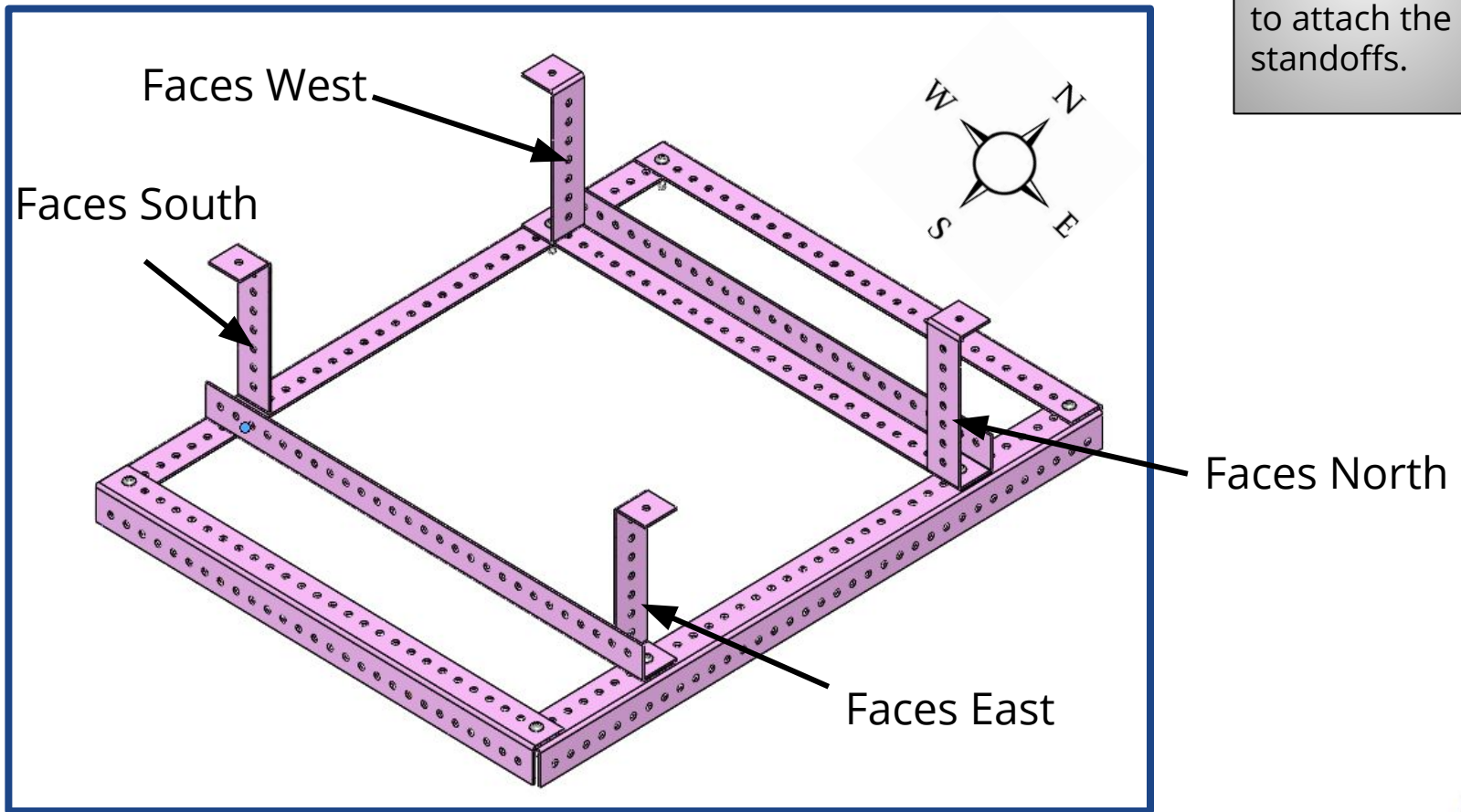
Fasten on all four corners





# How to Ideally Orient the Standoffs

Note: The next slide will go into more detail on how to attach the standoffs.



STEP

2

# PIONEERS IN ENGINEERING

**\*NOTE: If the standoffs do not fit in a certain direction, you can rotate them until they are in an orientation that fits well.\***

NOTE: All hole numbers are labeled in reference to hole 1

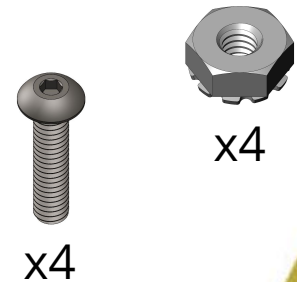
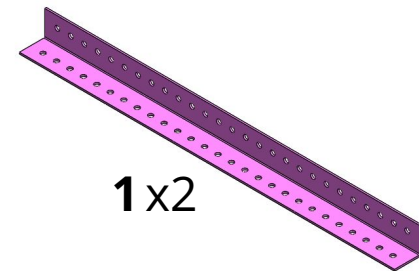
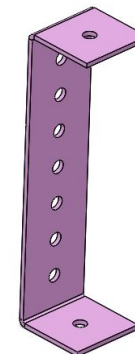
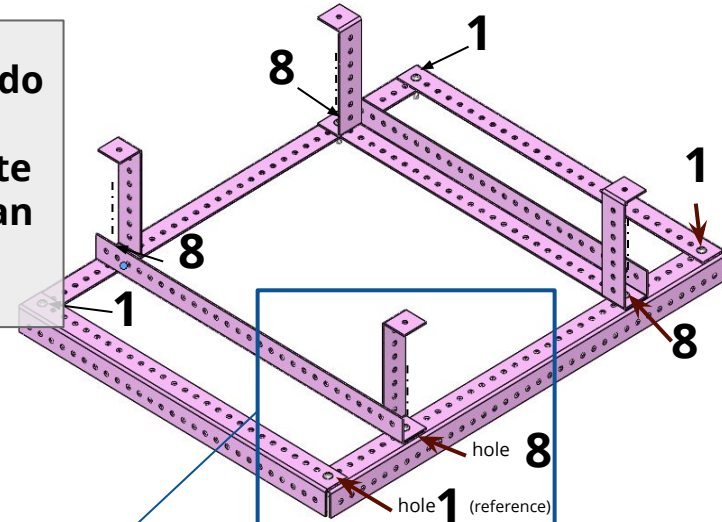
hole 1 (reference)

STEP

3

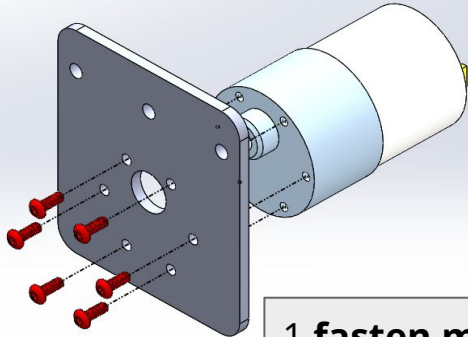
hole 8

Fasten the four "inner" corners

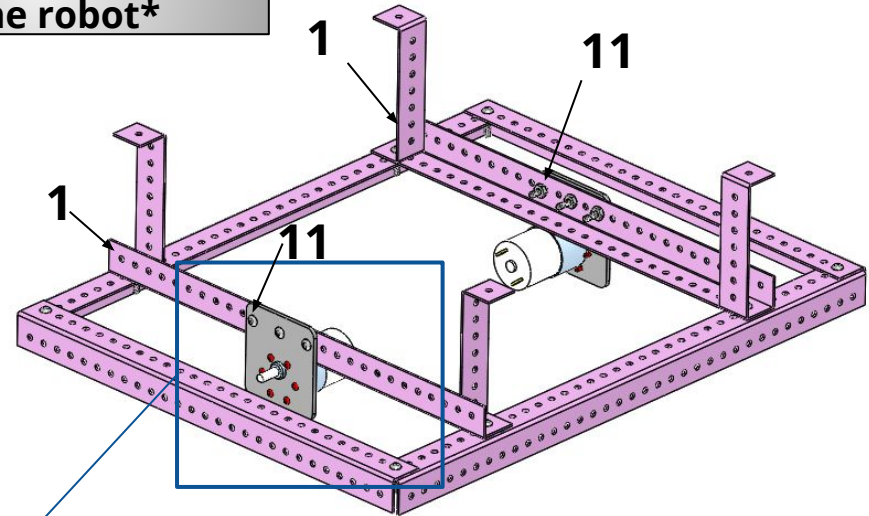


# PIONEERS IN ENGINEERING

\*Count from the same side of the robot\*



1 fasten motor to motor mount



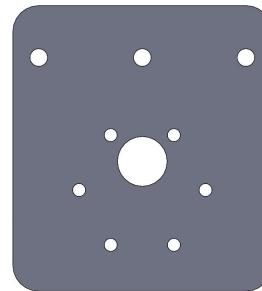
hole 11

2 fasten assembly to frame

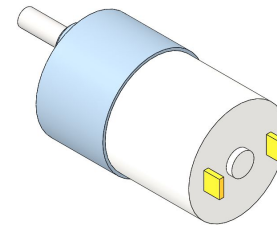
STEP

4

Do fastening for both motors



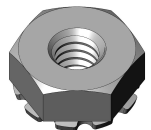
x2



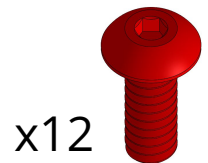
x2



x6



x6

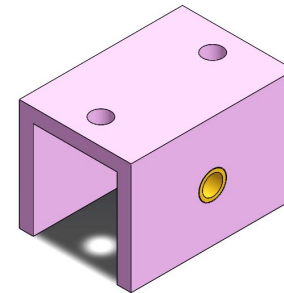
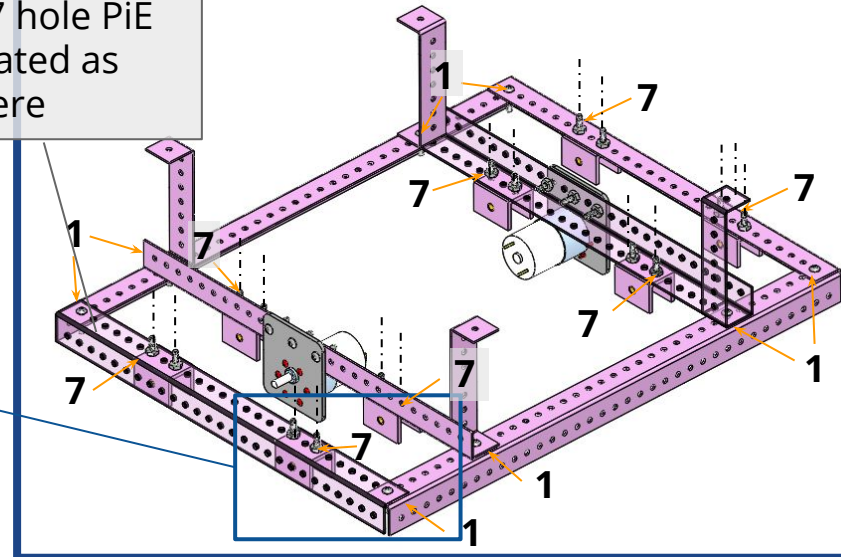
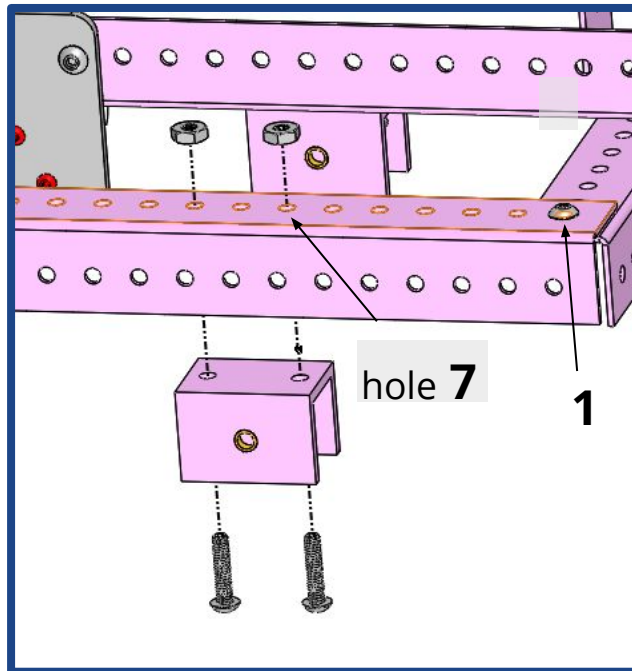
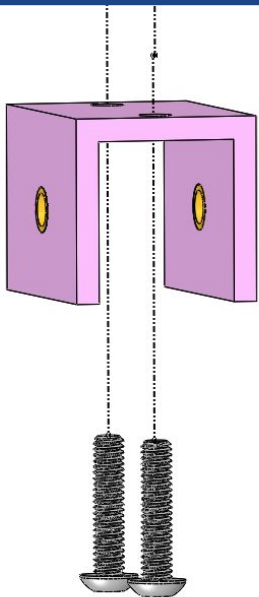


x12

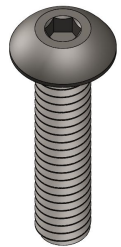


# PIONEERS IN ENGINEERING

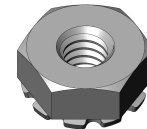
Note: Some 27 hole PiE metal is illustrated as transparent here



x8



x16



x16

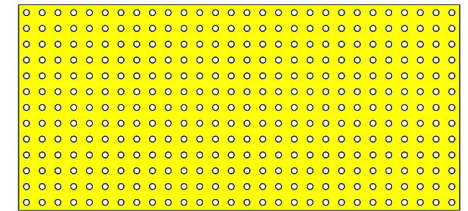
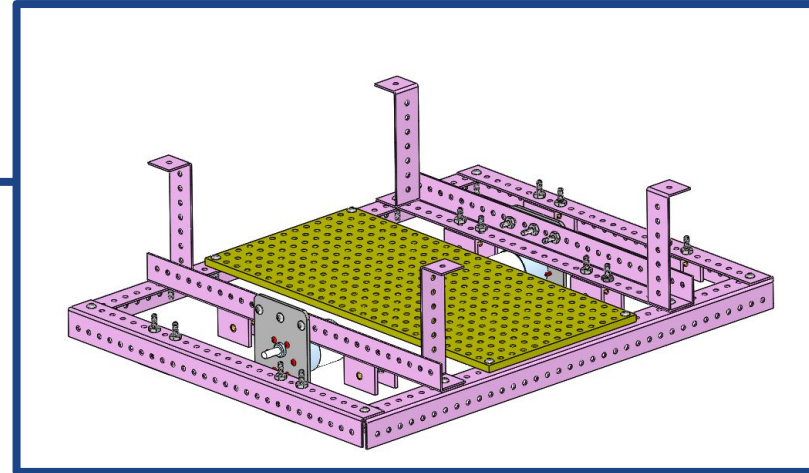
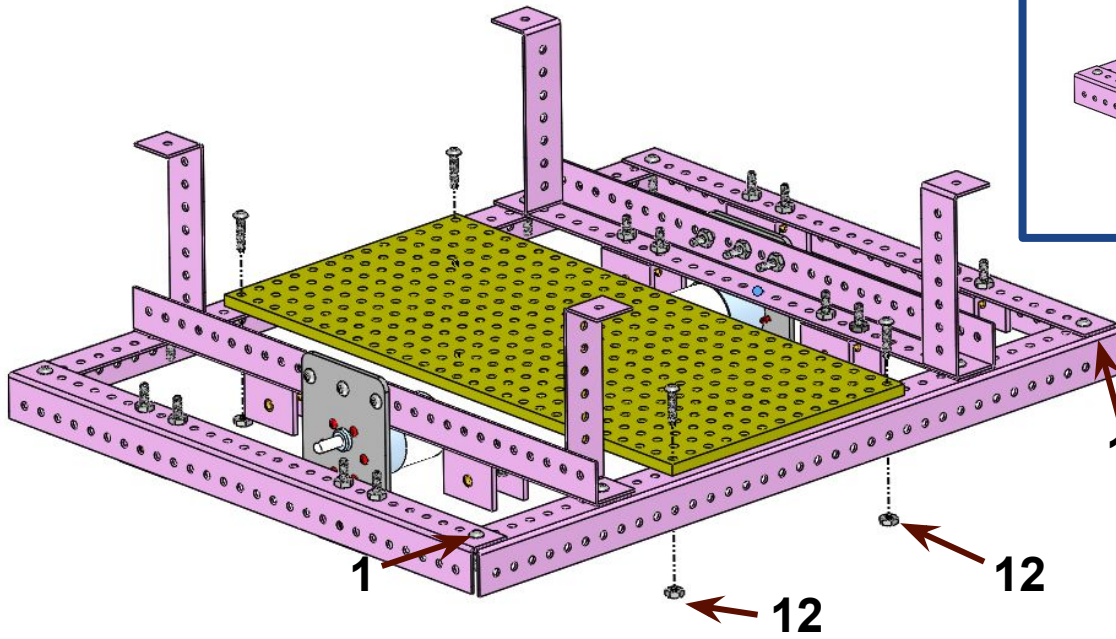
STEP

5

Fasten all eight bearing blocks.  
Note: You may have to fasten one screw at a time



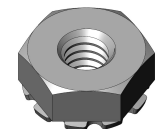
# PIONEERS IN ENGINEERING



x1



x4



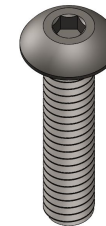
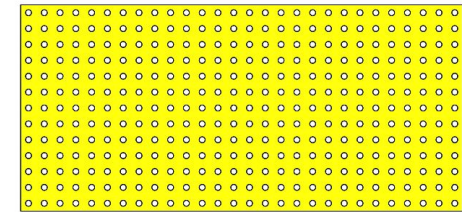
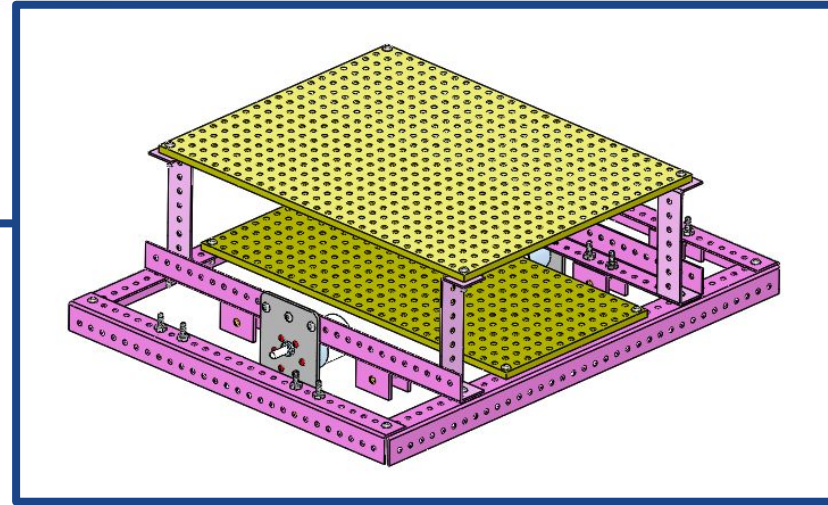
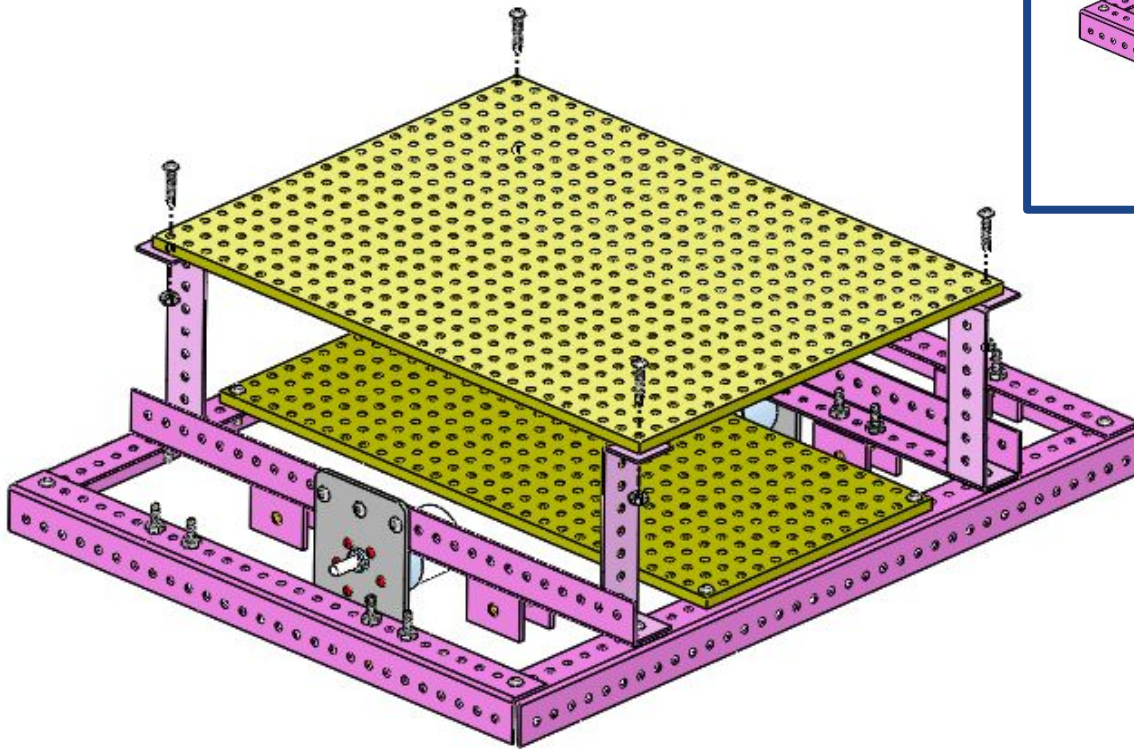
x4

STEP

6

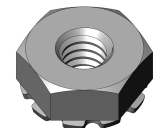
Fasten all four corners of the "bottom" plastic board

# PIONEERS IN ENGINEERING



x4

x1



x4

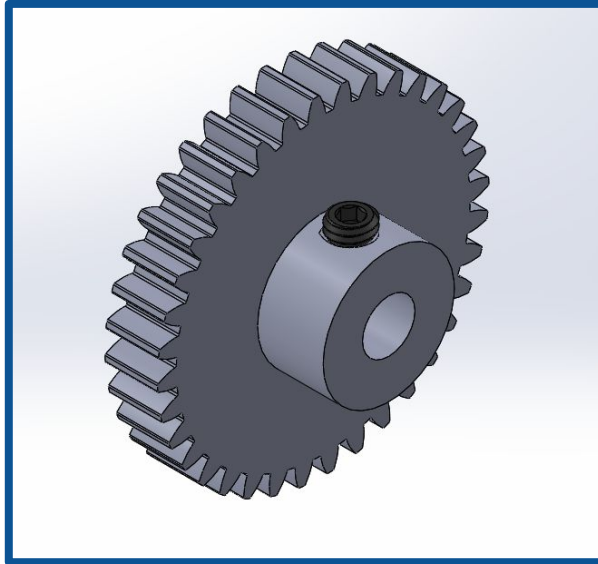
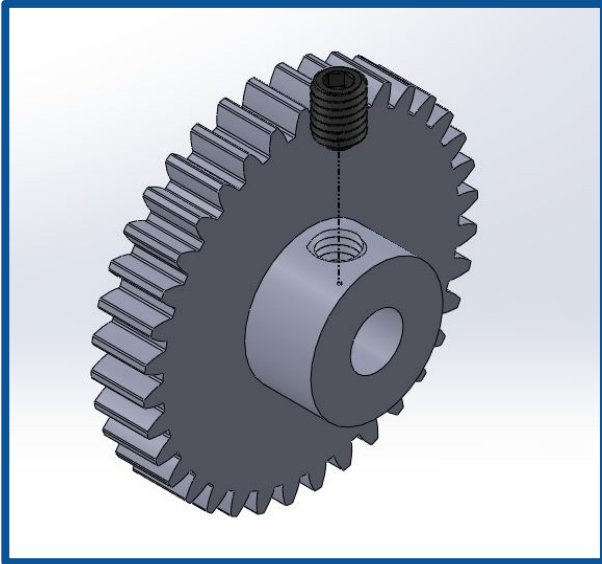
STEP

7

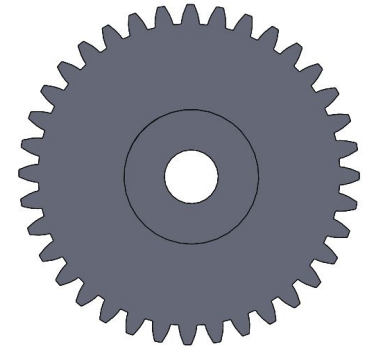
Fasten all four corners of the "top" board

# PIONEERS IN ENGINEERING

**NOTE:** Your kit should come with set screws already inserted into the hub gears, although it may have to be loosened. But in the case that the set screw comes out, please follow this step.



**TIP:** Screw can be relatively loose; do about four full turns with the hex key on the top of the “set” screw to secure it in the hub gear opening.



x2



x2

**STEP**

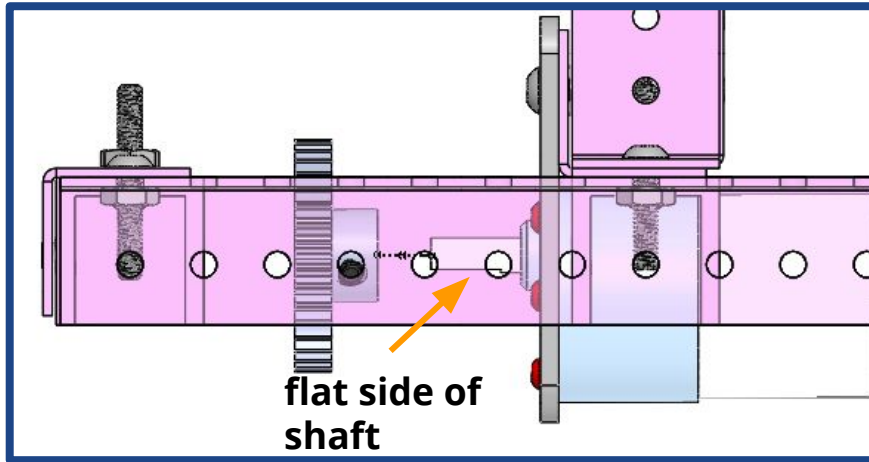
**8**

Insert set screw. Repeat for other hub gear.



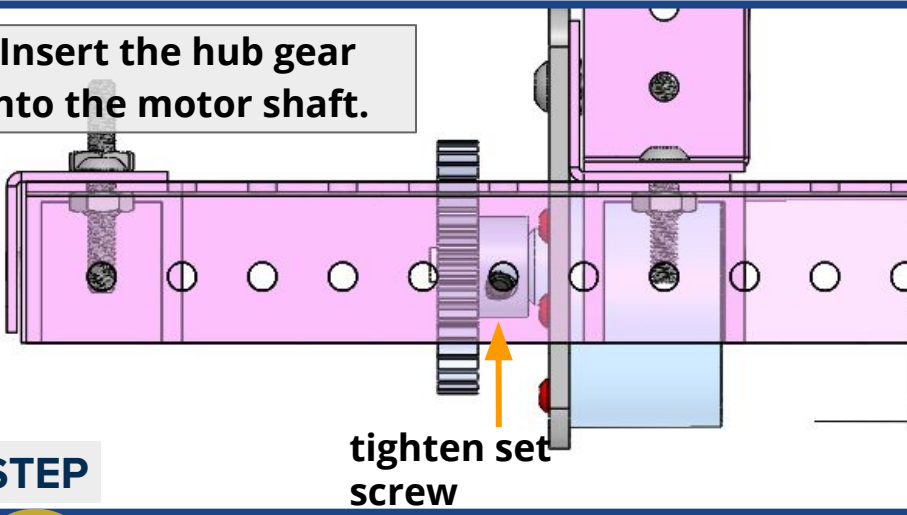
# PIONEERS IN ENGINEERING

SIDE VIEW



flat side of  
shaft

1 Insert the hub gear  
onto the motor shaft.

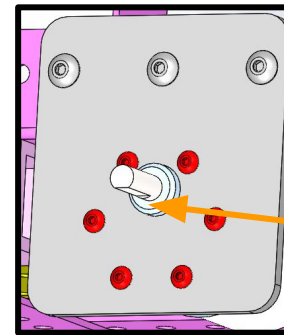
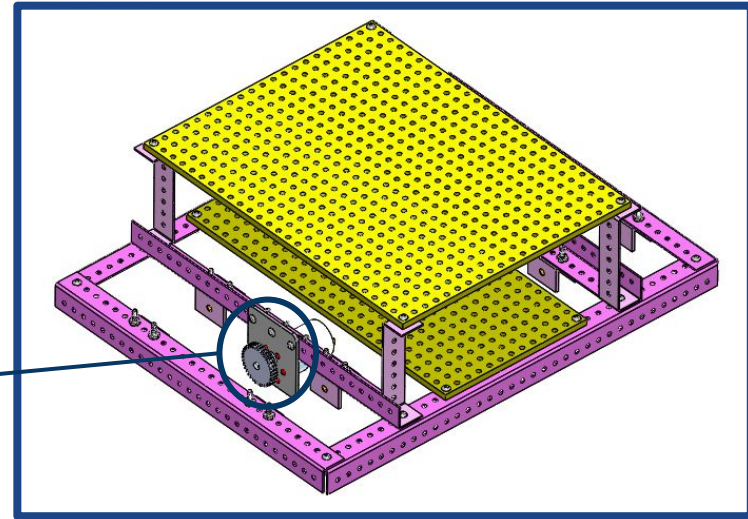


tighten set  
screw

STEP

9

Attach hub gear to motor shaft. Repeat for other side.



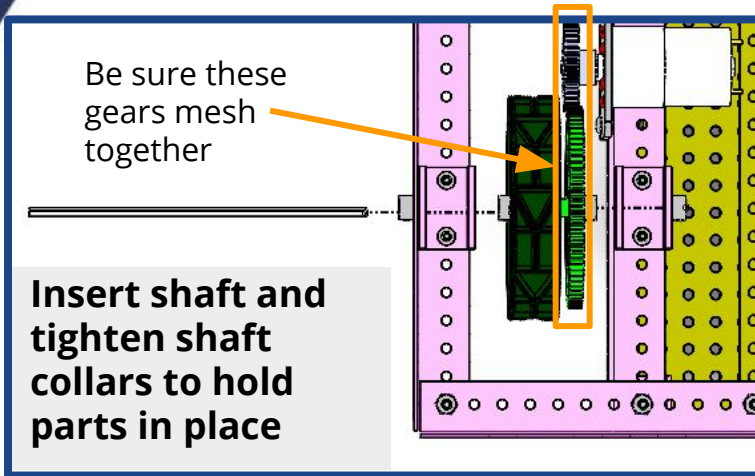
flat side of  
motor shaft

2 Rotate the gear until the set screw  
faces the flat side of the motor shaft  
and tighten the set screw so it stays in  
place

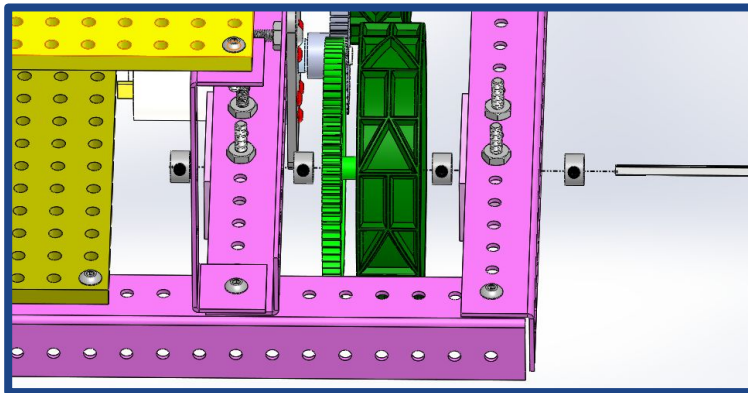


# PIONEERS IN ENGINEERING

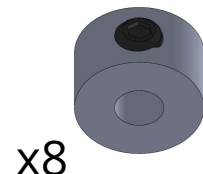
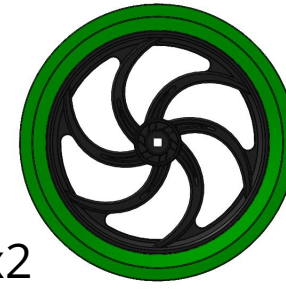
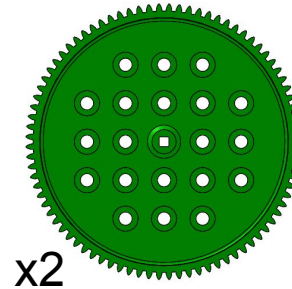
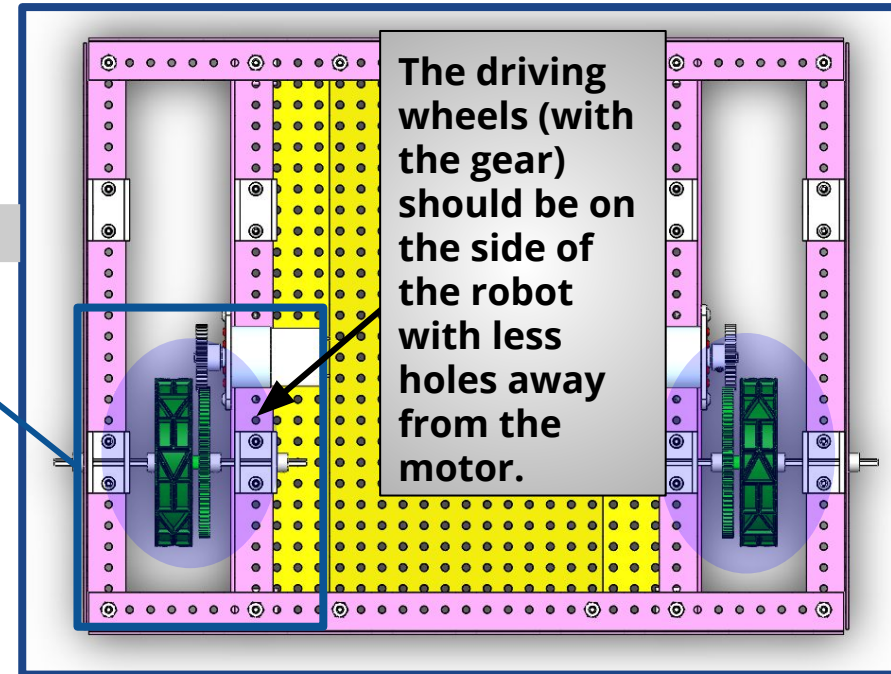
BOTTOM VIEW



FRONT VIEW



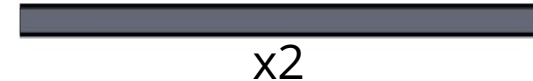
BOTTOM VIEW



STEP

10

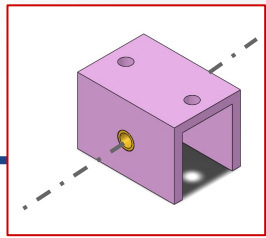
Assemble and fasten "driven" wheels



# PIONEERS IN ENGINEERING

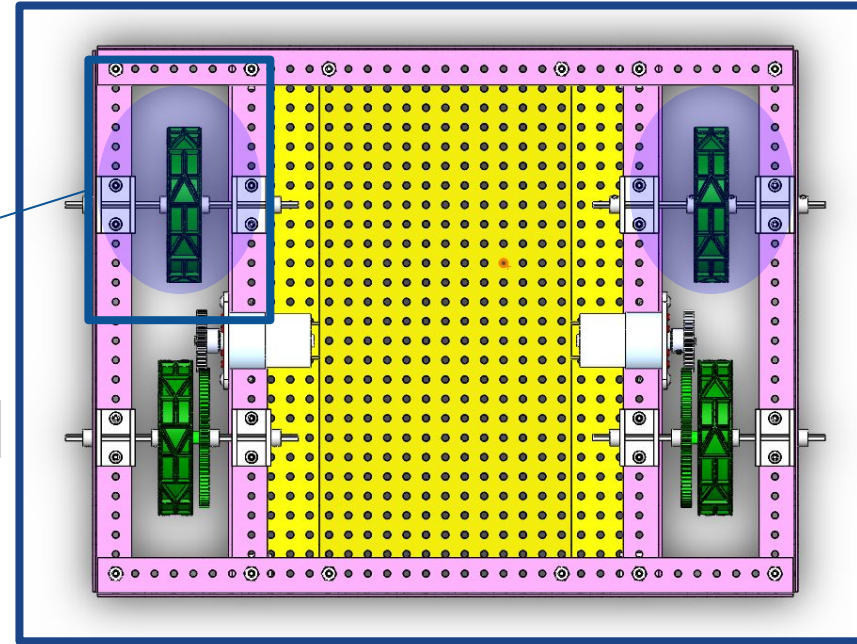
**BOTTOM VIEW**

1 insert shaft through parts and bearing blocks as shown



**FRONT VIEW**

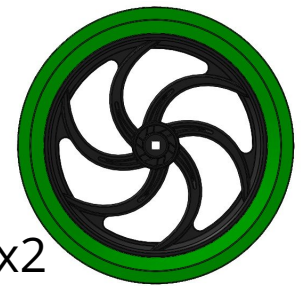
**BOTTOM VIEW**



2 tighten set screws in shaft collars to prevent parts from sliding



x8



x2



x2

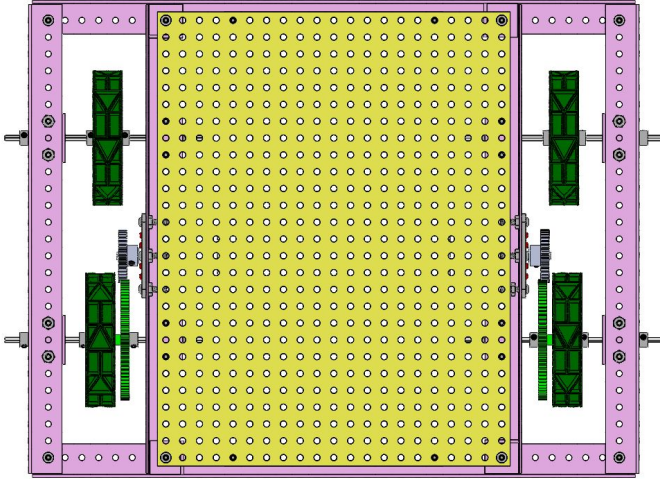
**STEP**

**11**

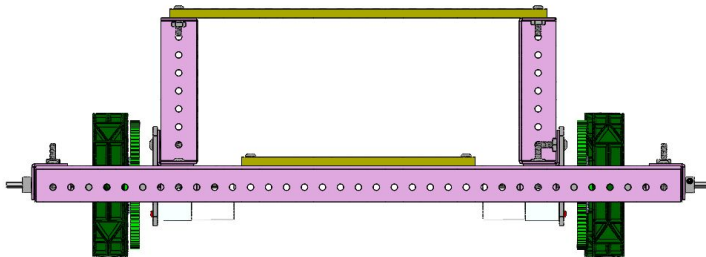
Assemble and fasten front wheels.



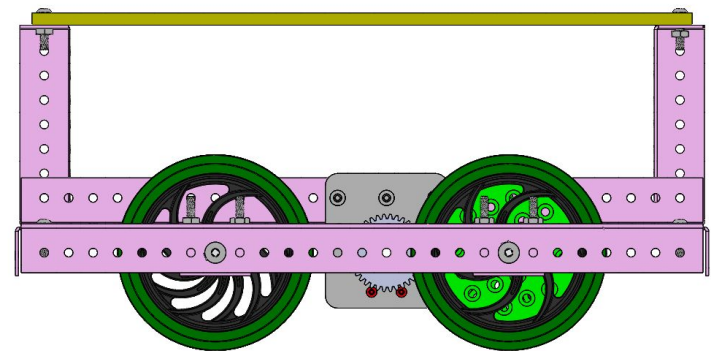
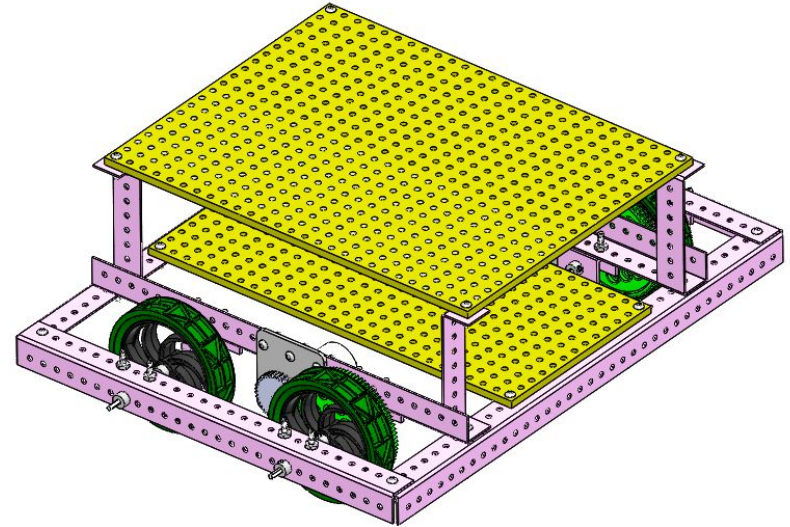
## MULTIVIEW



TOP



FRONT



RIGHT