

**Learning Objectives:**

1. Represent any linear transformation as a matrix multiplication.
2. Determine whether a given linear transformation is one-to-one and/or onto.

## 1 The matrix of a linear transformation

We previously saw that if  $A$  is a matrix then the transformation defined by  $T(\mathbf{x}) = A\mathbf{x}$  is linear. What about the other direction? If  $T$  is linear, can it always be represented by a matrix? The amazing fact is:

**Every** linear transformation  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  can be represented (uniquely) as a matrix transformation:  $T(\mathbf{x}) = A\mathbf{x}$  for some  $m \times n$  matrix  $A$ .

The trick to understand this is to use the so-called *standard basis vectors*. In  $\mathbb{R}^3$  they are

The *identity matrix* is the matrix whose columns are the standard basis vectors:  $I_n = (\mathbf{e}_1 \ \dots \ \mathbf{e}_n)$ .

**Example 1.** Suppose  $T$  is a linear transformation from  $\mathbb{R}^2$  to  $\mathbb{R}^3$  which maps

$$T(\mathbf{e}_1) = \begin{pmatrix} 5 \\ -7 \\ 2 \end{pmatrix}, \quad T(\mathbf{e}_2) = \begin{pmatrix} -3 \\ 8 \\ 0 \end{pmatrix}.$$

Determine a matrix  $A$  which represents  $T$ .

**Theorem:** Let  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear transformation. Then, there exists a unique matrix  $A$  of size  $m \times n$  such that

$$T(\mathbf{x}) = A\mathbf{x} \text{ for all } \mathbf{x} \in \mathbb{R}^n.$$

The matrix  $A$  is given by

where  $\mathbf{e}_i$  is the  $i$ th basis vector. We call  $A$  the *standard matrix of the linear transformation*  $T$ .

**Example 2.** Write down the matrix representation of the rotation transformation  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  which rotates all vectors counterclockwise by  $90^\circ$ .

## 2 Transformation properties

We have seen a common theme of linear algebra is answering the question: “is  $A\mathbf{x} = \mathbf{b}$  solvable? Are solutions unique?” We have also seen that the case  $A\mathbf{x} = \mathbf{0}$  is particularly important.

We ask the same questions of transformations:

A mapping  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  is **onto** or **surjective** if

That is,  $T$  is onto if given any  $\mathbf{b}$  there is

A mapping  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  is **into** or **one-to-one** or **injective** if

That is,  $T$  is one-to-one if whenever  $T(\mathbf{u}) = T(\mathbf{v})$  then

**Example 3.** Let  $T$  be the linear transformation whose standard matrix row reduces to

$$R = \begin{pmatrix} 1 & -4 & 8 & 1 \\ 0 & 2 & -1 & 3 \\ 0 & 0 & 0 & 5 \end{pmatrix}.$$

Is  $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$  onto? into?

**Theorem:** Let  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear transformation. Then  $T$  is one-to-one if and only if the equation  $T(\mathbf{x}) = \mathbf{0}$  has only the trivial solution  $\mathbf{x} = \mathbf{0}$ .

**Example 4.** Assume  $T$  is a linear transformation and  $A$  is its standard matrix. Fill in the following table with the following concepts:

Columns of  $A$  linearly independent, columns of  $A$  span  $\mathbb{R}^m$ , pivot in each row of  $A$ , pivot in each column of  $A$ , row reducing never results in row  $(0 \ 0 \ \dots \ 0 \ b)$ ,  $A$  has no free variables,  $A\mathbf{x} = \mathbf{0}$  has only the trivial solution

$T$ is one-to-one	$T$ is onto

**Example 5.** Let  $T(x_1, x_2) = (3x_1 + x_2, 5x_1 + 7x_2, x_1 + 3x_2)$ . Show that  $T$  is injective. Is it surjective?

**Example 6.** Suppose that  $A$  is a  $2 \times 3$  matrix. **T/F:** The transformation  $T(\mathbf{x}) = A\mathbf{x}$  can be one-to-one.