

Minjune Hwang

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EDUCATION

University of Southern California <i>Ph.D. in Computer Science; GPA: 4.0/4.0</i>	Los Angeles, CA Aug. 2024 – Present
Stanford University <i>M.S. in Computer Science; GPA: 3.95/4.3</i>	Stanford, CA Sep. 2021 – Dec. 2023
University of California, Berkeley <i>B.A. in Computer Science & B.A. in Statistics; GPA: 3.90/4.0</i>	Berkeley, CA Aug. 2017 – May. 2021

RESEARCH INTEREST

My research empowers robots to learn from humans for daily tasks by: (1) finetuning **robotic foundation policies** with diverse feedback (e.g., demonstrations, preferences, explicit reasoning) **to align with true user intent** and (2) training robust policies with **data curation/augmentation to overcome limited and noisy data** in robotics. In doing so, I use language as a medium for human-robot interaction, developing **communicative agents** that can proactively ask and answer questions while physically interacting in environments.

RESEARCH EXPERIENCE

Sensing, Learning & Understanding for Robotic Manipulation (SLURM) Lab <i>Ph.D. Researcher, advised by Prof. Daniel Seita</i>	Los Angeles, CA Aug. 2024 – Present
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- Developing a structured data augmentation and curation method to achieve zero-shot compositional & hierarchical generalization in end-to-end VLA policies.
- Designed a preference-based reward learning method that uses natural language reasons to overcome causal confusion and improve policy generalization.

Stanford Vision & Learning (SVL) Lab <i>Graduate Research Assistant, advised by Prof. Fei-Fei Li & Prof. Jiajun Wu</i>	Stanford, CA Mar. 2022 – Dec. 2023
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- Proposed hierarchical human-in-the-loop learning algorithms for efficient human-robot collaboration in complex manipulation tasks, leading into multiple paper acceptances in top conferences as a first author (Corl, IROS).
- Designed controllers and skills for robot learning in large-scale embodied-AI simulation, BEHAVIOR-1K.
- Researched scene-graph-based RL algorithms for navigation and mobile manipulation.

Berkeley AI Research <i>Research Assistant, advised by Prof. Alexandre Bayen & Prof. Laurent El Ghaoui</i>	Berkeley, CA Feb. 2019 – May. 2021
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- Led the development of object detection & tracking model for a large-scale trajectory dataset for vehicle behavior learning and researched on safe motion planning with the dataset, under Prof. Alexandre Bayen.
- Researched extractive text summarization with sparse convex optimization, topic modeling, and RNNs.
- Developed a sparsity-invariant CNNs for adversarial attack detection via partial occlusion of images.

INDUSTRY EXPERIENCE

Amazon Robotics <i>Applied Scientist Intern</i>	Westborough, MA Sep. 2022 – Dec. 2022
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- Developed ML algorithms and pipelines for object detection & tracking in warehouse human-robot collaboration.

Microsoft <i>Research Intern</i>	Berkeley, CA Jun. 2022 – Sep. 2022
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- Designed an RL algorithm for offline sim-to-real transfer via reward augmentation and residual policy learning.

Apple, Special Project Group <i>Software Engineering Intern, Motion & Trajectory Planning</i>	Cupertino, CA May. 2021 – Aug. 2021
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- Researched imitation learning for the warm-start of trajectory optimization of autonomous robots.
- Developed motion sampling & planning algorithms for generating safe and kinematically feasible trajectories.

SELECTED PUBLICATIONS

*: denotes equal contribution, †: equal advising

1. **Minjune Hwang**, Yigit Korkmaz, Daniel Seita[†], Erdem Bıyük[†]. Causally Robust Reward Learning from Reason-Augmented Preference Feedback. *HiTL Workshop at RSS 2025 (Oral)*, In submission to *ICLR 2026*. [\[poster\]](#).
2. Fangyu Wu, Dequan Wang, **Minjune Hwang**, Chenhui Hao, Jiawei Lu, Trevor Darrell, Alexandre Bayen. Decentralized Vehicle Coordination: The Berkeley DeepDrive Drone Dataset. *ICRA 2025*. [\[pdf\]](#).
3. Ruohan Zhang*, Sharon Lee*, **Minjune Hwang***, Ayano Hiranaka*, Chen Wang, Wensi Ai, Jin Jie Ryan Tan, ..., Anthony Norcia, Li Fei-Fei, Jiajun Wu. NOIR: Neural Signal Operated Intelligent Robots for Everyday Activities. *CoRL 2023*. [\[pdf\]](#), [\[project page\]](#).
4. **Minjune Hwang***, Ayano Hiranaka*, Sharon Lee, Chen Wang, Li Fei-Fei, Jiajun Wu, Ruohan Zhang. Primitive Skill-Based Robot Learning from Human Evaluative Feedback. *IROS 2023*. [\[pdf\]](#), [\[project\]](#).
5. Michael Lingelbach, Chengshu Li, **Minjune Hwang**, Andrey Kurenkov, Alan Lou, Roberto Martín-Martín, Ruohan Zhang, Li Fei-Fei, Jiajun Wu. Task-Driven Graph Attention for Hierarchical Relational Object Navigation. *ICRA 2023*. .
6. Chengshu Li*, ..., **Minjune Hwang**, ..., Silvio Savarese, Hyowon Gweon, Karen Liu, Jiajun Wu, Li Fei-Fei. BEHAVIOR-1K: A Benchmark for Embodied AI with 1,000 Everyday Activities and Realistic Simulation. *CoRL 2022*. **Best Paper Nominee** [\[pdf\]](#), [\[project page\]](#).
7. Michael McCoyd, Won Park, Steven Chen, Neil Shah, Ryan Roggenkemper, **Minjune Hwang**, Jason Xinyu Liu, David Wagner. Minority Reports Defense: Defending Against Adversarial Patches. *Security in Machine Learning and its Applications (SiMLA), 2020*. **Best Paper Award** [\[pdf\]](#).

TEACHING EXPERIENCE

CS 231N: Deep Learning for Computer Vision <i>Graduate Teaching Assistant</i>	Stanford, CA <i>Mar. 2023 – Jun. 2023</i>
EE 227BT: Convex Optimization <i>Undergraduate Teaching Assistant</i>	Berkeley, CA <i>Aug. 2019 – Dec. 2019</i>
CS 61A: Structure and Interpretation of Computer Programs <i>Lab Assistant</i>	Berkeley, CA <i>Jan. 2018 – May. 2018</i>

HONORS & FELLOWSHIPS

Viterbi School of Engineering Fellowship	<i>Aug. 2024 – Jul. 2026</i>
High Distinction in General Scholarship (Magna Cum Laude)	<i>May. 2021</i>
Summer Undergraduate Research Fellowship (SURF), UC Berkeley	<i>May. 2020</i>
Berkeley Undergraduate Scholarship	<i>Aug. 2017 – May. 2021</i>

SERVICES

Serving/Served as a reviewer for CoRL, ICLR, ICRA, IROS, THRI, and workshops in RSS.

Mentoring a number of undergraduate students and summer interns at USC.

Organizing UROS, a student-run, cross-department robotics reading group and seminar series at USC.

Serving as a PhD mentor for USC CS Undergraduate Mentoring Program.

EXPERTISES

Robotics: ROS, TAMP, Optimal Control (LQR/LQG, MPC, MPPI, etc), Motion Planning, VLA Models

Robot Policy Learning: RL (DDPG, SAC, CQL, IQL), IL (BC, GAIL, ACT, Diffusion Policy), Inverse RL, PbRL

Computer Vision: Object Segmentation & Tracking, Diffusion Models, Vision Transformer, Sensor Calibration, SLAM

Libraries: PyTorch, Tensorflow, IsaacLab, ManiSkill, Robosuite, OMPL, OpenCV, Ray, cvxopt, SageMaker, Mujoco