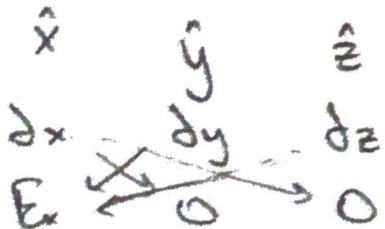


6.1.1) Find the magnetic field \mathbf{B}
 that must exist using $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$

$$\nabla \times \mathbf{E} = \nabla \times (\mathbf{E}_{ox} \cos(k_z z - \omega t) \hat{x})$$



$$\langle 0, \frac{\partial z}{\partial z} E_x - 0, 0 - \cancel{\frac{\partial y}{\partial z} E_x} \rangle$$

$$\nabla \times \mathbf{E} = -k_z \mathbf{E}_{ox} \sin(k_z z - \omega t) \hat{y} \leftarrow \text{plug in}$$

$$-\frac{\partial \mathbf{B}}{\partial t} = -k_z \mathbf{E}_{ox} \sin(k_z z - \omega t) \hat{y}$$

$$\oint + d\mathbf{B} = \int + k_z \mathbf{E}_{ox} \sin(k_z z - \omega t) \hat{y} dt$$

$$\mathbf{B} = k_z \mathbf{E}_{ox} \int \sin(k_z z - \omega t) \hat{y} dt$$

$$\phi = k_z z - \omega t$$

$$d\phi = -\omega dt \rightarrow dt = \frac{d\phi}{\omega}$$

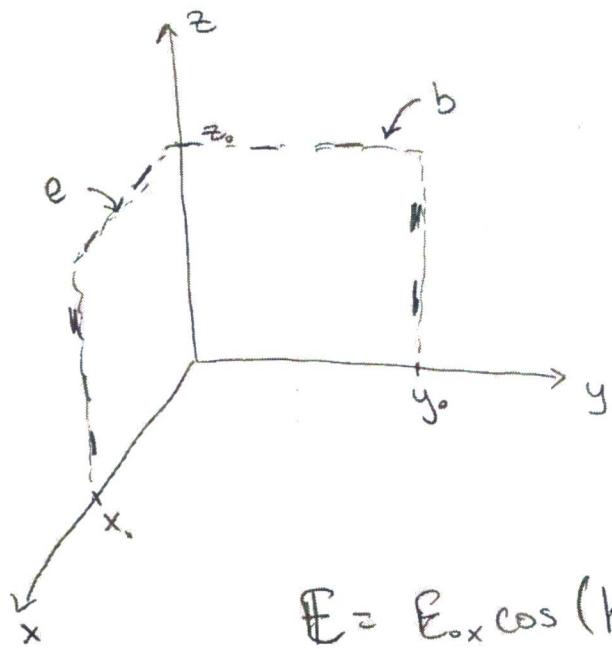
6.1) Faraday's law

$$\oint \vec{E} \cdot d\vec{l} = -\frac{\partial \Phi_B}{\partial t}$$

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Generalized Ampere's law ($J=0$)

$$\oint \vec{B} \cdot d\vec{l} = \frac{1}{c^2} \frac{\partial \Phi_E}{\partial t}$$



$$\vec{E} = E_{ox} \cos(k_z z - \omega t) \hat{x}$$

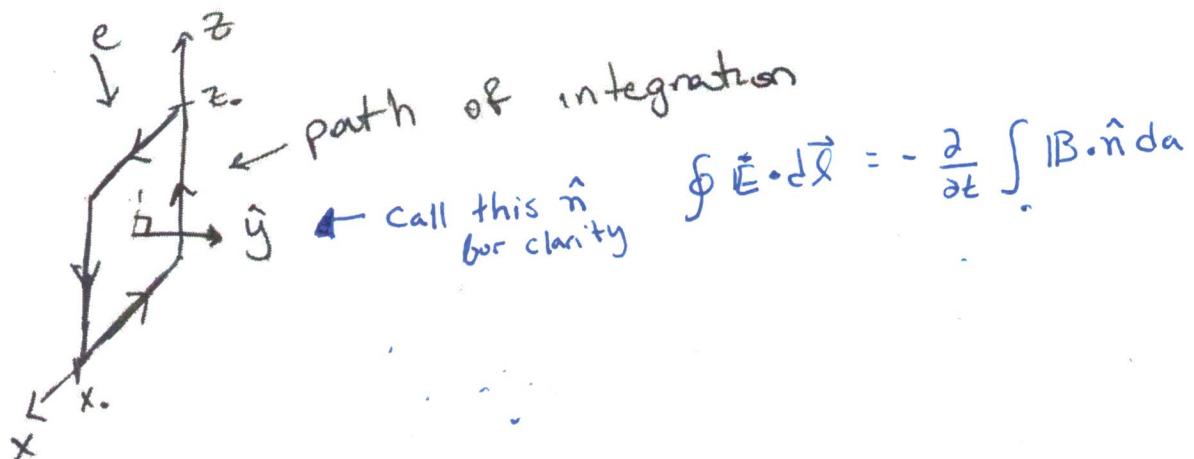
$$\mathbf{B} = \frac{k_z E_{ox}}{\omega} \int -\sin \phi \, d\phi \hat{y}$$

$$\mathbf{B} = \frac{k_z E_{ox}}{\omega} \cos \phi \hat{y}$$

$$\boxed{\mathbf{B} = \frac{k_z E_{ox}}{\omega} \cos(k_z z - \omega t) \hat{y}}$$



6.1.2) Show that \vec{E} satisfies Faraday's Law in the form of $\oint \vec{E} \cdot d\vec{l} = -\frac{\partial \Phi_B}{\partial t}$ along the rectangle e



$$\oint \vec{E} \cdot d\vec{l} = - \frac{d\Phi_B}{dt} = - \int \frac{d\Phi}{dt} d\vec{a} \quad \leftarrow \begin{matrix} \text{area} \\ \text{Static} \end{matrix} \quad \text{Sect} \rightarrow S \rightarrow \vec{z}$$

$$-\int \frac{d\Phi}{dt} \cdot d\vec{a} = - \int \frac{\partial}{\partial t} \left(E_{ox} \frac{k_z}{\omega} \cos(k_z z - \omega t) \right) dx dz \hat{j} \hat{j}$$

$$= - E_{ox} \frac{k_z}{\omega} \int \frac{\partial}{\partial t} \cos(k_z z - \omega t) dz \times \Big|_0^{x_0}$$

$$= \left(- E_{ox} \frac{k_z}{\omega} \int_0^{x_0} + \omega (+ \sin(k_z z - \omega t) dz) \Big|_0^{x_0} \right)$$

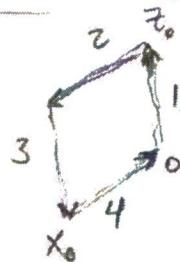
$$\phi = k_z z - \omega t$$

$$d\phi = dz \quad k_z \Rightarrow dz = \frac{d\phi}{k_z}$$

$$= - E_{ox} \frac{k_z}{\omega} \int_{-\omega t}^{k_z x_0 - \omega t} \sin(\phi) d\phi$$

$$= - E_{ox} x_0 - \cos \phi \Big|_{-\omega t}^{k_z x_0 - \omega t}$$

$$= \frac{d\Phi_B}{dt} = E_{ox} x_0 (\cos(k_z x_0 - \omega t) - \cos(-\omega t))$$



$$\textcircled{1} \rightarrow \int_0^{z_0} \vec{E} \cdot d\vec{z} \Big|_{x=0}$$

$$\textcircled{2} \rightarrow \int_0^{x_0} \vec{E} \cdot d\vec{x} \Big|_{z=z_0}$$

$$\textcircled{3} \rightarrow \int_{-z_0}^0 \vec{E} \cdot d\vec{z} \Big|_{x=x_0}$$

$$\textcircled{4} \rightarrow \int_{x_0}^0 \vec{E} \cdot d\vec{x} \Big|_{z=0}$$

$$\textcircled{1} \int_{z_0}^{z_0} E_{ox} \cos(k_z z - \omega t) \hat{x} \cdot \hat{z} dz = 0$$

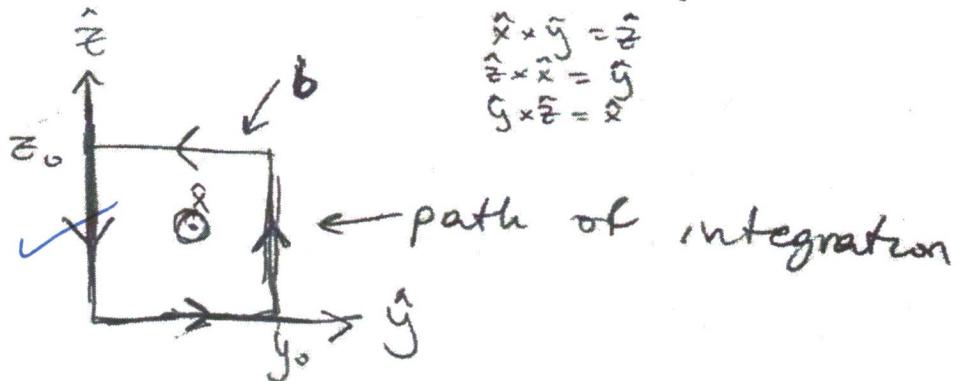
$$\textcircled{2} \int_0^{k_x} E_{ox} \cos(k_z z_0 - \omega t) (\hat{x} \cdot \hat{x}) dx = E_{ox} \cos(k_z z_0 - \omega t) x_0$$

$$\textcircled{3} \int_{z_0}^0 E_{ox} \cos(k_z z - \omega t) \hat{x} \cdot \hat{z} dz = 0$$

$$\textcircled{4} \int_{x_0}^0 E_{ox} \cos(10 - \omega t) \hat{x} \cdot \hat{x} dx = -E_{ox} \cos(-\omega t) x_0$$

$$E_{ox} x_0 (\cos(k_z z_0 - \omega t) - \cos(-\omega t)) = \\ E_{ox} x_0 (\cos(k_z z_0 - \omega t) - \cos(-\omega t)) \quad \checkmark$$

6.1.3) Show that this \mathbf{B} satisfies Ampere's Law along rectangle b. Draw the integral path.



$$\oint \mathbf{B} \cdot d\vec{l} = \frac{1}{c^2} \frac{\partial \Phi_E}{\partial t} \quad \text{S} \rightarrow C \rightarrow -S \rightarrow -C$$

$$\begin{aligned} \frac{1}{c^2} \frac{\partial \Phi_E}{\partial t} &= \int \frac{1}{c^2} \frac{\partial}{\partial t} (\mathbf{E}) d\vec{a} \\ &= \int \frac{1}{c^2} \frac{\partial}{\partial t} (E_{ox} \cos(k_z z - \omega t)) \hat{x} \cdot \hat{x} dy dz \end{aligned}$$

$$= \frac{E_{ox}}{c^2} \int_0^{y_0} dy \int_0^{z_0} \frac{\partial}{\partial t} (\cos(k_z z - \omega t)) dz$$

$$= \frac{E_{ox} y_0}{c^2} \int_0^{z_0} +w_0 + \sin(k_z z - \omega t) dz$$

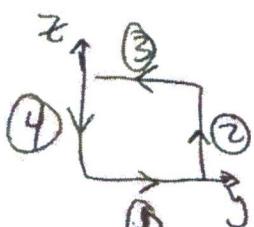
$$\phi = k_z z - \omega t \quad d\phi = k_z dz$$

$$dz = d\phi / k_z$$

$$= \frac{E_{ox} y_0}{c^2} \frac{\omega}{k_z} \int_{-wt}^{k_z z_0 - \omega t} \sin \phi d\phi$$

$$\frac{1}{c^2} \frac{\partial \Phi_E}{\partial t} = \frac{E_{ox} y_0}{c^2} \frac{\omega}{k_z} (-\cos(k_z z_0 - \omega t) + \cos(-\omega t))$$

$$\oint \mathbf{B} \cdot d\vec{l} = \begin{aligned} &\textcircled{1} \rightarrow \int_0^{y_0} \mathbf{B} \cdot d\vec{y} \Big|_{z=0} \\ &\textcircled{2} \rightarrow \int_0^{z_0} \mathbf{B} \cdot d\vec{z} \Big|_{y=y_0} \checkmark \\ &\textcircled{3} \quad \int_{y_0}^0 \mathbf{B} \cdot d\vec{y} \Big|_{z=z_0} \checkmark \\ &\textcircled{4} \quad \int_{z_0}^0 \mathbf{B} \cdot d\vec{z} \Big|_{y=0} \end{aligned}$$



$$\textcircled{1} \int_0^{y_0} \frac{k_z E_{ox}}{\omega} \cos(-\omega t) \hat{g} \cdot \hat{g} dy = \frac{k_z E_{ox} y_0}{\omega} \cos(-\omega t)$$

$$\textcircled{2} \int_0^{z_0} \frac{k_z E_{ox}}{\omega} \cos(k_z z - \omega t) \hat{g} \cdot \hat{z} dz = 0$$

$$\textcircled{3} \int_{y_0}^0 \frac{k_z E_{ox}}{\omega} \cos(k_z z - \omega t) \hat{g} \cdot \hat{y} dy = -\frac{k_z E_{ox} y_0}{\omega} \cos(k_z z_0 - \omega t)$$

$$\textcircled{4} \int_{z_0}^0 \frac{k_z E_{ox}}{\omega} \cos(k_z z - \omega t) \hat{z} \cdot \hat{y} dz = 0$$

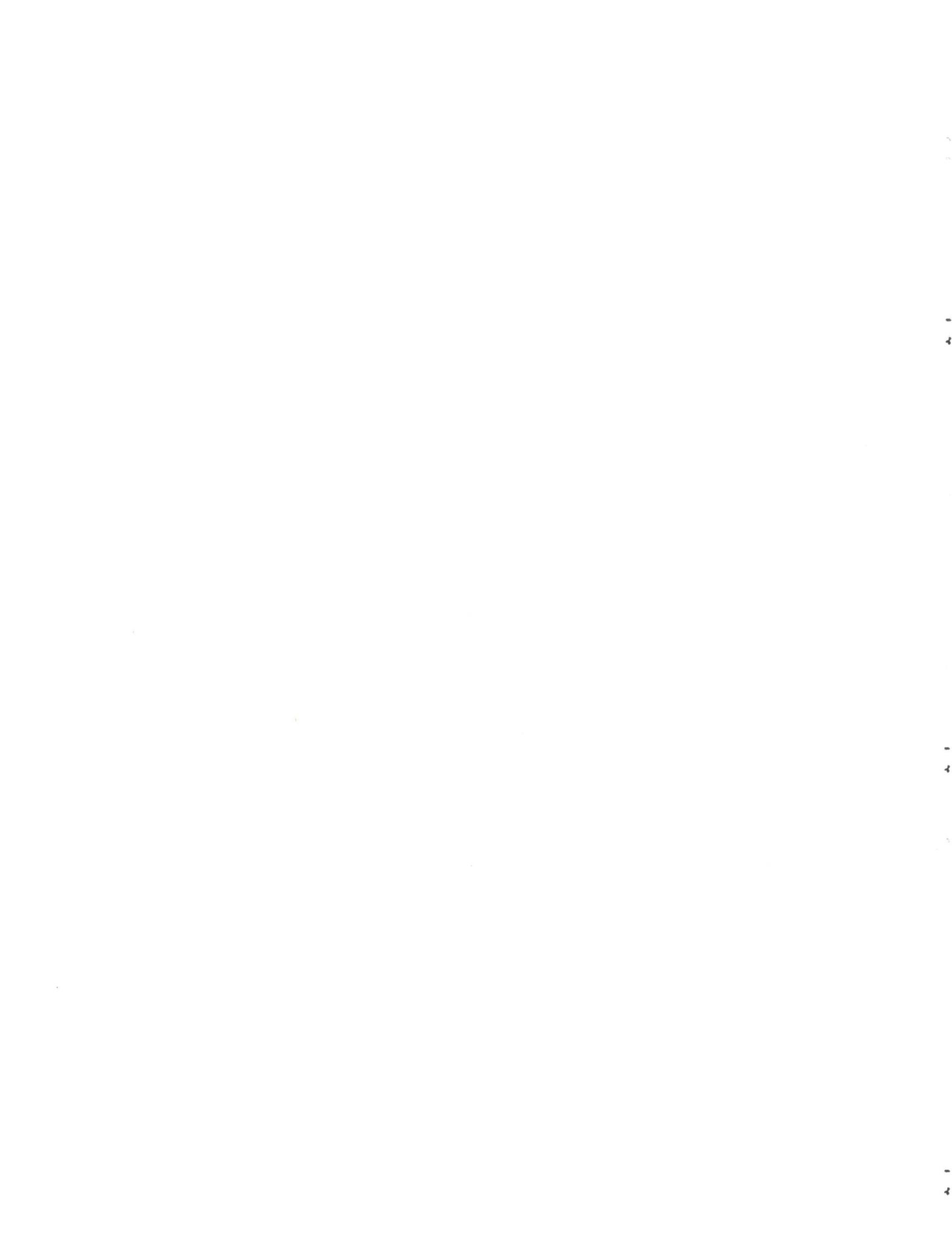
$$\frac{k_z E_{ox} y_0}{\omega} (\cos(\omega t) - \cos(k_z z_0 - \omega t)) = \oint \mathbf{B} \cdot d\mathbf{l}$$

$$\frac{k_z E_{ox} y_0}{\omega} (\cos(\omega t) - \cos(k_z z_0 - \omega t)) =$$

$$= \frac{E_{ox} y_0}{C^2} \frac{\omega}{k_z} (\cos(-\omega t) - \cos(k_z z_0 - \omega t)) \quad \checkmark$$

$$\frac{k_z E_{ox} y_0}{\omega} = \frac{E_{ox} y_0}{C^2} \frac{\omega}{k_z}$$

$$C^2 = \left(\frac{\omega}{k_z}\right)^2 \quad \checkmark$$



$$6.2) \quad \mathbf{E} = E_{ox}(x,t)\hat{x} + E_{oy}(x,t)\hat{y} + E_{oz}(x,t)\hat{z}$$

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and $\mathbf{B} = B_{ox}(x,t)\hat{x} + B_{oy}(x,t)\hat{y} + B_{oz}(x,t)\hat{z}$

6.2.1) Show $E_y(x,t)$, $E_z(x,t)$, $B_y(x,t)$ and $B_z(x,t)$ each individually obey a wave equation of the form

$$\frac{\partial^2 F}{\partial u^2} = \frac{1}{c^2} \frac{\partial^2 f}{\partial t^2}$$

Where u is a place holder for one of the cartesian variables and F is one of the components stated above

Start with Faraday's law for E_y

$$\nabla \times \mathbf{E}_y = \begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{matrix} = \begin{matrix} (0 - \partial_z E_y) \hat{x} \\ 0 \\ \partial_x E_y - 0 \end{matrix}$$

$$\nabla \times \mathbf{E}_y = \frac{\partial E_y}{\partial x} \hat{z} = - \frac{\partial B}{\partial t} \quad \checkmark$$

$$\frac{\partial B}{\partial t} = - \frac{\partial E_y}{\partial x} \hat{z}$$

differential

Look at complete Ampere's Law when $J=0$

$$\nabla \times \mathbf{B} = \mu_0 E_0 \frac{\partial \mathbf{E}}{\partial t} \quad \checkmark$$

Apply time derivative to both sides

$$\frac{\partial}{\partial t} (\nabla \times \mathbf{B}) = \frac{\partial}{\partial t} \left(\mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right)$$

$$\nabla \times \frac{\partial \mathbf{B}}{\partial t} = \mu_0 \epsilon_0 \frac{\partial^2 \mathbf{E}}{\partial t^2}$$

Plug $\frac{\partial \mathbf{B}}{\partial t}$ in

$$\nabla \times \frac{-\partial E_y}{\partial x} \hat{z} = \mu_0 \epsilon_0 \frac{\partial^2 E}{\partial t^2}$$

$$\begin{array}{ccc} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & 0 \end{array} \quad \begin{array}{l} \left(\frac{\partial E_y}{\partial x} - 0 \right) \hat{z} \\ = (0 - \frac{\partial^2 E_y}{\partial x^2}) \hat{y} \\ \frac{\partial E_y}{\partial x} (0) \hat{z} \end{array}$$

$$+ \left(+ \frac{\partial^2 E_y}{\partial x^2} \right) \hat{y} = \mu_0 \epsilon_0 \frac{\partial^2 E}{\partial t^2} \quad \mu_0 \epsilon_0 = \frac{1}{c^2}$$

$$\frac{\partial^2 E_y}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 E_y}{\partial t^2}$$

b/c $\frac{\partial^2 E}{\partial t^2}$ is only dependent
on E_y in \hat{y} direction ✓

Do the same as E_y but with E_z

$$\nabla \times \mathbf{E}_z = \begin{array}{ccc} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & E_z \end{array} = \begin{array}{l} \left(\frac{\partial E_z}{\partial y} - 0 \right) \hat{x} \\ = (0 - \frac{\partial^2 E_z}{\partial x^2}) \hat{y} \\ = 0 \hat{z} \end{array}$$

$$-\nabla \times \mathbf{E}_z = + \frac{\partial E_z}{\partial x} \hat{y} = + \frac{\partial B}{\partial t} \quad \checkmark$$

$$\frac{\partial B}{\partial t} = \frac{\partial E_z}{\partial x} \hat{y}$$

Look at complete Ampere's Law when $J=0$

$$\nabla \times \mathbf{B} = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$$

Apply time derivative to both sides

$$\frac{\partial}{\partial t} (\nabla \times \mathbf{B}) = \frac{\partial}{\partial t} (\mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t})$$

$$\nabla \times \frac{\partial \mathbf{B}}{\partial t} = \mu_0 \epsilon_0 \frac{\partial^2 \mathbf{E}}{\partial t^2}$$

$$\mu_0 \epsilon_0 = \frac{1}{c^2}$$

Plug $\frac{\partial \mathbf{B}}{\partial t}$ in

$$\nabla \times \frac{\partial \mathbf{E}_z}{\partial x} \hat{y} = \mu_0 \epsilon_0 \frac{\partial^2 \mathbf{E}}{\partial t^2}$$

$$\frac{\partial^2 \mathbf{E}_z}{\partial x^2} \hat{z} = \mu_0 \epsilon_0 \frac{\partial^2 \mathbf{E}}{\partial t^2}$$

$$\begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & \frac{\partial \mathbf{E}_z}{\partial x} & 0 \end{matrix} = \begin{matrix} (0 - \frac{\partial^2 \mathbf{E}_z}{\partial x \partial z}) \hat{x} \\ 0 \hat{y} \\ (\frac{\partial^2 \mathbf{E}_z}{\partial x^2} - 0) \hat{z} \end{matrix}$$

b/c $\frac{\partial^2 \mathbf{E}}{\partial t^2}$ is only dependent on E_z in \hat{z}

Start with B_y and Ampere's law

$$\nabla \times B_y = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$$

$$\begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & B_y & 0 \end{matrix} = \begin{matrix} (0 - \frac{\partial^2 B_y}{\partial z \partial y}) \hat{x} \\ 0 \hat{y} \\ (\partial_x B_y - 0) \hat{z} \end{matrix}$$

$$\frac{\partial B_y}{\partial x} \hat{z} = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$$

Take time derivative of Faraday's law

$$\frac{\partial}{\partial t} (\nabla \times \mathbf{E}) = \frac{\partial}{\partial t} - \left(\frac{\partial \mathbf{B}}{\partial t} \right)$$

$$\nabla \times \frac{\partial \mathbf{E}}{\partial t} = - \frac{\partial^2 \mathbf{B}}{\partial t^2}$$

$$\frac{\partial \mathbf{E}}{\partial t} = \frac{1}{\mu_0 \epsilon_0} \frac{\partial B_y}{\partial x} \hat{z}$$

$$\nabla \times \frac{1}{\mu_0 \epsilon_0} \frac{\partial B_y}{\partial x} \hat{z} = - \frac{\partial^2 B}{\partial t^2}$$

$$\begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & \frac{\partial B_y}{\partial x} \end{matrix} = \begin{matrix} (\frac{\partial^2 B_y}{\partial x \partial y} - 0) \hat{x} \\ (0 - \frac{\partial^2 B_y}{\partial x^2}) \hat{y} \\ 0 \hat{z} \end{matrix}$$

$$+\frac{1}{\mu_0} \frac{\partial^2 B_y}{\partial x^2} \hat{y} = +\frac{\partial^2 B}{\partial t^2}$$

$$\boxed{\frac{\partial^2 B_y}{\partial x^2} \hat{y} = \mu_0 \frac{\partial^2 B}{\partial t^2}}$$

Start with B_z and Ampere's law

$$\nabla \times B_z = \mu_0 \epsilon_0 \frac{\partial E}{\partial t} \quad \begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ \partial x & \partial y & \partial z \\ 0 & 0 & B_z \end{matrix} = \begin{matrix} (\partial_x B_z - 0) \hat{x} \\ (0 - \partial_x B_z) \hat{y} \\ 0 \hat{z} \end{matrix}$$

$$-\frac{\partial B_z}{\partial x} \hat{y} = \mu_0 \epsilon_0 \frac{\partial E}{\partial t} \Rightarrow \frac{\partial E}{\partial t} = -\frac{1}{\mu_0 \epsilon_0} -\frac{\partial B_z}{\partial x} \hat{y}$$

Take time derivative of Faraday's law

$$\nabla \times \frac{\partial E}{\partial t} = -\frac{\partial B}{\partial t^2} \quad \begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ \partial x & \partial y & \partial z \\ 0 & \frac{\partial B_z}{\partial x} & 0 \end{matrix} = \begin{matrix} (0 - \frac{\partial^2 B_z}{\partial x^2}) \hat{x} \\ 0 \hat{y} \\ (\frac{\partial^2 B_z}{\partial x^2} - 0) \hat{z} \end{matrix}$$

$$\nabla \times +\frac{1}{\mu_0 \epsilon_0} \frac{\partial B_z}{\partial x} \hat{y} = +\frac{\partial^2 B}{\partial t^2}$$

$$\boxed{\frac{\partial^2 B_z}{\partial x^2} \hat{z} = \mu_0 \epsilon_0 \frac{\partial^2 B}{\partial t^2}}$$



6. 2.2) Does it follow that

$$E_x(x,t) = B_x(x,t) = 0?$$

Given that $\nabla \cdot E = 0$ and $\nabla \cdot B = 0$

and $\nabla \times E = -\frac{dB}{dt}$ and $\nabla \times B = \mu_0 \epsilon_0 \frac{dE}{dt}$.

$$\nabla \cdot E = 0 \quad \text{use } E = E_x(x,t) \hat{x}$$

$$\frac{\partial E_x}{\partial x} = 0 \quad \checkmark$$

$$\int dE_x = \int 0 dx$$

$$B_x = g_2(t) + C_2$$

$E_x = g_1(t) + C_1$ → same can be done for B

$$\nabla \times E = -\frac{\partial B}{\partial t} \quad \begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ \partial x & \cancel{\partial y} & \partial z \end{matrix} = (\partial z E_x - 0) \hat{y} \quad (0) \cancel{\hat{x}}$$

$$\nabla \times E = \frac{\partial E_x}{\partial z} \hat{y} = \frac{\partial B}{\partial y} \hat{z} = -\frac{\partial B}{\partial t} \cancel{\hat{z}} \neq 0$$

$$\int \frac{\partial B}{\partial t} dt = 0 \Rightarrow \int dB = -\int 0 dt$$

$B = C_2$ ← same can be done with
Ampere's Law for B

$$E_x(x,t) = C_1 \quad \checkmark \quad B_x(x,t) = C_2 \text{ not } 0$$

(6.2.3) Show how 1 is consistent with

$$\nabla^2 \mathbf{E} = \frac{1}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2} \quad \nabla^2 \mathbf{B} = \frac{1}{c^2} \frac{\partial^2 \mathbf{B}}{\partial t^2}$$

from 6.2.1

$$\frac{\partial^2 E_x}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 E_x}{\partial t^2} \quad \frac{\partial^2 E_y}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 E_y}{\partial t^2}$$

$$\frac{\partial^2 B_y}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 B_y}{\partial t^2} \quad \frac{\partial^2 B_z}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 B_z}{\partial t^2}$$

Start : $\nabla^2 \mathbf{E} = \frac{1}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2}$

$$\nabla^2 \mathbf{E} = \nabla^2 E_x \hat{x} + \nabla^2 E_y \hat{y} + \nabla^2 E_z \hat{z} \quad \text{expand } \nabla^2 \mathbf{E}$$

$$\nabla^2 E_x = \frac{\partial^2 E_x}{\partial x^2} + \frac{\partial^2 E_x}{\partial y^2} + \frac{\partial^2 E_x}{\partial z^2} \quad \checkmark$$

$$\nabla^2 E_y = \frac{\partial^2 E_y}{\partial x^2} + \frac{\partial^2 E_y}{\partial y^2} + \frac{\partial^2 E_y}{\partial z^2} \quad \begin{matrix} \text{compare to} \\ \text{time derivative} \end{matrix}$$

$$\nabla^2 E_z = \frac{\partial^2 E_z}{\partial x^2} + \frac{\partial^2 E_z}{\partial y^2} + \frac{\partial^2 E_z}{\partial z^2} \quad \checkmark$$

$$\frac{\partial^2 \mathbf{E}}{\partial t^2} = \frac{\partial^2 E_x}{\partial t^2} \hat{x} + \frac{\partial^2 E_y}{\partial t^2} \hat{y} + \frac{\partial^2 E_z}{\partial t^2} \hat{z} \quad \begin{matrix} \text{expand time} \\ \text{derivative} \end{matrix}$$

$$\nabla^2 E_x = \frac{\partial^2 E_x}{\partial t^2} \frac{1}{c^2} \leftarrow \text{skipping the one}$$

Compare components

$$\nabla^2 E_y = \frac{\partial^2 E_y}{\partial t^2} \frac{1}{c^2}$$

$$\nabla^2 E_z = \frac{\partial^2 E_z}{\partial t^2} \frac{1}{c^2}$$

$$\frac{\partial^2 E_y}{\partial x^2} + \cancel{\frac{\partial^2 E_y}{\partial y^2}} + \cancel{\frac{\partial^2 E_y}{\partial z^2}} = \frac{\partial^2 E_y}{\partial t^2} \frac{1}{c^2}$$

If E_y depends only on x and t

$$\frac{\partial^2 E_y}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 E_y}{\partial t^2}$$

$$\frac{\partial^2 E_z}{\partial x^2} + \cancel{\frac{\partial^2 E_z}{\partial y^2}} + \cancel{\frac{\partial^2 E_z}{\partial z^2}} = \frac{1}{c^2} \frac{\partial^2 E_z}{\partial t^2}$$

If E_z depends only on x and t

$$\frac{\partial^2 E_z}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 E_z}{\partial t^2}$$

Do the same for B



skipping to component step

$$\nabla^2 B_x = \frac{1}{c^2} \frac{\partial^2 B_x}{\partial t^2} \quad \leftarrow \text{skip this component}$$

$$\nabla^2 B_y = \frac{1}{c^2} \frac{\partial^2 B_y}{\partial t^2}$$

$$\nabla^2 B_z = \frac{1}{c^2} \frac{\partial^2 B_z}{\partial t^2}$$

$$\frac{\partial^2 B_y}{\partial x^2} + \frac{\partial^2 B_y}{\partial y^2} + \frac{\partial^2 B_y}{\partial z^2} = \frac{1}{c^2} \frac{\partial^2 B_y}{\partial t^2}$$

if B_y depends only on x and t

$$\frac{\partial^2 B_y}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 B_y}{\partial t^2}$$

$$\frac{\partial^2 B_z}{\partial x^2} + \frac{\partial^2 B_z}{\partial y^2} + \frac{\partial^2 B_z}{\partial z^2} = \frac{1}{c^2} \frac{\partial^2 B_z}{\partial t^2}$$

if B_z depends only on x and t

$$\frac{\partial^2 B_z}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 B_z}{\partial t^2} \quad \checkmark$$

6.3.1) Show

Matthew Jackson
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$$\vec{E} = E_{ox} \cos(k_z z - \omega t + \delta_x) \hat{x}$$

Satisfies

$$\nabla^2 \vec{E} = \frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2}$$

and

$$\vec{B} = B_{ox} \cos(k_z z - \omega t + \delta'_x) + B_{oy} \cos(k_z z - \omega t + \delta'_y) \hat{y}$$

Satisfies

$$\nabla^2 \vec{B} = \frac{1}{c^2} \frac{\partial^2 \vec{B}}{\partial t^2}$$

Start with \vec{E}

$$\nabla^2 \vec{E} = \frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\begin{aligned} \nabla^2 \vec{E} &= \nabla^2 E_x \hat{x} + \nabla^2 E_y \hat{y} + \nabla^2 E_z \hat{z} \\ &= \left(\frac{\partial^2}{\partial x^2} E_x + \frac{\partial^2}{\partial y^2} E_y + \frac{\partial^2}{\partial z^2} E_z \right) \hat{x} \end{aligned}$$

$$\nabla^2 E_x = -k_z^2 E_{ox} \cos(k_z z - \omega t + \delta_x) \hat{x}$$

$$\begin{aligned} \frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2} &= \frac{1}{c^2} \frac{\partial^2}{\partial t^2} (E_{ox} \cos(k_z z - \omega t + \delta_x) \hat{x}) \frac{1}{c^2} \\ &= -\frac{\omega^2}{c^2} E_{ox} \cos(k_z z - \omega t + \delta_x) \end{aligned}$$

$$\nabla^2 E = \frac{1}{c^2} \frac{\partial^2 E}{\partial t^2}$$

$$-k_z^2 E_{ox} \cos(k_z z - \omega t + \delta_x) = -\frac{\omega^2}{c^2} E_{ox} \cos(k_z z - \omega t + \delta_x)$$

$$+ k_z^2 E = + \frac{\omega^2}{c^2} E$$

$$\sqrt{k_z^2 + \frac{\omega^2}{c^2}} \rightarrow k_z = \pm \frac{\omega}{c}$$

$\nabla^2 E = \frac{1}{c^2} \frac{\partial^2 E}{\partial t^2}$ is true when k_z is related to ω by c such that $|k_z c| = |\omega|$

$$\nabla^2 B = \frac{1}{c^2} \frac{\partial^2 B}{\partial t^2}$$

$$\nabla^2 B = \nabla^2 B_x \hat{x} + \nabla^2 B_y \hat{y} + \nabla^2 B_z \hat{z}$$

$$= \left(\frac{\partial^2}{\partial x^2} B_x + \frac{\partial^2}{\partial y^2} B_x + \frac{\partial^2}{\partial z^2} B_x \right) \hat{x} +$$

$$\left(\frac{\partial^2}{\partial x^2} B_y + \frac{\partial^2}{\partial y^2} B_y + \frac{\partial^2}{\partial z^2} B_y \right) \hat{y}$$

$$= \frac{\partial^2}{\partial z^2} B_x \hat{x} + \frac{\partial^2}{\partial z^2} B_y \hat{y}$$

$$= \frac{\partial^2}{\partial z^2} B_{ox} \cos(k_z z - \omega t + \delta_x) \hat{x} +$$

$$\frac{\partial^2}{\partial z^2} B_{oy} \cos(k_z z - \omega t + \delta_y) \hat{y}$$

$$\nabla^2 B = -k_z^2 \left(B_{ox} \cos(k_z z - \omega t + \delta_x) \hat{x} + B_{oy} \cos(k_z z - \omega t + \delta_y) \hat{y} \right)$$

$$\frac{1}{c^2} \frac{\partial^2 \mathbf{B}}{\partial t^2} = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \left(B_{0x} \cos(k_z z - \omega t + \delta_x') \hat{x} + B_{0y} \cos(k_z z - \omega t + \delta_y') \hat{y} \right)$$

$$= \frac{-\omega^2}{c^2} \left(B_{0x} \cos(k_z z - \omega t + \delta_x') \hat{x} + B_{0y} \cos(k_z z - \omega t + \delta_y') \hat{y} \right) \underbrace{\frac{-\omega^2}{c^2} \mathbf{B}}$$

$$\nabla^2 \mathbf{B} = \frac{1}{c^2} \frac{\partial^2 \mathbf{B}}{\partial t^2}$$

$$+ k_z^2 \mathbf{B} = \frac{-\omega^2}{c^2} \mathbf{B}$$

$$\sqrt{k_z^2} = \sqrt{\frac{\omega^2}{c^2}} \Rightarrow k_z = \pm \frac{\omega}{c}$$

$\nabla^2 \mathbf{B} = \frac{1}{c^2} \frac{\partial^2 \mathbf{B}}{\partial t^2}$ is true when k_z is related

to ω by c such that $|k_z c| = |\omega|$

6.3.2) Show that $k_z, \omega, E_x, B_{ox}, B_{oy}, S_x, S'_x$, or S'_y must be related or 0 for \mathbf{B} and \mathbf{E} to be consistent with Maxwell's equations

Maxwell's Eq

$\rightarrow \sin \rightarrow \cos \rightarrow -\sin \rightarrow -\cos$

$$\nabla \cdot \mathbf{E} = P/G = 0 \quad (\varphi = 0)$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \quad (\because \mathbf{J} = 0)$$

$$\mathbf{E} = E_{ox} \cos(k_z z - \omega t + S_x) \hat{x}$$

$$\mathbf{B} = B_{ox} \cos(k_z z - \omega t + S'_x) \hat{x} + B_{oy} \cos(k_z z - \omega t + S'_y) \hat{y}$$

$$\nabla \times \mathbf{E} = \begin{matrix} \hat{x} & \hat{y} & \hat{z} & 0 \end{matrix} \begin{matrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \mathbf{E} & 0 & 0 \end{matrix} = \begin{matrix} 0 \\ 0 \\ 0 \end{matrix} = (0 - E_x) \hat{y} + (0 - \frac{\partial E_x}{\partial z}) \hat{z}$$

$$\nabla \times \mathbf{E} = -k_z E_{ox} \sin(k_z z - \omega t + S_x) \hat{y}$$

$$\frac{\partial \mathbf{B}}{\partial t} = +\omega (+B_{ox} \sin(k_z z - \omega t + S'_x) \hat{x} + B_{oy} \sin(k_z z - \omega t + S'_y) \hat{y})$$

$$\nabla \times \mathbf{B} = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$$

$$\nabla \times \mathbf{B} = \begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ B_x & B_y & 0 \end{matrix} = \begin{matrix} (0 - \partial_z B_y) \hat{x} \\ (\partial_z B_x - 0) \hat{y} \\ (\partial_x B_y - \partial_y B_x) \hat{z} \end{matrix}$$

$$\nabla \times \mathbf{B} = +k_z (+B_{oy} \sin(k_z z - \omega t + \delta'_y) \hat{x}) + \\ k_z (-B_{ox} \sin(k_z z - \omega t + \delta'_x) \hat{y})$$

$$\frac{\partial \mathbf{E}}{\partial t} = +\omega (+E_{ox} \sin(k_z z - \omega t + \delta_x) \hat{x})$$

$$\nabla \times \mathbf{B} = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$$

$$k_z B_{oy} \sin(k_z z - \omega t + \delta'_y) \hat{x} - B_{oy}^{\leftarrow} \sin(k_z z - \omega t + \delta'_x) \hat{y} = \\ \text{must be } 0 \\ = \mu_0 \epsilon_0 \omega E_{ox} \sin(k_z z - \omega t + \delta_x) \hat{x}$$

IF $B_{ox} = 0$, all components work out

$$k_z B_{oy} \sin(k_z z - \omega t + \delta'_y) \hat{x} = \mu_0 \epsilon_0 \omega E_{ox} \sin(k_z z - \omega t + \delta_x) \hat{x}$$

IF $\delta'_y = \delta_x$, then $k_z B_{oy} = \mu_0 \epsilon_0 \omega E_{ox}$. Using

$$\frac{E_{ox}}{B_{oy}} = \frac{\omega}{k_z} \text{ then } k_z = \mu_0 \epsilon_0 \omega \left(\frac{E_{ox}}{\omega} \right)$$

$$\text{Thus } \left(\frac{\omega}{k_z} \right)^2 = \frac{1}{\mu_0 \epsilon_0}$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$-k_z E_{ox} \sin(k_z z - \omega t + \delta_x) \hat{\mathbf{g}} = -(\omega (B_{ox} \sin(k_z z - \omega t + \delta'_x)) \hat{\mathbf{x}} \\ B_{oy} \sin(k_z z - \omega t + \delta'_y) \hat{\mathbf{y}})$$

$-\omega B_{ox} \sin(k_z z - \omega t + \delta'_x) \hat{\mathbf{x}}$ must equal 0
 $B_{ox} = 0$ achieves this

$$+ k_z E_{ox} \sin(k_z z - \omega t + \delta_x) \hat{\mathbf{g}} = +\omega B_{oy} \sin(k_z z - \omega t + \delta'_y) \hat{\mathbf{g}}$$

$$k_z \phi = k_z z - \omega t$$

$$k_z E_{ox} \sin(\phi + \delta_x) = \omega B_{oy} \sin(\phi + \delta'_y)$$

$$k_z E_{ox} (\sin(\phi) \cos(\delta_x) + \cos(\phi) \sin(\delta_x)) = \Rightarrow \\ \omega B_{oy} (\sin(\phi) \cos(\delta'_y) + \cos(\phi) \sin(\delta'_y))$$

IF $\delta_x = \delta'_y$, then $k_z E_{ox} = \omega B_{oy}$ or

$$\frac{E_{ox}}{B_{oy}} = \frac{\omega}{k_z}$$

technically,
one egn & two unknowns B_{oy} & δ'_y
Integrate to show $B_{oy} = E_{ox}/c$. then
left with one egn. & one unknown δ'_y .

Thus $B_{0x} = 0$

$$\frac{E_{0x}}{B_{0y}} = \frac{\omega}{k_z}, \quad \left(\frac{\omega}{k_z}\right)^2 = \frac{1}{\mu_0 \epsilon_0} \quad \text{when } \delta_x = \delta_y$$

Use this to see if other solutions to δ_x and δ_y

Resume from Ampere's law $\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I$

$$k_z B_{0y} (\sin \phi \cos \delta_y + \cos \phi \sin \delta_y) = \mu_0 \omega E_{0x} (\sin \phi \cos \delta_x + \cos \phi \sin \delta_x)$$

$$(\sin \phi \cos \delta_y + \cos \phi \sin \delta_y) = \frac{\mu_0 \omega}{k_z} \frac{E_{0x}}{B_{0y}} (\sin \phi \cos \delta_x + \cos \phi \sin \delta_x)$$

$$(\sin \phi \cos \delta_y + \cos \phi \sin \delta_y) = (\sin \phi \cos \delta_x + \cos \phi \sin \delta_x)$$

Pick an offset such that $\delta_y = n\pi + \delta_x$

$$\begin{aligned} \sin \phi \cos(n\pi + \delta_x) + \cos \phi \sin(n\pi + \delta_x) &= \sin \phi \cos \delta_x + \cos \phi \sin \delta_x \\ \sin \phi (\cos n\pi \cos \delta_x - \sin n\pi \sin \delta_x) + \cos \phi (\sin n\pi \cos \delta_x + \cos n\pi \sin \delta_x) &= \\ \pm (\sin \phi \cos \delta_x + \cos \phi \sin \delta_x) &= \sin \phi \cos \delta_x + \cos \phi \sin \delta_x \end{aligned}$$

This sign flip would imply that $E_{0y}/B_{0y} = \pm \frac{\omega}{k_z}$
 Which can not be true. Therefore n
 must be an even integer.

Thus $\frac{1}{\sqrt{\mu_0 \epsilon_0}} = \left(\frac{\omega}{k_z} \right) = \frac{B_{ox}}{B_{oy}}$, $B_{ox} = 0$, and

$$\delta_x = \delta_y + n\pi \quad \text{when } n \text{ is an even integer}$$

6.3.3) If $\mathbf{E} = E_{oy} \cos(k_z z - \omega t + \delta_y) \hat{j}$

Faraday's law (I think this is for \hat{y})

$$\nabla \times \mathbf{E} = \begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial z} & \frac{\partial}{\partial y} & \frac{\partial}{\partial x} \\ 0 & E_{oy} & 0 \end{matrix} = \begin{matrix} 0 & -\frac{\partial}{\partial z} E_{oy} & 0 \\ 0 & 0 & 0 \end{matrix} \hat{x}$$

$$\nabla \times \mathbf{E} = -k_z (-E_{oy} \sin(k_z z - \omega t + \delta_y)) \hat{x}$$

use $\frac{d\mathbf{B}}{dt}$ from 6.3.2 $\phi = k_z z - \omega t$

$$+ k_z (+E_{oy} \sin(\phi + \delta_y)) \hat{x} = -\omega (B_{ox} \sin(\phi + \delta_x) \hat{x} + B_{oy} \sin(\phi + \delta_y) \hat{y})$$

$B_{oy} = 0$ to cancel \hat{y} component

$$k_z E_{oy} \sin(\phi + \delta_y) \hat{x} = -\omega B_{ox} \sin(\phi + \delta_x) \hat{x}$$

Assume trivial solution $\delta_y = \delta_x$

$$k_z E_{oy} = -\omega B_{ox}$$

$$\frac{E_{oy}}{B_{ox}} = -\frac{\omega}{k_z}$$

Ampere's law

$$\frac{\partial \mathbf{E}}{\partial t} = +\omega (+E_{oy} \sin(k_z z - \omega t + \delta_y) \hat{j})$$

use $\nabla \times \mathbf{B}$ from 6.3.2

$$k_z B_{oy} \sin(k_z z - \omega t + \delta_y) \hat{x} - k_z B_{ox} \sin(k_z z - \omega t + \delta_x') \hat{y} = \mu_0 \omega E_{oy} \sin(k_z z - \omega t + \delta_y) \hat{z}$$

$$B_{oy} = 0$$

$$-k_z B_{ox} \sin(k_z z - \omega t + \delta_x') = \mu_0 \omega B_{oy} \sin(k_z z - \omega t + \delta_y)$$

$$\text{if } \delta_x' = \delta_y$$

$$-k_z B_{ox} = \mu_0 \omega B_{oy}$$

$$1 = \mu_0 \left(\frac{-\omega}{k_z} \right) \frac{E_{oy}}{B_{ox}} < \left(\frac{-\omega}{k_z} \right)$$

$$\frac{\omega}{k_z} = \frac{\pm 1}{\sqrt{\mu_0}}$$

From 6.3.2 $\delta_y = \delta_x' + n\pi$ $n=0, 1, \dots$

thus $\frac{E_{oy}}{B_{ox}} = -\frac{\omega}{k}$, $\frac{\omega}{k} = \frac{\pm 1}{\sqrt{\mu_0}}$, $B_{oy} = 0$

6.3.4) Using $\mathbf{k} = k_x \hat{x} + k_y \hat{y} + k_z \hat{z}$

Show that 2 and 3 are consistent with

$$\mathbf{B} = \frac{1}{c} \mathbf{k} \times \mathbf{E}$$

from 6.3.2

$$\frac{\mathbf{E}_{ox}}{B_{oy}} = \frac{\omega}{k_z}$$

from 6.3.3

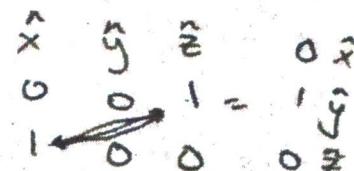
$$\frac{\mathbf{E}_{oy}}{B_{ox}} = -\frac{\omega}{k_z}$$

using $\mathbf{k} = k_z \hat{z}$ and $\omega/k = c$

6.3.2 $\rightarrow B_{oy} \hat{y} = \frac{1}{c} \mathbf{k} \times \mathbf{E}_x \hat{x}$ ✓

$$= \frac{k}{\omega} \hat{z} \times \mathbf{E}_x \hat{x}$$

$$= \frac{E_x k}{\omega} (\hat{z} \times \hat{x})$$



$$B_{oy} \hat{y} = \frac{E_x k}{\omega} \hat{y} \quad \checkmark$$

From
6.3.3

$$\frac{E_{oy}}{B_{ox}} = -\frac{\omega}{k_z}$$

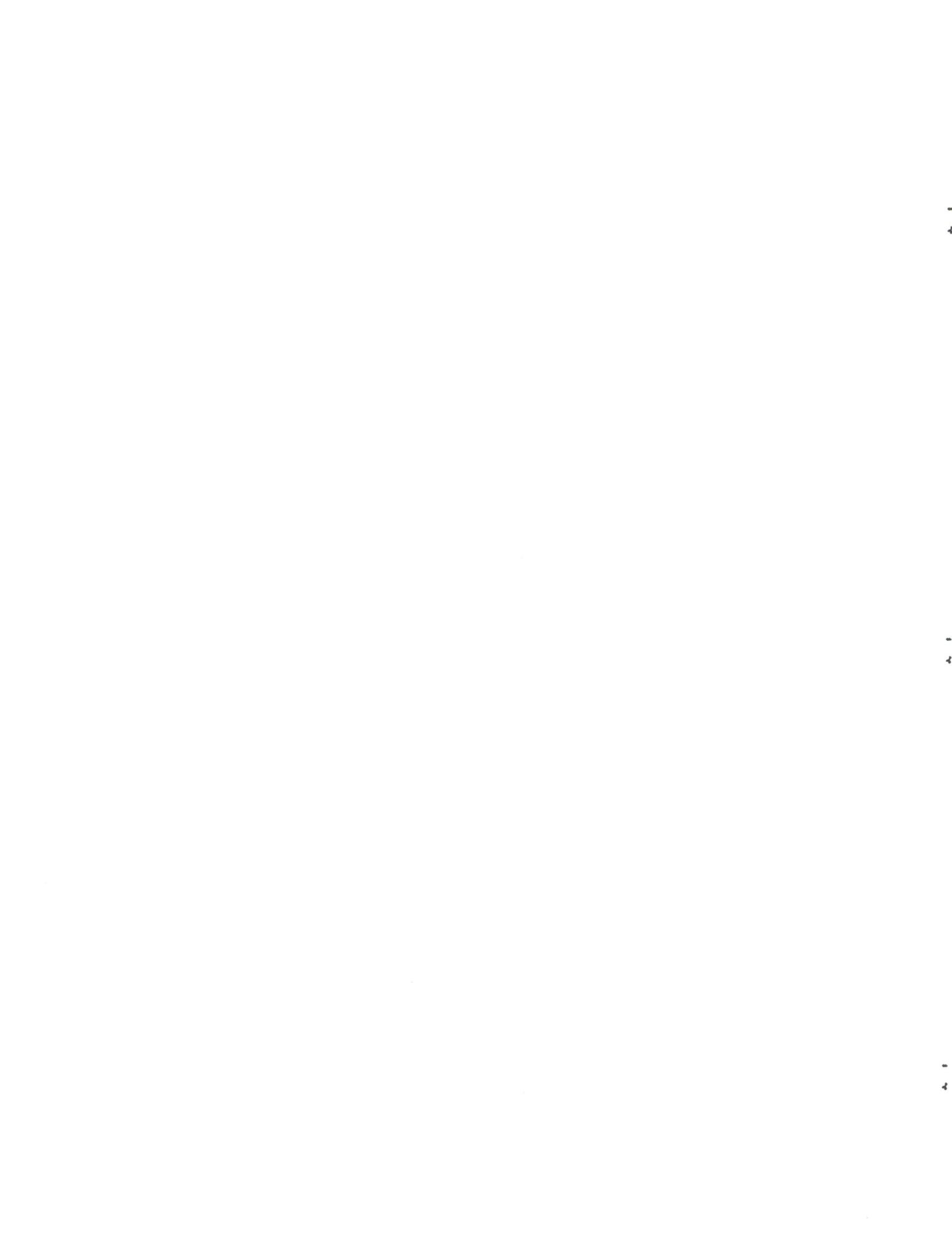
$$B_x \hat{x} = -\frac{k_z}{\omega} E_{oy} \hat{y} = \frac{1}{c} \hat{k} \times E_{oy} \hat{y}$$

$$\begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{matrix}$$

$$B_x \hat{x} = \frac{E_{oy} k}{\omega} \hat{z} \times \hat{y}$$

$$\begin{matrix} 0 & -1 & \hat{x} \\ 0 & \hat{y} & \\ 0 & \hat{z} & \end{matrix} \leftarrow$$

$$B_x \hat{x} = -\frac{E_{oy} k}{\omega} \hat{x}$$



Matthew
Jackson
PHYs 313
October 13, 2013
HW #6

6.4) Using $\mathbf{E} = \operatorname{Re}[\tilde{\mathbf{E}} e^{-i(\omega t - \mathbf{k} \cdot \mathbf{r})}]$

$$\mathbf{B} = \operatorname{Re}[\tilde{\mathbf{B}} e^{-i(\omega t - \mathbf{k} \cdot \mathbf{r})}]$$

$$\mathbf{k} = k_x \hat{x} + k_y \hat{y} + k_z \hat{z}$$

$$\mathbf{r} = x \hat{x} + y \hat{y} + z \hat{z}$$

Show that $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$ leads to

$$\tilde{\mathbf{B}} = \frac{1}{c} \hat{\mathbf{k}} \times \tilde{\mathbf{E}}$$

and explain how it relates to

$$\mathbf{B} = \frac{1}{c} \hat{\mathbf{k}} \times \mathbf{E}$$

$$\nabla \times \mathbf{E} = \operatorname{Re}[e^{-i\omega t} \nabla \times \tilde{\mathbf{E}} e^{i\mathbf{k} \cdot \mathbf{r}}]$$

$$-\frac{\partial \mathbf{B}}{\partial t} = \operatorname{Re}[\mathbf{B}(-i\omega) e^{-i\omega t} e^{i\mathbf{k} \cdot \mathbf{r}}]$$

Pick a direction such that $\tilde{\mathbf{B}}$ is only in the \hat{x}

$$\operatorname{Re}[e^{-i\omega t} \nabla \times \tilde{\mathbf{E}} e^{i\mathbf{k} \cdot \mathbf{r}}] = \frac{\hat{x}}{\partial_x} \frac{\hat{y}}{\partial_y} \frac{\hat{z}}{\partial_z} (\frac{\partial y E_z - \partial z E_y}{\partial z E_x - \partial x E_z})_x$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$= \frac{\hat{x}}{E_x} \frac{\hat{y}}{E_y} \frac{\hat{z}}{E_z} (\partial_x E_y - \partial_y E_x)_z$$

$$\frac{\partial}{\partial y} e^{ik \cdot r} = iku e^{ik \cdot r}$$

$$\text{Re} \left[e^{-i\omega t} \left(\frac{\partial}{\partial y} \tilde{E}_z e^{ik_z r} - \frac{\partial}{\partial z} \tilde{E}_y e^{ik_z r} \right) \right]$$

$$\text{Re} \left[e^{-i\omega t} \left(\tilde{E}_z i k_y e^{ik_z r} - \tilde{E}_y i k_z e^{ik_z r} \right) \right]$$

Assuming $\text{Im} \left[\frac{\hat{k} \times \tilde{E}}{c} = \mathbf{B} \right]$ such that the Re

Part can be dropped

Further more $e^{-i\omega t} e^{ik_z r}$ is on both sides,
so I will remove them

$$\tilde{E}_z i k_y - \tilde{E}_y i k_z = -\omega \tilde{B}_x$$

$$\begin{array}{lll} x & y & z \\ k_x & k_y & k_z = \frac{k_x E_x - k_z E_y}{k_x B_z - k_y B_z} \\ E_x & B_y & B_z = \frac{k_y E_z - k_z E_y}{k_x E_z - k_y E_x} \end{array}$$

IF $k_x = B_x = 0$

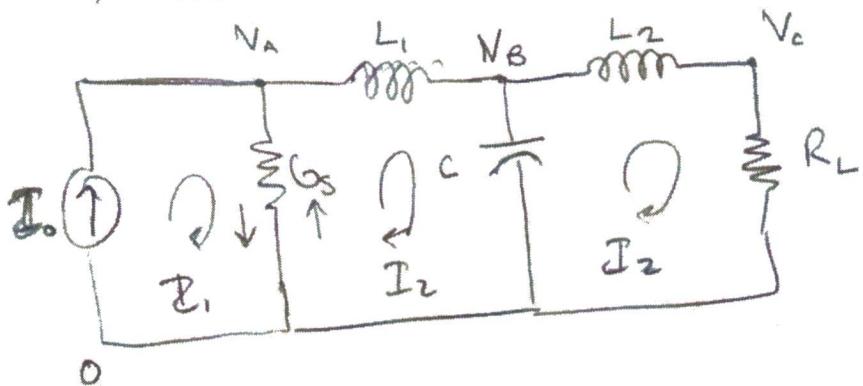
$$\hat{k} \times \tilde{E} = \omega \mathbf{B}$$

$$|\hat{k}|(\hat{k} \times \tilde{E}) = \omega \mathbf{B} \quad \frac{\omega}{k} = c \quad \text{OK, but see soln.}$$

$$\underline{c^{-1}(\hat{k} \times \tilde{E}) = \tilde{B}}$$

$\mathbf{B} = \frac{1}{c} \hat{k} \times \tilde{E}$ is related to $\tilde{\mathbf{B}} = \frac{1}{c} \hat{k} \times \tilde{E}$
by showing that there is an imaginary
component to the \tilde{E} and $\tilde{\mathbf{B}}$ fields
that follow the same equations. Furthermore
the real components of \tilde{E} & $\tilde{\mathbf{B}}$ are the
real electric and magnetic fields.

7.2) 4.3b from book



Matthew Jackson
PHYS 513
HW #7
October 20, 2020

First loop

Not possible with current source ✓

Second loop

$$-\frac{(I_2 - I_a)}{G_s} - L_1 \frac{dI_2}{dt} - \frac{1}{C} \int (I_2 - I_3) dt = 0 \quad \checkmark$$

Third Loop

$$-\frac{1}{C} \int (I_3 - I_2) dt - L_2 \frac{dI_3}{dt} - R_L I_3 = 0$$

Nodes $\rightarrow \downarrow \rightarrow$

$$A: I_o - V_A G_S - \frac{1}{L_1} \int (V_a - V_b) dt = 0$$

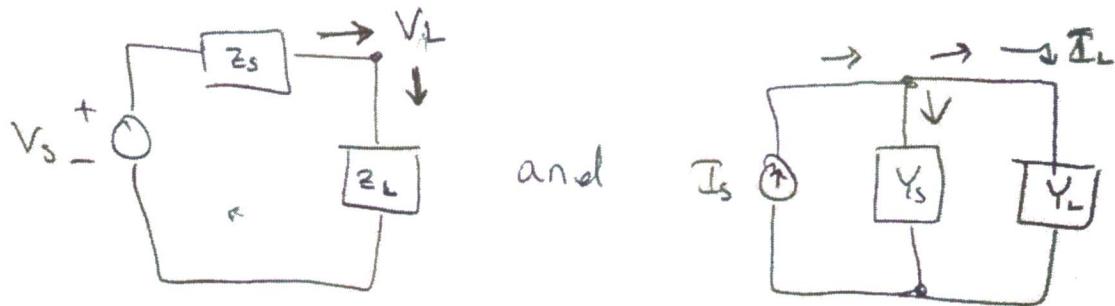
$$B: \frac{1}{L_1} \int (V_b - V_a) dt + \frac{1}{L_2} \int (V_b - V_c) dt + C \frac{dV}{dt} = 0$$

$$C: \frac{1}{L_2} \int (V_c - V_b) dt + \frac{V_c}{R_L} = 0 \quad \checkmark$$

Should comment on relationship w/ other circuit

7.2) 4.3c

Show that



produce the same current to and Voltage across the Load.

$$\frac{V_s - V_L}{Z_s} - \frac{V_L}{Z_L} = 0$$

$$\frac{V_s}{Z_s} - V_L \left(\frac{1}{Z_s} + \frac{1}{Z_L} \right) = 0$$

$$\frac{V_s}{Z_s} = V_L \left(\frac{1}{Z_s} + \frac{1}{Z_L} \right)$$

$$\frac{V_s}{Z_s} = V_L \left(\frac{Z_L}{Z_s Z_L} + \frac{Z_s}{Z_L Z_s} \right)$$

$$\frac{V_s}{Z_s} = V_L \left(\frac{Z_L + Z_s}{Z_s Z_L} \right)$$

$$V_L = V_s \left(\frac{Z_L}{Z_s + Z_L} \right)$$

Check with Norton circuit

Check currents into node

$$I_s - V_L Y_s - V_L Y_L = 0$$

$$I_s - \frac{V_L}{Z_s} - \frac{V_L}{Z_L} = 0$$

$$I_s = \frac{V_L}{Z_s} + \frac{V_L}{Z_L}$$

$$I_s = \frac{Z_L V_L + Z_s V_L}{Z_s Z_L}$$

$$I_s Z_s Z_L = V_L (Z_L + Z_s)$$

$$\frac{I_s Z_s Z_L}{(Z_L + Z_s)} = V_L$$

$$V_L = \frac{V_s Z_L}{(Z_L + Z_s)} \quad \leftarrow \text{same voltage} \checkmark$$

Given that Z_L and V_L are the same I_L should also be the same

7.2) 4.3 d

V_s and Z_s are constant. Show
that Power is maximized when
 $Z_L = Z_s^*$

$$P = VI \rightarrow \operatorname{Re}[V e^{i\omega t}] \operatorname{Re}[I e^{i\omega t}]$$

$$P = \operatorname{Re}[(V_r + iV_i)(\cos(\omega t) + i\sin(\omega t))] =$$

$$\operatorname{Re}[I_r + iI_i](\cos(\omega t) + i\sin(\omega t)]$$

$$\operatorname{Re}[(V_r + iV_i)(\cos(\omega t) + i\sin(\omega t))] =$$

$$\operatorname{Re}[V_r \cos(\omega t) + iV_r \sin(\omega t) + iV_i \cos(\omega t) - V_i \sin(\omega t)]$$

same with $I \uparrow$

$$\operatorname{Re}[(V_r + iV_i)(\cos(\omega t) + i\sin(\omega t))] = V_r \cos(\omega t) + V_i \sin(\omega t)$$

$$P = (V_r \cos(\omega t) + V_i \sin(\omega t))(I_r \cos(\omega t) - I_i \sin(\omega t))$$

$$P = V_r I_r \cos^2(\omega t) + V_i I_i \sin^2(\omega t) - (V_r I_i + V_i I_r) \cos(\omega t) \sin(\omega t)$$

$$\bar{P} = \frac{1}{2}(V_r I_r + V_i I_i) = \frac{1}{2} \operatorname{Re}[VI^*]$$

$$\bar{P} = \frac{1}{2} \operatorname{Re}[VI^*] \quad V = IZ$$

$$\bar{P} = \frac{1}{2} \operatorname{Re} [\bar{V} \bar{I}^*]$$

$$\text{Maximize } \bar{P}_L = \frac{1}{2} \operatorname{Re} [\bar{V}_L \bar{I}^*]$$

$$V_L = I Z_L$$

$$\bar{P}_L = \frac{1}{2} |\bar{I}|^2 \operatorname{Re}[Z_L]$$

$$\bar{P}_L = \frac{1}{2} \left(\frac{|V_s|}{|Z_s + Z_L|} \right)^2 \operatorname{Re}[Z_L]$$

$$\bar{P} = \frac{1}{2} \left(\frac{|V_s|}{|Z_{SR} + iZ_{Si} + Z_{LR} + iZ_{Li}|} \right)^2 \operatorname{Re}[Z_L]$$

$\operatorname{Re}[Z_s + Z_L]^2 + \operatorname{Im}[Z_s + Z_L]^2 \leftarrow \text{get this to zero}$

with $\operatorname{Im}[Z_L] = -\operatorname{Im}[Z_s]$

$$\bar{P} = \frac{1}{2} \left(\frac{|V_s|^2 \operatorname{Re}[Z_L]}{(\operatorname{Re}[Z_s] + \operatorname{Re}[Z_L])^2} \right) + \text{take derivative wrt } \operatorname{Re}[Z_L]$$

$$u = \operatorname{Re}[Z_L], v = \operatorname{Re}[Z_s]$$

$$\frac{\partial \bar{P}}{\partial u} = \frac{\partial}{\partial u} \left(\frac{1}{2} \frac{|V_s|^2 u}{(u+v)^2} \right) = 0$$

$$\frac{\partial \bar{P}}{\partial u} = \left(\frac{1}{(u+v)^2} + \frac{-2u}{(u+v)^3} \right) \cancel{\frac{1}{2} |V_s|^2} = 0$$

$$\frac{(u+v) - 2u}{(u+v)^3} = 0$$

only care about numerator but require

$$u+v \neq 0$$

$$\lambda + V - Z_u = 0$$

$V = u \leftarrow$ sub back in

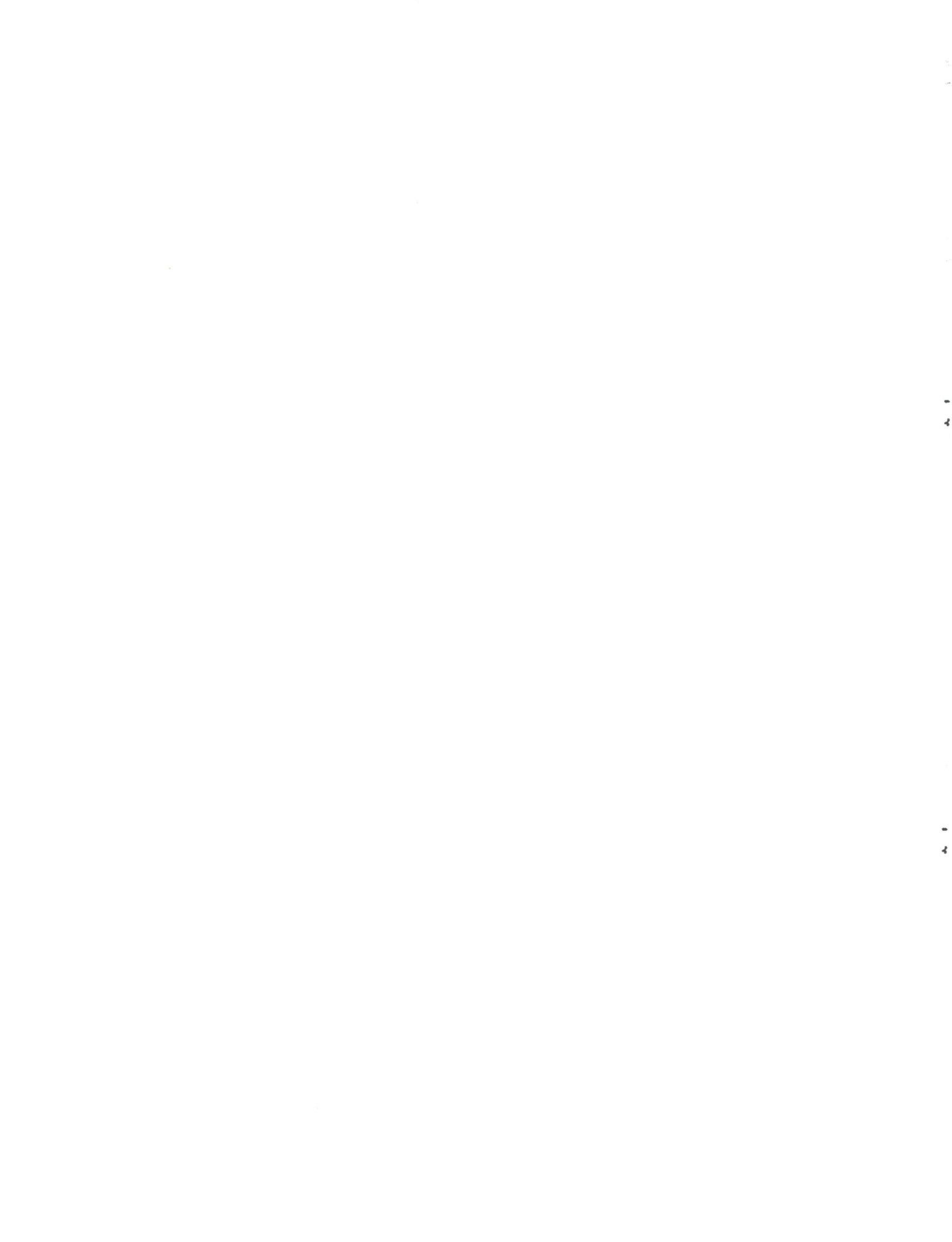
$$\operatorname{Re}[z_s] = \operatorname{Re}[z_L]$$

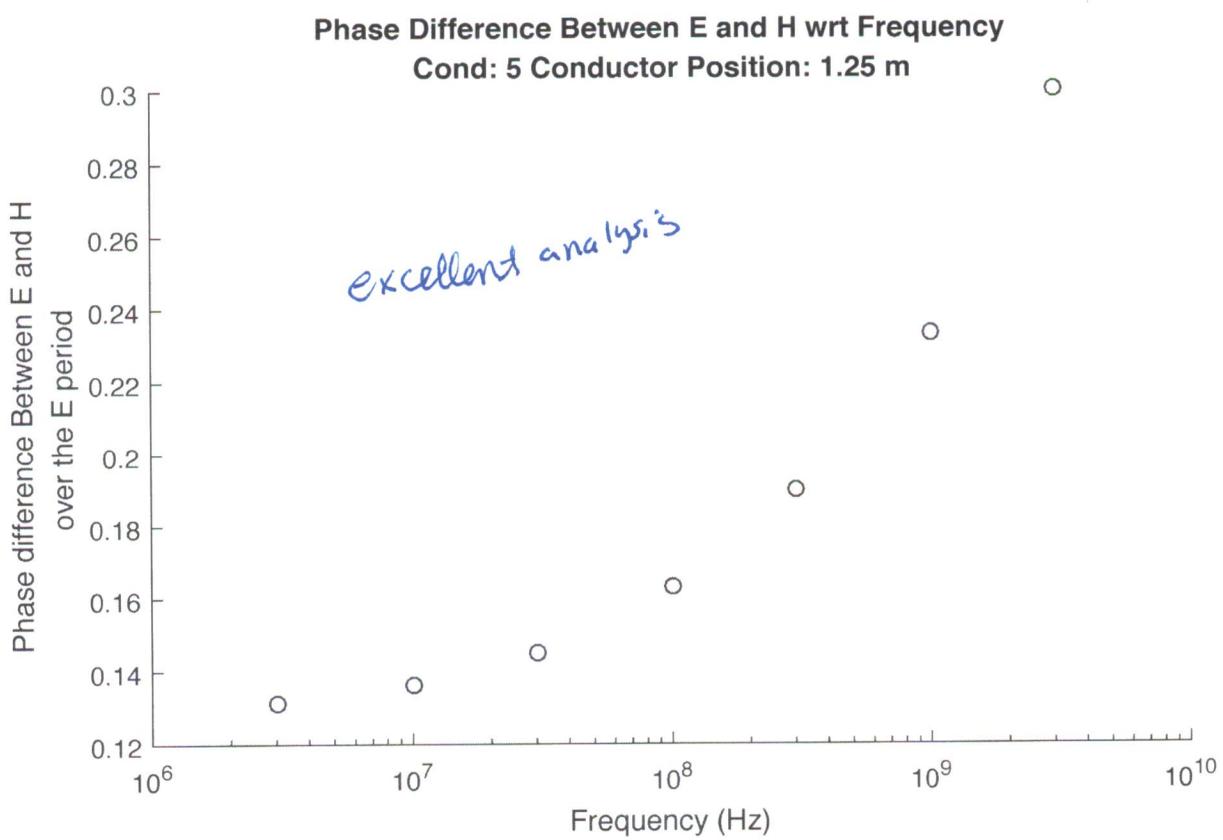
$$(\operatorname{Im}[z_s] = -\operatorname{Im}[z_s])$$

Plug in $z_L = z_s^*$

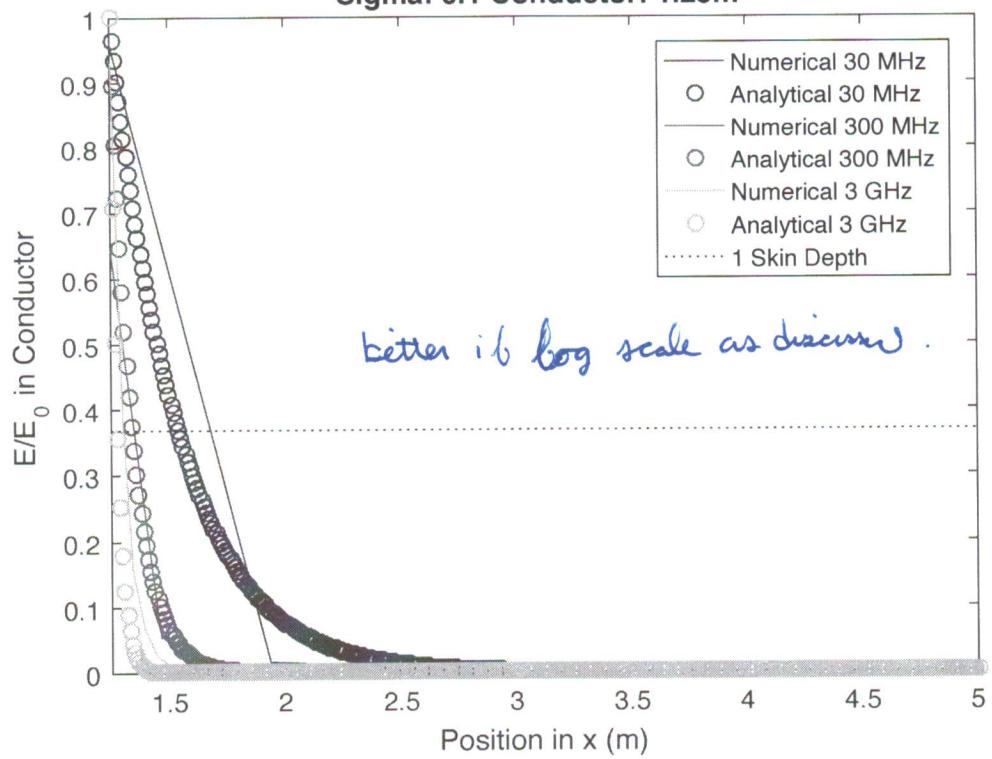
This should be the local max
because if $z_L \ll z_s$ then $\bar{P} \rightarrow 0$
and if $z_L \gg z_s$ $\bar{P} \propto \frac{1}{z_L}$ which goes
to 0.

$\therefore P$ is maximized when $\checkmark z_L = z_s^*$

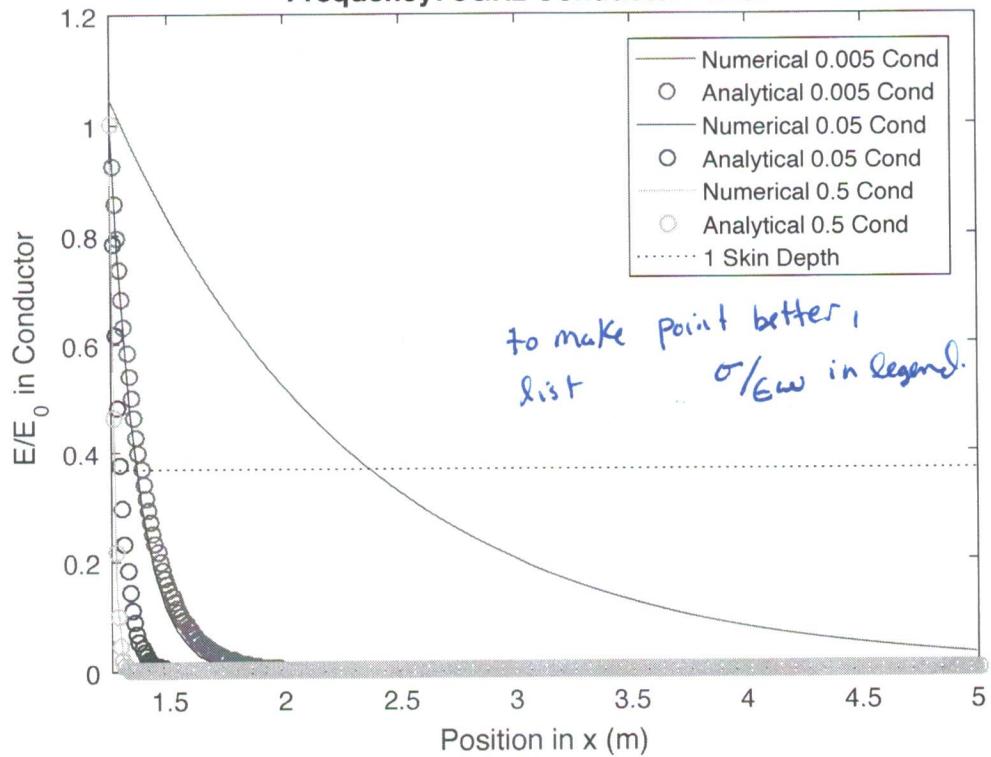


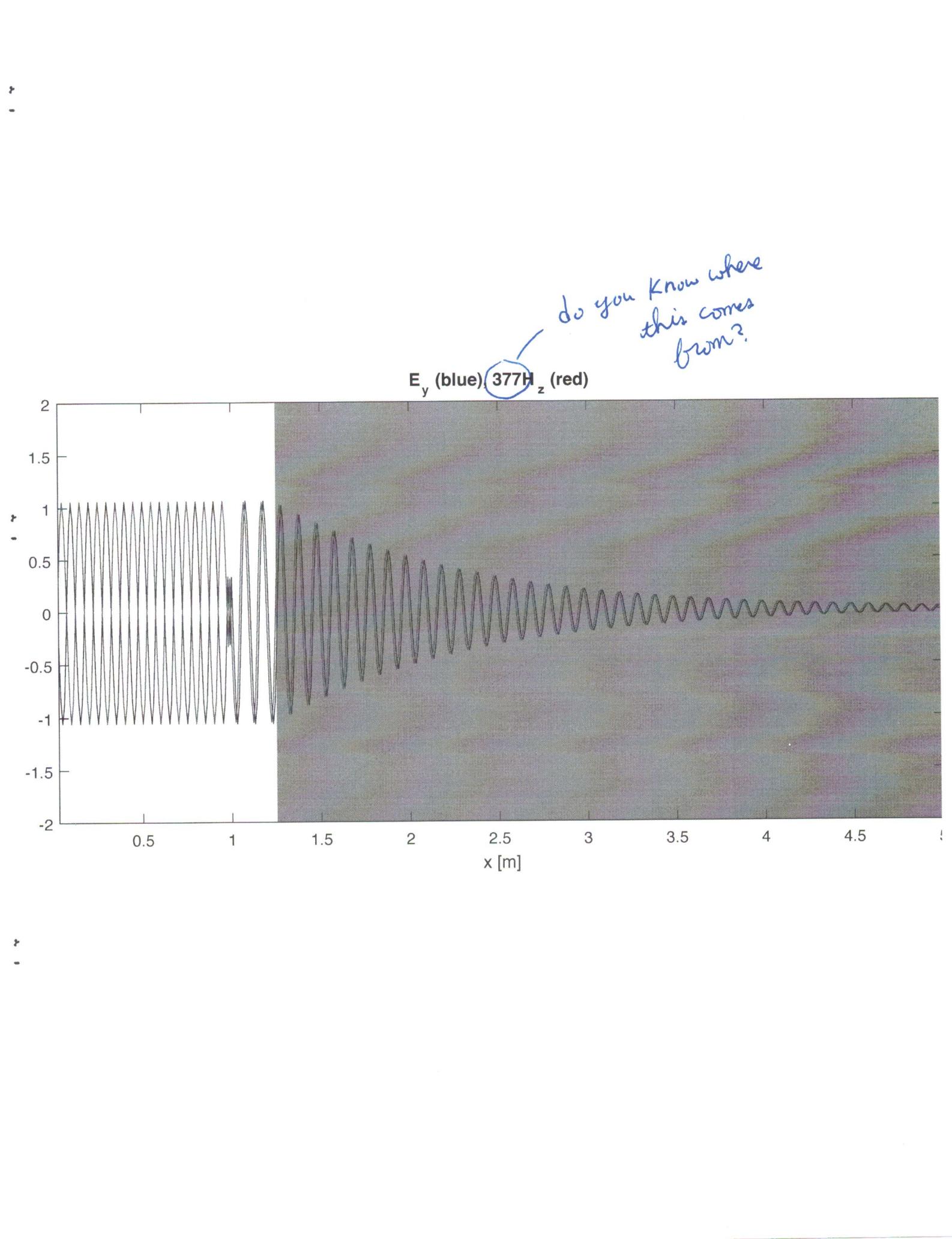


Plot of Max E field in Conductor
Sigma: 0.1 Conductor: 1.25m

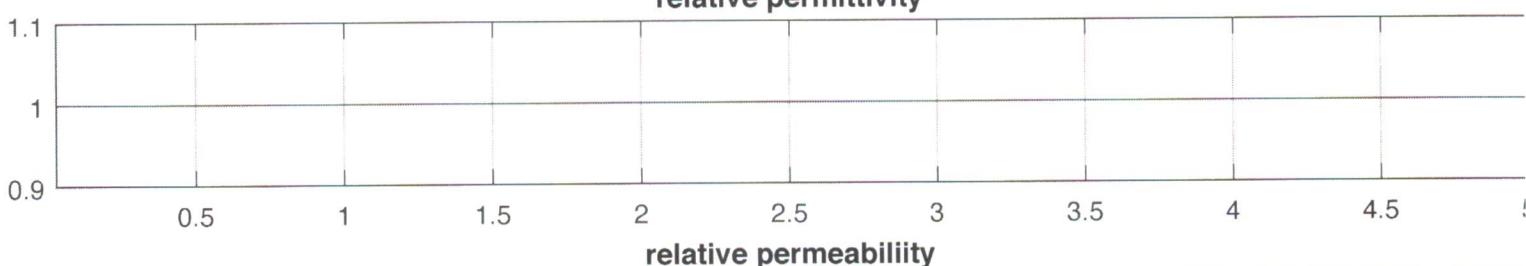


Plot of Max E field in Conductor
Frequency: 3GHz Conductor: 1.25m

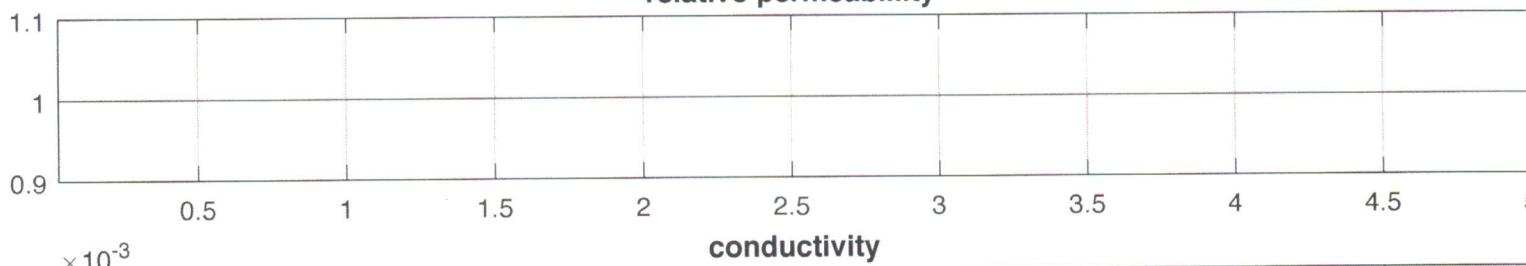




relative permittivity



relative permeability



conductivity

