

Understanding Sparse JL for Feature Hashing

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Dimensionality reduction (ℓ_2 -to- ℓ_2)

Informal goal: Project vectors in \mathbb{R}^n to \mathbb{R}^m (for $m \ll n$) with a linear map while “preserving geometry” (i.e. Euclidean norm distances).

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Many applications:

- ▶ Document classification tasks (Weinberger et al. '09, etc)
- ▶ Support Vector Machines (Paul et al. '14)
- ▶ k-means/k-medians (Makarychev, Makarychev, Razenshteyn '18)
- ▶ Nearest neighbors (Ailon, Chazelle '09, Har-Peled et al. '14, Wei '19)
- ▶ Numerical linear algebra (Clarkson and Woodruff '12, Nelson and Nguyen '14, etc.)

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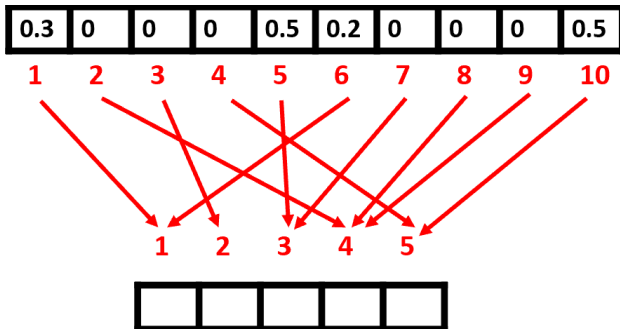
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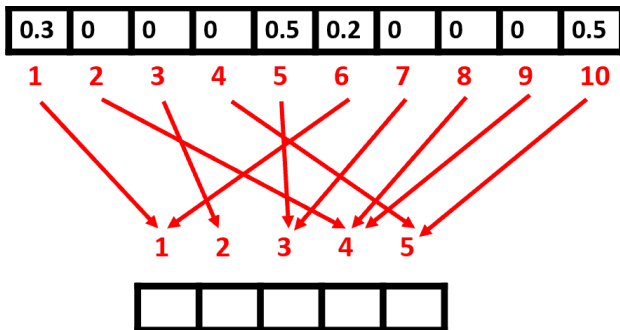
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But how should collisions be handled?

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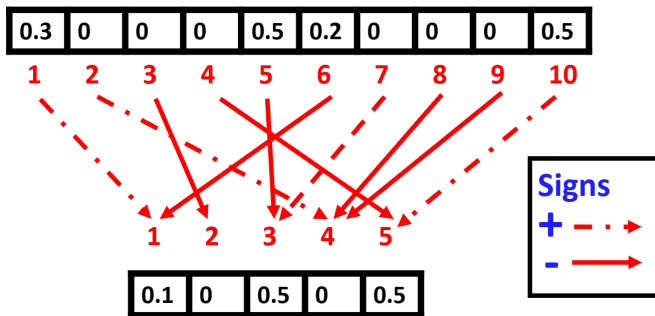
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Analysis of sparse JL on feature vectors in terms of s .

\implies *Sparse JL with ≥ 4 hash functions can have much better norm-preserving properties on feature vectors than feature hashing.*

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- ▶ Can apply to distances between vectors since f is linear.

Choosing s and m

Notation: ϵ is target error, δ is target failure probability.

Goal: $\mathbb{P}_{f \in \mathcal{F}}[(1 - \epsilon) \|x\|_2 \leq \|f(x)\|_2 \leq (1 + \epsilon) \|x\|_2] > 1 - \delta$.

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$m = O(\min(2\epsilon^{-2}/\delta, \epsilon^{-2} \log(1/\delta) e^{\Theta(\epsilon^{-1} \log(1/\delta)/s)}))$ (Cohen '16).

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Tight bounds on $\nu(m, \epsilon, \delta, s)$ for a general $s > 1$

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$$S_v = \{x \in \mathbb{R}^n \mid \|x\|_\infty \leq v \|x\|_2\},$$

$v(m, \epsilon, \delta, s) := \inf \text{ over } v \in [0, 1] \text{ s.t. } \ell_2\text{-norm goal is met on } x \in S_v.$

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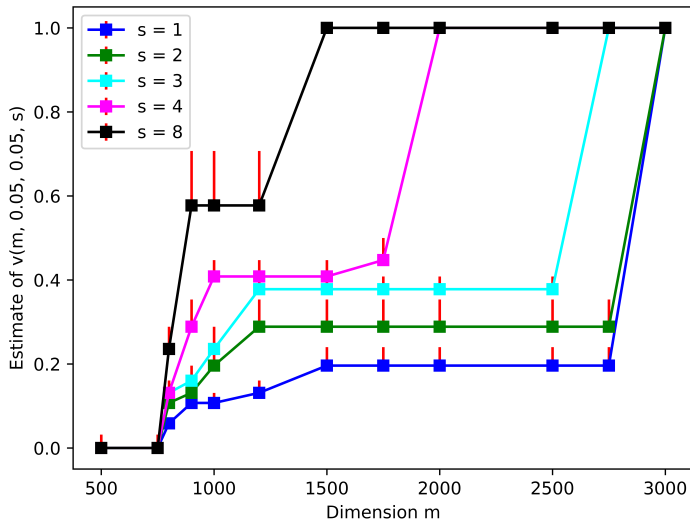
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\implies *Characterization of sparse JL performance in terms of ϵ , δ , and ℓ_∞ -to- ℓ_2 norm ratio for a general # of hash functions s*

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Under mild conditions, $v(m, \epsilon, \delta, s)$ is equal to $f'(m, \epsilon, \ln(1/\delta), s)$, where

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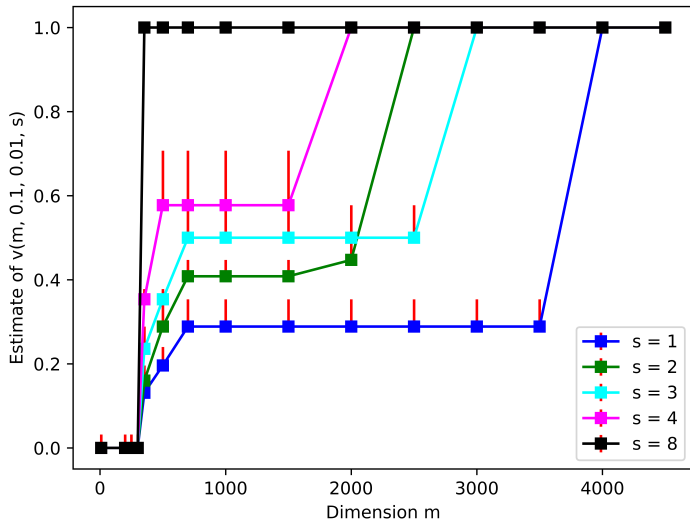
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$$f'(m, \epsilon, p, s) = \begin{cases} 1 & \text{High } m, \text{ full norm preservation} \\ \Theta \left(\sqrt{\epsilon s} \frac{\sqrt{\ln(\frac{m\epsilon^2}{p})}}{\sqrt{p}} \right) & \text{Medium } m, \text{ middle regime} \\ \Theta \left(\sqrt{\epsilon s} \min \left(\frac{\ln(\frac{m\epsilon}{p})}{p}, \frac{\sqrt{\ln(\frac{m\epsilon^2}{p})}}{\sqrt{p}} \right) \right) & \text{Medium } m, \text{ middle regime} \\ 0 & \text{Small } m, \text{ no norm preservation} \end{cases}$$

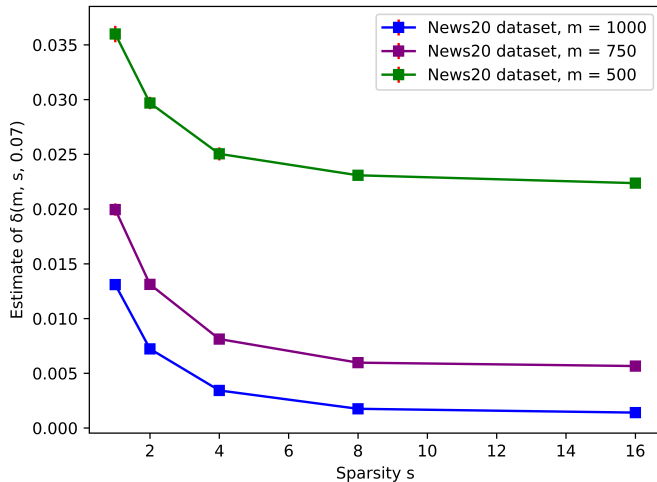
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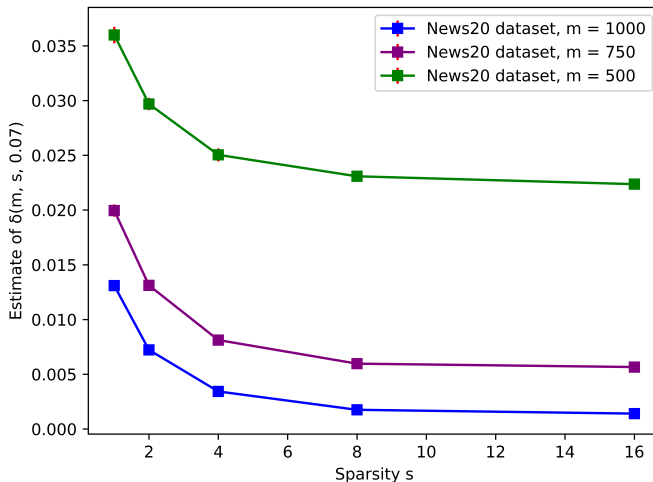


Sparse JL on News20 dataset

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Use sparse JL with more than one hash function!!

Sparse JL as a Sparse Random Projection (KN '12)

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(r, i) th coordinate is $\eta_{r,i}\sigma_{r,i}/\sqrt{s}$, where $\eta_{r,i} \in \{0, 1\}$, $\sigma_{r,i} \in \{-1, 1\}$

High-level approach of our analysis

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This random variable has been repeatedly analyzed in the literature.

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Need tight bounds on $\mathbb{E}[R(x_1, \dots, x_n)^p]$ on S_v at every threshold v .

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Issues with existing approaches:

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We use a non-combinatorial approach with Rademacher-specific bounds.

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Hope to see you at the poster session!!!