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definition

```
% d : desired signal
% N :length of filter
% M : length of input signal
% alpha : learning rate
% e : errors
% w : weights of filter
% p : power of input signal
% v : noise
% l : noise amplitude
% d_t : corrupted desired signal
a=1;
b=[1,1.8,0.81];
                         % impulse response
inputs=randn(1,100);
d=filter(b,a,inputs);
M=length(inputs);
```

part a

```
1 = 1;
alpha = 0.5;
N = 4;

v = randn(1,100);
d_t=d+1*v;

% calulate mu max for N=4
p= inputs*inputs'/M;
alpha_max=2/(3*N*p);
disp('mu max for N=4 and is :');
disp(alpha_max);

% N=4 and mu=0.5
```

```
disp('because mu is begger than u_max may be LMS algorithm not converged')
[w,~]=LMS(inputs,d t,N,alpha,M);
disp("weights for mu=0.5, N=4 and l=1 :");
disp(w');
N=5 and u=0.5
N=5;
% calulate mu max for N=5
alpha_max=2/(3*N*p);
disp('mu max for N=5 and is :');
disp(alpha_max);
disp('because mu is begger than u_max may be LMS algorithm not converged')
[w,~]=LMS(inputs,d_t,N,alpha,M);
disp("weights for mu=0.5, N=5 and l=1:");
disp(w');
mu max for N=4 and is :
    0.1530
```

because mu is begger than u_max may be LMS algorithm not converged

part b

```
1 = 0.1;
N = 4;
v = randn(1,100);
d t=d+l*v;
% calulate mu max for N=4
 alpha_max=2/(3*N*p);
disp('mu max for N=4 and is :');
disp(alpha max);
% M=4 \text{ and } mu=0.5 \text{ and } l=0.1
disp('because mu is begger than u_max may be LMS algorithm not converged')
[w,~]=LMS(inputs,d_t,N,alpha,M);
disp("weights for mu=0.5 , N=4 and l=0.1 :");
disp(w');
N=5 and u=0.5 l=0.1
N=5;
% calulate mu max for N=4
alpha \max=2/(3*N*p);
disp('mu max for N=5 and is :');
disp(alpha max);
disp('because mu is begger than u_max may be LMS algorithm not converged')
[w,~]=LMS(inputs,d_t,N,alpha,M);
disp("weights for mu=0.5, N=5 and l=0.1:");
disp(w');
```

```
disp('if mu smaller than mu_max in the best practice noise of desired signal
  not eliminate and if noise amplitude is lower, the output of system is more
  accurate ')
mu max for N=4 and is:
     0.1530

because mu is begger than u_max may be LMS algorithm not converged
```

LMS algorithms

```
function[w,cost,J_min,J_inf]=LMS(inputs,d,N,alpha,M)
% e : error
% u_temp : because LMS run when the first sample arrive, we put M-1 zeros in
beging of inputs, if whe don't put this zeros we must wait to m sample arrive
   u_temp=[zeros(1,N-1),inputs];
    e=zeros(1,M);
   w=zeros(1,N);
    for i=N:M
        u=u_temp(i:-1:i-N+1);
       y=dot(w,u);
        e(i-N+1)=d(i-N+1)-y;
        w = w + alpha*e(i-N+1)*u;
    end
    cost=e.^2;
    J min=min(cost);
    J_{inf=sum(cost(M-19:M))/20;}
end
weights for mu=0.5 , N=4 and l=1 :
   1.0e+03 *
  -1.8307
   0.2614
    0.2503
   -1.7754
mu max for N=5 and is:
    0.1224
because mu is begger than u_max may be LMS algorithm not converged
weights for mu=0.5 , N=5 and l=1 :
   1.0e+04 *
   -3.5558
   1.3391
    3.7414
    2.3906
   -7.0320
```

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