Table of Contents

definitiondefinition	
part a	1
part b	2
part b	2
clc;	
clear;	
close all;	

Mohammd Javad Amin 401211193 Problem 1, exercise 2

definition

```
% d : desired signal
% N :length of filter
% M : length of input signal
% alpha : mu tilde
% e : errors
% w : weights of filter
% p : power of input signal
% v : noise
% 1 : noise amplitude
% d_t : corrupted desired signal
a=1;
b=[1,1.8,0.81];
                        % impulse response
inputs=randn(1,100);
d=filter(b,a,inputs);
M=length(inputs);
```

part a

```
l = 1;
alpha = 0.5;
N = 4;

v = randn(1,100);
d_t=d+l*v;

% N=4 and mu mu tilde=0.5

[w,~]=NLMS(inputs,d_t,N,alpha,M);
disp("weights for mu tilde=0.5 , N=4 and l=1 :");
disp(w');

%N=5 and mu tilde = 0.5
```

```
N=5;
[w,~]=NLMS(inputs,d_t,N,alpha,M);
disp("weights for mu tilde=0.5, N=5 and l=1:");
disp(w');
disp("if the algorithm not converged must increase the tap of filter ")
part b
1 = 0.1;
N = 4;
v = randn(1,100);
d t=d+l*v;
% M=4 and mu tilde=0.5 and l=0.1
[w,~]=NLMS(inputs,d_t,N,alpha,M);
disp("weights for mu tilde=0.5, N=4 and l=0.1 :");
disp(w');
N=5 and mu tilde = 0.5 l=0.1
N=5;
[w,~]=NLMS(inputs,d_t,N,alpha,M);
disp("weights for mu tilde=0.5 , N=5 and l=0.1 :");
disp(w');
disp('in the best practice noise of desired signal not eliminate and if noise
 amplitude is lower, the output of system is more accurate ')
NLMS algorithms
function[w,cost,J_min,J_inf]=NLMS(inputs,d,N,alpha,M)
% e : error
% u_temp : because LMS run when the first sample arrive, we put M-1 zeros in
beging of inputs, if whe don't put this zeros we must wait to m sample arrive
    u_temp=[zeros(1,N-1),inputs];
    e=zeros(1,M);
    w=zeros(1,N);
    for i=N:M
        u=u_temp(i:-1:i-N+1);
        y=dot(w,u);
        e(i-N+1)=d(i-N+1)-y;
        w = w + (alpha/(norm(u)^2))*e(i-N+1)*u;
    end
    cost=e.^2;
    J min=min(cost);
    J_{inf=sum(cost(M-19:M))/20;}
end
```

weights for mu tilde=0.5 , N=4 and l=1 :

```
1.4207

1.6784

1.0633

0.0398

weights for mu tilde=0.5 , N=5 and l=1 :

1.3041

1.5875

1.1443

-0.0190

0.0834

if the algorithm not converged must increase the tap of filter
```

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