

- Revisit Basic Example

$$P(A_i|B) = \frac{P(B|A_i)P(A_i)}{P(B)}$$

- Suppose there are events A_1, A_2, \dots, A_N that could occur

• note that $P(B)$ is

(updated 3/21)

$$P(B) = P(B|A_1)P(A_1) + P(B|A_2)P(A_2) + \dots + P(B|A_N)P(A_N)$$

$$\Rightarrow P(B) = \sum_{i=1}^N P(B|A_i)P(A_i)$$

$$P(B) = \int_{\Omega} P(B|A_i)P(A_i) dA_i$$

- So let $P(\theta) \equiv \pi_y(\vec{y})$

$$\pi(\vec{\theta}|\vec{y}) = \frac{P(\vec{y}|\vec{\theta}) \cdot \pi_0(\vec{\theta})}{\pi_y(\vec{y})}$$

E.g. if each θ_i 's
is independent

$$\Rightarrow \pi_0(\vec{\theta}) = \prod_{i=1}^P \pi_0(\theta_i)$$

using definition above

\Rightarrow

$$\pi(\vec{\theta}|\vec{y}) = \frac{P(\vec{y}|\vec{\theta}) \cdot \pi_0(\vec{\theta})}{\int_{\Omega} P(\vec{y}|\vec{\theta}) \cdot \pi_0(\vec{\theta}) d\vec{\theta}}$$

* These terms
are evaluated
for each $\vec{\theta}$ value

$$\theta \sim \mathcal{U}(a,b)$$

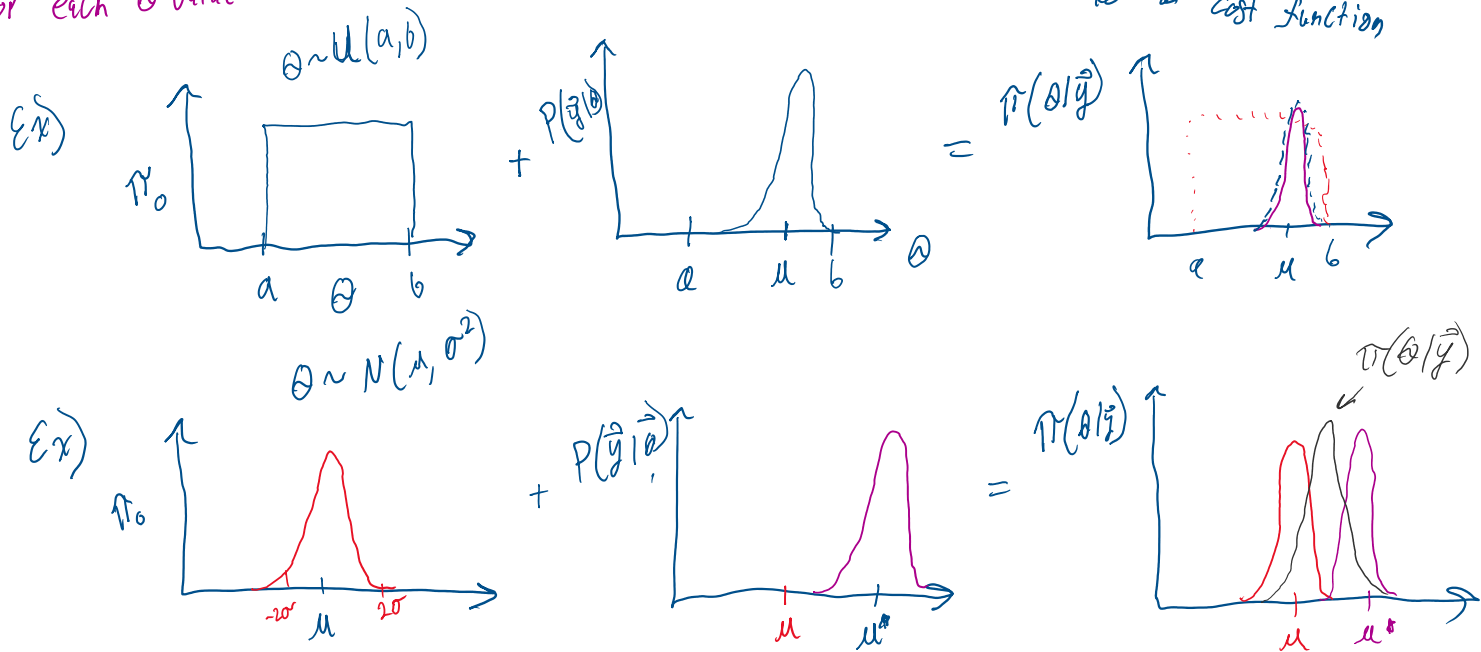
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$P(\vec{y}|\vec{\theta}) \equiv$ likelihood similar
to a cost function

is deterministic
& fixed

for each θ value

to a cost function



The likelihood


- The likelihood tells us how likely our observations are conditioned on our model, $f(x; \vec{\theta})$, + value $\vec{\theta}$ are currently.

- So if $\epsilon_i \sim N(0, \sigma_\epsilon^2)$

$$\Rightarrow P(\vec{y}|\vec{\theta}) = \frac{1}{(2\pi\sigma_\epsilon^2)^{N_f/2}} \exp\left(-\frac{1}{2\sigma_\epsilon^2} \sum_{i=1}^{N_f} (y_i - f(x_i; \vec{\theta}))^2\right)$$

where $i=1, \dots, N_f$ is number of observations.

How to get $\int_{\Omega} P(\vec{y}|\vec{\theta}) \pi_0(\vec{\theta}) d\vec{\theta}$?

- Quadrature 
- Markov chain Monte Carlo (MCMC)