

Metropolis's with error Variance

- So far we have assumed

$$\bar{y} = f(\bar{x}; \bar{\theta}) + \bar{\epsilon}, \quad \bar{\epsilon} \sim N(0, \sigma_{\epsilon}^2)$$

where σ_{ϵ}^2 is i) known or ii) estimated.

- We typically set $\sigma_{\epsilon}^2 = \frac{1}{N_y - P} \sum_{i=1}^{N_y} (y_i - f(x_i; \bar{\theta}^0))^2$

- However, we can also infer σ_{ϵ}^2 using a conjugate prior + MCMC

- If we assume $\epsilon_i \sim N(0, \sigma_{\epsilon}^2)$ for our likelihood, then we can assume σ_{ϵ}^2 has an inverse-gamma prior

$$\pi_0(\sigma_{\epsilon}^2) \propto (\sigma_{\epsilon}^2)^{-(\alpha+1)} \cdot \exp\left(-\beta/\sigma_{\epsilon}^2\right) \sim \text{inv gamma}(\alpha, \beta)$$

- Because $\pi_0(\sigma_{\epsilon}^2)$ is a conjugate prior,

$$\pi(\sigma_{\epsilon}^2 | \bar{\theta}, \bar{y}) \propto (\sigma_{\epsilon}^2)^{-(\alpha + 1 + N_y/2)} \exp\left(-\frac{\beta + SS(\bar{\theta})/2}{\sigma_{\epsilon}^2}\right)$$

$$\Rightarrow \pi(\sigma_{\epsilon}^2 | \bar{\theta}, \bar{y}) \sim \text{inv. gamma}\left(\alpha + \frac{N_y}{2}, \beta + \frac{SS(\bar{\theta})}{2}\right)$$

Metropolis-Hastings (MH)

- The MH algorithm extends the metropolis algorithm beyond symmetric proposals, $J(\bar{\theta}^* | \bar{\theta}^{t-1})$.

- Idea: we need to account for $J(\bar{\theta}^* | \bar{\theta}^{t-1})$ explicitly in acceptance

- Idea: We need to account for ...

$$r_{MH} = \left(\frac{\pi(\vec{\theta}^* | \vec{y})}{\mathcal{J}(\vec{\theta}^* | \vec{\theta}^{k-1})} \right) / \left(\frac{\pi(\vec{\theta}^{k-1} | \vec{y})}{\mathcal{J}(\vec{\theta}^{k-1} | \vec{\theta}^*)} \right)$$

$$= \frac{p(\vec{y} | \vec{\theta}^*) \pi_0(\vec{\theta}^*) \mathcal{J}(\vec{\theta}^{k-1} | \vec{\theta}^*)}{p(\vec{y} | \vec{\theta}^{k-1}) \pi_0(\vec{\theta}^{k-1}) \mathcal{J}(\vec{\theta}^* | \vec{\theta}^{k-1})}$$

Note: If \mathcal{J} is symmetric (think Gaussian)

$$\mathcal{J}(\vec{\theta}^* | \vec{\theta}^{k-1}) \propto \exp\left(-\frac{1}{2}(\vec{\theta}^* - \vec{\theta}^{k-1})^T \underline{V}^{-1}(\vec{\theta}^* - \vec{\theta}^{k-1})\right)$$

$$= \mathcal{J}(\vec{\theta}^{k-1} | \vec{\theta}^*) \propto \exp\left(-\frac{1}{2}(\vec{\theta}^{k-1} - \vec{\theta}^*)^T \underline{V}^{-1}(\vec{\theta}^{k-1} - \vec{\theta}^*)\right)$$

Stationarity

- Why does the chain converge to $\pi(\vec{\theta} | \vec{y})$?

i) Does the algorithm satisfy detailed balance?

- Note:

- a chain with transition \underline{P} + distribution $\tilde{\pi}$ is reversible if

$$\pi_i P_{ij} = \pi_j P_{ji}, \quad \forall x_i, x_j \in S$$

+ Satisfies detailed balance.

- Detailed Balance \Rightarrow Stationary distribution, $\tilde{\pi}$.

- Let our stationary distribution be $\pi(\vec{\theta} | \vec{y})$.

. Recall that the acceptance criteria for a symmetric proposal, $\mathcal{J}(\vec{\theta}^* | \vec{\theta}^{k-1})$

- Let θ^*

- Recall that the acceptance criteria for a symmetric proposal, $J(\theta^* | \theta^{2,1})$ is given by

$$p(\theta^*, \theta^{2,1}) = \min \left(\frac{\pi(\theta^* | \vec{y})}{\pi(\theta^{2,1} | \vec{y})}, 1 \right) = \min \left(\frac{p(\vec{y} | \theta^*) \pi_0(\theta^*)}{p(\vec{y} | \theta^{2,1}) \pi_0(\theta^{2,1})}, 1 \right)$$

- using this, the transition probability is

$$P_{\theta, \theta^{2,1}} = \begin{cases} p(\theta^*, \theta^{2,1}) J(\theta^* | \theta^{2,1}), & \theta^* \neq \theta^{2,1} \\ 1 - p(\theta^*, \theta^{2,1}) J(\theta^* | \theta^{2,1}), & \theta^* = \theta^{2,1} \end{cases}$$