

■ mark@mjedmonds.com | 🛪 www.mjedmonds.com | 🖸 mjedmonds | 🛅 mjedmonds

Education _

University of California, Los Angeles

Los Angeles, CA

Ph.D. in Computer Science, Artifical Intelligence Concentration; Advisor: Prof. Song-Chun Zhu

Sep 2017 - Present

University of California, Los Angeles

Los Angeles, CA

M.S. in Computer Science; Thesis Advisor: Prof. Song-Chun Zhu

Sep 2015 - Jun 2017

University of Dayton

Dayton, OH

B.S. in Computer Engineering; Magna Cum Laude; Thesis Advisor: Prof. Tarek Taha

Aug 2011 - May 2015

Research Interests

Causality Causal model induction through simulation and exploration

Reinforcement Learning Transfer learning and domain adaptation

Robotics Learning from demonstration and transfer learning

Journal Publications _

[1] Mark Edmonds, Tanvir Atahary, Scott Douglass, Tarek Taha

"Hardware Accelerated Semantic Declarative Memory Systems through CUDA and MapReduce," TPDS 2018

Conference Publications _

[6] M. Edmonds*, J. Kubricht*, Colin Summers, Y. Zhu, B. Rothrock, S.C. Zhu, H. Lu "Human Causal Transfer: Challenges for Deep Reinforcement Learning," CogSci 2018 Oral Pres.

[5] X. Xie*, H. Liu*, M. Edmonds, F. Gao, S. Qi, Y. Zhu, B. Rothrock, S.C. Zhu

"Unsupervised Learning of Hierarchical Models for Hand-Object Interactions," ICRA 2018

[4] M. Edmonds*, F. Gao*, X. Xie, H. Liu, S. Qi, Y. Zhu, B. Rothrock, & S.C. Zhu

Oral Pres.

"Feeling the Force: Integrating Force and Pose for Fluent Discovery through Imitation Learning to Open Medicine Bottles," IROS 2017

[3] H. Liu*, X. Xie*, M. Millar*, M. Edmonds, F. Gao, Y. Zhu, V. Santos, B. Rothrock, & S.C. Zhu

Oral Pres.

[2] M. Edmonds, T. Atahary, T. Taha, & S. Douglass

"High Performance Declarative Memory Systems through MapReduce," SNPD 2015

[1] D. Prince, M. Edmonds, A. Sutter, M. Cusumano, W. Lu, & V. Asari

"Brain Machine Interface using Emotiv EPOC to control Robai Cyton Robotic Arm," NAECON 2015

"A Glove-based System for Studying Hand-Object Manipulation via Pose and Force Sensing," IROS 2017

(* indicates equal contribution)

Research ___

Causal Transfer Learning

Los Angeles, CA

Graduate Student Researcher; Center for Vision, Cognition, Learning, and Autonomy (VCLA)

Sep 2017 – Present

- Examining how causal knowledge can be incorporated into reinforcement learning to enable better knowledge transfer across task and environment domains.
- Studied how humans perform in causal transfer tasks and compared performance against state-of-the-art reinforcement learning algorithms.

Imitation Learning using Tactile Feedback

Los Angeles, CA

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Graduate Student Researcher; Center for Vision, Cognition, Learning, and Autonomy (VCLA)

Sep 2015 - Sep 2017

- · Transferred visually latent causal changes from a human demonstrator to a robot using a tactile glove and an And-Or graph through autoencoders and neural networks.
- · The manipulation policy uses the And-Or graph to encode long-term temporal constraints and uses haptic feedback to incorporate real-time sensor data.
- · Deployed robot localization on a ROS-based Baxter robot combining SLAM (using RGB-D and LIDAR), wheel odometry, and IMU data through Kalman filtering.

Declarative Memory Acceleration

Dayton, OH

Undergraduate Researcher; Air Force Research Lab (AFRL)

May 2014 - Sep 2015

- Accelerated the declarative memory module of AFRL's CECEP cognitive architecture (based on ACT-R).
- The research focused on leveraging the parallelization of CUDA, yielding a 100x speedup over the fastest existing
 implementation. Utilized CUDA, thread pools, ontology parsers, and IPC.

Experience _____

Santa Monica College Santa Monica, CA

Adjunct Professor, Computer Science Department

Jun 2016 - Present

- CS 80, Internet Programming, a class focused on HTML, CSS, JavaScript, MySQL, and PHP.
- CS 50, Introduction to C Programming, a class focused on C fundamentals.
- CS 52, Introduction to C++ Programming, a class focused on C++ fundamentals.

Garmin International Olathe, KS

Software Engineering Intern, Aviation Department

May 2013 - Aug 2013

• Reduced testing time by 40% for the Datalink team, saving hundreds of vendor-certification testing time hours.

Cristo Rey Kansas City High School

Kansas City, MO

Teacher and Tutor May 2011 - Aug 2012

• Pre-calculus and chemistry tutor and teacher at an inner city high school.

Skills _____

Programming Python, C/C++, Shell, LaTeX, Matlab, Javascript, HTML5, CSS, Node.JS, Java, CUDA

Topics Machine Learning, Graphical Models, Reinforcement Learning, Bayesian Networks, Statistical Modeling

Teaching Introduction to C, Introduction to C++, Internet Programming

Honors & Awards_

2017	NSF Doctoral Consortium, IROS 2017	Vancouver, CA
2015	The Anthony Horvath and Elmer Steger Award of Excellence, University of Dayton	Dayton, OH
2014	Eta Kappa Nu IEEE Honor Society, Member	Dayton, OH
2014	Tau Beta Pi Engineering Honor Society, Member	Dayton, OH
2011	Eagle Scout, Boy Scouts of America	Kansas City, KS

Invited Talks

ONR MURI Meeting

RSS Causal Imitation Workshop

Causal Transfer: Challenges for Causal Learning and Reinforcement Learning White Mountain, NH

Sep 2018

Human Causal Transfer: Challenges for Deep Reinforcement Learning

Madison, WI

CogSci Oral Presentation Jul 2018

Causal Imitation: The Necessity of Integrating Observations and Interventions

Jun 2018

Pittsburgh, PA

Feeling the Force: Integrating Force and Pose for Imitation Learning

Mountain View, CA

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CoRL Lightning Talk

Nov 2017

Feeling the Force: Integrating Force and Pose for Imitation Learning Los Angeles, CA

ONR MURI Meeting Aug 2017