

yes, but see wikipedia  
 "Image Moments"  
 I look for the  
 bit about eigenvectors  
 and orientation

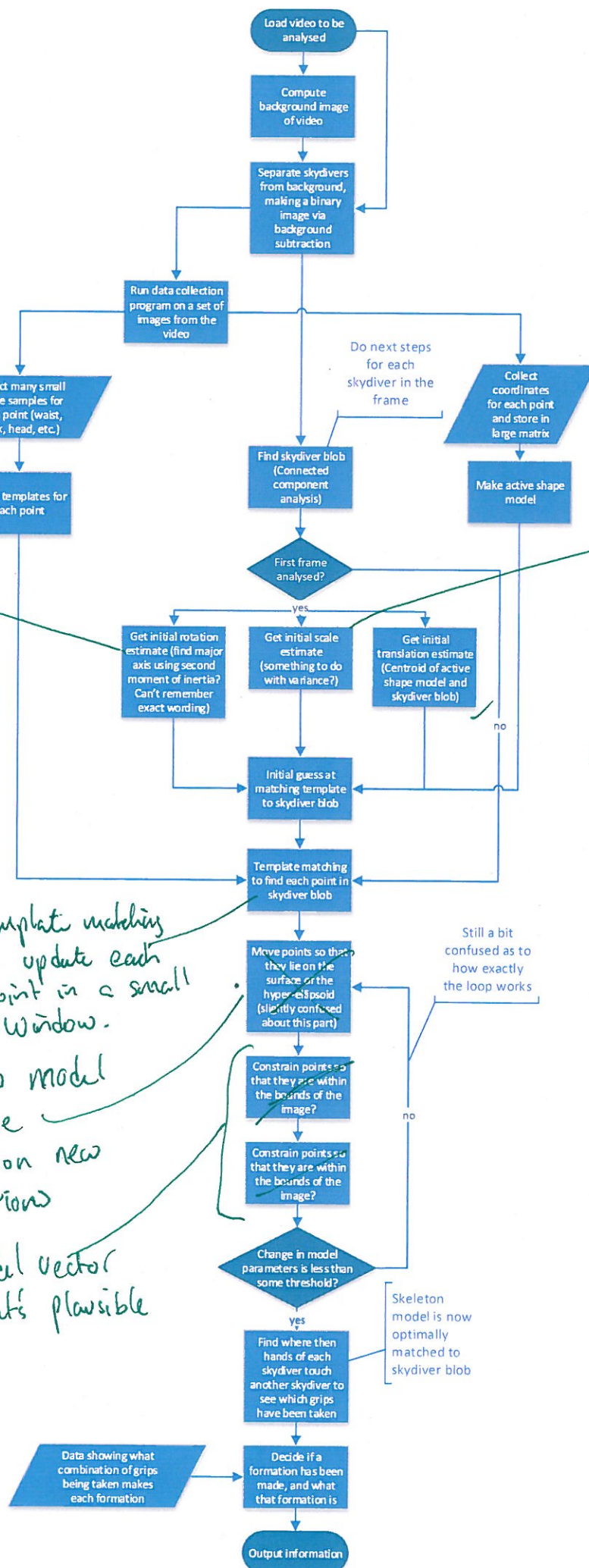
"intrinsic scale"  
 is the RMS  
 distance of all  
 points from the  
 Centroid -

The ratio of intrinsic  
 scale of the  
 model to the  
 connected component  
 will give the  
 relevant scale  
 factor.

template matching  
 to update each  
 point in a small  
 window.

Compute new model  
 Vector & pose  
 Matrix based on new  
 point positions

Constrain model vector  
 by ensuring it's plausible



Still a bit  
 confused as to  
 how exactly  
 the loop works

Skeleton  
 model is now  
 optimally  
 matched to  
 skydiver blob