



# Time reverse imaging of tsunami waveforms

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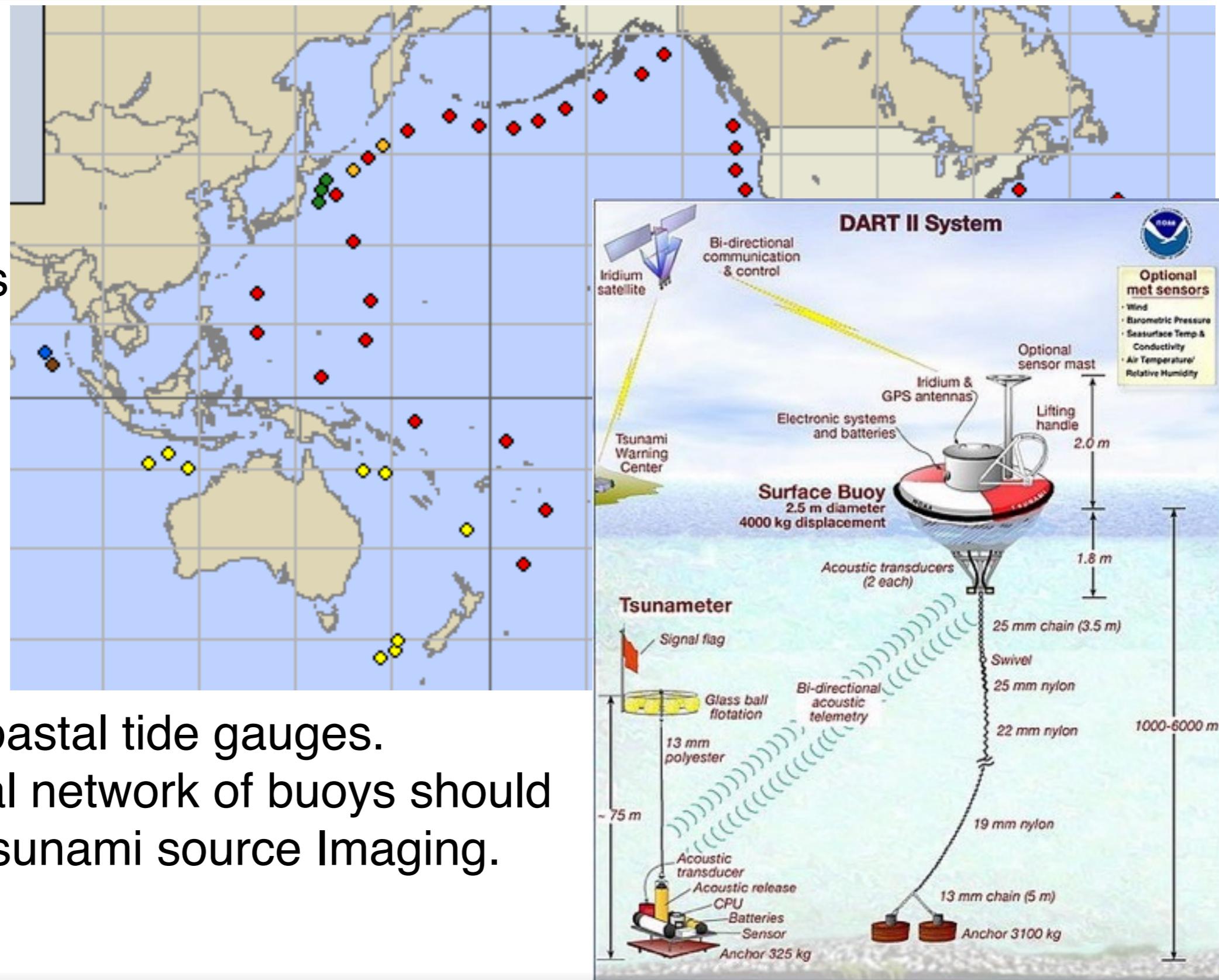
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Canberra ACT Australia

(Collaborators: Toshitaka Baba, Sebastian Allgeyer)

ASA Spring Meeting  
24 May 2016

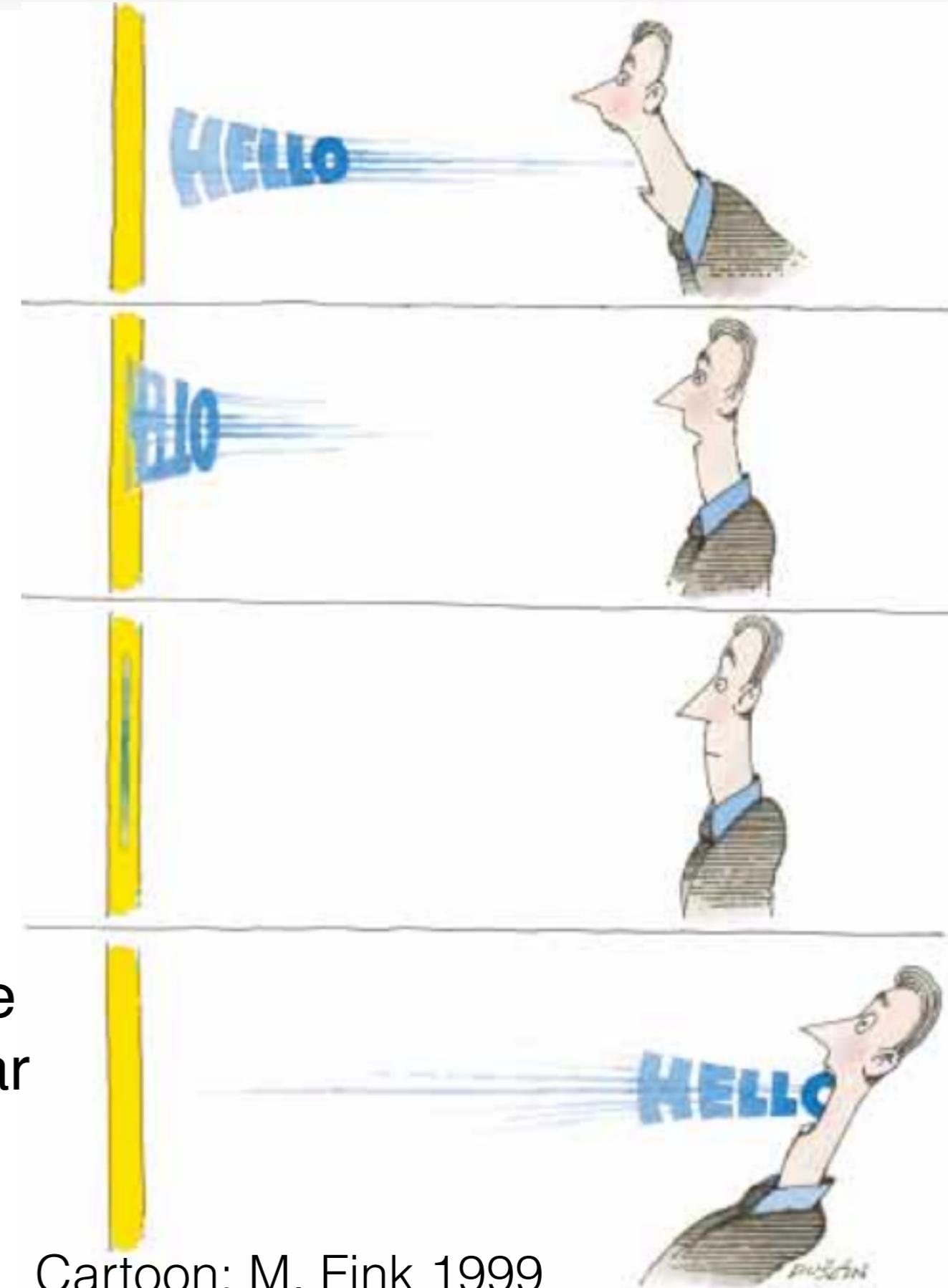
# New Frontiers in Tsunami Observation: Global DART Buoy Network & Friends

- Like hard-rock seismometers, deep-ocean tsunami measurements suffer only benign path effect
- They give much clearer picture of the tsunami source than coastal tide gauges.
- The new global network of buoys should revolutionize tsunami source Imaging.



# Time reverse imaging (TRI) can reproduce source

- Common in acoustics, medical science, material science... (long distance communication, destruction of tumours & kidney stones, detection of material defects)
- Basis: **The physical processes underlying wave propagation are unchanged if time is reversed**
- Time-reversed signal: Refocuses @ location of original source regardless of the complexity of the propagation medium, with a similar shape (depending number of sensors)



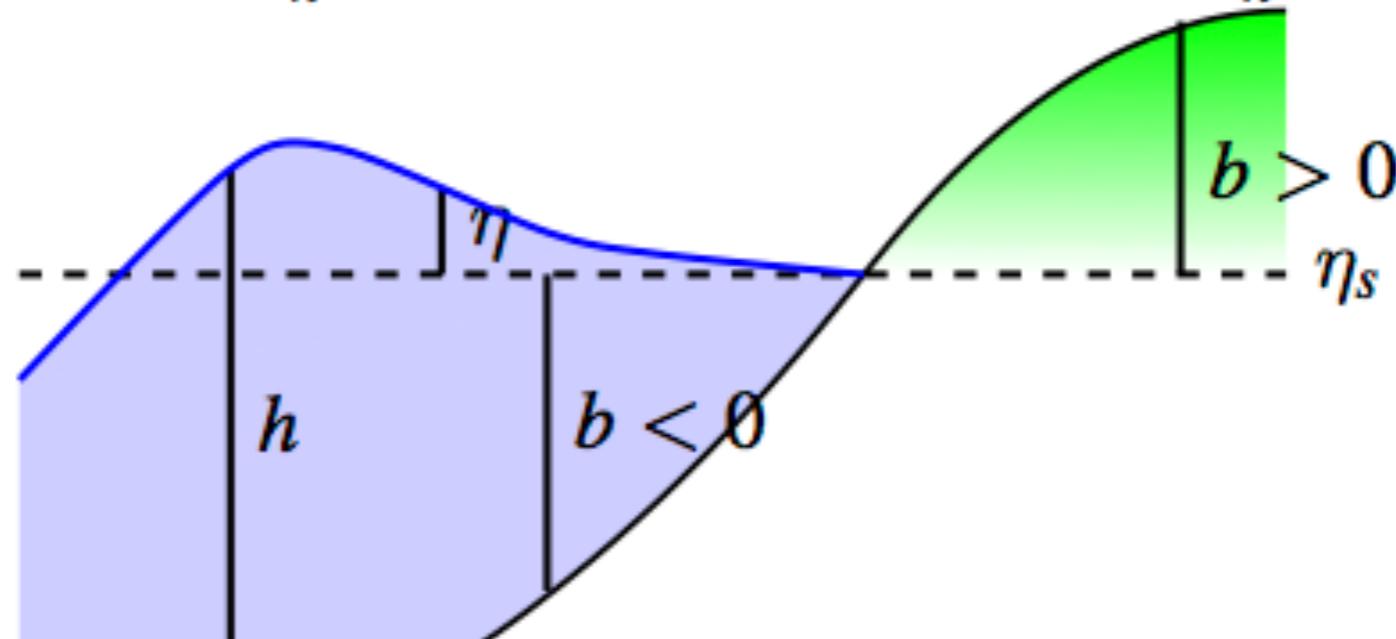
# Tsunami propagation: Shallow water wave equations

- All terms involving t, u, v change sign under time reversal
- Equations are invariant if the **bed friction** terms ( $D$ ) are dropped

$$\frac{\partial h}{\partial t} + \frac{\partial(hu)}{\partial x} + \frac{\partial(hv)}{\partial y} = 0$$
$$\frac{\partial(hu)}{\partial t} + \frac{\partial}{\partial x}(u^2h + \frac{1}{2}gh^2) + \frac{\partial(huv)}{\partial y} = -gh\frac{\partial b}{\partial x} - ghD_x$$
$$\frac{\partial(hv)}{\partial t} + \frac{\partial(huv)}{\partial x} + \frac{\partial(v^2h + \frac{1}{2}gh^2)}{\partial y} = -gh\frac{\partial b}{\partial y} - ghD_y$$

where  $b(x, y)$  is the bed elevation and  $D$  is the bed friction.

$$D_x = \frac{u\zeta^2\sqrt{u^2+v^2}}{h^{8/3}}$$
 and 
$$D_y = \frac{v\zeta^2\sqrt{u^2+v^2}}{h^{8/3}}$$

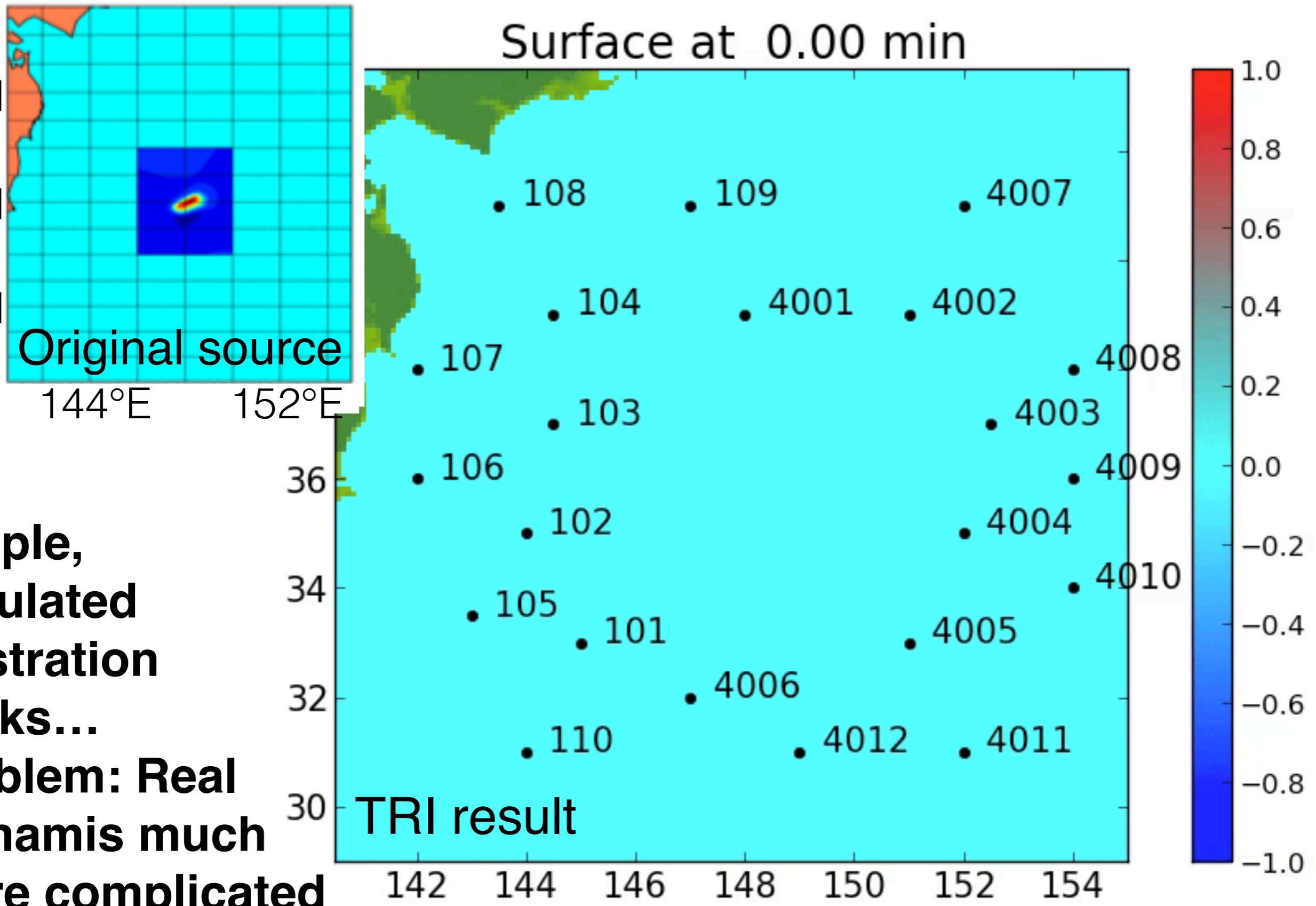


Details: Hossen et al. Pure & Applied Geophysics (2015)

# Tsunami TRI: Simulation with encouraging results

**Simple,  
simulated  
illustration  
works...**

**Problem: Real  
tsunamis much  
more complicated**



# Tsunami TRI: Simulation with encouraging results

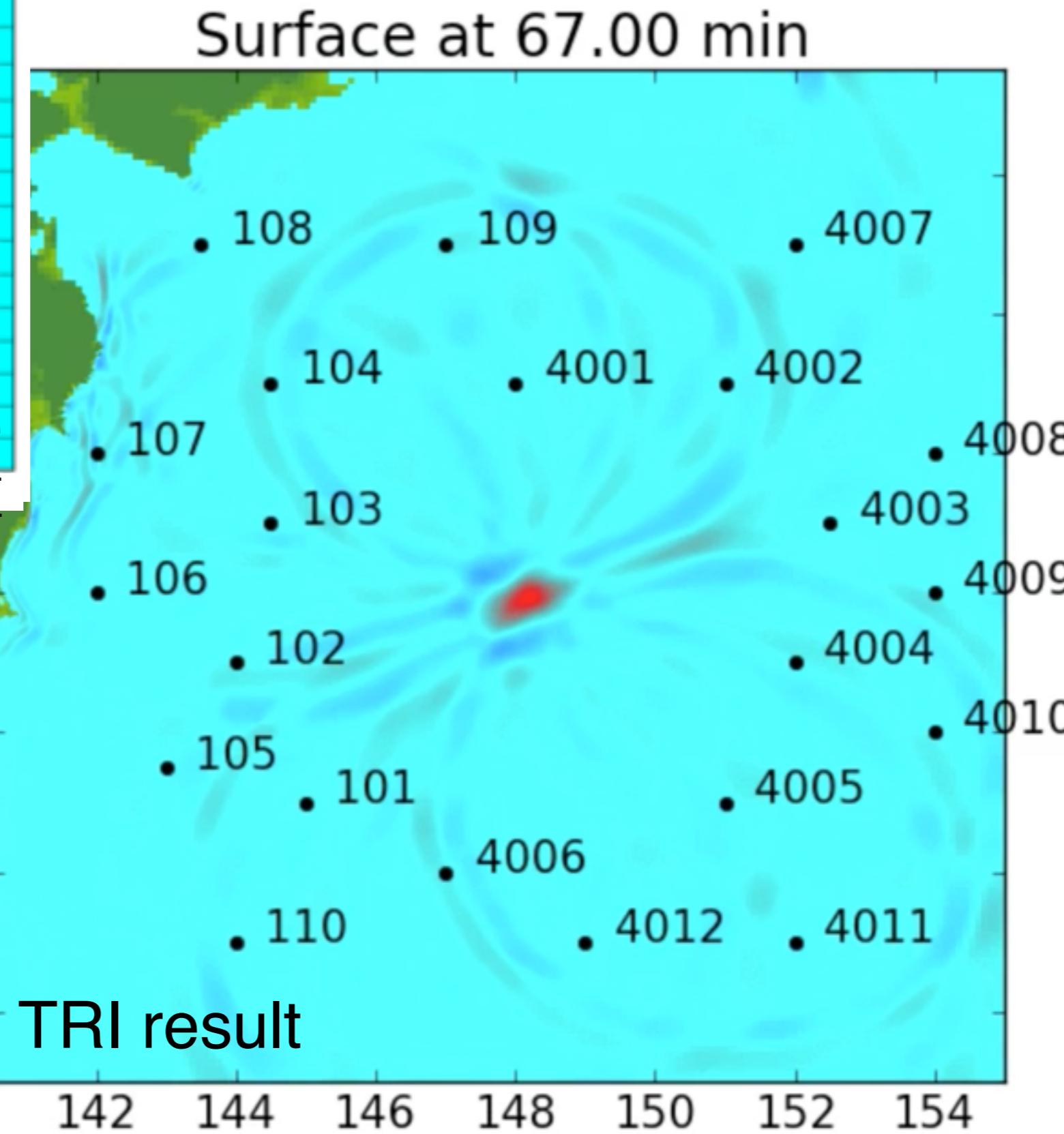
40°N  
36°N  
32°N

Original source

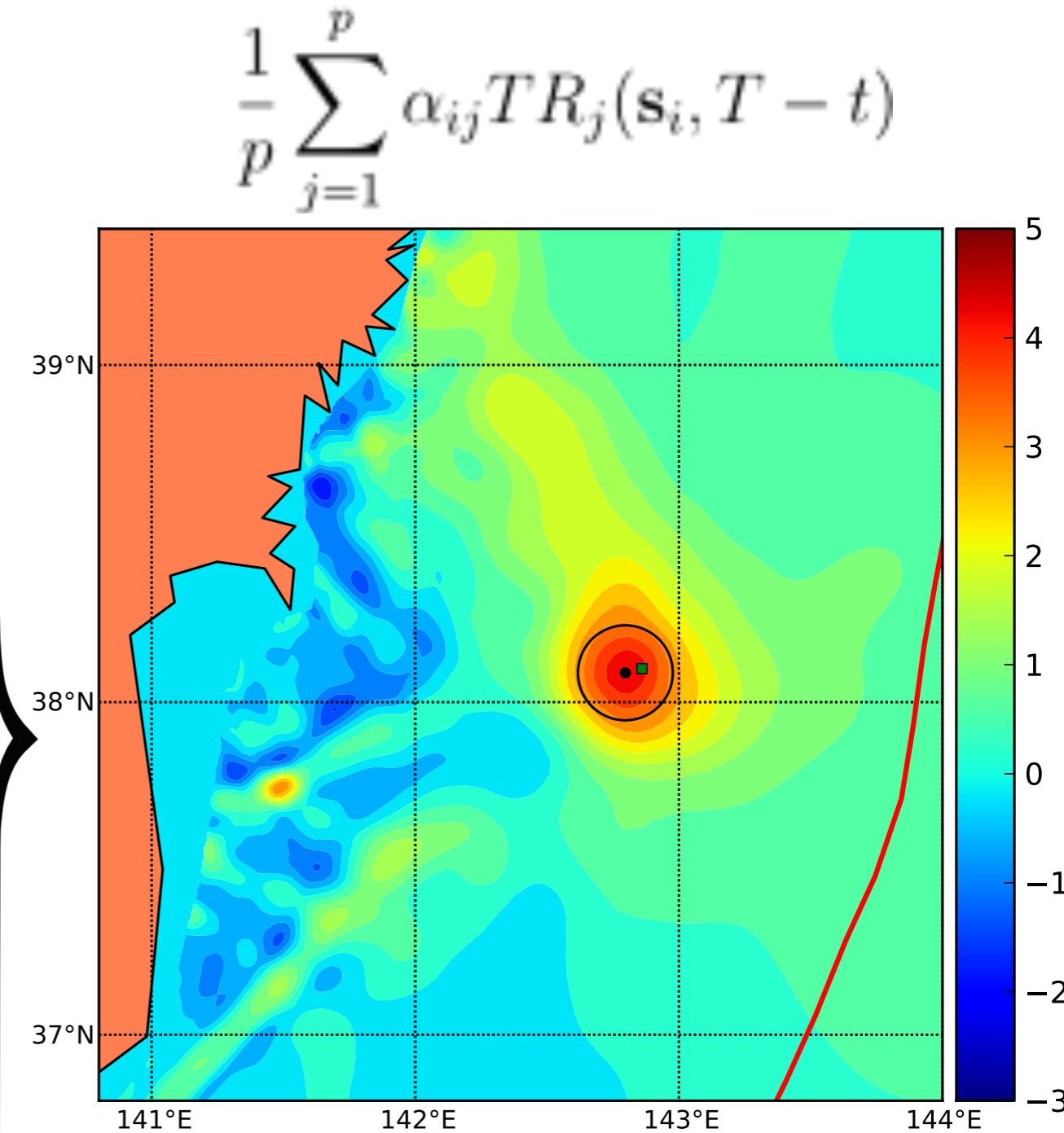
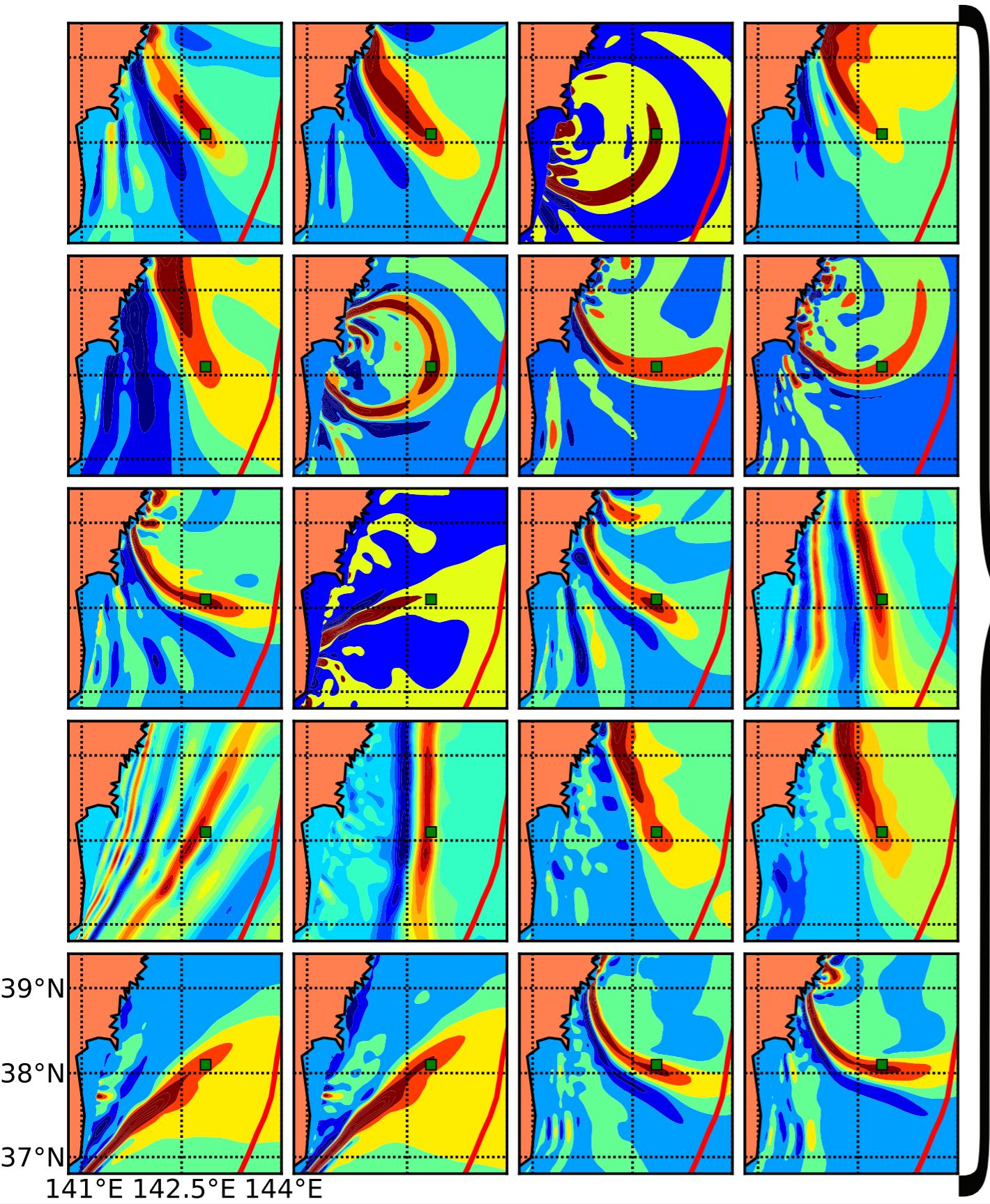
144°E 152°E

**Simple,  
simulated  
illustration  
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**Problem: Real  
tsunamis much  
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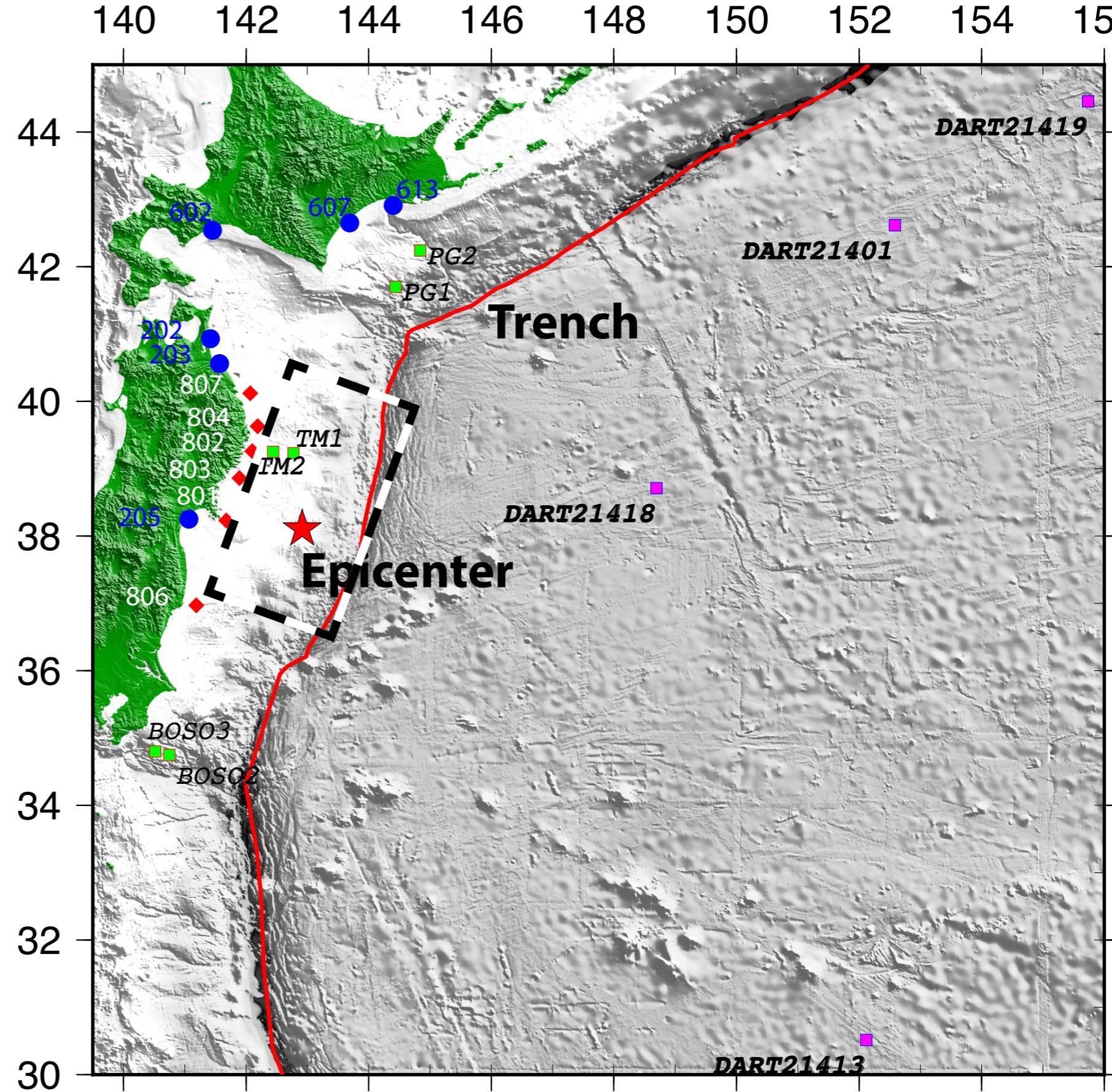
# TRI works with uniform scaling... but crude source estimate



**Problem: Real tsunamis  
much more complicated...**

# 2011 Japan tsunami: Ideal to study source process

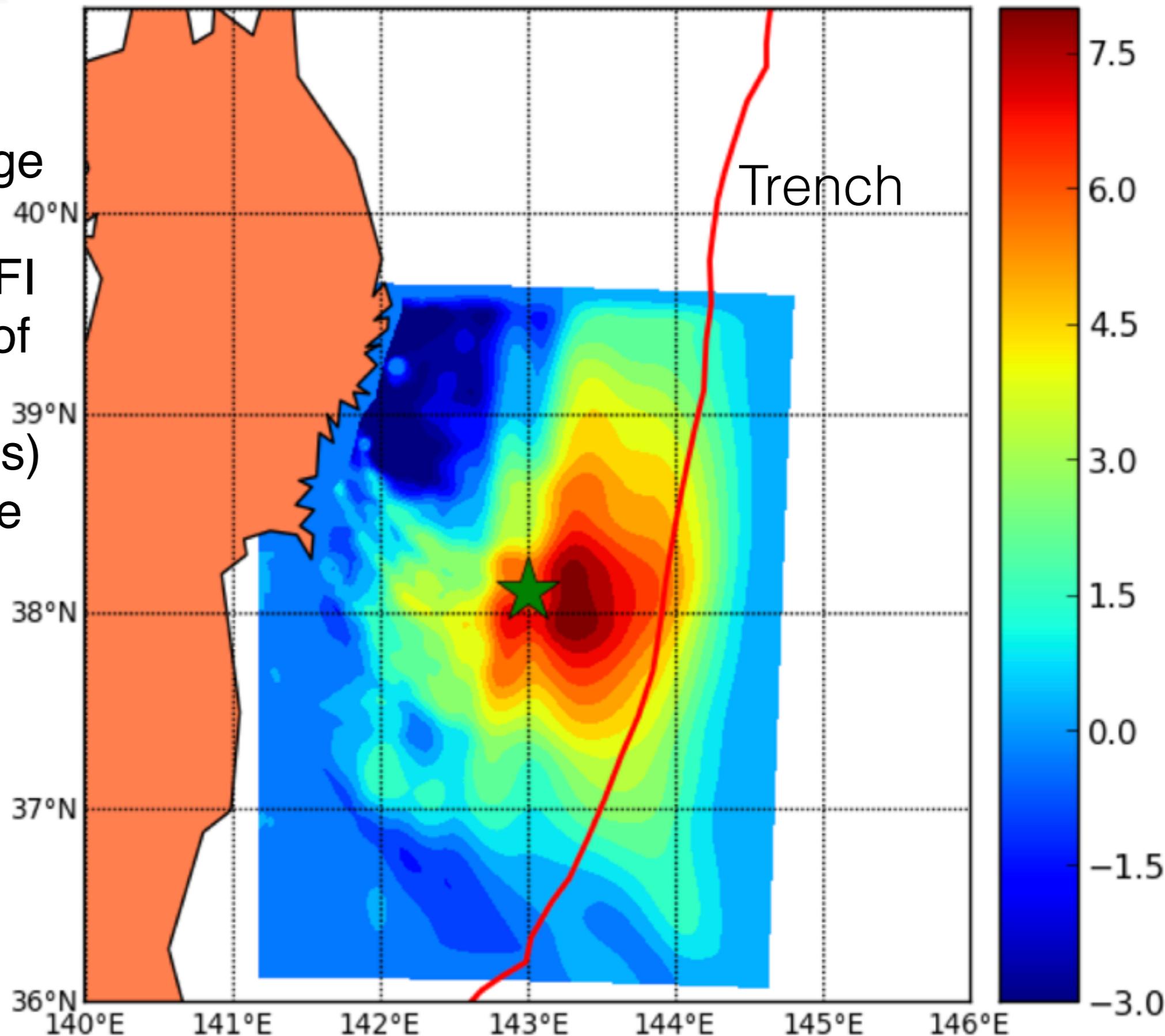
- Very large tsunami due to giant Mw 9 earthquake
- Unprecedented array of tsunami observations available
- Many published source models for comparison



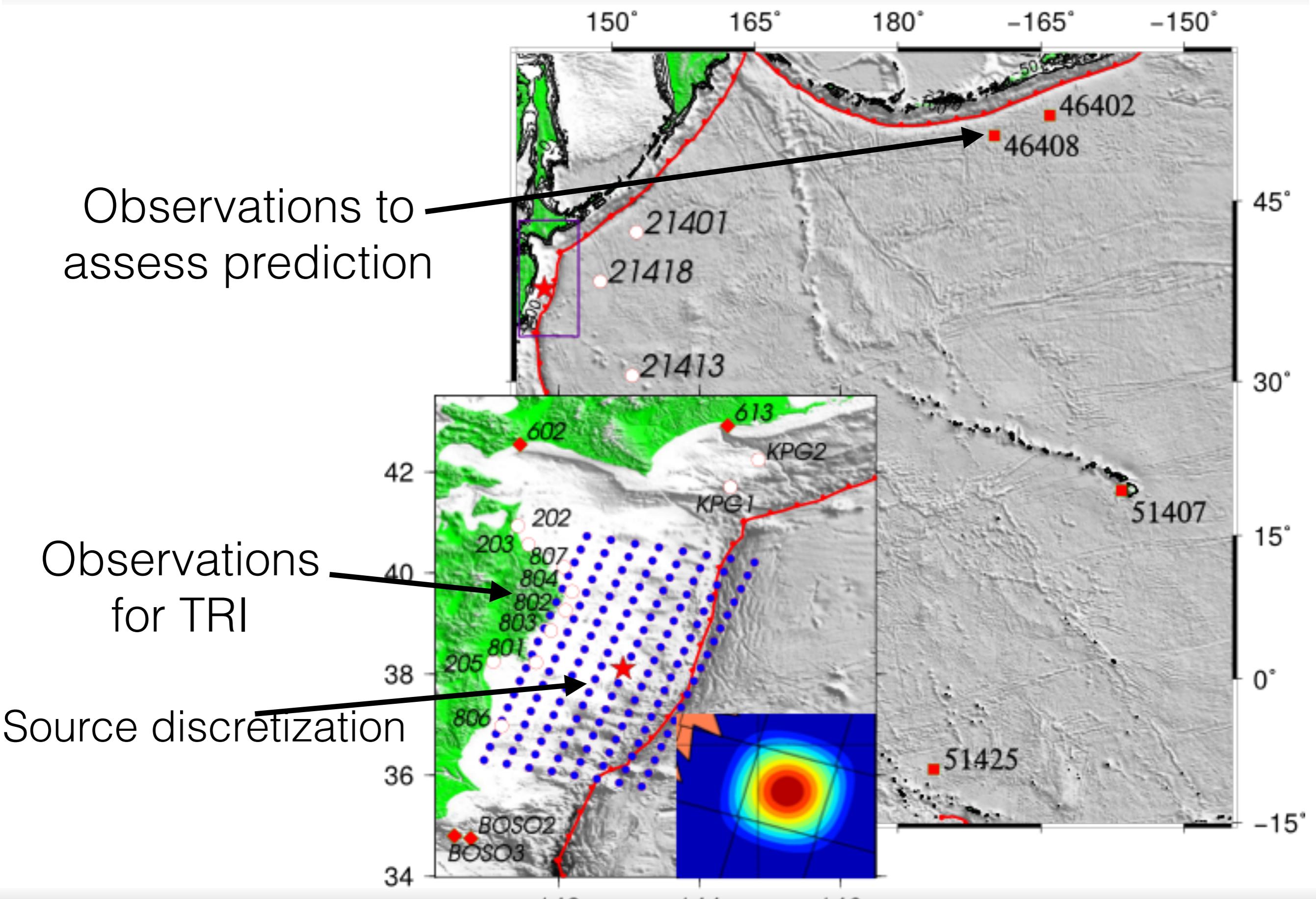
# Basic TRI applied to Japan tsunami: Crude estimate

## Problems:

- TRI source image lacks detail evident in the FFI result (sparsity of data causes incomplete focus)
- Artefacts outside source (incomplete destructive interference)

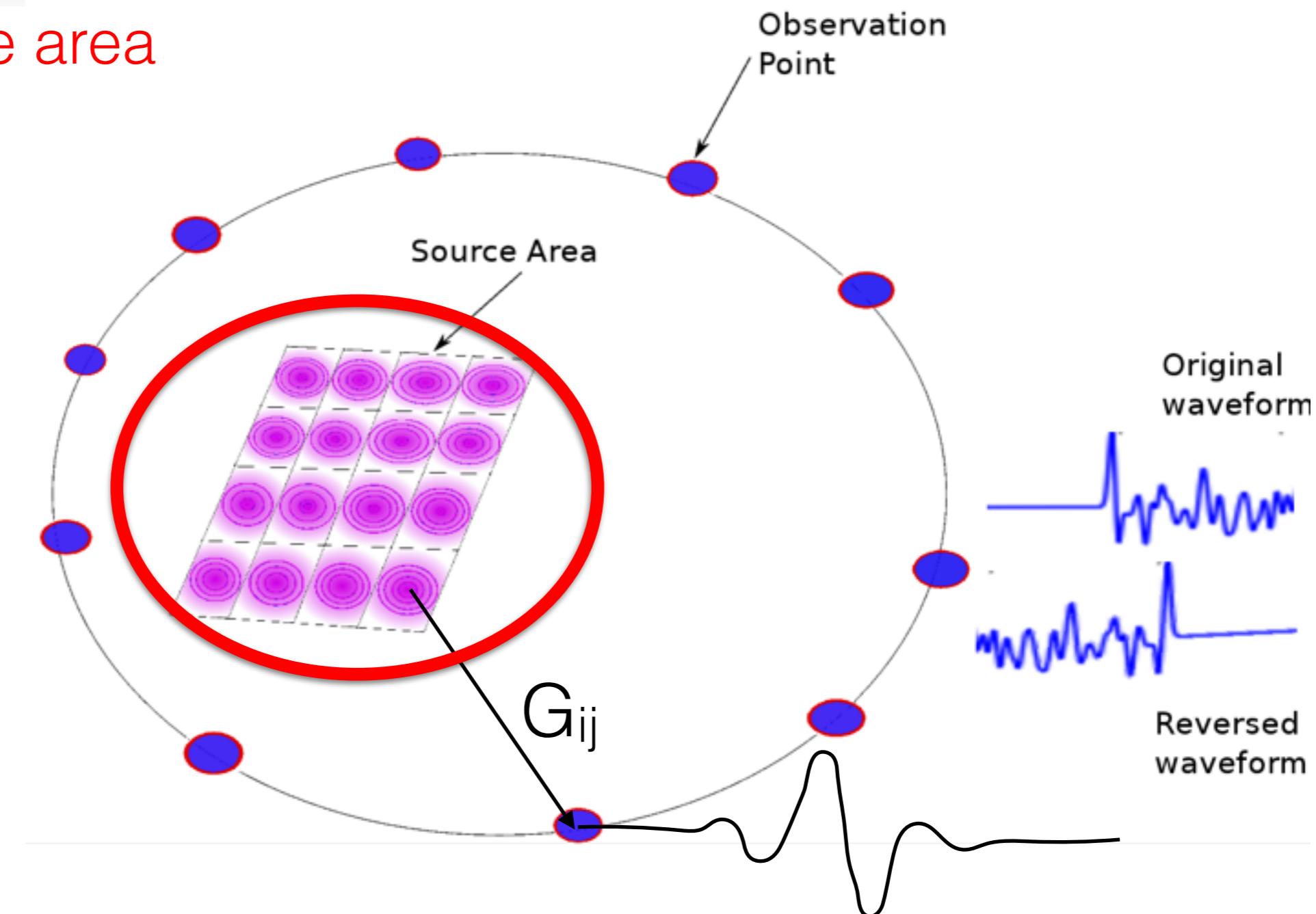


# 2011 Japan tsunami: Ideal to study source process



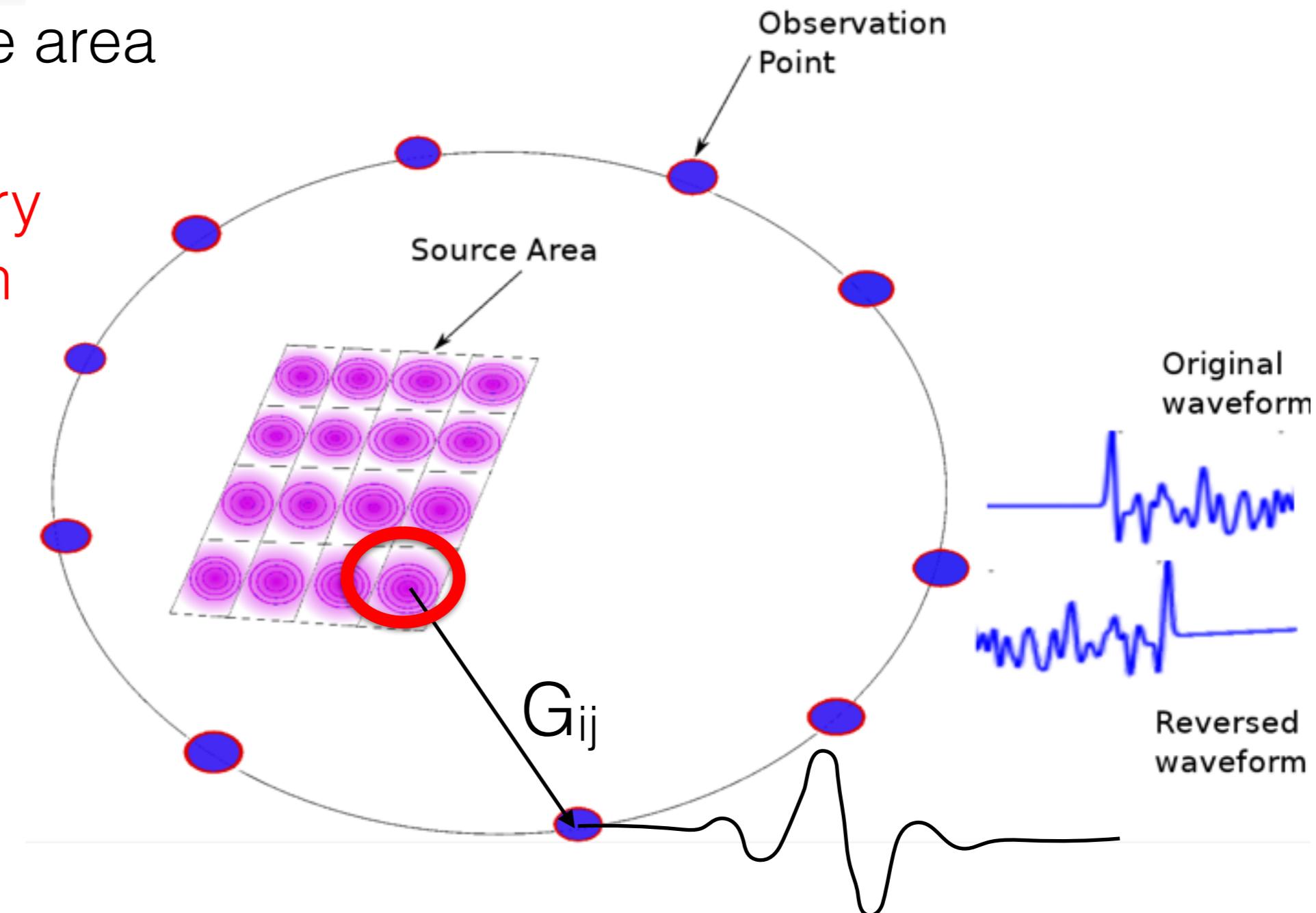
# TRI with Green's function scaling

- Divide the source area into subregions



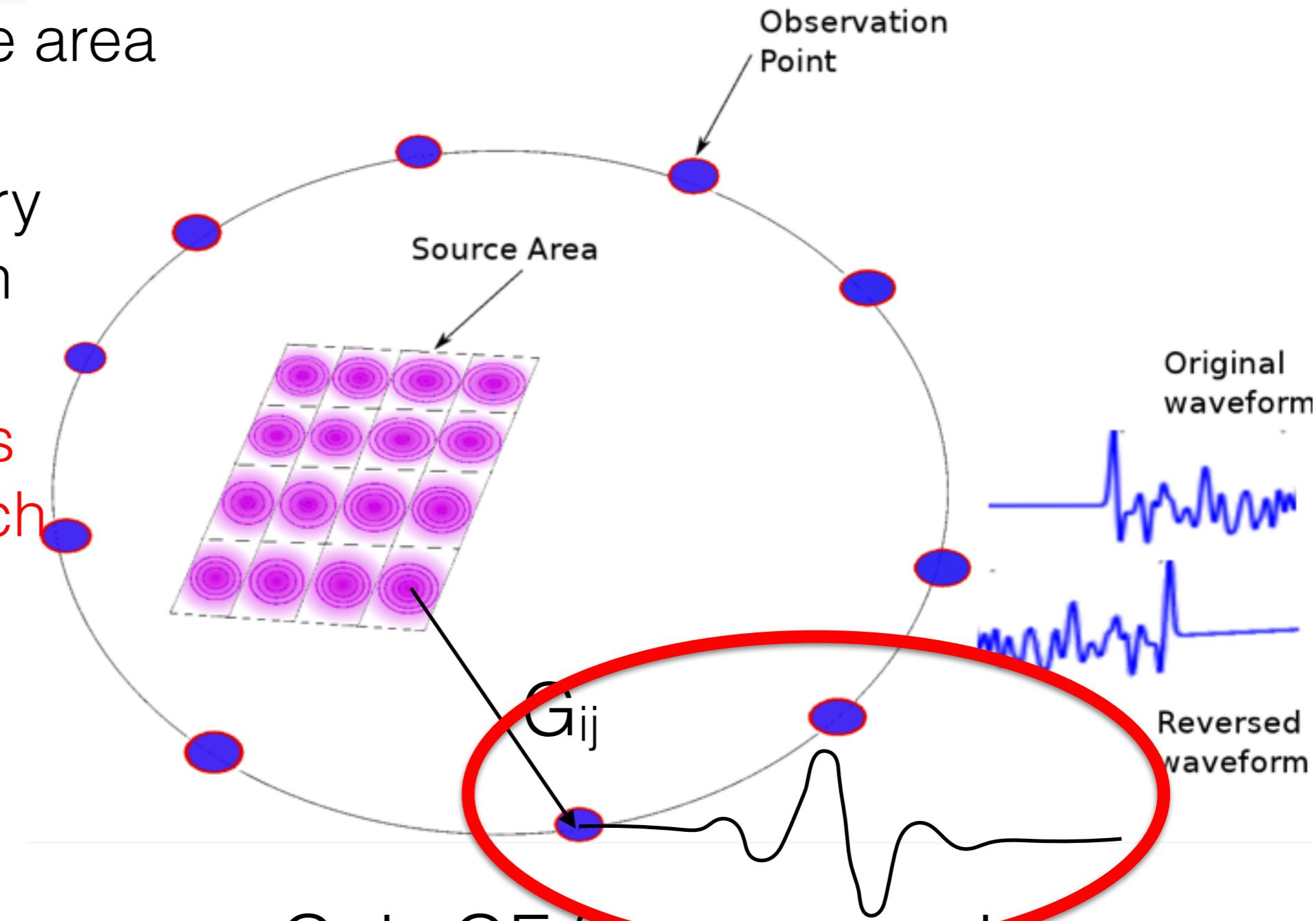
# TRI with Green's function scaling

- Divide the source area into subregions.
- Create elementary source over each subregion



# TRI with Green's function scaling

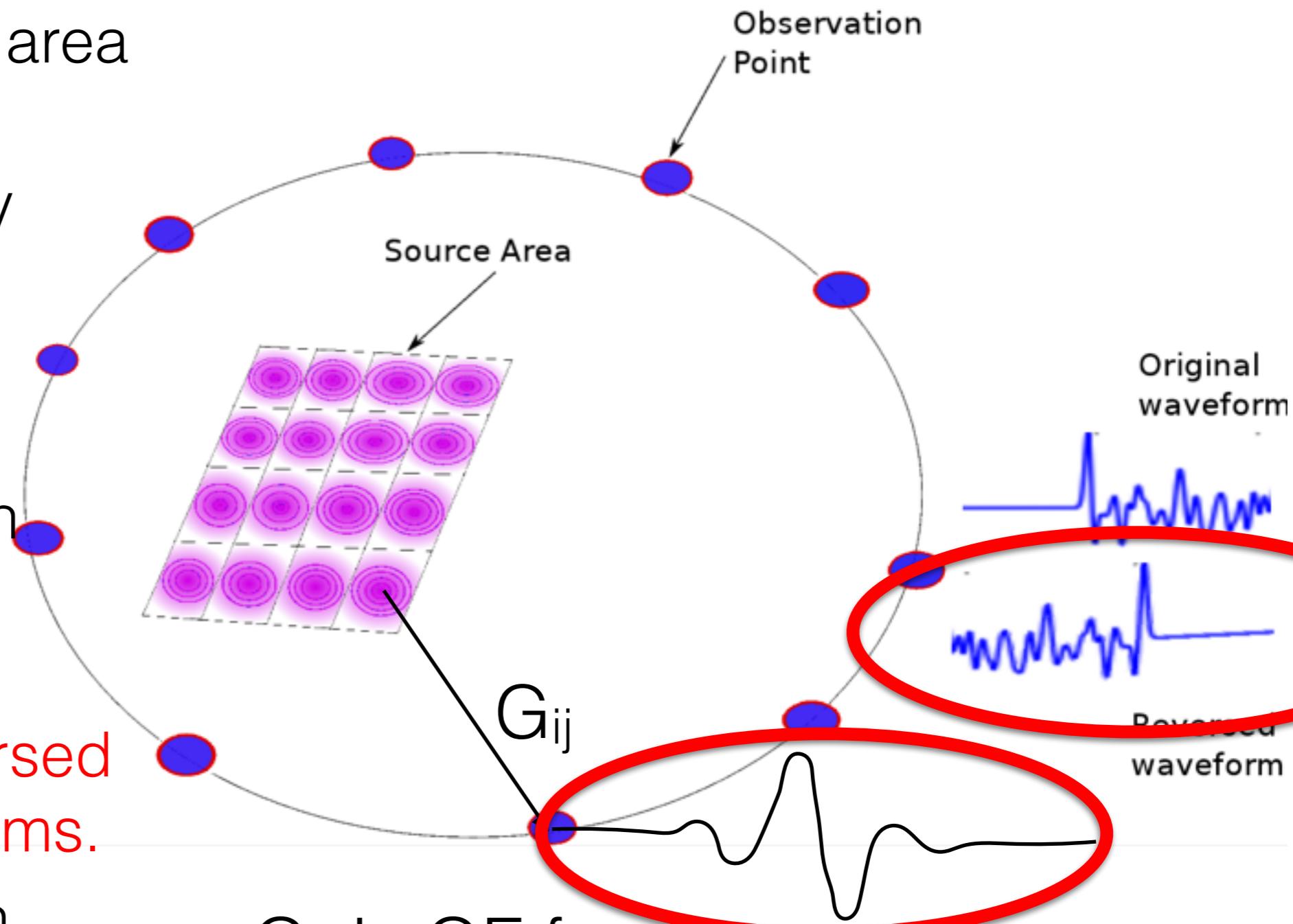
- Divide the source area into subregions.
- Create elementary source over each subregion
- Compute Green's function from each subregion



$G_{ij}$  is GF from source i to receiver j (describe tsunami propagation from i to j; depend on seabed topography)

# TRI with Green's function scaling

- Divide the source area into subregions.
- Create elementary source over each subregion
- Compute Green's function from each subregion
- Convolve Green's function with reversed observed waveforms.
- Amplitude at each subregion:  
Scaled wave height at the final time



$G_{ij}$  is GF from source i to receiver j (describe tsunami propagation from i to j; depend on seabed topography)

## Green functions: Provide more detail & scaling

Kawakatsu & Montanger (2008): Allow source inversion problem guide choice of TRI scaling factor

$$\left| \sum_{i=1}^n G_i(\mathbf{x}_j, \omega) a_i(\omega) - d_j(\omega) \right|^2 \xrightarrow{\frac{\partial J}{\partial \hat{a}_i} = 0} \sum_{i=1}^n G_{i'}^*(\mathbf{x}_j, \omega) G_i(\mathbf{x}_j, \omega) \hat{a}_{ij}(\omega) = G_{i'}^*(\mathbf{x}_j, \omega) d_j(\omega)$$

Approximate normal equation matrix as diagonal, with entries:

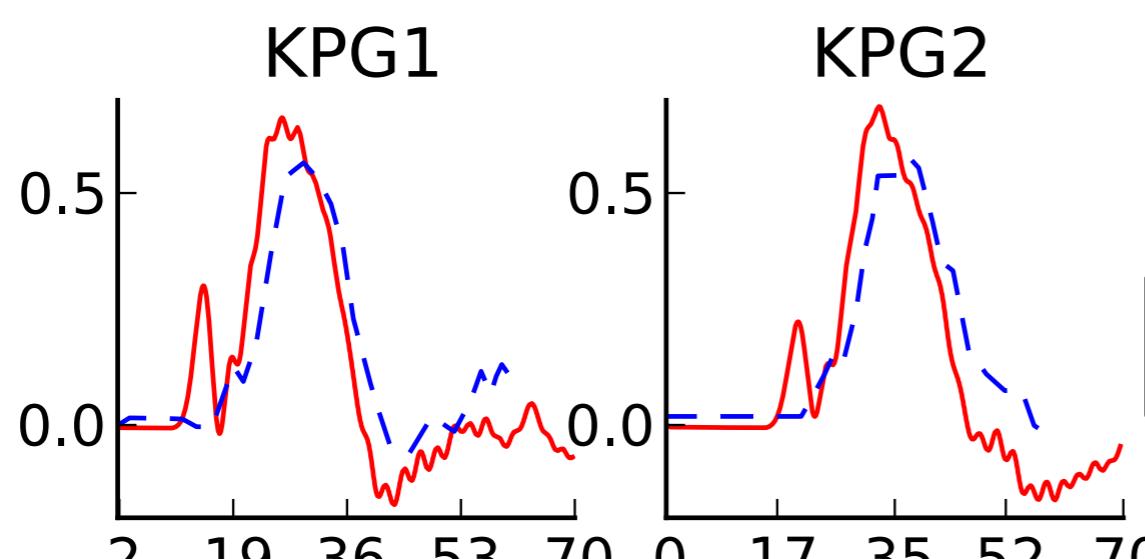
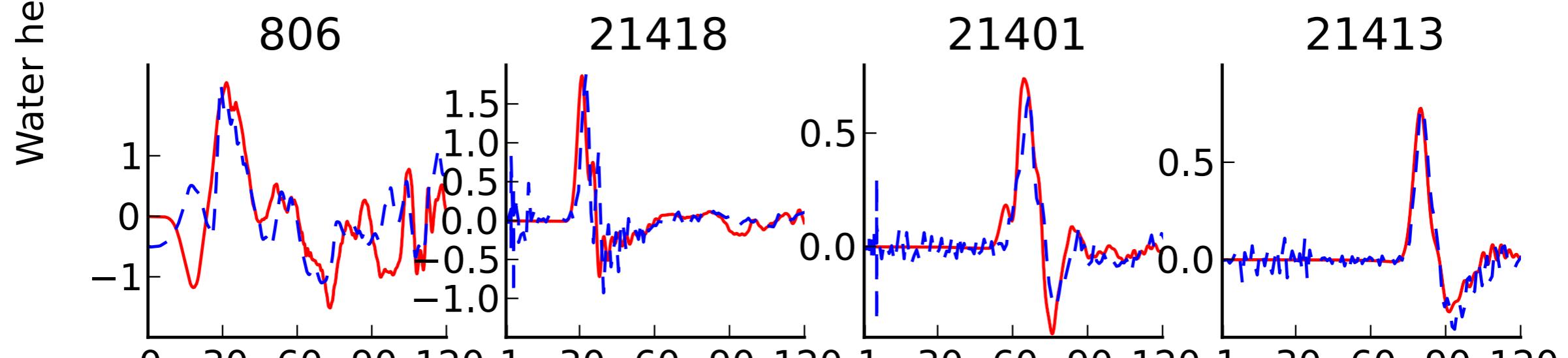
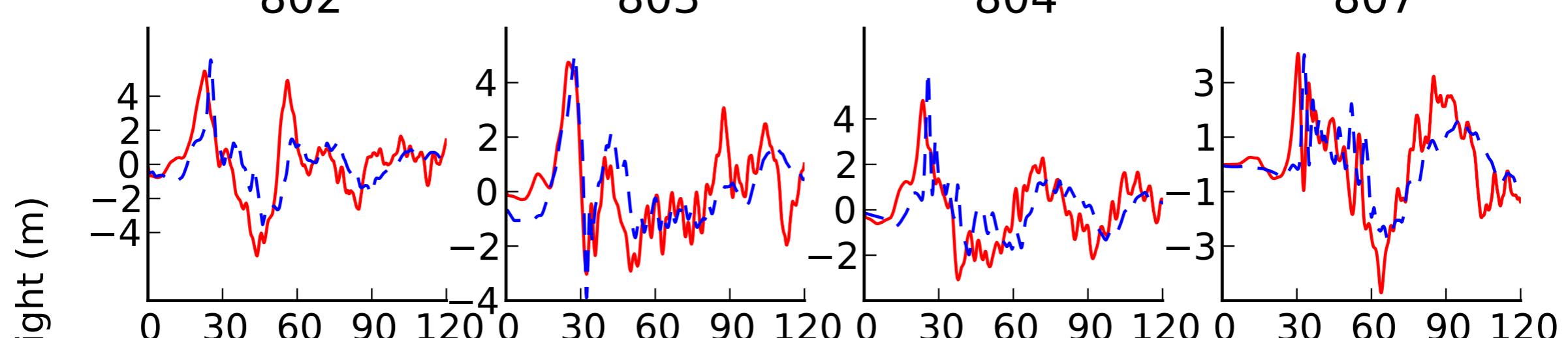
$$\int G_{i'}(\mathbf{x}_j, \tau) G_i(\mathbf{x}_j, t + \tau) d\tau \approx |G_{ij}|^2 \delta_{ii'}$$

Yields an expression for TRI with scaling factor determined:

$$\begin{aligned} \hat{a}_{ij}(\omega) &= \frac{1}{|G_{ij}|^2} G_{i'}^*(\mathbf{x}_j, \omega) d_j(\omega) \\ &= \frac{e^{i\omega T}}{|G_{ij}|^2} TR_j^*(\mathbf{s}_i, \omega) \end{aligned}$$

i.e., scaling factor is inverse of zero-lag autocorr. of GF

# New approach: Excellent waveform agreement (similar to MTW)



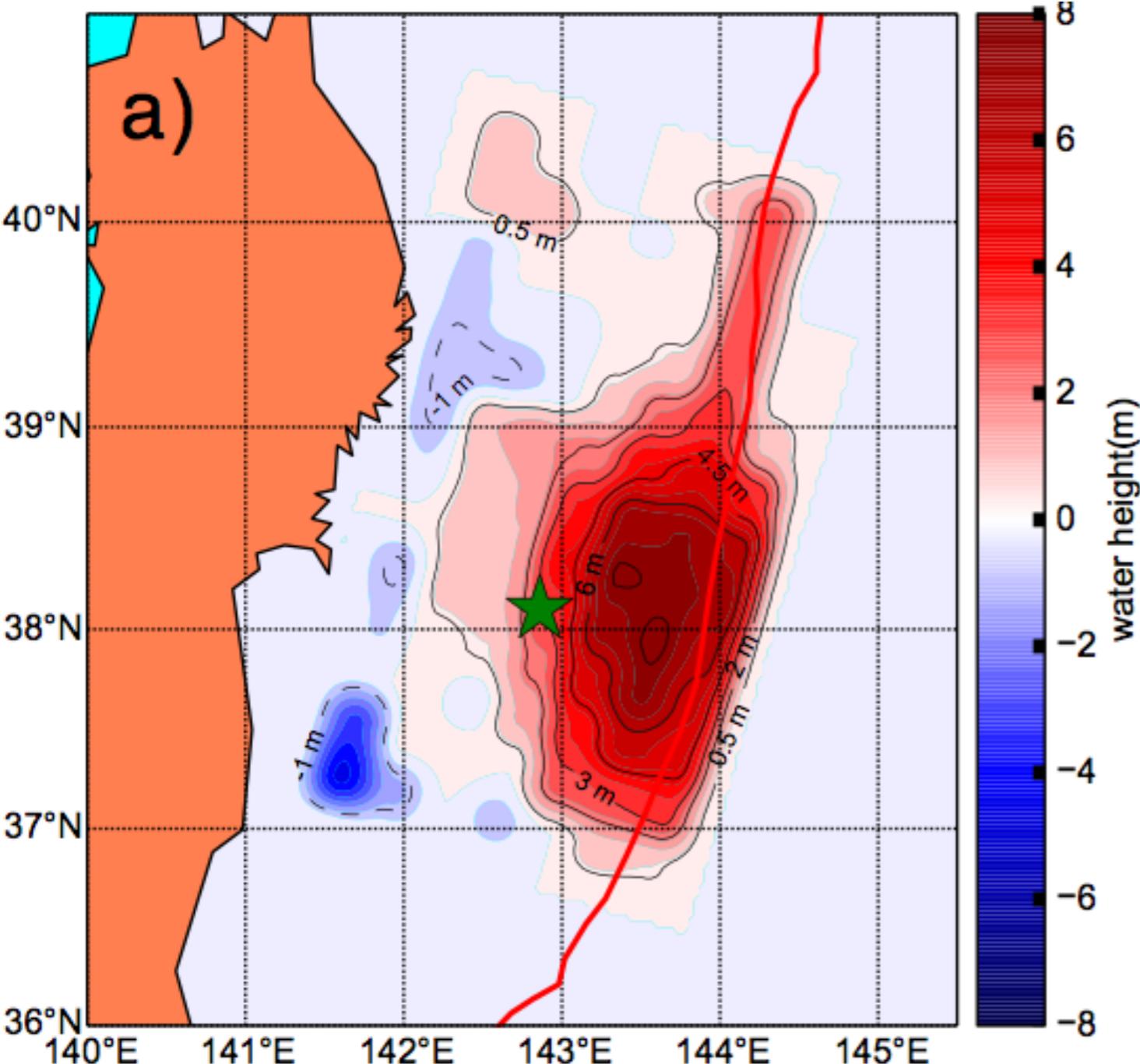
GFTRI  
Observed

Time (min)

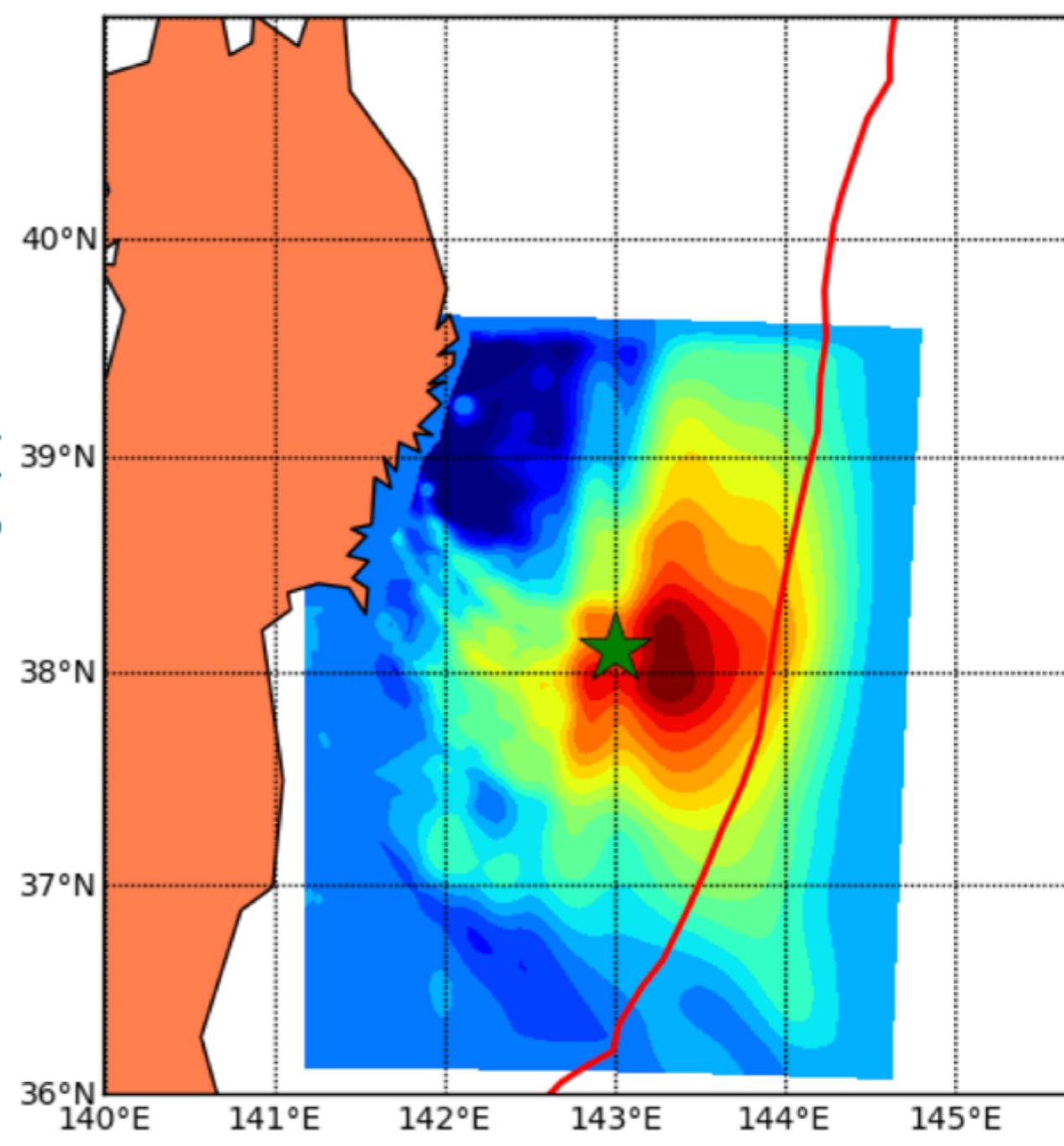
**These data are included in analysis**

New approach: Similar resolution;  
Fraction of computational cost, fewer subjective choices

GF-TRI Hossen et al. (2015)



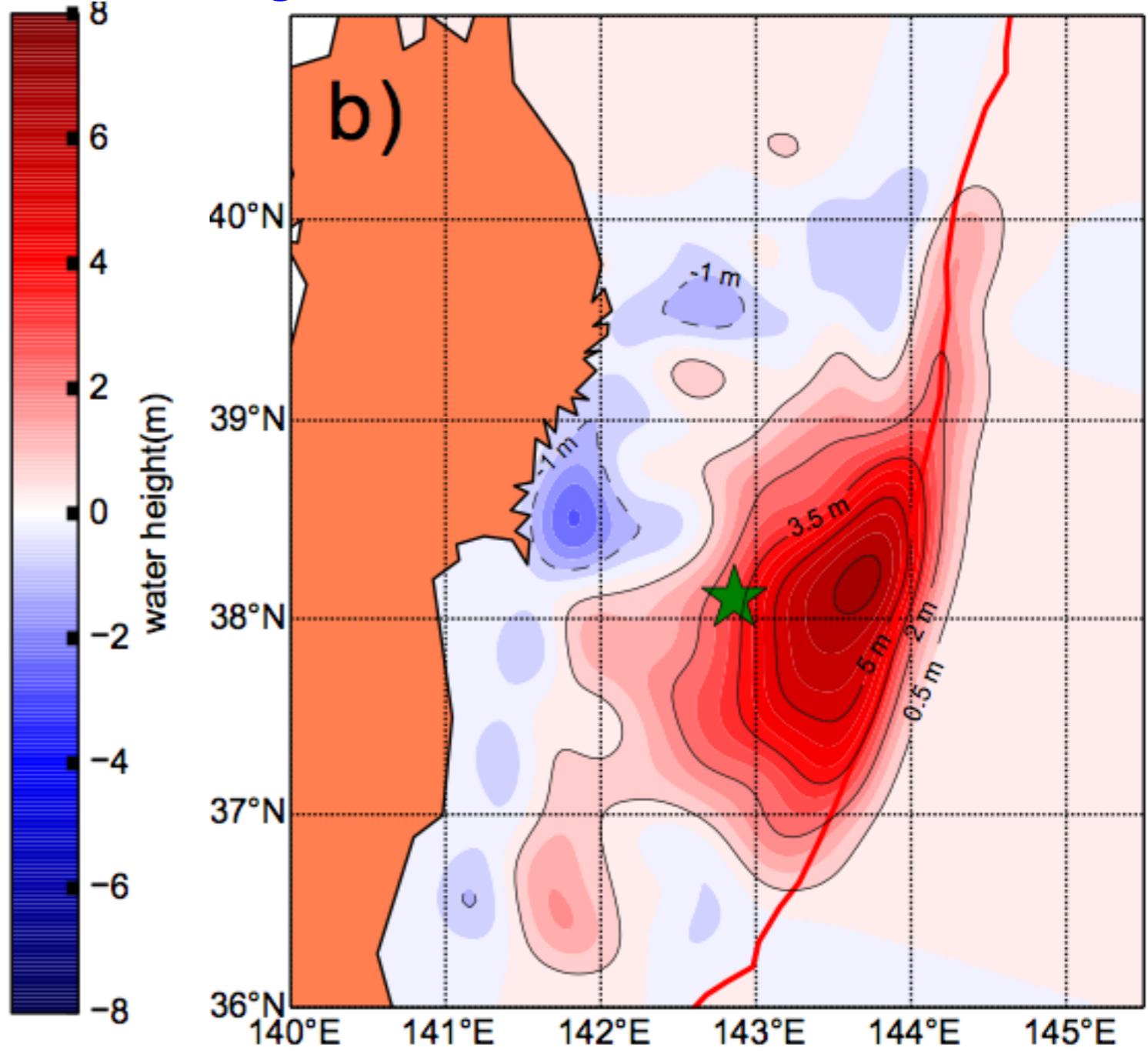
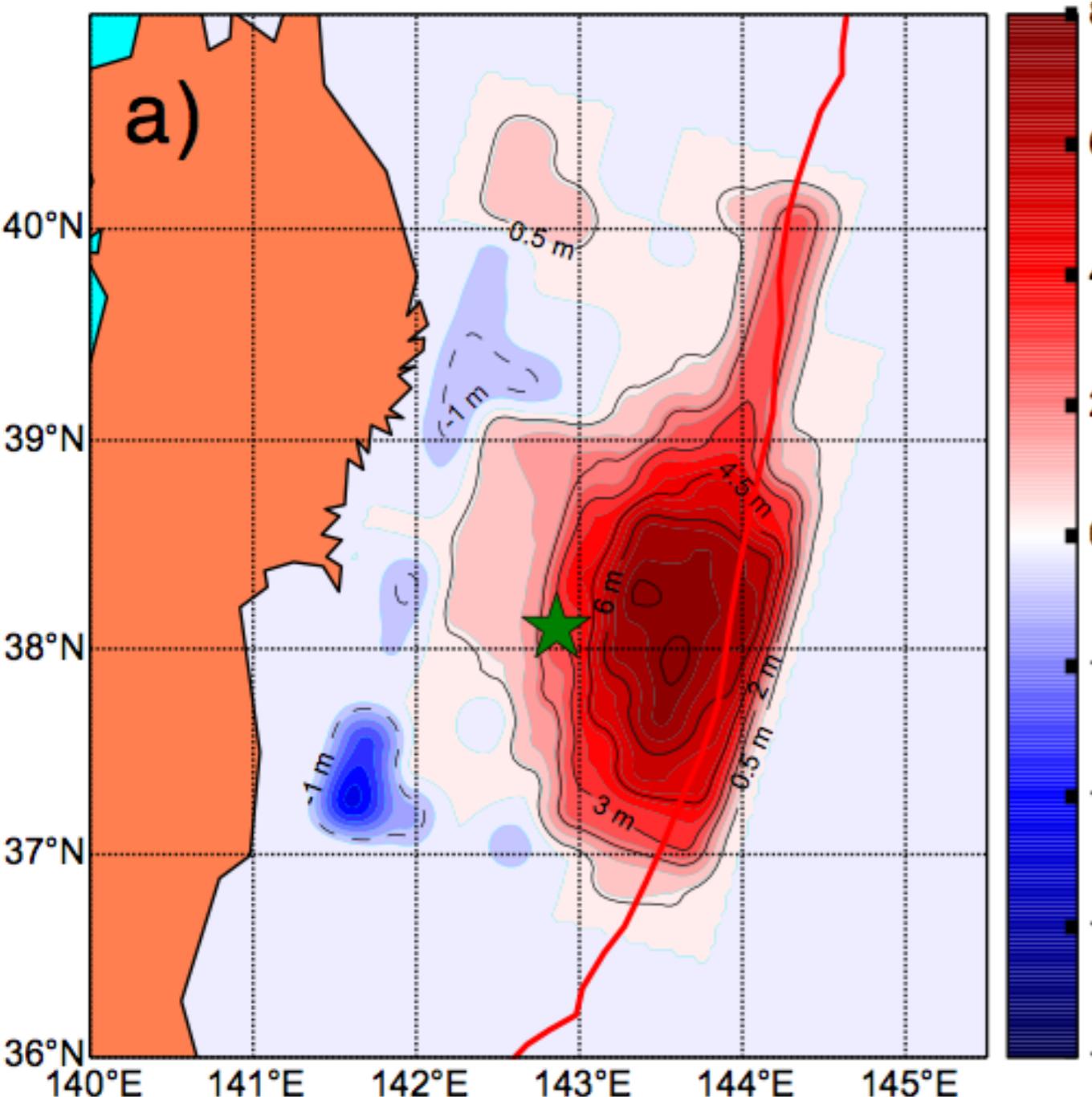
Previous TRI



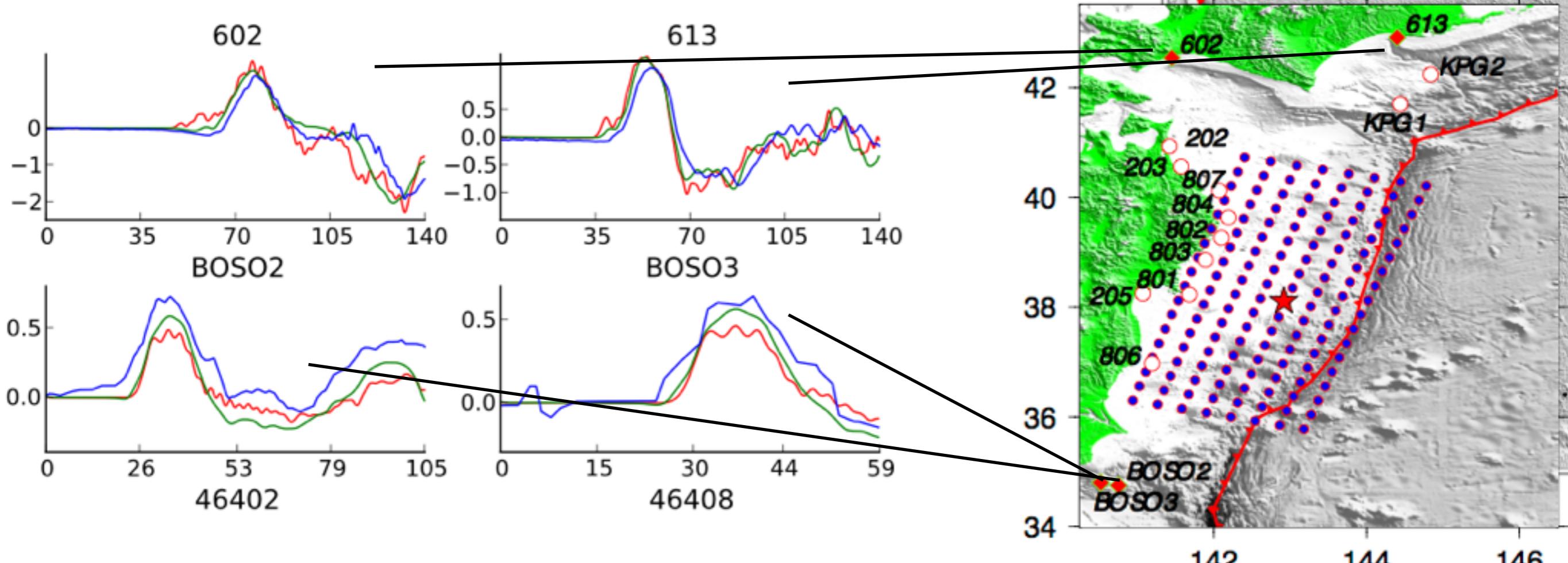
# New approach: Similar resolution; Fraction of computational cost, fewer subjective choices

TRI method with GF,  
Hossen et al. (2015)

Conventional inversion  
method (multiple time window  
**regularized** inversion)



# Predictive power near field: Similar to conventional but much faster & more objective



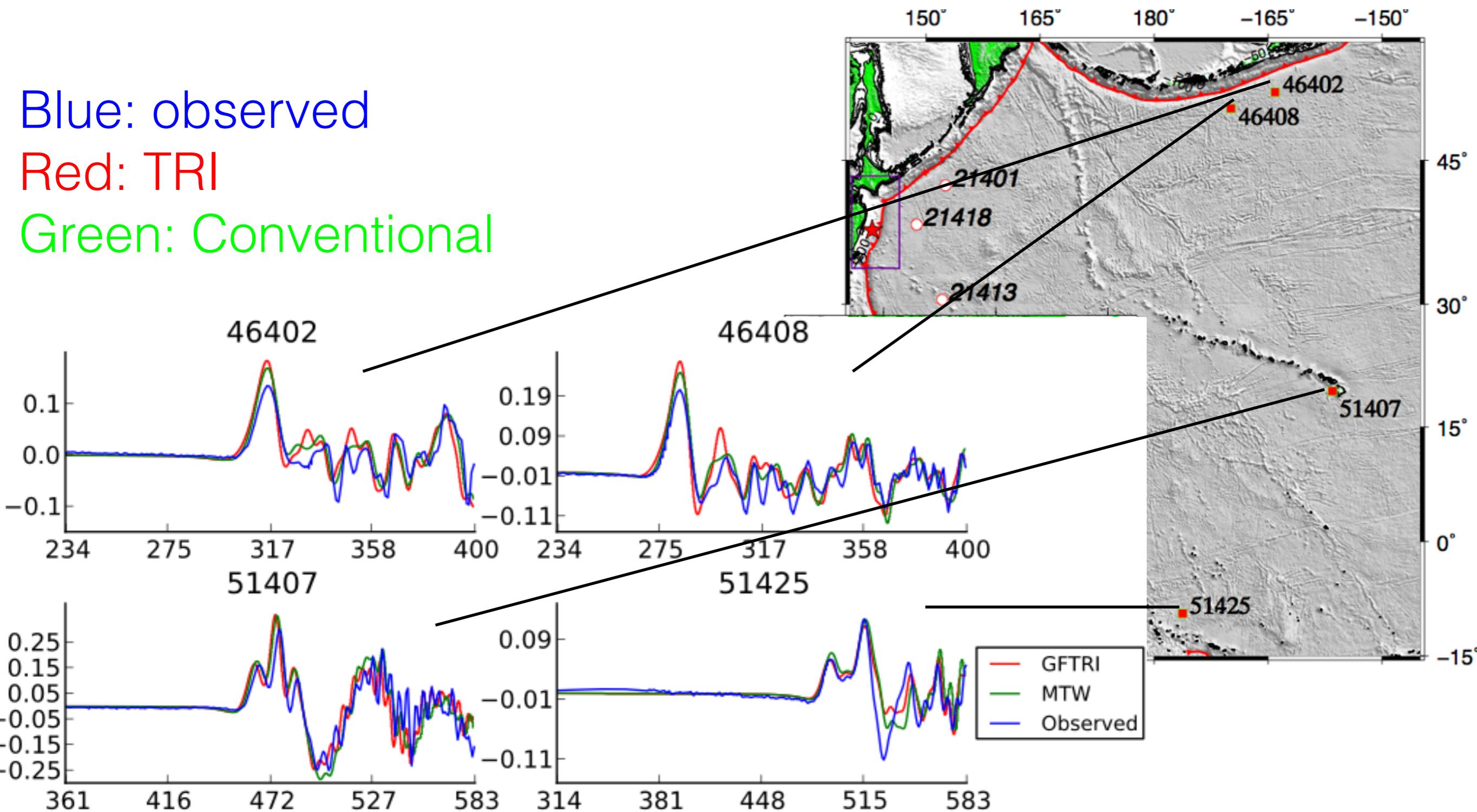
Blue: observed

Red: TRI

Green: Conventional

# Predictive power far field: Excellent

Blue: observed  
Red: TRI  
Green: Conventional



# Importance/future impact: Tsunamis & harbour resonance

- Coastal populations already warned of far-field tsunamis & can escape
- Effects on ports persist for many hours & depend on subtle waveform features that may excite harbour resonance
- Example: Resonance excited in the harbour at Geraldton, Western Australia, by the 2004 Indian Ocean Tsunami

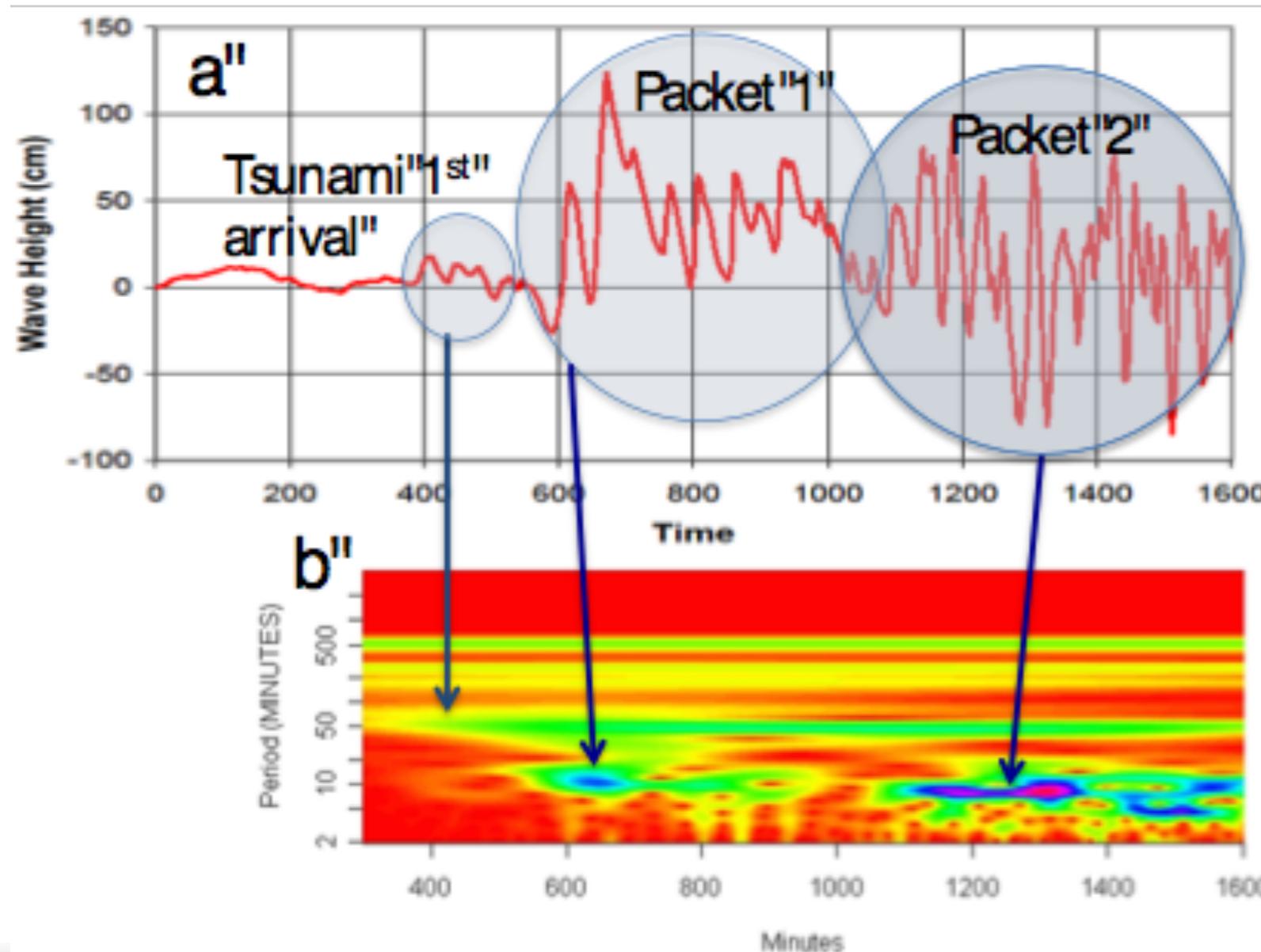


Figure: Geoscience Australia

# Summary

- New sea level sensors can be used for time reverse imaging of large tsunami sources
- Tsunami TRI is simple: Average observed waveforms convolved with Green's functions pre-calculated for an array of source points (i.e. no real-time tsunami simulation necessary to estimate source)
- Prediction of far-field waveforms using TRI-determined source is excellent
- Current warning systems work well for alerting distant coastal communities, ports are more difficult to protect:  
Resonances excited by late-arriving phases require better tsunami source estimates which may be forecast effectively using TRI

## References:

- Hossen et al., (2015). Geophysical Research Letters, 42. doi:10.1002/2015GL065868
- Hossen et al., (2015). Pure and Applied Geophysics, 172, 969-984. doi:10.1007/s00024-014-1014-5

Both available upon request.

# Appendix

# More far-field agreements

