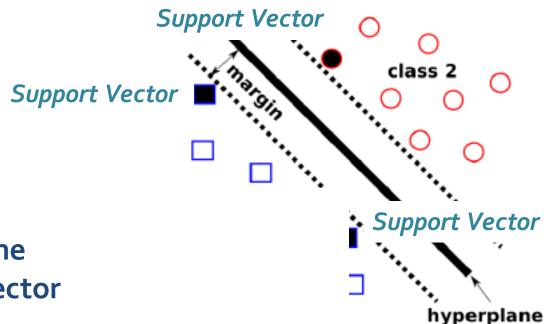


Chapter 9. Advanced Classification: Support Vector Machines (SVMs)

Meng Jiang

CSE 40647/60647 Data Science Fall 2017

Concepts



Quick start:

- 1. Hyperplane
- 2. Supper Vector
- 3. Margin
- 4. SVMs
- 5. Maximize Margin Width
- 6. Non-linear SVMs: Kernel Function

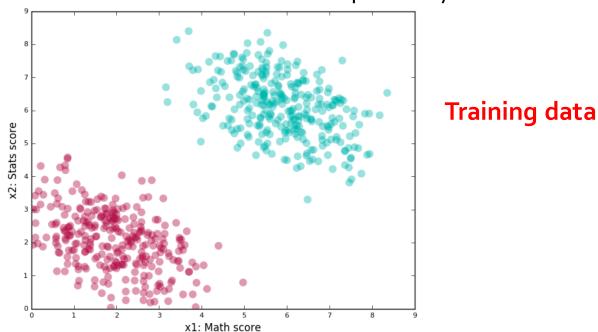
A Classification Problem

Dataset

- Suppose data science course instructors have observed that students get the most out of the course if they are good at Math or Stats.
- Over time, they have recorded the scores of the enrolled students in these subjects.
- Also, for each of these students, they have a *label* depicting their performance in the data science course: "*Good*" or "*Bad*".

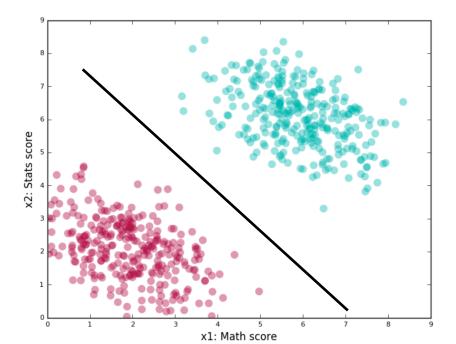
- Research problem
 - Now they want to determine the relationship between Math and Stats scores and the performance (label) in the ML course.
- Application
 - Perhaps, based on what they find, they want to specify a prerequisite for enrolling in the course.

- Data Preprocessing + Visualization
 - Draw a two-dimensional scatter plot, where one axis represents scores in Math, while the other represents scores in Stats.
 - A <u>student</u> with certain scores is shown as a <u>point</u> on the graph.
 - The color of the point green or red represents how he/she did on the data science course: "Good" or "Bad" respectively.

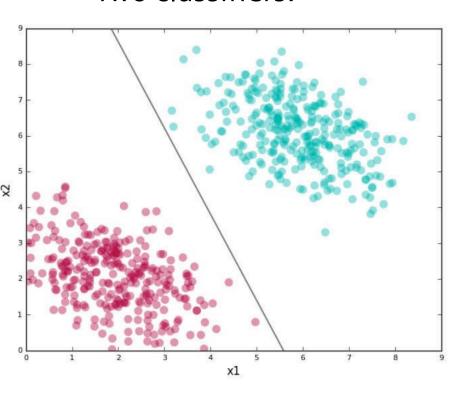


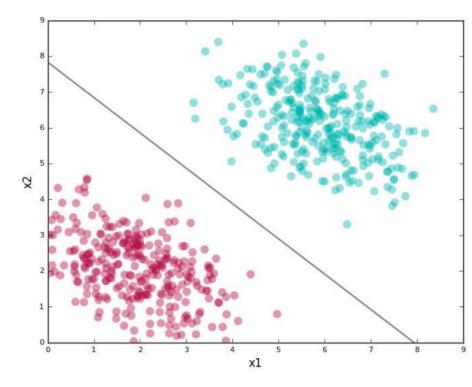
Goal

 Finding a *line* that passes between the red and green clusters, and then *determining which side* of this line a score tuple lies on, is a good algorithm.



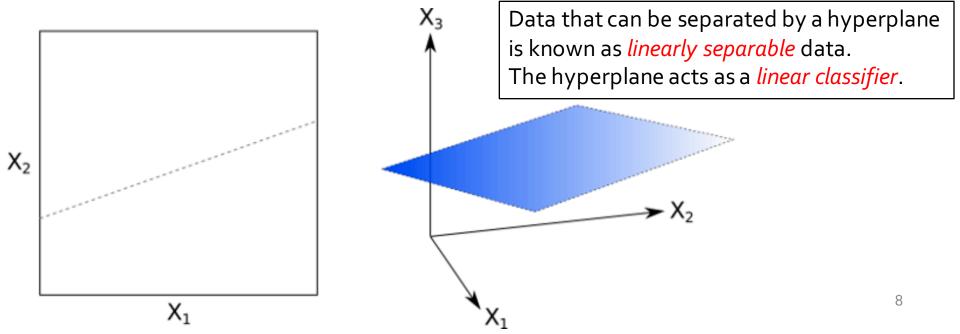
- The *line* is our *separating boundary* (because it separates out the labels) or *classifier* (we use it classify points).
- Two classifiers:



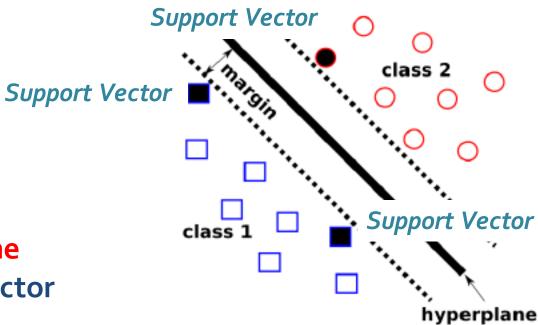


Concept 1: Hyperplane

- In two dimensions we find a line.
- In three dimensions we find a plane.
- In high dimensions we find a *hyperplane* a generalization of the two-dimensional line and three-dimensional plane to an *arbitrary number of dimensions*.



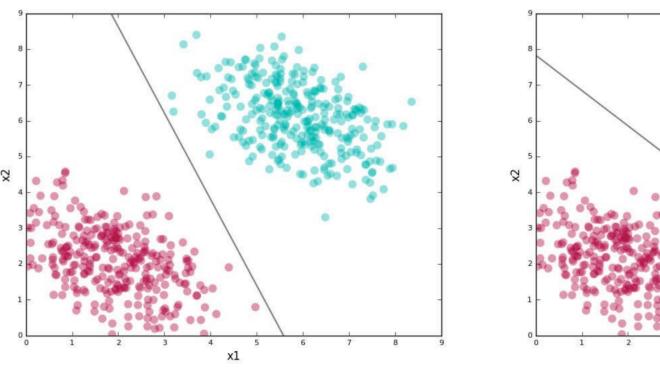
Concepts

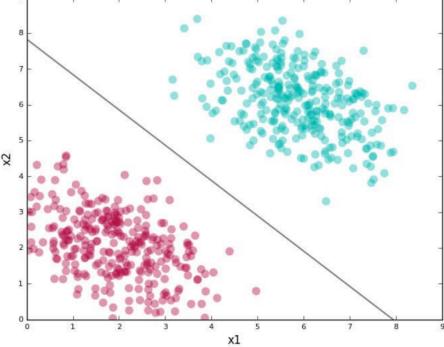


Quick start:

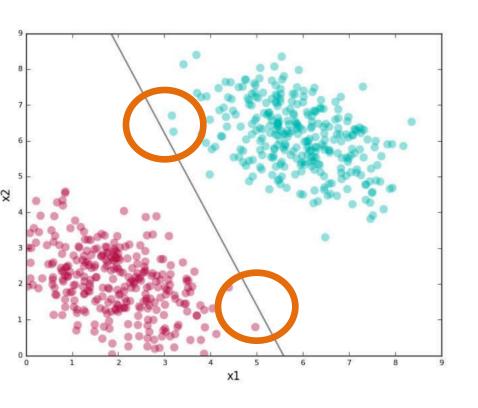
- 1. Hyperplane
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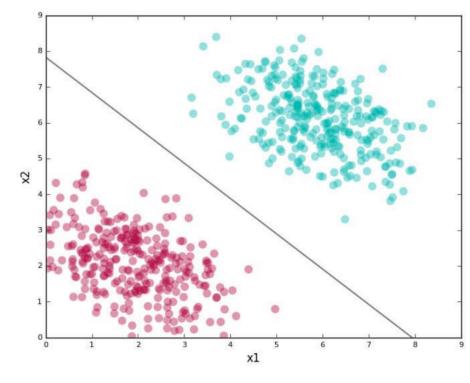
Q: Both lines separate the red and green clusters. Is there a good reason to choose one over another?





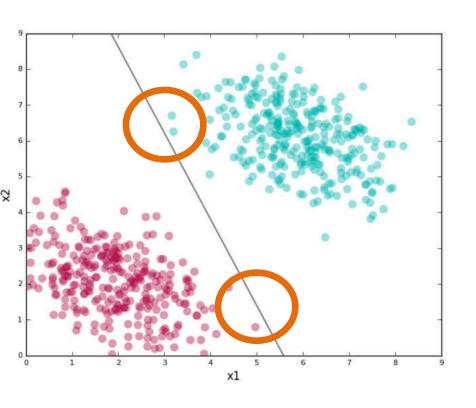
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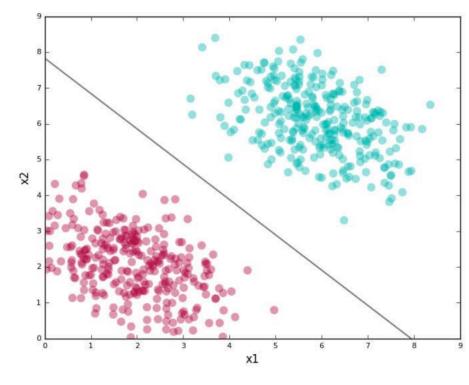




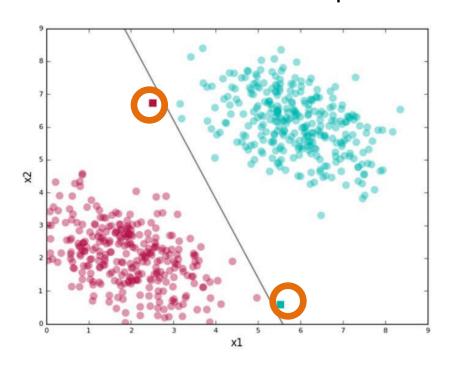
A: We try to find the second kind of line.

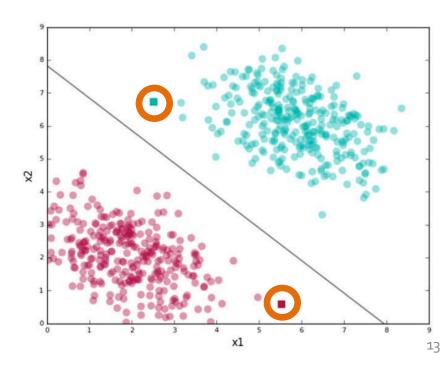
Q': Define *underlying philosophy* in the general case.





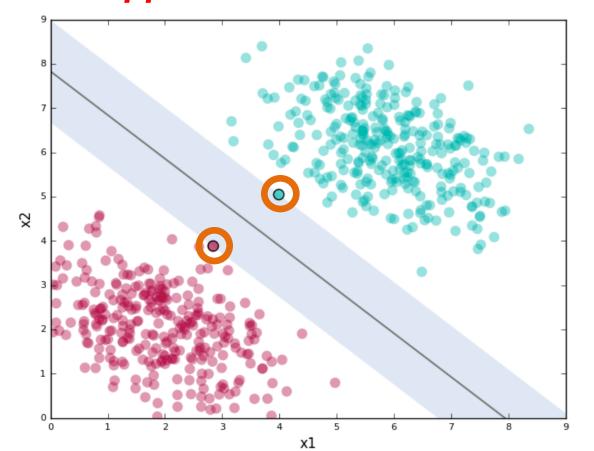
- Philosophy
 - Find lines that correctly classify the training data
 - Among all such lines, pick the one that has the greatest distance to the points closest to it





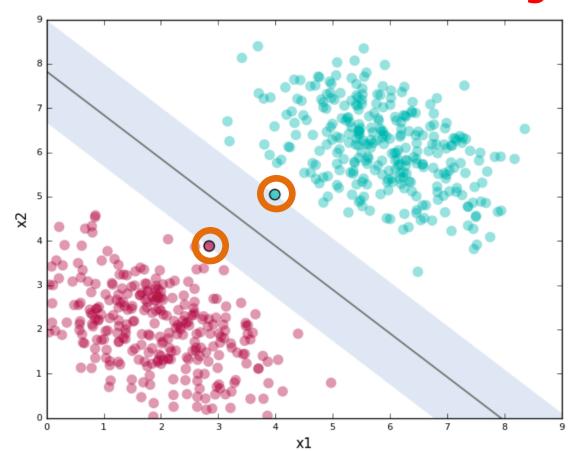
Concept 2: Support Vector

 The closest points that identify this line are known as support vectors.

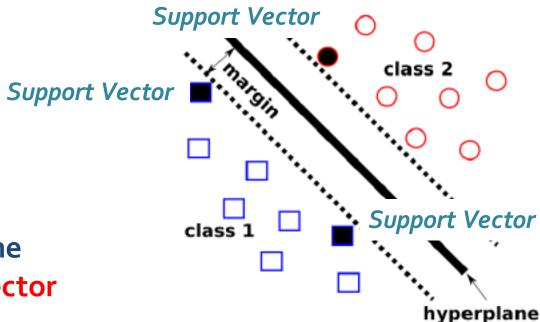


Concept 3: Margin

• The (shaded) region support vectors define around the line is known as the margin.



Concepts



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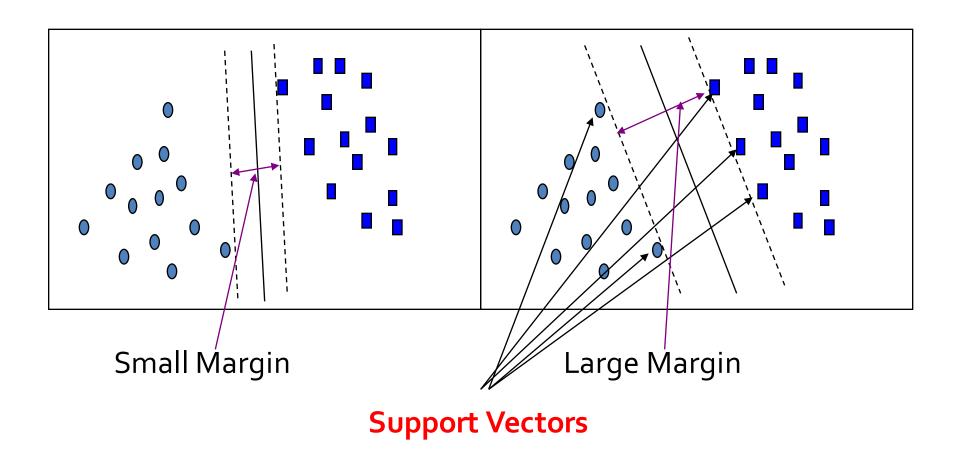
Support Vector Machines

- Definition (Wikipedia)
 - A SVM is a discriminative classifier formally defined by a separating hyperplane. In other words, given labeled training data, the algorithm outputs an optimal hyperplane which categorizes new examples.
 - A data point is viewed as a p-dimensional vector, and we want to know whether we can separate such points with a (p-1)-dimensional hyperplane.

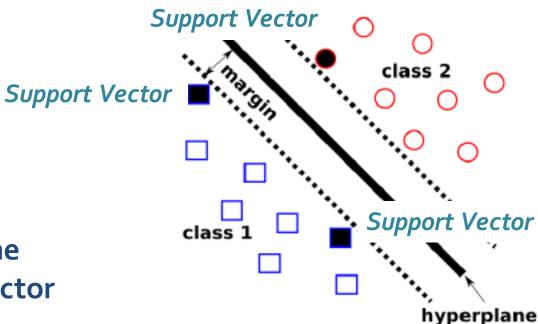
Use

 SVMs give you a way to pick between many possible classifiers in a way that guarantees a higher chance of correctly labeling your test data.

SVM: General Philosophy



Concepts

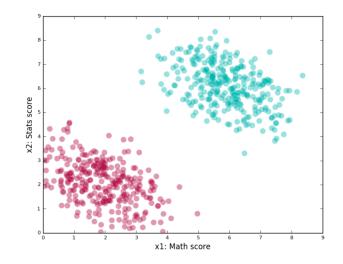


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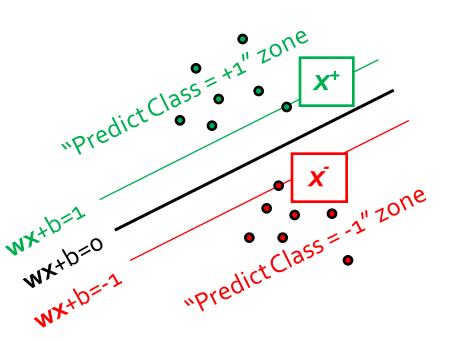
Formally Define the Problem

- Binary Classification
 - E.g., course performance classification
 - $x_i = (x_1, x_2, x_3, ...)$: Subject scores
 - $y_i = +1 \text{ or } -1$: "Good" or "Bad"
 - x₁: score of subject Math
 - x₂: score of subject Stats



- Mathematically, $x \in \Re^n$, $y \in \{+1, -1\}$,
 - We want to derive a function $f: X \rightarrow Y$

Optimization



Support vectors:





Hyperplane:

wx+b=0

What we know:

•
$$\mathbf{W} \cdot \mathbf{X}^+ + b = +1$$

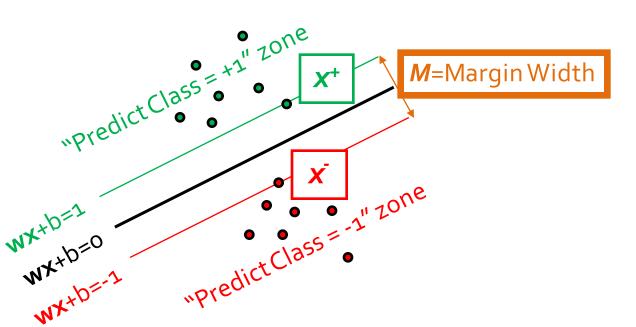
•
$$\mathbf{W} \cdot \mathbf{X} + b = -1$$

A separating hyperplane can be written as

$$\mathbf{w} \cdot \mathbf{x} + \mathbf{b} = \mathbf{o}$$

where $\mathbf{w} = \{\mathbf{w}_1, \mathbf{w}_2, ..., \mathbf{w}_n\}$ is a weight vector and \mathbf{b} a scalar (bias).

Optimization



Support vectors:





Hyperplane:

wx+b=0

What we know:

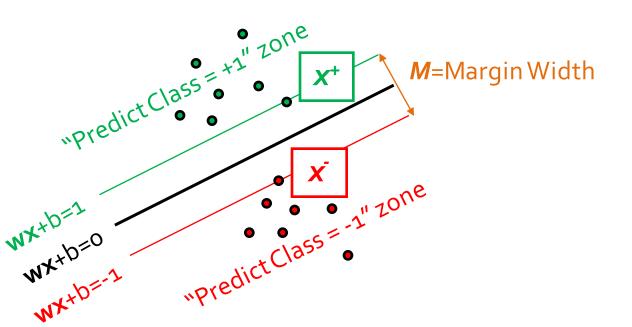
•
$$\mathbf{W} \cdot \mathbf{X}^+ + b = +1$$

•
$$\mathbf{W} \cdot \mathbf{X} + b = -1$$

How to calculate the Margin Width?

Distance between two parallel lines.

Optimization: Maximize Margin Width



Support vectors: X⁺



Hyperplane:

wx+b=0

What we know:

•
$$\mathbf{W} \cdot \mathbf{X}^+ + b = +1$$

•
$$\mathbf{W} \cdot \mathbf{X} + b = -1$$

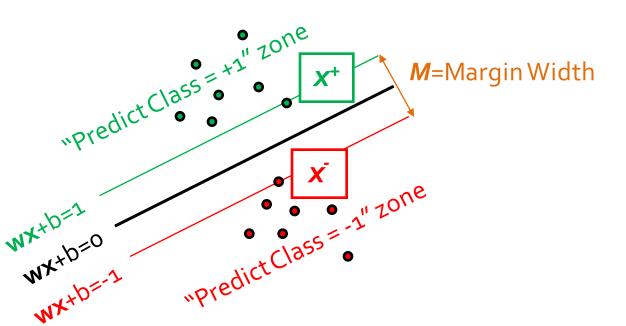
$$max M = \frac{(x^+ - x^-) \cdot w}{|w|} = \frac{2}{|w|}$$

same as $min = \frac{1}{2} w^t w$

Any constraints?

Correctly categorize...

Optimization: Maximize Margin Width



Support vectors: X⁺



Hyperplane:

wx+b=0

What we know:

•
$$\mathbf{W} \cdot \mathbf{X}^+ + b = +1$$

•
$$\mathbf{w} \cdot \mathbf{x} + b = -1$$

$$max M = \frac{(x^+ - x^-) \cdot w}{|w|} = \frac{2}{|w|}$$

same as $min = \frac{1}{2} w^t w$

$$H_1: \mathbf{w} \mathbf{x}_i + b \ge 1$$
 for $y_i = +1$
 $H_2: \mathbf{w} \mathbf{x}_i + b \le -1$ for $y_i = -1$
 $\rightarrow y_i (\mathbf{w} \mathbf{x}_i + b) \ge 1$ for all i

The MMW Problem

min
$$\Phi(w) = \frac{1}{2}w^t w$$

s.t. $y_i(wx_i + b) \ge 1$ for all i

It's a Constrained (Convex) Quadratic Optimization Problem!

Quadratic optimization problems are a well-known class of mathematical programming problems, and many (rather intricate) algorithms exist for solving them.

Solving the MMW Problem

- Need to optimize a quadratic function subject to linear constraints.
- Quadratic objective function and linear constraints →
 Quadratic Programming (QP) → Lagrangian multipliers
- The solution involves constructing a dual problem where a **Lagrange multiplier** α_i is associated with every constraint in the primary problem:

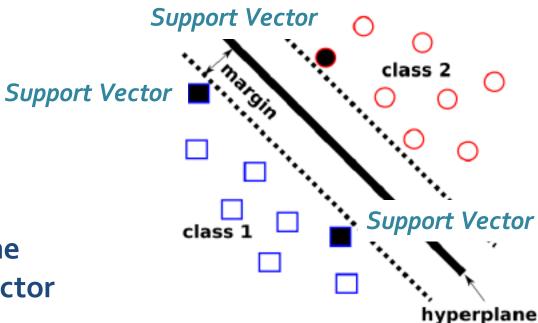
Find **w** and b such that $\Phi(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w}$ is minimized; and for all $\{(\mathbf{x}_i, y_i)\}: y_i (\mathbf{w}^T \mathbf{x}_i + b) \ge 1$

Find $\alpha_1 ... \alpha_N$ such that

$$\mathbf{Q}(\mathbf{\alpha}) = \sum \alpha_i - \frac{1}{2} \sum \sum \alpha_i \alpha_j y_i y_j \mathbf{x_i}^\mathsf{T} \mathbf{x_j}$$
 is maximized and

- (1) $\sum \alpha_i y_i = 0$
- (2) α_i ≥ o for all α_i

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LinearSVM: Summary

- The classifier is a separating hyperplane.
 - Linearly separable data points
- Most "important" training points are support vectors; they define the hyperplane.

maximum marginal hyperplane

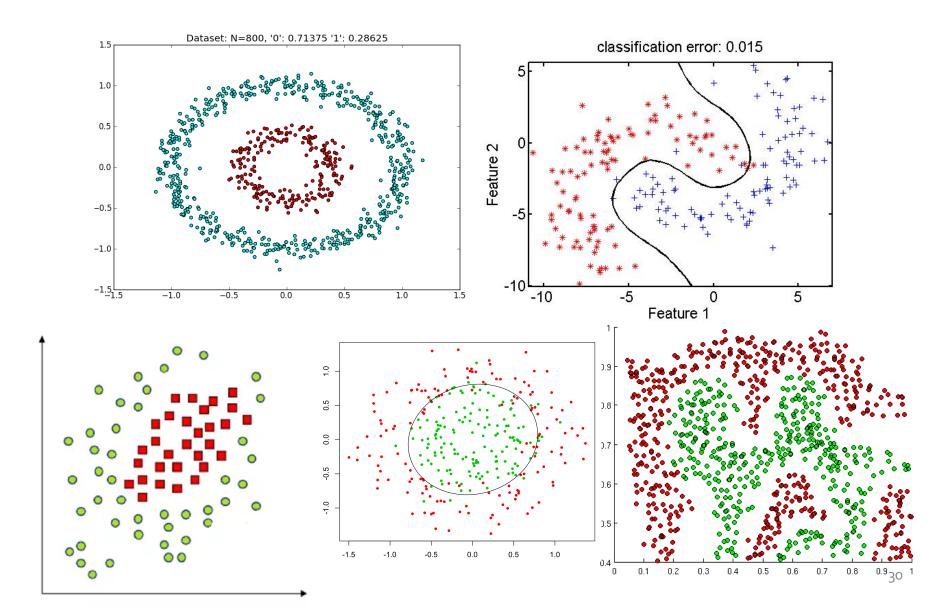
• Quadratic optimization algorithms can identify which training points x_i are support vectors with non-zero Lagrangian multipliers α_i .

Find $\alpha_1...\alpha_N$ such that $Q(\alpha) = \Sigma \alpha_i - \frac{1}{2} \Sigma \Sigma \alpha_i \alpha_j y_i y_j x_i^T x_j$ is maximized and (1) $\Sigma \alpha_i y_i = 0$ (2) $0 \le \alpha_i \le C$ for all α_i

Why is SVM Effective on High Dimensional Data?

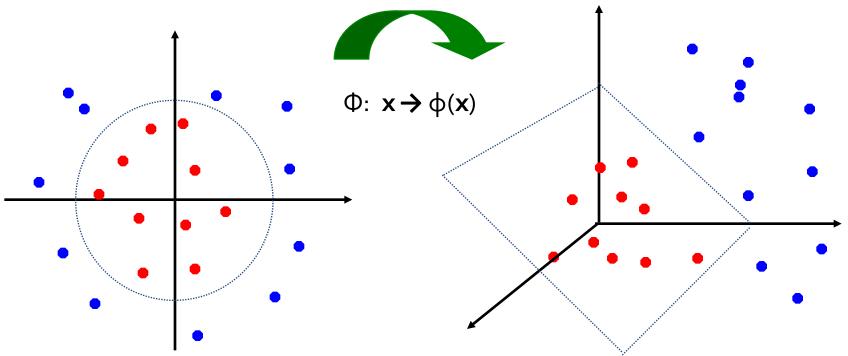
- The complexity of trained classifier is characterized by the # of support vectors rather than the dimensionality of the data.
- The support vectors are the essential or critical training examples — they lie closest to the decision boundary.
- If all other training examples are removed and the training is repeated, the same separating hyperplane would be found.

Non-Linear Data Points



Non-linear SVMs: Feature Spaces

 General idea: The original input space can always be mapped to some higher-dimensional feature space where the training set is separable:



The "Kernel Trick"

The classifier relies on dot product between vectors

$$K(x_i, x_j) = x_i^T x_j$$

• If every data point is mapped into high-dimensional space via some transformation $\Phi: x \to \phi(x)$, the dot product becomes:

$$K(x_i, x_j) = \varphi(x_i)^T \varphi(x_j)$$

• A *kernel function* is some function that corresponds to an inner product in some expanded feature space.

What Functions are Kernels?

- For some functions $K(x_i, x_j)$ checking that $K(x_i, x_j) = \phi(x_i)^T \phi(x_j)$ can be cumbersome.
- Mercer's theorem:

Every semi-positive definite symmetric function is a kernel

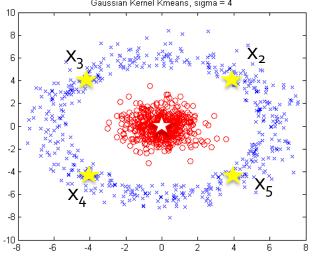
• Semi-positive definite symmetric functions correspond to a semi-positive definite symmetric Gram matrix:

| K = | $K(\mathbf{x}_1,\mathbf{x}_1)$ | $K(\mathbf{x_1},\mathbf{x_2})$ | $K(\mathbf{x}_1,\mathbf{x}_3)$ | | $K(\mathbf{x}_1,\mathbf{x}_N)$ |
|-----|---------------------------------|--------------------------------|--------------------------------|-----|---------------------------------|
| | $K(\mathbf{x}_2,\mathbf{x}_1)$ | $K(\mathbf{x_2},\mathbf{x_2})$ | $K(\mathbf{x}_2,\mathbf{x}_3)$ | | $K(\mathbf{x_2},\mathbf{x_N})$ |
| | ••• | | ••• | | |
| | $K(\mathbf{x_N}, \mathbf{x_1})$ | $K(\mathbf{x_N},\mathbf{x_2})$ | $K(\mathbf{x_N},\mathbf{x_3})$ | ••• | $K(\mathbf{x_N}, \mathbf{x_N})$ |

Example: A Kernel Function

- Polynomial kernel of degree h=2: $K(X_i, X_j) = X_i X_j^2 \rightarrow \varphi(x, y) = (x^2, \sqrt{2}xy, y^2)$
- Suppose there are 5 original 2-dimensional points:

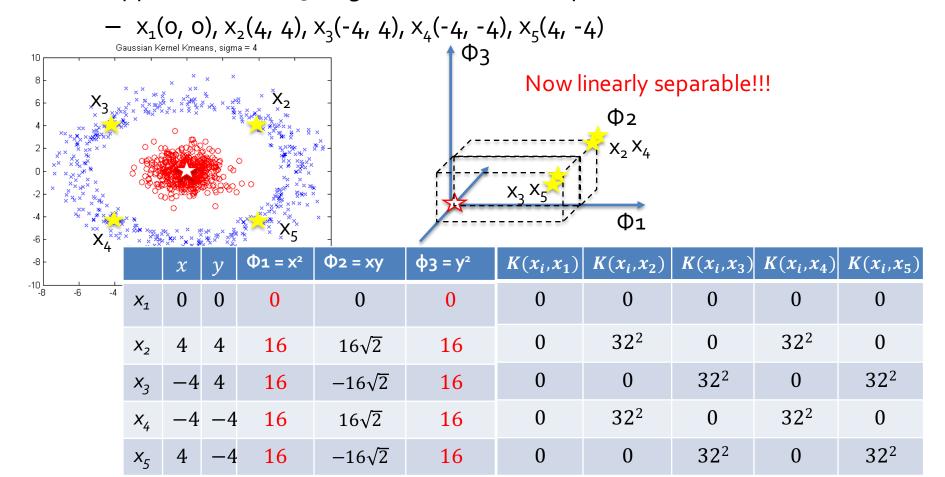
$$- X_1(0, 0), X_2(4, 4), X_3(-4, 4), X_4(-4, -4), X_5(4, -4)$$



| | x | у | Ф1 = X ² | Ф2 = ху | ф3 = у² |
|-----------------------|----|----|---------------------|---------------|---------|
| X ₁ | 0 | 0 | 0 | 0 | 0 |
| <i>X</i> ₂ | 4 | 4 | 16 | $16\sqrt{2}$ | 16 |
| <i>x</i> ₃ | -4 | 4 | 16 | $-16\sqrt{2}$ | 16 |
| <i>X</i> ₄ | -4 | -4 | 16 | $16\sqrt{2}$ | 16 |
| <i>X</i> ₅ | 4 | -4 | 16 | $-16\sqrt{2}$ | 16 |

Example: A Kernel Function

- Polynomial kernel of degree h=2: $K(X_i, X_j) = X_i X_j^2 \rightarrow \phi(x, y) = (x^2, \sqrt{2}xy, y^2)$
- Suppose there are 5 original 2-dimensional points:



Kernel Functions for Nonlinear Classification

- Instead of computing the dot product on the transformed data, it is mathematically equivalent to applying a kernel function $K(\mathbf{X_i}, \mathbf{X_j})$ to the original data, i.e., $K(\mathbf{X_i}, \mathbf{X_j}) = \Phi(\mathbf{X_i}) \Phi(\mathbf{X_j})$.
- Typical Kernel Functions

Polynomial kernel of degree $h: K(X_i, X_j) = (X_i \cdot X_j + 1)^h$

Gaussian radial basis function kernel: $K(X_i, X_i) = e^{-\|X_i - X_j\|^2/2\sigma^2}$

Sigmoid kernel: $K(X_i, X_j) = \tanh(\kappa X_i \cdot X_j - \delta)$

Non-linear SVMs: Optimization

Dual problem formulation:

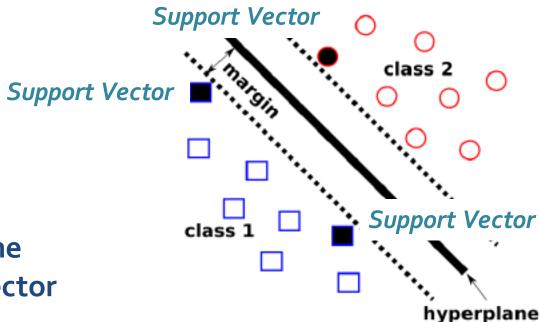
Find
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 such that $Q(\alpha) = \sum \alpha_i - \frac{1}{2} \sum \sum \alpha_i \alpha_j y_i y_j K(x_i, x_j)$ is maximized and (1) $\sum \alpha_i y_i = 0$ (2) $\alpha_i \ge 0$ for all α_i

The solution is:

$$f(x) = \sum \alpha_i y_i K(x_i, x_i) + b$$

• Optimization techniques for finding α_i 's remain the same!

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SVM: History and Applications

- Vapnik and colleagues (1992)—groundwork from Vapnik & Chervonenkis' statistical learning theory in 1960s
- Features: training can be slow but accuracy is high owing to their ability to model complex nonlinear decision boundaries (margin maximization)
- Applications:
 - Text categorization
 - Image classification
 - Hand-written digit/character recognition
 - Object recognition
 - Bioinformatics (Protein classification, Cancer classification...)

SVM Related Links

- SVM Website: http://www.kernel-machines.org/
- Representative implementations
 - LIBSVM: an efficient implementation of SVM, multi-class classifications, nu-SVM, one-class SVM, including also various interfaces with java, python, etc.
 - SVM-light: simpler but performance is not better than LIBSVM,
 support only binary classification and only in C
 - SVM-torch: another recent implementation also written in C
 - http://www.meng-jiang.com/teaching/SVMDemo.zip

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