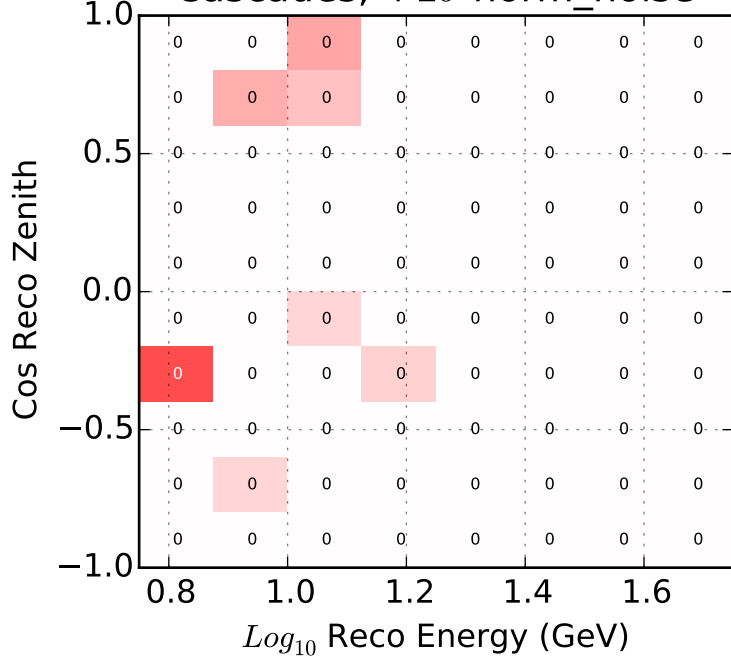


Cascades, $+1\sigma$ norm_noiseTracks, $+1\sigma$ norm_noise