

aml_ctrl.utilities.lin
_interp.LinInterp

- + dt
- + tau
- + timesteps
- + lin_interp_traj
- + start_pos
- + goal_pos
- + start_qt
- + goal_qt

- + __init__()
- + configure()
- + lin_step_qt()
- + lin_step_pos()
- + get_interpolated_trajectory()
- + plot_lin_interp_traj()