

aml\_pcloud::PCLProcessor

- + PCLProcessor()
- + getCloudFromPcdFile()
- + saveToPcdFile()
- + downsampleCloud()
- + getPointsNotInPlane()
- + computeNormalForAllPoints()
- + computeNormalForAllPoints()
- + fitPlaneAndGetCurvature()
- + transformPointCloud()
- + addPointClouds()
- + computeCentroid()