

aml_ctrl.utilities.min
_jerk_interp.MinJerkInterp

- + dt
- + tau
- + timesteps
- + min_jerk_traj
- + start_pos
- + goal_pos
- + start_qt
- + goal_qt

- + __init__()
- + configure()
- + min_jerk_step()
- + min_jerk_step_pos()
- + min_jerk_step_qt()
- + get_interpolated_trajectory()
- + plot_min_jerk_traj()