```
aml robot.bullet.push
 world.push world.PushWorld
+ rate
+ init ()
+ step()
+ on shutdown()
+ set_pre_push_location()
+ push box()
+ check within limits()
+ fsm()
+ run()
 test push world.TestModel
         PushWorld
   init ()
 + draw_prediction()
 + draw()
 + handle event()
 + is time to train()
 + plot()
```

+ update()