```
object
aml_robot.box2d.box2d
    robot.Box2DRobot
+ init ()
+ configure default pos()
+ configure camera()
+ get image()
+ get ee pose()
+ get pos ori()
+ get contact points()
+ set default pos ori()
+ set pos ori()
+ get int state()
+ set int state()
+ apply external force()
+ apply external torque()
+ get point()
+ get screen point()
+ get screen point2()
```