

gazebo\_ros\_control  
::GazeboRosControlPlugin

```
classDiagram
    class GazeboRosControlPlugin {
    }
    class InteraGripperGazeboRosControlPlugin {
        + Load()
        + enableCommandCallback()
        + rightEndEffectorCommandCallback()
    }
    GazeboRosControlPlugin <|-- InteraGripperGazeboRosControlPlugin
```

intera\_gripper\_gazebo  
\_plugin::InteraGripperGazebo  
RosControlPlugin

+ Load()  
+ enableCommandCallback()  
+ rightEndEffectorCommandCallback()