

aml_ctrl.controllers.os
_controllers.os_moveit
_baxter_controller.BaxterMoveIt
Controller

- + robot
- + scene
- + left_group_configured
- + right_group_configured
- + both_group_configured
- + display_trajectory_publisher
- + group_left_arm
- + group_right_arm
- + group_both_arms

- + __init__()
- + add_static_objects_to_scene()
- + set_group_handles()
- + set_tolerance()
- + get_group_handle()
- + get_plan()
- + execute_plan()
- + clear_pose_targets()
- + clean_shutdown()
- + plan_both_arms()
- + self_test()