

gym::Env

```
classDiagram
    class gymEnv["gym::Env"]
    class amlEnv["aml_rl_envs.aml_rl_env.AMLREnv"]
    amlEnv --|> gymEnv
```

The diagram illustrates a class hierarchy. At the top is the 'gym::Env' class, represented by a rectangle divided into three horizontal sections. The top section contains the text 'gym::Env', while the two bottom sections are empty. Below this is the 'aml\_rl\_envs.aml\_rl\_env.AMLREnv' class, represented by a single large rectangle divided into three horizontal sections. The top section contains the class name. The middle section lists four attributes: '+ viewer', '+ action\_space', '+ observation\_space', and '+ metadata'. The bottom section lists six methods: '+ \_\_init\_\_()', '+ set\_space\_lims()', '+ setup\_env()', '+ simple\_step()', '+ \_\_del\_\_()', and '+ step2()'. A blue arrow with an open triangular head points from the top of the 'aml\_rl\_envs.aml\_rl\_env.AMLREnv' class to the bottom of the 'gym::Env' class, indicating that 'aml\_rl\_envs.aml\_rl\_env.AMLREnv' inherits from 'gym::Env'.

aml\_rl\_envs.aml\_rl\_env.AMLREnv

+ viewer  
+ action\_space  
+ observation\_space  
+ metadata

+ \_\_init\_\_()  
+ set\_space\_lims()  
+ setup\_env()  
+ simple\_step()  
+ \_\_del\_\_()  
+ step2()